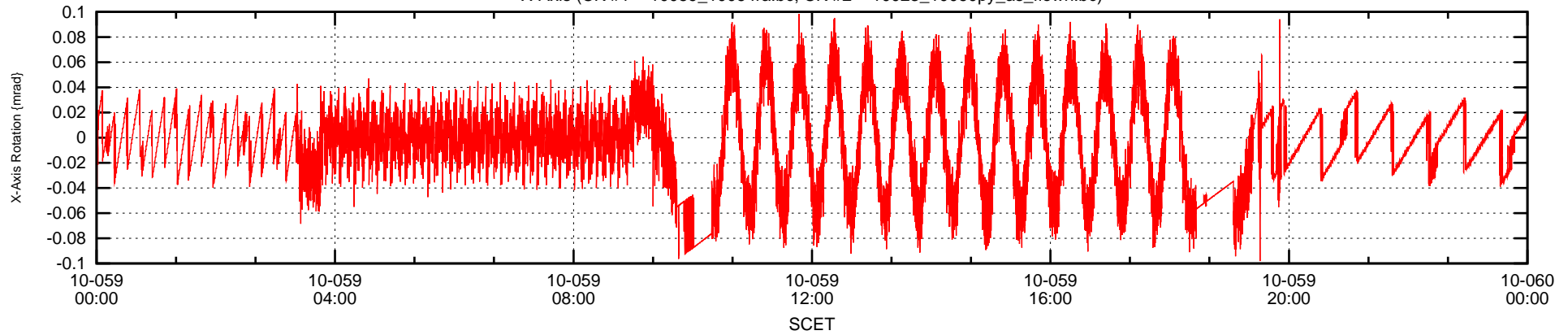
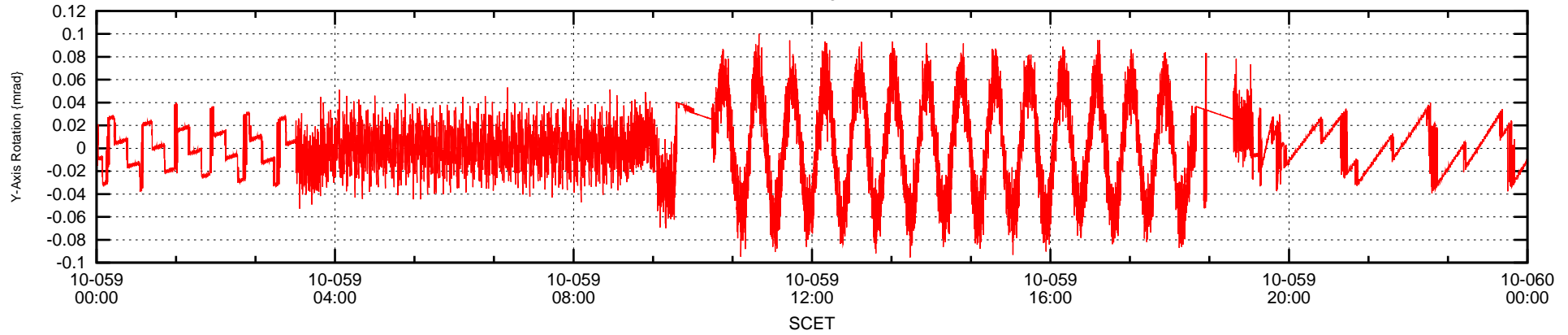


Rotation From CK #2 to CK #1 (DOY 059-060)

