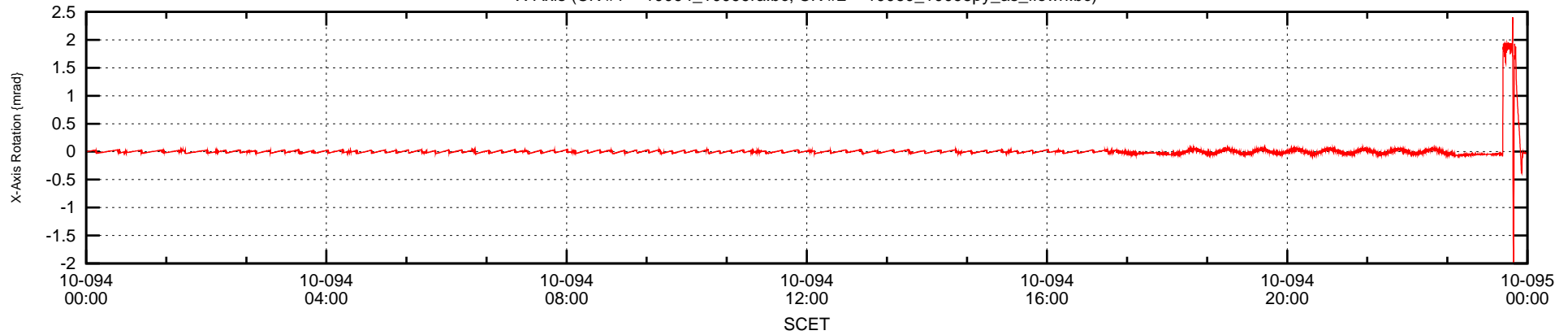
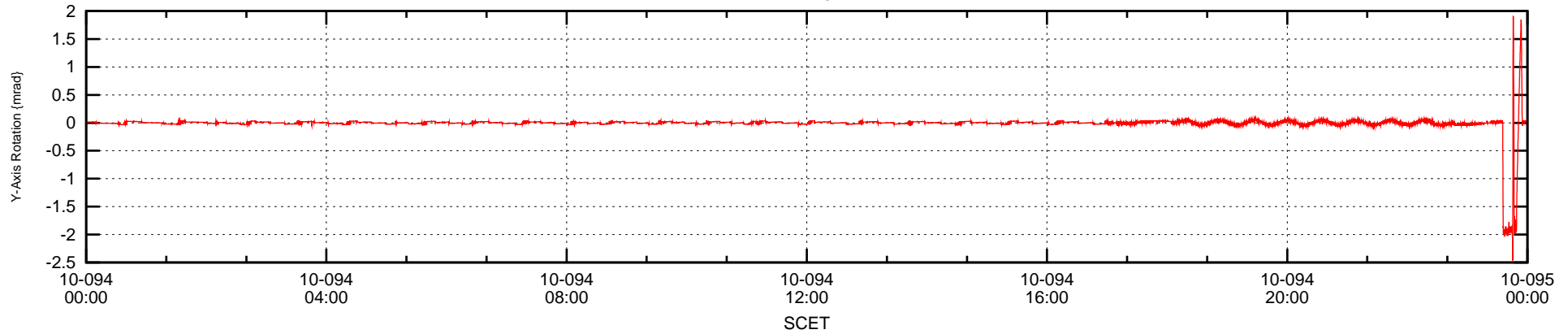


Rotation From CK #2 to CK #1 (DOY 094-095)

