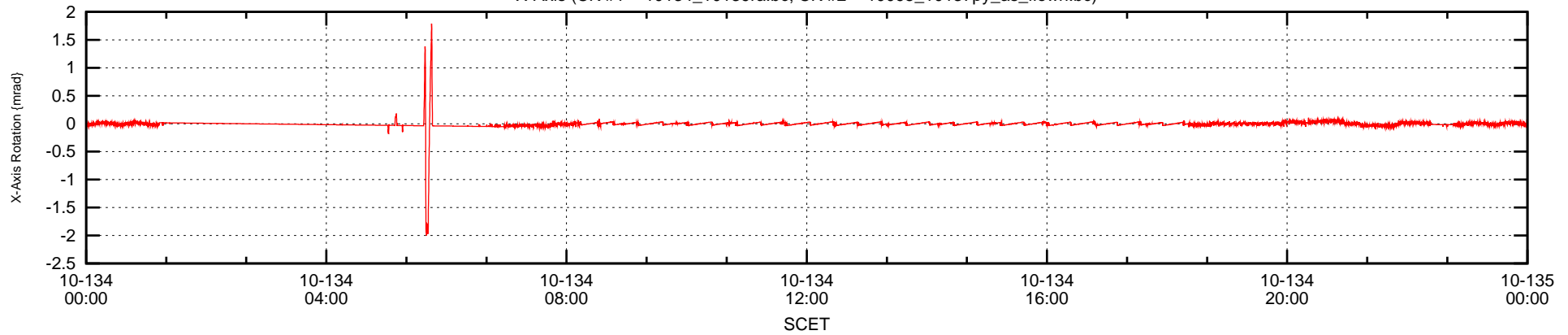
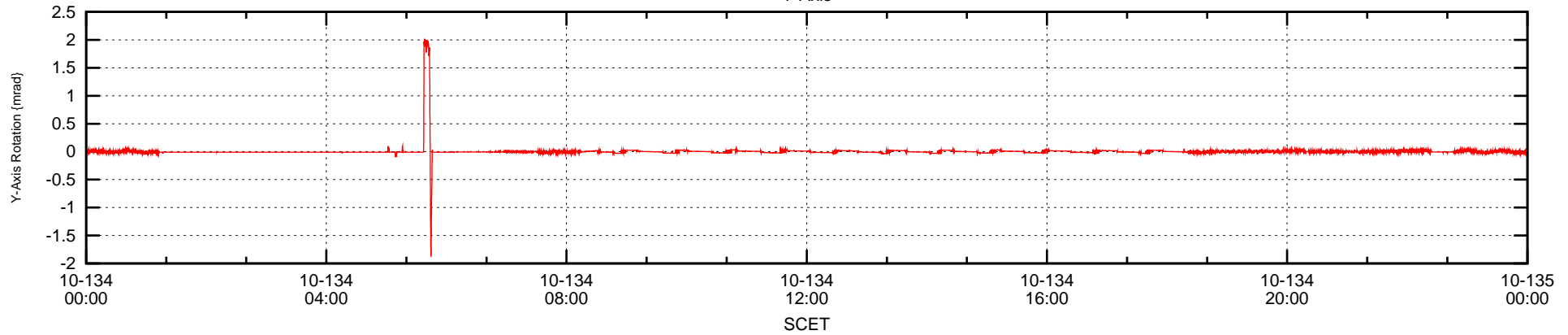


# Rotation From CK #2 to CK #1 (DOY 134-135)

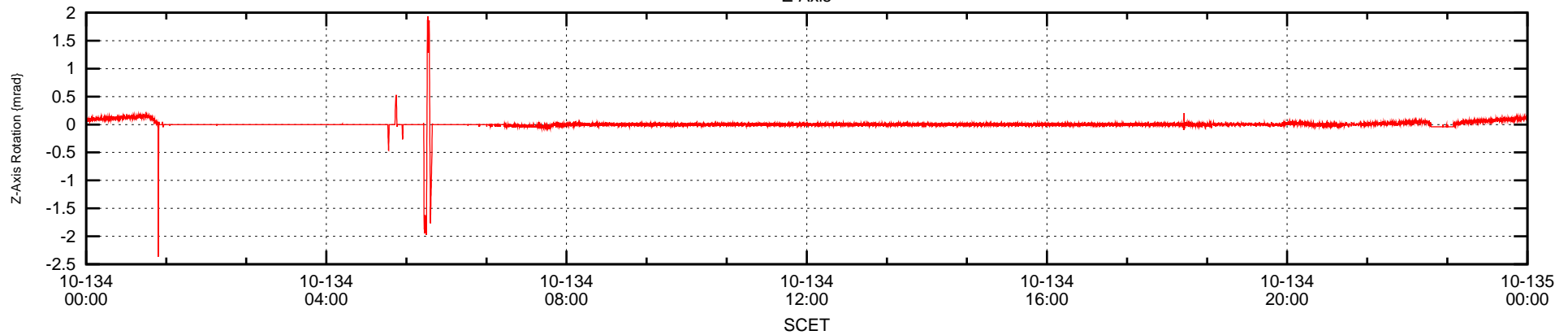
X-Axis (CK #1 = 10134\_10139ra.bc; CK #2 = 10095\_10137py\_as\_flowm.bc)



