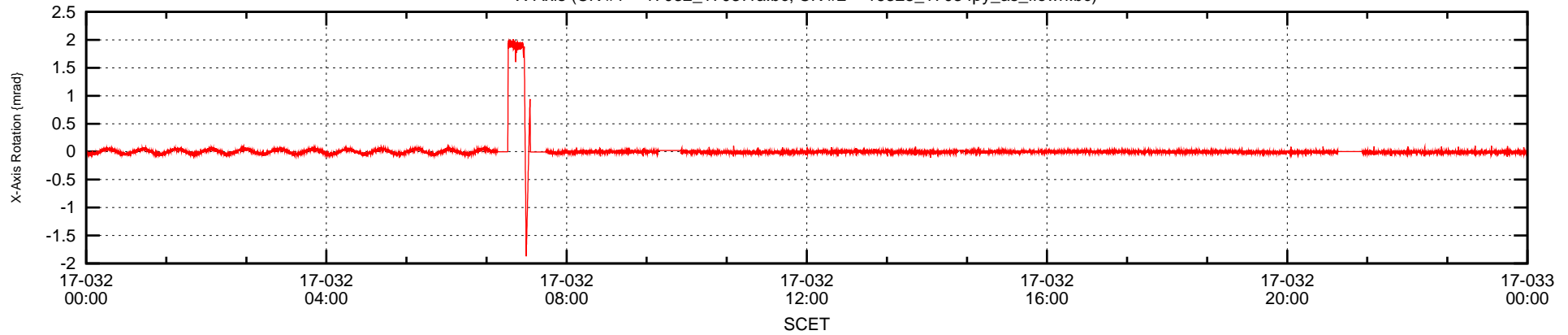
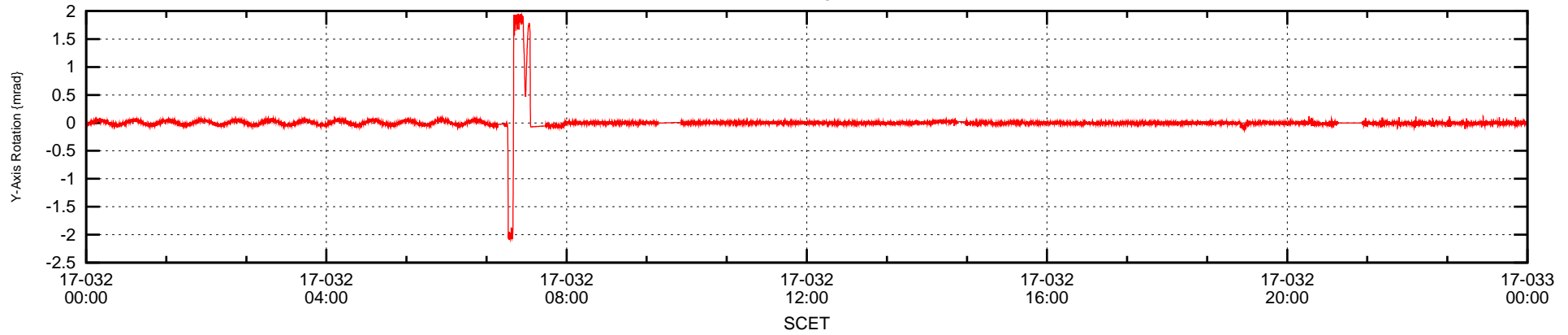


# Rotation From CK #2 to CK #1 (DOY 032-033)

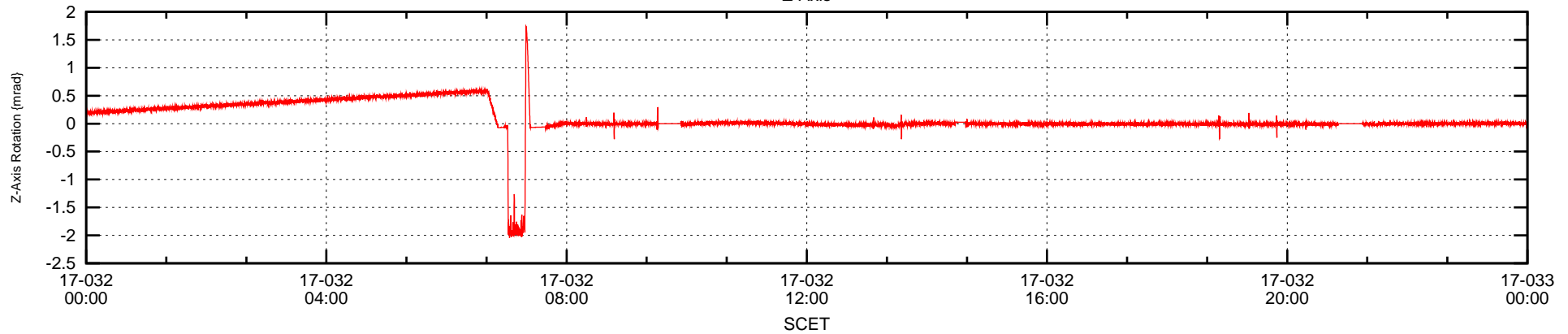
X-Axis (CK #1 = 17032\_17037ra.bc; CK #2 = 16328\_17034py\_as\_flowm.bc)