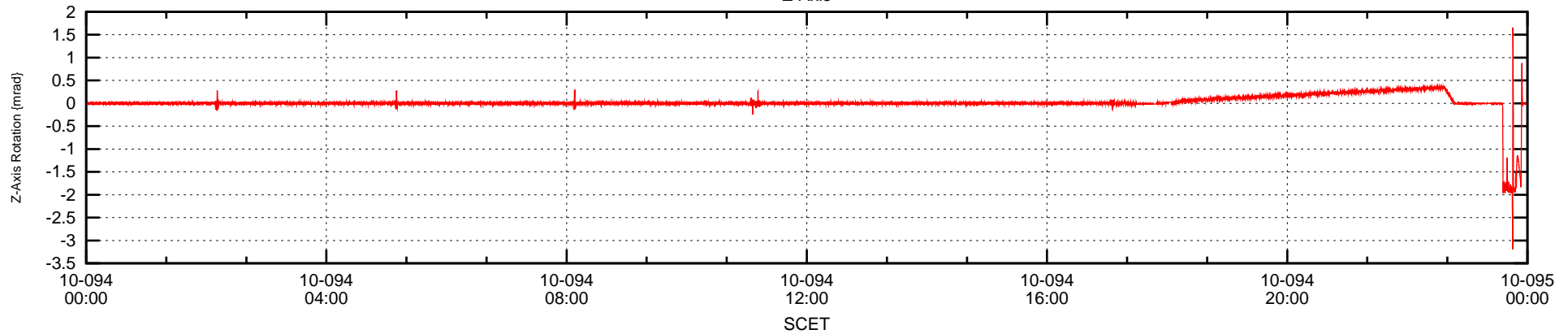
X-Axis (CK #1 = 10094_10099ra.bc; CK #2 = 10060_10095py_as_flowm.bc)