Y-Axis

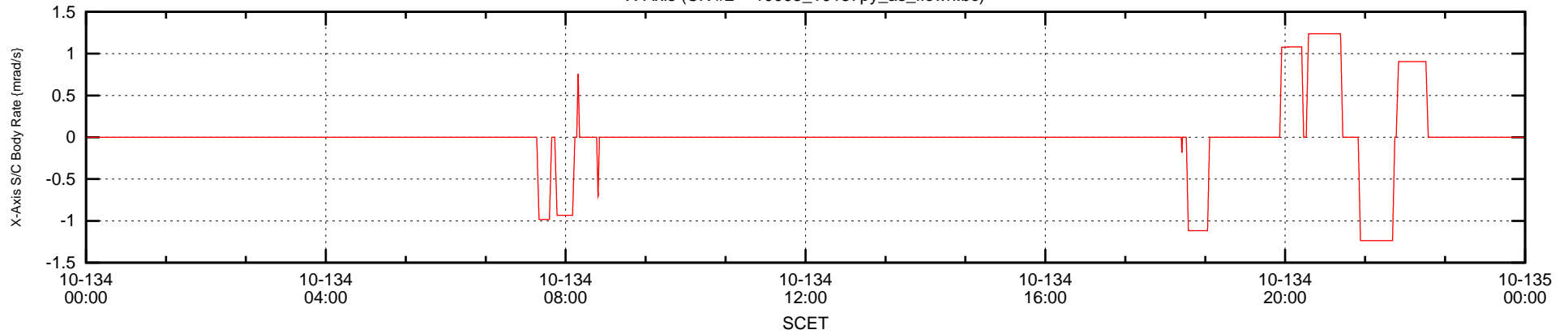


Z-Axis

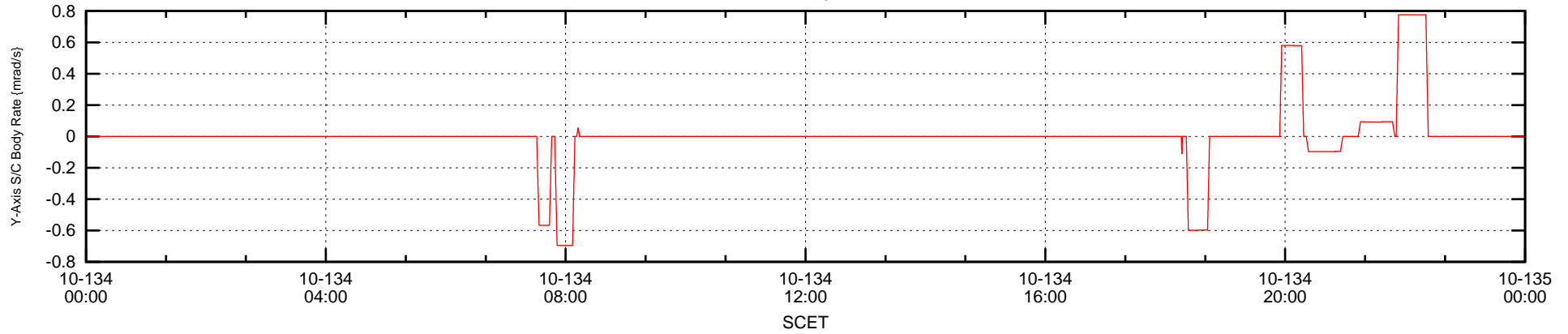


# CK #2 S/C Body Rates (DOY 134-135)

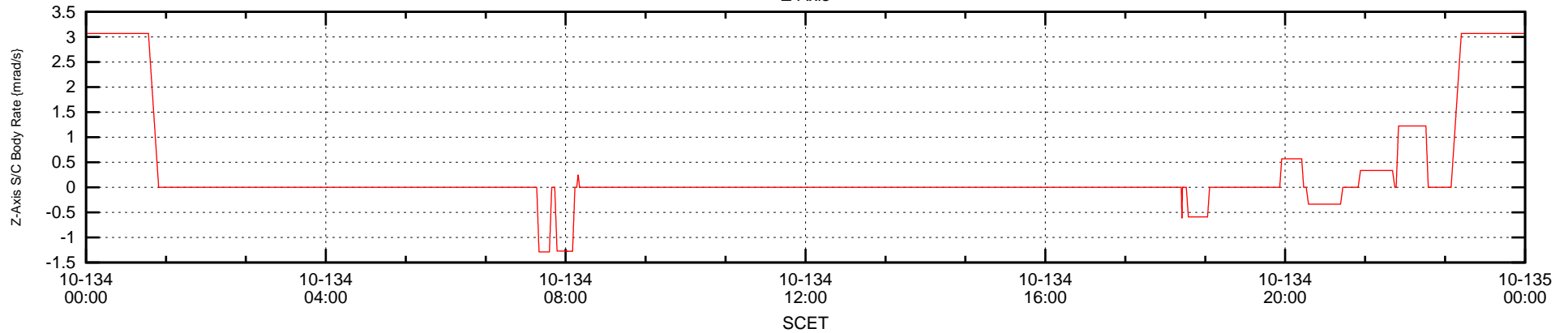
X-Axis (CK #2 = 10095\_10137py\_as\_flowm.bc)



