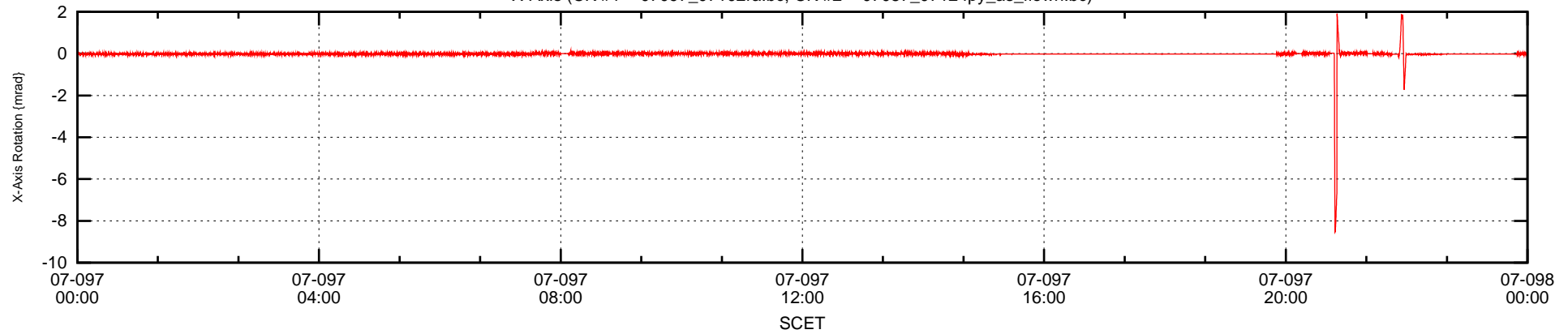
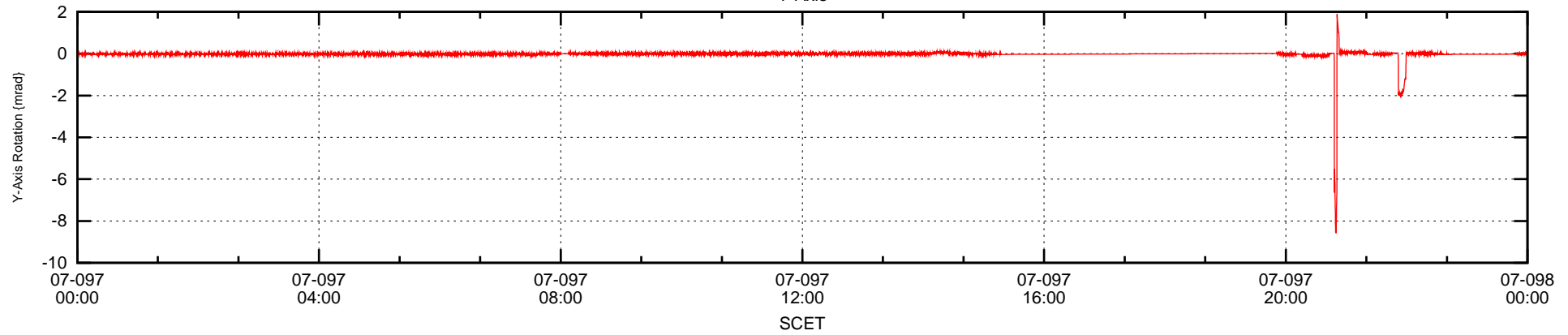


Rotation From CK #2 to CK #1 (DOY 097-098)

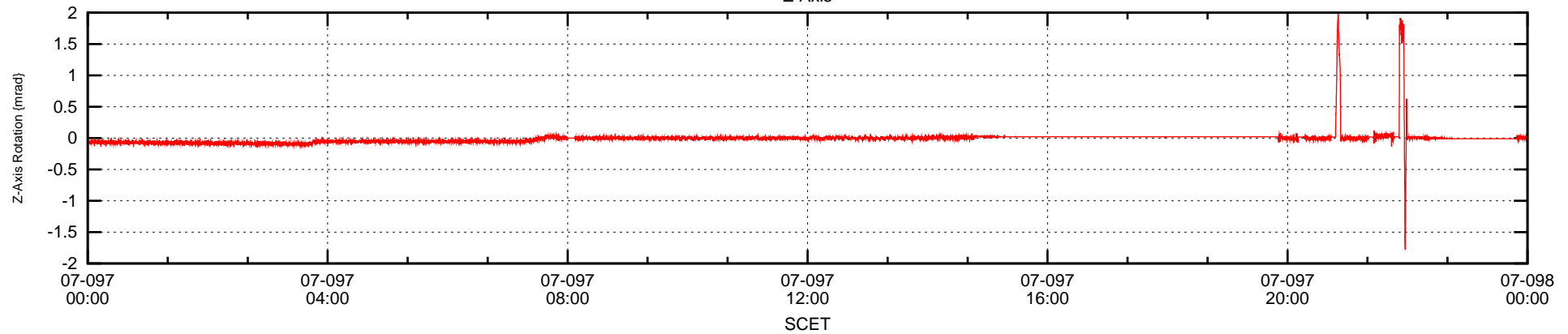
X-Axis (CK #1 = 07097_07102ra.bc; CK #2 = 07087_07124py_as_flowm.bc)



