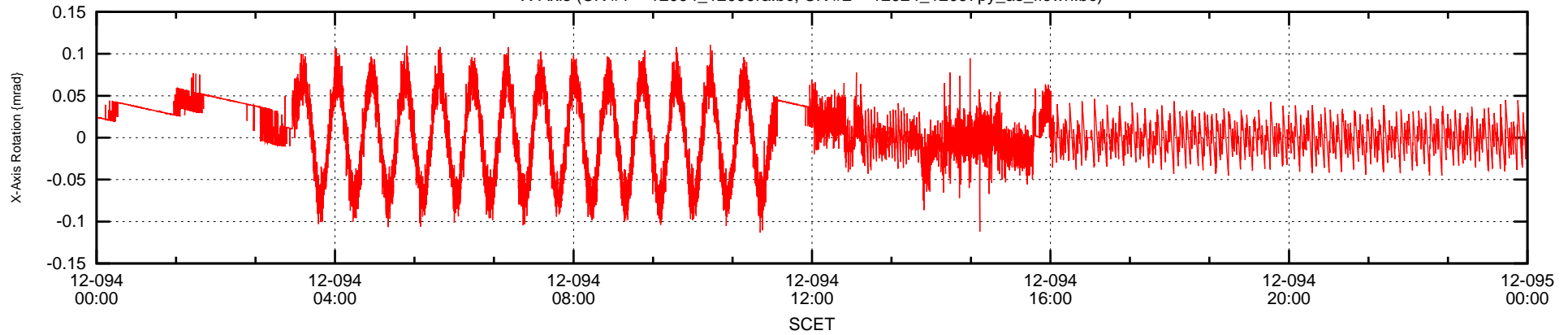
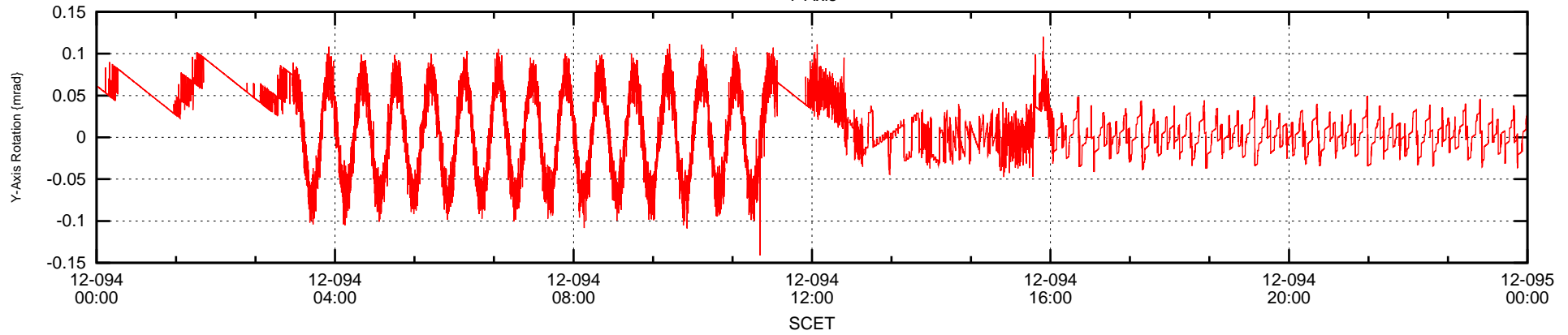


# Rotation From CK #2 to CK #1 (DOY 094-095)

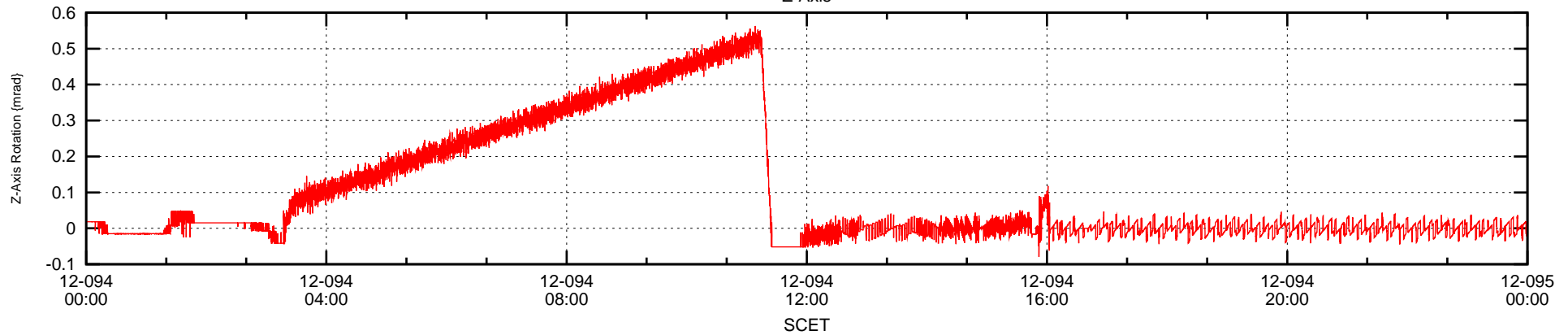
X-Axis (CK #1 = 12094\_12099ra.bc; CK #2 = 12024\_12097py\_as\_flowm.bc)



