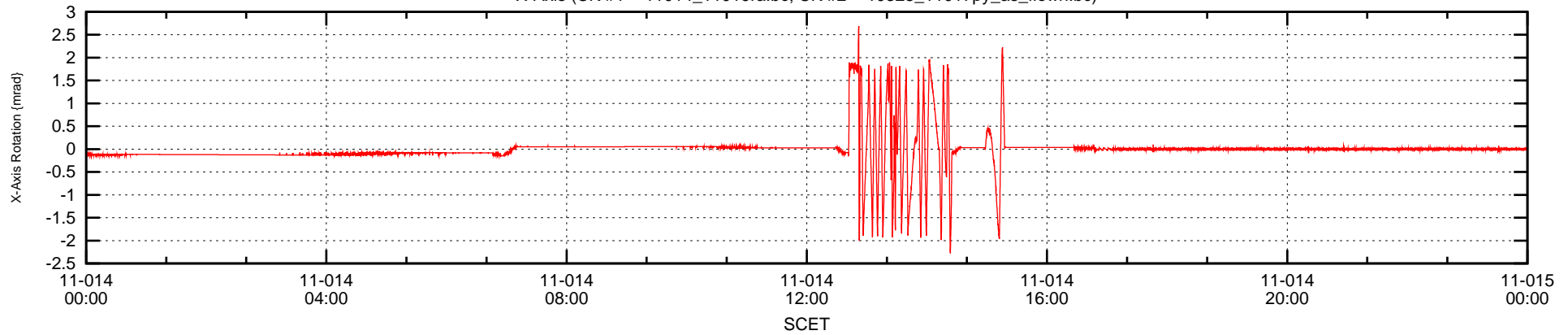
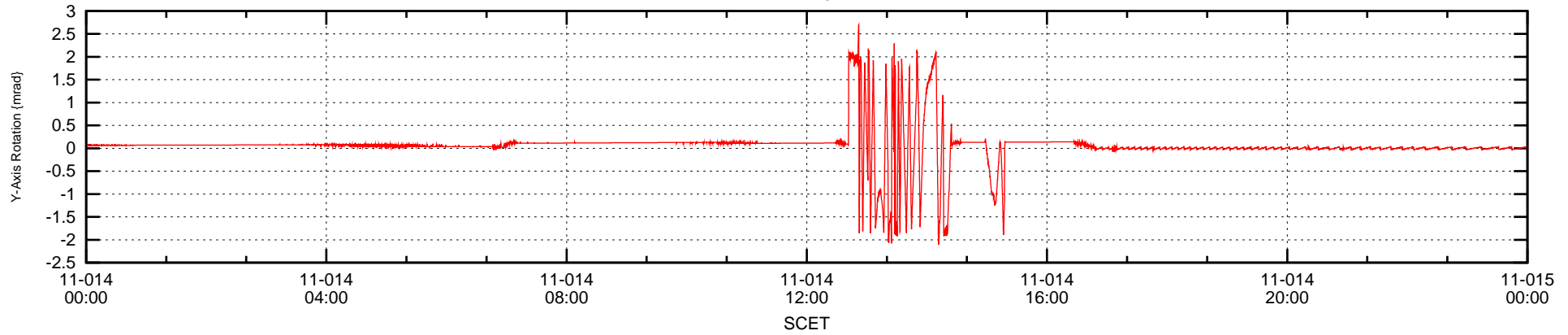


# Rotation From CK #2 to CK #1 (DOY 014-015)

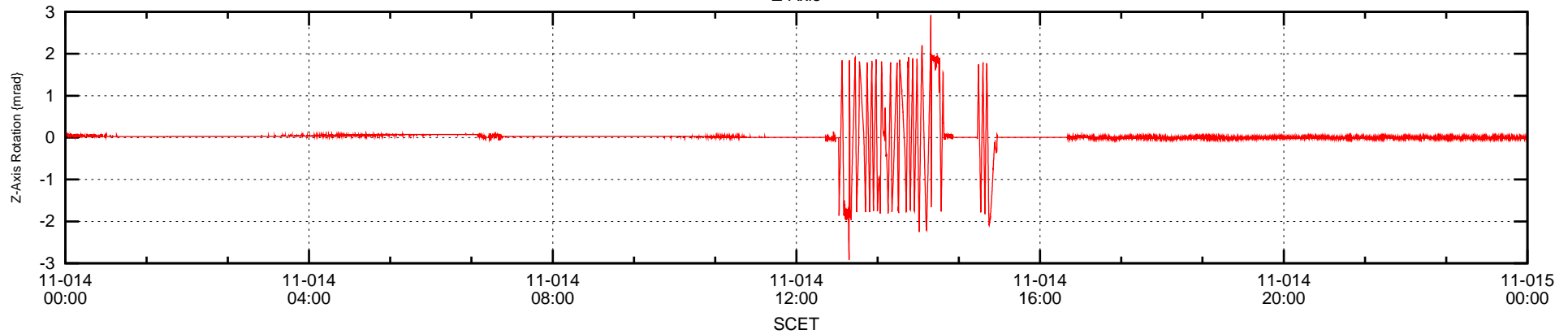
X-Axis (CK #1 = 11014\_11019ra.bc; CK #2 = 10328\_11017py\_as\_flowm.bc)



