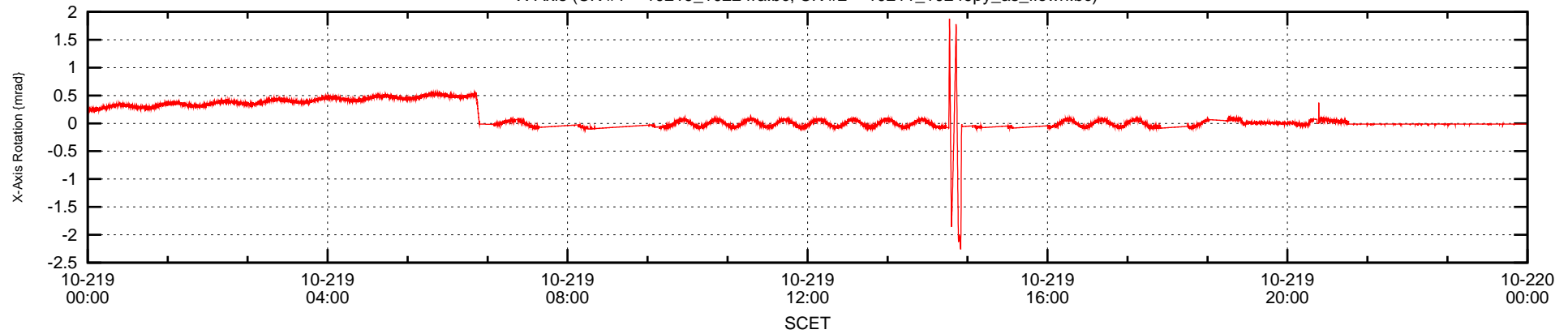
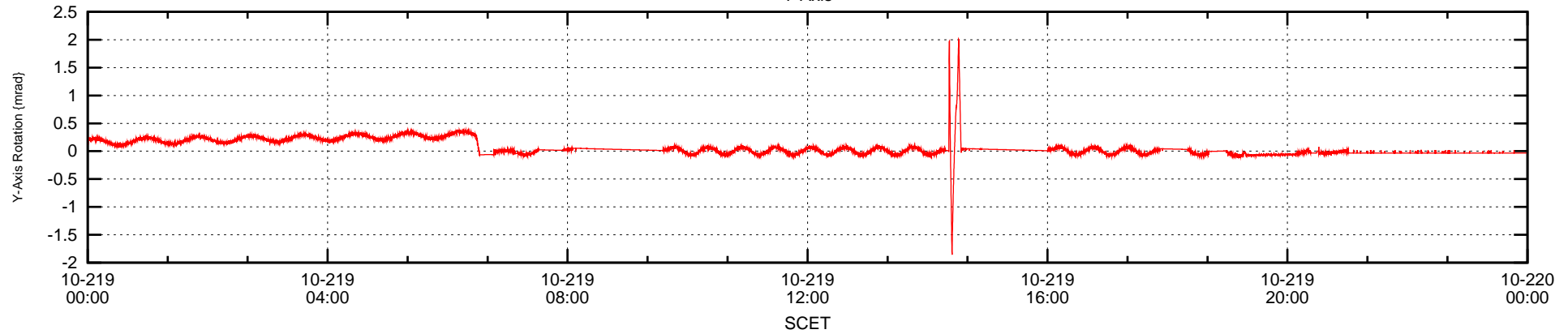


Rotation From CK #2 to CK #1 (DOY 219-220)

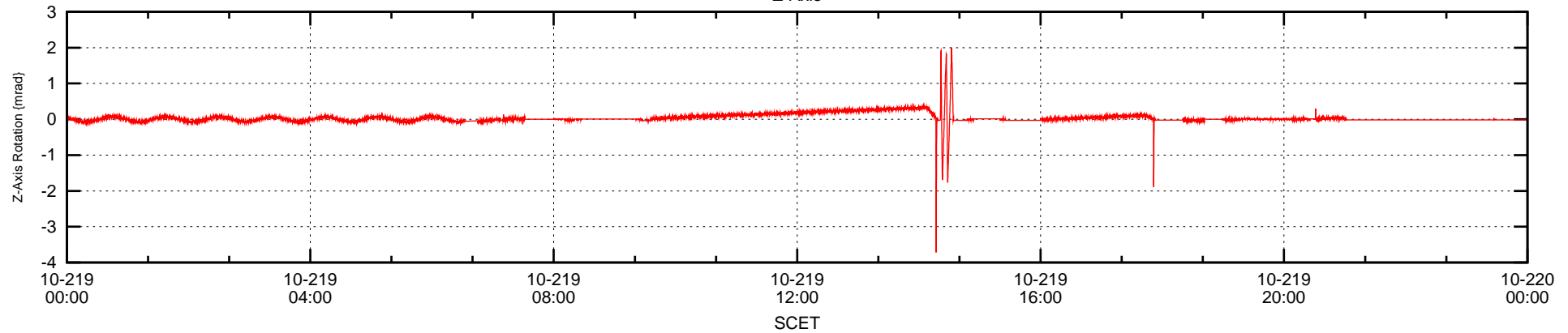
X-Axis (CK #1 = 10219_10224ra.bc; CK #2 = 10211_10249py_as_flown.bc)