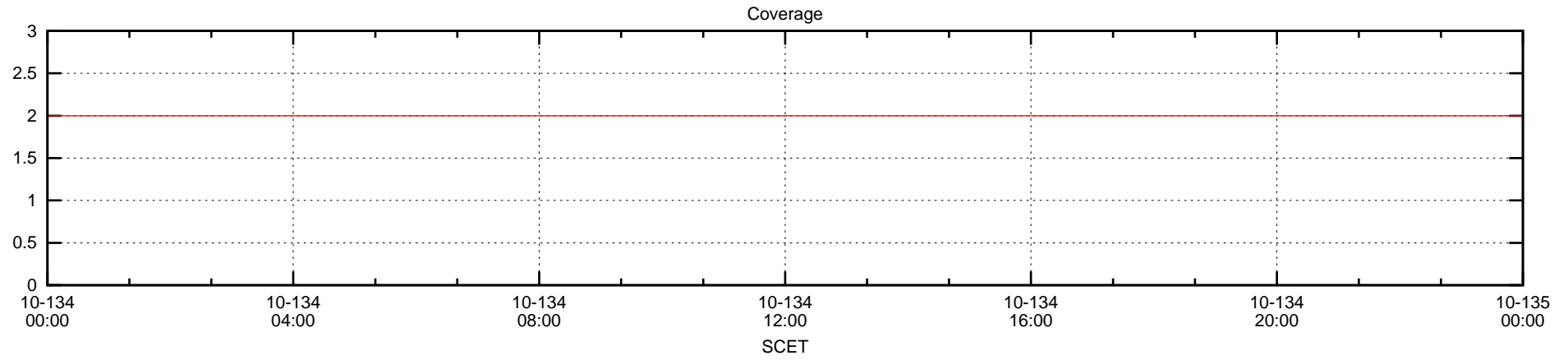
Y-Axis



Z-Axis

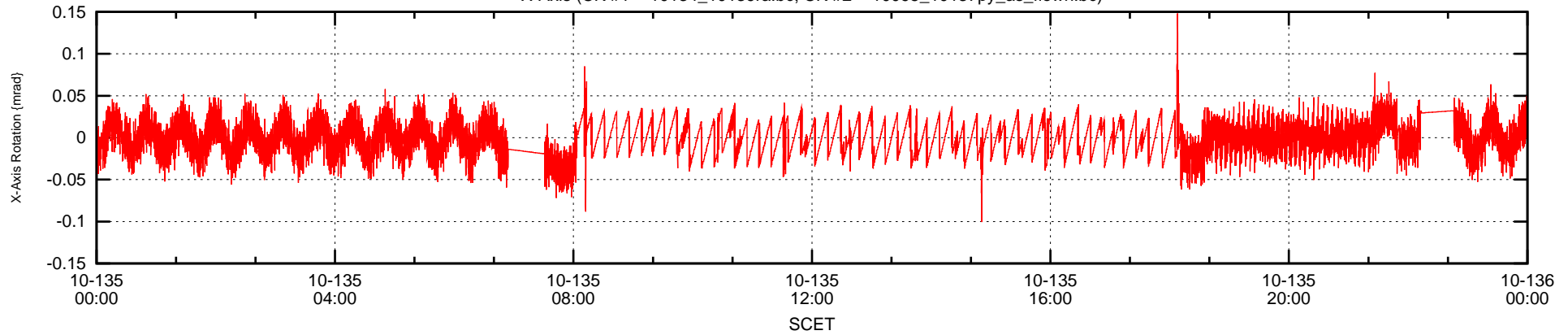


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 134-135)

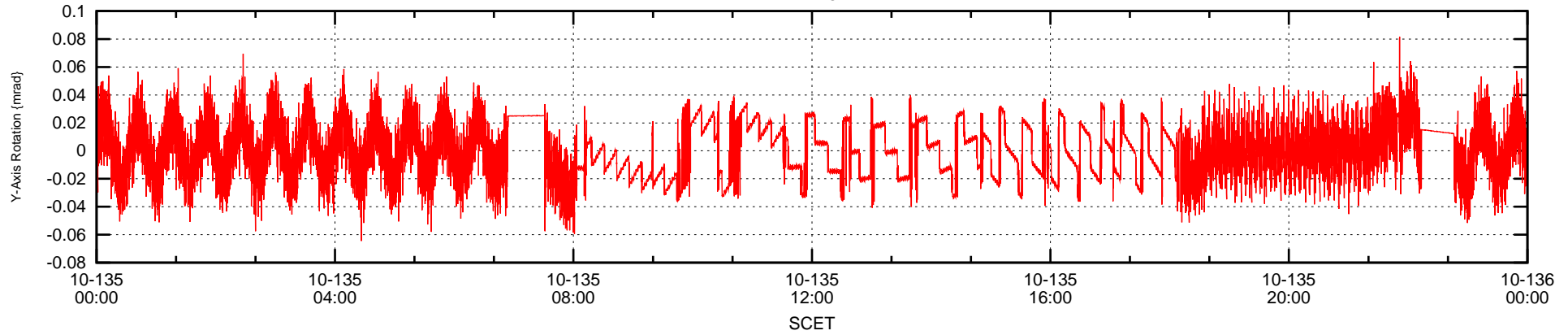


# Rotation From CK #2 to CK #1 (DOY 135-136)

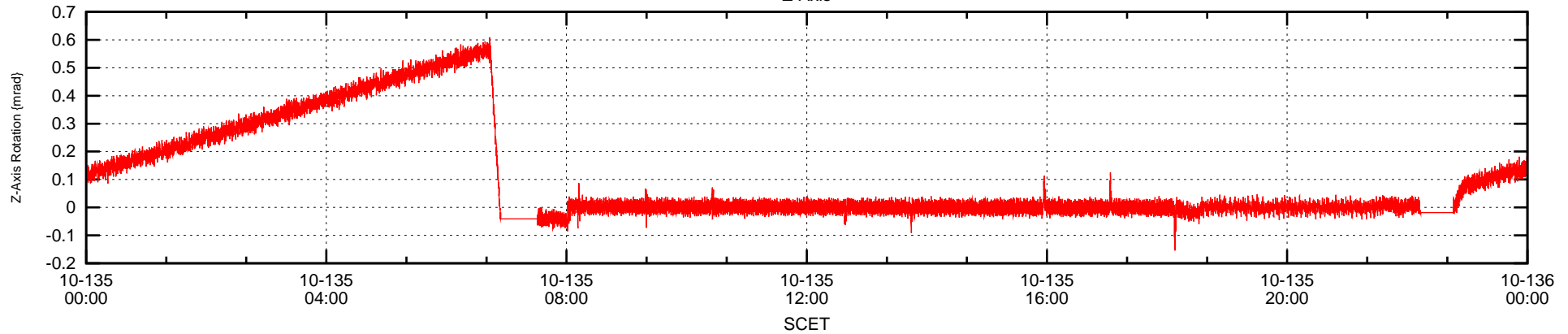
X-Axis (CK #1 = 10134\_10139ra.bc; CK #2 = 10095\_10137py\_as\_flown.bc)