Y-Axis

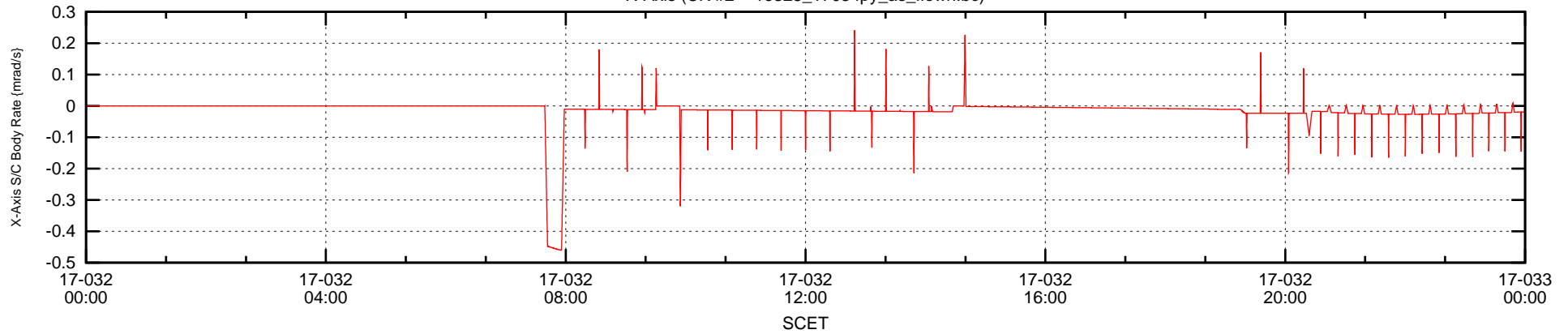


Z-Axis

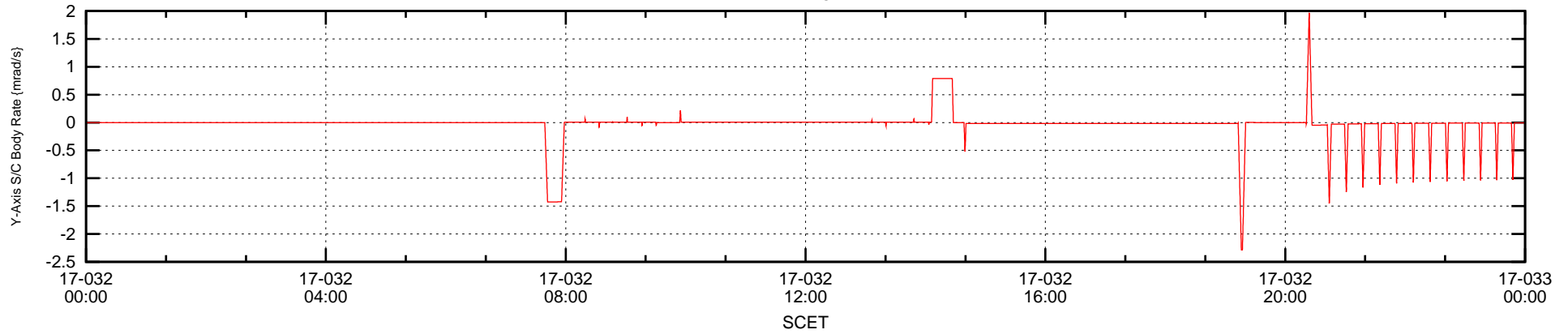


# CK #2 S/C Body Rates (DOY 032-033)

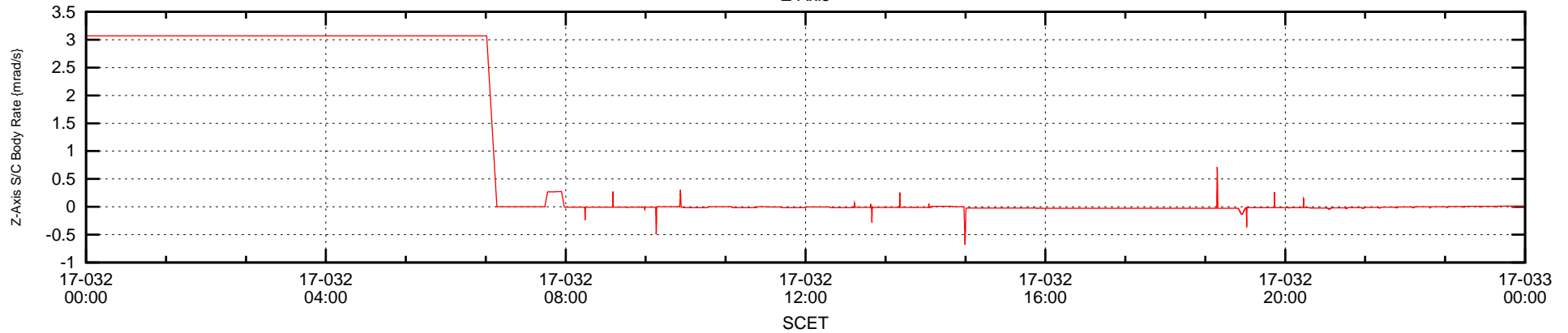