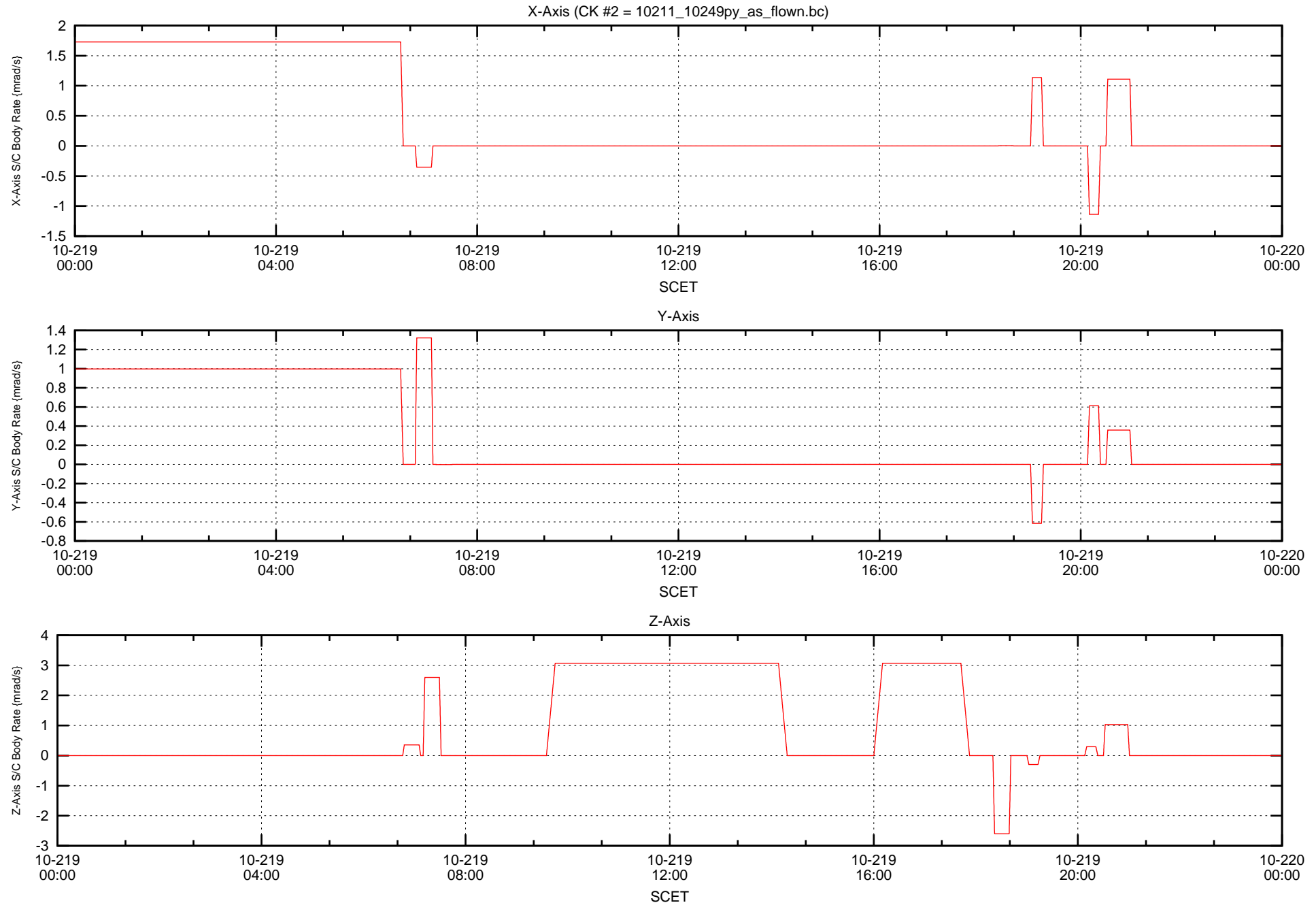
Y-Axis



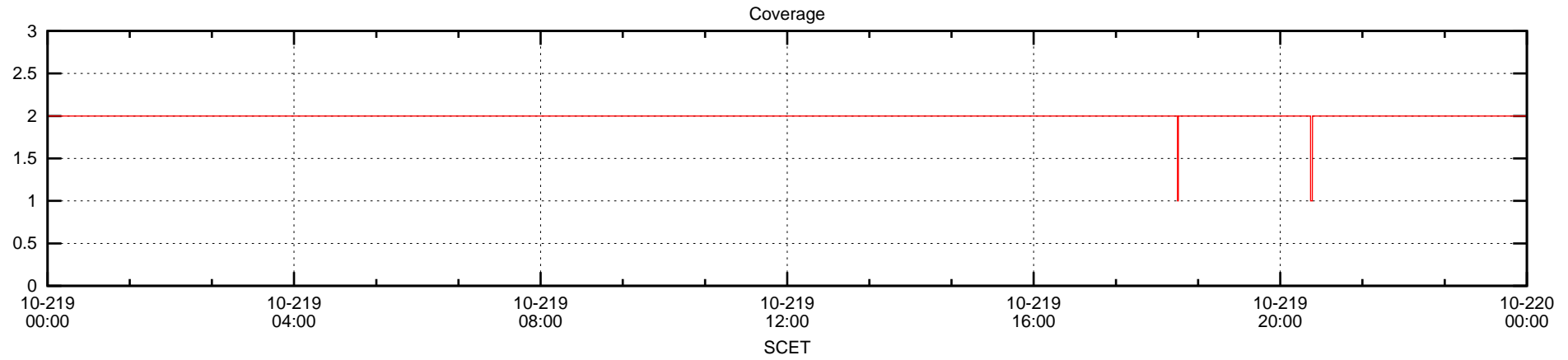
Z-Axis



CK #2 S/C Body Rates (DOY 219-220)

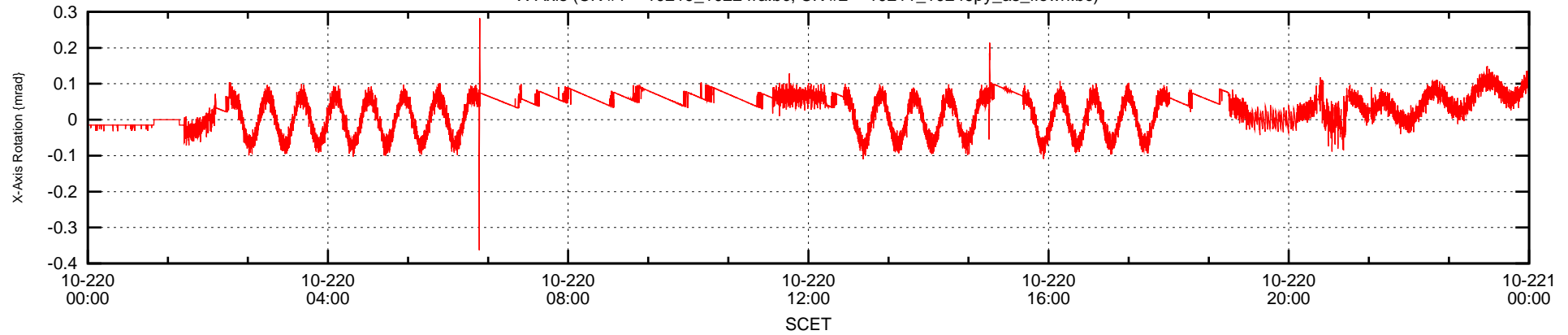


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 219-220)