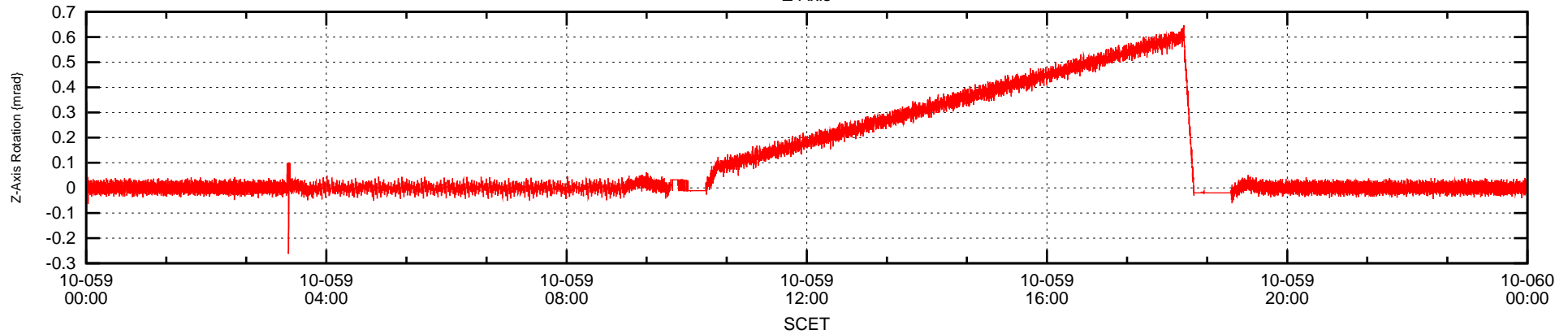
X-Axis (CK #1 = 10059_10064ra.bc; CK #2 = 10023_10060py_as_flow.bc)



