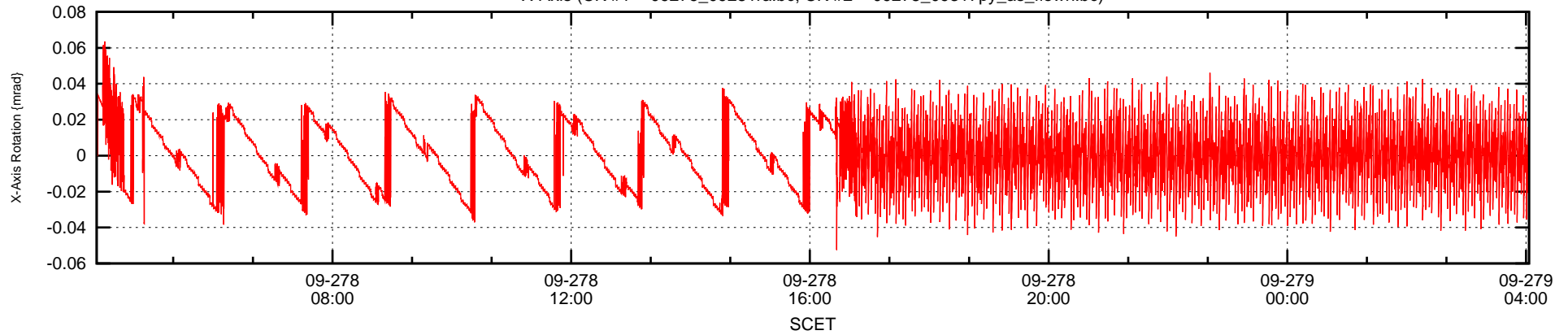
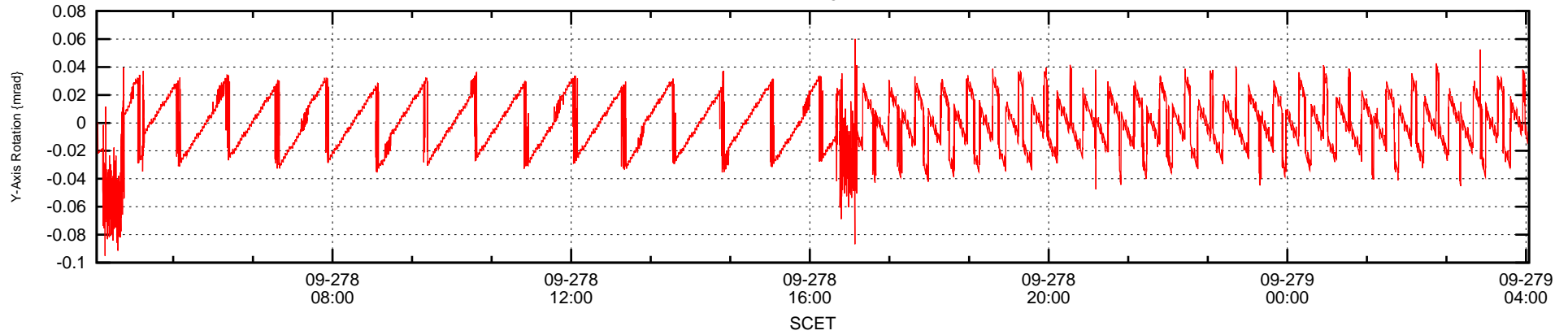


# Rotation From CK #2 to CK #1 (DOY 278-279)

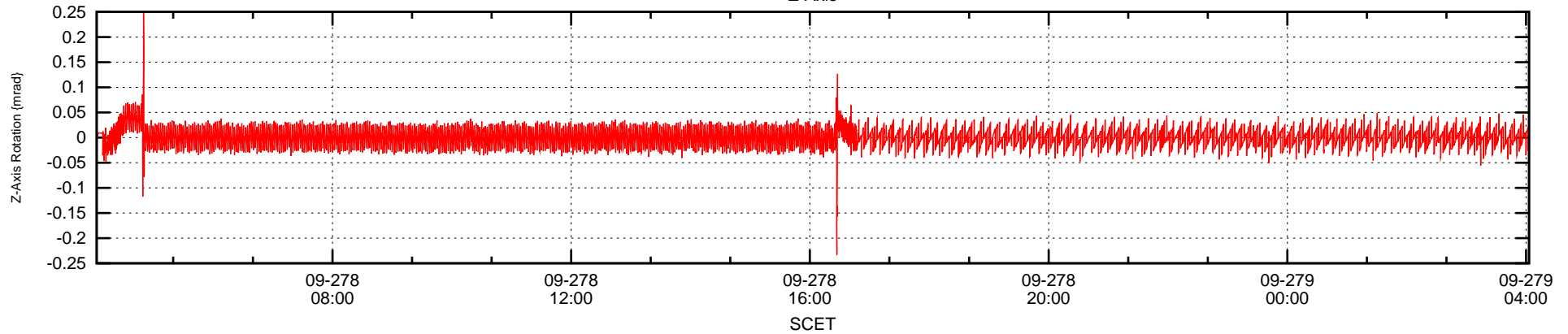
X-Axis (CK #1 = 09276\_09281ra.bc; CK #2 = 09278\_09317py\_as\_flown.bc)