X-Axis (CK #2 = 16328\_17034py\_as\_flowm.bc)



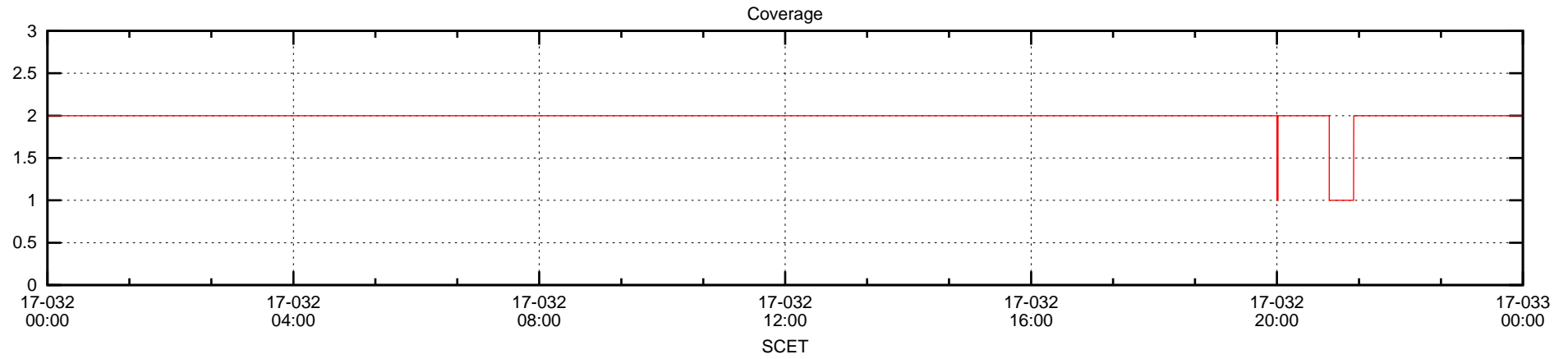
Y-Axis



Z-Axis

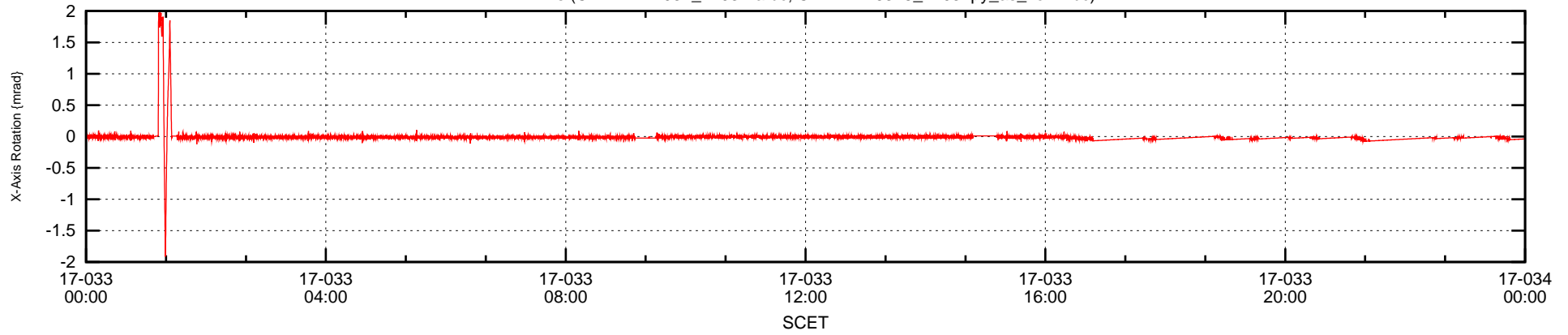


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 032-033)