Y-Axis

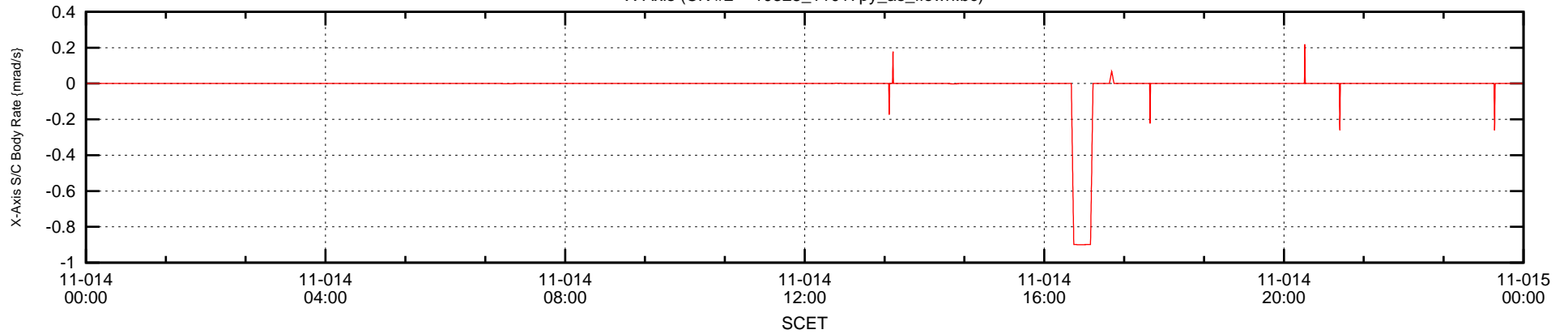


Z-Axis

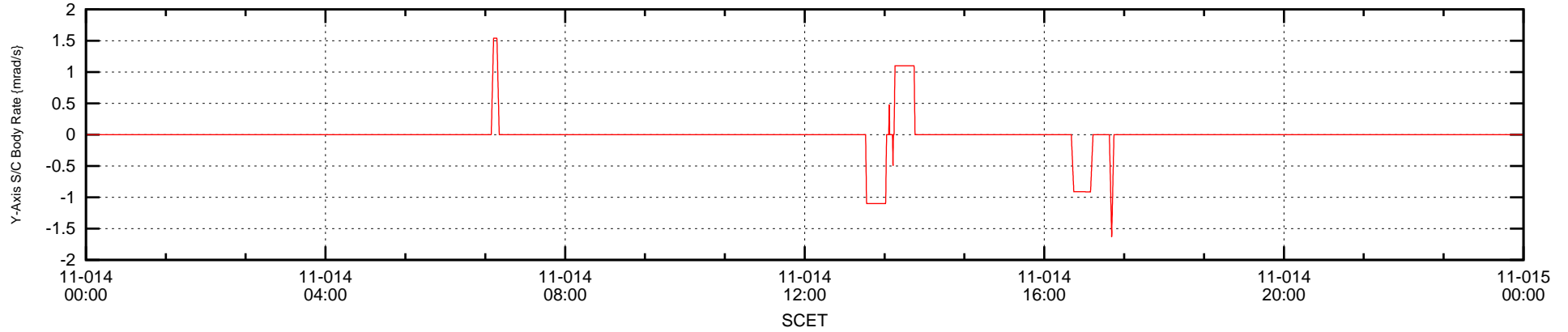


# CK #2 S/C Body Rates (DOY 014-015)

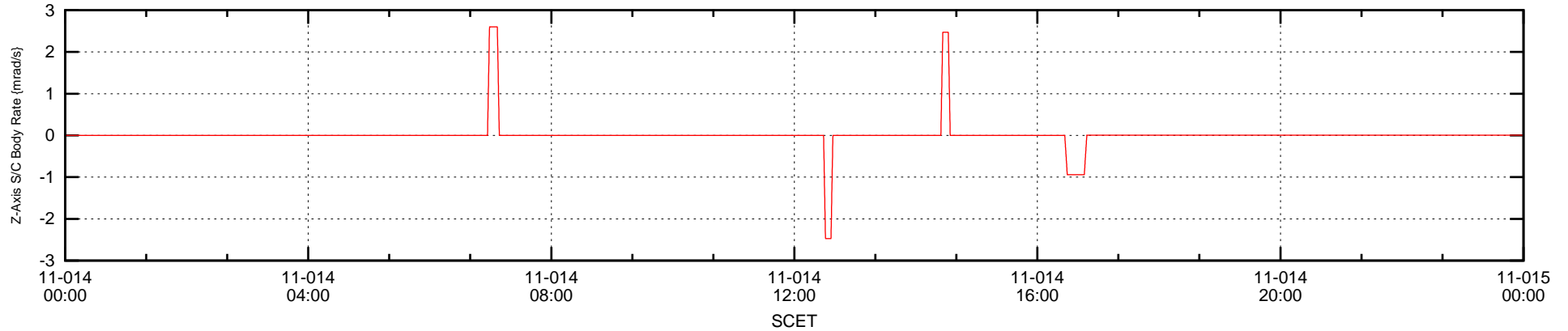
X-Axis (CK #2 = 10328\_11017py\_as\_flowm.bc)