Y-Axis

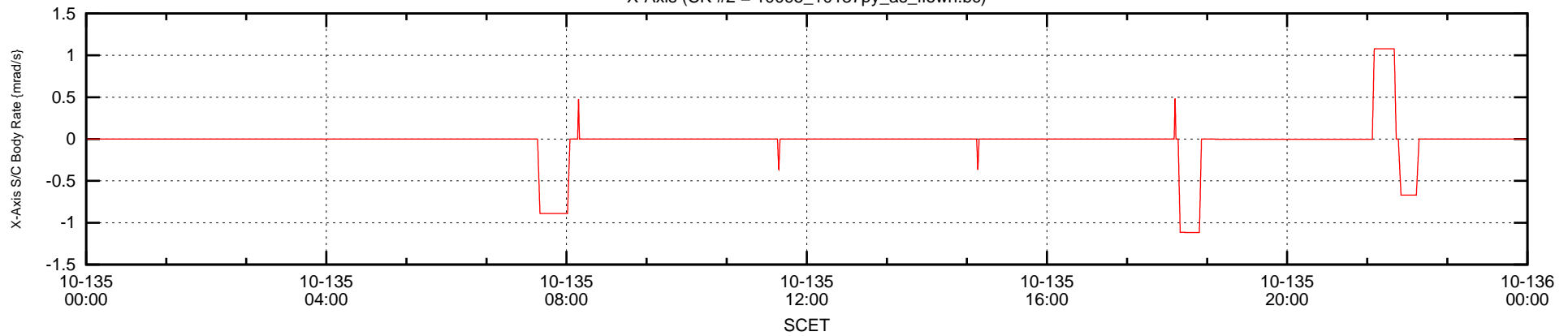


Z-Axis

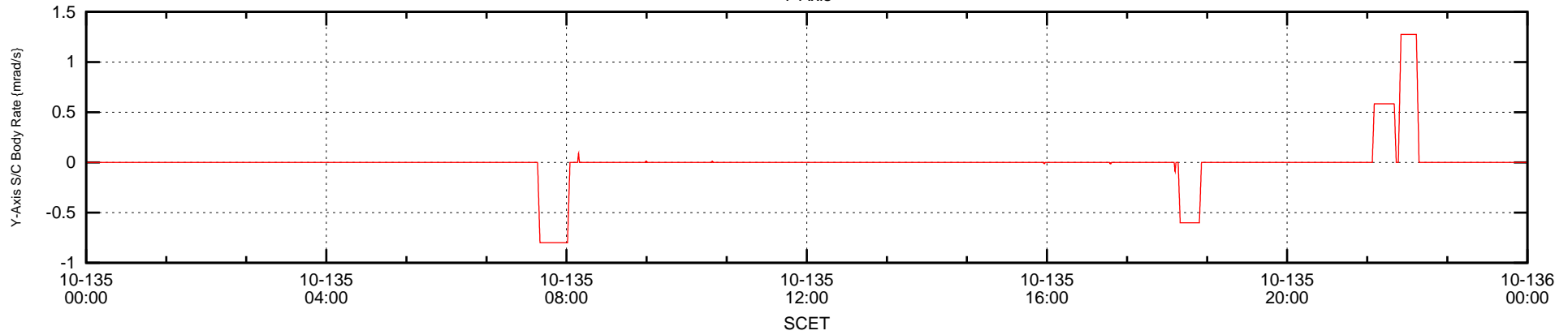


# CK #2 S/C Body Rates (DOY 135-136)

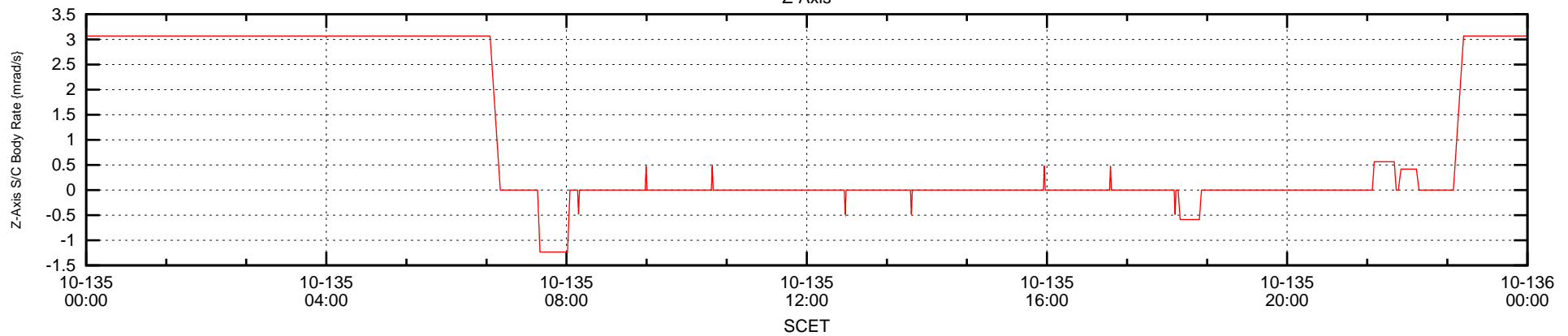
X-Axis (CK #2 = 10095\_10137py\_as\_flowm.bc)



