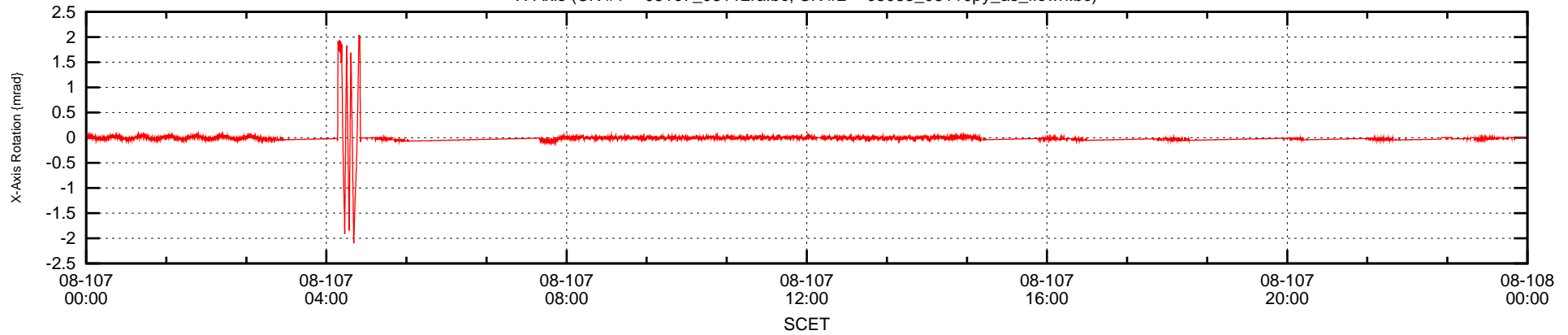
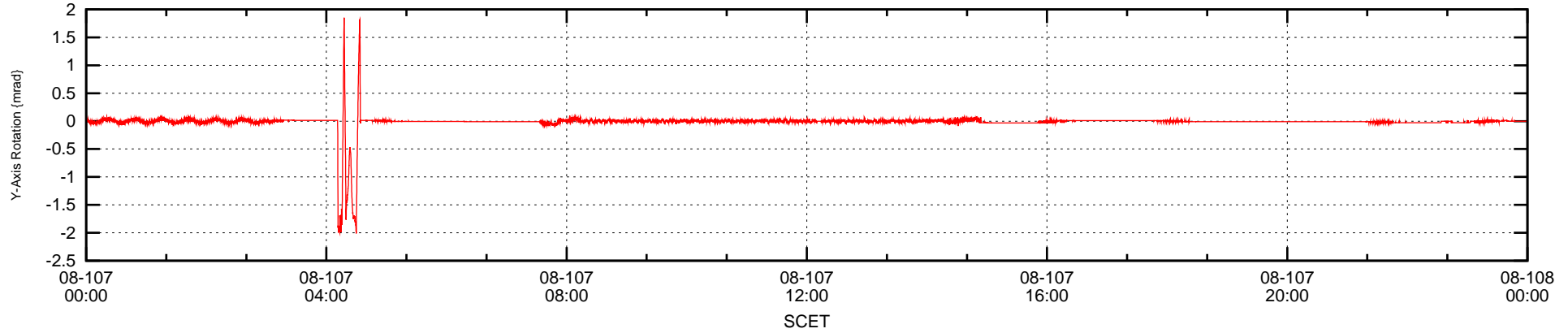


# Rotation From CK #2 to CK #1 (DOY 107-108)

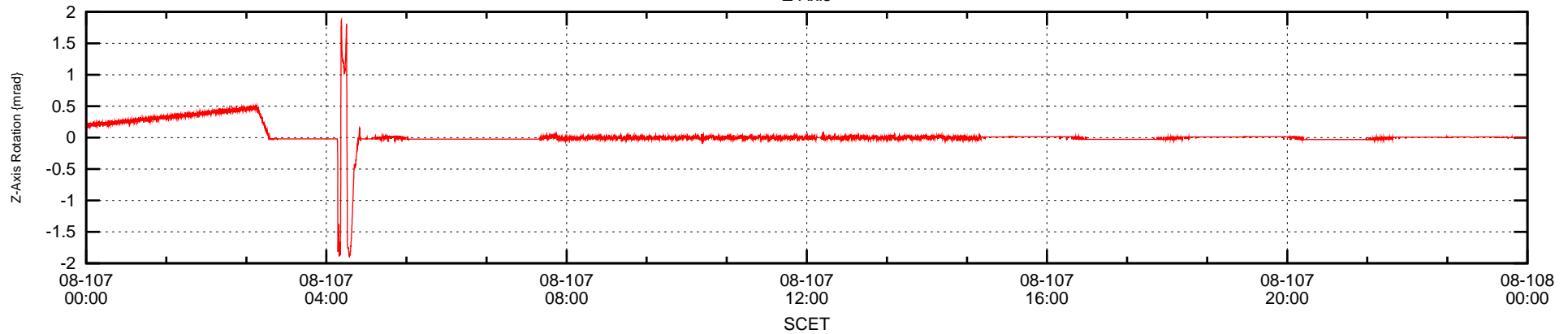
X-Axis (CK #1 = 08107\_08112ra.bc; CK #2 = 08083\_08110py\_as\_flowm.bc)