Y-Axis

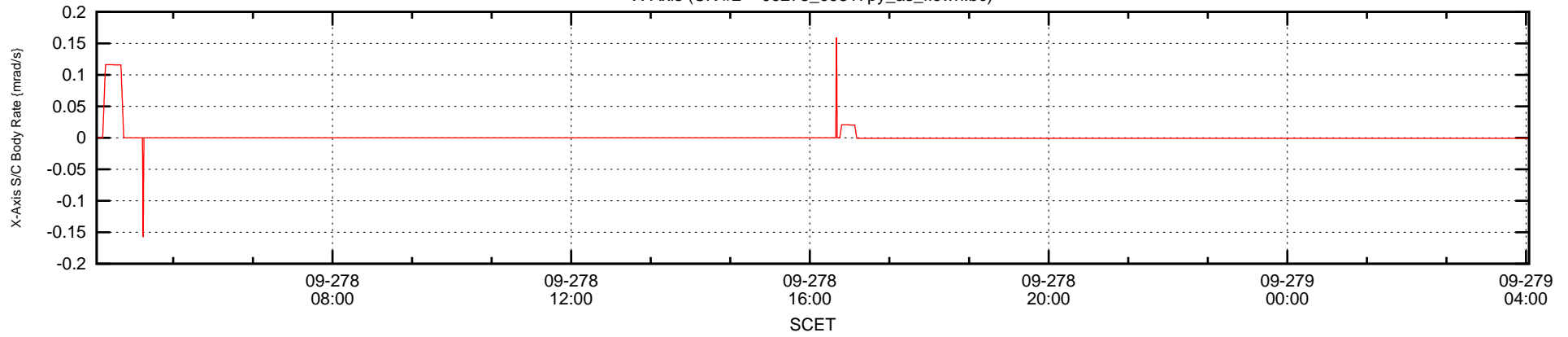


Z-Axis

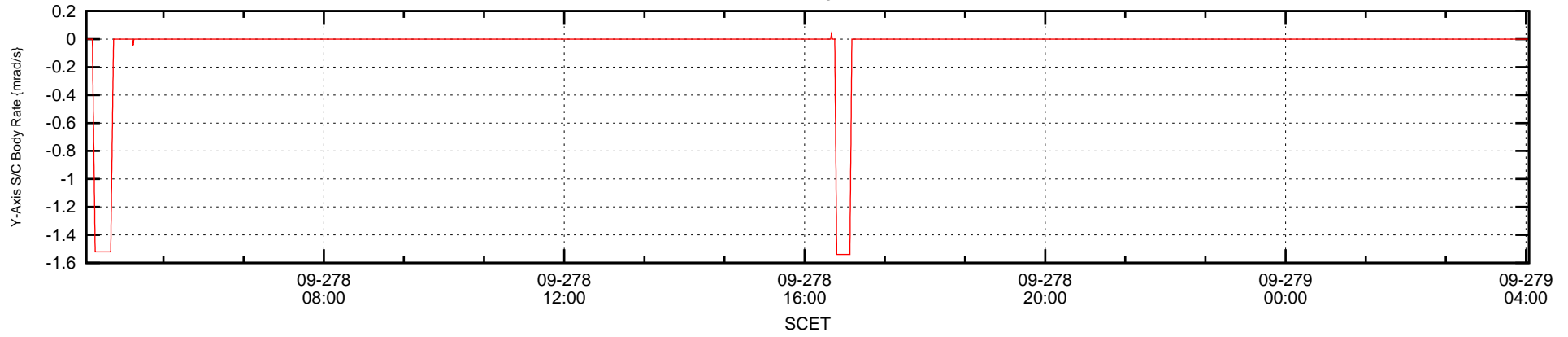


# CK #2 S/C Body Rates (DOY 278-279)

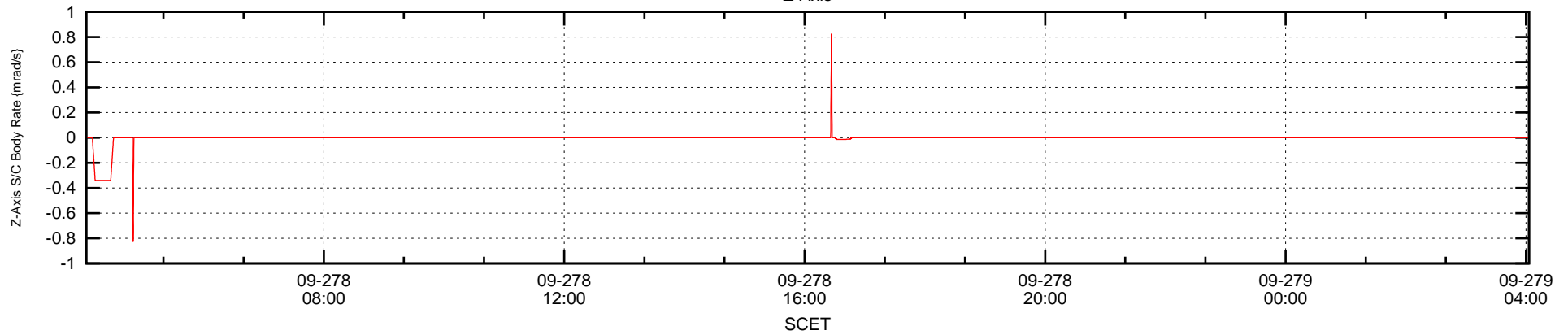
X-Axis (CK #2 = 09278\_09317py\_as\_flown.bc)