Y-Axis

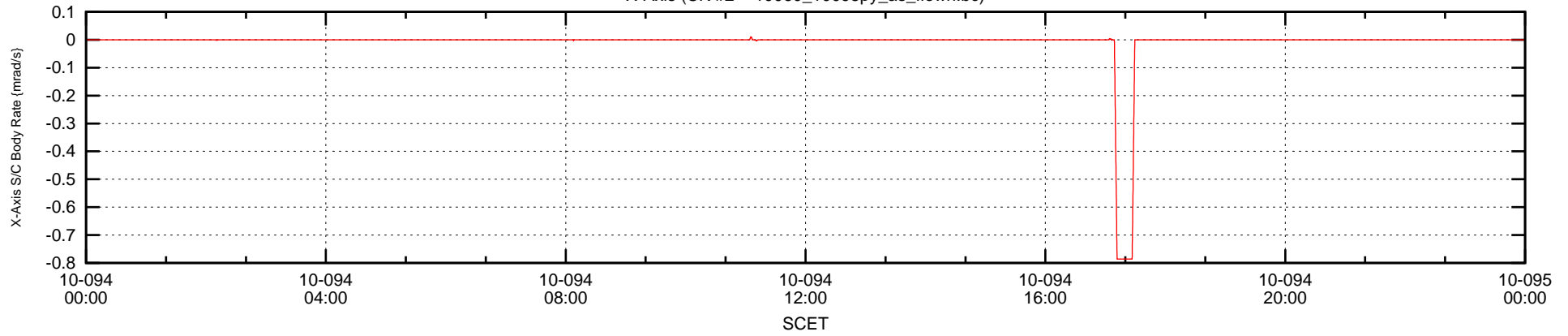


Z-Axis

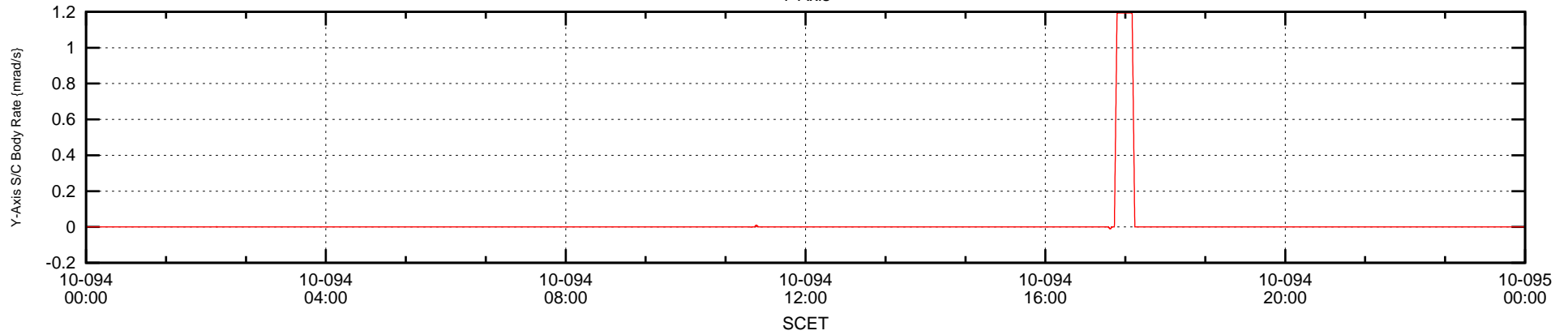


CK #2 S/C Body Rates (DOY 094-095)

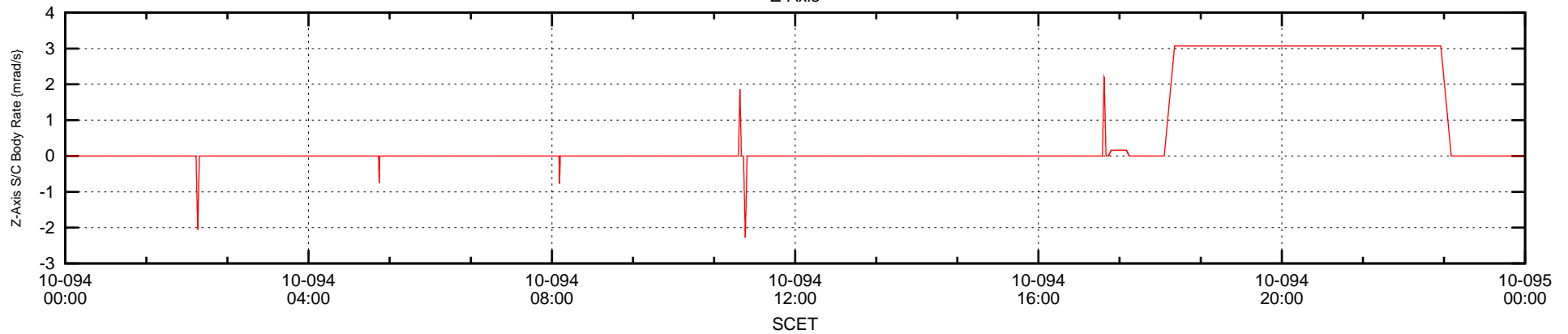
X-Axis (CK #2 = 10060_10095py_as_flowm.bc)