Y-Axis

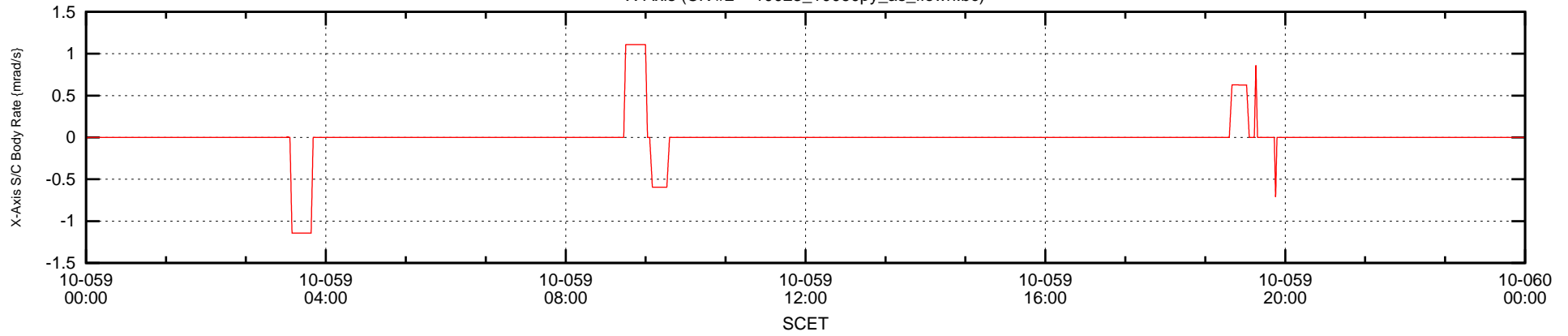


Z-Axis

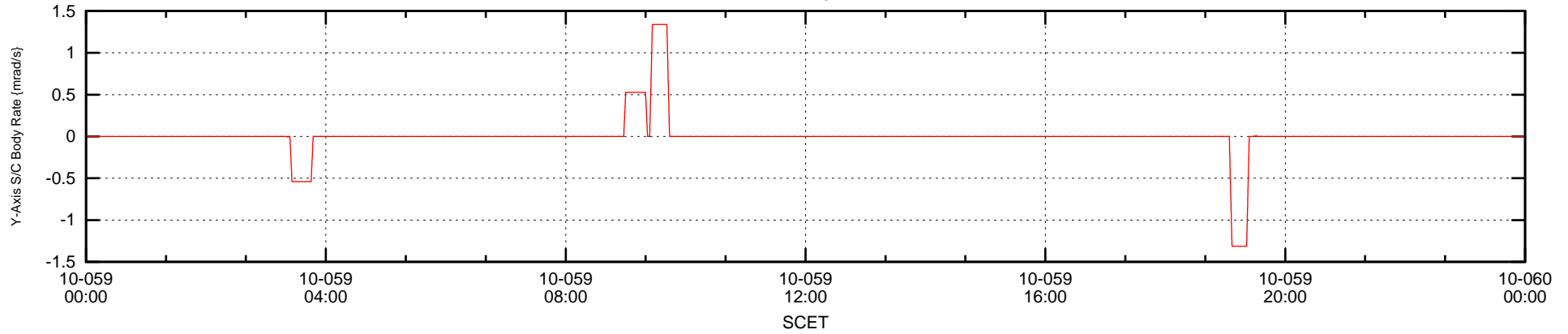


CK #2 S/C Body Rates (DOY 059-060)

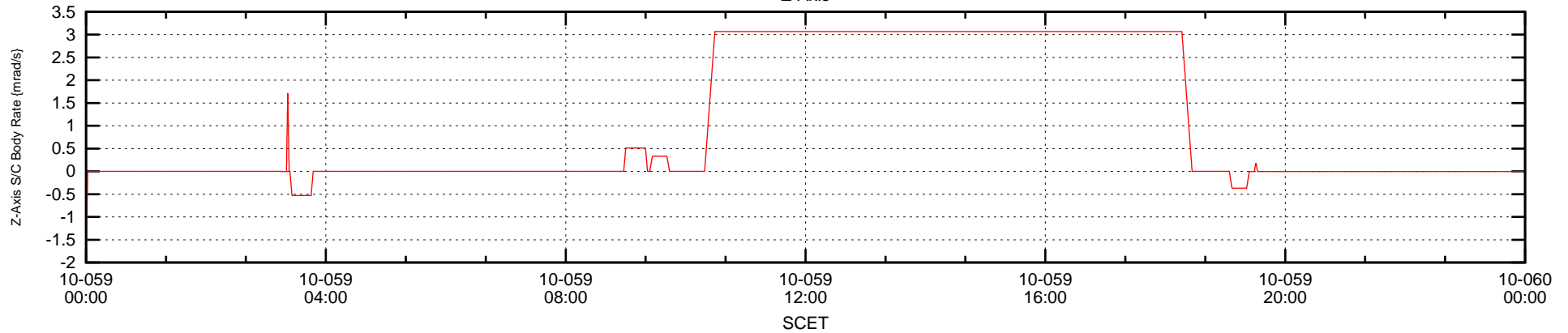
X-Axis (CK #2 = 10023_10060py_as_flowm.bc)