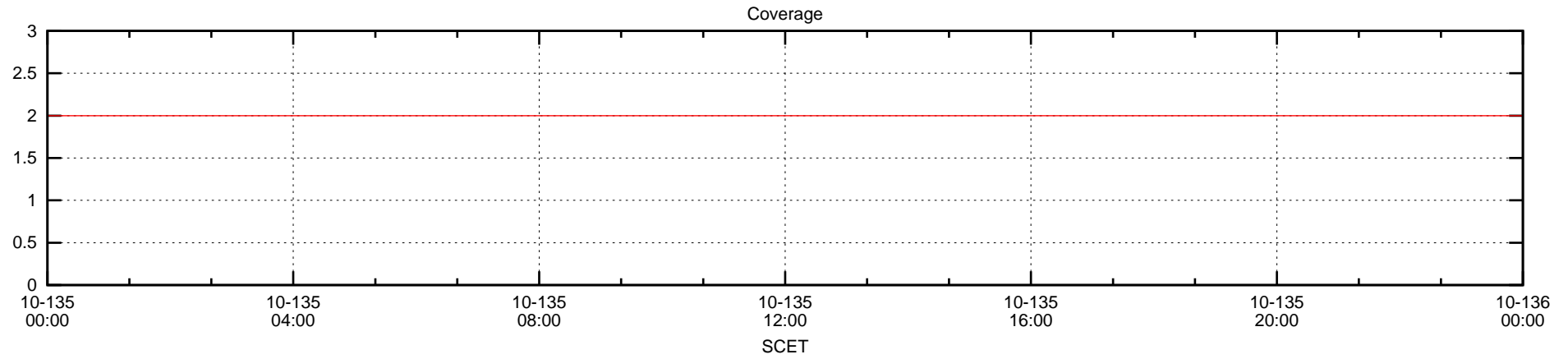
Y-Axis



Z-Axis

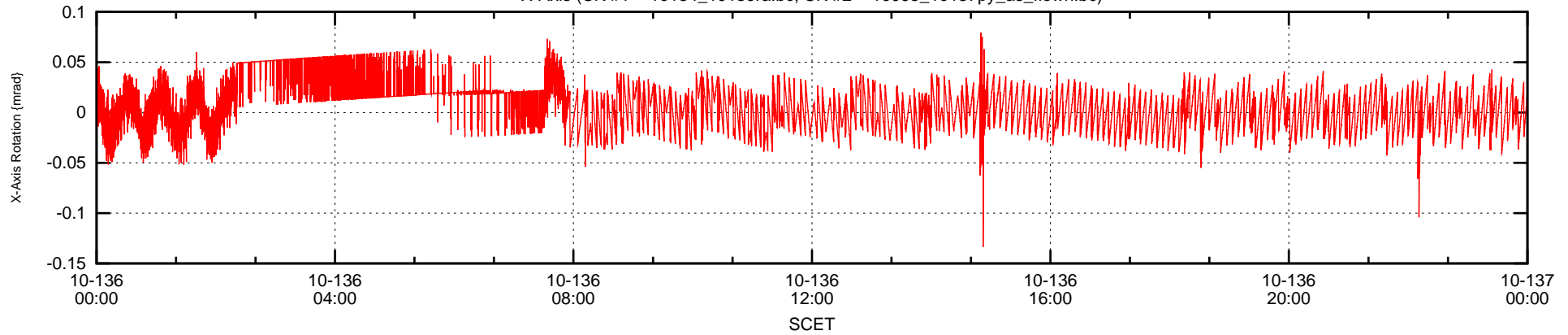


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 135-136)

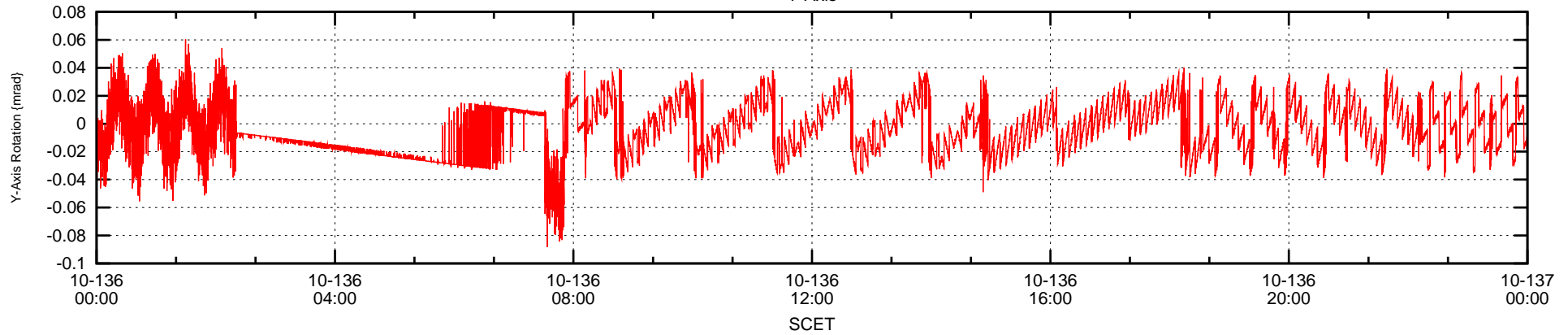


# Rotation From CK #2 to CK #1 (DOY 136-137)

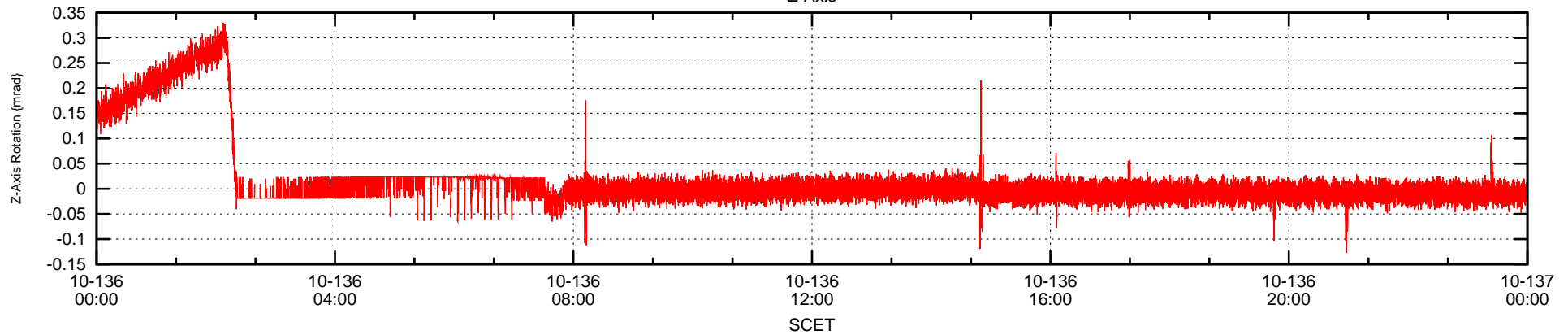
X-Axis (CK #1 = 10134\_10139ra.bc; CK #2 = 10095\_10137py\_as\_flowm.bc)