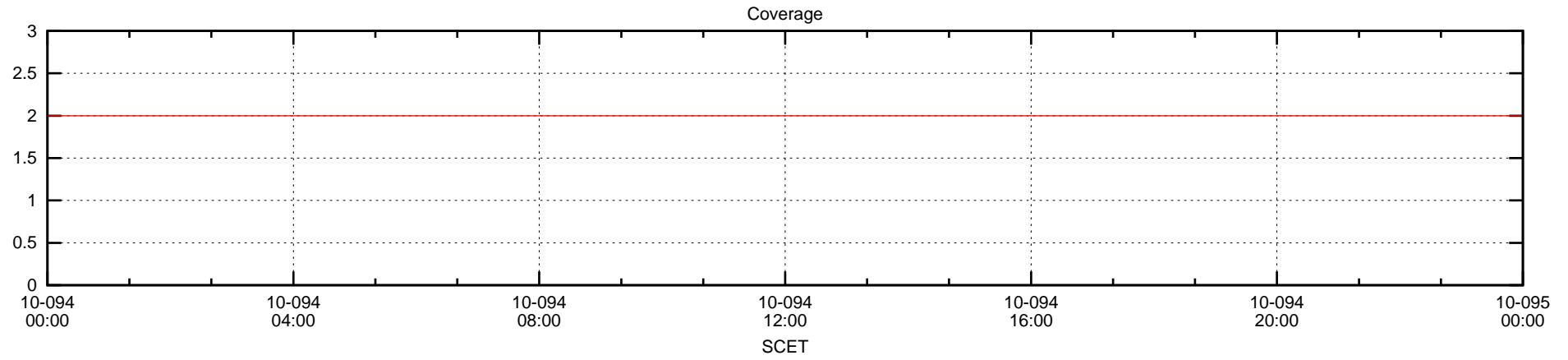
Y-Axis



Z-Axis

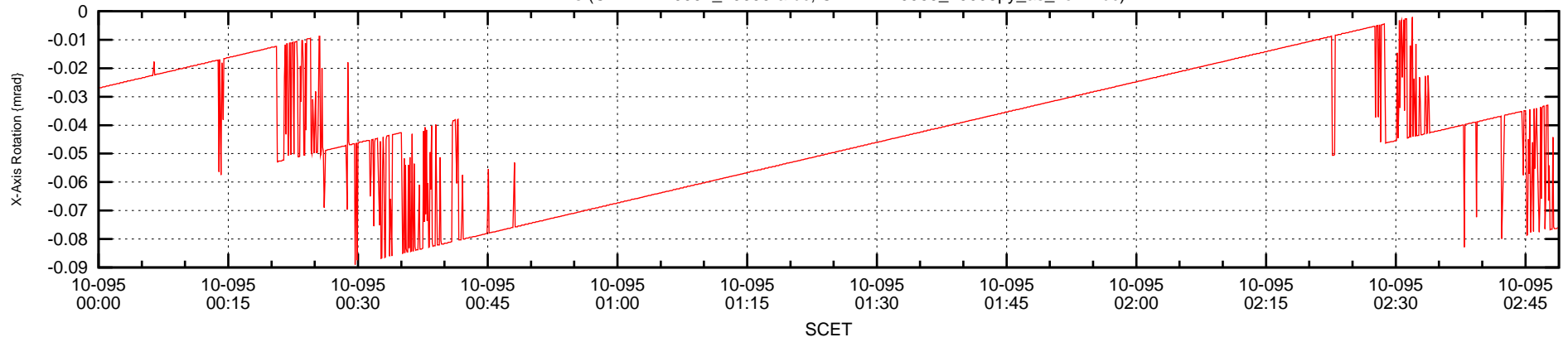


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 094-095)

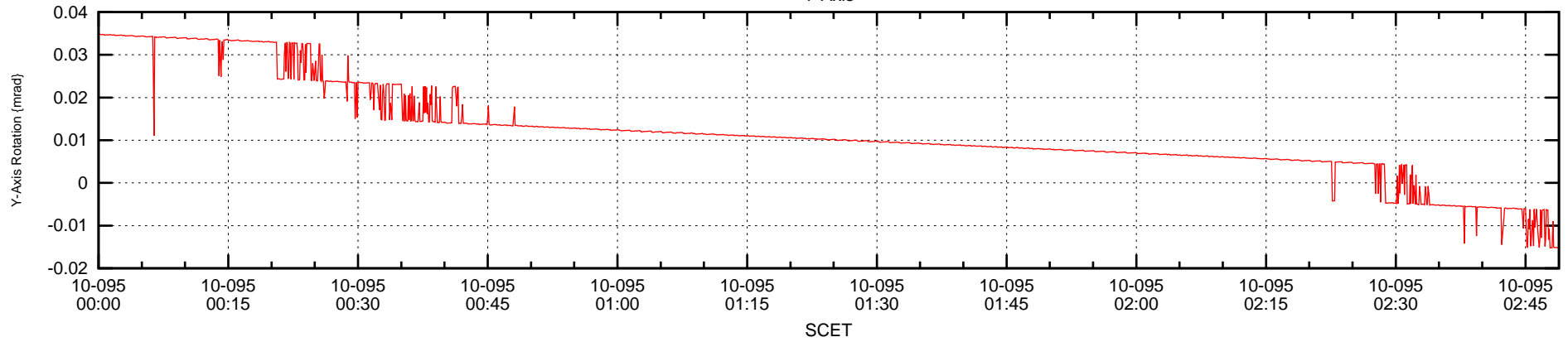


Rotation From CK #2 to CK #1 (DOY 095-095)