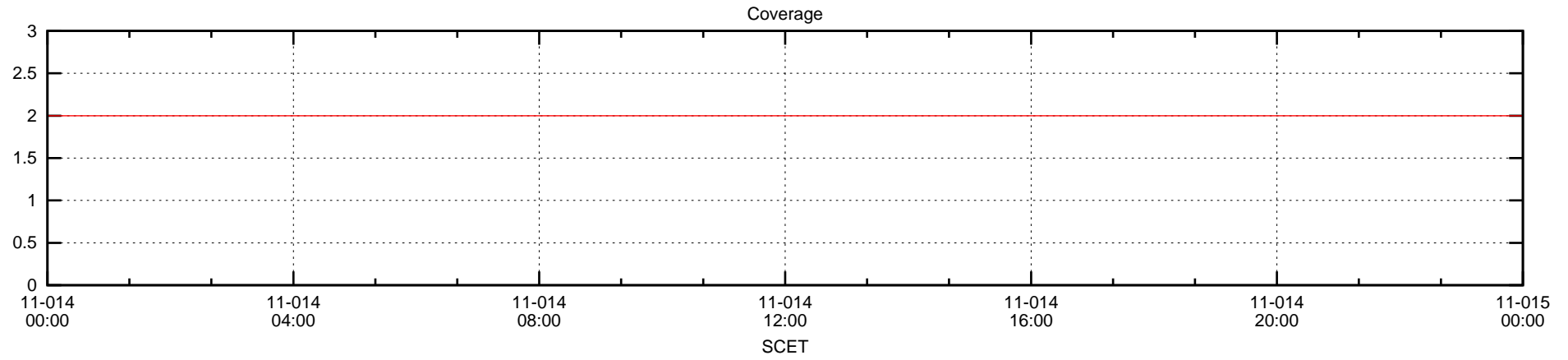
Y-Axis



Z-Axis

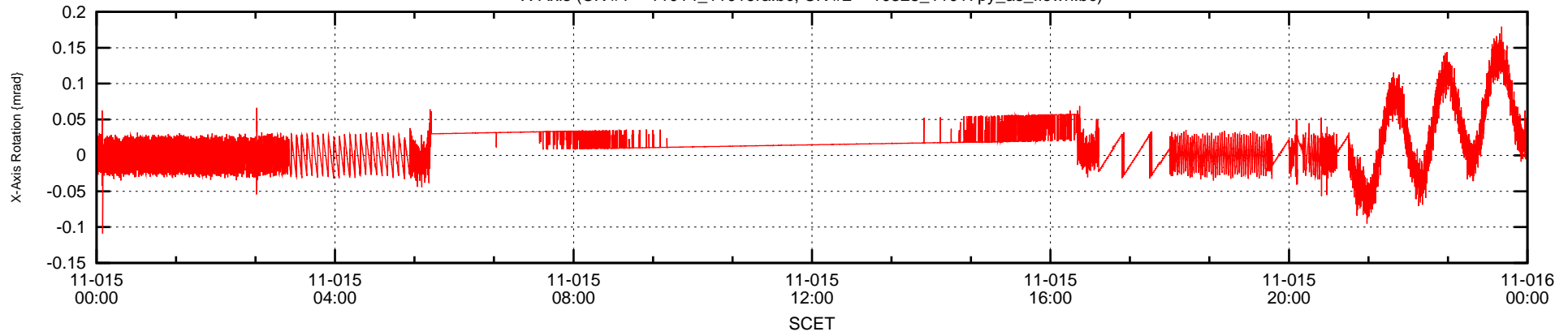


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 014-015)

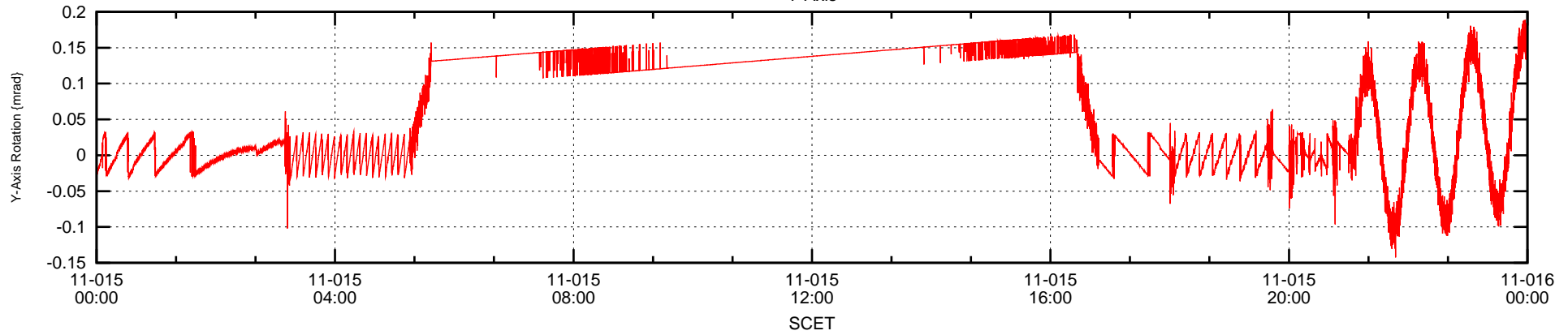


# Rotation From CK #2 to CK #1 (DOY 015-016)

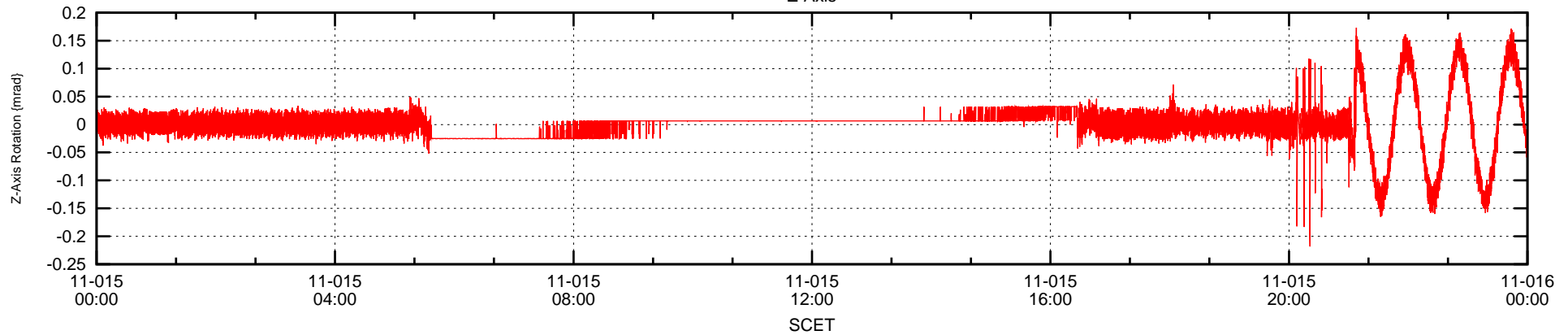
X-Axis (CK #1 = 11014\_11019ra.bc; CK #2 = 10328\_11017py\_as\_flowm.bc)