Y-Axis

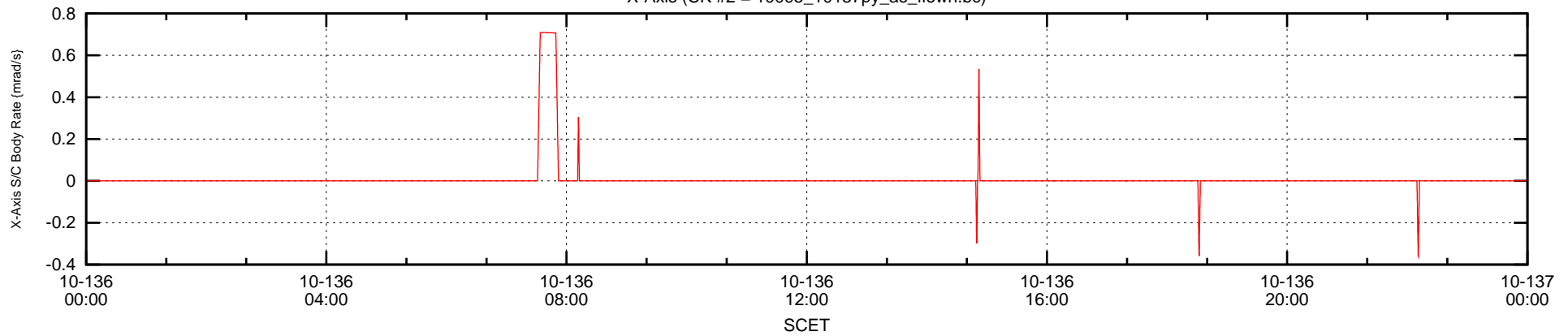


Z-Axis

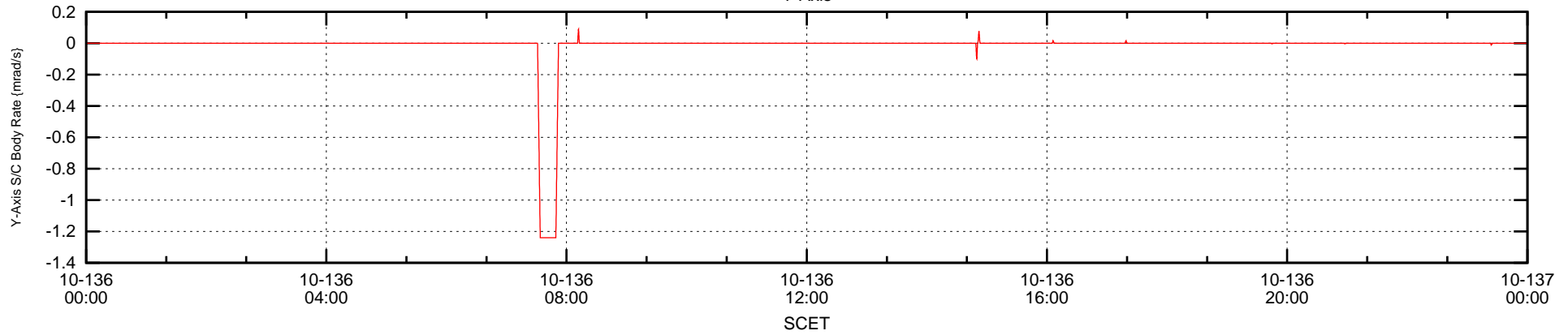


# CK #2 S/C Body Rates (DOY 136-137)

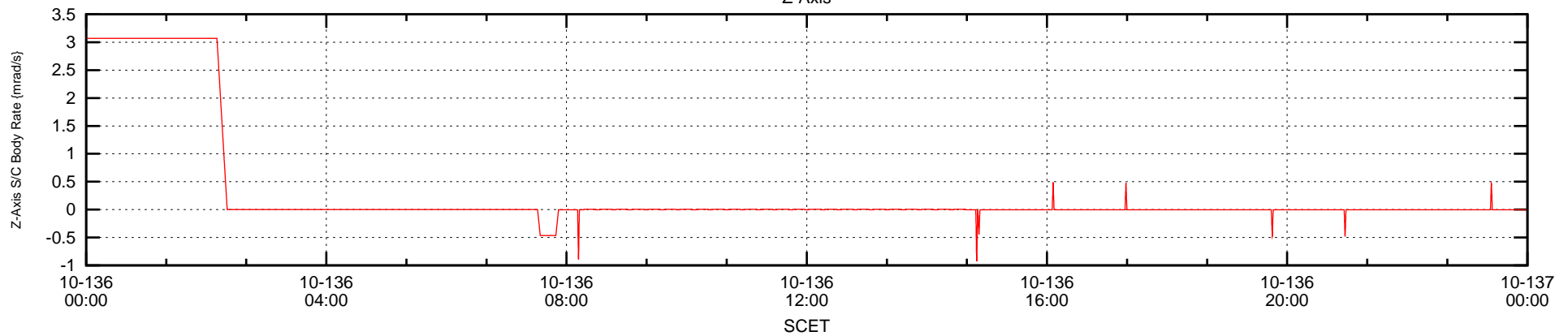
X-Axis (CK #2 = 10095\_10137py\_as\_flowm.bc)



