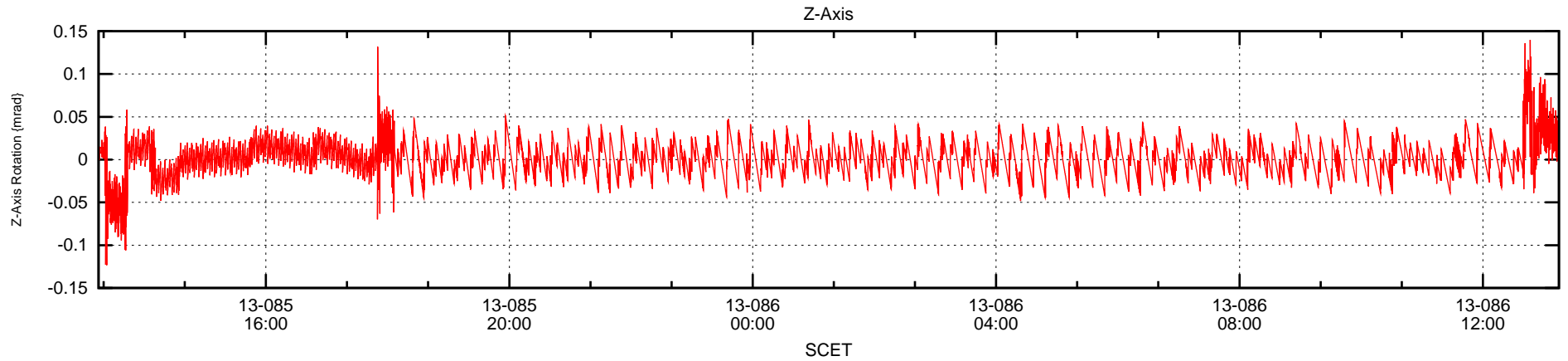
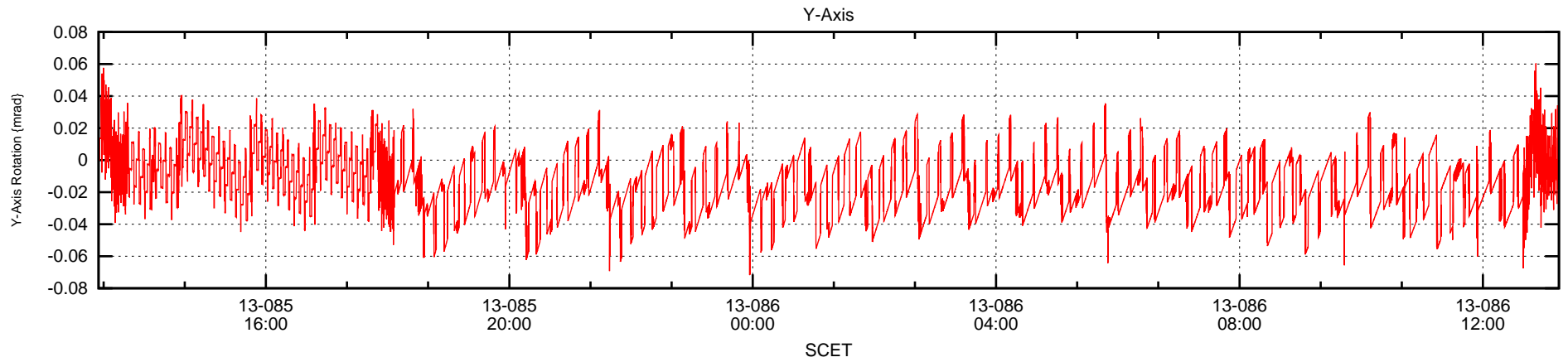
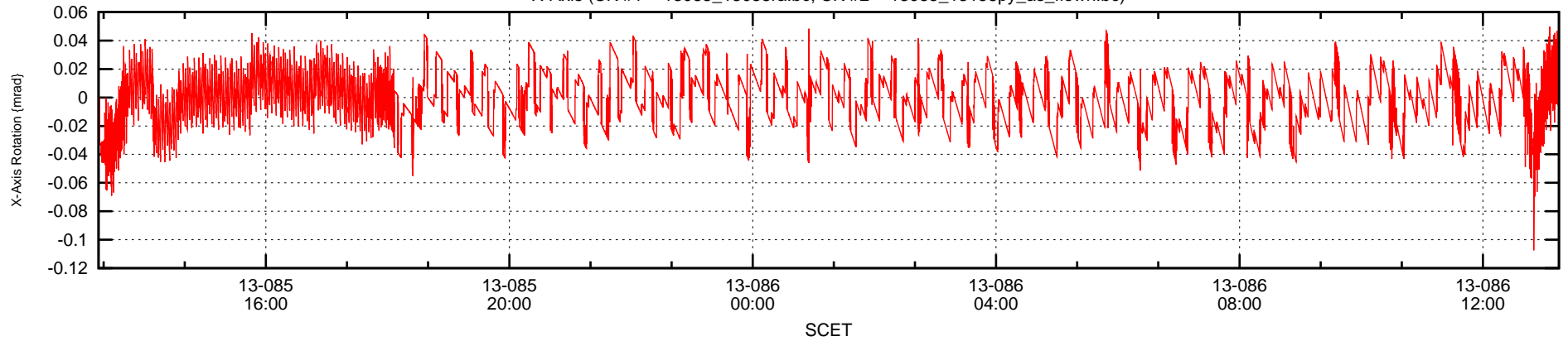


