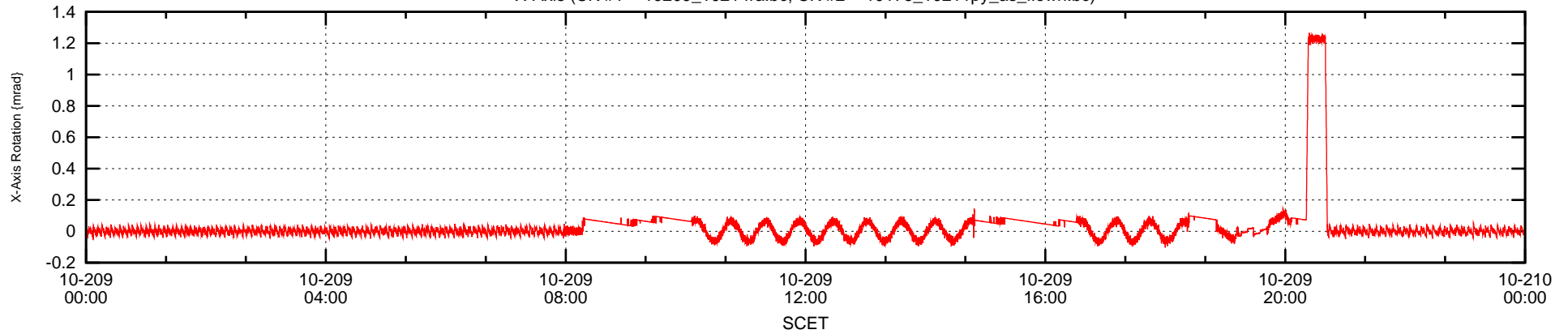
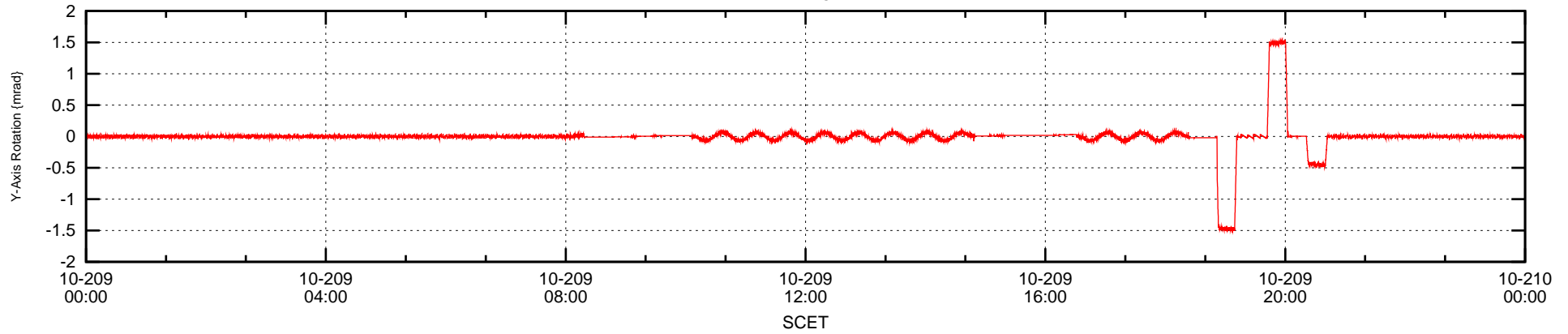


# Rotation From CK #2 to CK #1 (DOY 209-210)

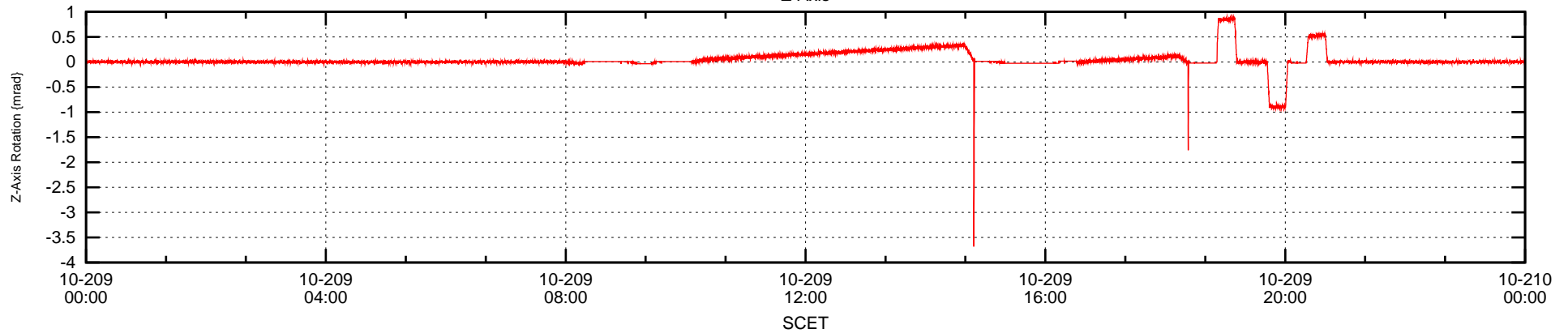
X-Axis (CK #1 = 10209\_10214ra.bc; CK #2 = 10176\_10211py\_as\_flowm.bc)



