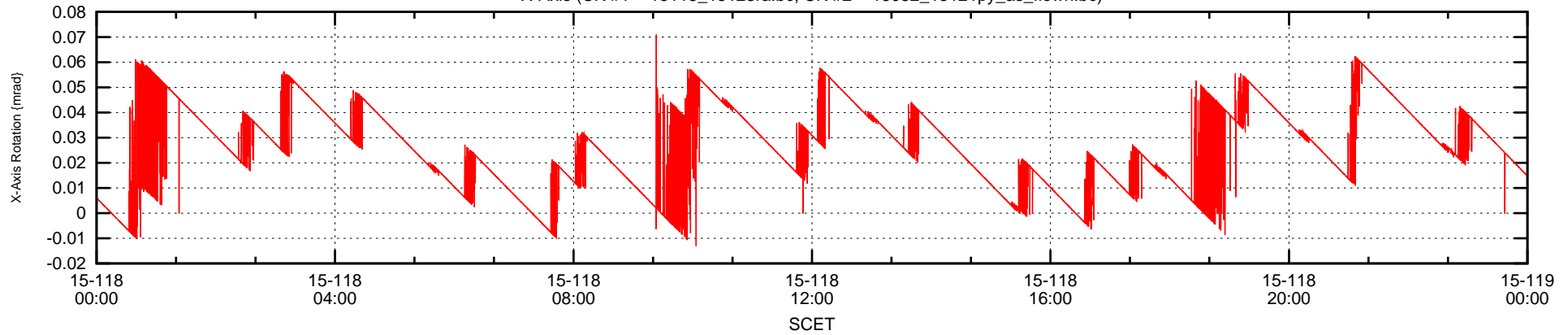
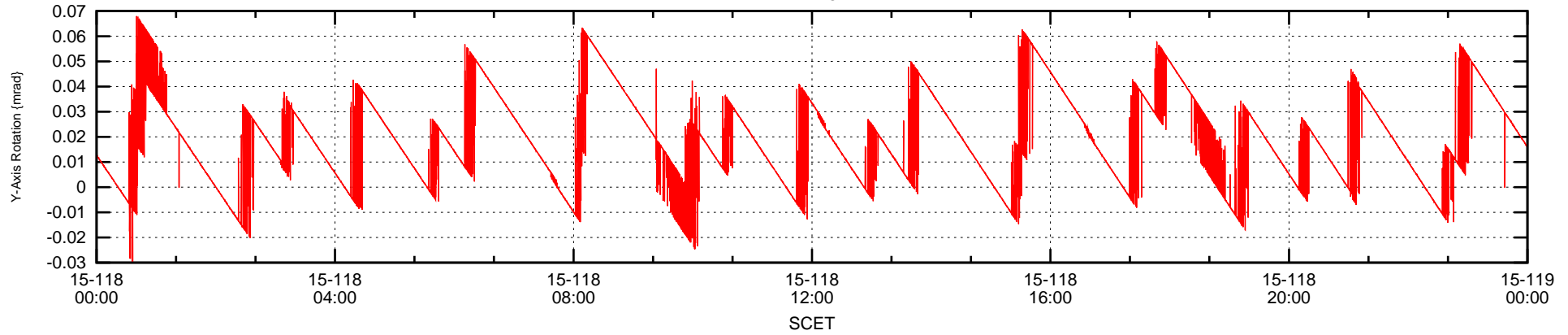


Rotation From CK #2 to CK #1 (DOY 118-119)

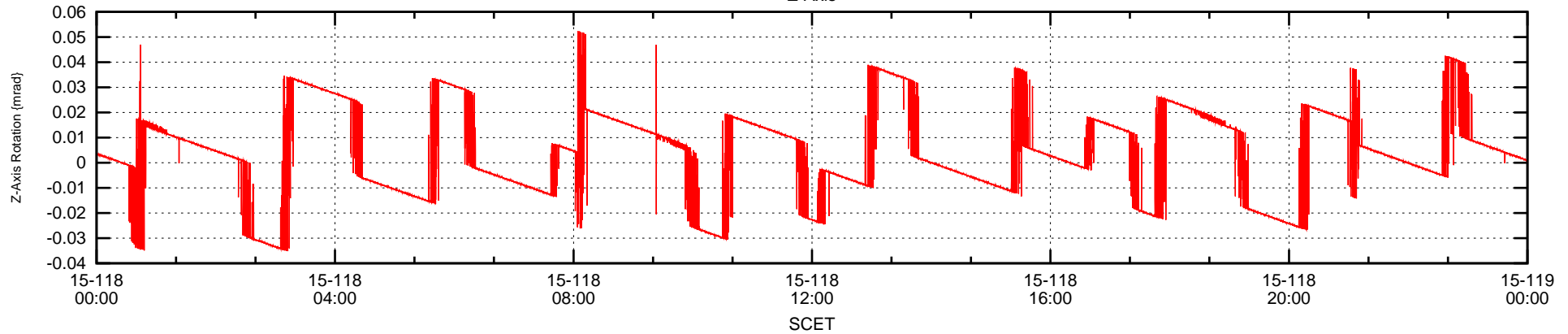
X-Axis (CK #1 = 15118_15123ra.bc; CK #2 = 15052_15121py_as_flowm.bc)