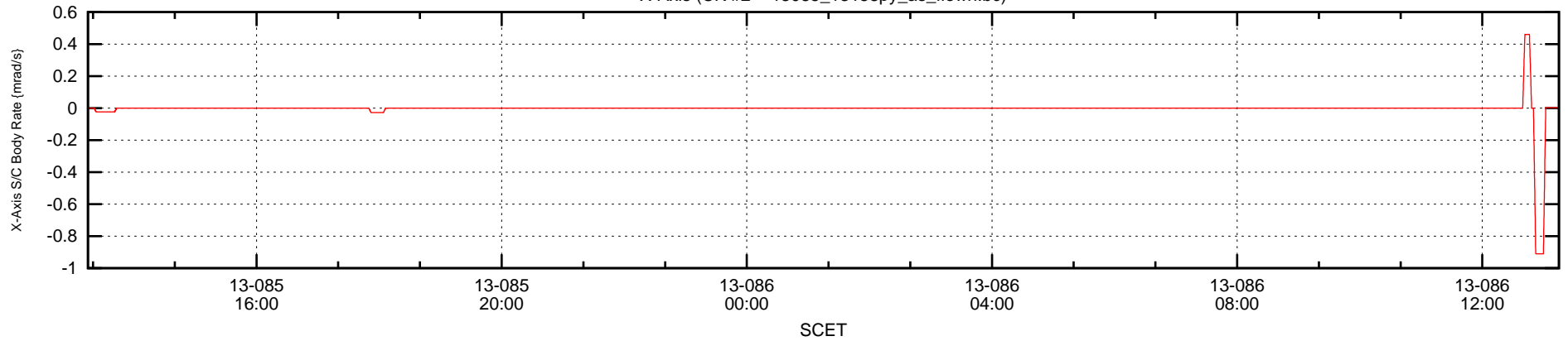
# Rotation From CK #2 to CK #1 (DOY 085-086)

X-Axis (CK #1 = 13083\_13088ra.bc; CK #2 = 13085\_13158py\_as\_flow.n.bc)