Y-Axis

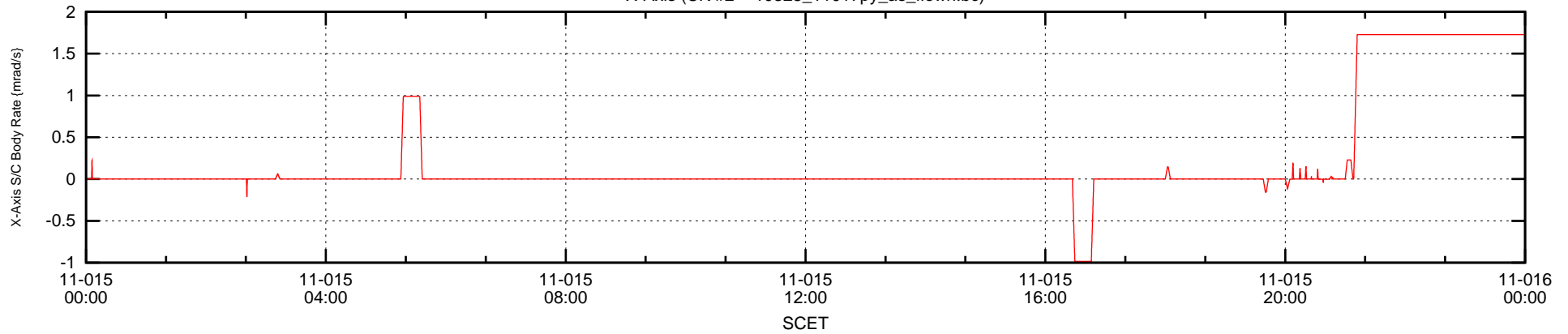


Z-Axis

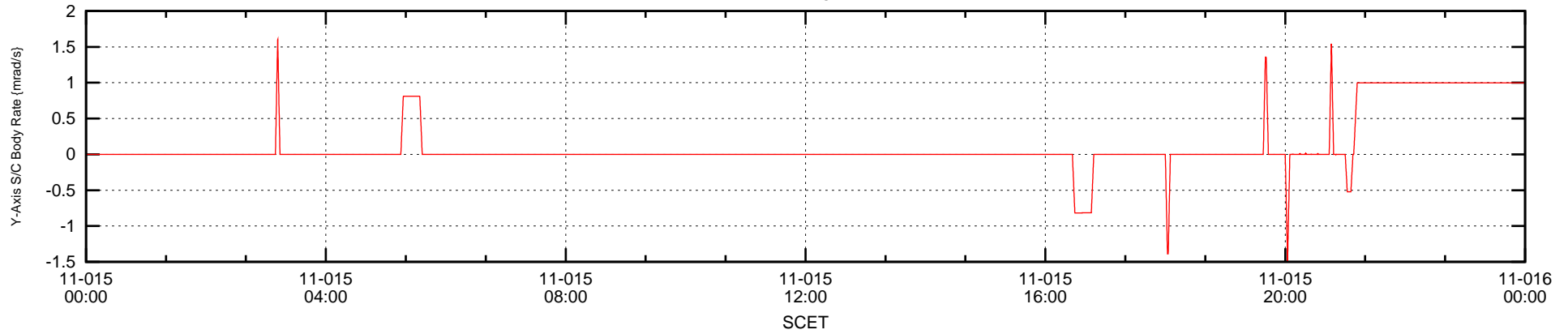


# CK #2 S/C Body Rates (DOY 015-016)

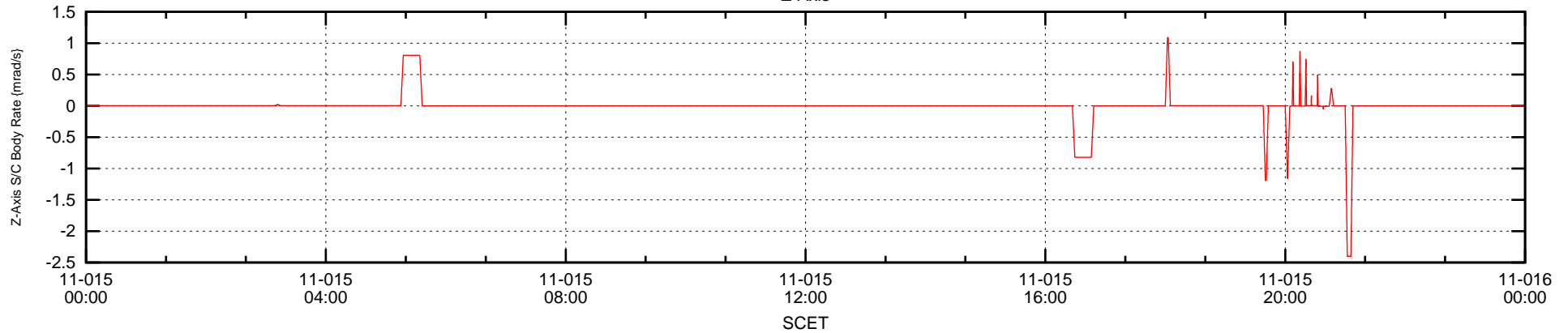
X-Axis (CK #2 = 10328\_11017py\_as\_flown.bc)