Y-Axis

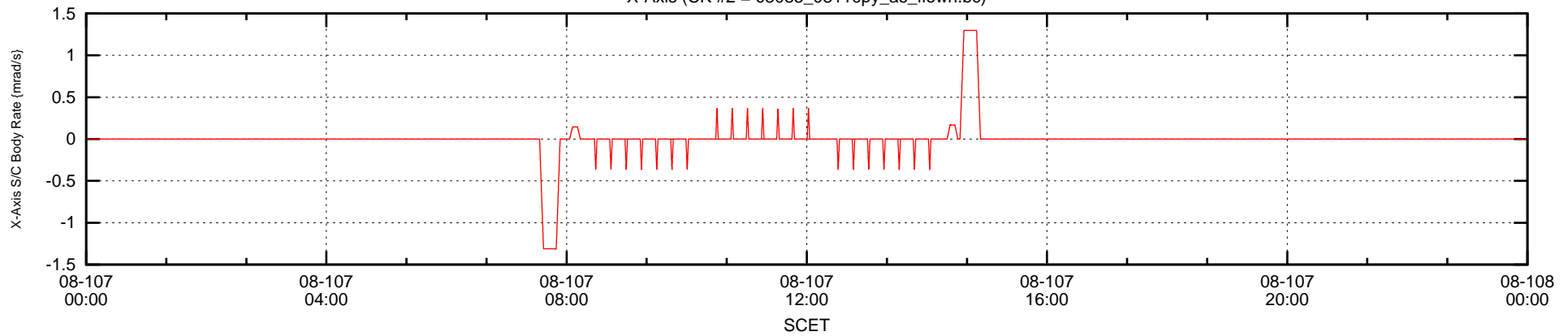


Z-Axis

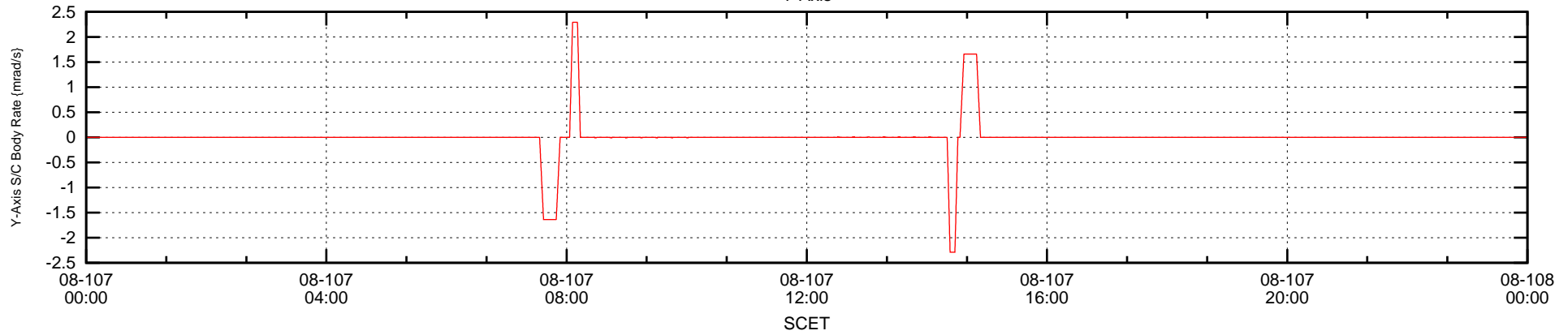


# CK #2 S/C Body Rates (DOY 107-108)

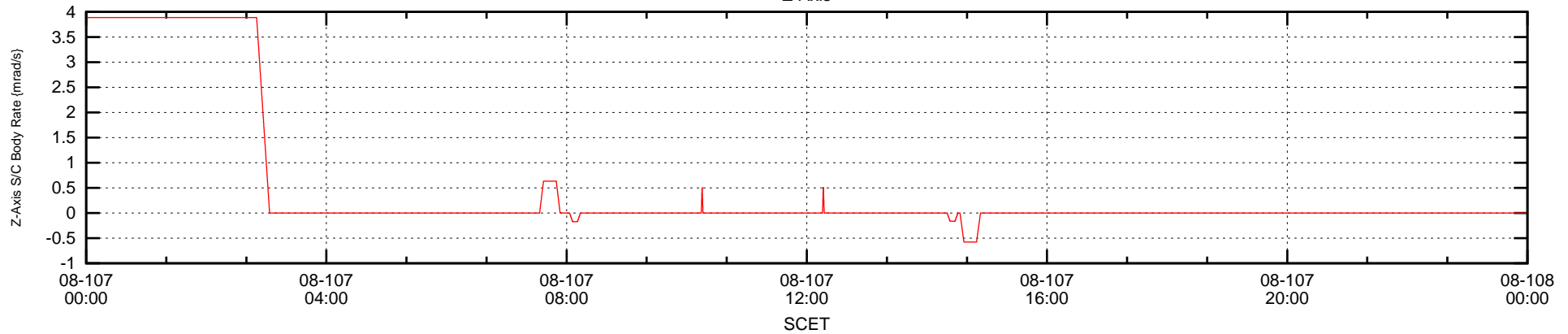
X-Axis (CK #2 = 08083\_08110py\_as\_flown.bc)