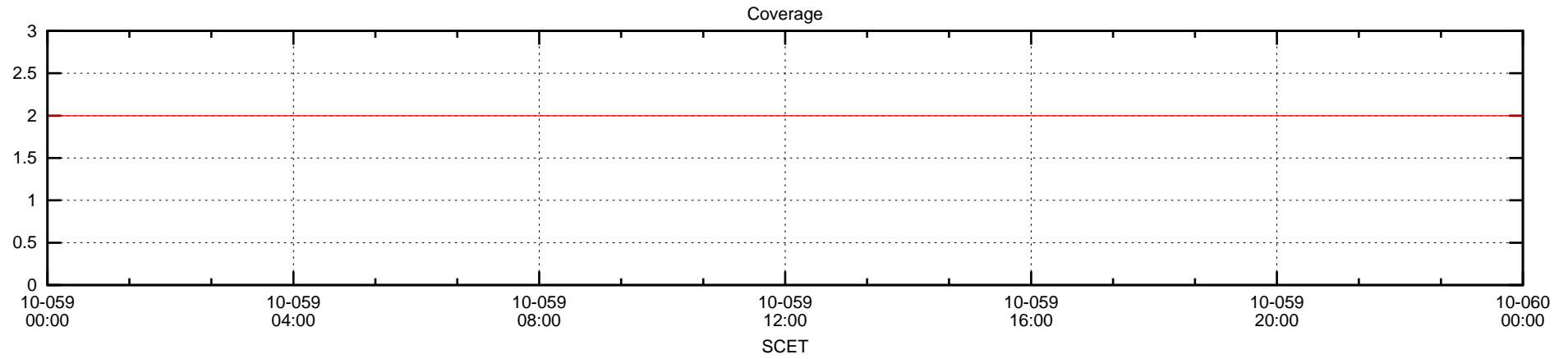
Y-Axis



Z-Axis

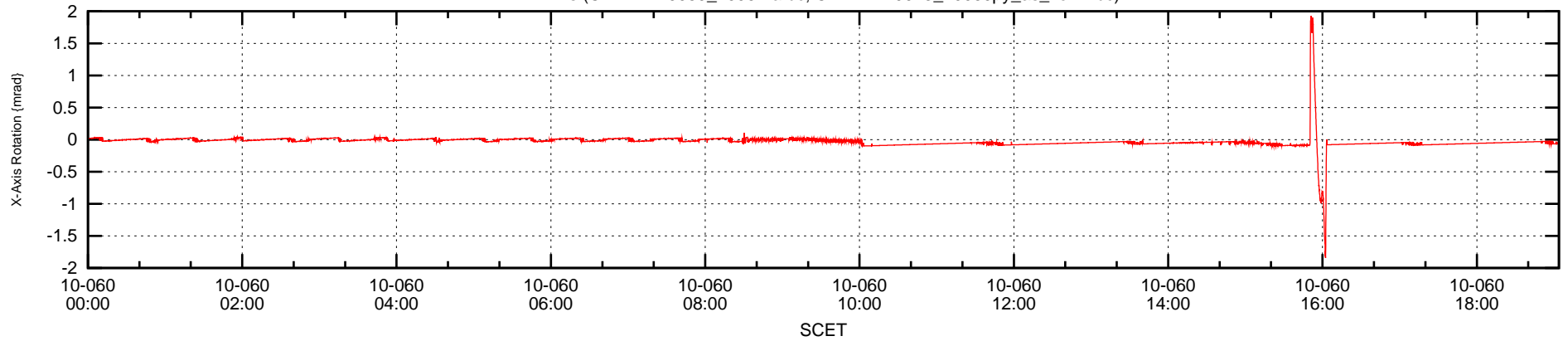


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 059-060)

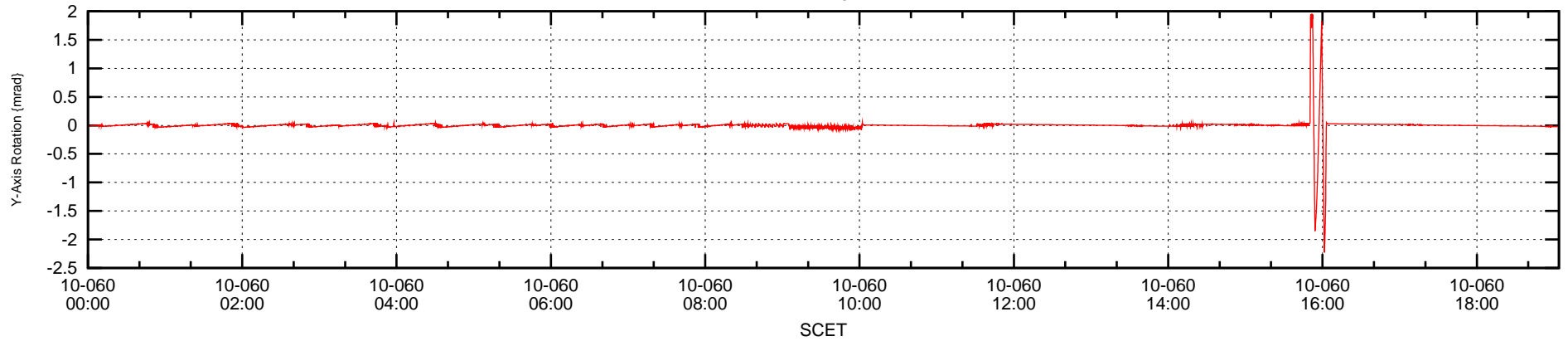


Rotation From CK #2 to CK #1 (DOY 060-060)