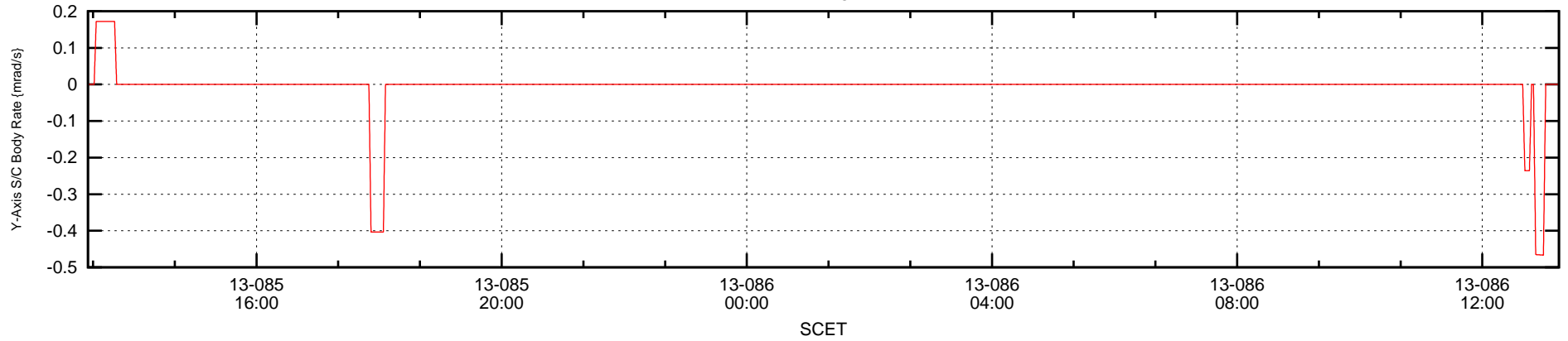


# CK #2 S/C Body Rates (DOY 085-086)

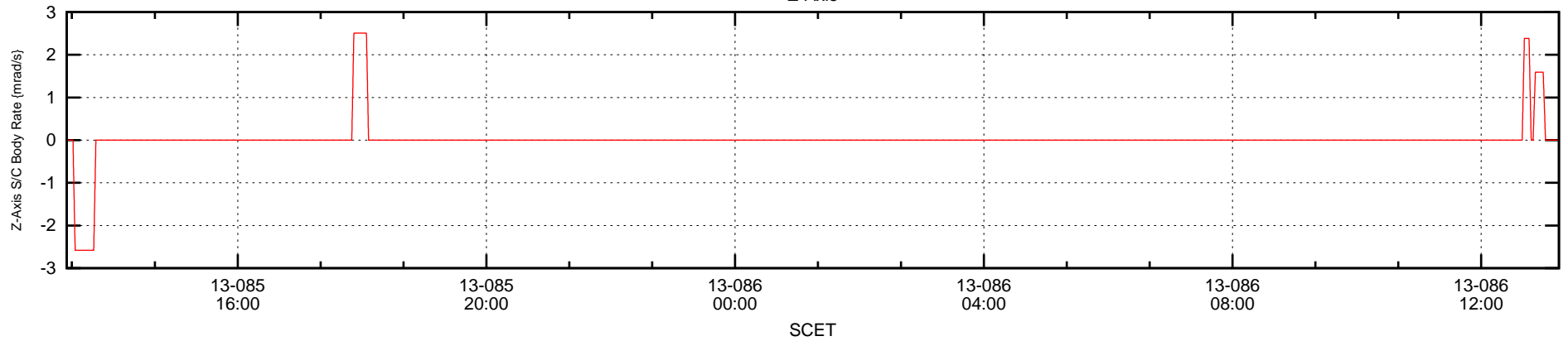
X-Axis (CK #2 = 13085\_13158py\_as\_flowm.bc)