Y-Axis

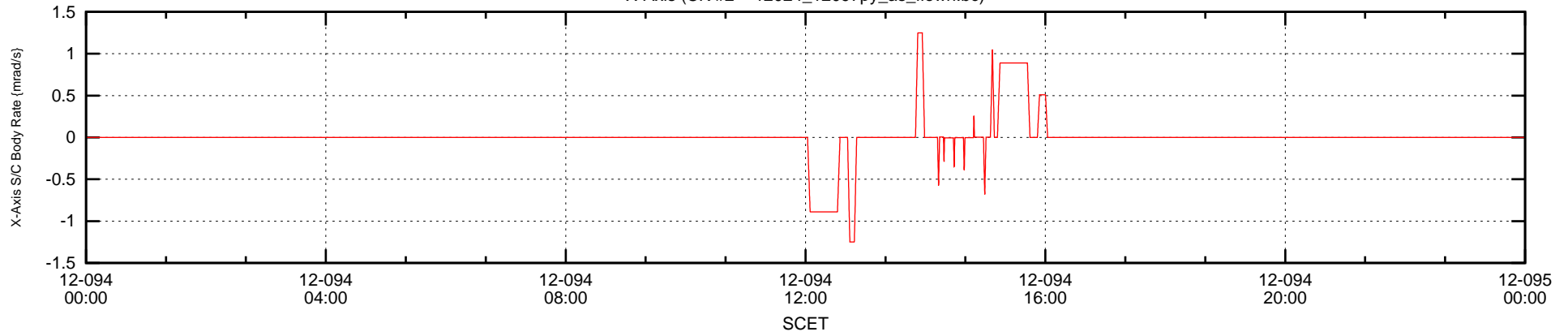


Z-Axis

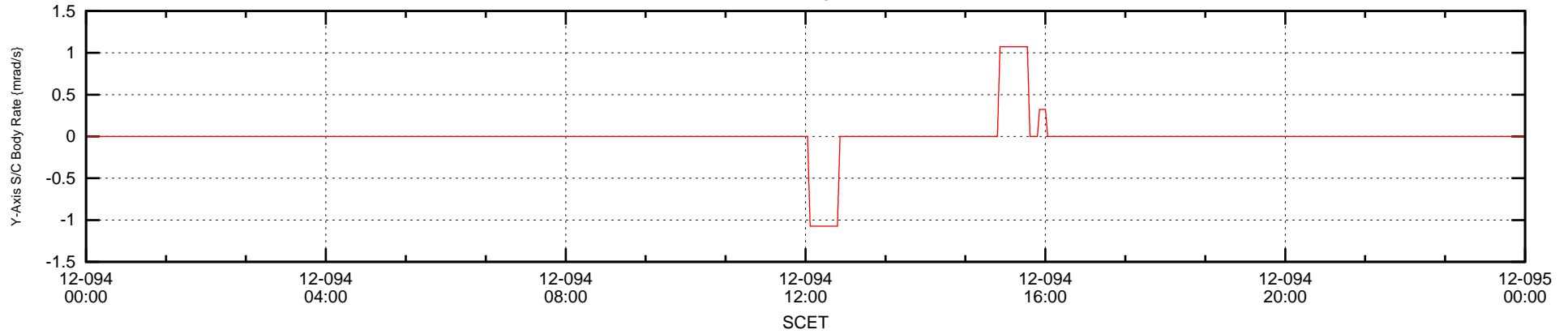


# CK #2 S/C Body Rates (DOY 094-095)

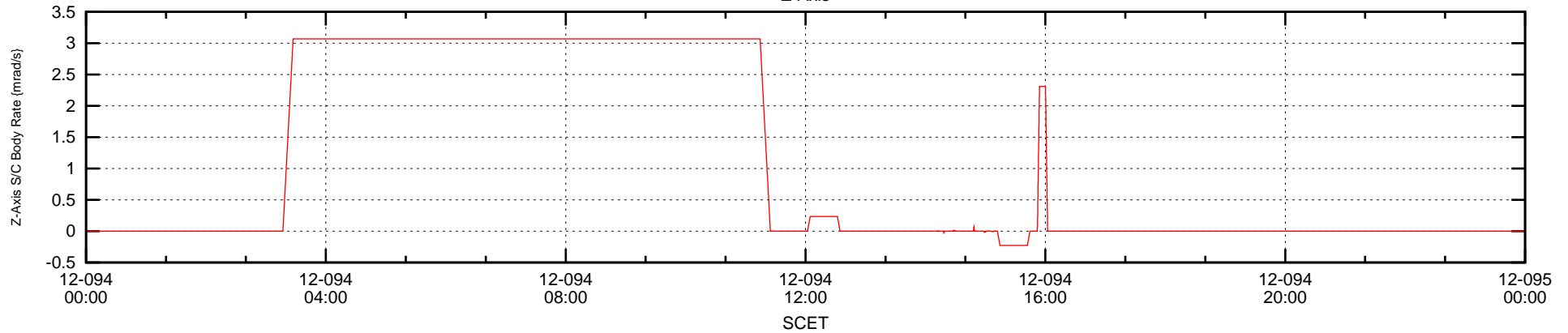
X-Axis (CK #2 = 12024\_12097py\_as\_flown.bc)