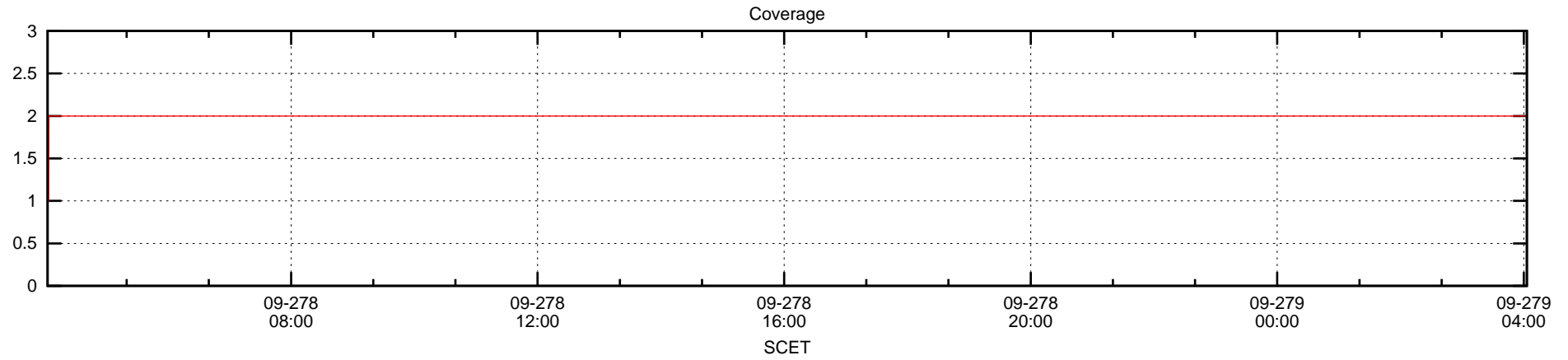
Y-Axis



Z-Axis

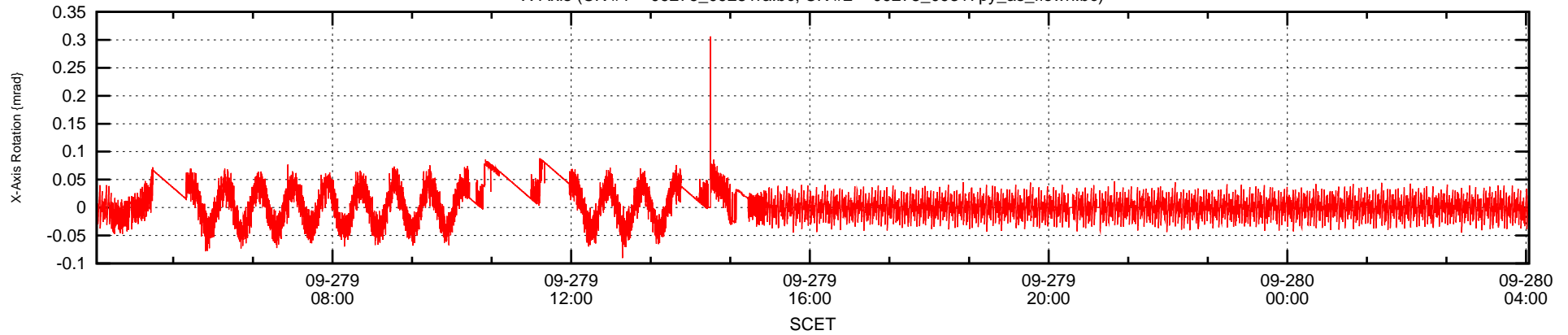


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 278-279)