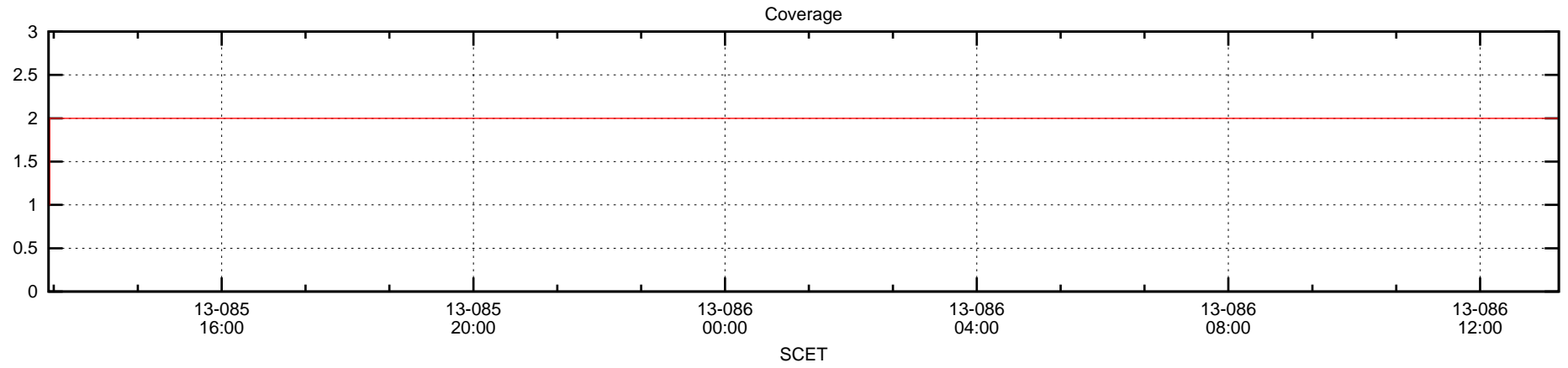
Y-Axis



Z-Axis

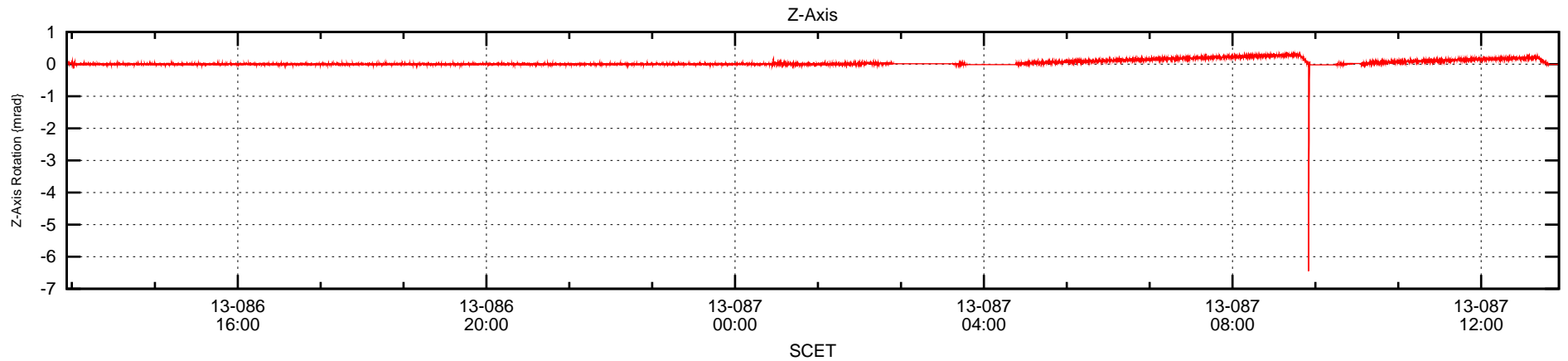
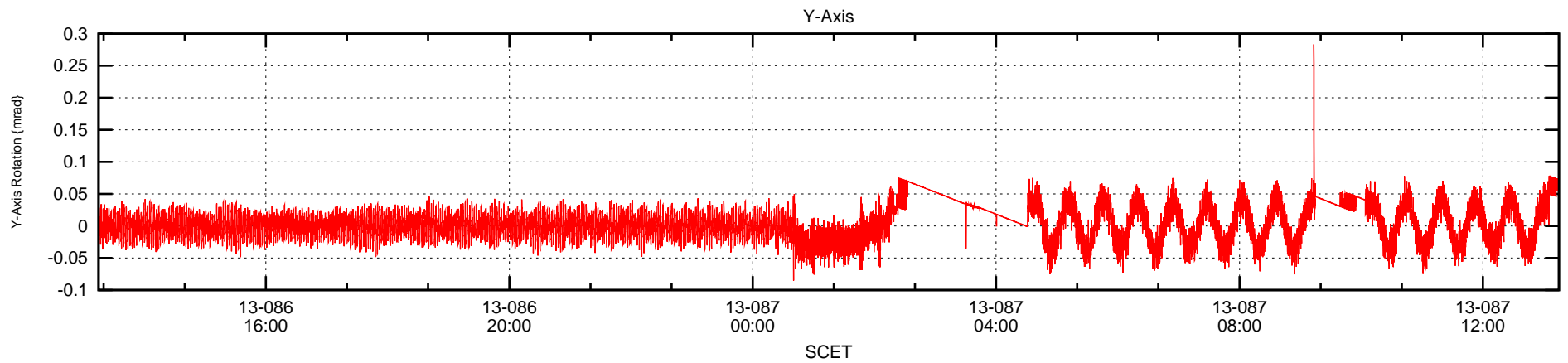
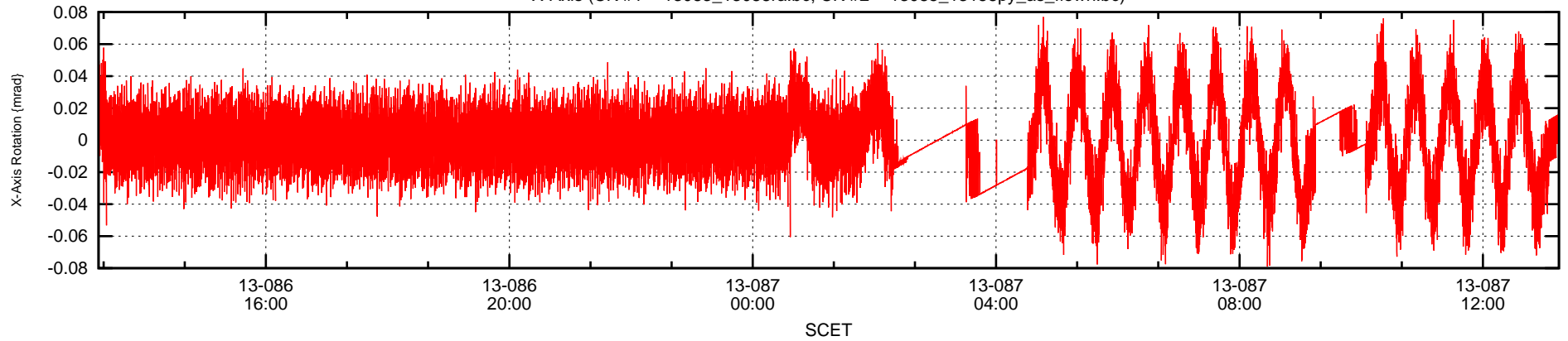