Y-Axis

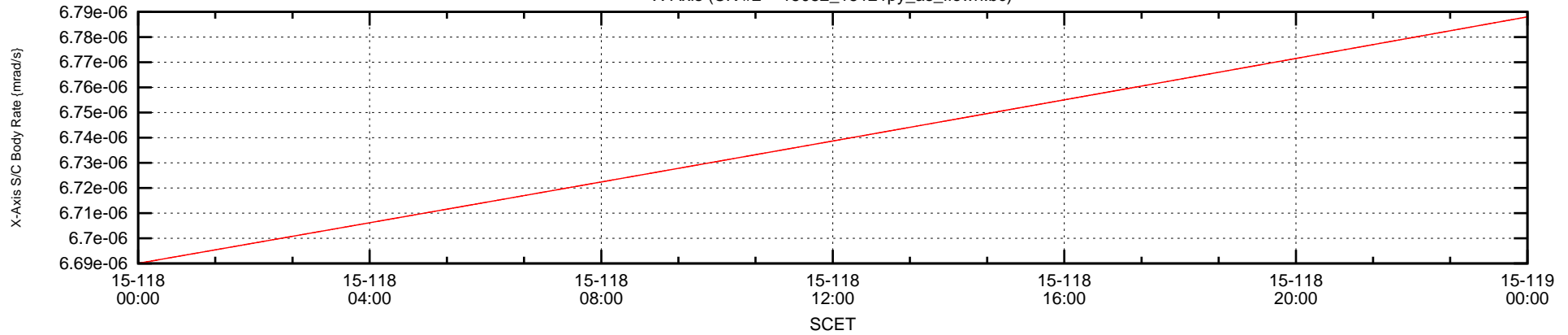


Z-Axis

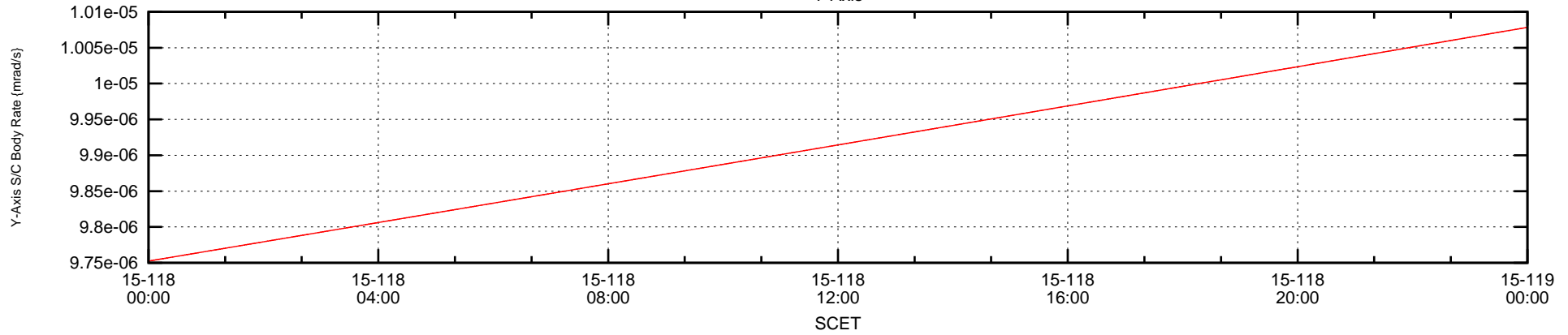


CK #2 S/C Body Rates (DOY 118-119)

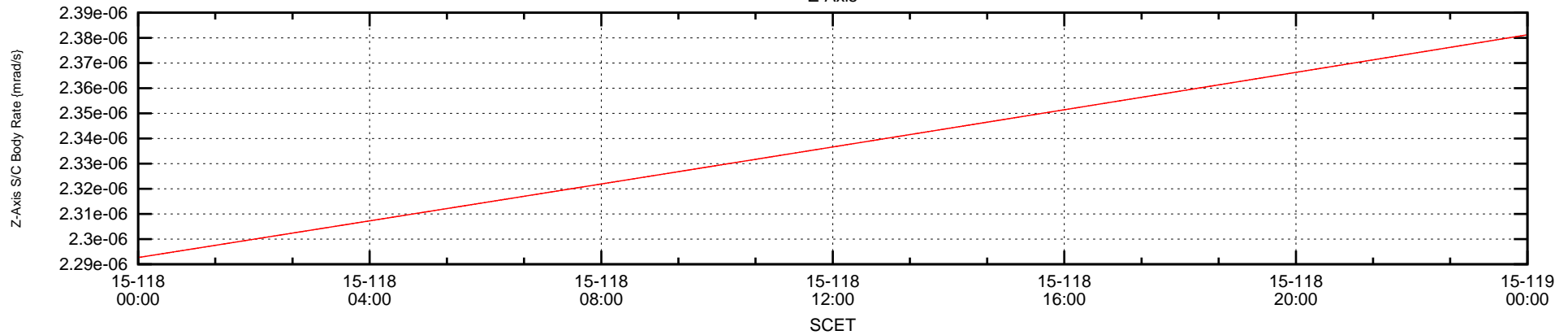
X-Axis (CK #2 = 15052_15121py_as_flowm.bc)