Y-Axis

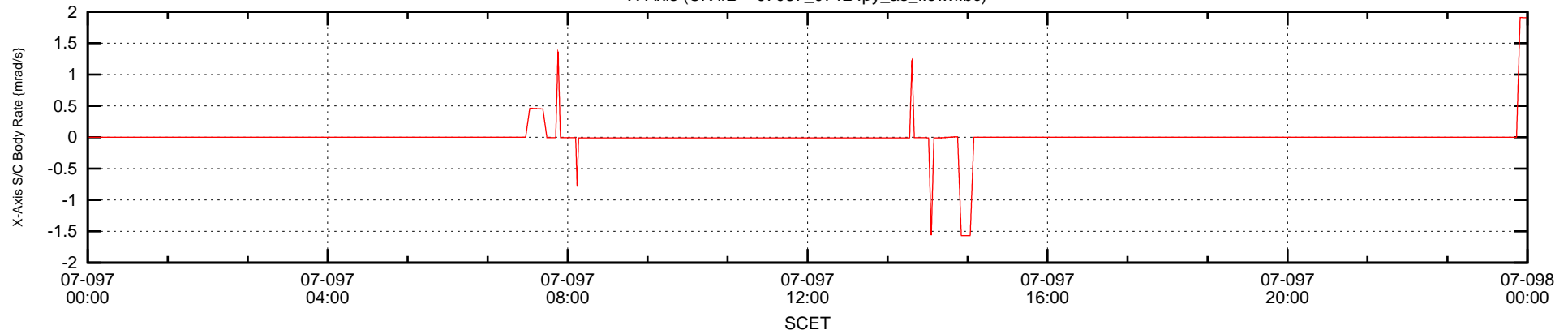


Z-Axis

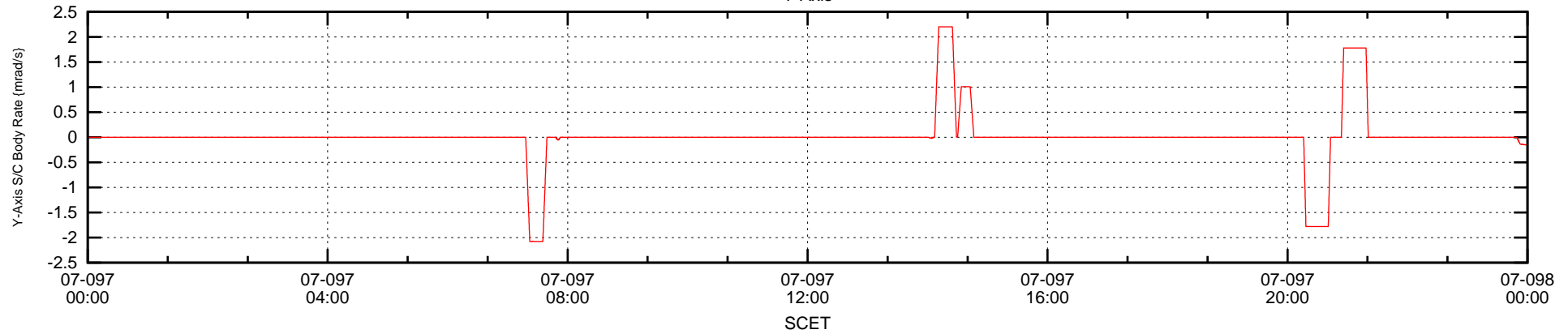


CK #2 S/C Body Rates (DOY 097-098)

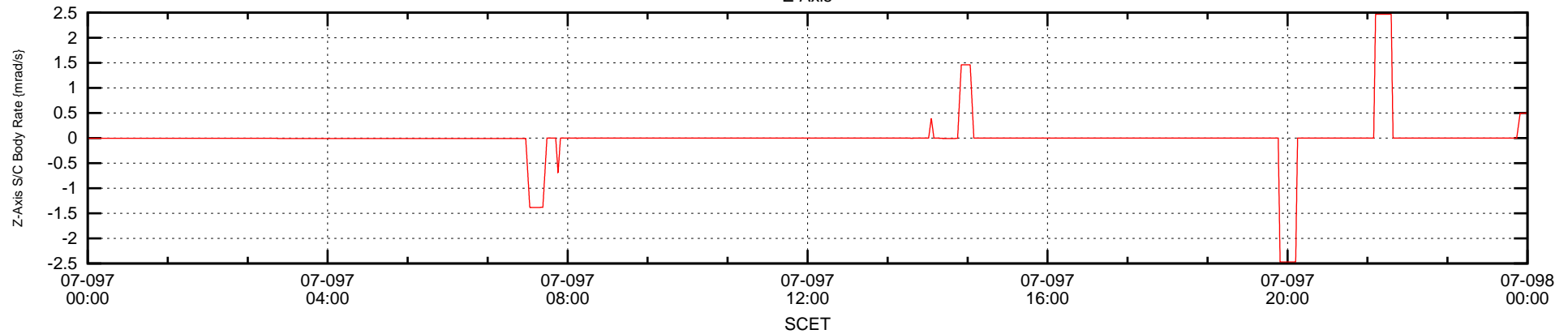
X-Axis (CK #2 = 07087_07124py_as_flown.bc)



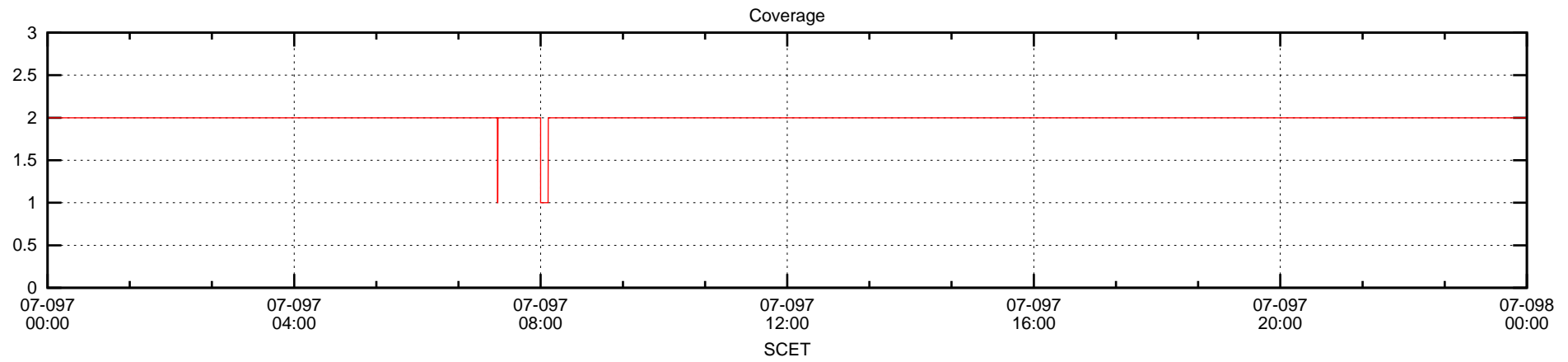
Y-Axis



Z-Axis

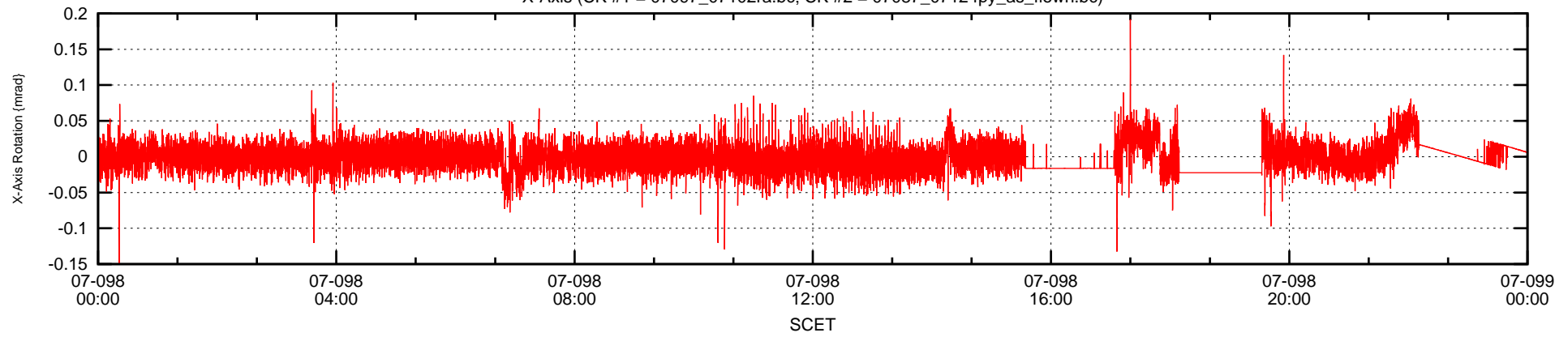


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 097-098)