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 085-086)



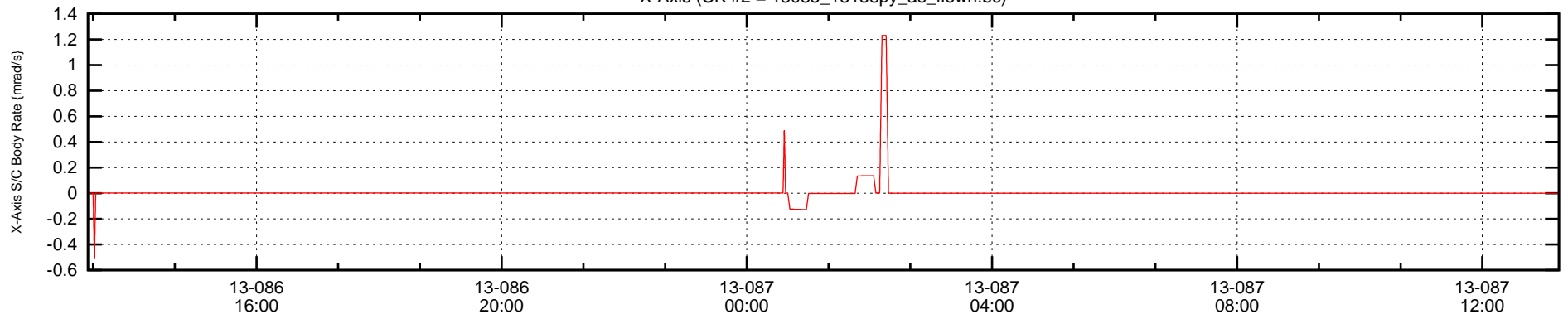
# Rotation From CK #2 to CK #1 (DOY 086-087)

X-Axis (CK #1 = 13083\_13088ra.bc; CK #2 = 13085\_13158py\_as\_flowm.bc)



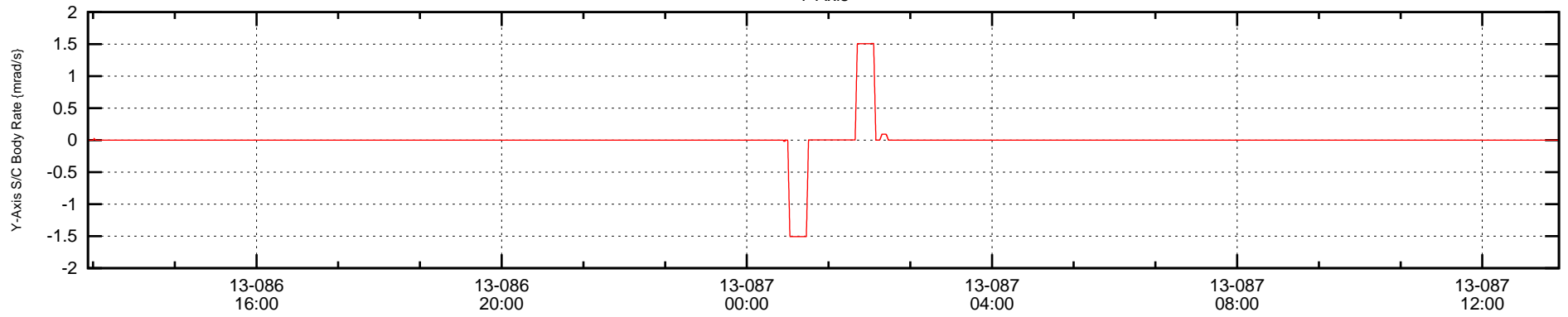
# CK #2 S/C Body Rates (DOY 086-087)

X-Axis (CK #2 = 13085\_13158py\_as\_flowm.bc)