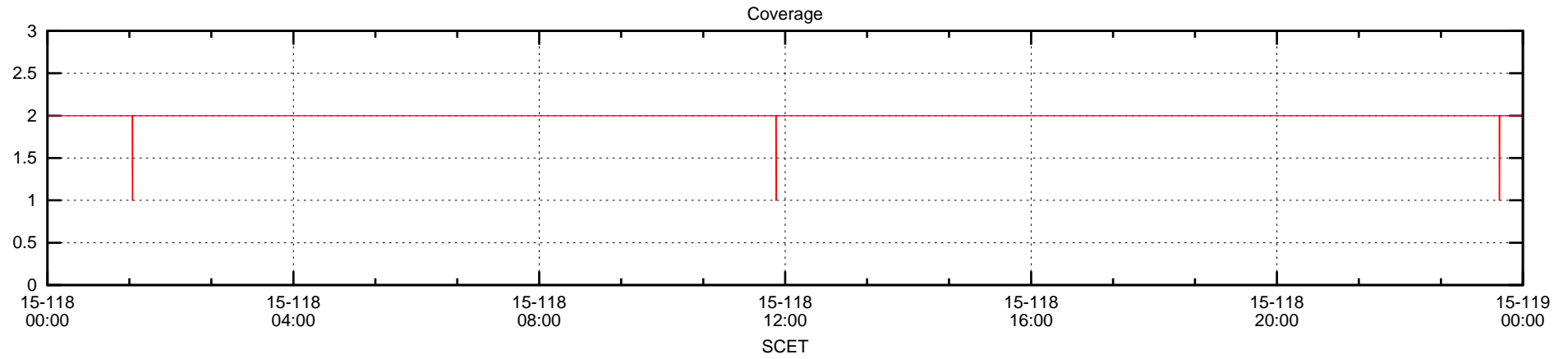
Y-Axis



Z-Axis

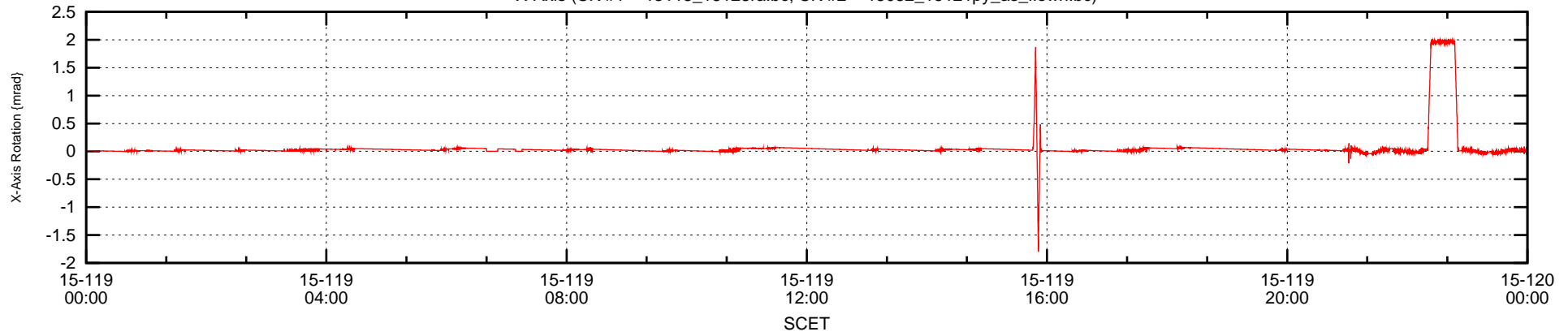


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 118-119)

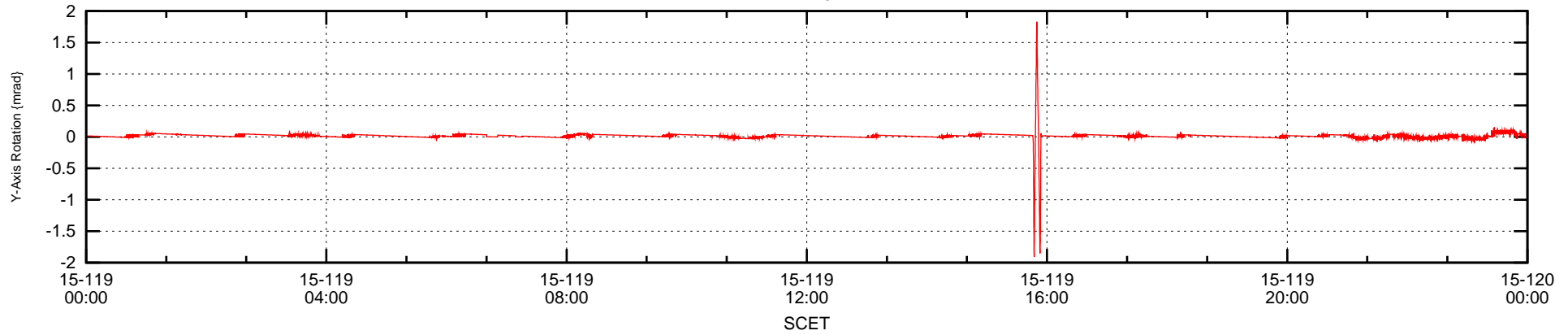


Rotation From CK #2 to CK #1 (DOY 119-120)

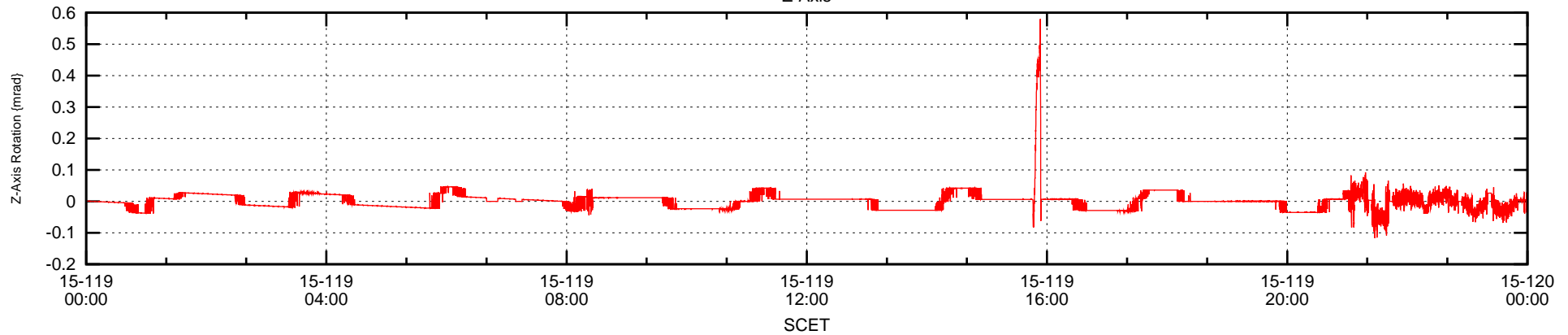
X-Axis (CK #1 = 15118_15123ra.bc; CK #2 = 15052_15121py_as_flow.bc)