Y-Axis



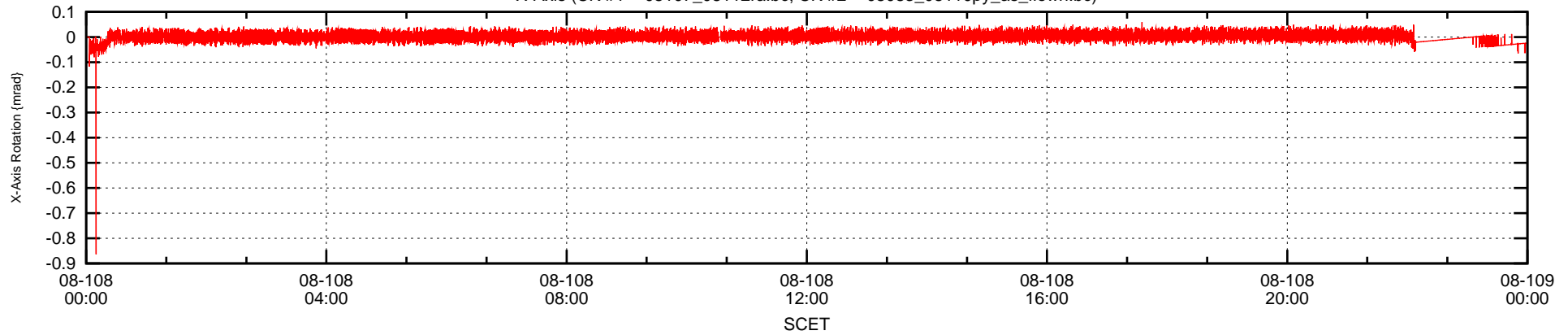
Z-Axis



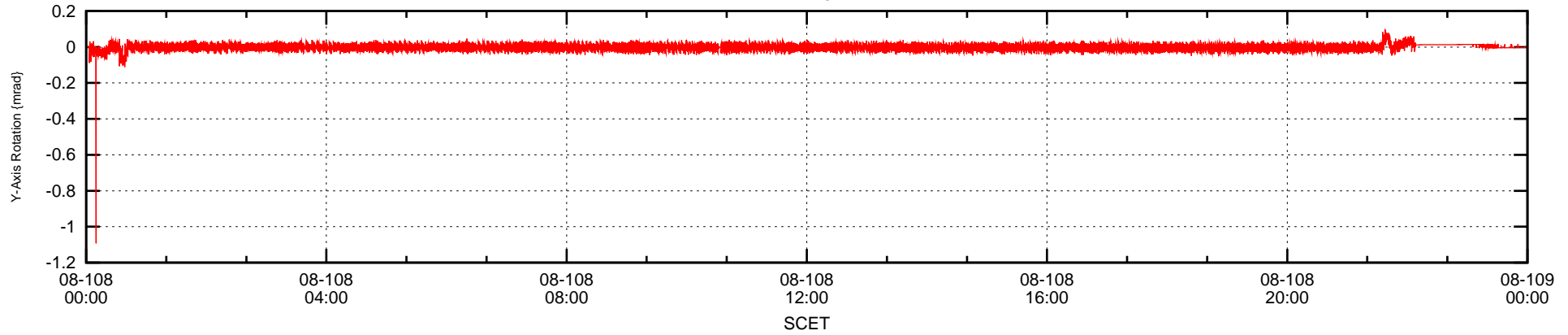


# Rotation From CK #2 to CK #1 (DOY 108-109)

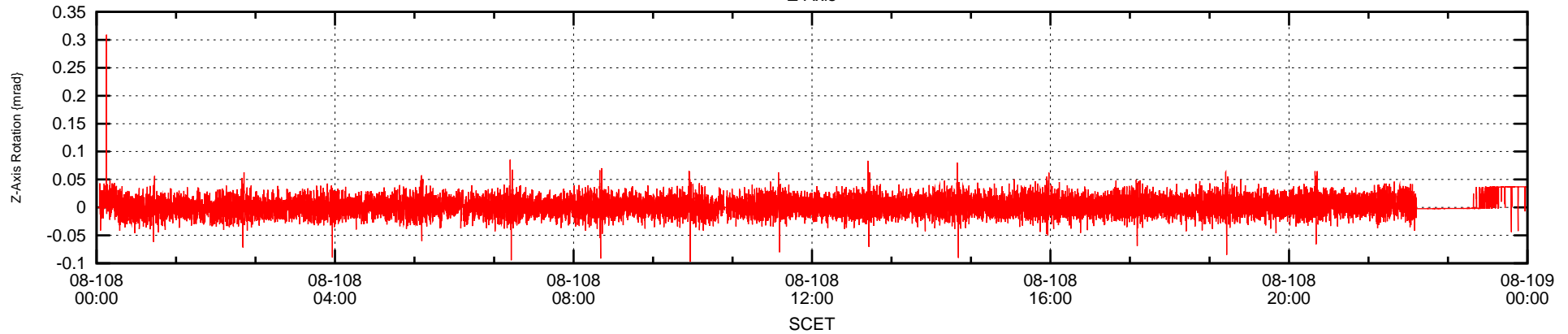
X-Axis (CK #1 = 08107\_08112ra.bc; CK #2 = 08083\_08110py\_as\_flown.bc)