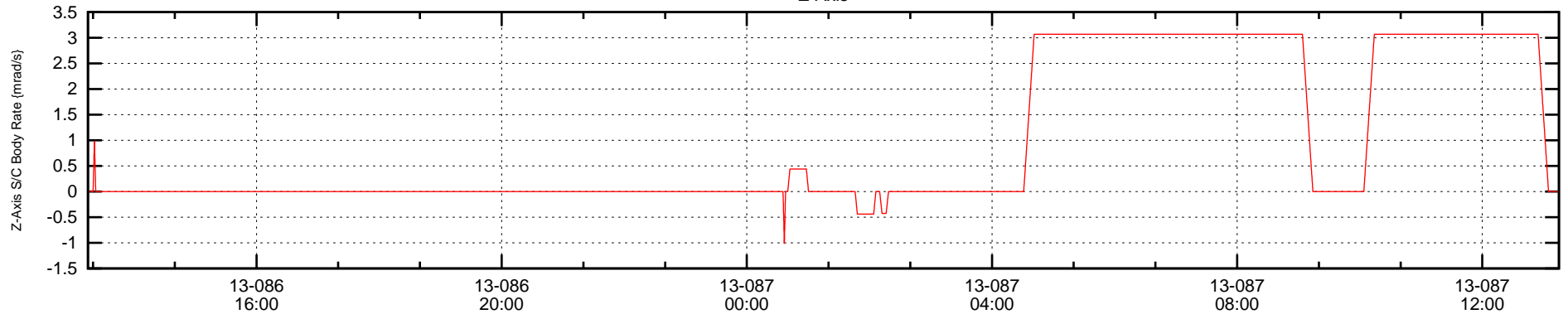
SCET

Y-Axis



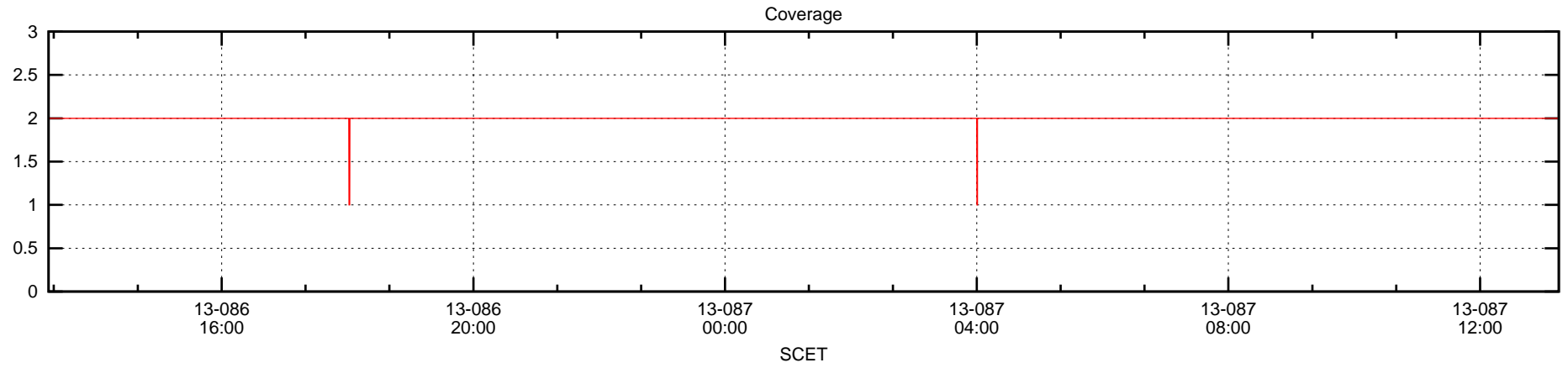
SCET

Z-Axis



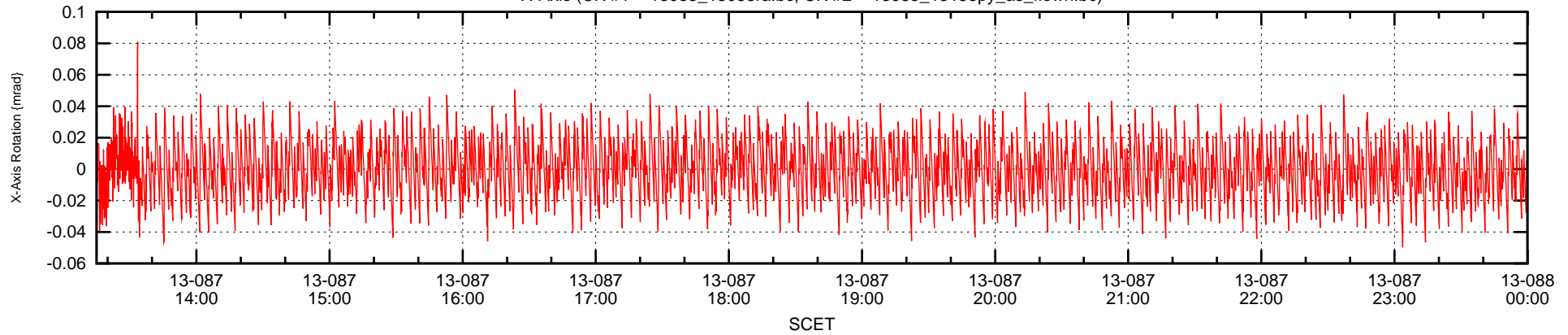
SCET

All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 086-087)