Y-Axis

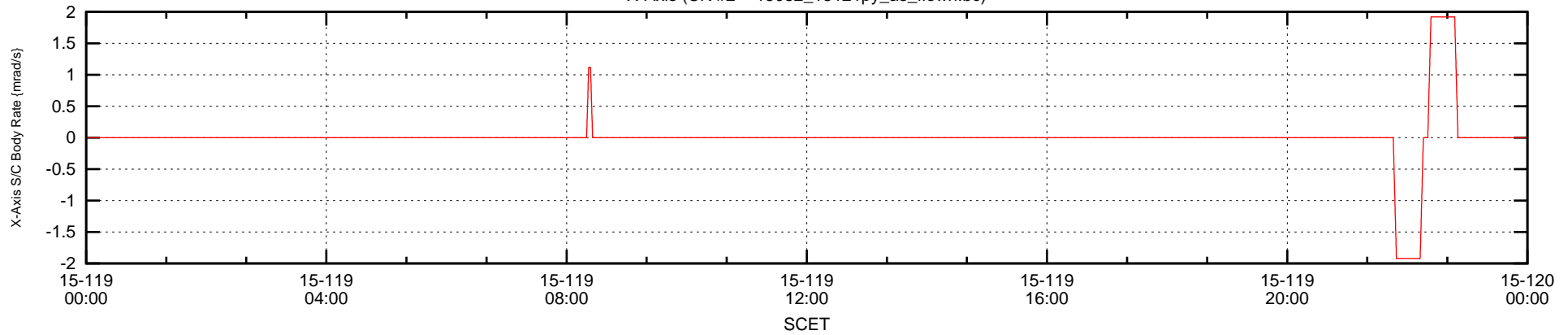


Z-Axis

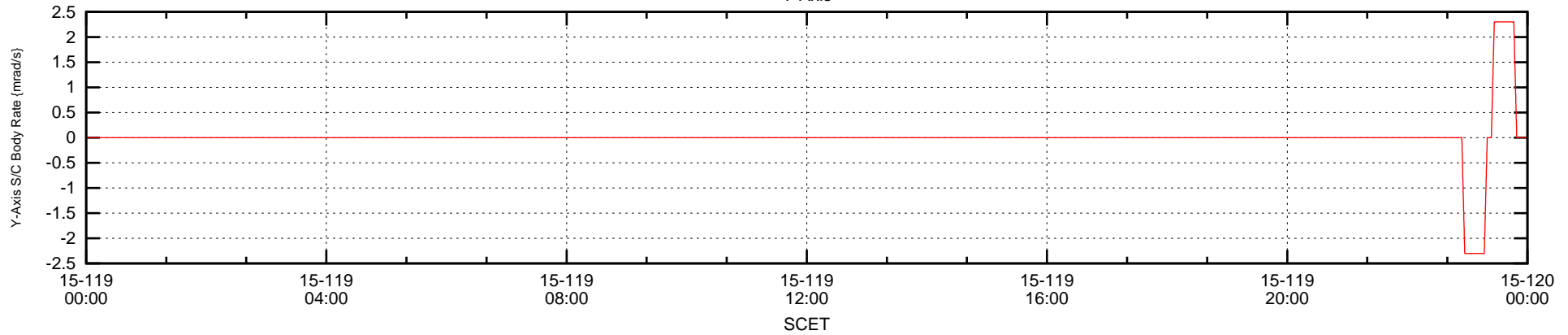


CK #2 S/C Body Rates (DOY 119-120)

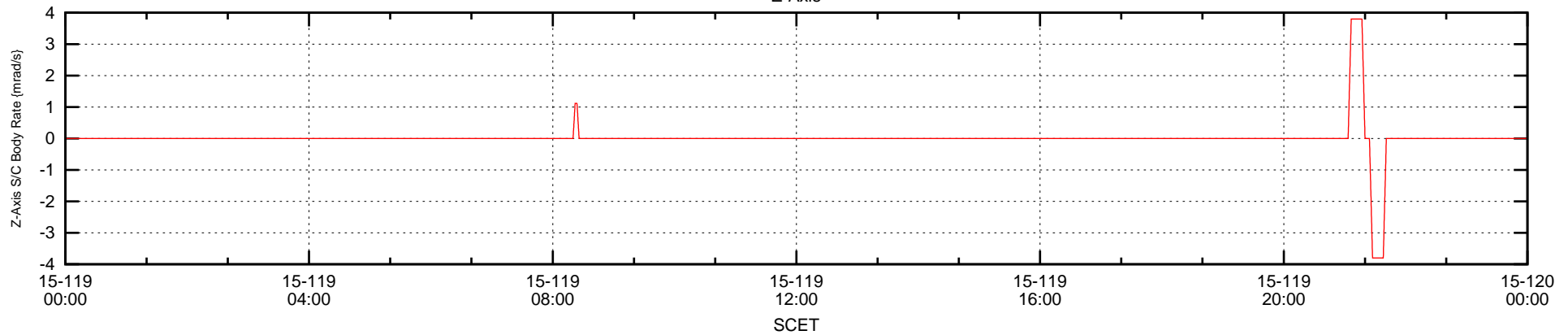
X-Axis (CK #2 = 15052_15121py_as_flow.n.bc)