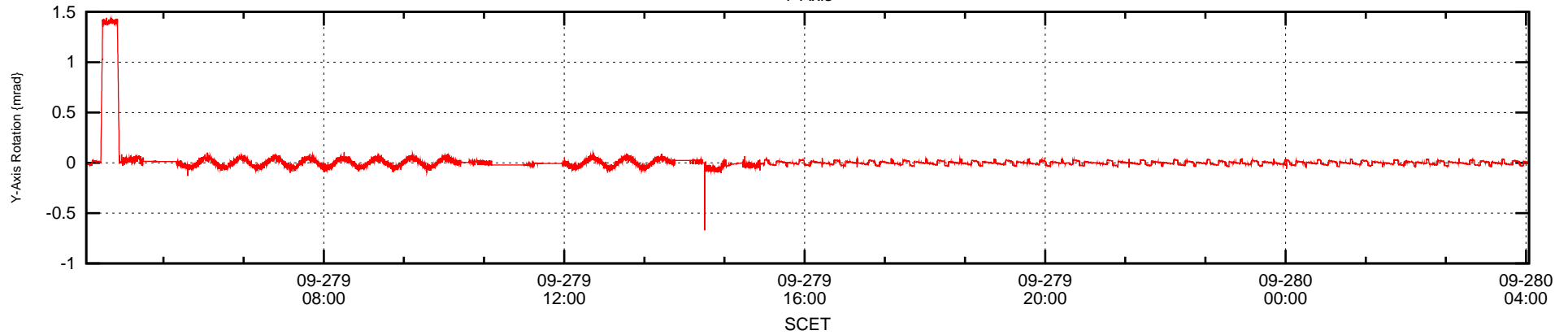


# Rotation From CK #2 to CK #1 (DOY 279-280)

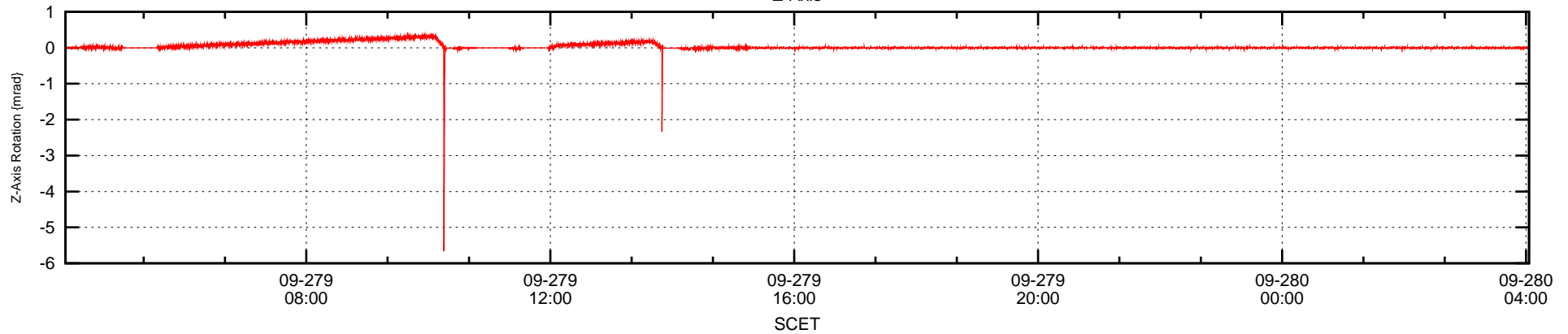
X-Axis (CK #1 = 09276\_09281ra.bc; CK #2 = 09278\_09317py\_as\_flown.bc)