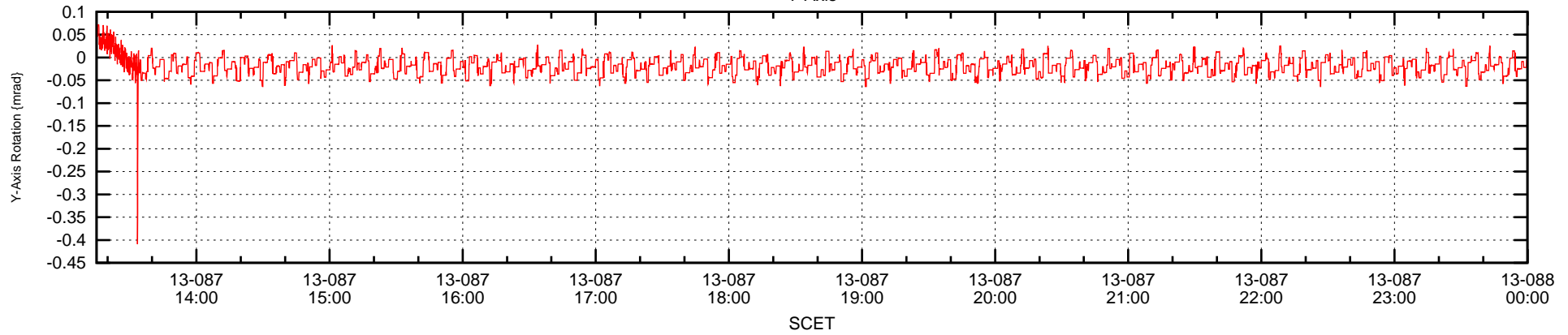


# Rotation From CK #2 to CK #1 (DOY 087-087)

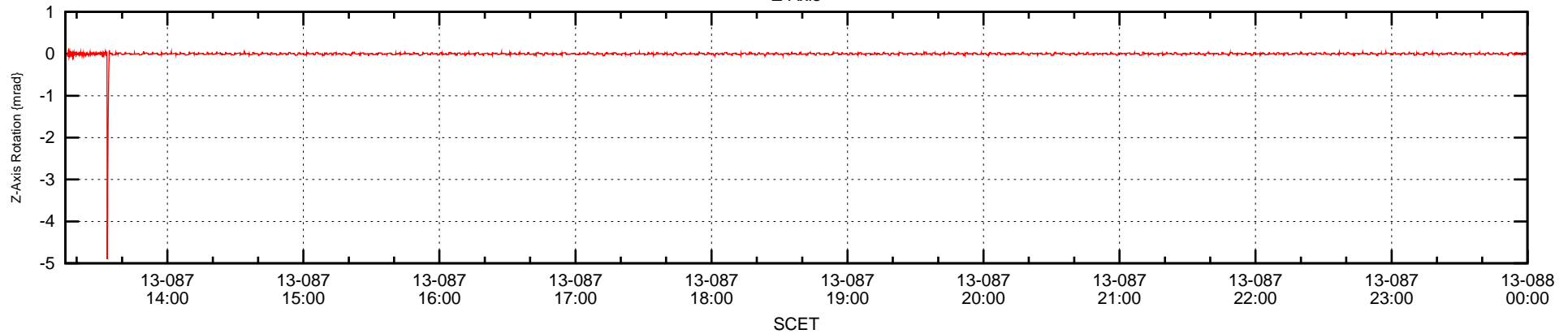
X-Axis (CK #1 = 13083\_13088ra.bc; CK #2 = 13085\_13158py\_as\_flown.bc)