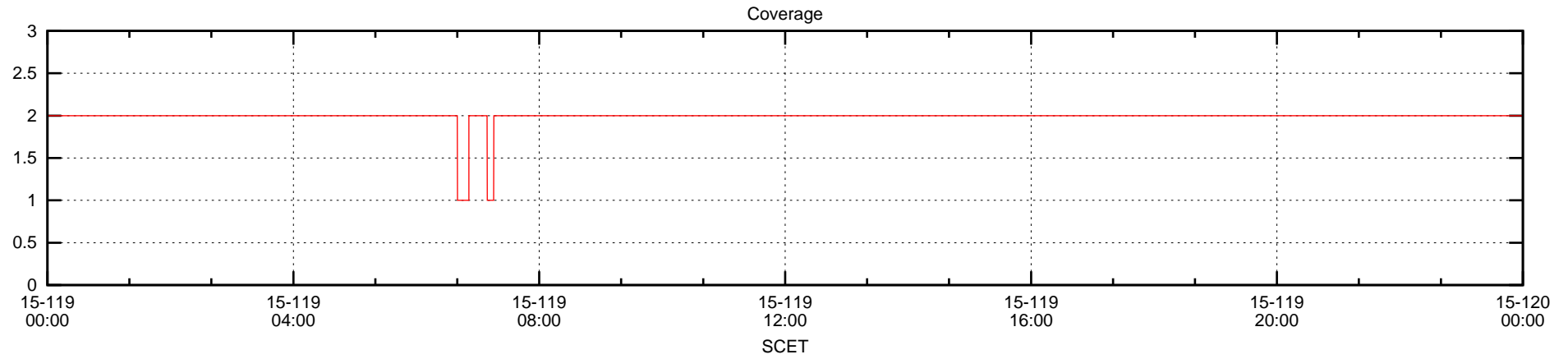
Y-Axis



Z-Axis

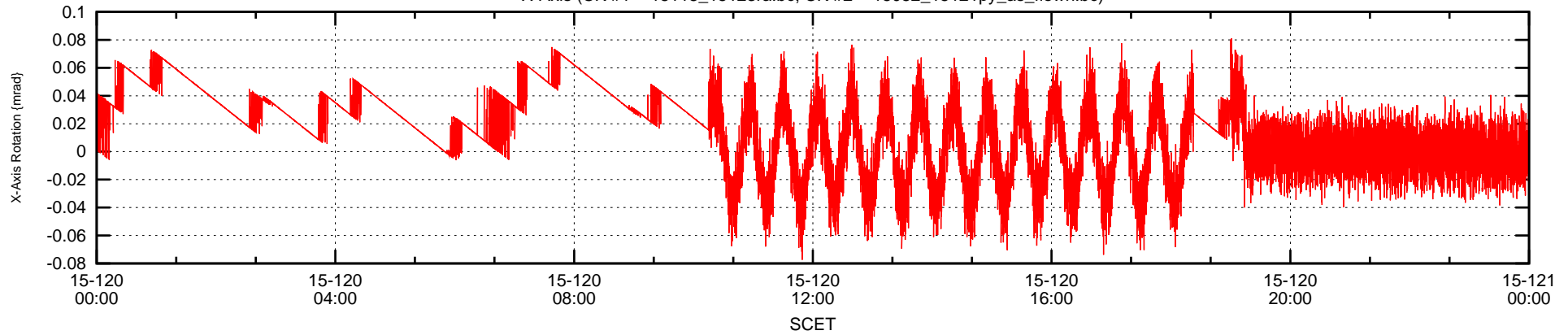


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 119-120)

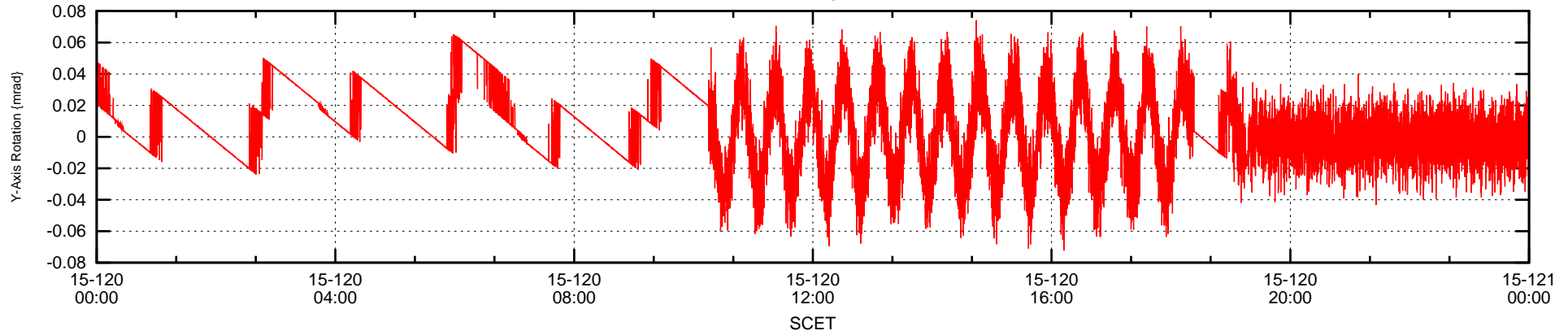


Rotation From CK #2 to CK #1 (DOY 120-121)

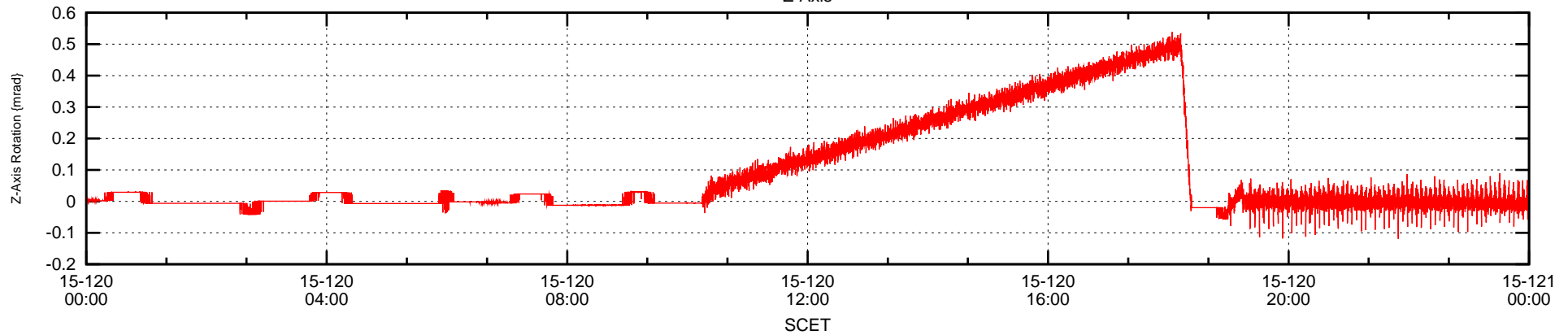
X-Axis (CK #1 = 15118_15123ra.bc; CK #2 = 15052_15121py_as_flown.bc)