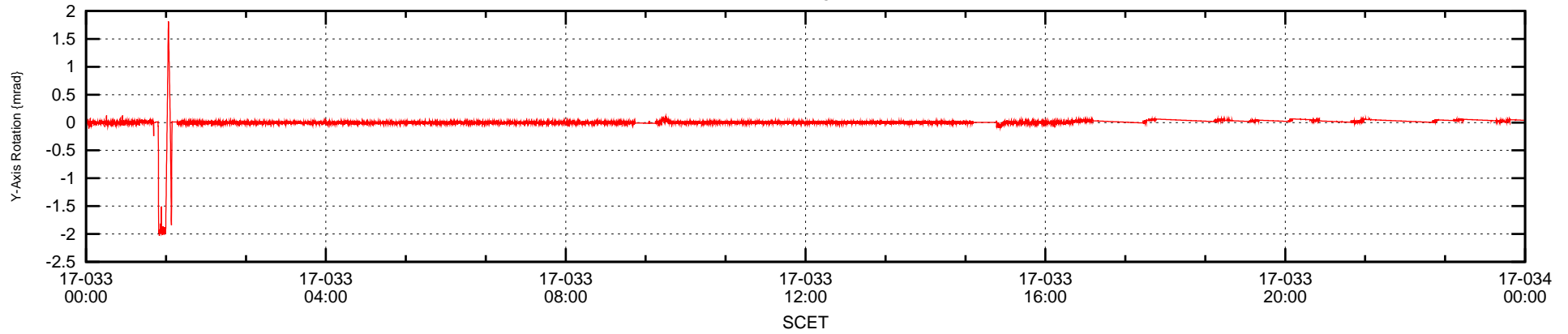


# Rotation From CK #2 to CK #1 (DOY 033-034)

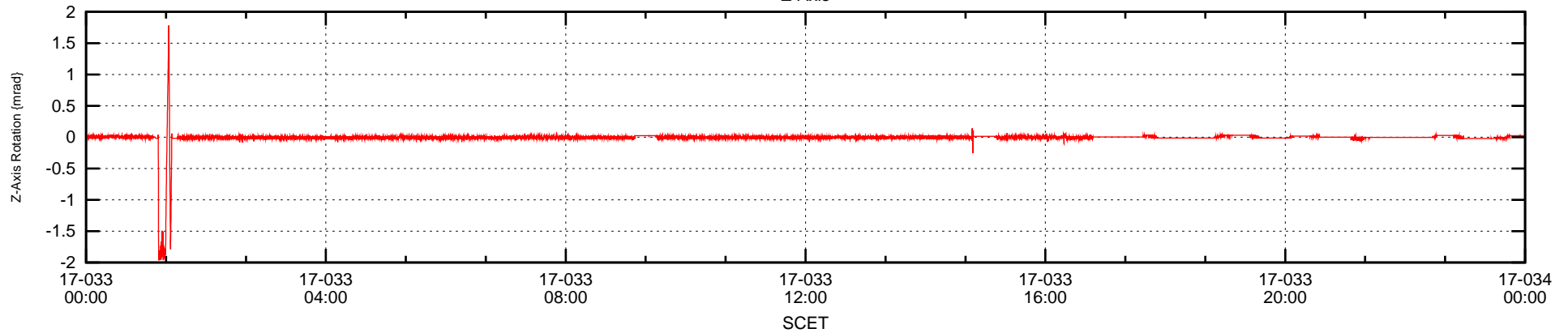
X-Axis (CK #1 = 17032\_17037ra.bc; CK #2 = 16328\_17034py\_as\_flown.bc)