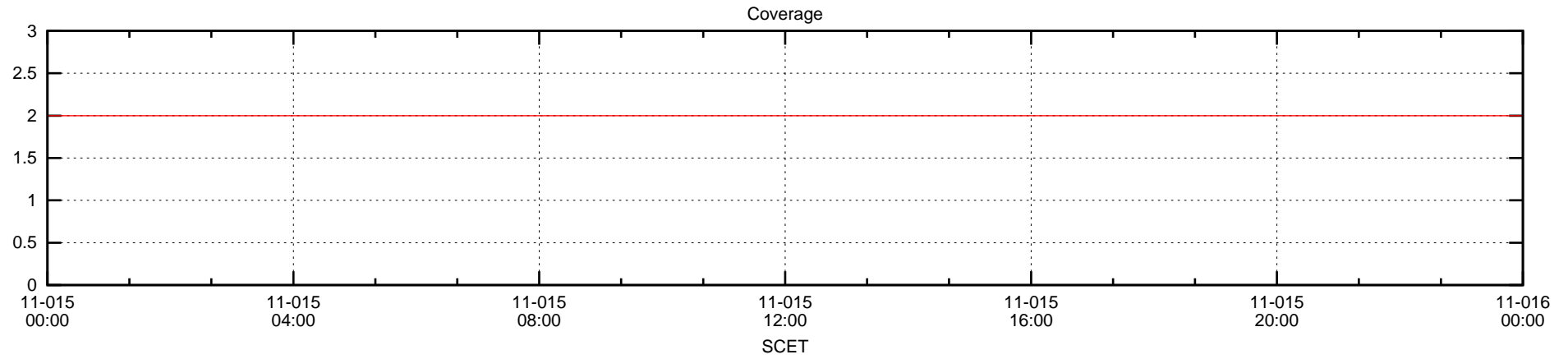
Y-Axis



Z-Axis

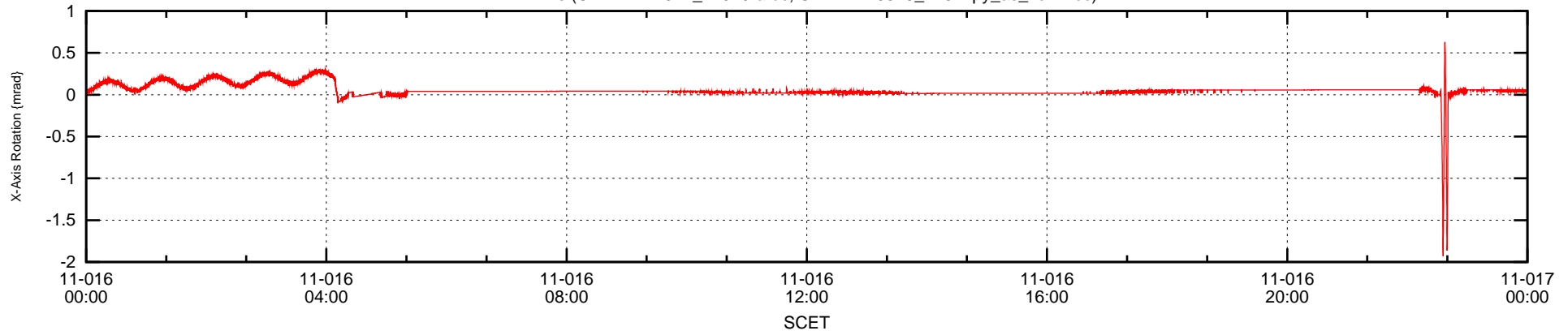


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 015-016)

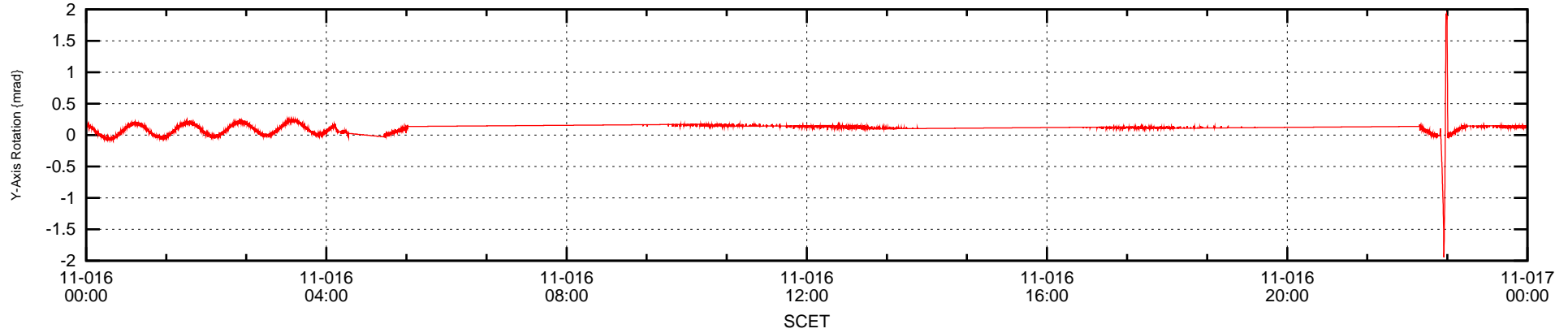


# Rotation From CK #2 to CK #1 (DOY 016-017)

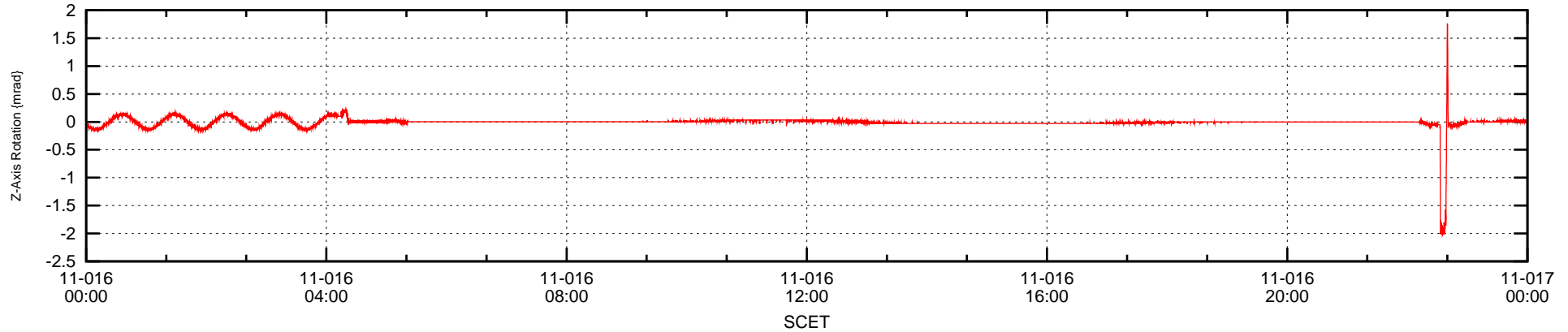
X-Axis (CK #1 = 11014\_11019ra.bc; CK #2 = 10328\_11017py\_as\_flowm.bc)