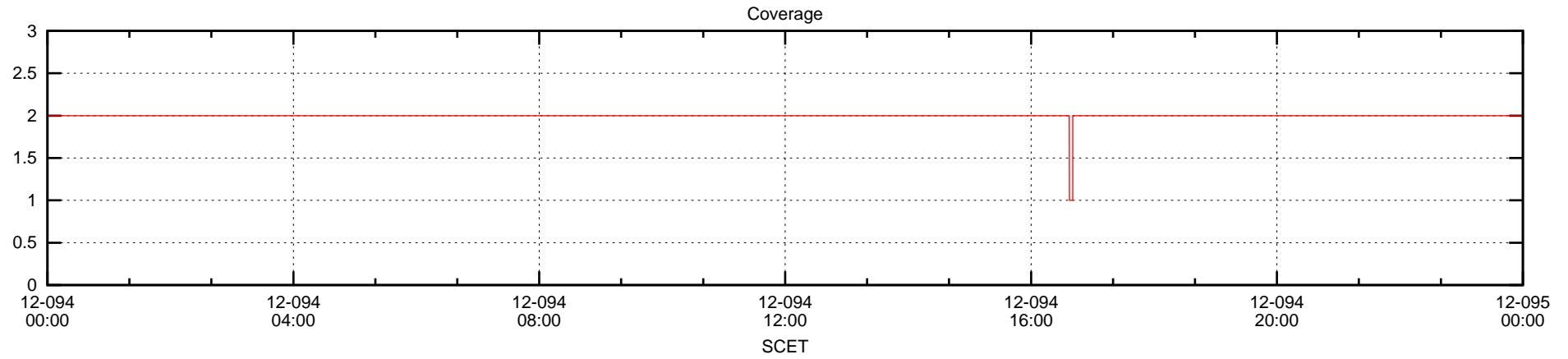
Y-Axis



Z-Axis

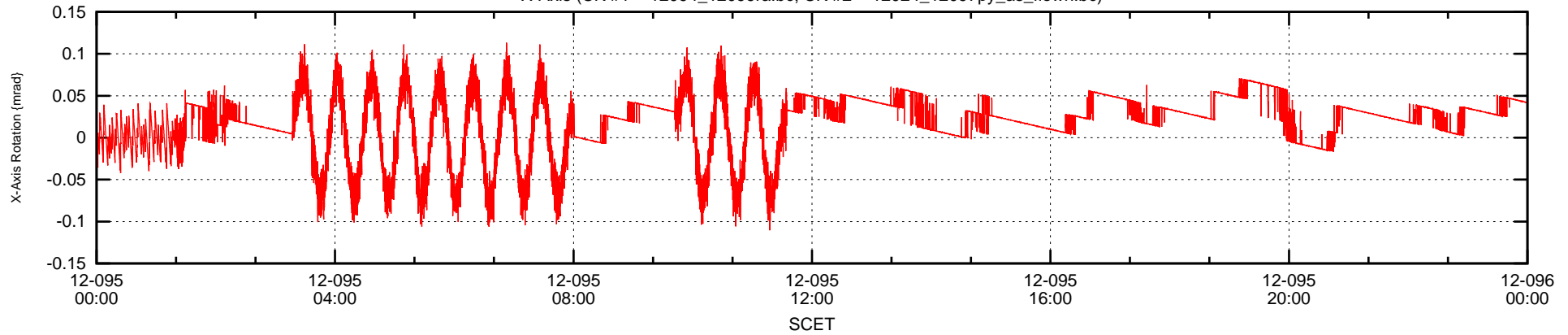


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 094-095)

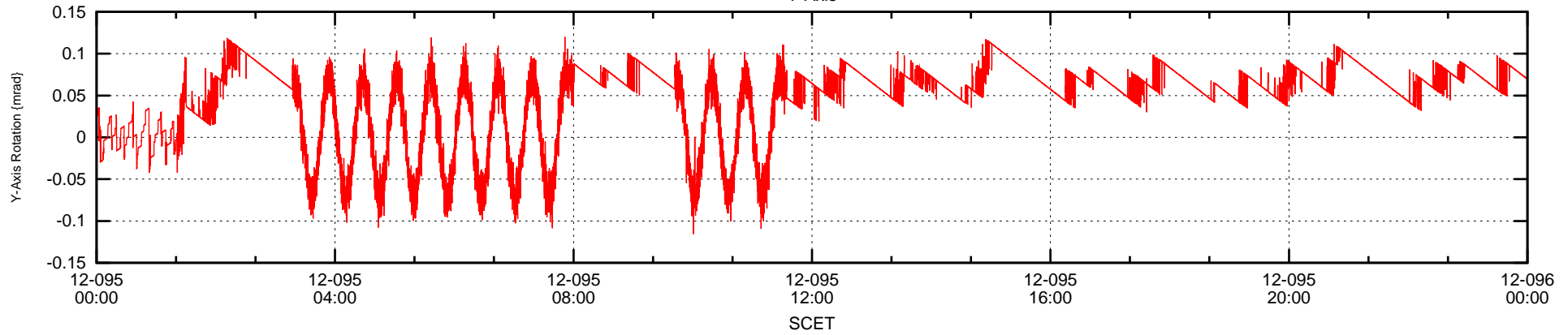


# Rotation From CK #2 to CK #1 (DOY 095-096)

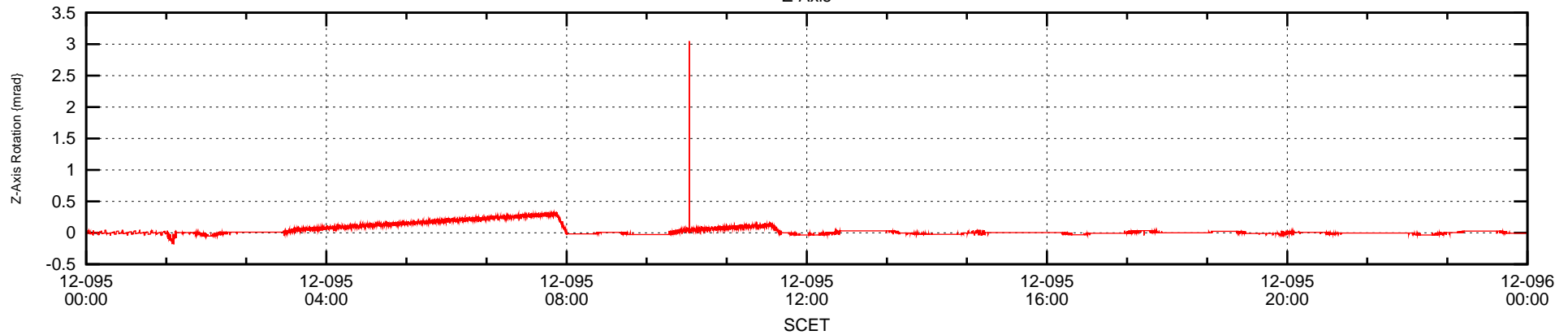
X-Axis (CK #1 = 12094\_12099ra.bc; CK #2 = 12024\_12097py\_as\_flowm.bc)