Y-Axis

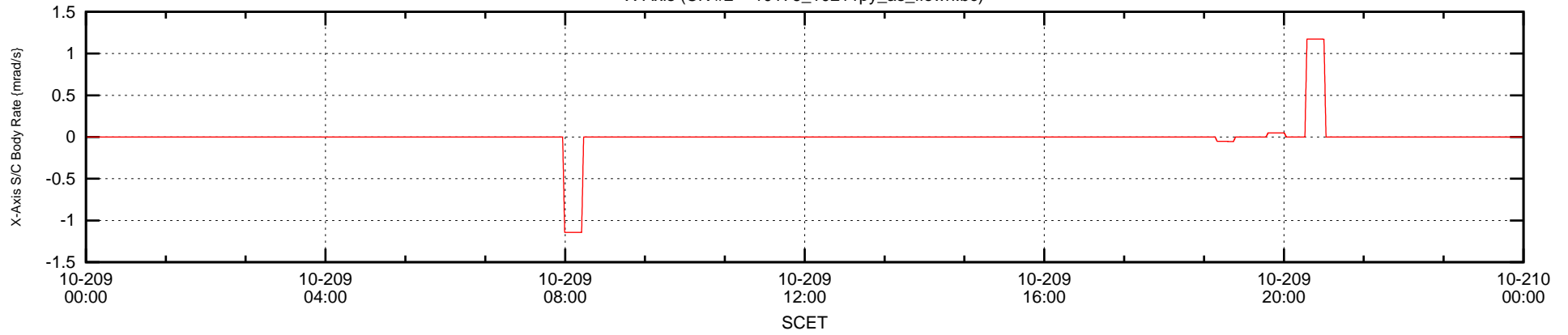


Z-Axis

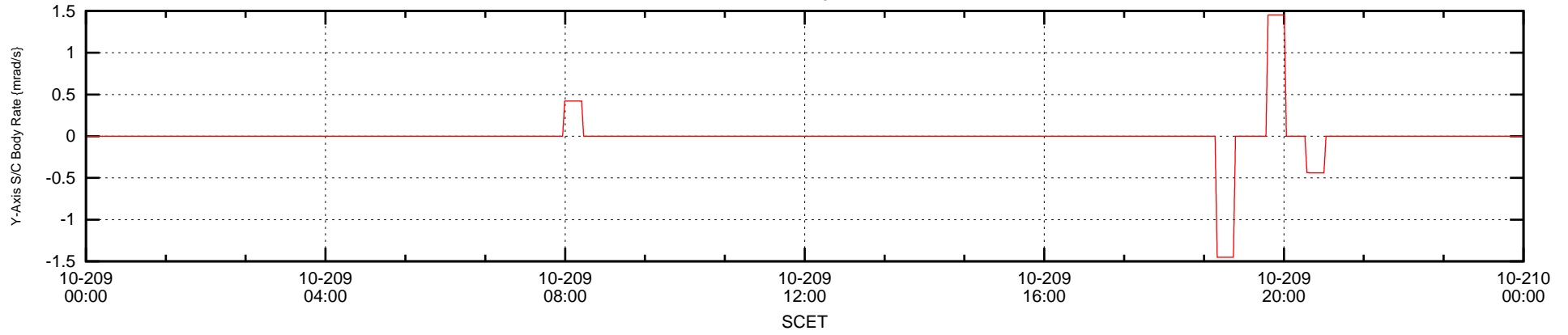


# CK #2 S/C Body Rates (DOY 209-210)

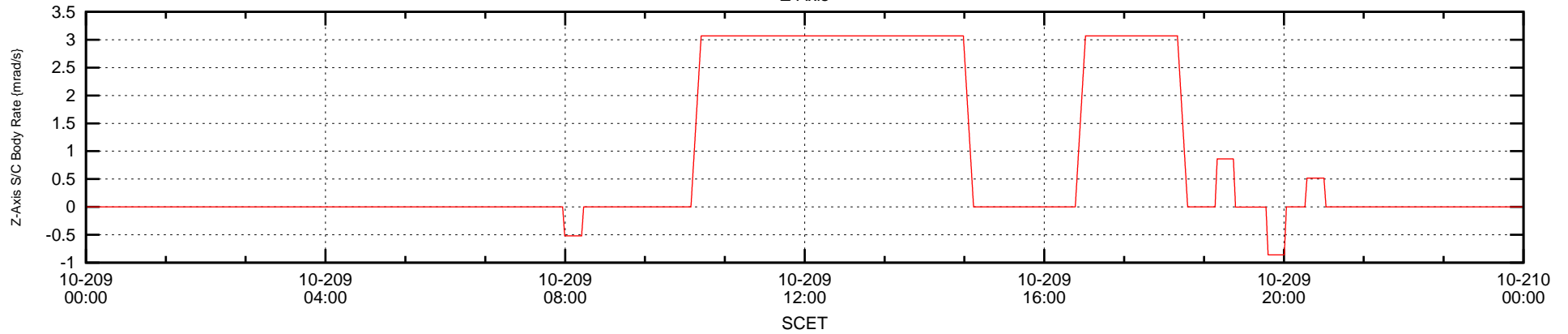