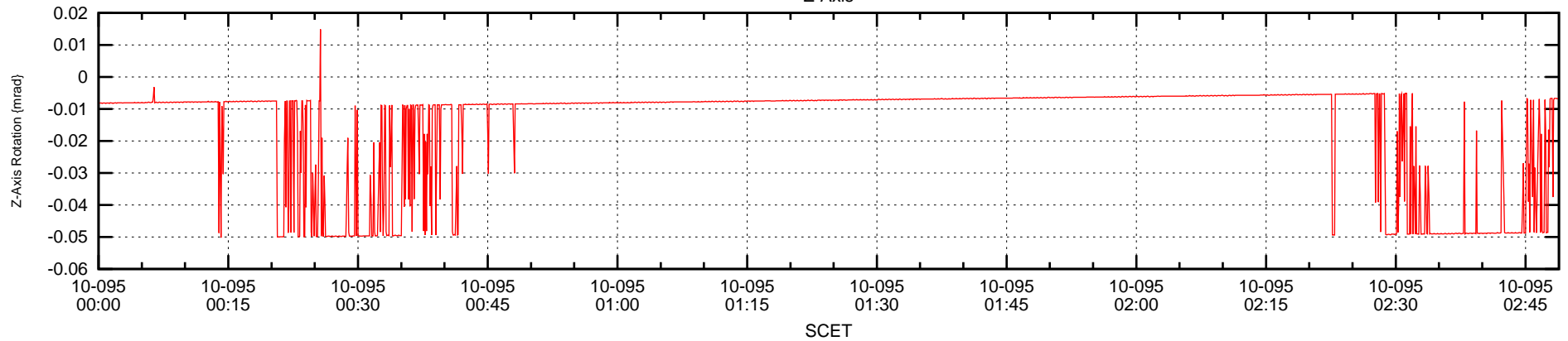
X-Axis (CK #1 = 10094_10099ra.bc; CK #2 = 10060_10095py_as_flowm.bc)