Y-Axis

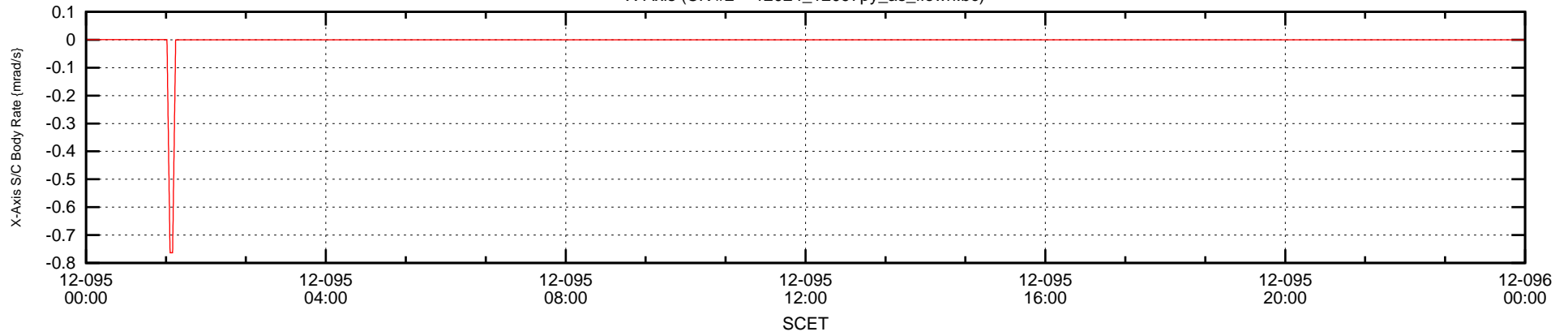


Z-Axis

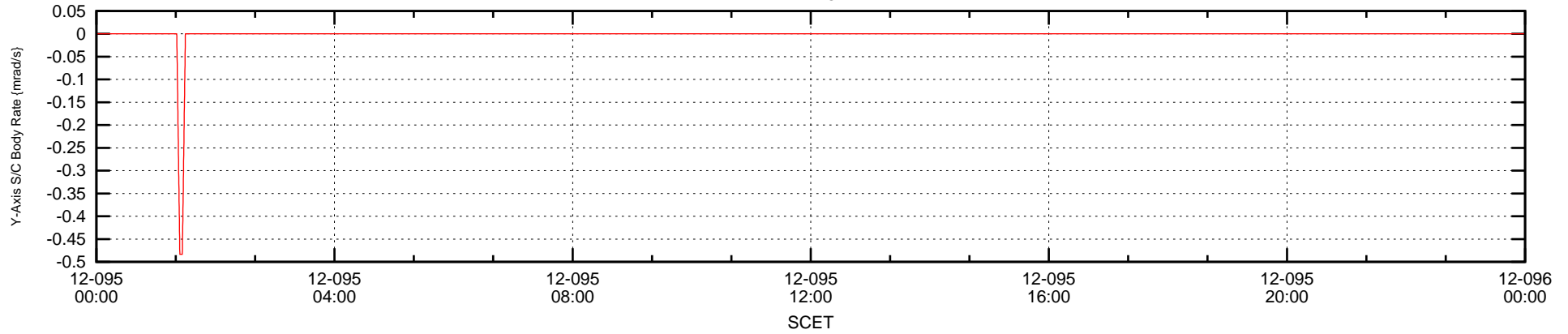


# CK #2 S/C Body Rates (DOY 095-096)

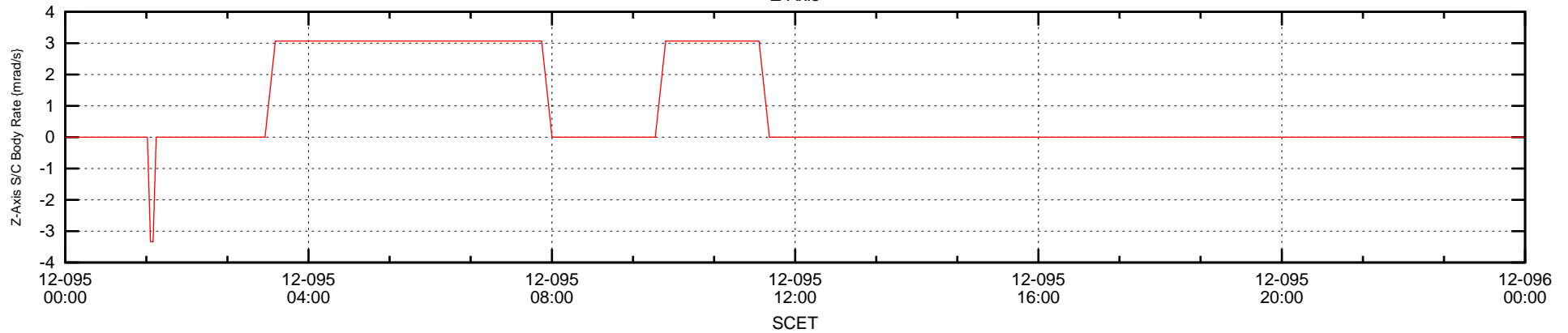
X-Axis (CK #2 = 12024\_12097py\_as\_flown.bc)