Y-Axis

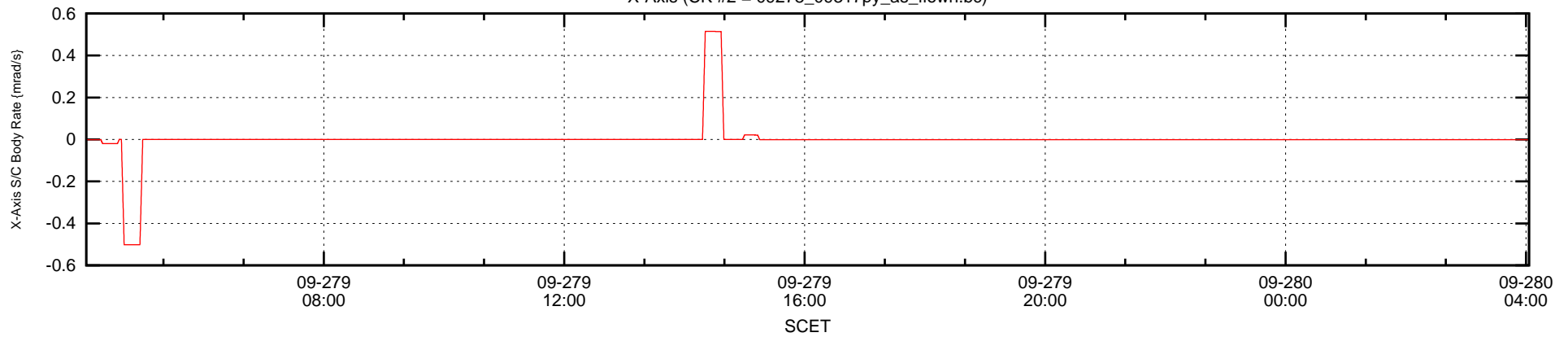


Z-Axis

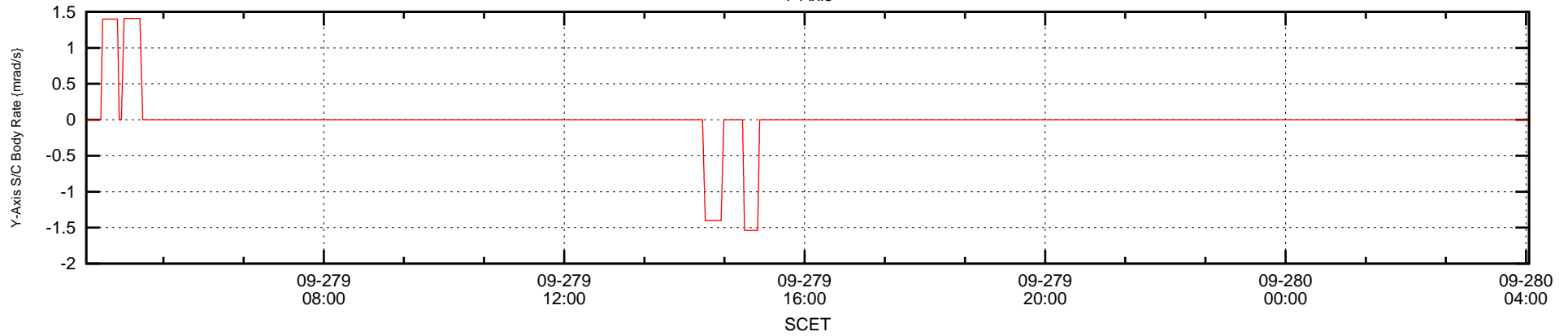


# CK #2 S/C Body Rates (DOY 279-280)

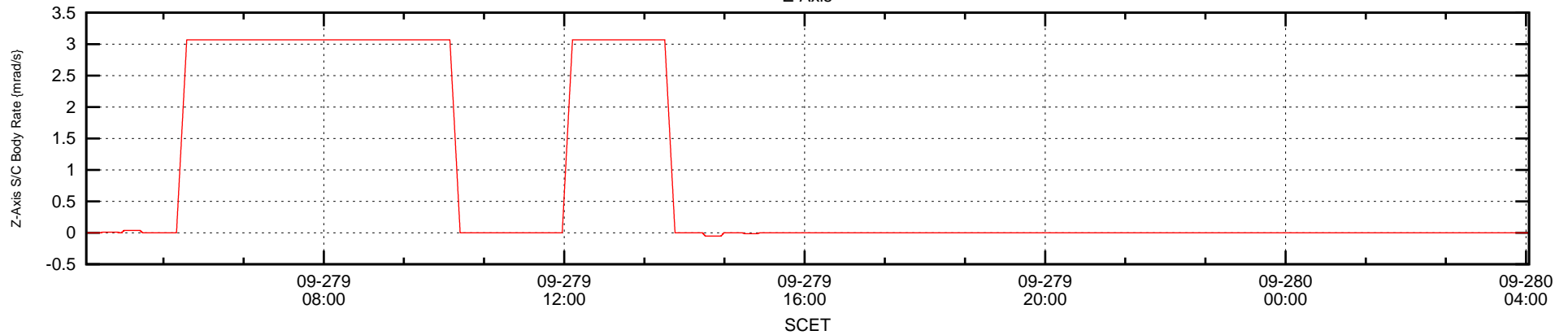