X-Axis (CK #2 = 10176\_10211py\_as\_flowm.bc)



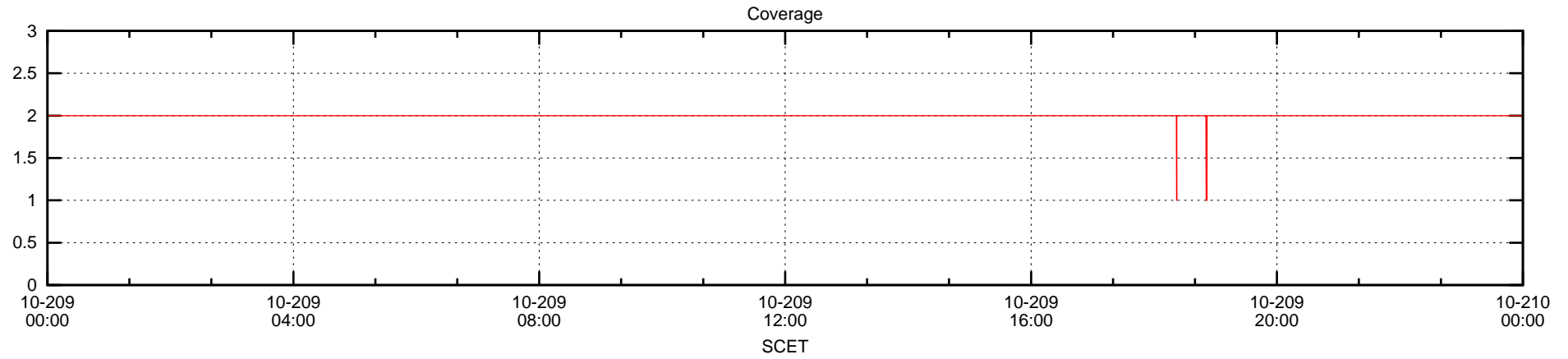
Y-Axis



Z-Axis

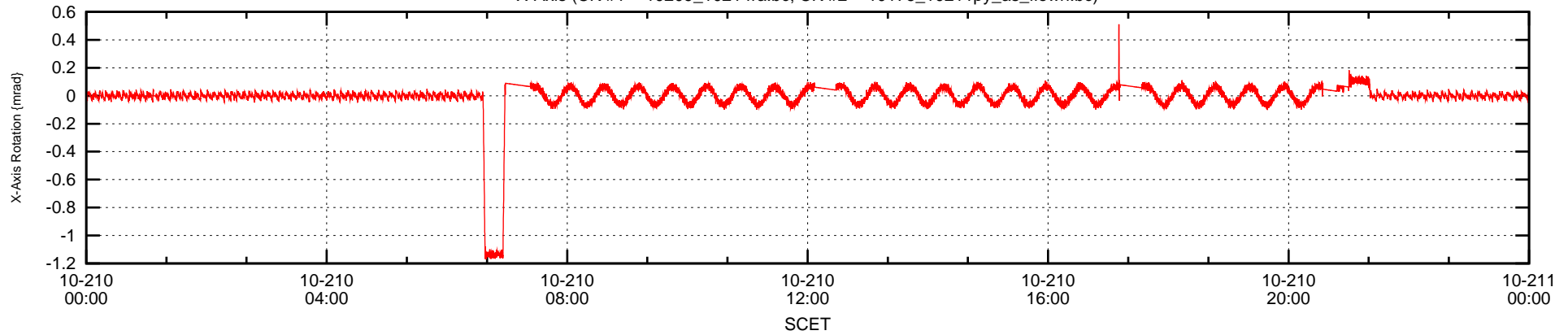


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 209-210)