Y-Axis

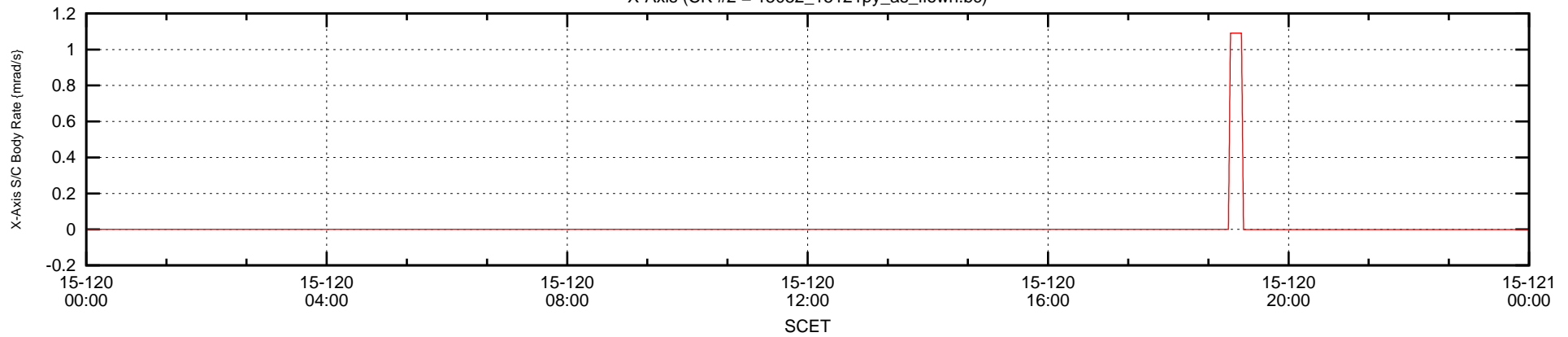


Z-Axis

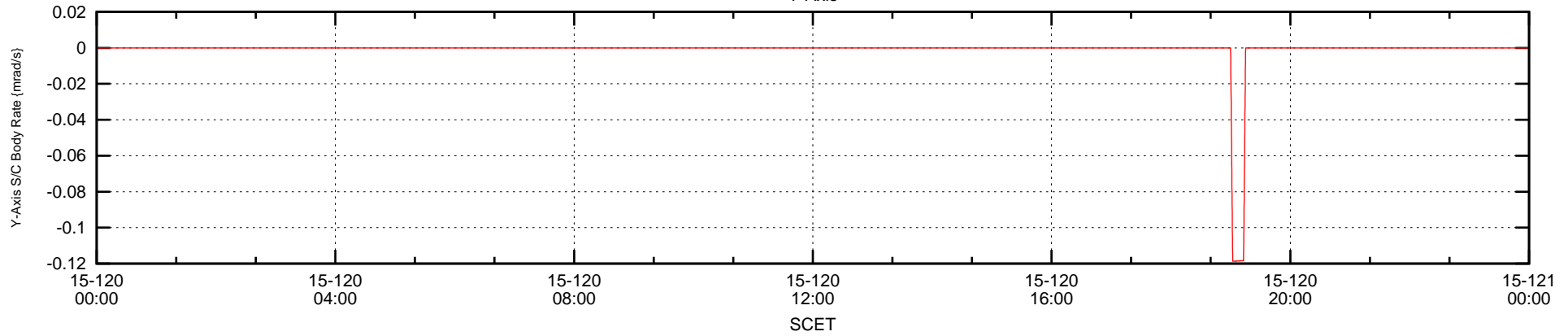


CK #2 S/C Body Rates (DOY 120-121)

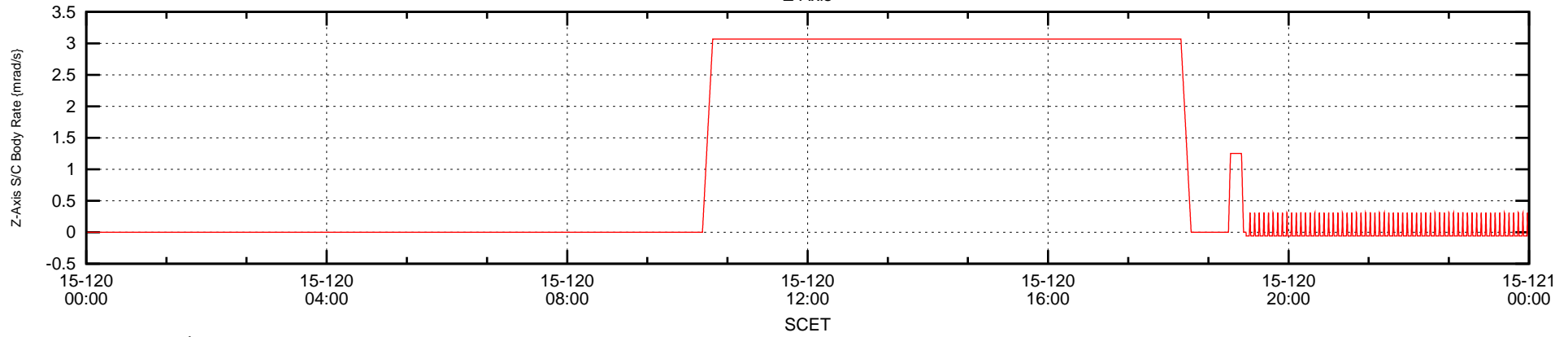
X-Axis (CK #2 = 15052_15121py_as_flowm.bc)