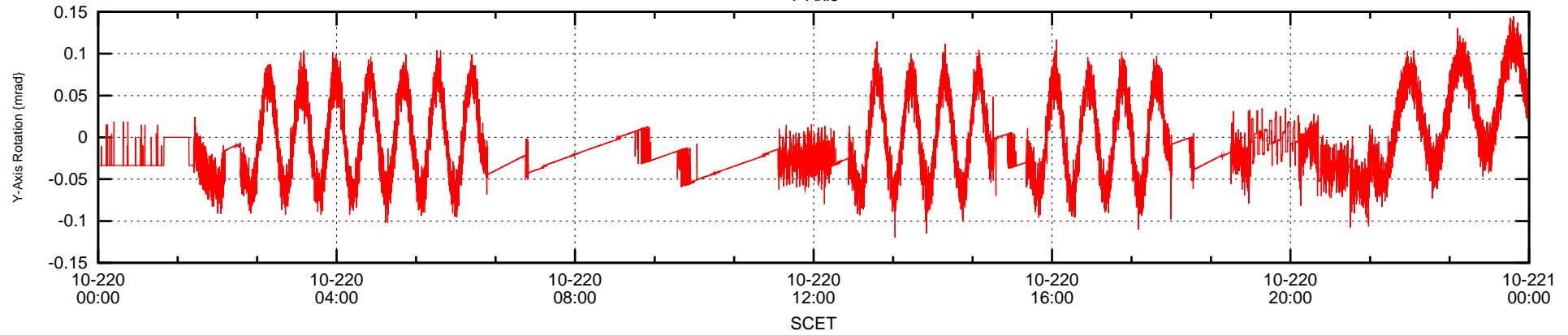


Rotation From CK #2 to CK #1 (DOY 220-221)

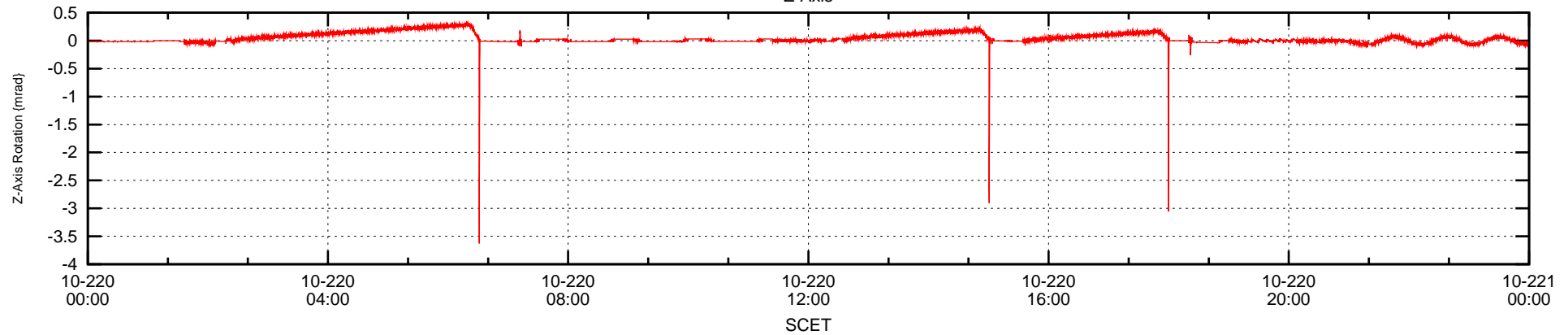
X-Axis (CK #1 = 10219_10224ra.bc; CK #2 = 10211_10249py_as_flown.bc)