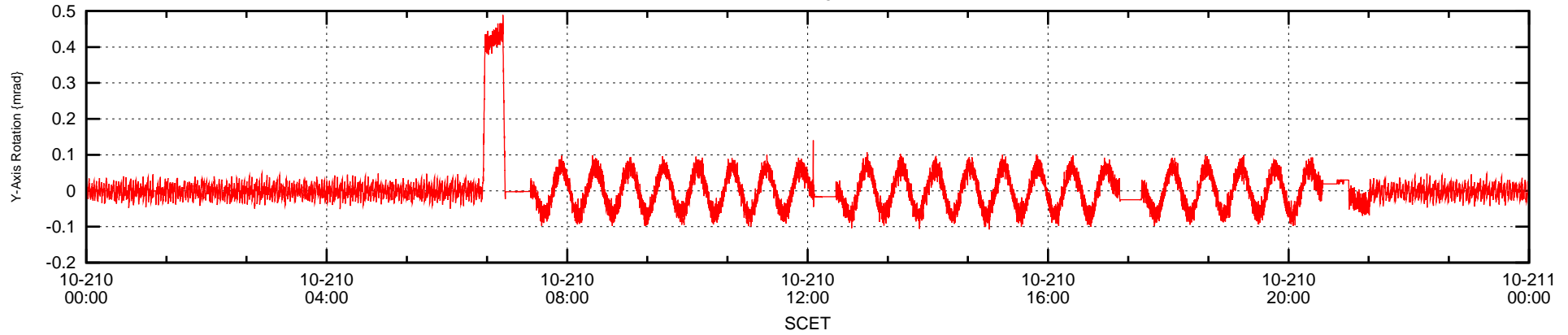


# Rotation From CK #2 to CK #1 (DOY 210-211)

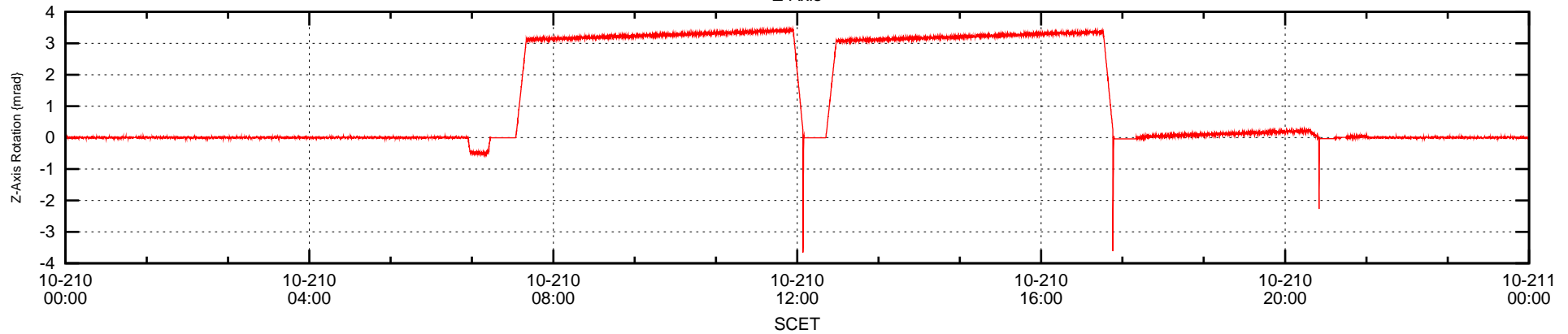
X-Axis (CK #1 = 10209\_10214ra.bc; CK #2 = 10176\_10211py\_as\_flowm.bc)