Y-Axis

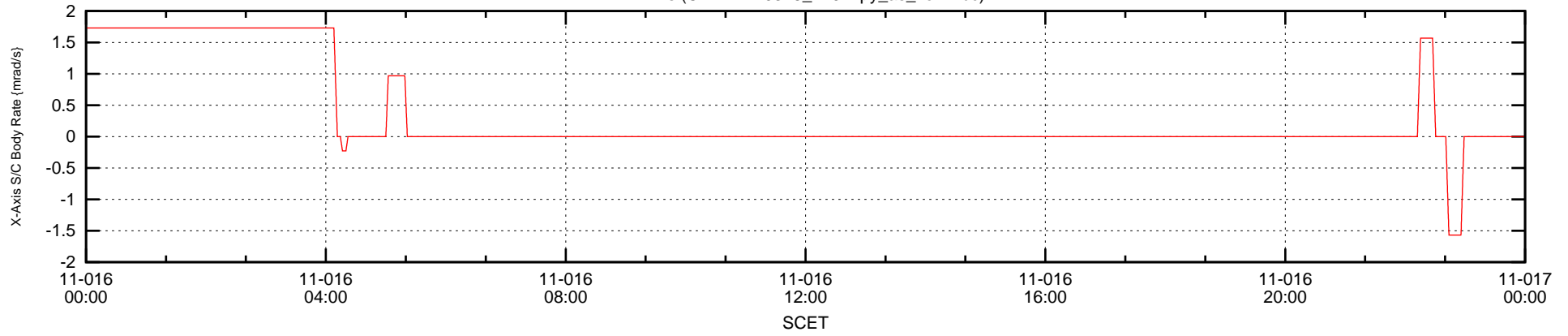


Z-Axis

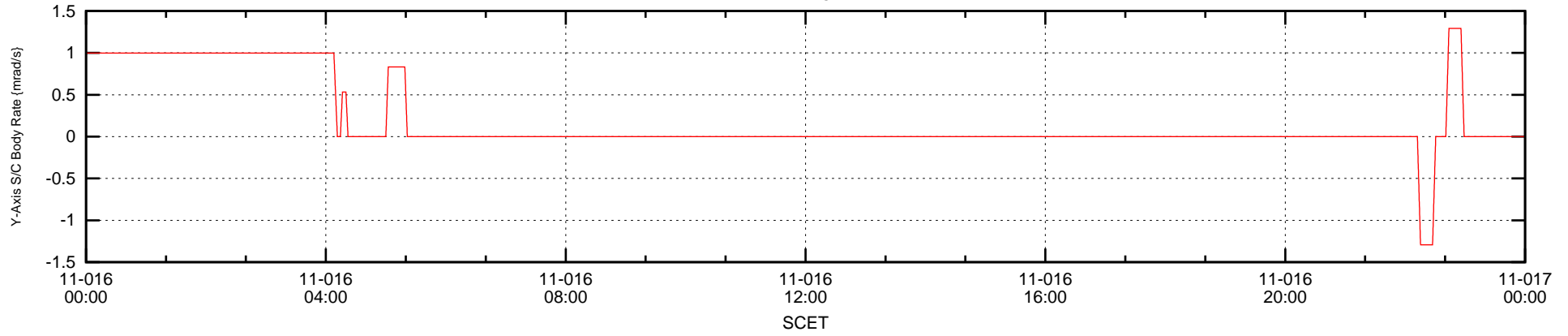


# CK #2 S/C Body Rates (DOY 016-017)

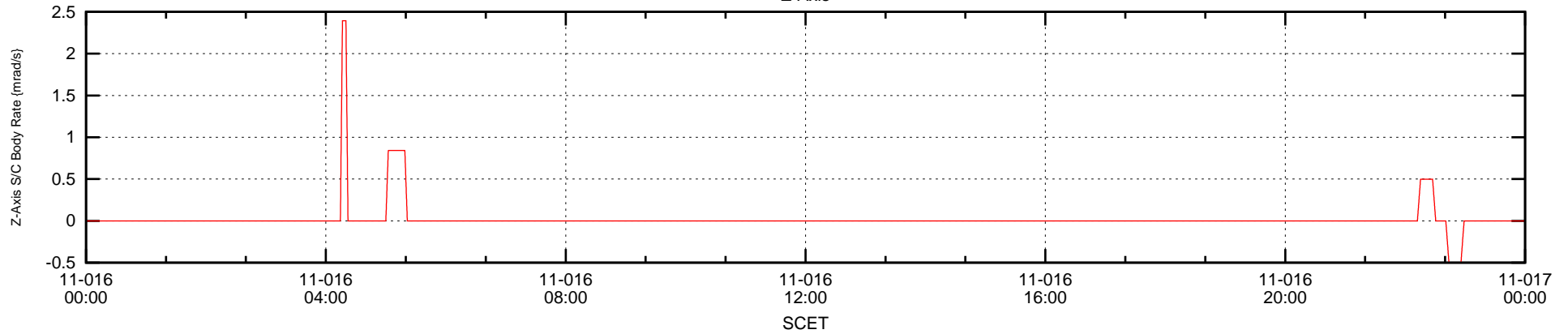
X-Axis (CK #2 = 10328\_11017py\_as\_flowm.bc)