Y-Axis

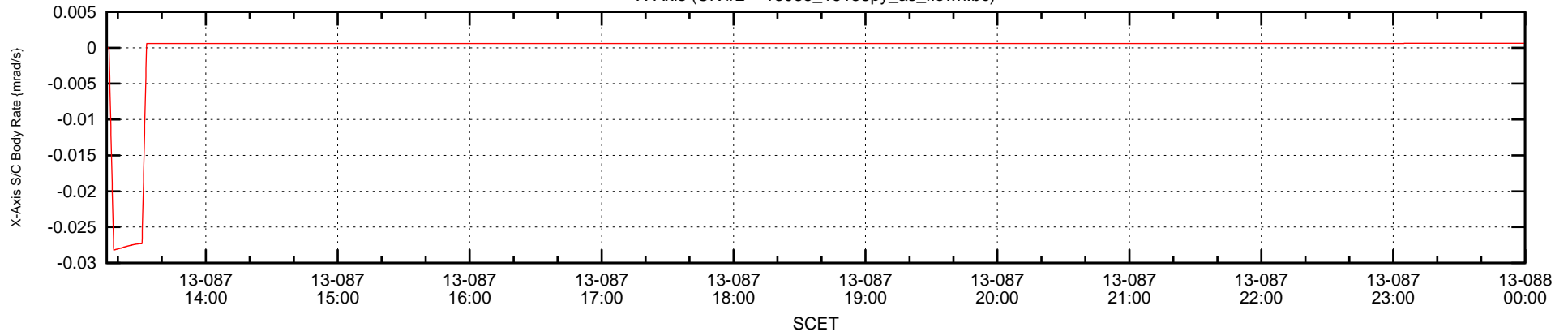


Z-Axis

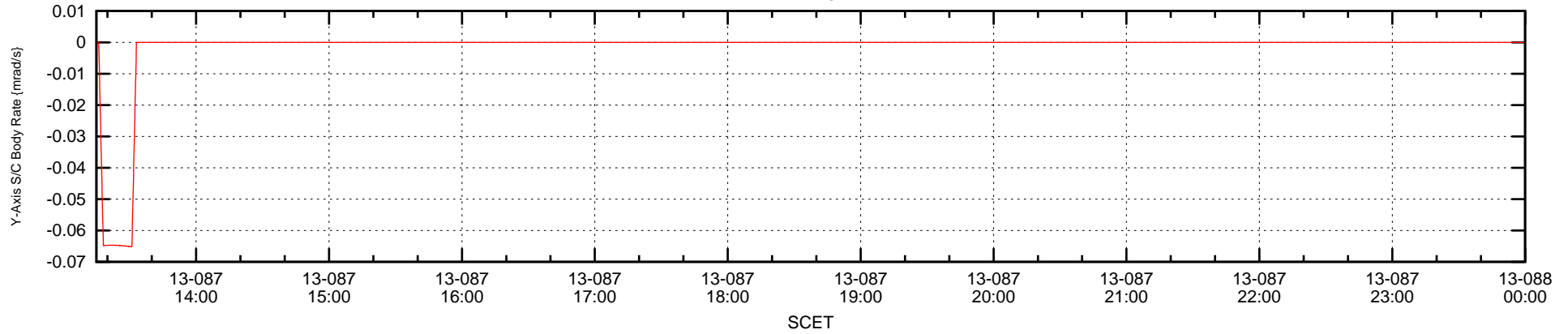


# CK #2 S/C Body Rates (DOY 087-087)

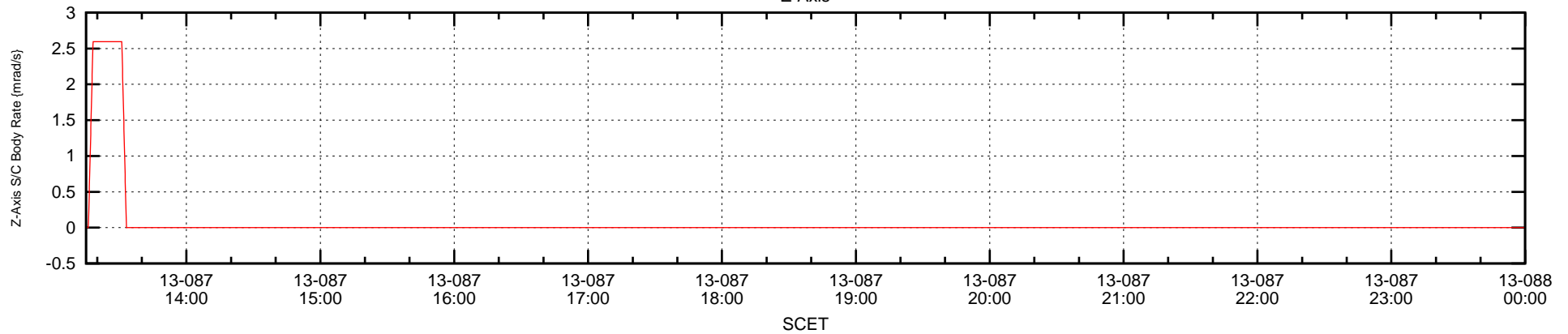
X-Axis (CK #2 = 13085\_13158py\_as\_flowm.bc)



Y-Axis



Z-Axis





All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 087-087)