Y-Axis

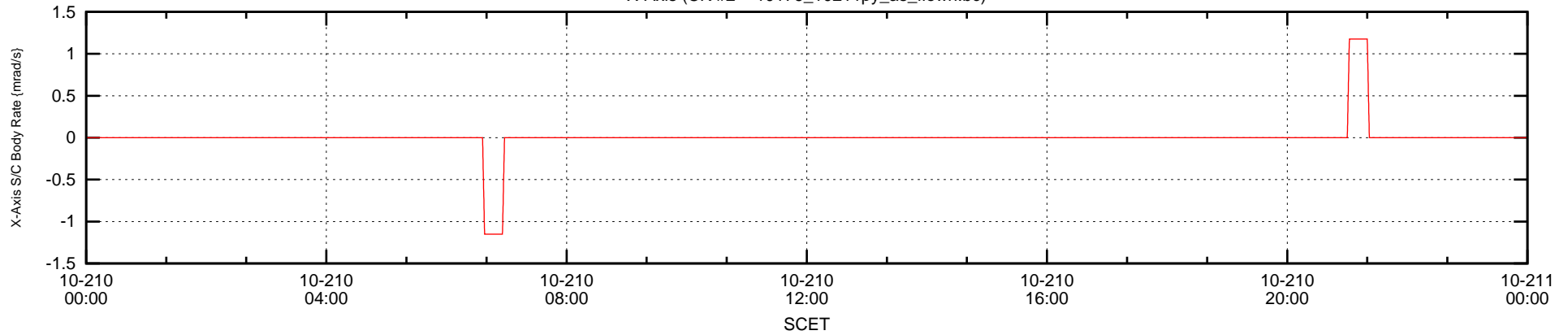


Z-Axis

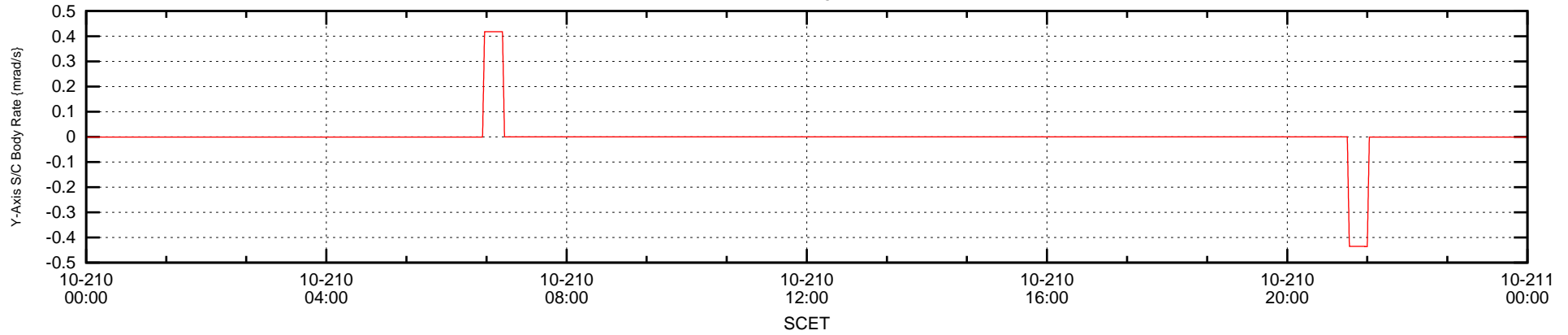


# CK #2 S/C Body Rates (DOY 210-211)

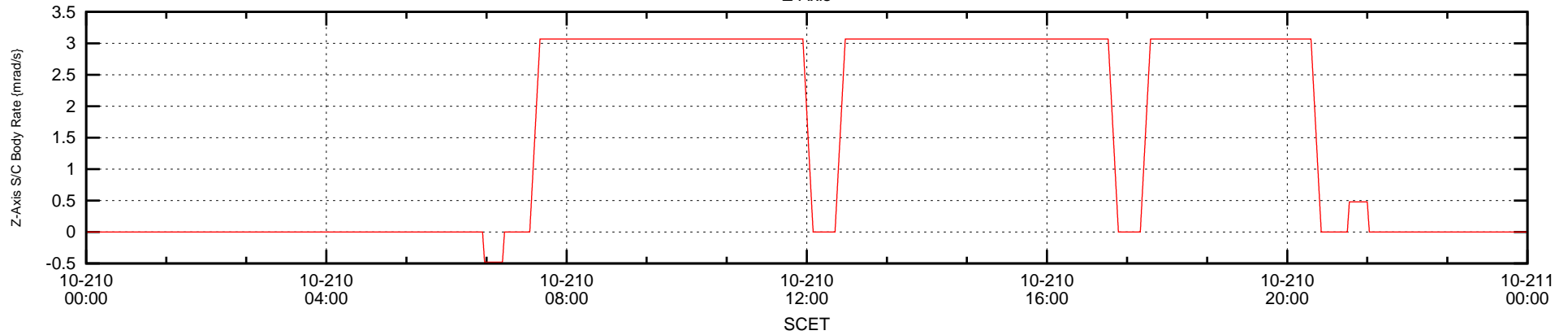
X-Axis (CK #2 = 10176\_10211py\_as\_flow.n.bc)