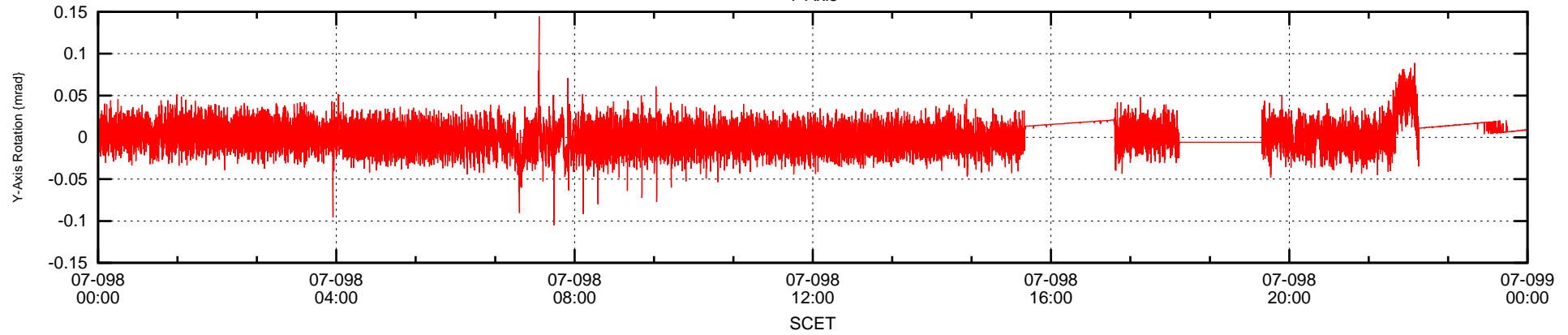


Rotation From CK #2 to CK #1 (DOY 098-099)

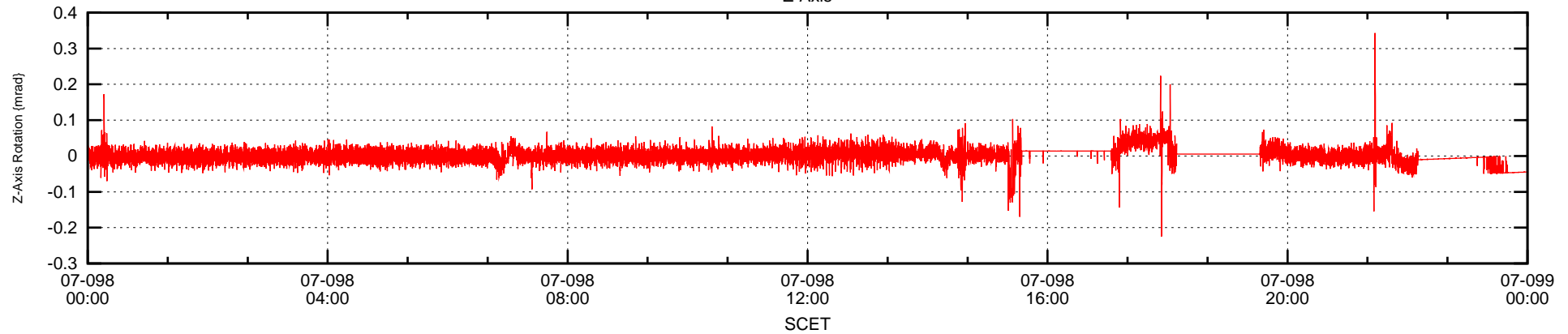
X-Axis (CK #1 = 07097_07102ra.bc; CK #2 = 07087_07124py_as_flowm.bc)