Y-Axis

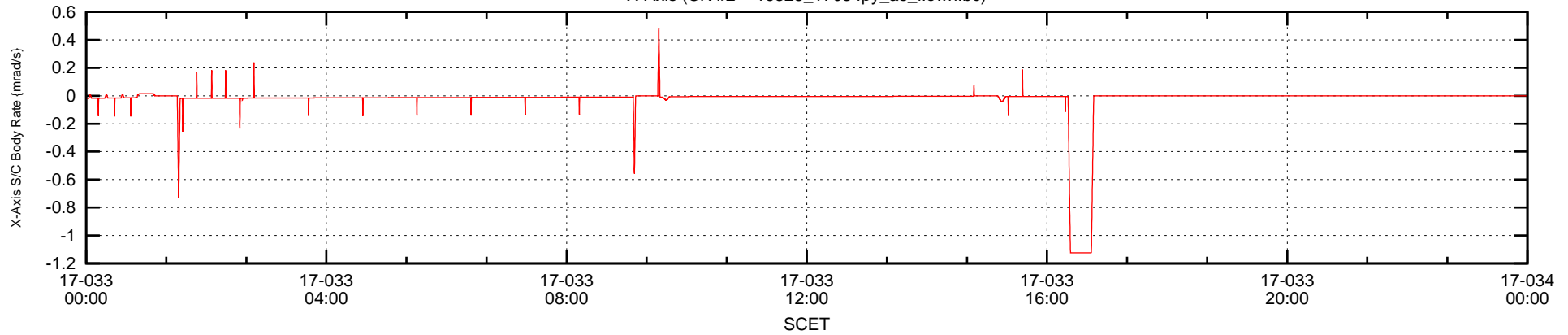


Z-Axis

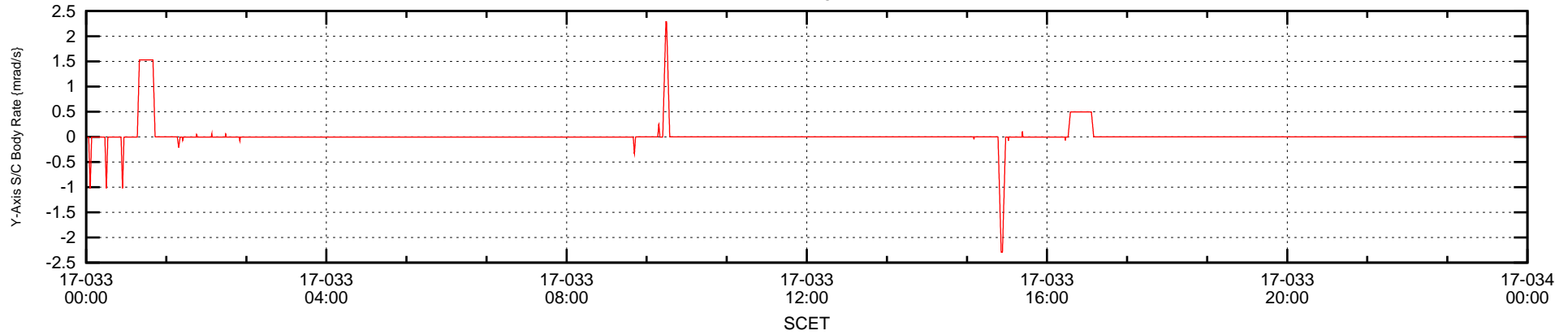


# CK #2 S/C Body Rates (DOY 033-034)

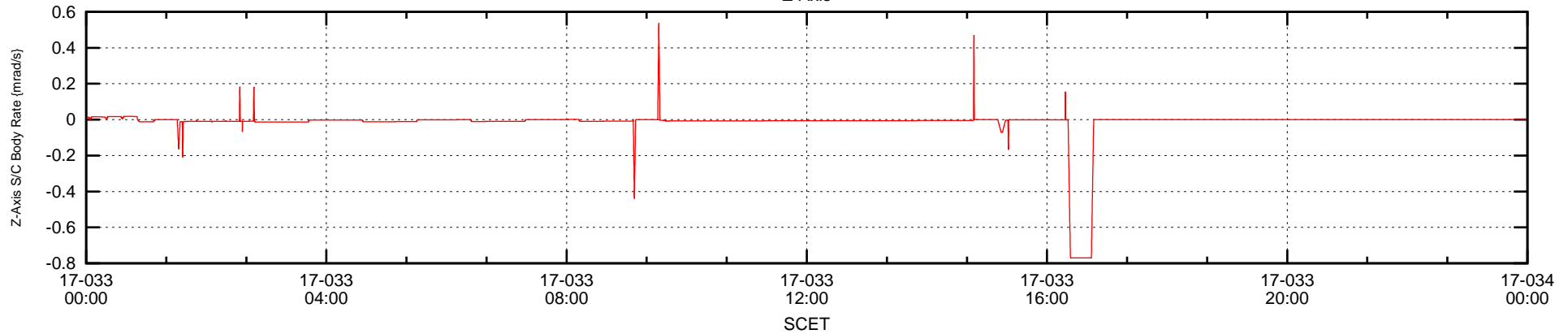
X-Axis (CK #2 = 16328\_17034py\_as\_flown.bc)