Y-Axis

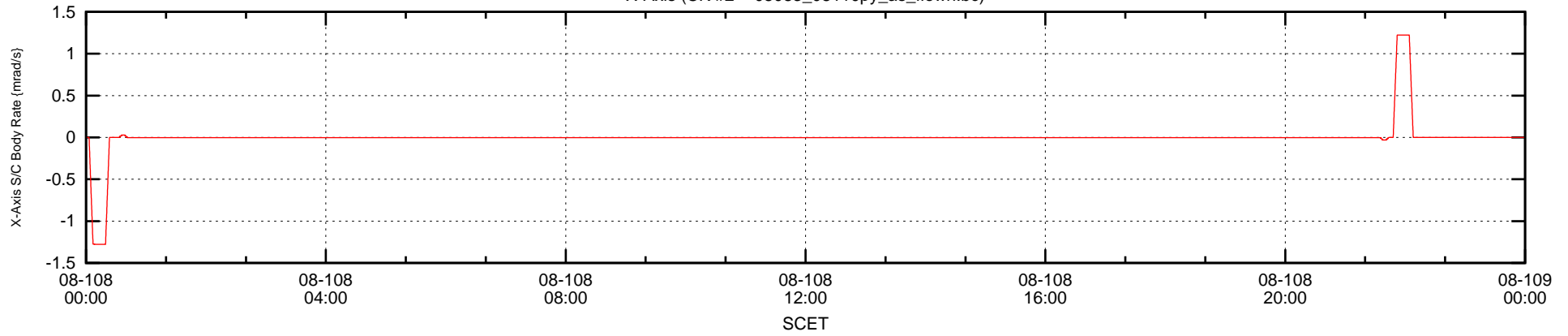


Z-Axis

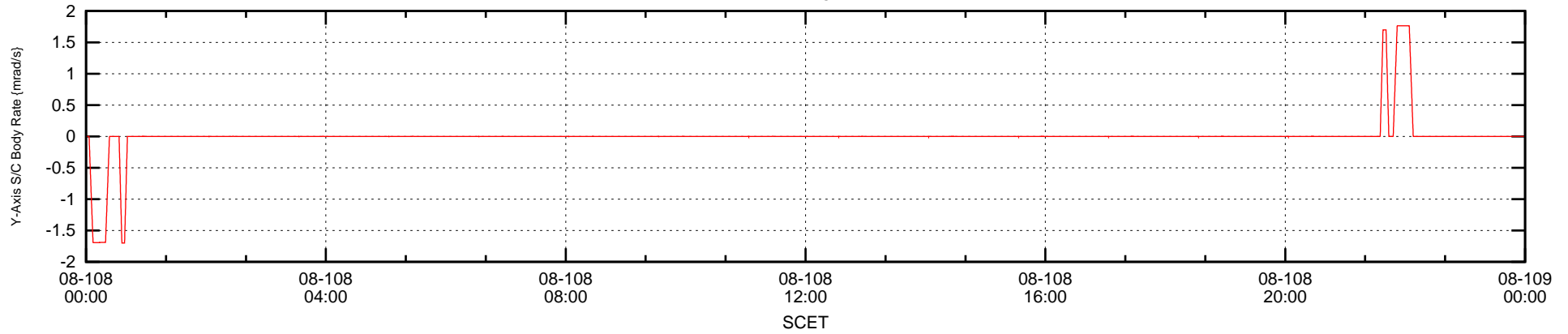


# CK #2 S/C Body Rates (DOY 108-109)

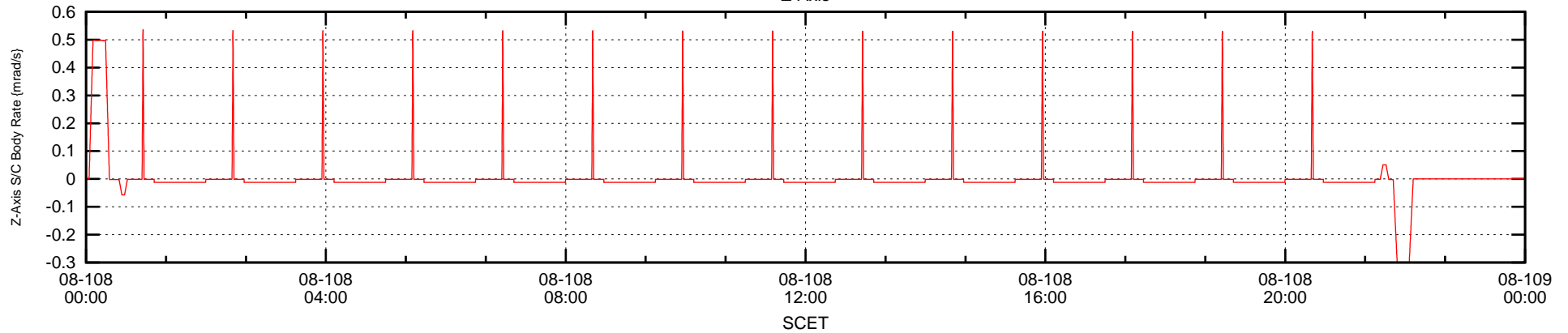
X-Axis (CK #2 = 08083\_08110py\_as\_flow.n.bc)