X-Axis (CK #2 = 09278\_09317py\_as\_flowm.bc)



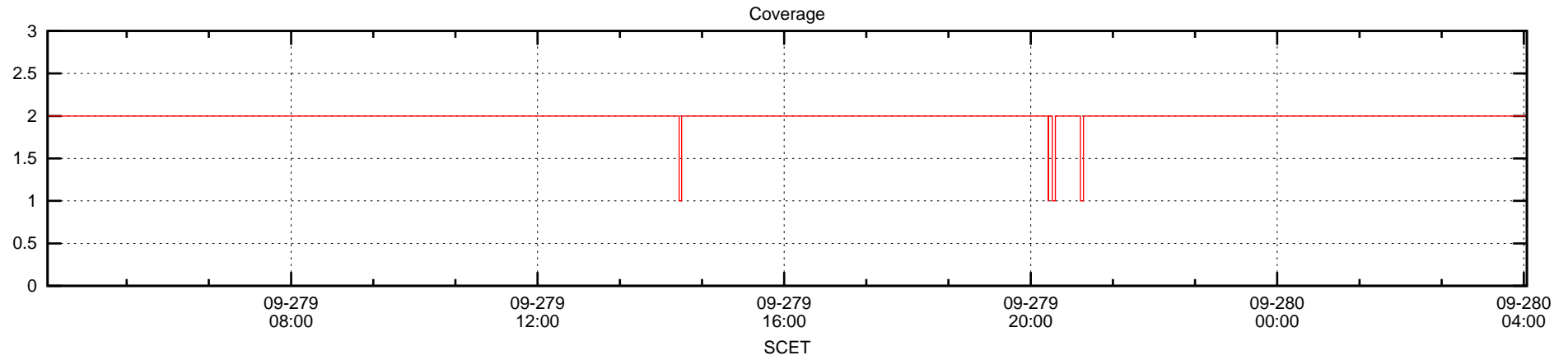
Y-Axis



Z-Axis

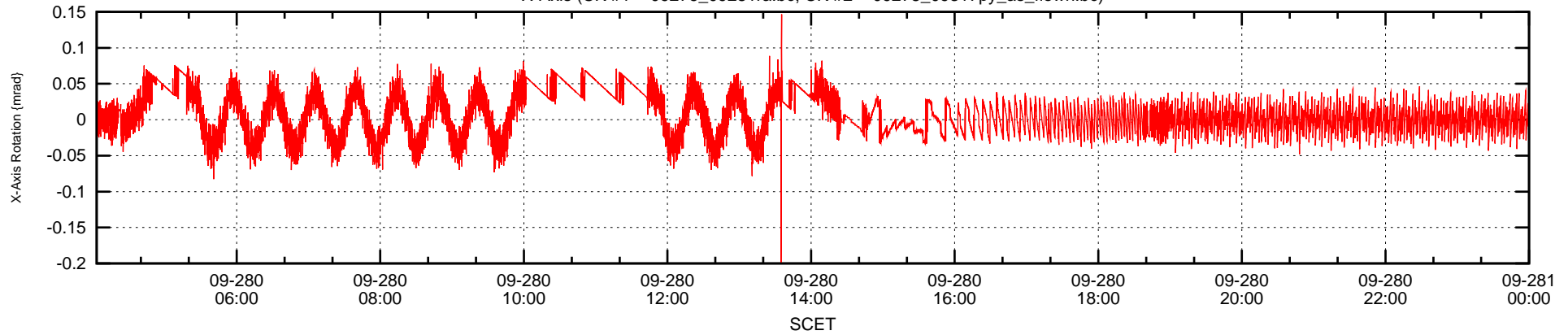


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 279-280)