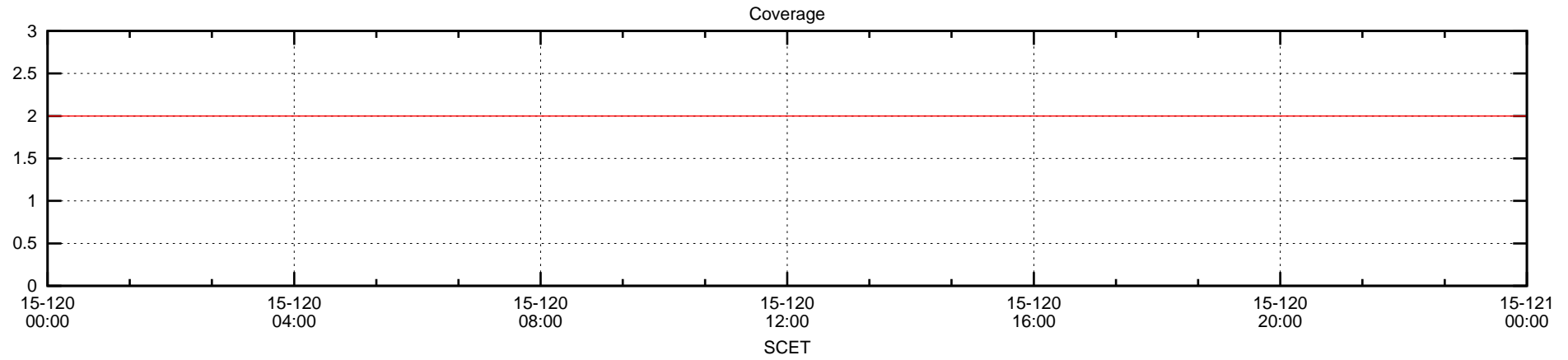
Y-Axis



Z-Axis

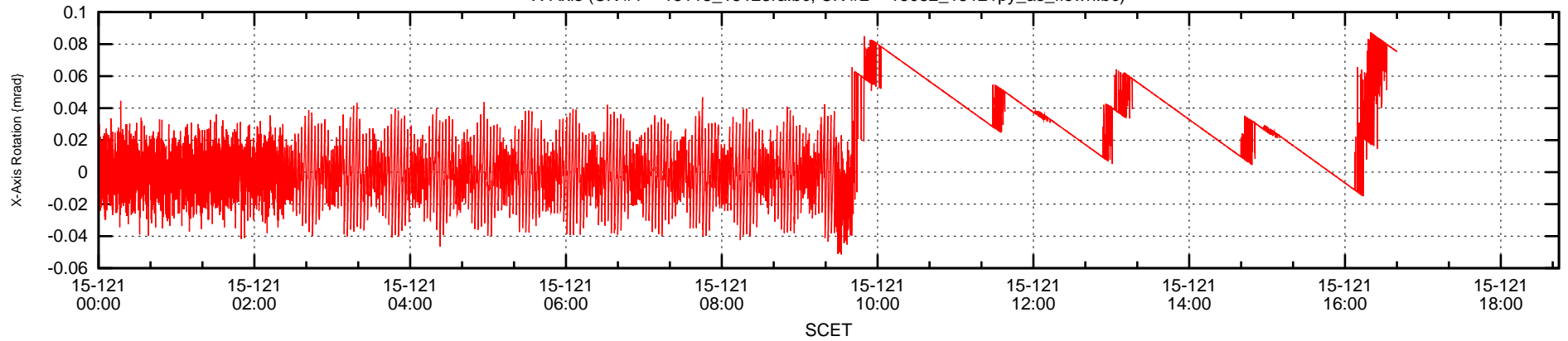


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 120-121)

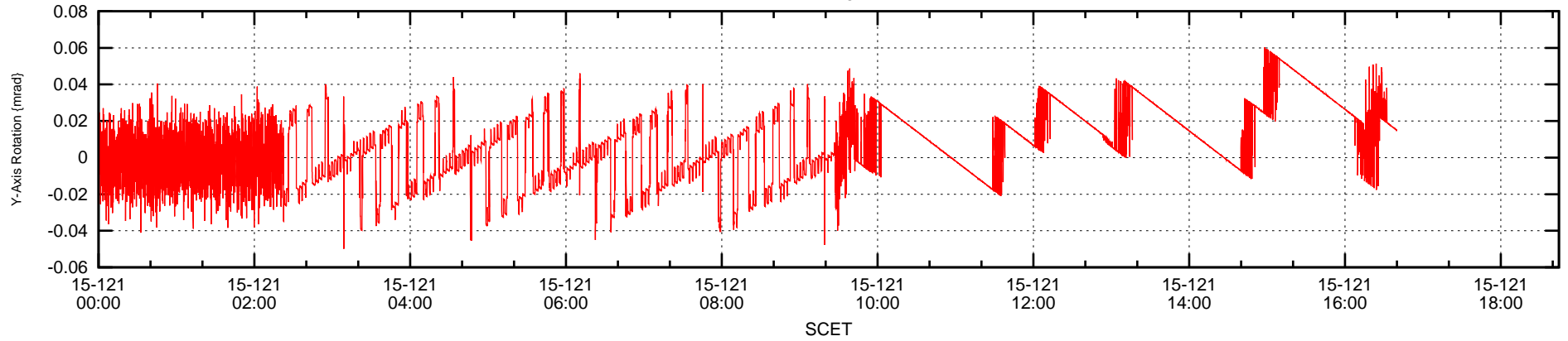


Rotation From CK #2 to CK #1 (DOY 121-121)

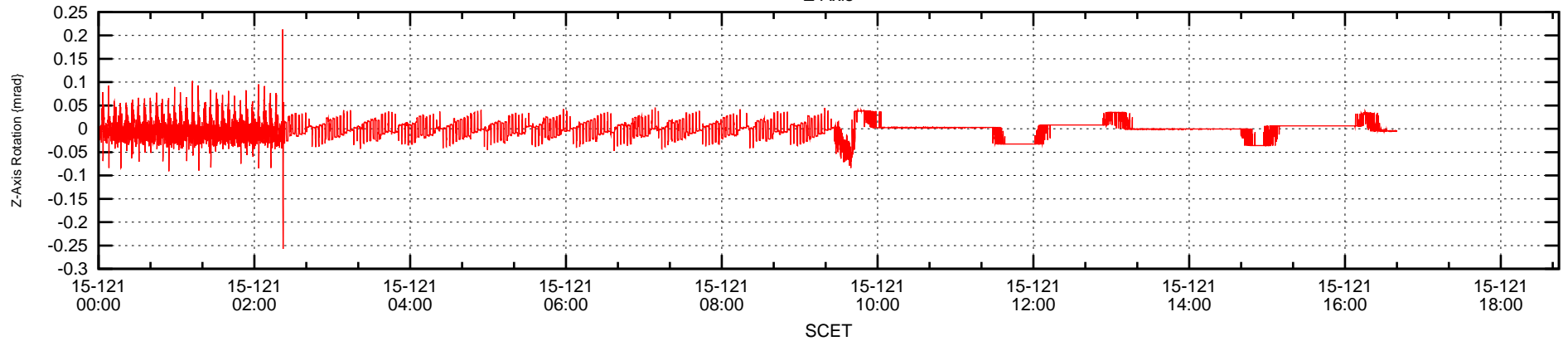
X-Axis (CK #1 = 15118_15123ra.bc; CK #2 = 15052_15121py_as_flowm.bc)