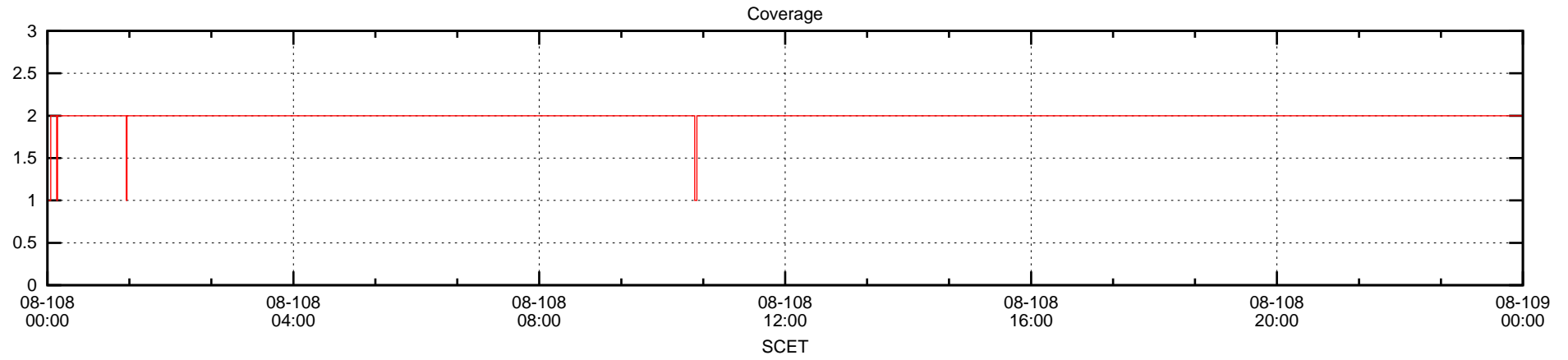
Y-Axis



Z-Axis

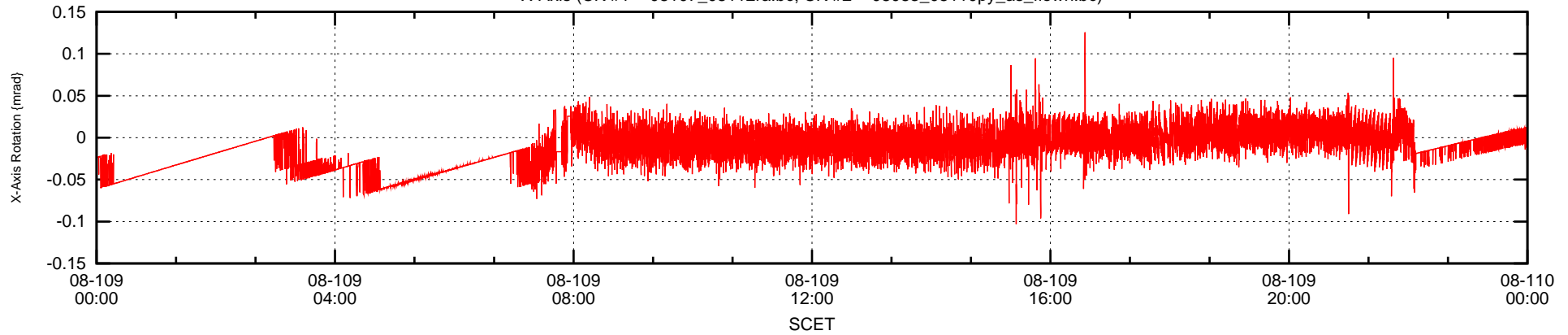


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 108-109)

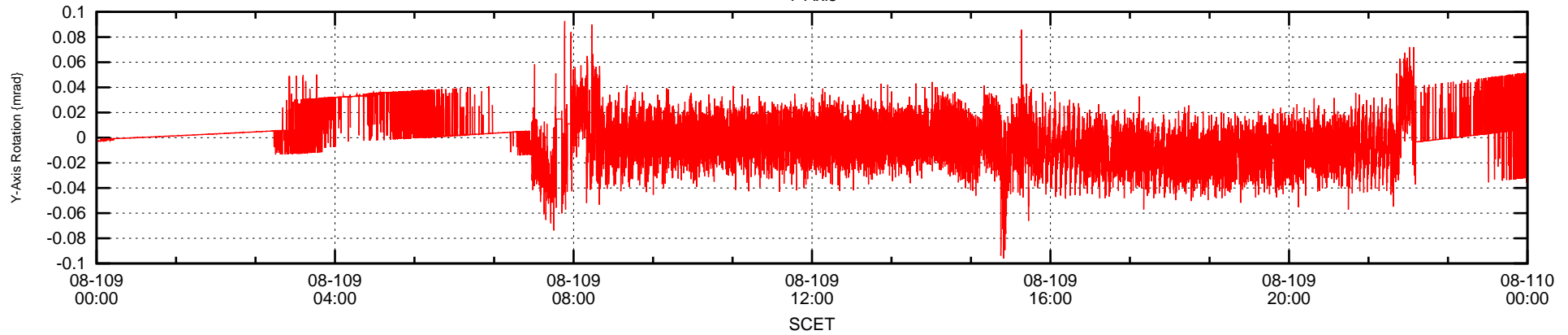


# Rotation From CK #2 to CK #1 (DOY 109-110)

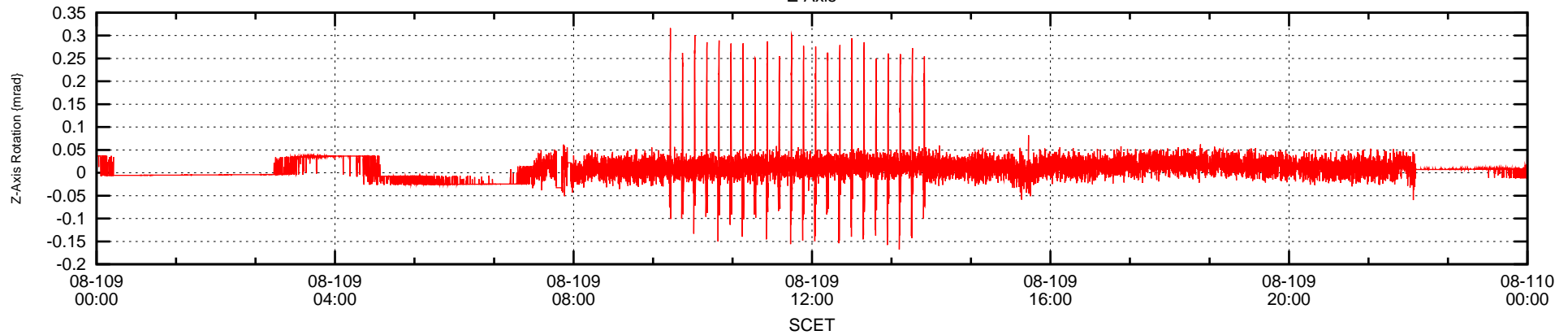
X-Axis (CK #1 = 08107\_08112ra.bc; CK #2 = 08083\_08110py\_as\_flown.bc)