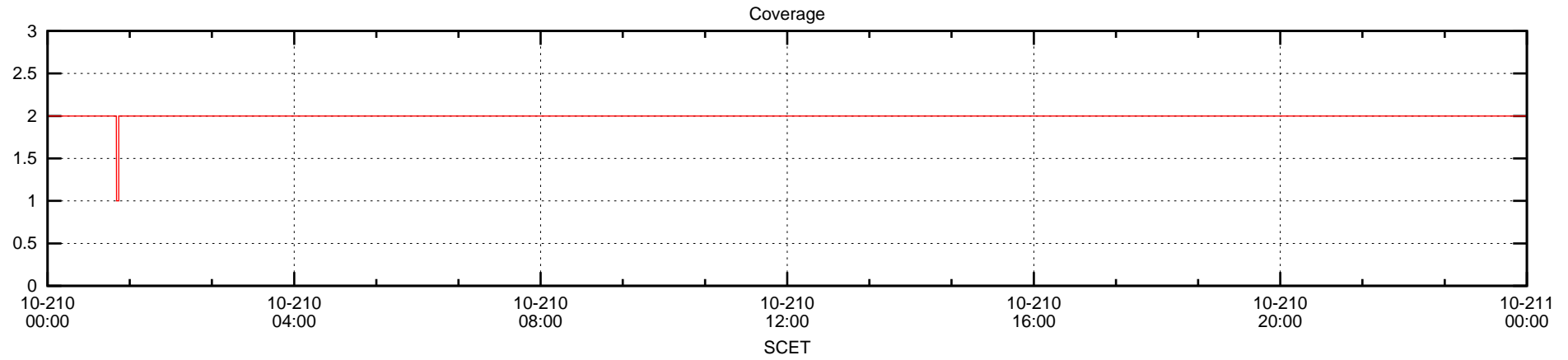
Y-Axis



Z-Axis

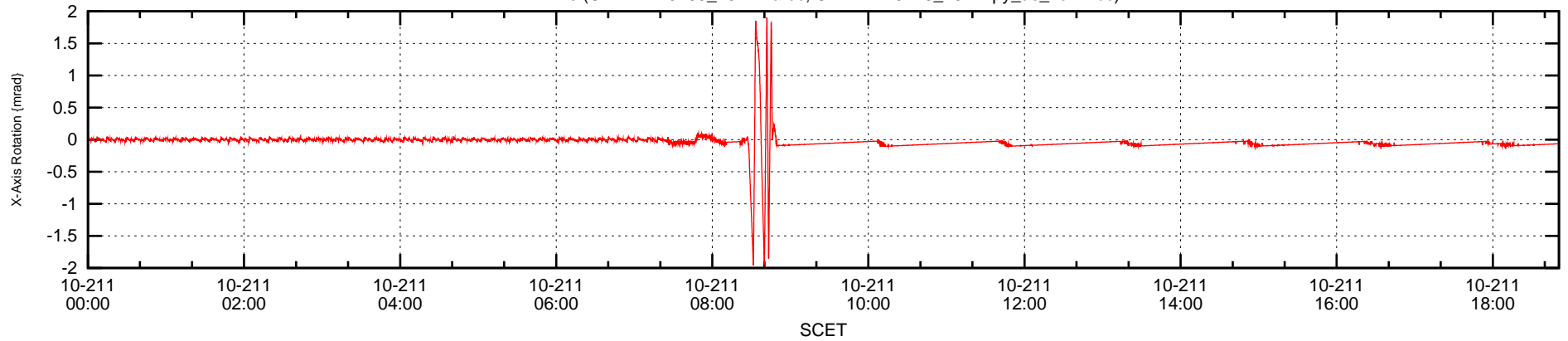


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 210-211)