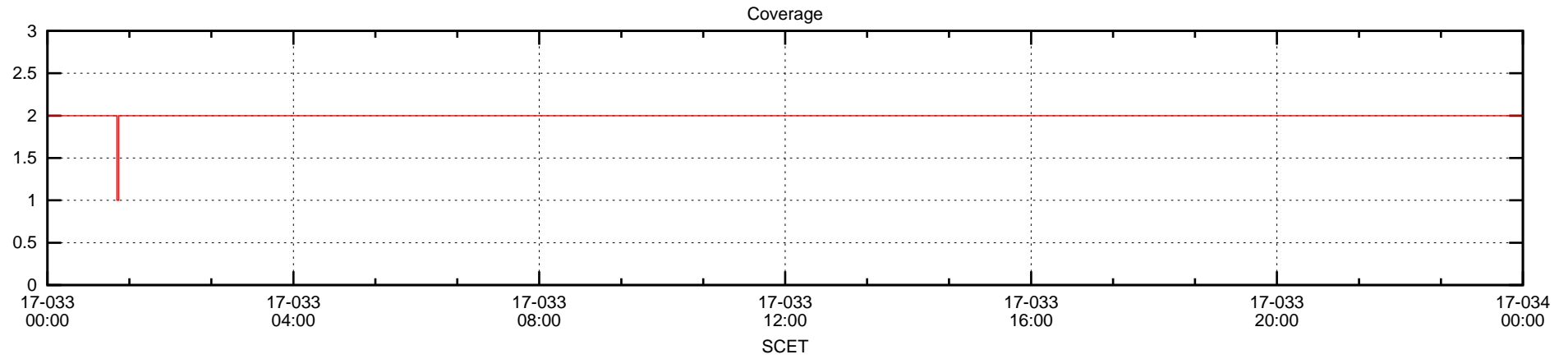
Y-Axis



Z-Axis

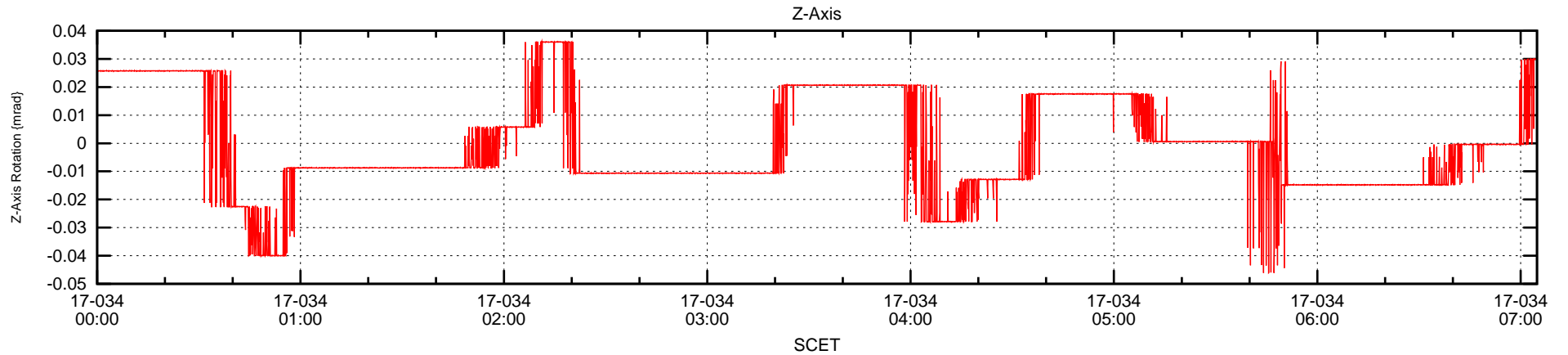
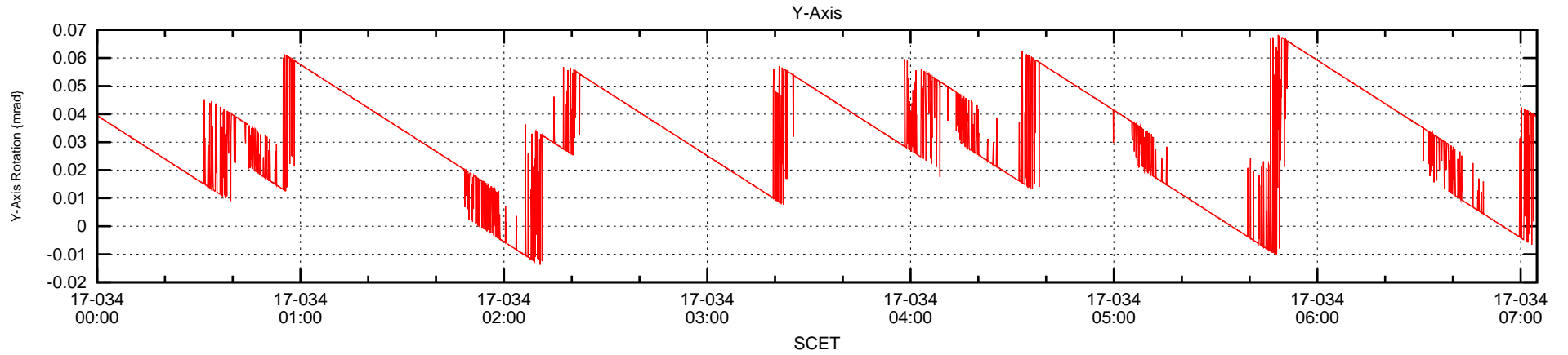