Y-Axis

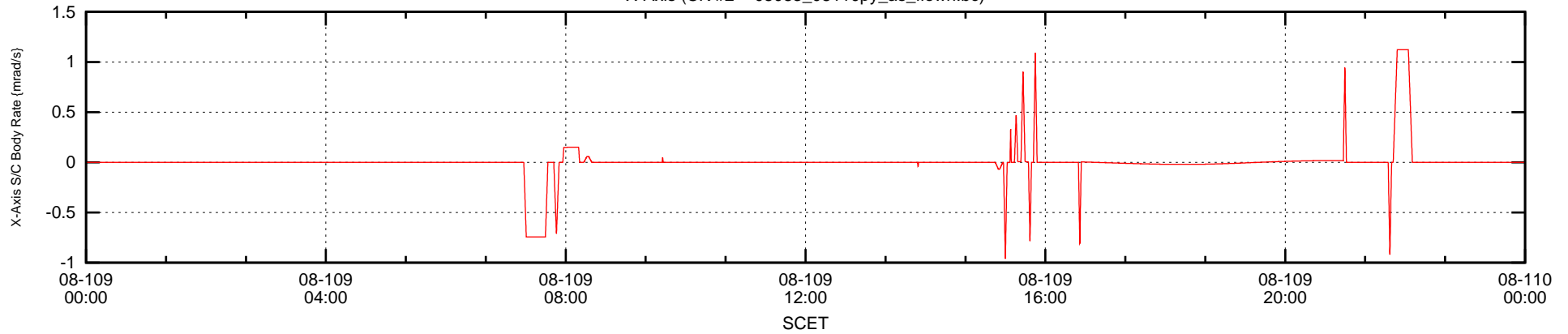


Z-Axis

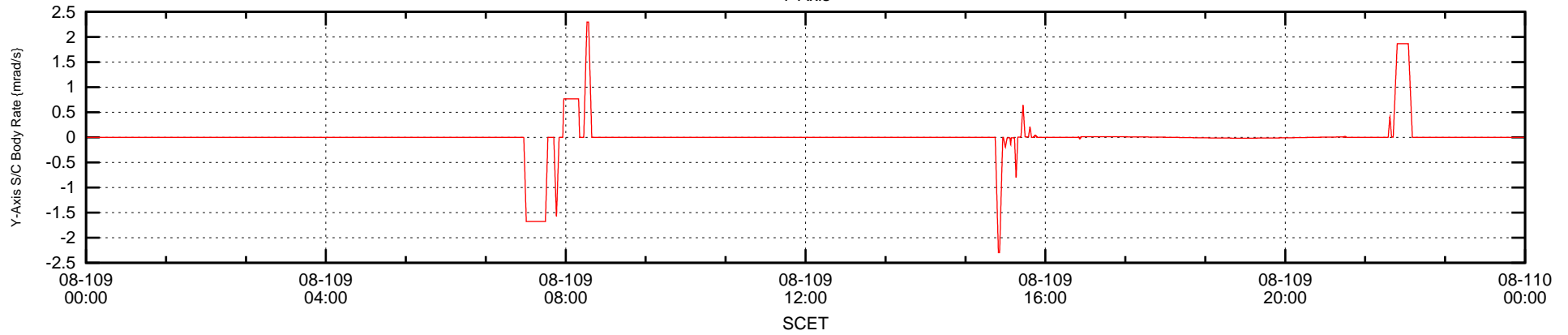


# CK #2 S/C Body Rates (DOY 109-110)

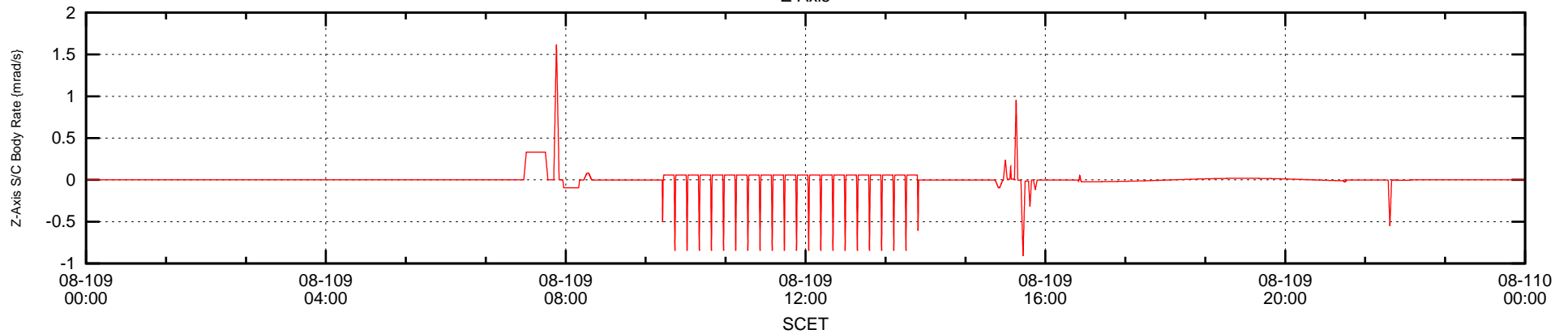
X-Axis (CK #2 = 08083\_08110py\_as\_flowm.bc)