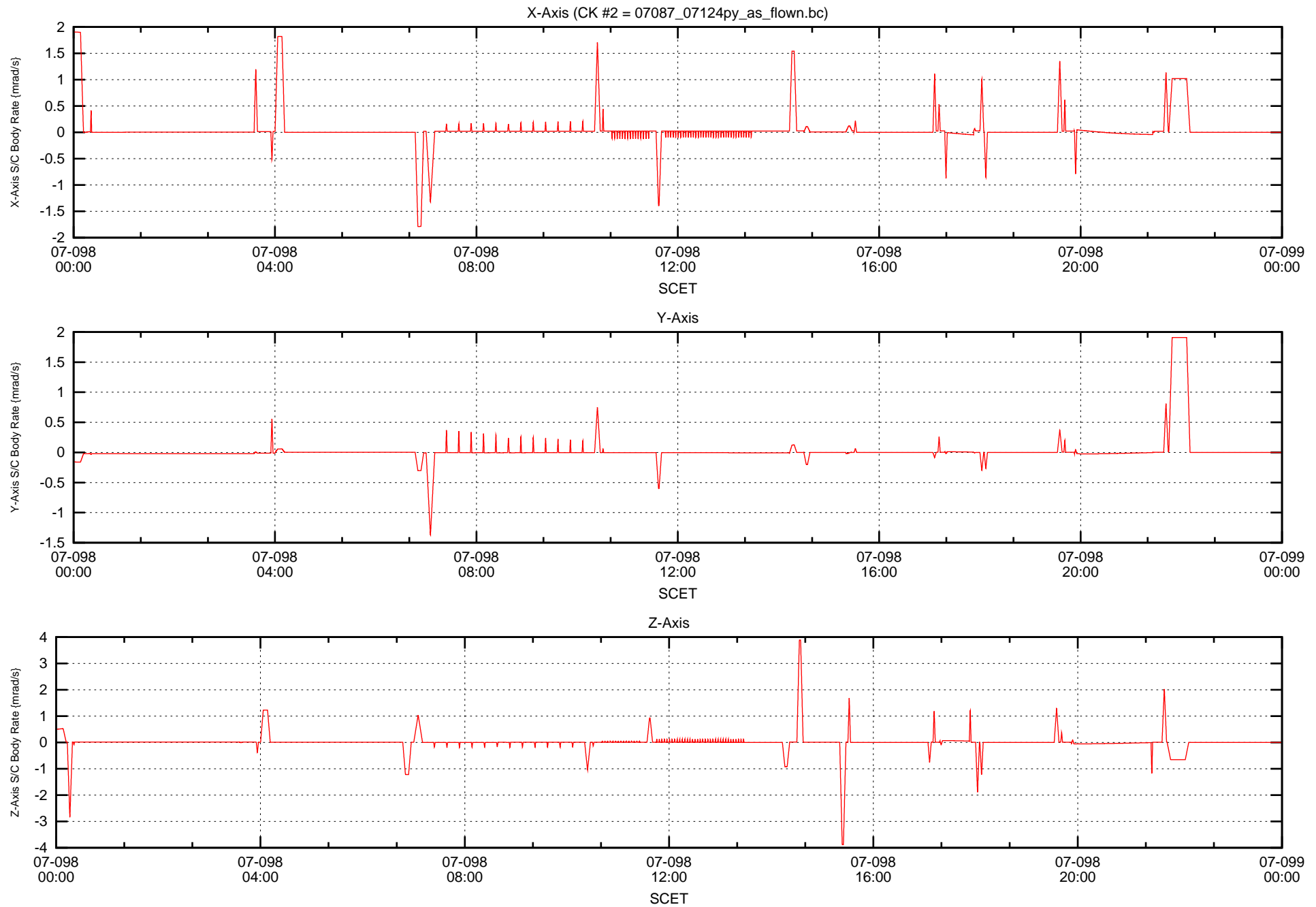
Y-Axis



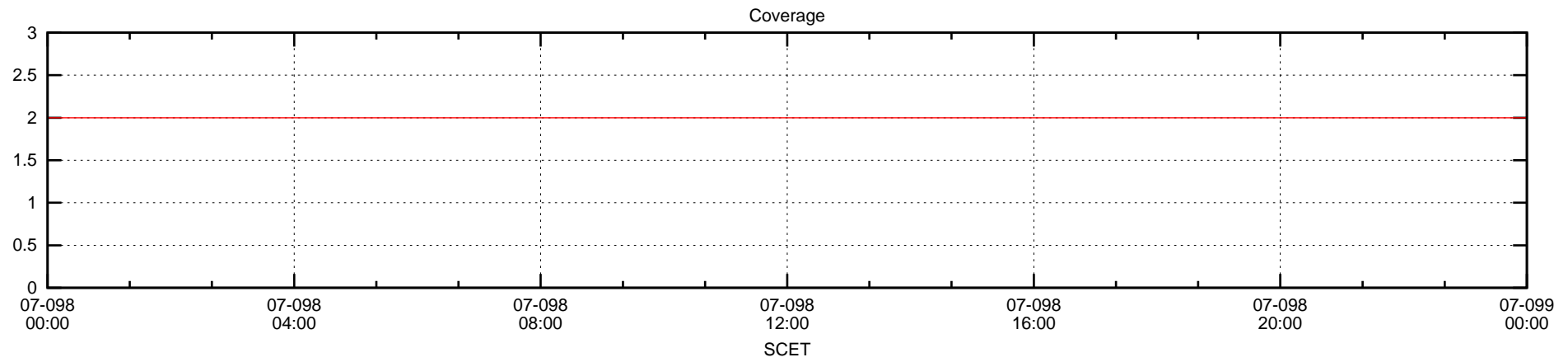
Z-Axis



CK #2 S/C Body Rates (DOY 098-099)

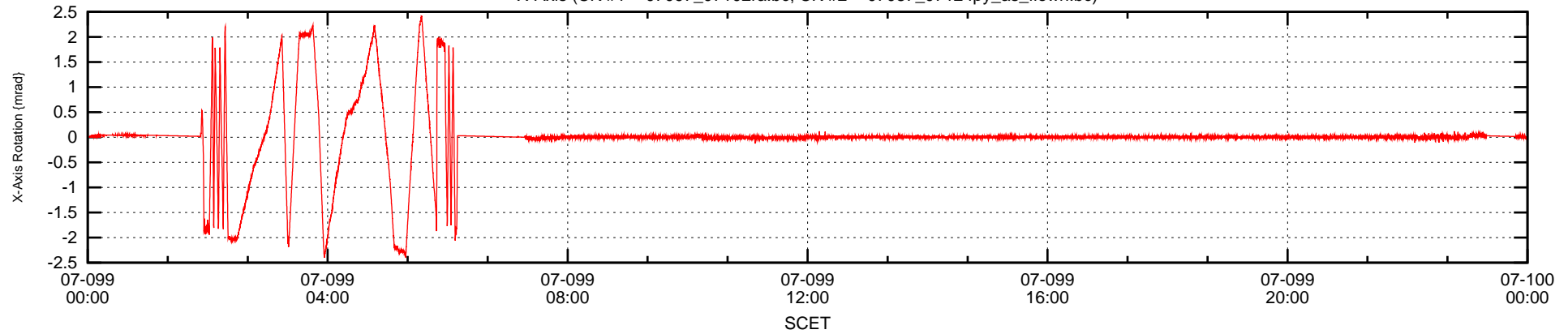


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 098-099)

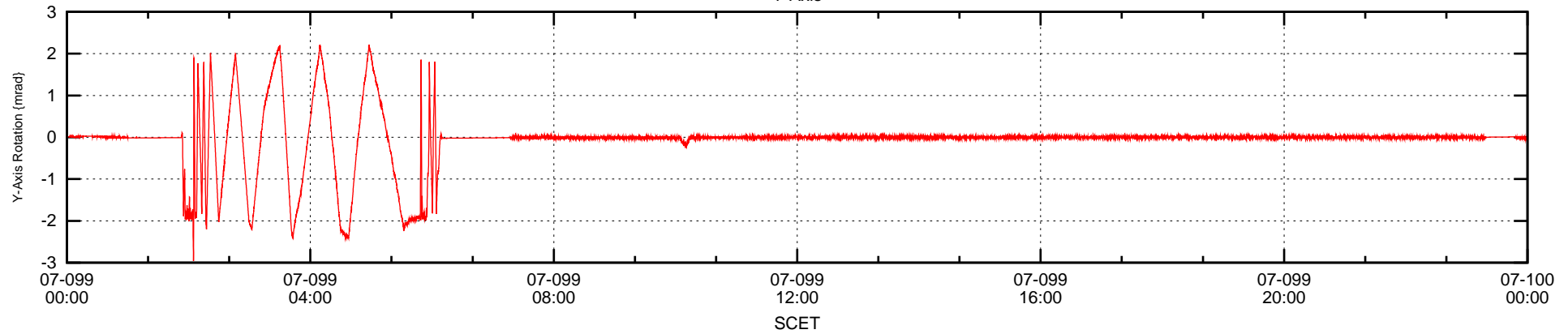


Rotation From CK #2 to CK #1 (DOY 099-100)

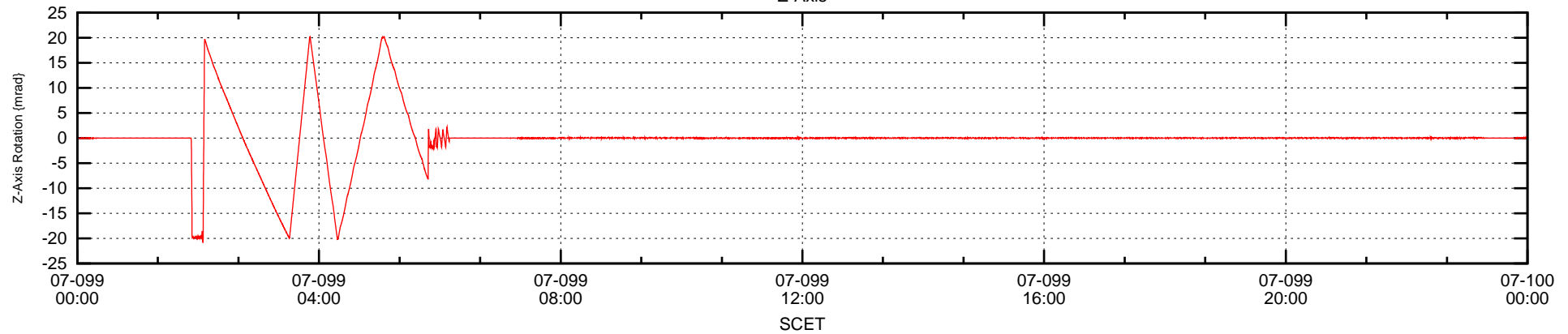
X-Axis (CK #1 = 07097_07102ra.bc; CK #2 = 07087_07124py_as_flown.bc)