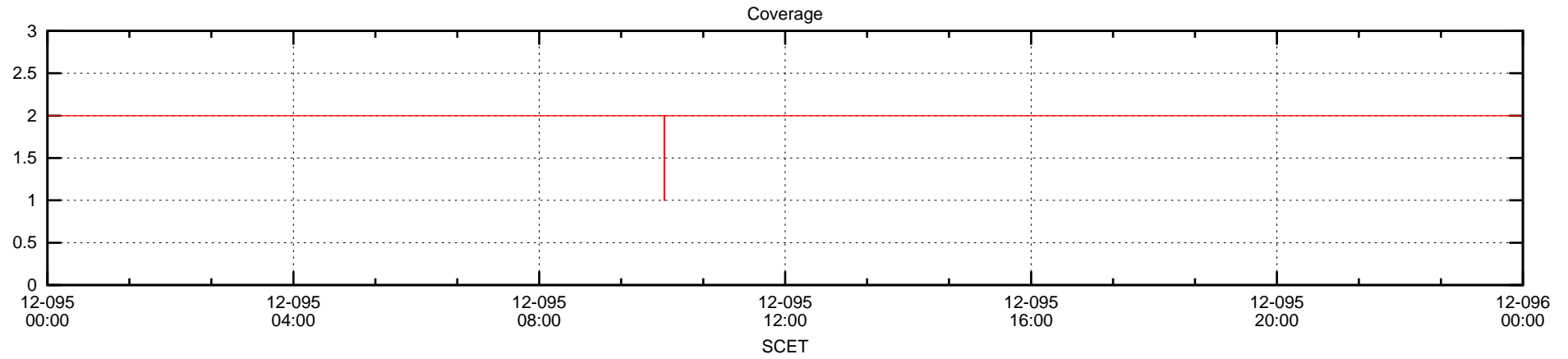
Y-Axis



Z-Axis

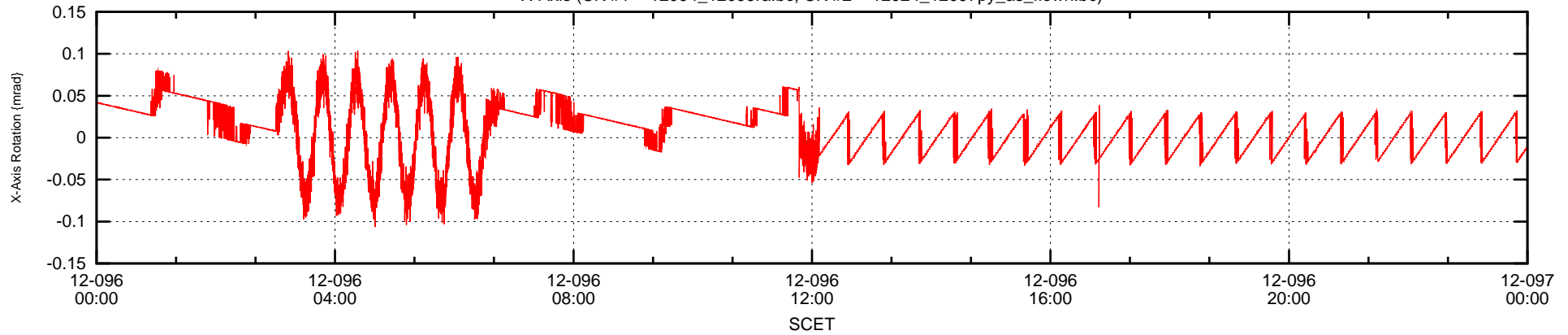


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 095-096)

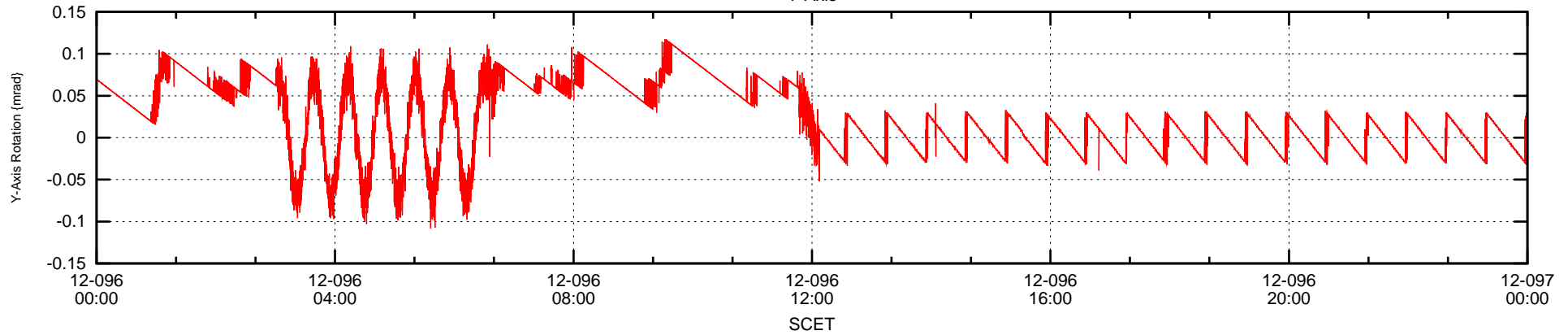


# Rotation From CK #2 to CK #1 (DOY 096-097)

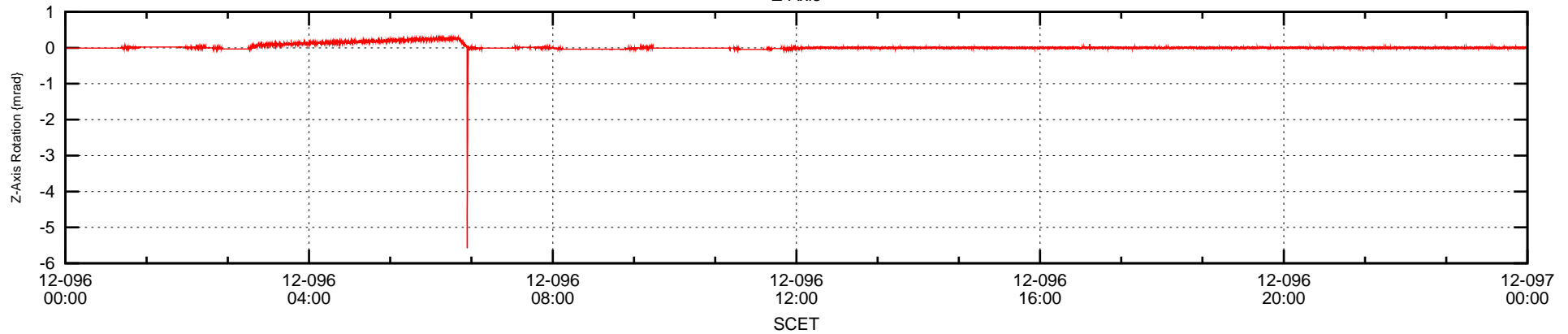
X-Axis (CK #1 = 12094\_12099ra.bc; CK #2 = 12024\_12097py\_as\_flown.bc)