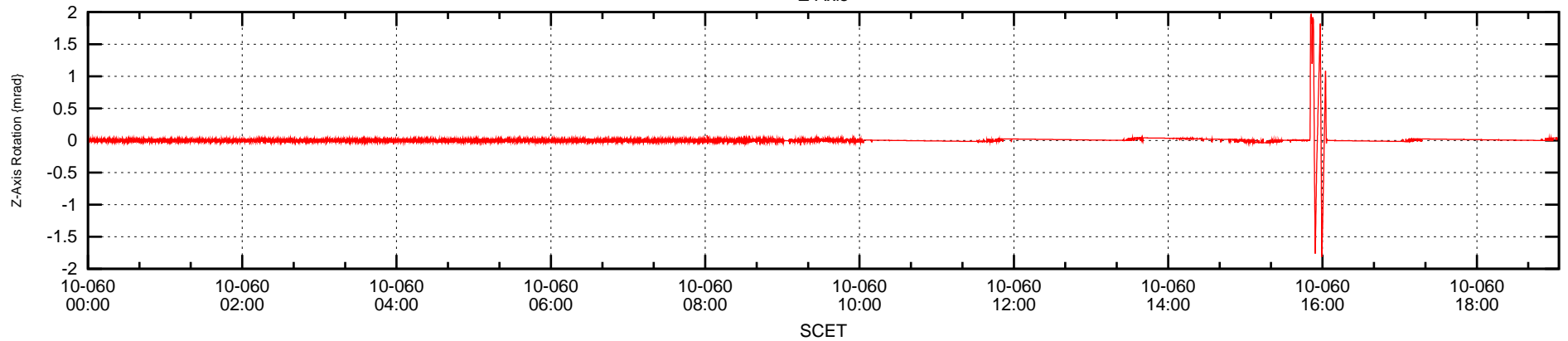
X-Axis (CK #1 = 10059_10064ra.bc; CK #2 = 10023_10060py_as_flown.bc)