Y-Axis

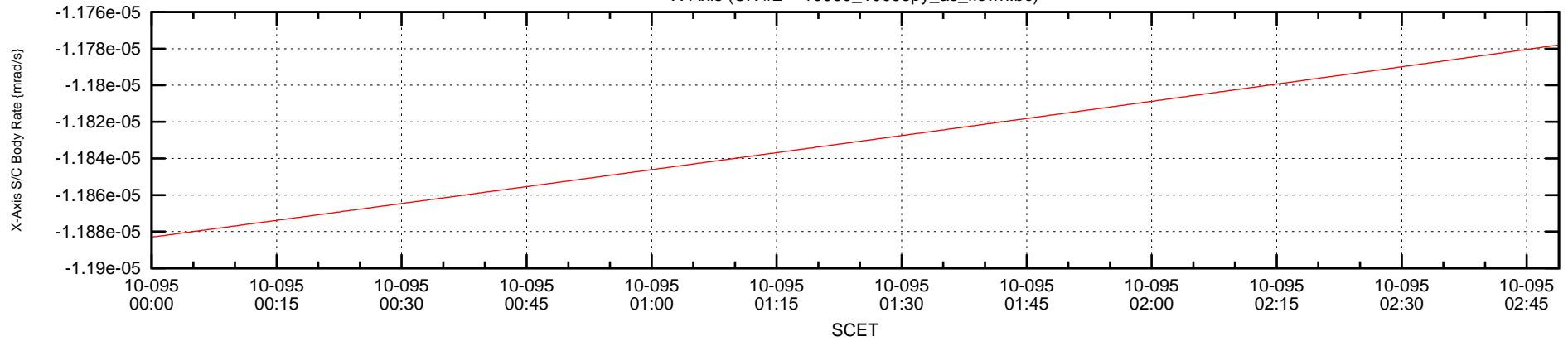


Z-Axis

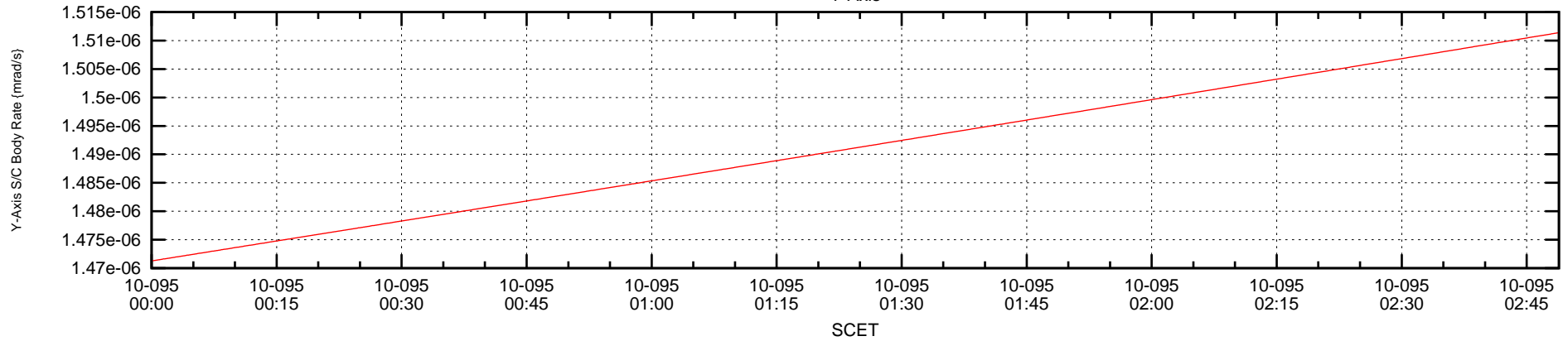


CK #2 S/C Body Rates (DOY 095-095)

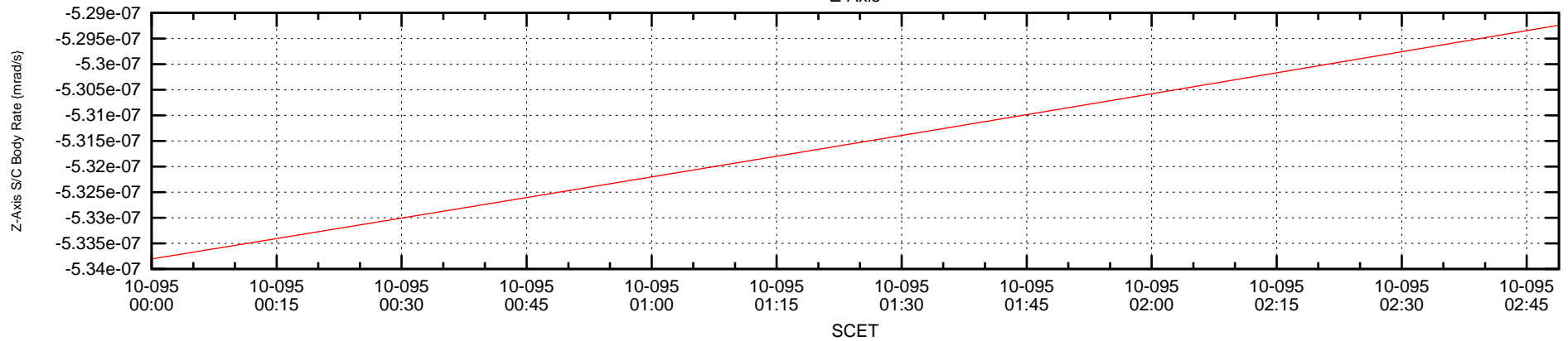
X-Axis (CK #2 = 10060_10095py_as_flown.bc)



Y-Axis



Z-Axis



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 095-095)