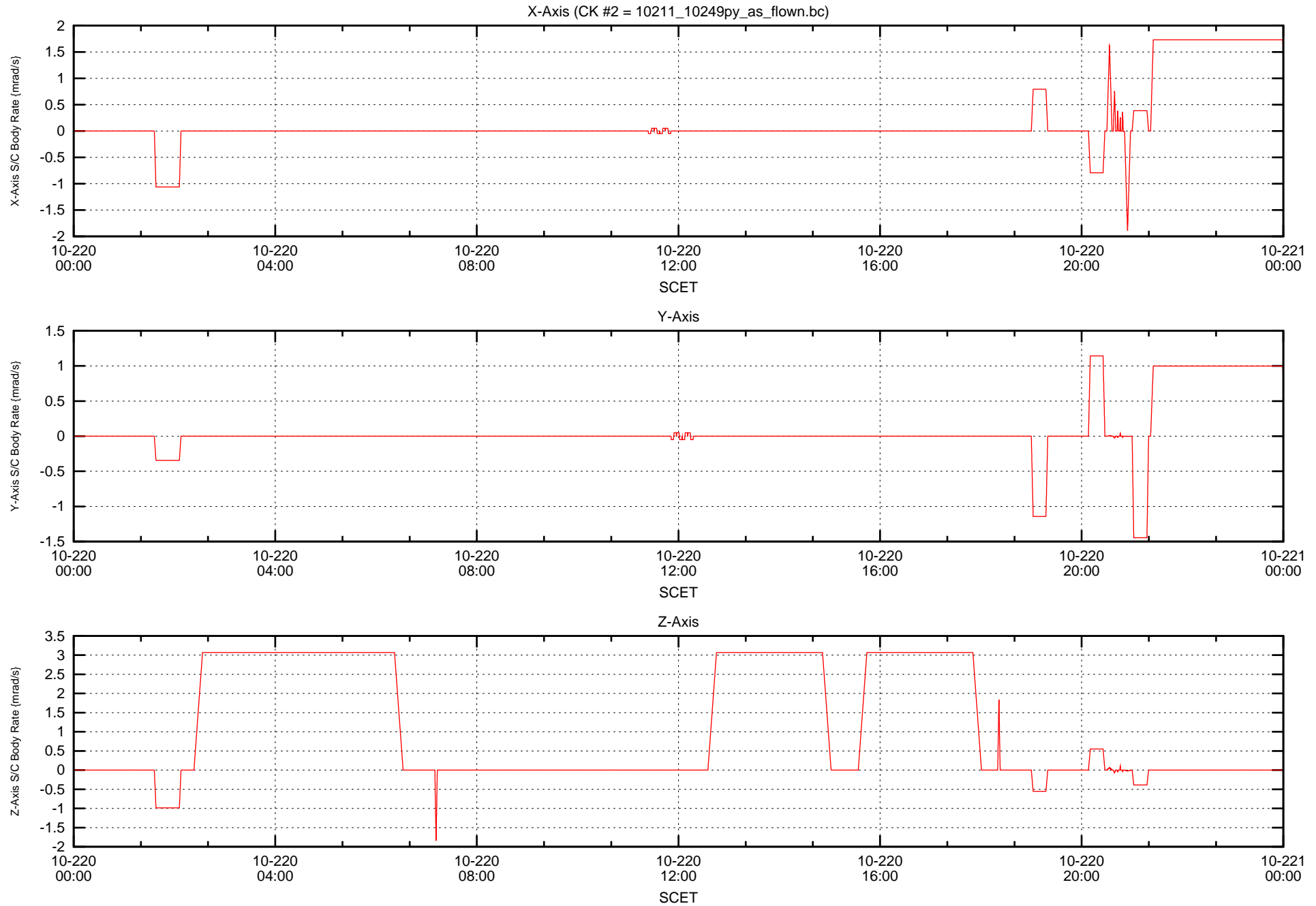
Y-Axis



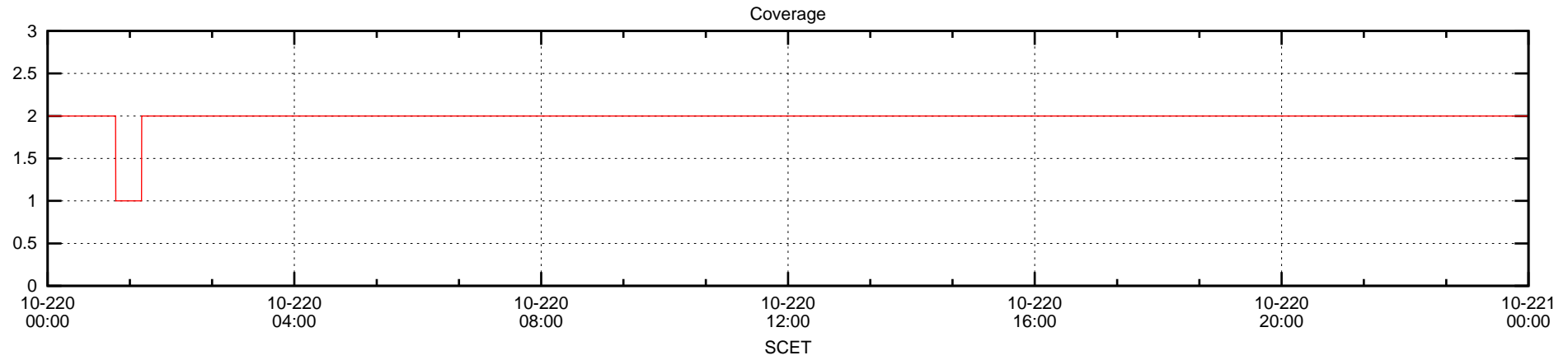
Z-Axis



CK #2 S/C Body Rates (DOY 220-221)

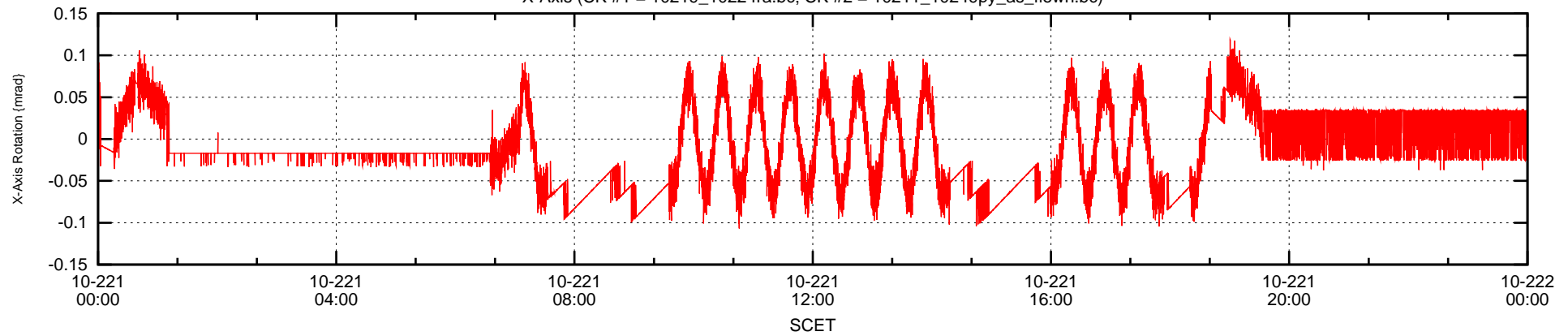


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 220-221)

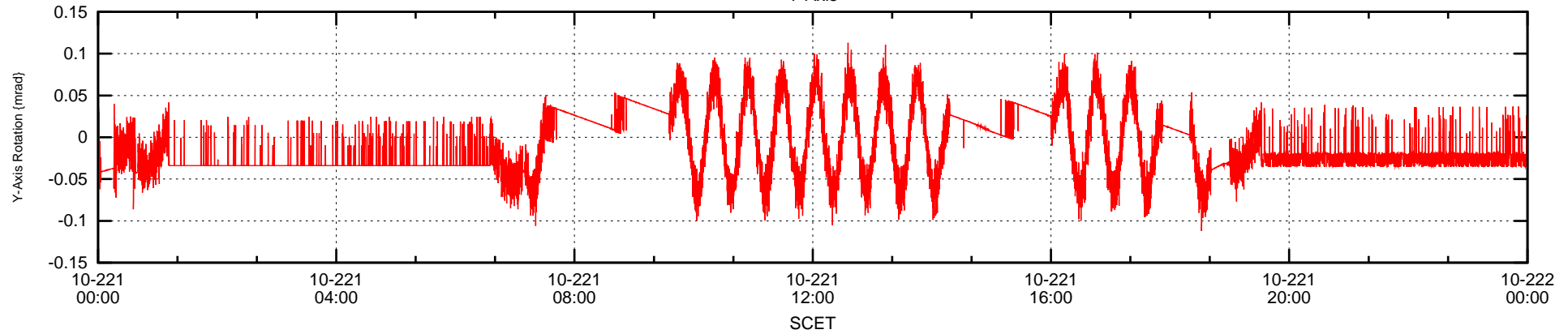


Rotation From CK #2 to CK #1 (DOY 221-222)

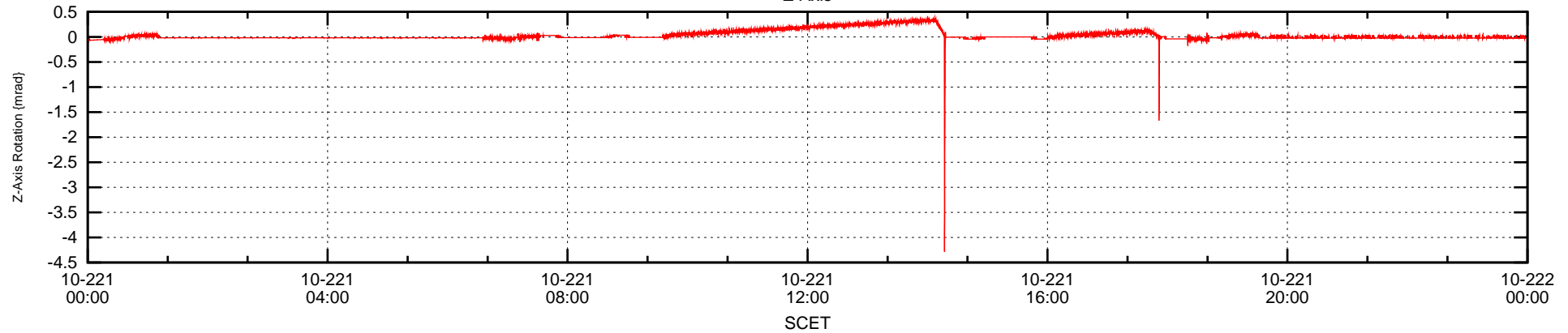
X-Axis (CK #1 = 10219_10224ra.bc; CK #2 = 10211_10249py_as_flown.bc)