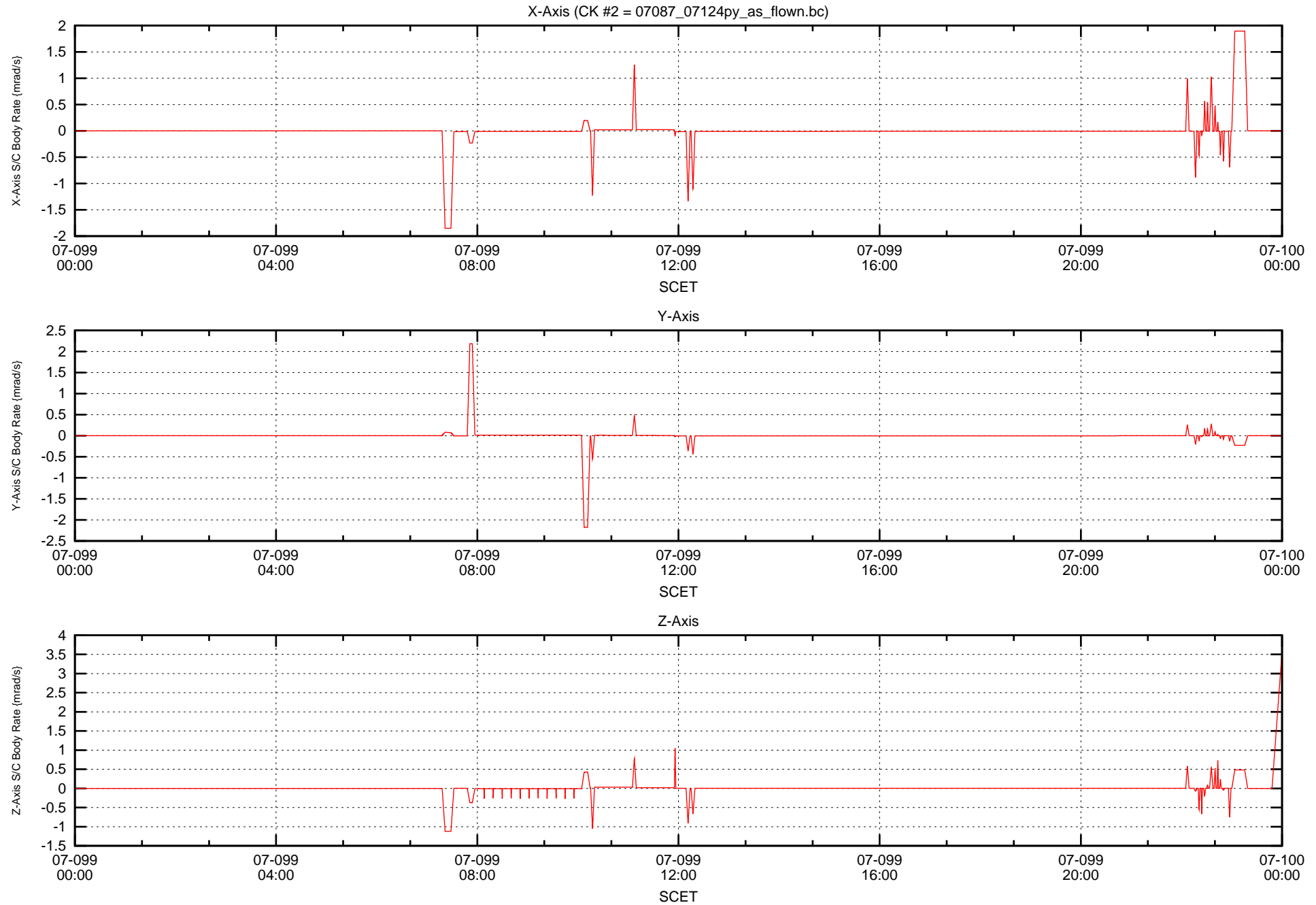
Y-Axis



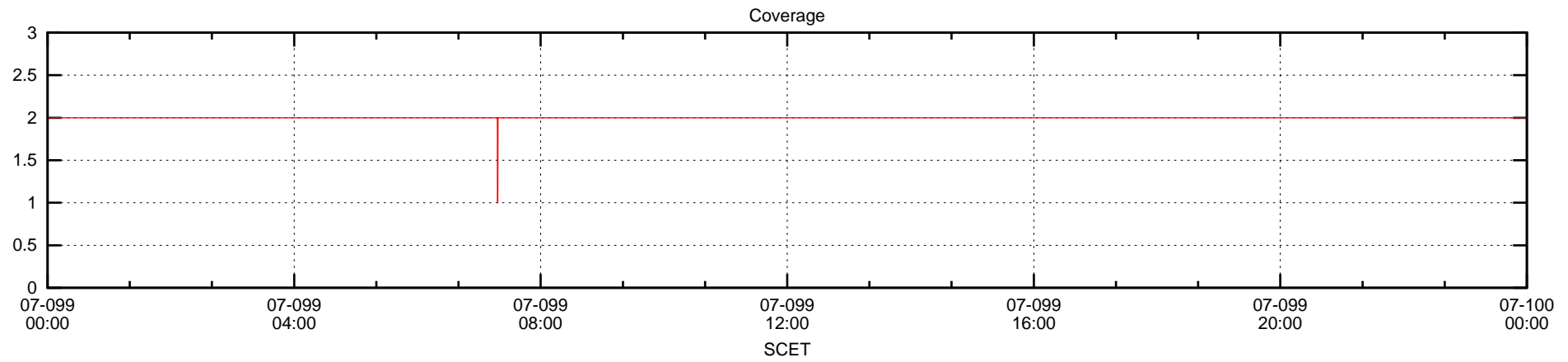
Z-Axis



CK #2 S/C Body Rates (DOY 099-100)