Y-Axis

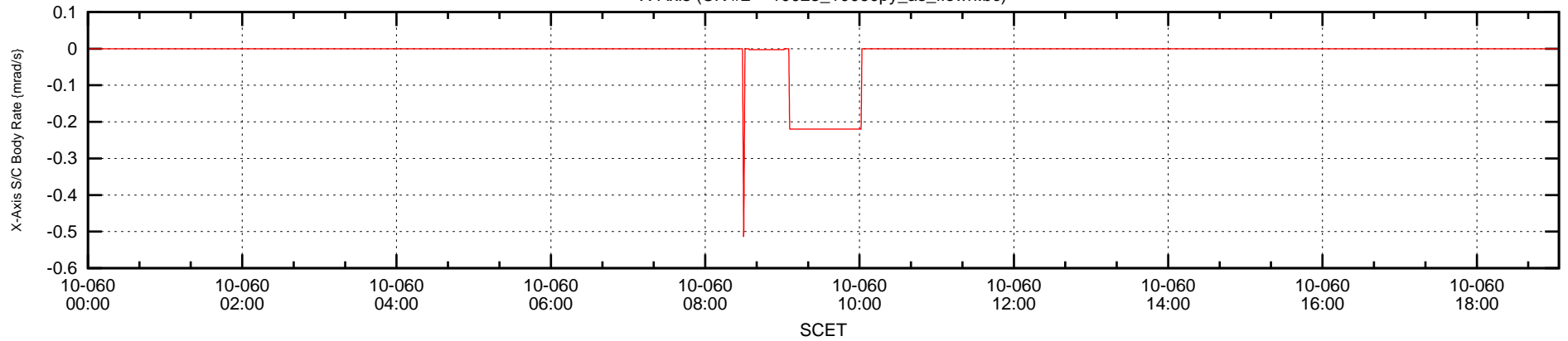


Z-Axis

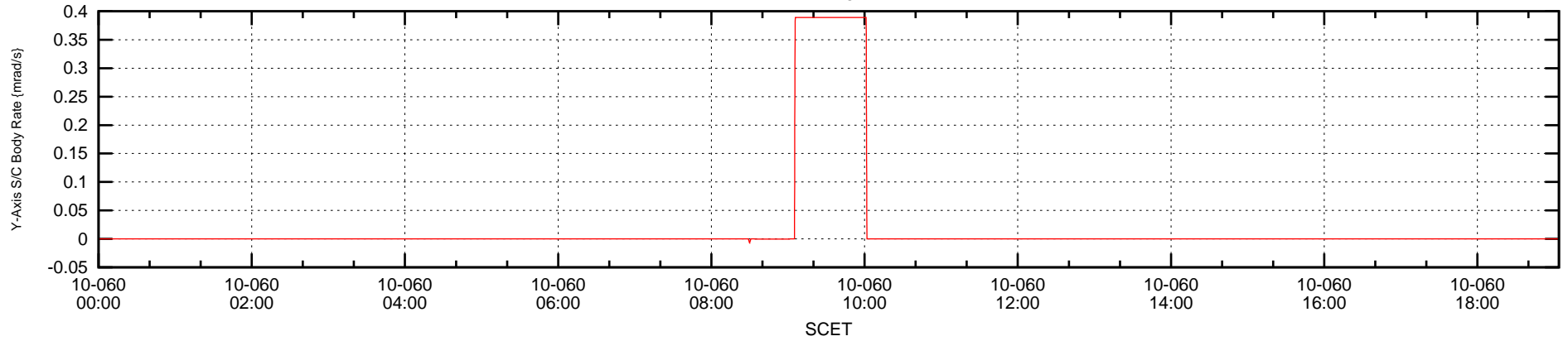


CK #2 S/C Body Rates (DOY 060-060)

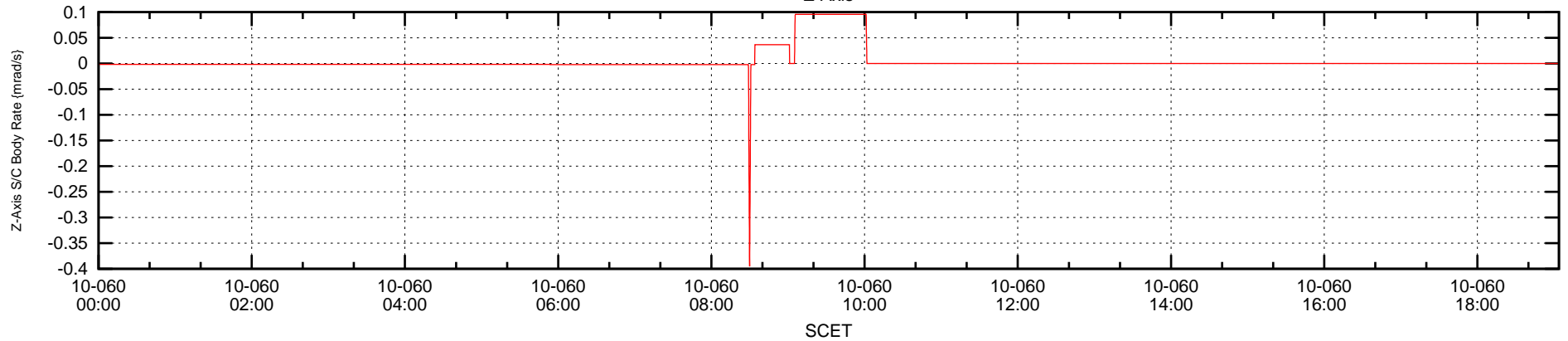
X-Axis (CK #2 = 10023_10060py_as_flown.bc)



Y-Axis



Z-Axis



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 060-060)