Y-Axis

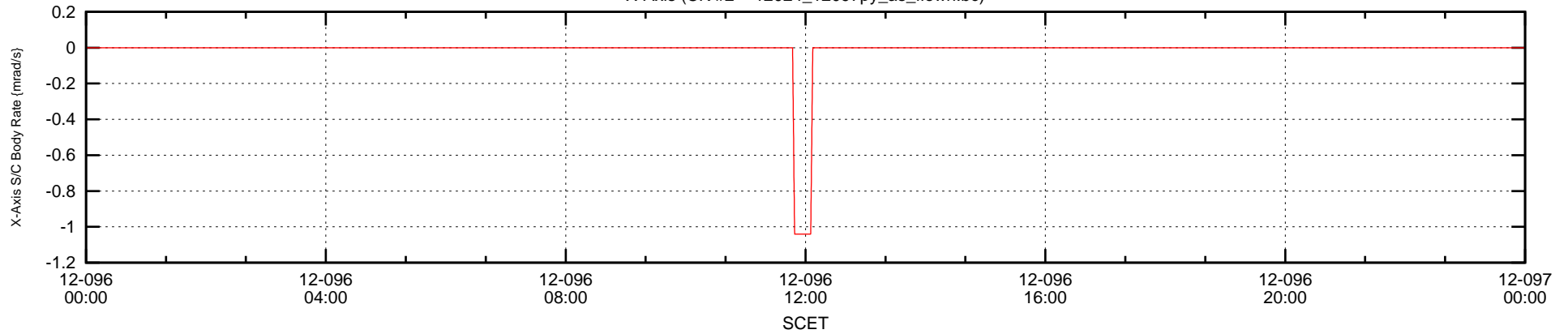


Z-Axis

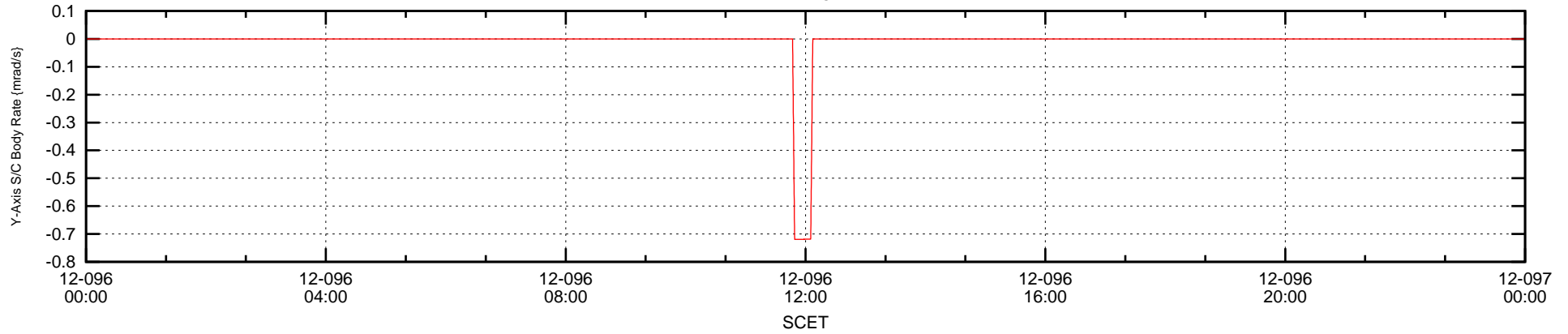


# CK #2 S/C Body Rates (DOY 096-097)

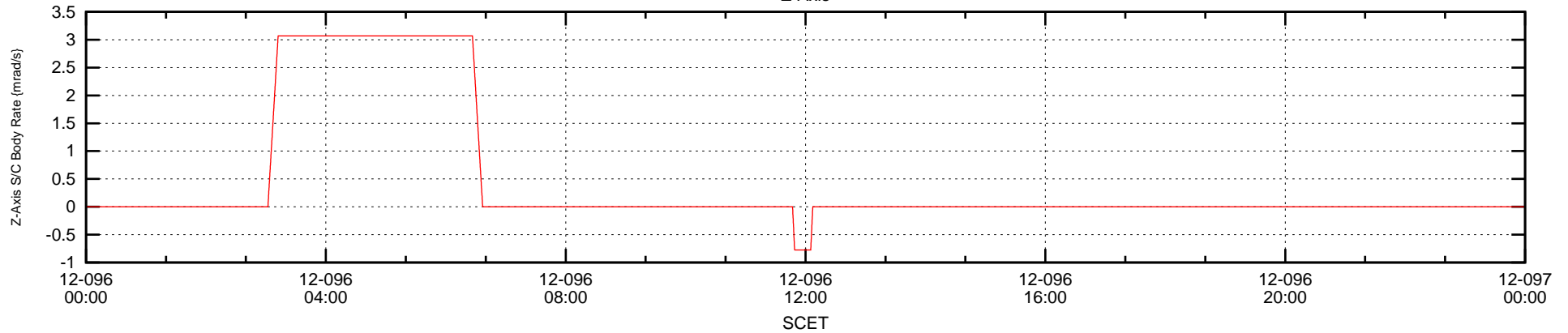
X-Axis (CK #2 = 12024\_12097py\_as\_flowm.bc)