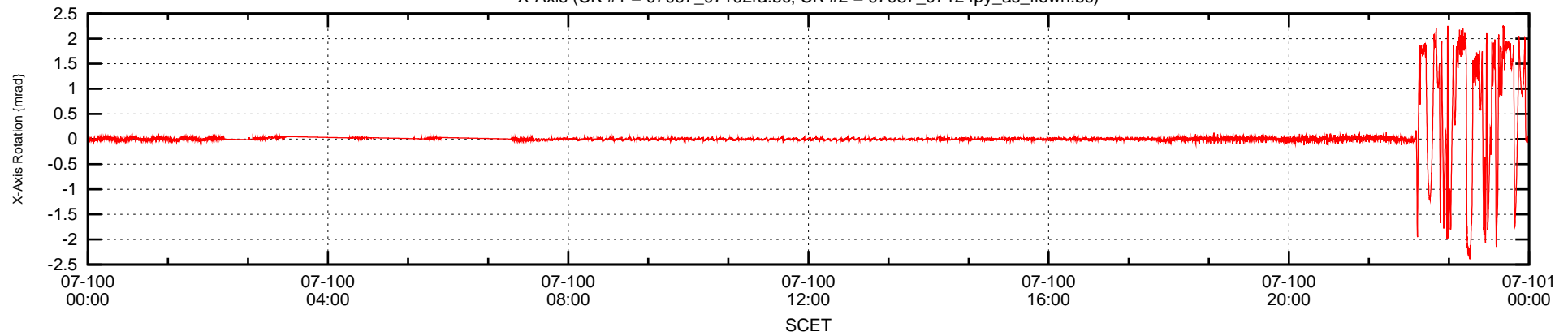


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 099-100)

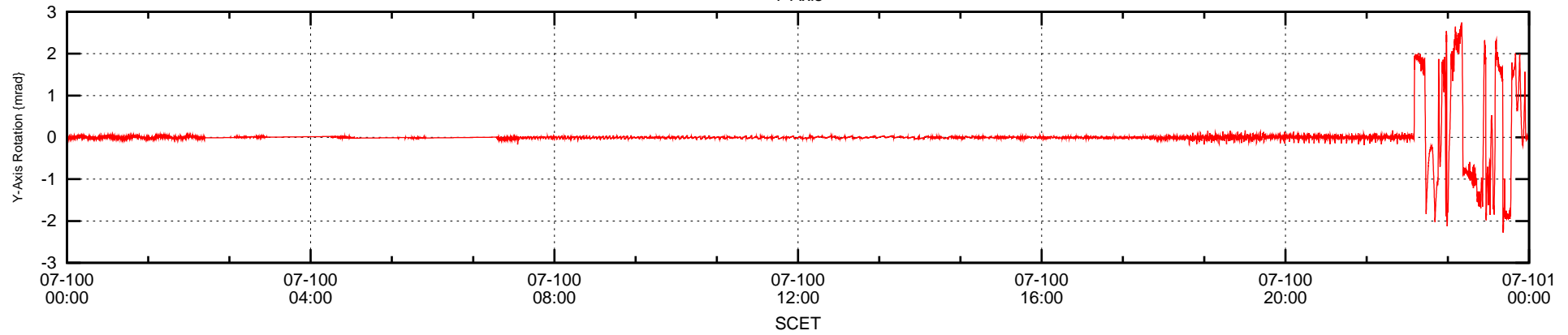


Rotation From CK #2 to CK #1 (DOY 100-101)

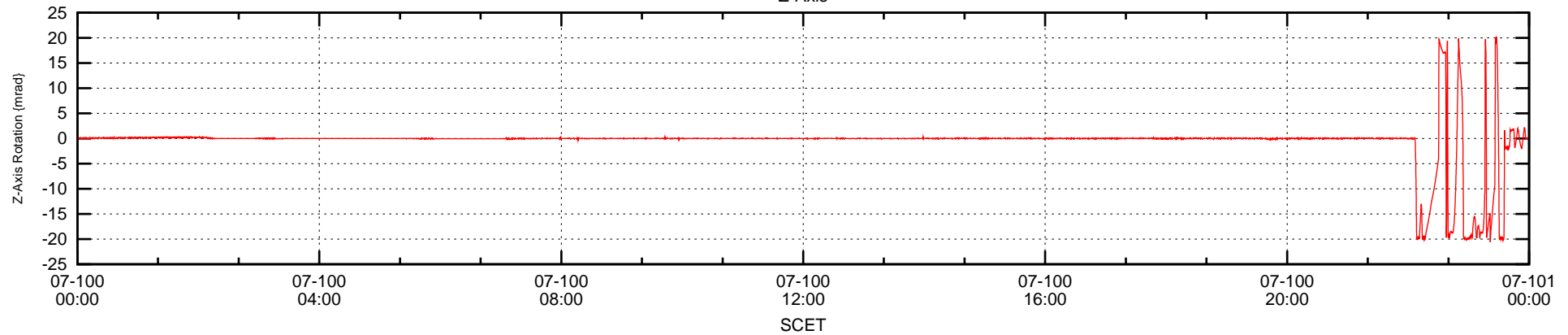
X-Axis (CK #1 = 07097_07102ra.bc; CK #2 = 07087_07124py_as_flown.bc)