Y-Axis

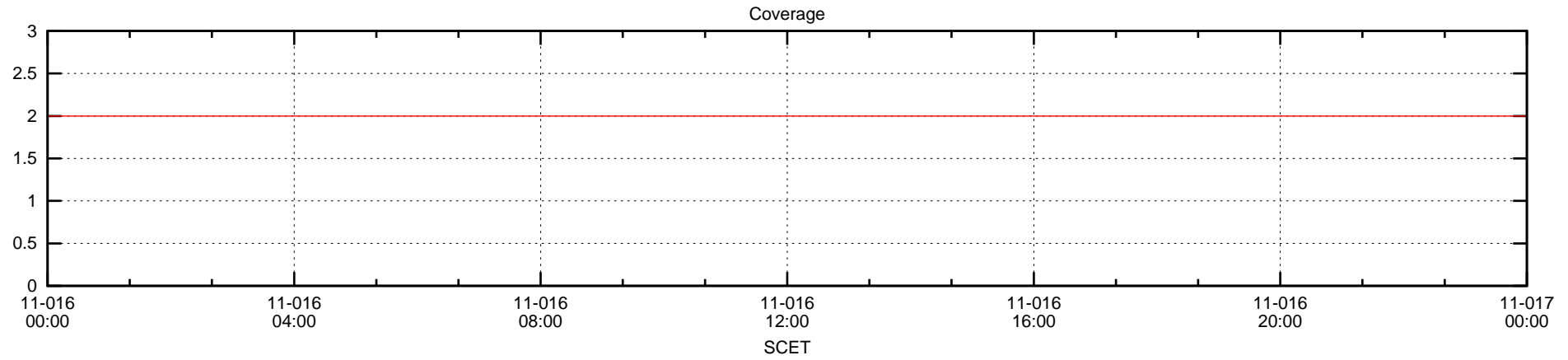


Z-Axis



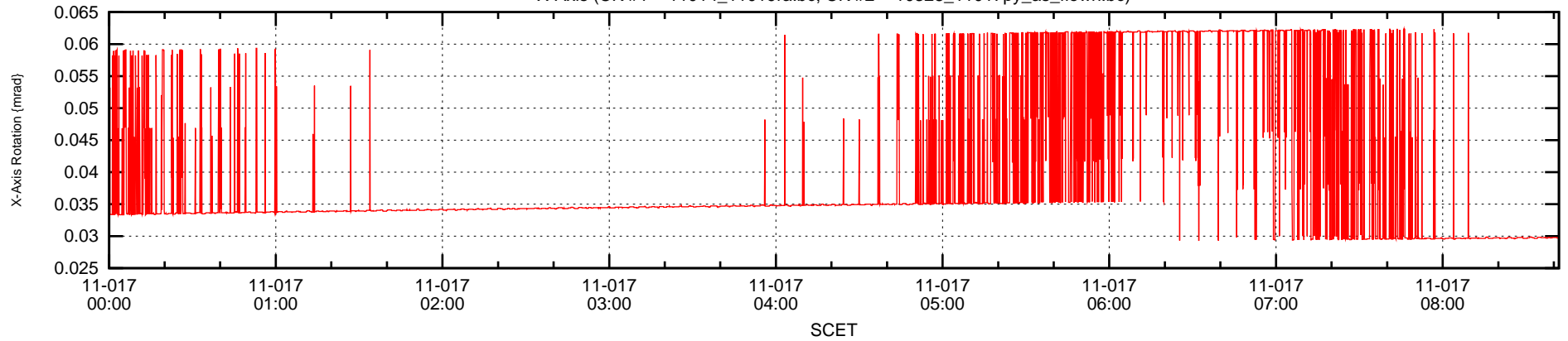


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 016-017)

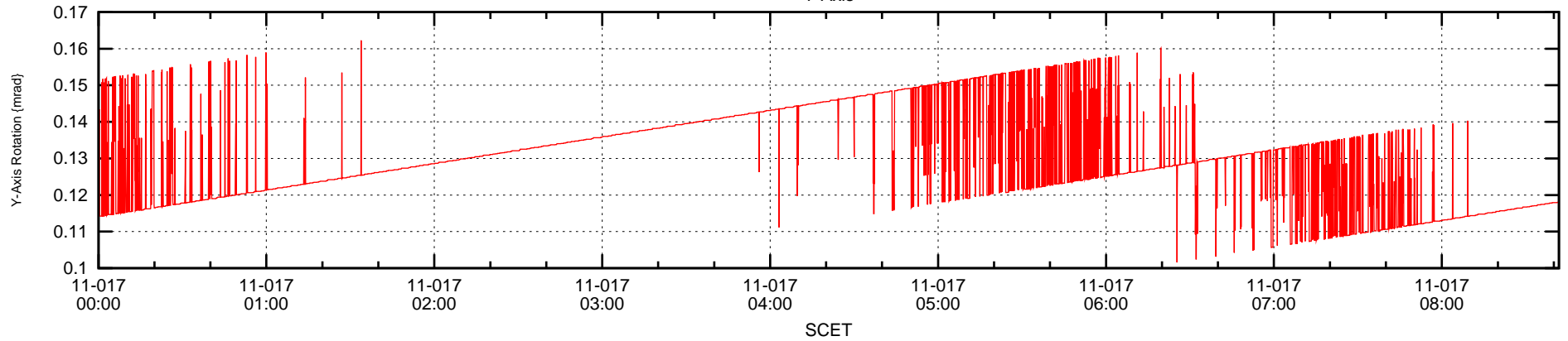


# Rotation From CK #2 to CK #1 (DOY 017-017)

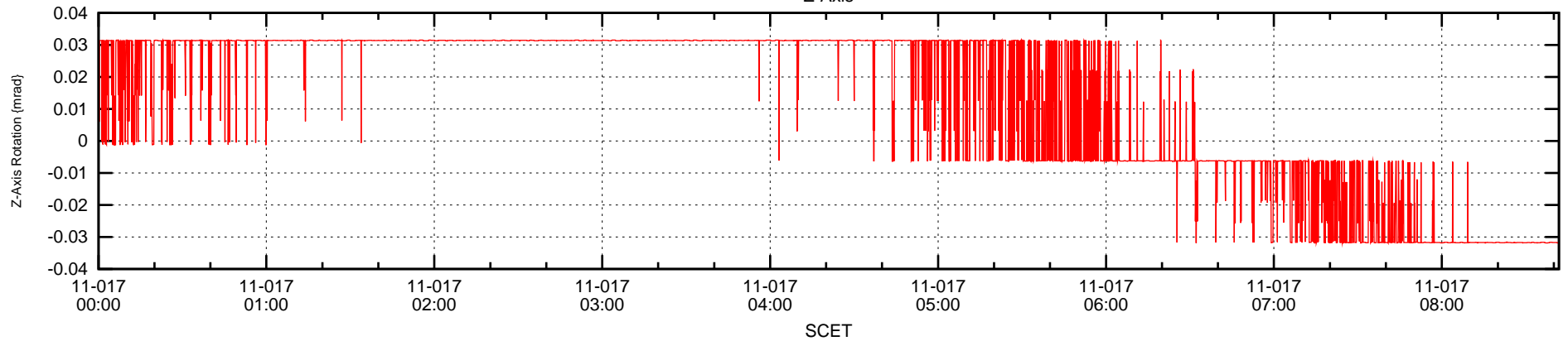
X-Axis (CK #1 = 11014\_11019ra.bc; CK #2 = 10328\_11017py\_as\_flown.bc)