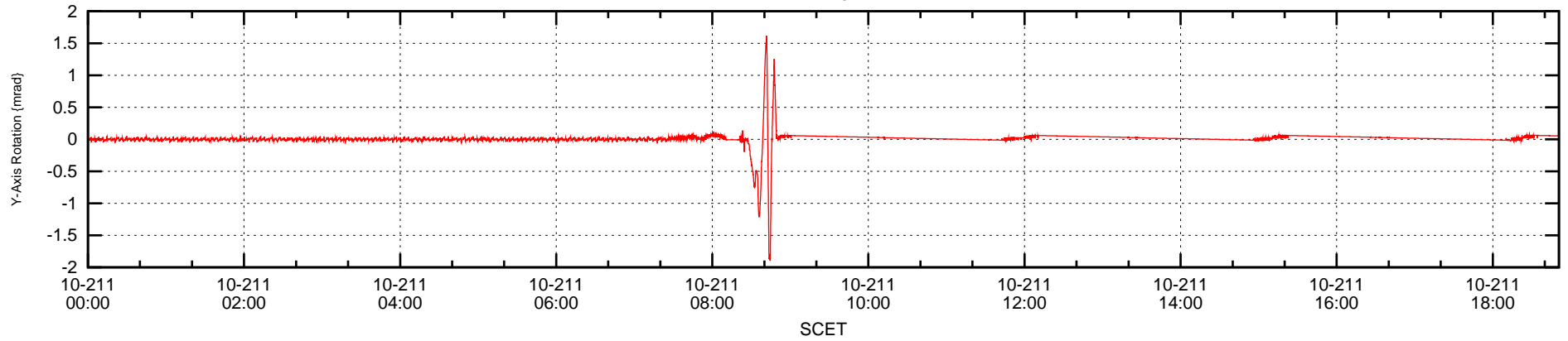


# Rotation From CK #2 to CK #1 (DOY 211-211)

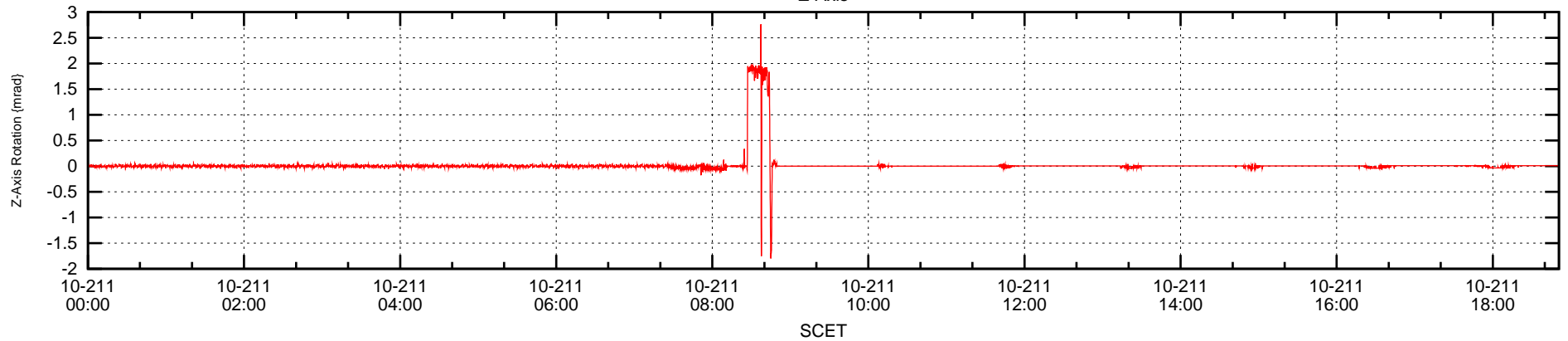
X-Axis (CK #1 = 10209\_10214ra.bc; CK #2 = 10176\_10211py\_as\_flowm.bc)