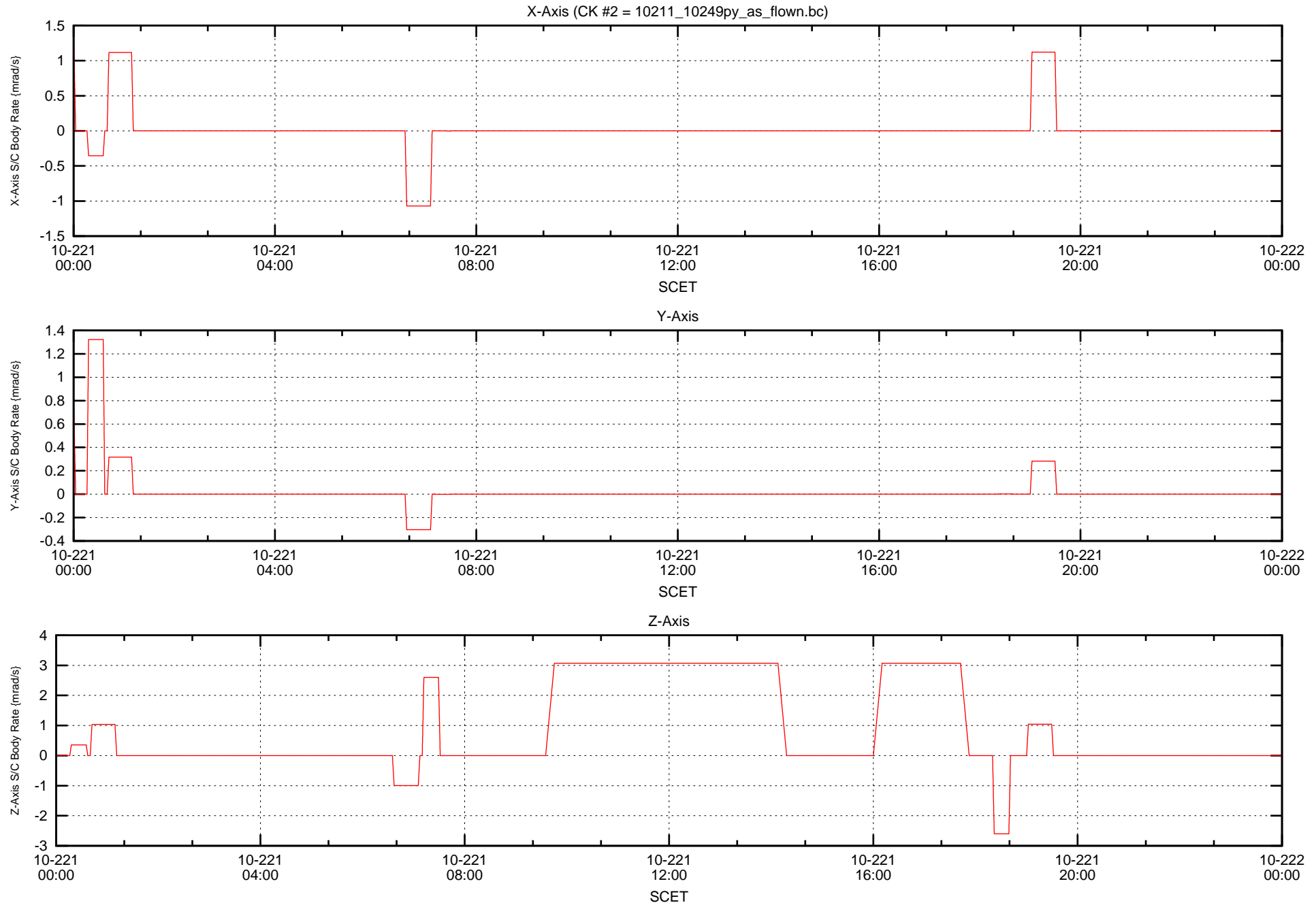
Y-Axis



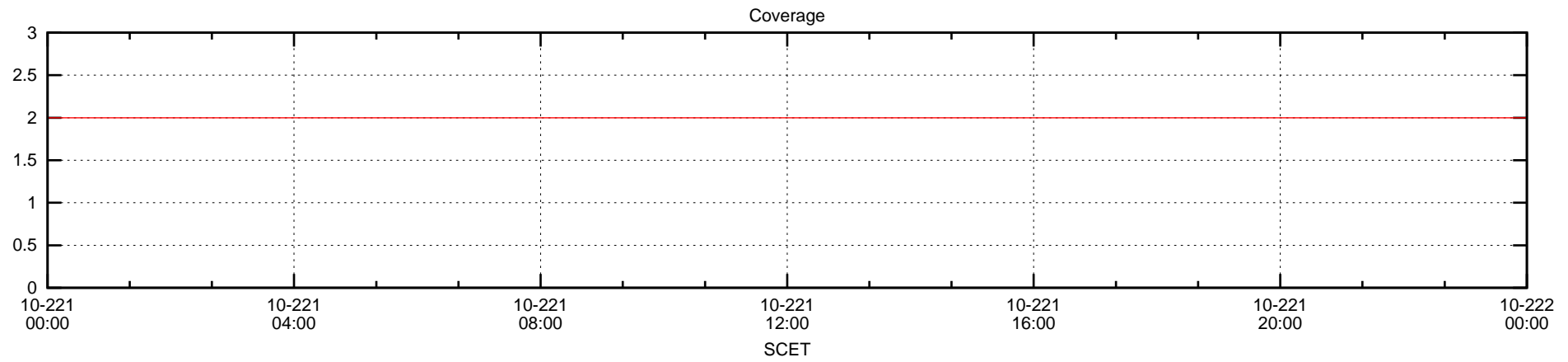
Z-Axis



CK #2 S/C Body Rates (DOY 221-222)