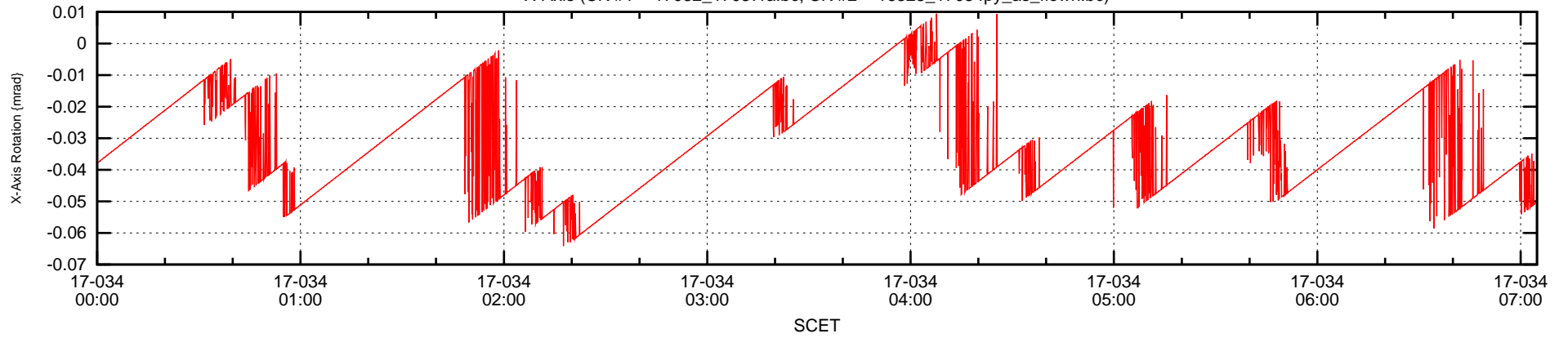


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 033-034)