Y-Axis

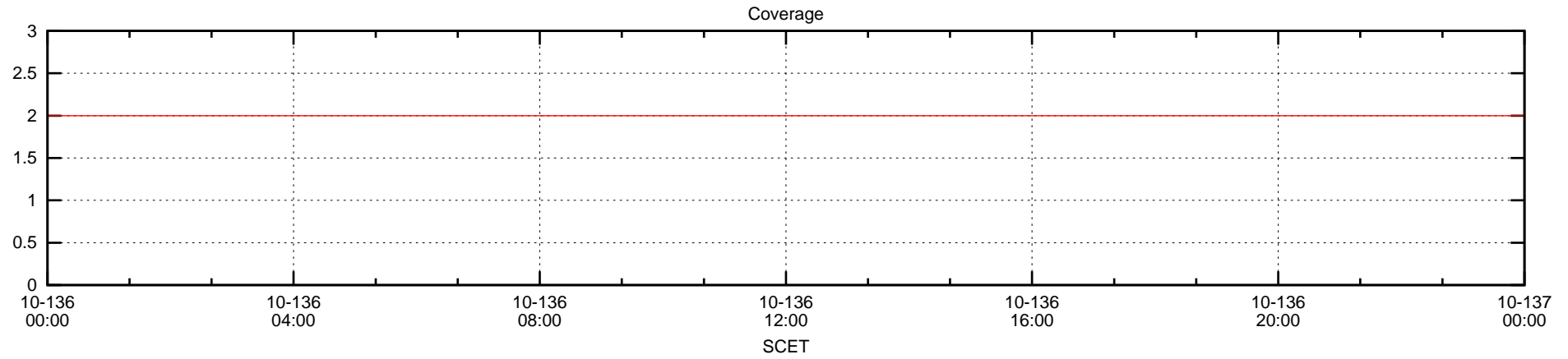


Z-Axis



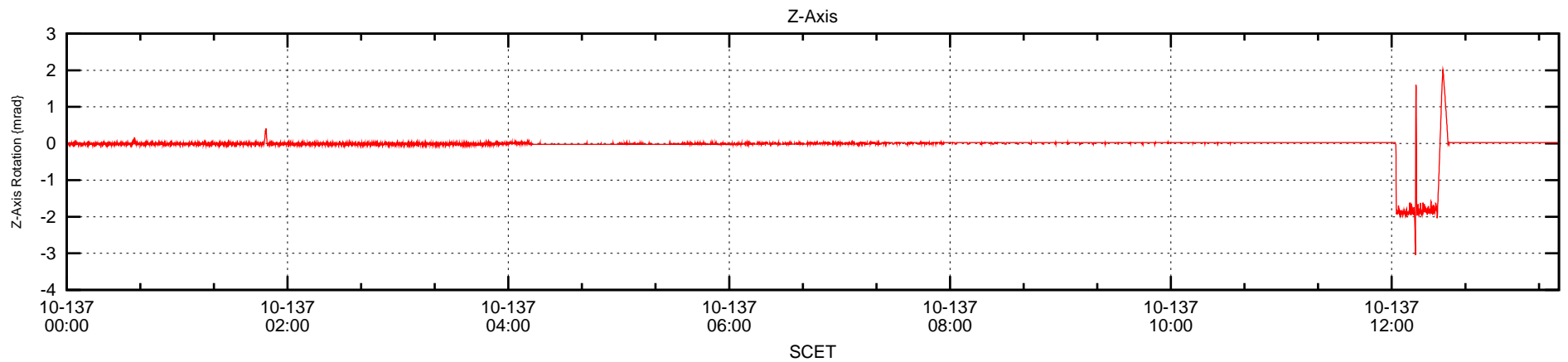
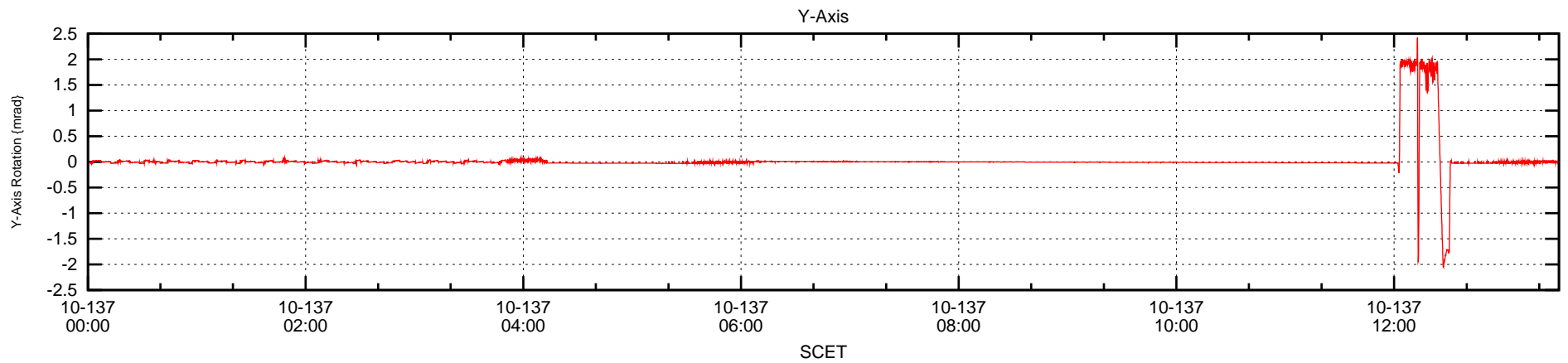
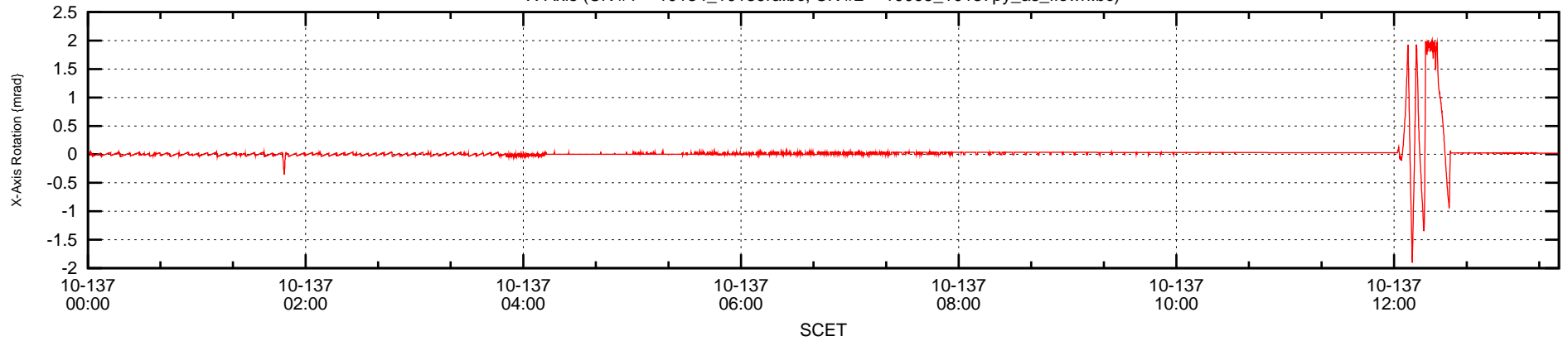