Y-Axis

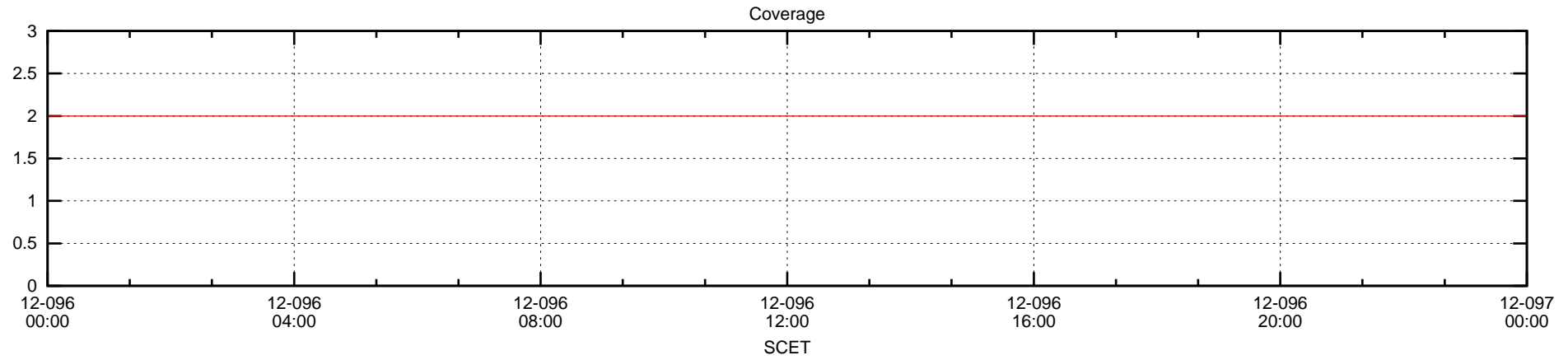


Z-Axis



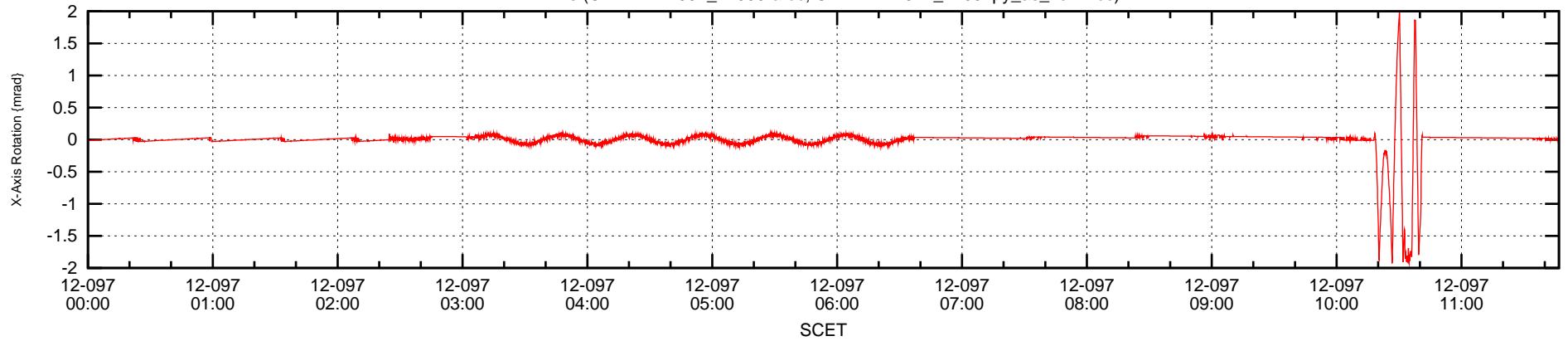


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 096-097)

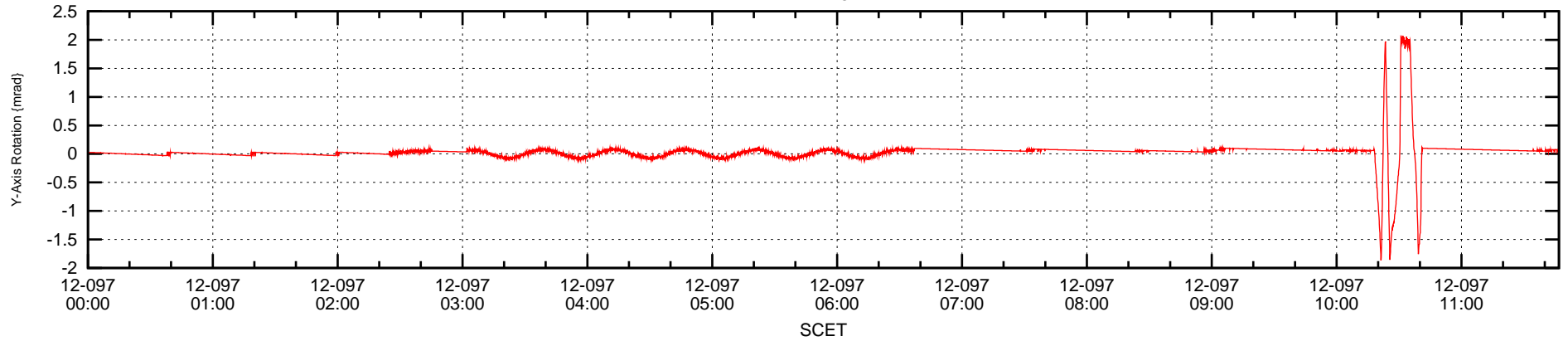


# Rotation From CK #2 to CK #1 (DOY 097-097)

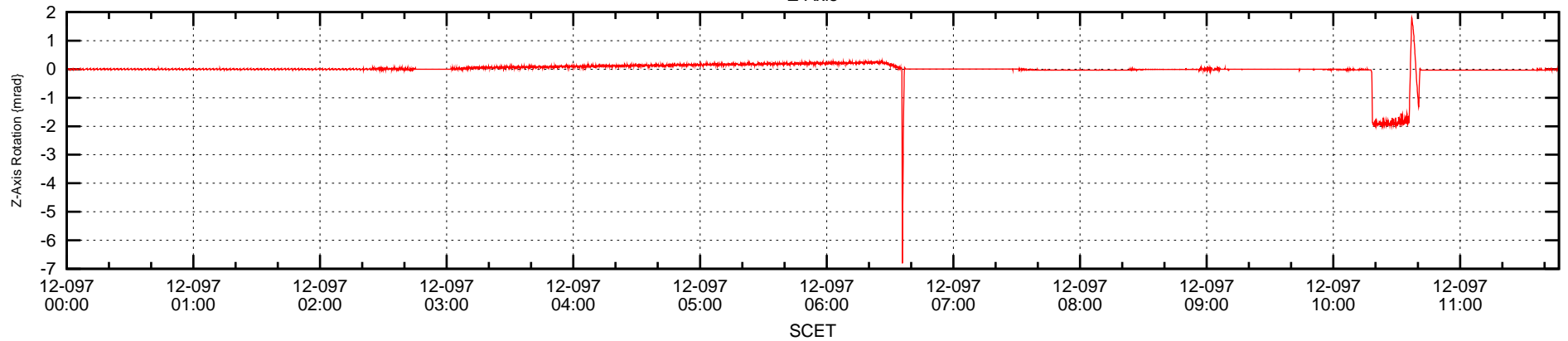
X-Axis (CK #1 = 12094\_12099ra.bc; CK #2 = 12024\_12097py\_as\_flown.bc)