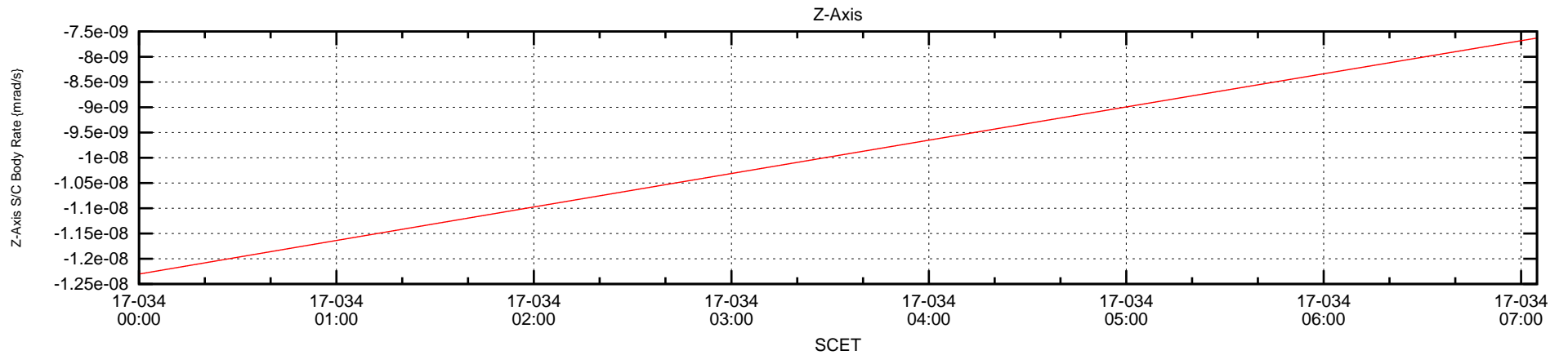
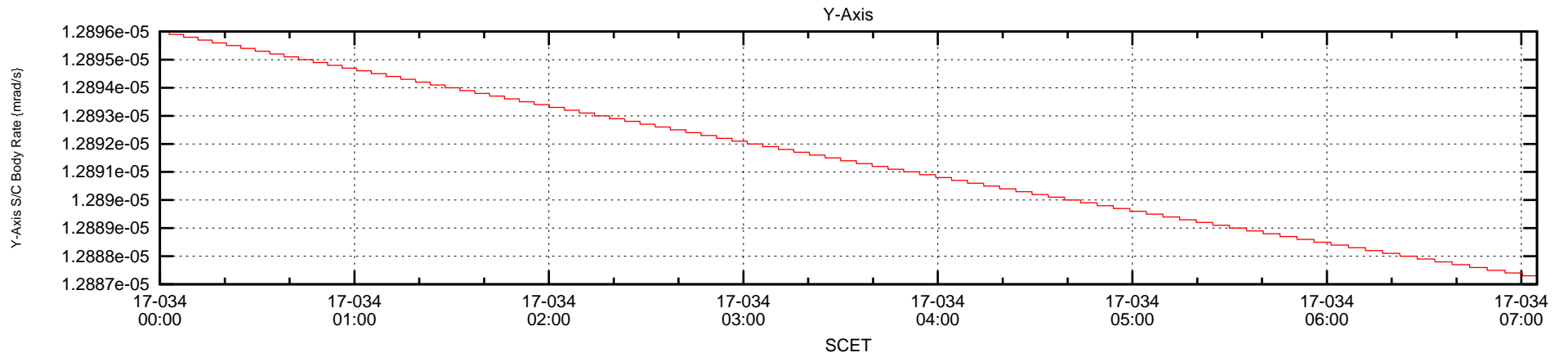
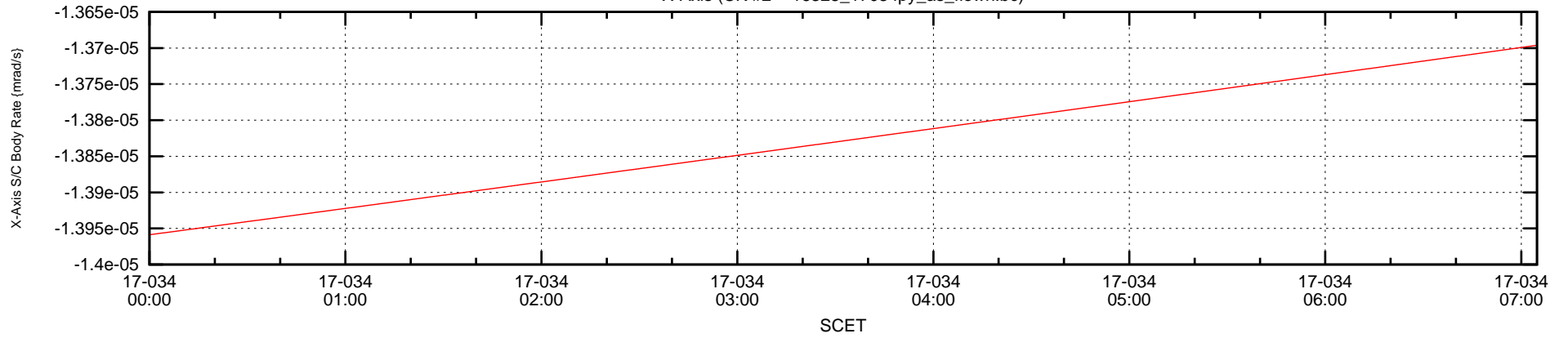
# Rotation From CK #2 to CK #1 (DOY 034-034)

X-Axis (CK #1 = 17032\_17037ra.bc; CK #2 = 16328\_17034py\_as\_flown.bc)



# CK #2 S/C Body Rates (DOY 034-034)

X-Axis (CK #2 = 16328\_17034py\_as\_flown.bc)





All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 034-034)