Y-Axis

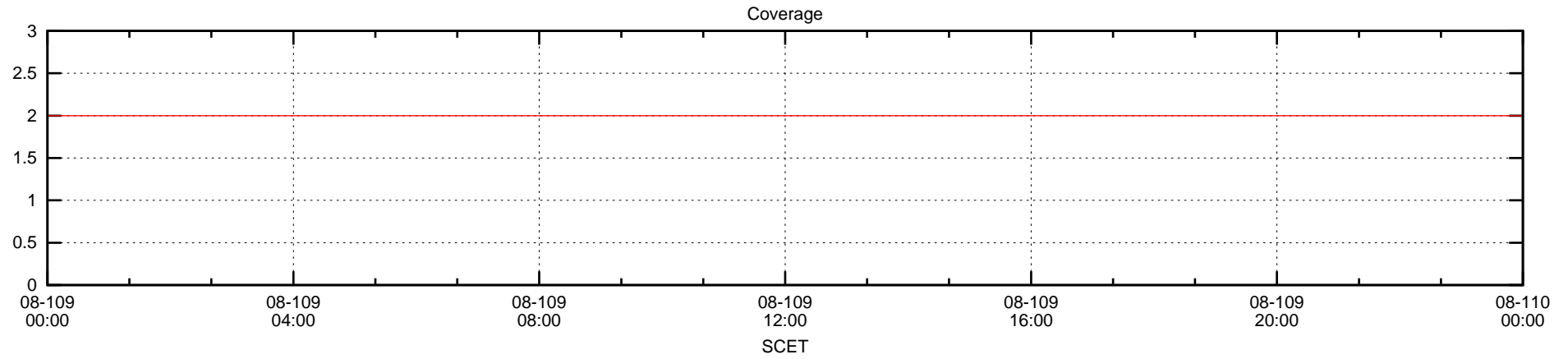


Z-Axis



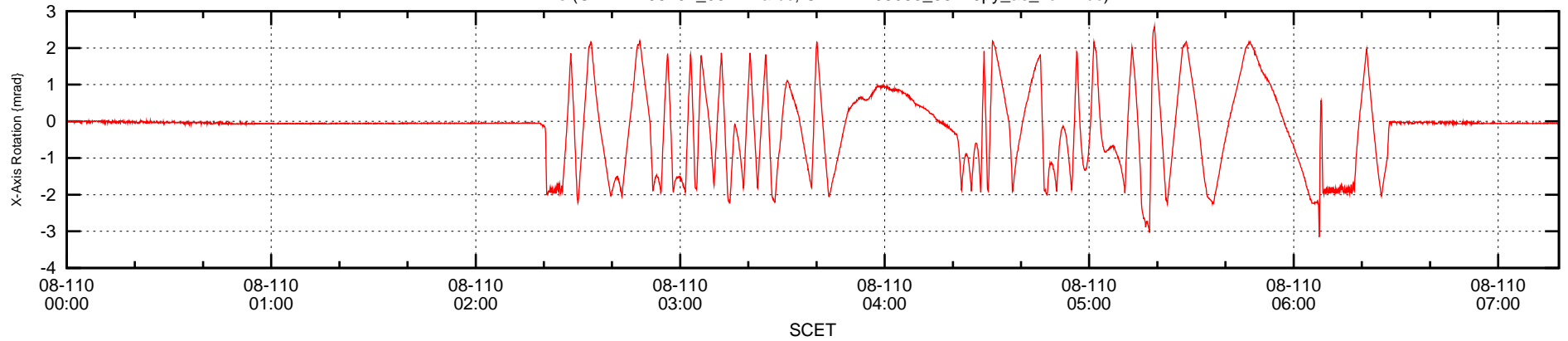


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 109-110)

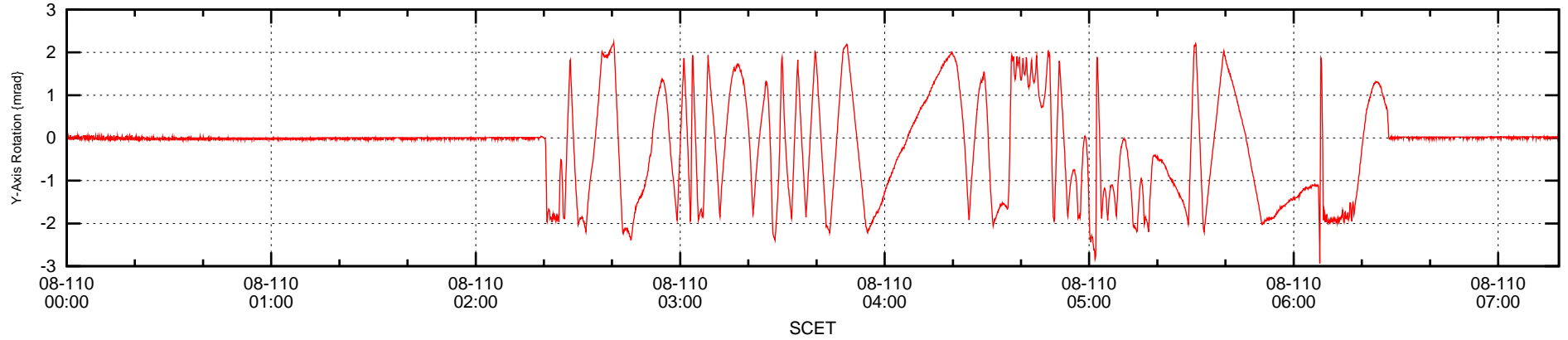


# Rotation From CK #2 to CK #1 (DOY 110-110)

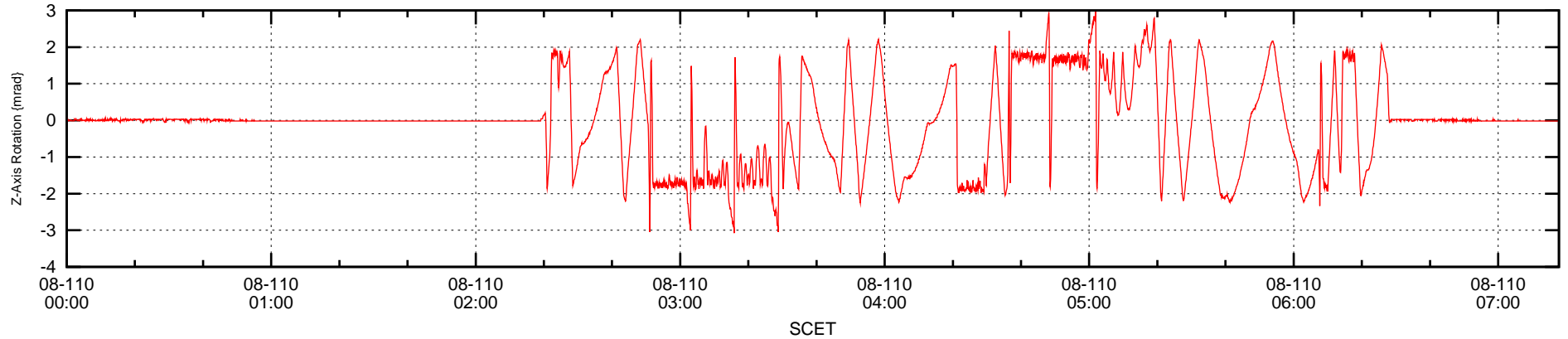
X-Axis (CK #1 = 08107\_08112ra.bc; CK #2 = 08083\_08110py\_as\_flown.bc)