Y-Axis

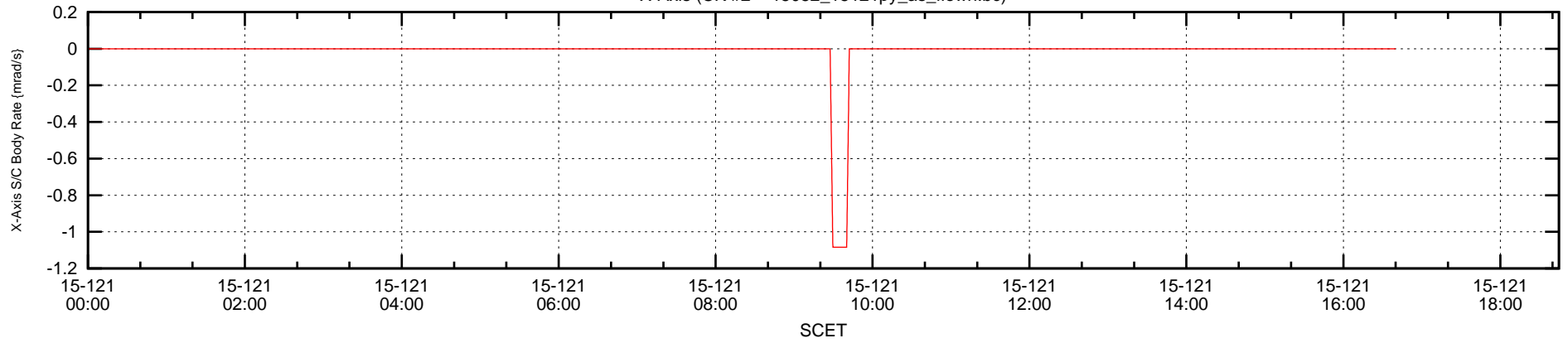


Z-Axis

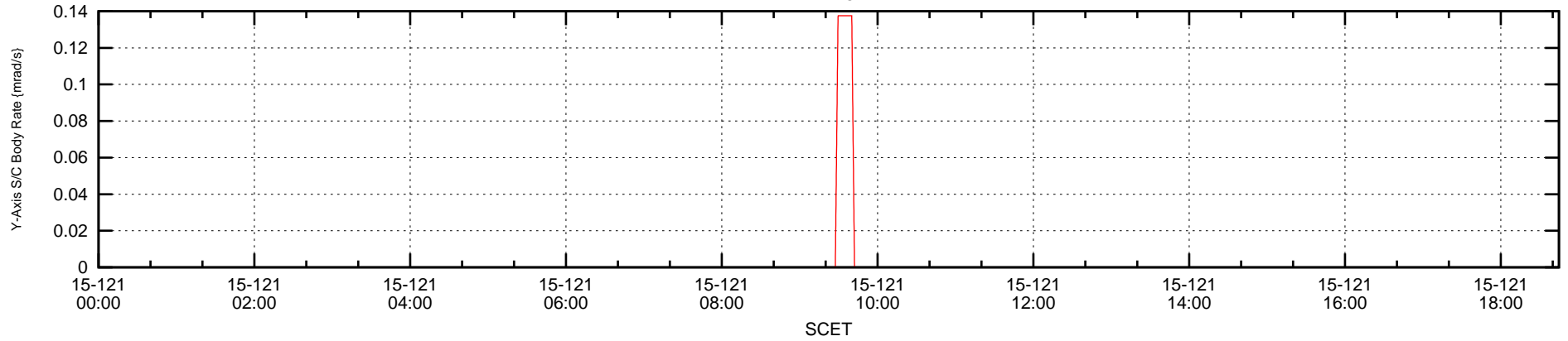


CK #2 S/C Body Rates (DOY 121-121)

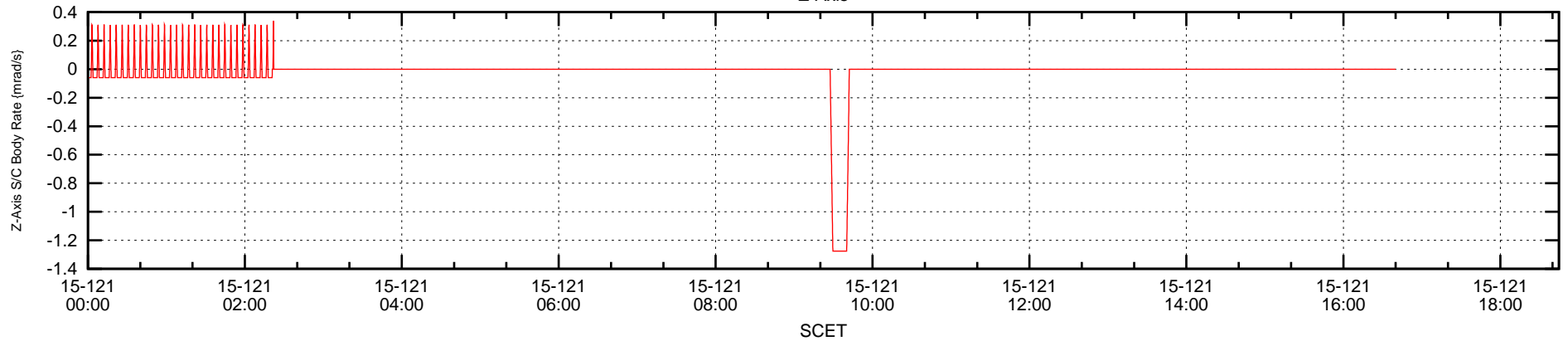
X-Axis (CK #2 = 15052_15121py_as_flowm.bc)



Y-Axis



Z-Axis



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 121-121)