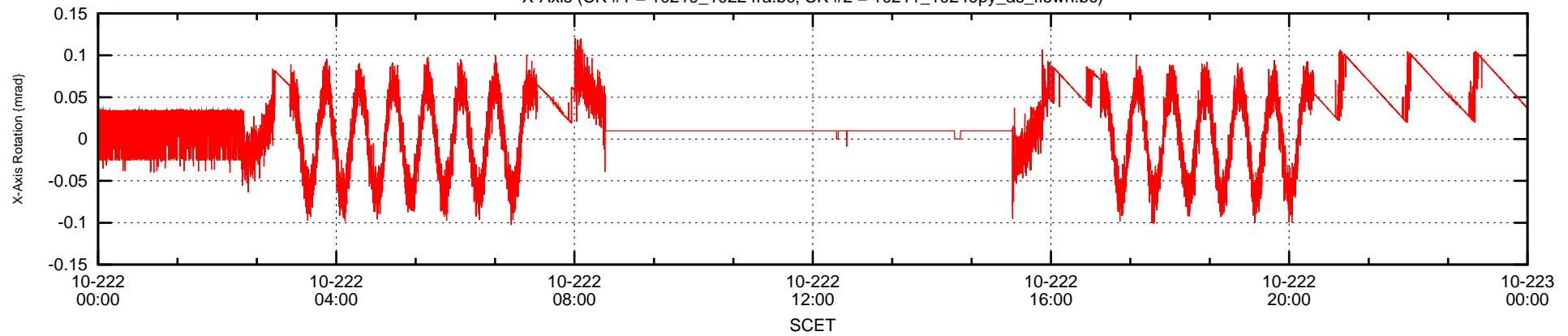


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 221-222)

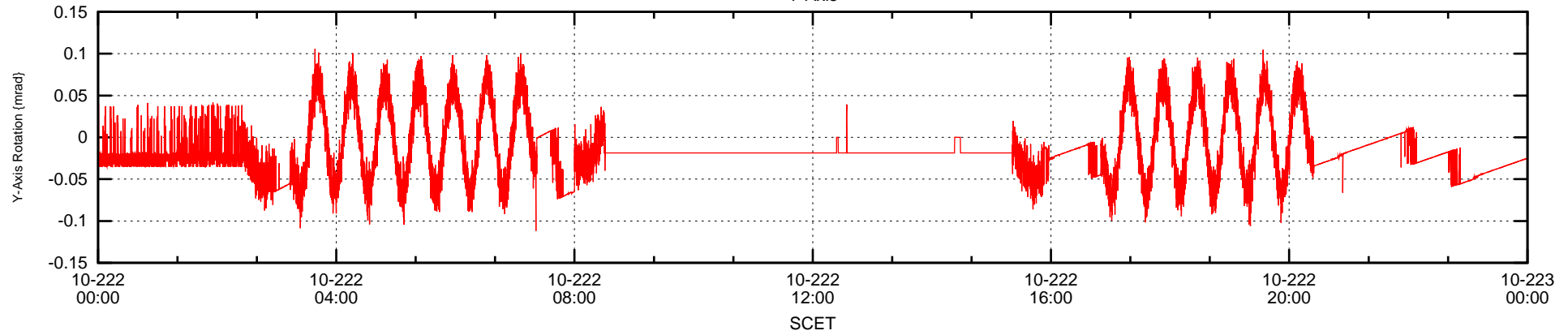


Rotation From CK #2 to CK #1 (DOY 222-223)

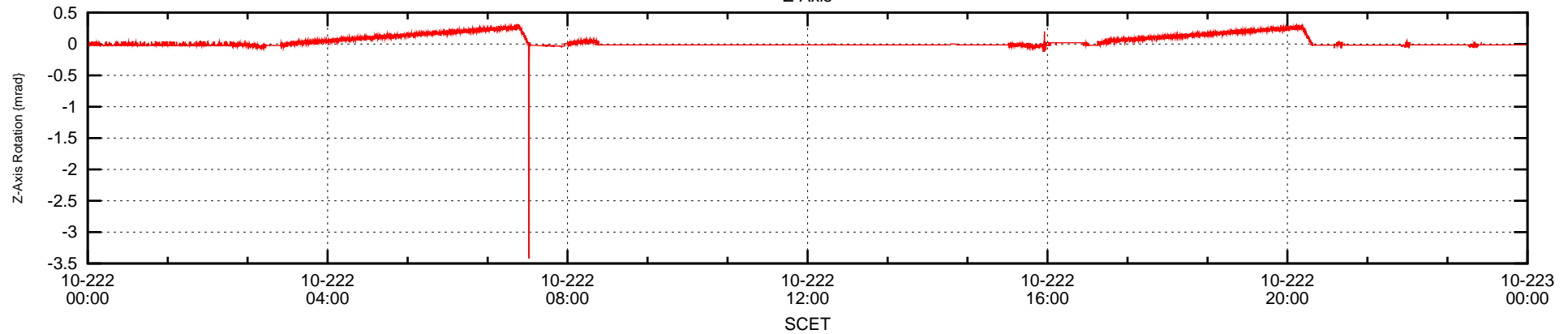
X-Axis (CK #1 = 10219_10224ra.bc; CK #2 = 10211_10249py_as_flowm.bc)