Y-Axis

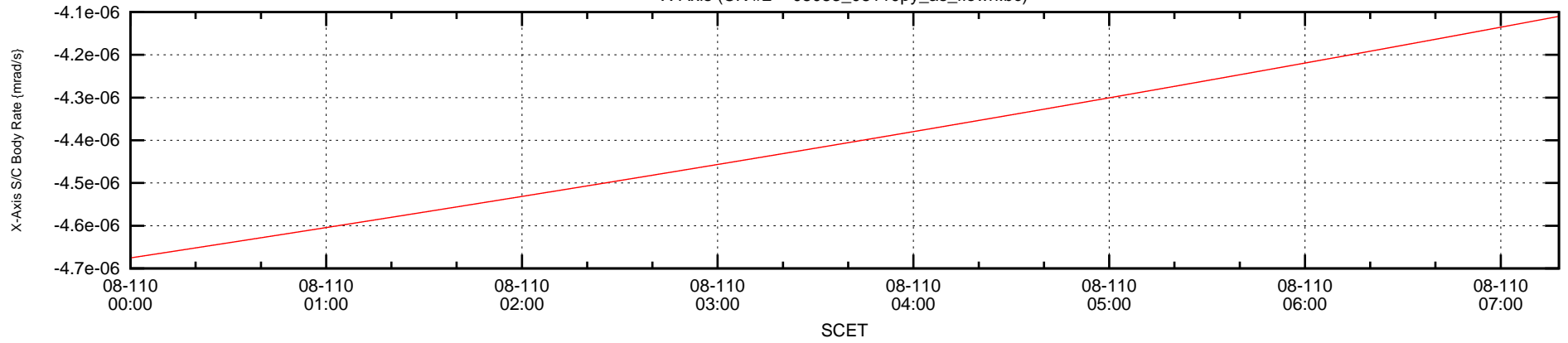


Z-Axis



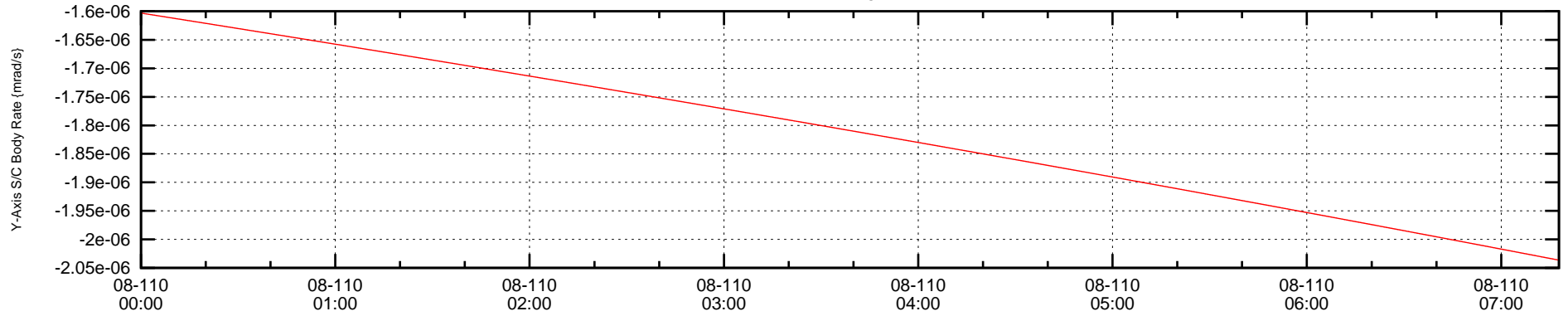
# CK #2 S/C Body Rates (DOY 110-110)

X-Axis (CK #2 = 08083\_08110py\_as\_flowm.bc)



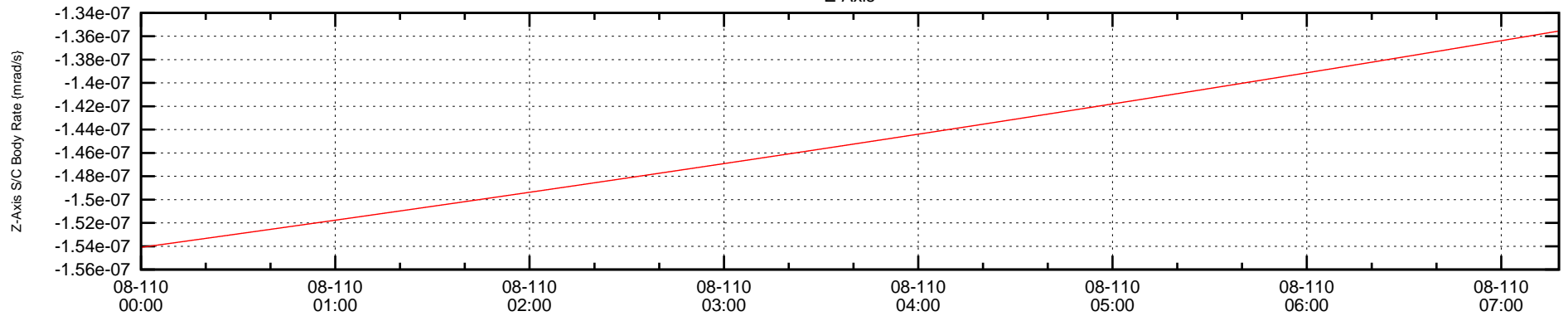
SCET

Y-Axis



SCET

Z-Axis



SCET

All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 110-110)