Y-Axis

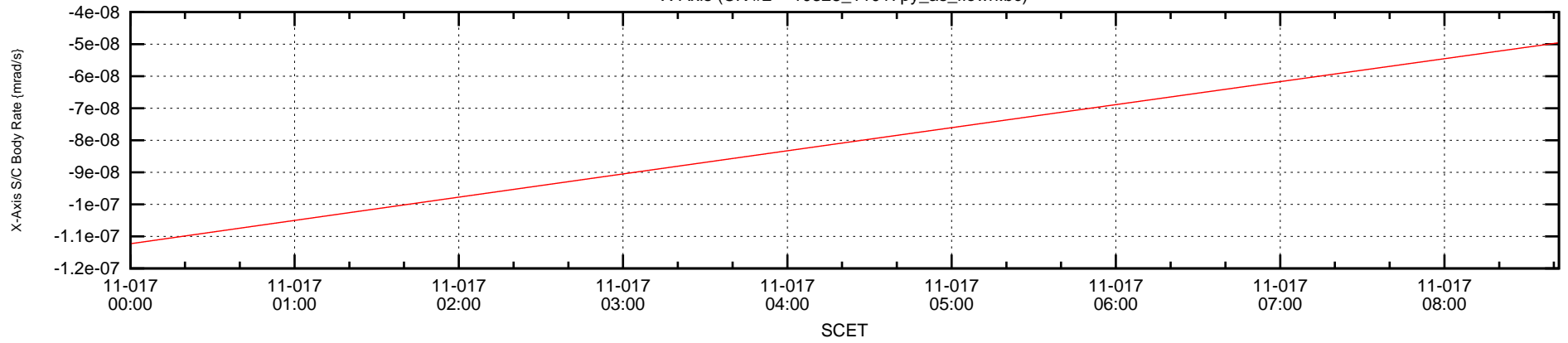


Z-Axis

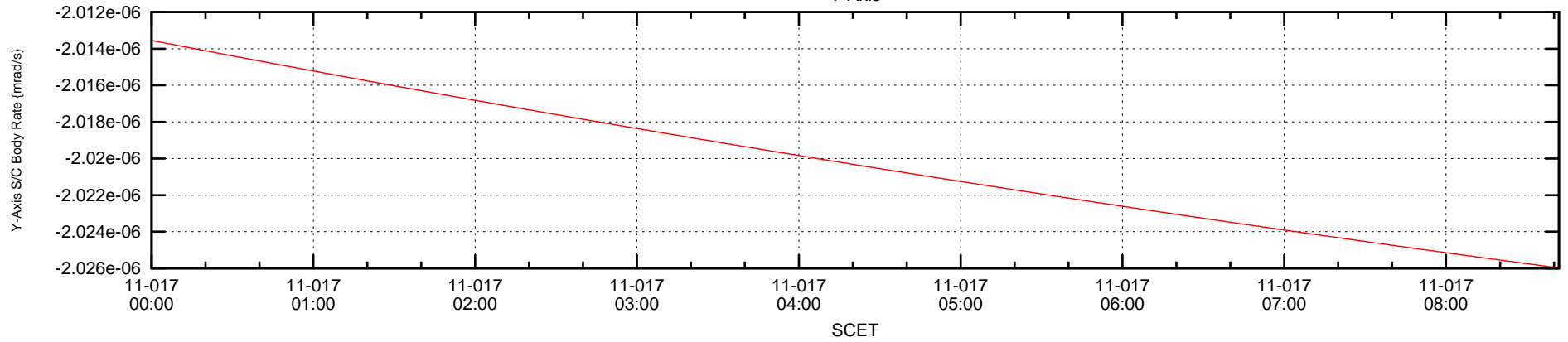


# CK #2 S/C Body Rates (DOY 017-017)

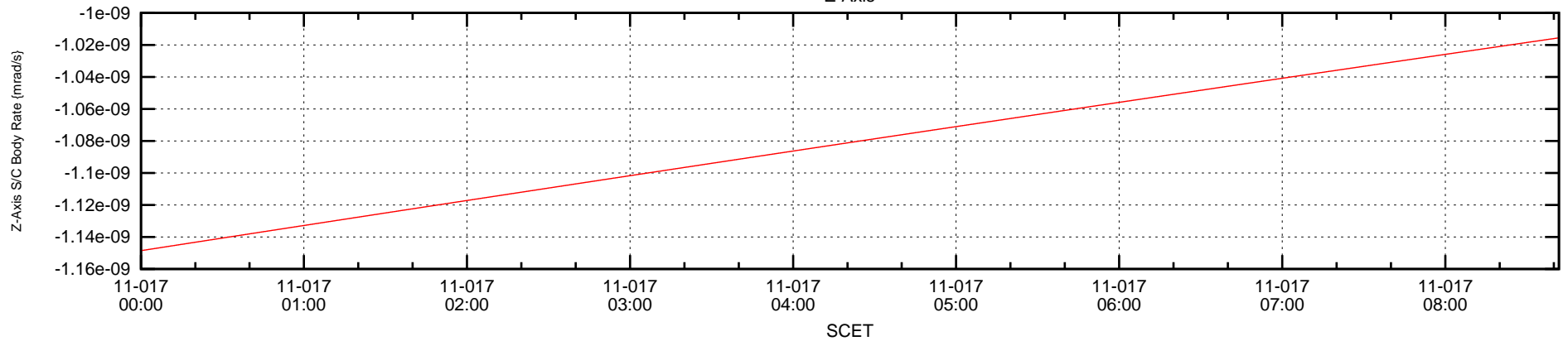
X-Axis (CK #2 = 10328\_11017py\_as\_flowm.bc)



Y-Axis



Z-Axis



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 017-017)