Y-Axis

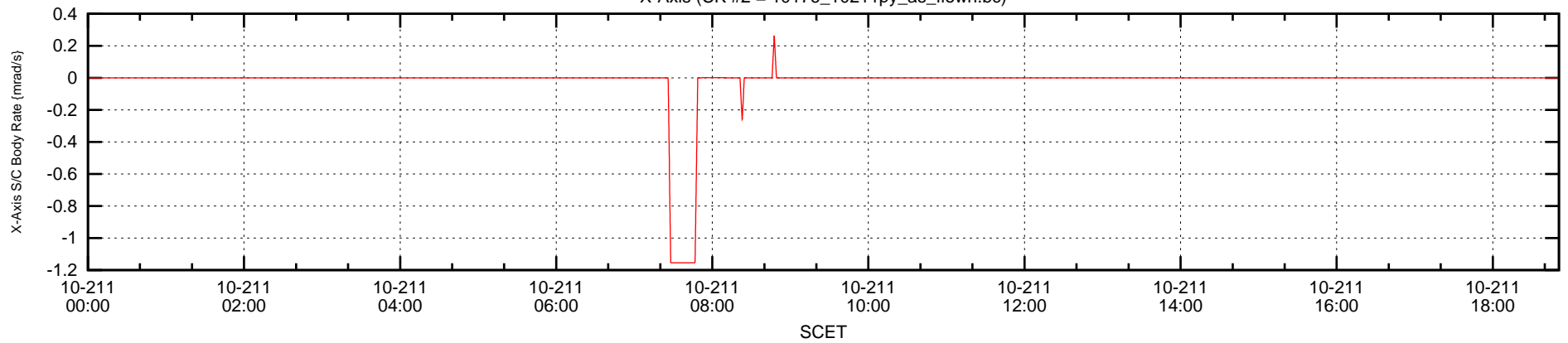


Z-Axis

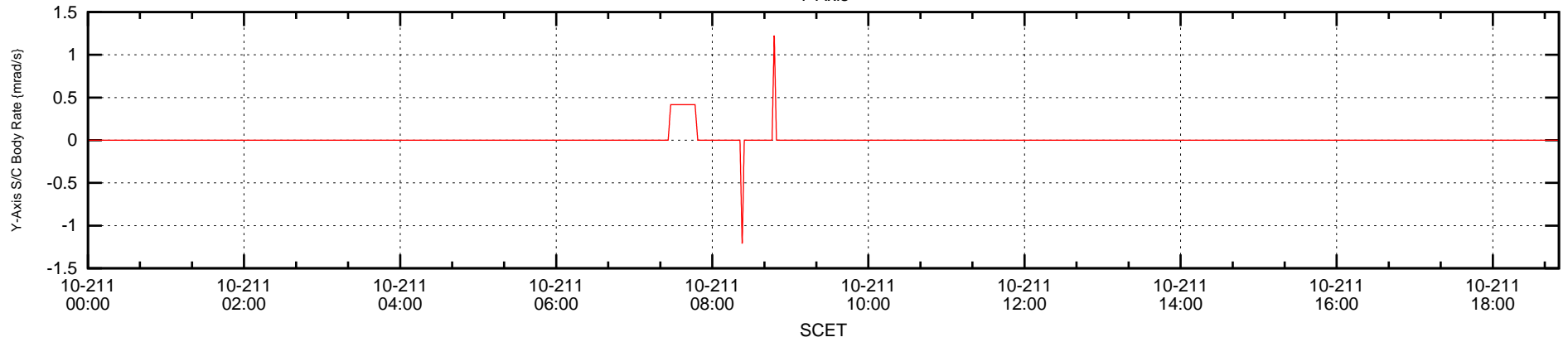


# CK #2 S/C Body Rates (DOY 211-211)

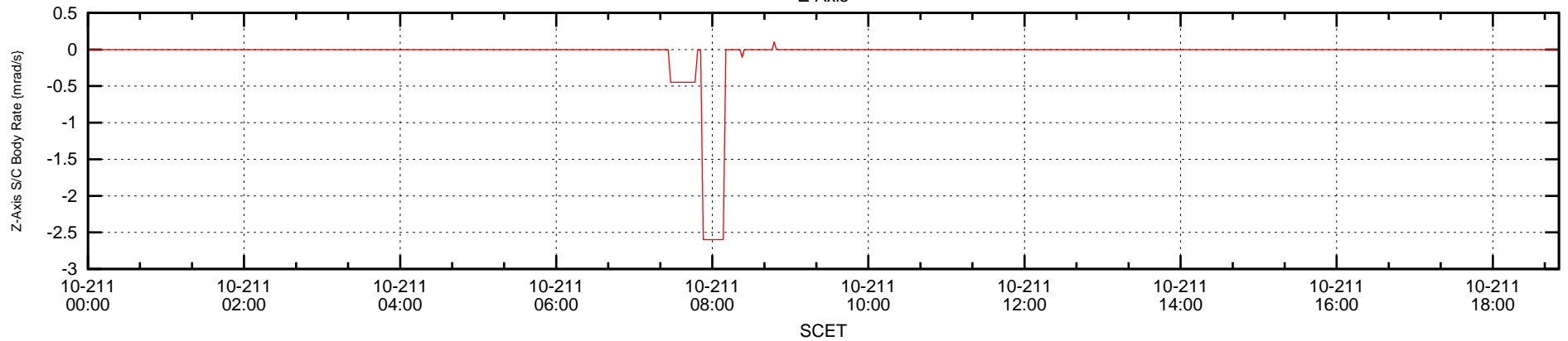
X-Axis (CK #2 = 10176\_10211py\_as\_flowm.bc)



Y-Axis



Z-Axis





All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 211-211)