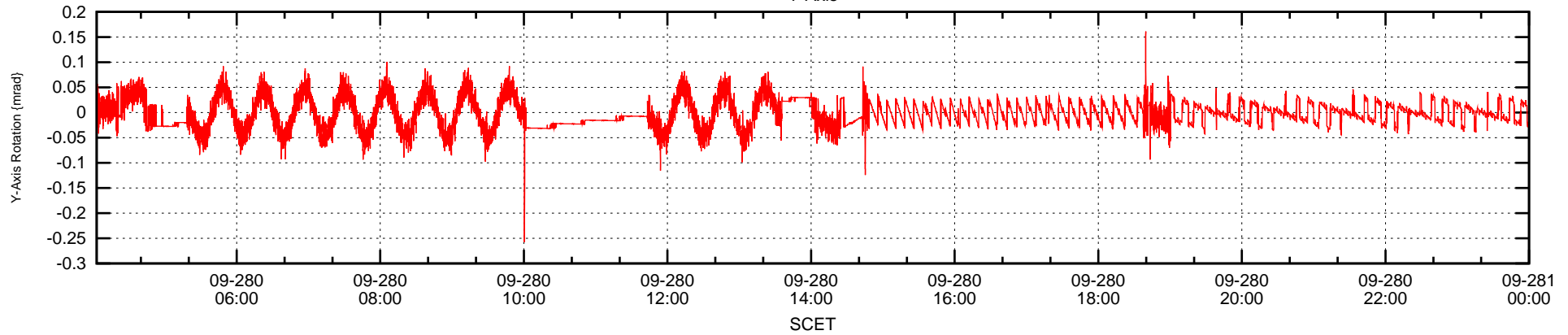


# Rotation From CK #2 to CK #1 (DOY 280-280)

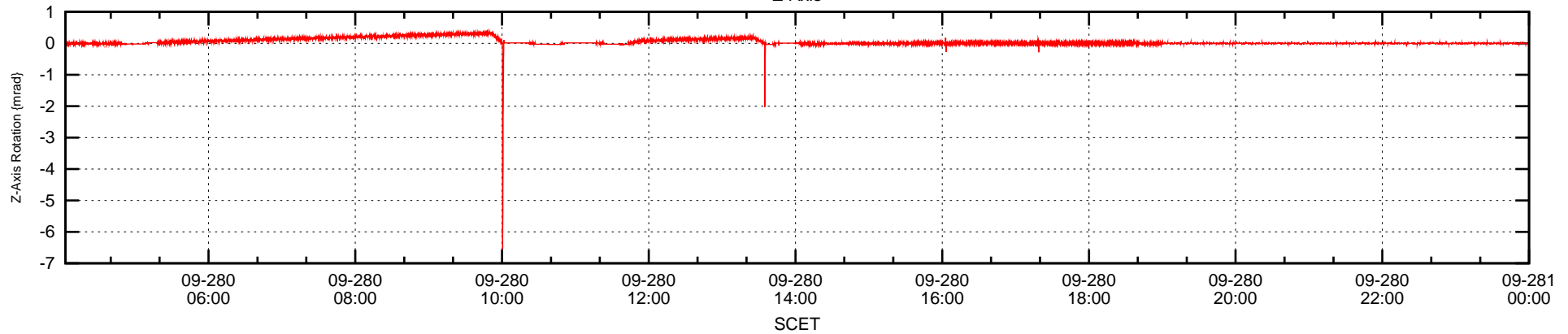
X-Axis (CK #1 = 09276\_09281ra.bc; CK #2 = 09278\_09317py\_as\_flowm.bc)