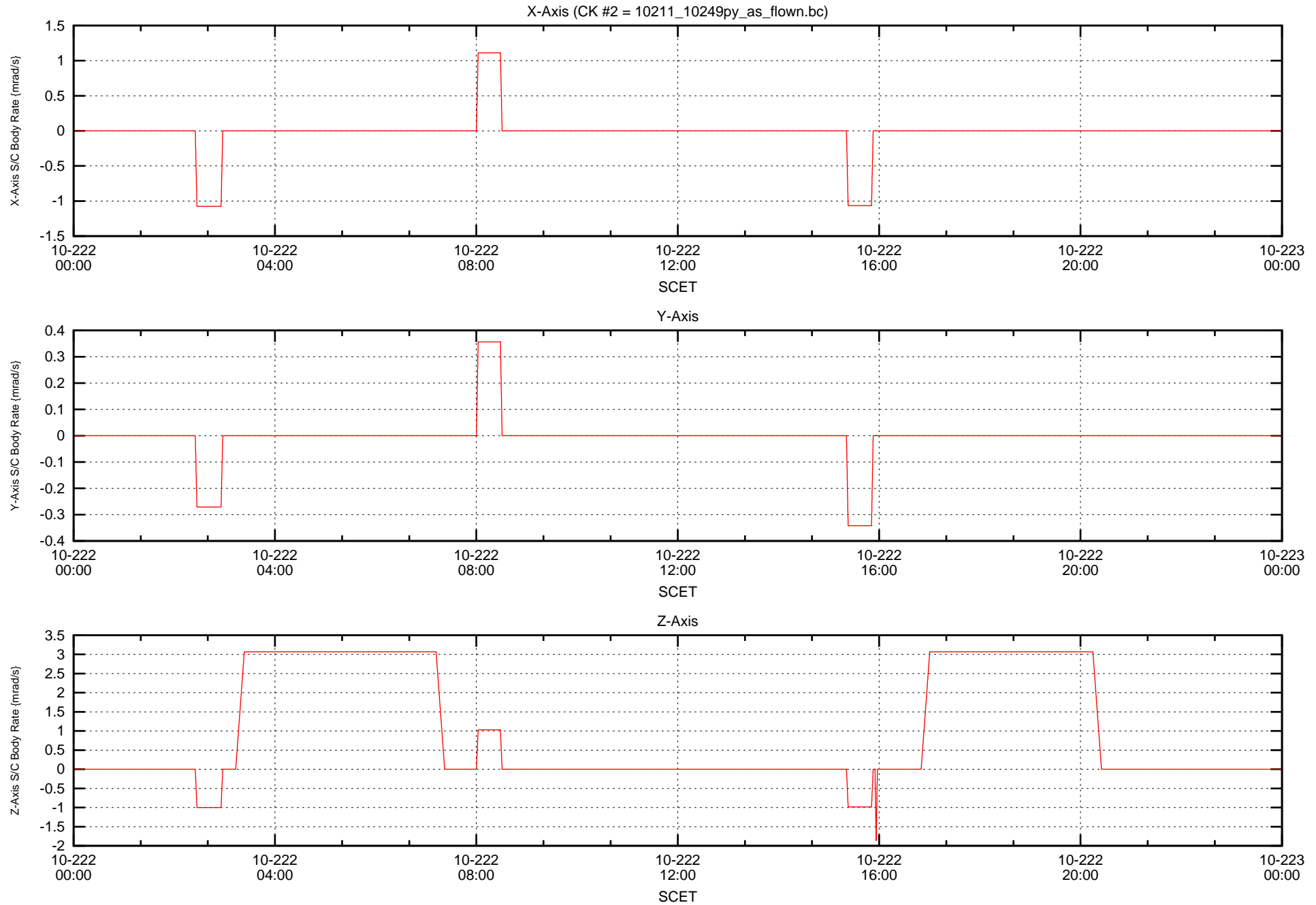
Y-Axis



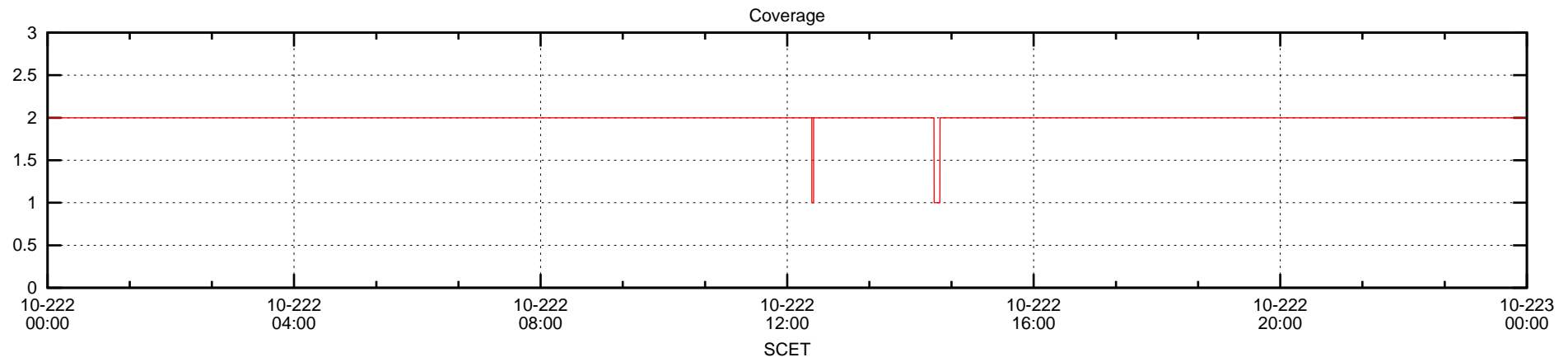
Z-Axis



CK #2 S/C Body Rates (DOY 222-223)

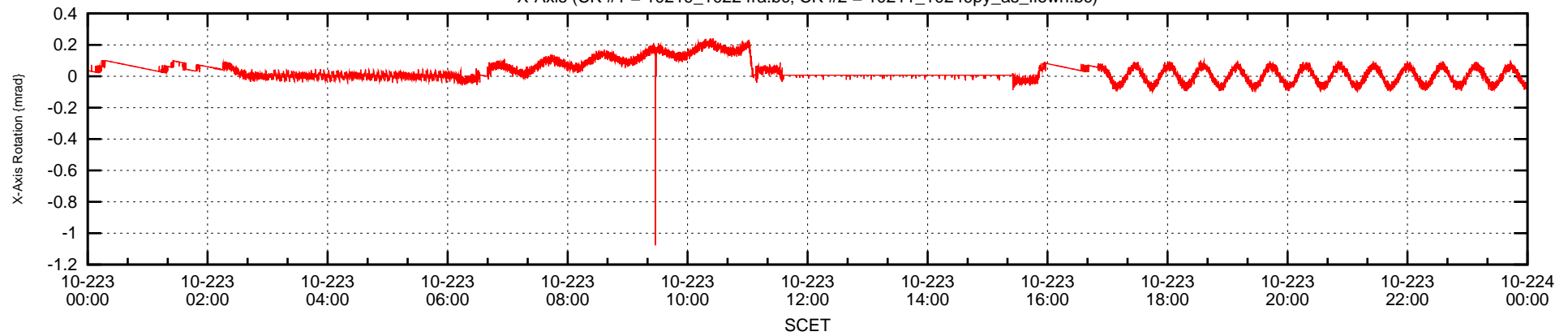


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 222-223)