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 136-137)



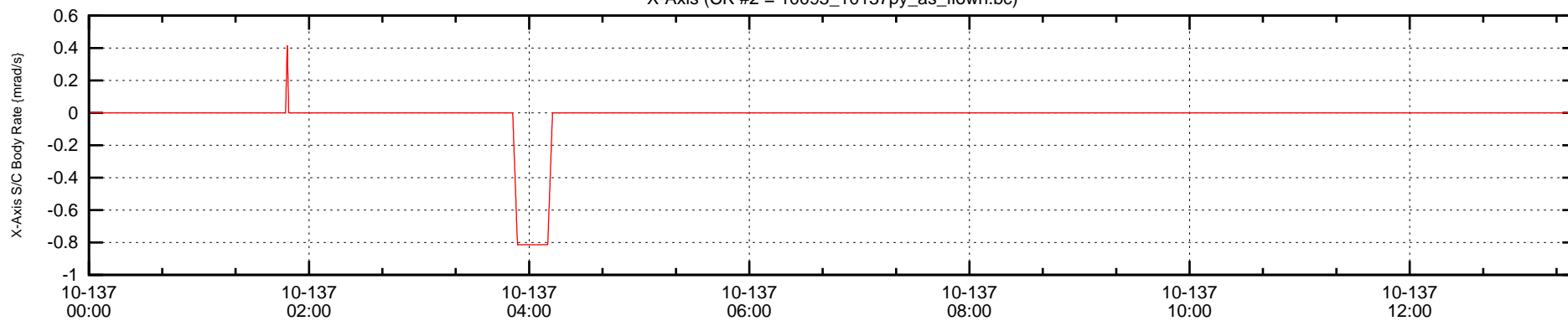
# Rotation From CK #2 to CK #1 (DOY 137-137)

X-Axis (CK #1 = 10134\_10139ra.bc; CK #2 = 10095\_10137py\_as\_flown.bc)



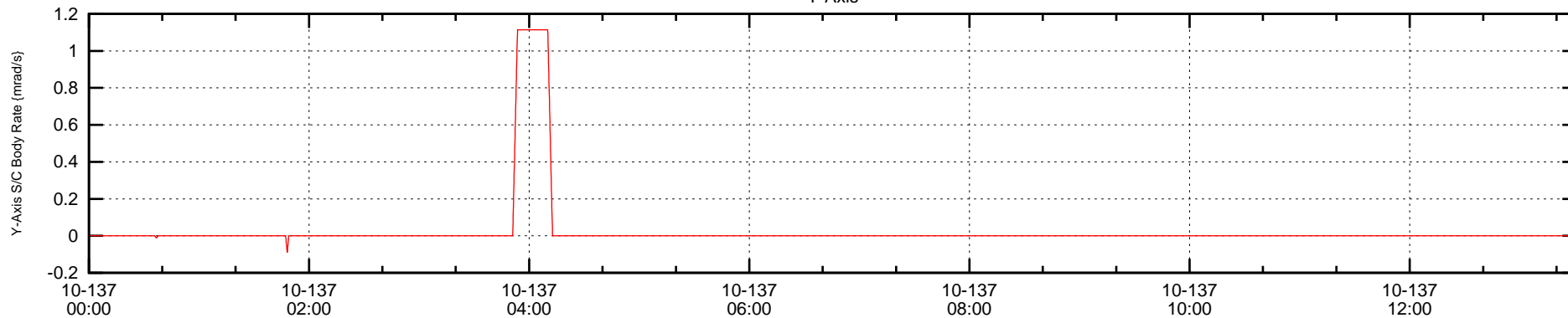
# CK #2 S/C Body Rates (DOY 137-137)

X-Axis (CK #2 = 10095\_10137py\_as\_flown.bc)



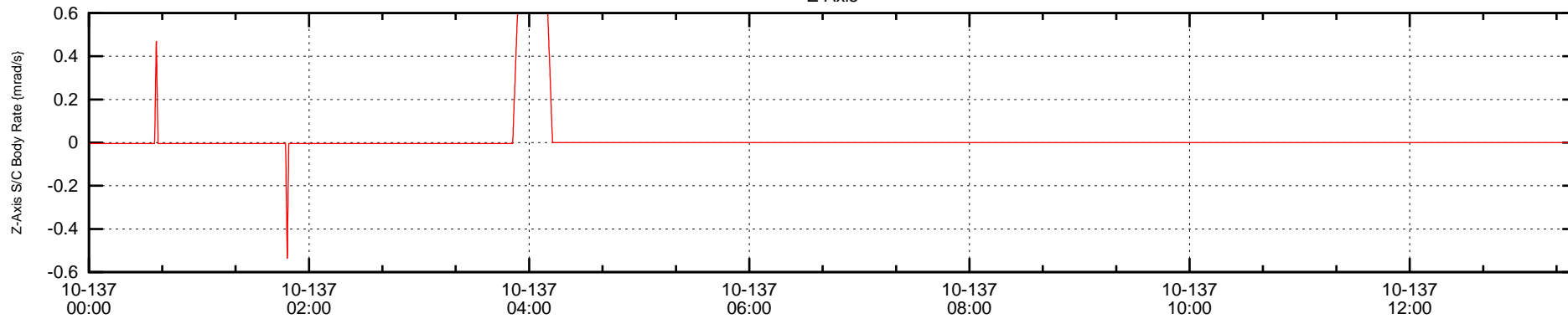
SCET

Y-Axis



SCET

Z-Axis



SCET

All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 137-137)