Y-Axis

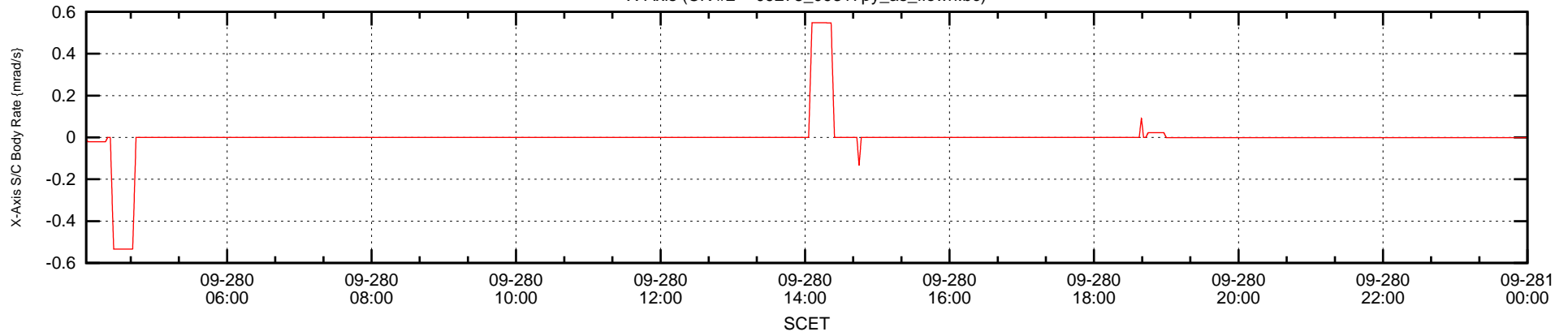


Z-Axis

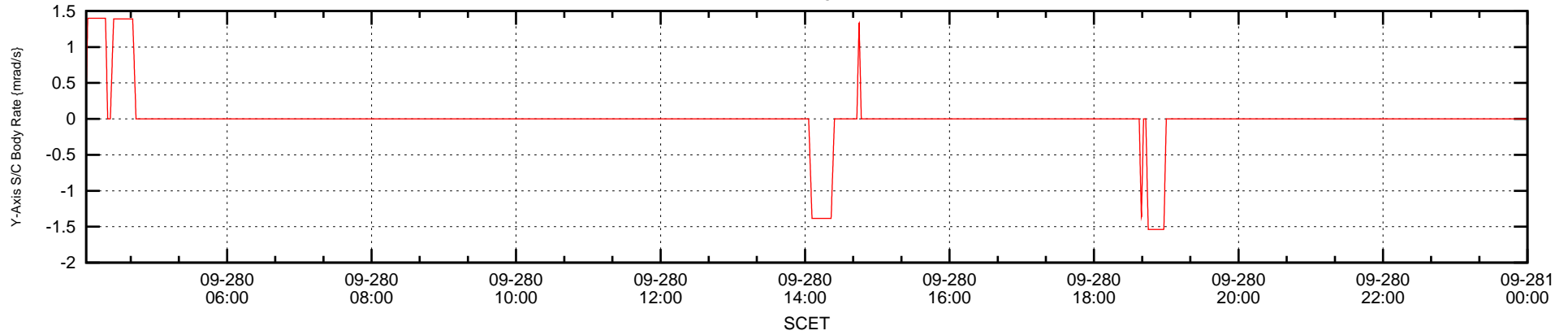


# CK #2 S/C Body Rates (DOY 280-280)

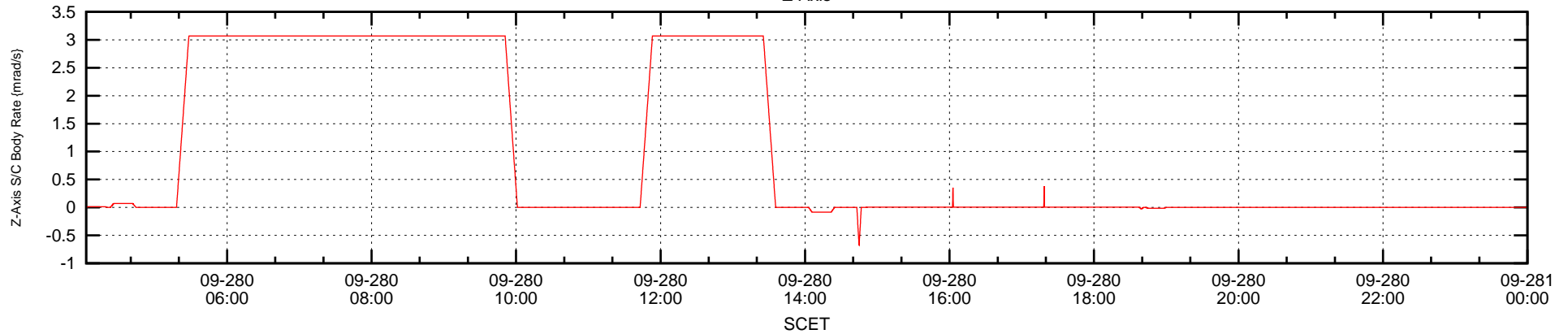
X-Axis (CK #2 = 09278\_09317py\_as\_flown.bc)



Y-Axis



Z-Axis





All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 280-280)