Y-Axis

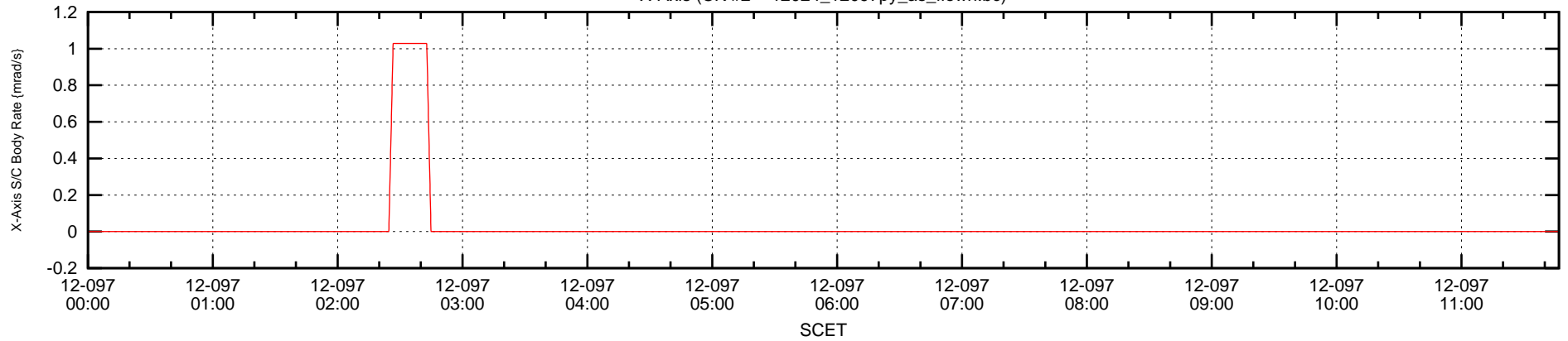


Z-Axis

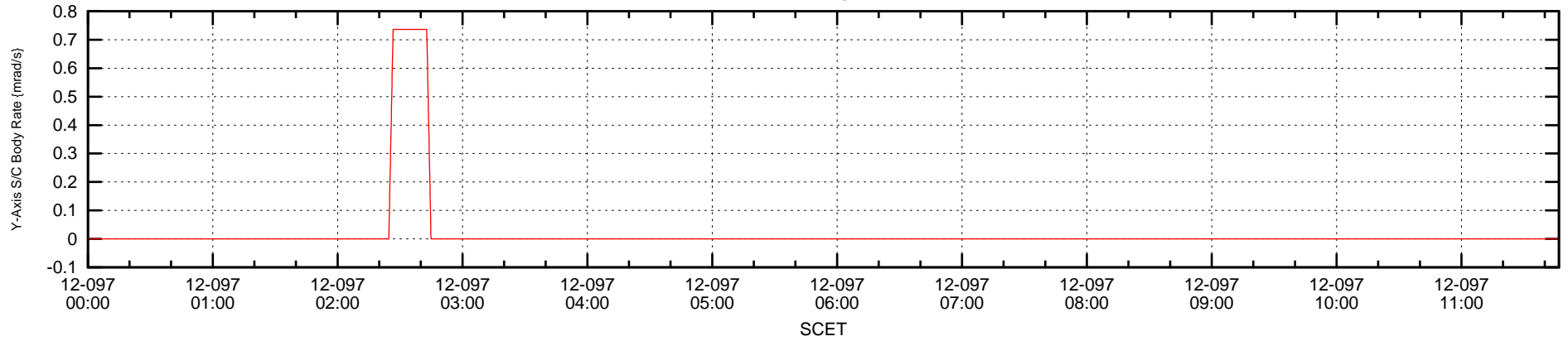


# CK #2 S/C Body Rates (DOY 097-097)

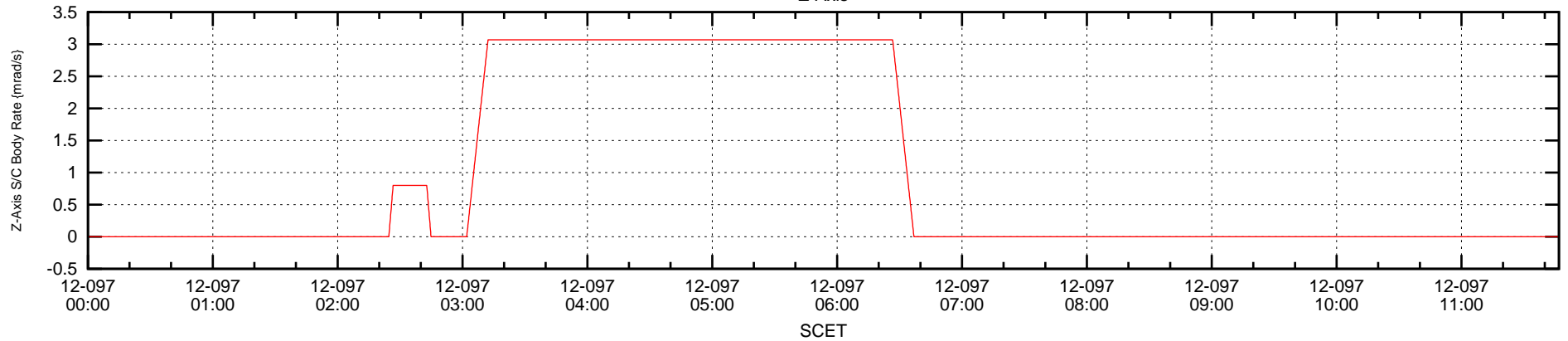
X-Axis (CK #2 = 12024\_12097py\_as\_flowm.bc)



Y-Axis



Z-Axis



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 097-097)