Y-Axis

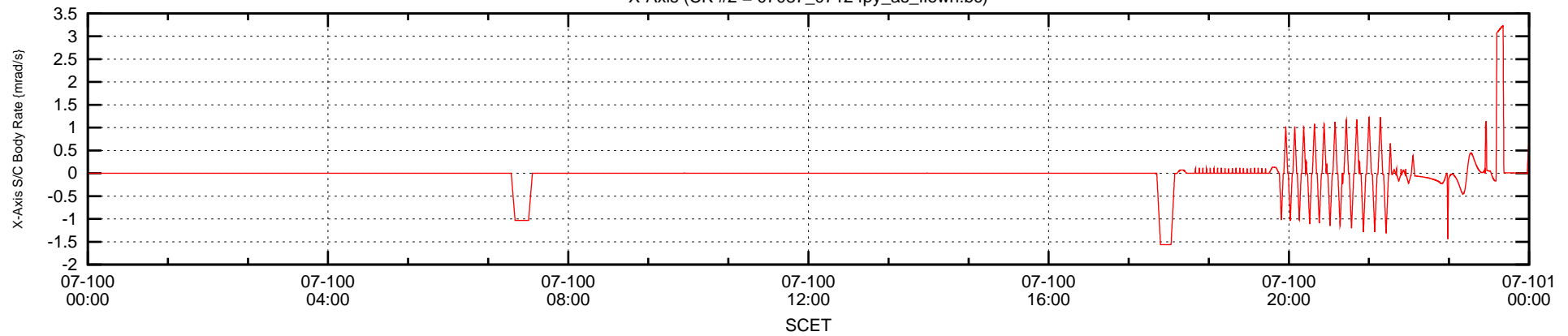


Z-Axis

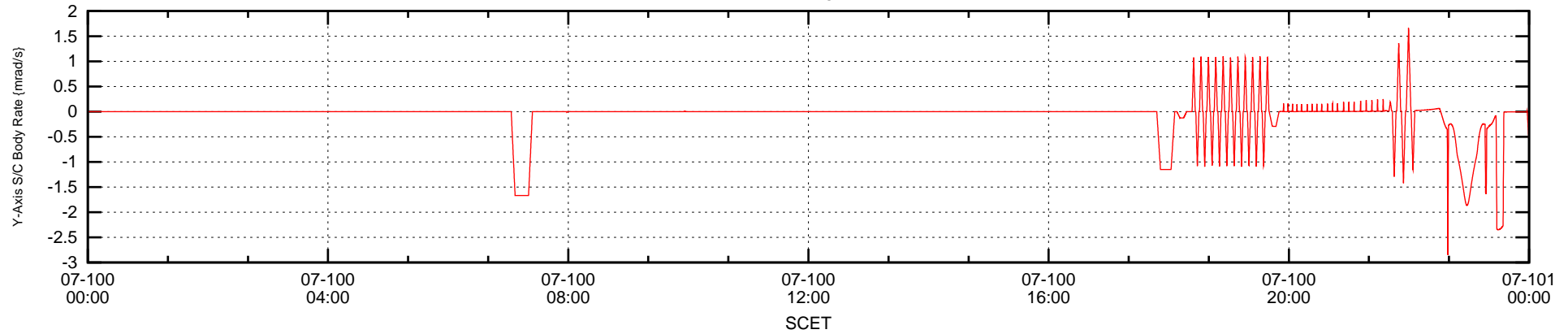


CK #2 S/C Body Rates (DOY 100-101)

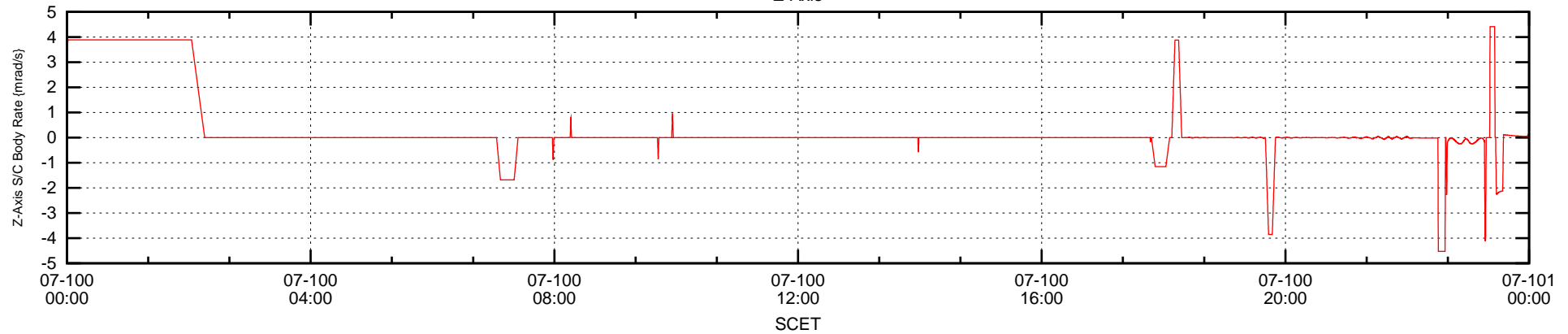
X-Axis (CK #2 = 07087_07124py_as_flowm.bc)



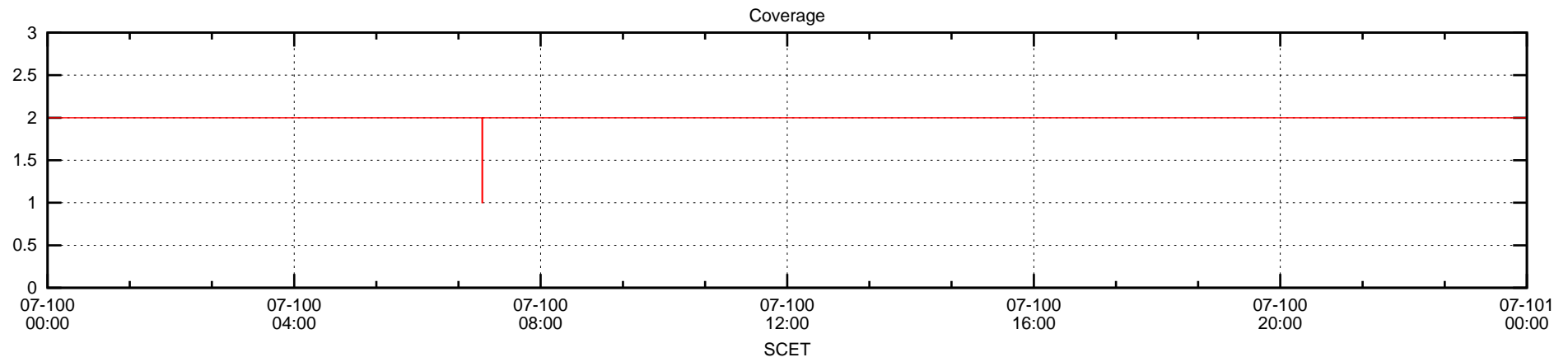
Y-Axis



Z-Axis

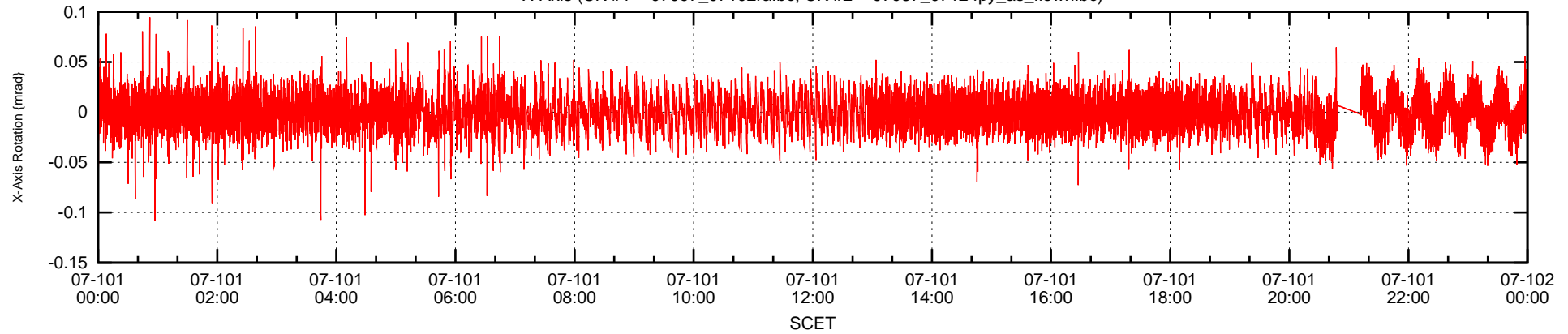


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 100-101)