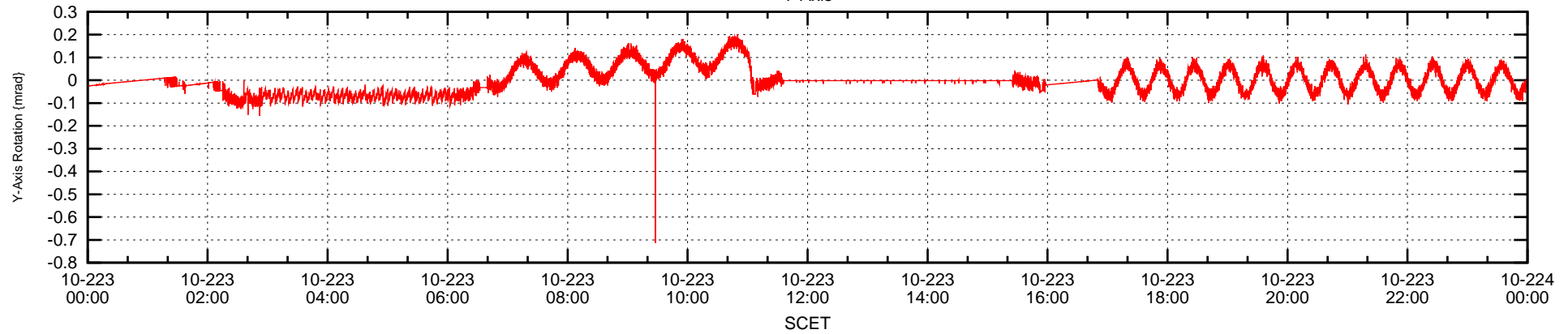


Rotation From CK #2 to CK #1 (DOY 223-223)

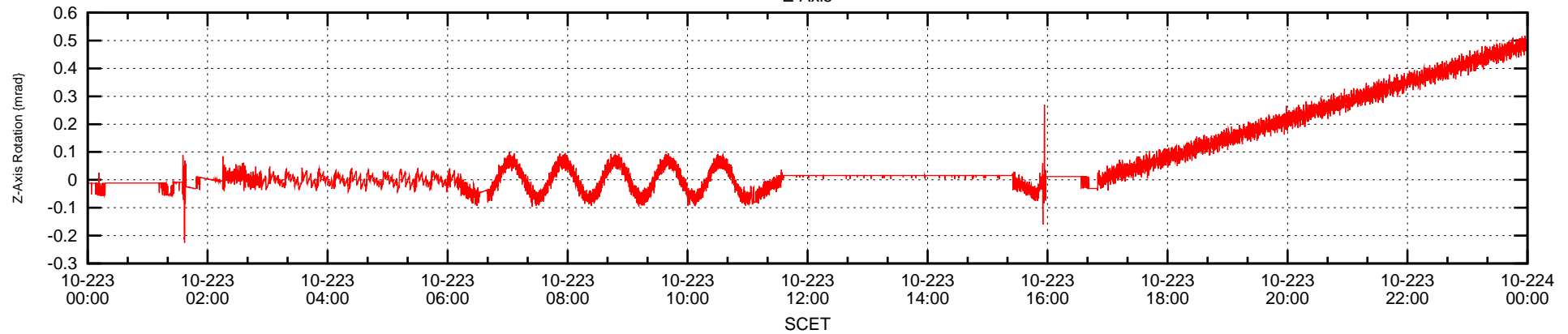
X-Axis (CK #1 = 10219_10224ra.bc; CK #2 = 10211_10249py_as_flown.bc)



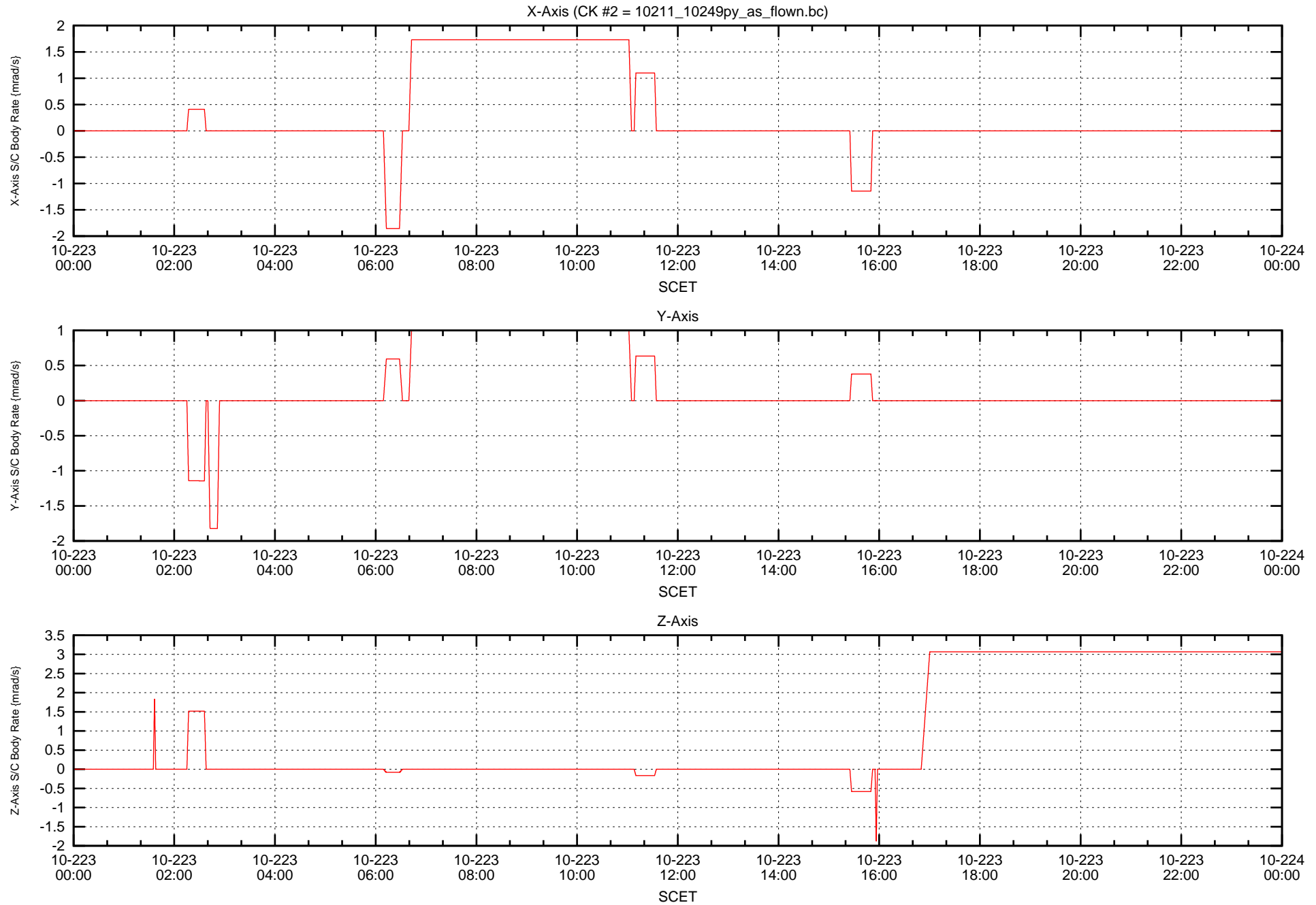
Y-Axis



Z-Axis



CK #2 S/C Body Rates (DOY 223-223)



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 223-223)