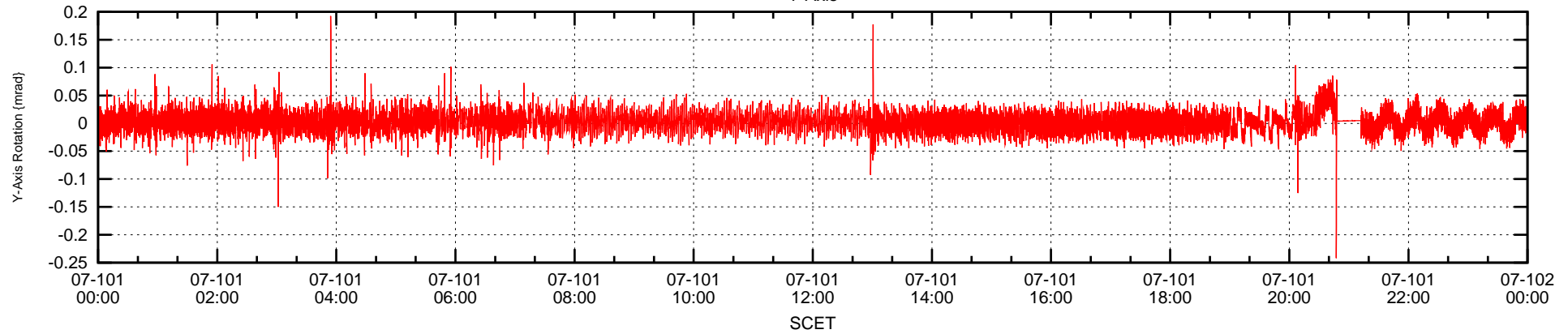


Rotation From CK #2 to CK #1 (DOY 101-101)

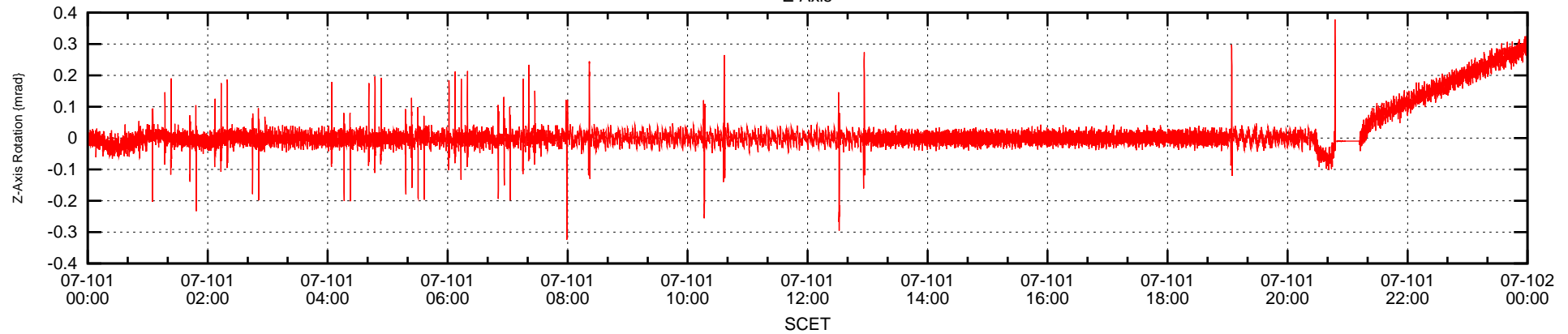
X-Axis (CK #1 = 07097_07102ra.bc; CK #2 = 07087_07124py_as_flown.bc)



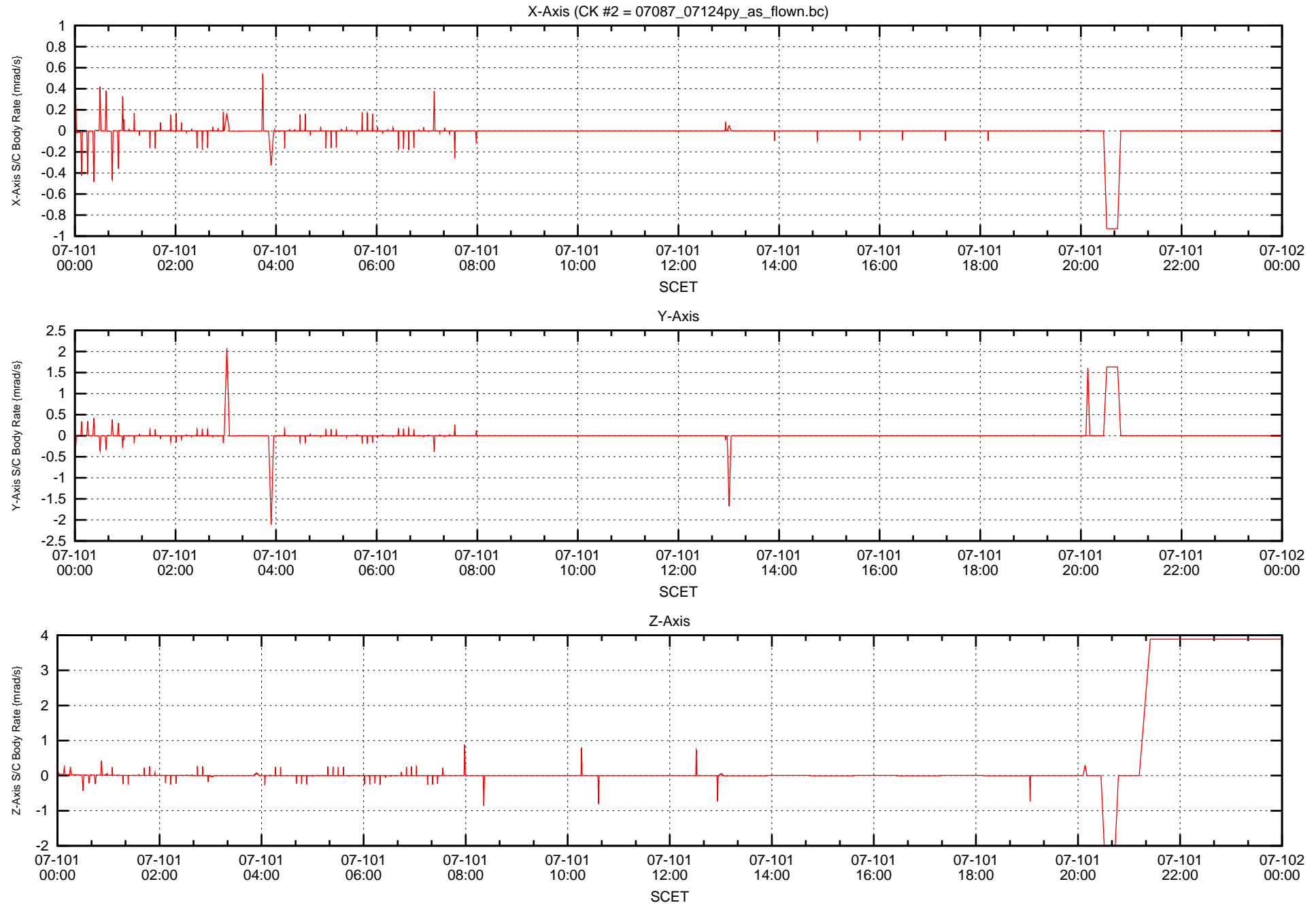
Y-Axis



Z-Axis



CK #2 S/C Body Rates (DOY 101-101)



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 101-101)

