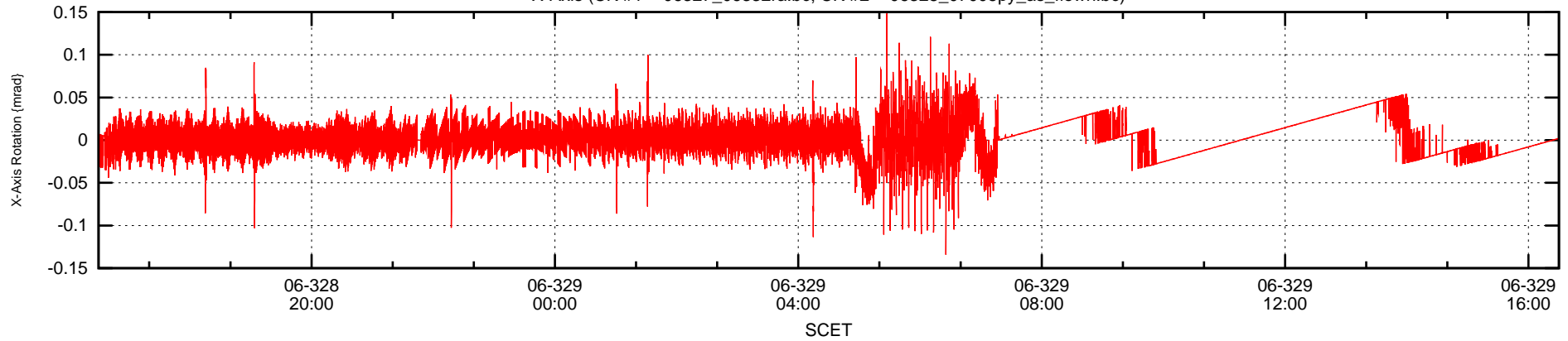
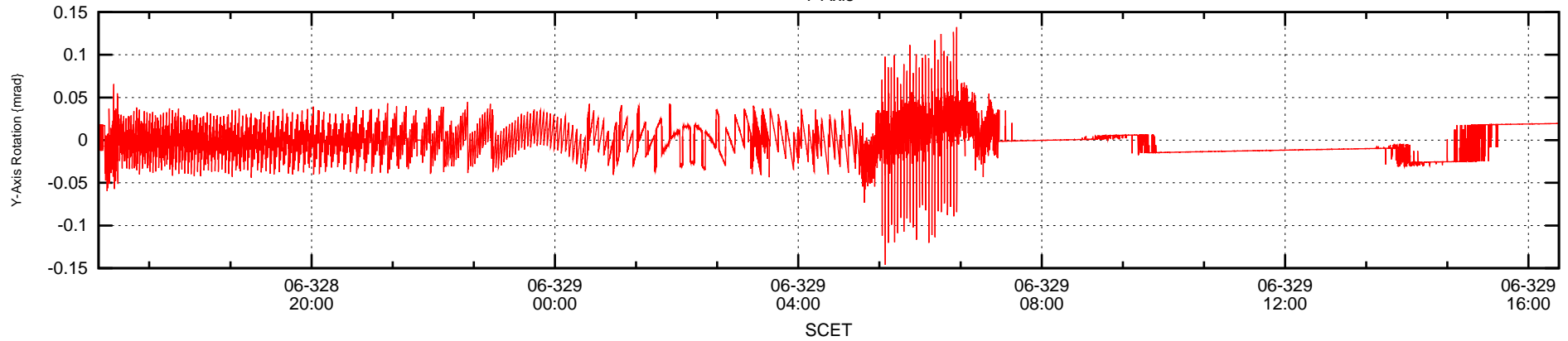


# Rotation From CK #2 to CK #1 (DOY 328-329)

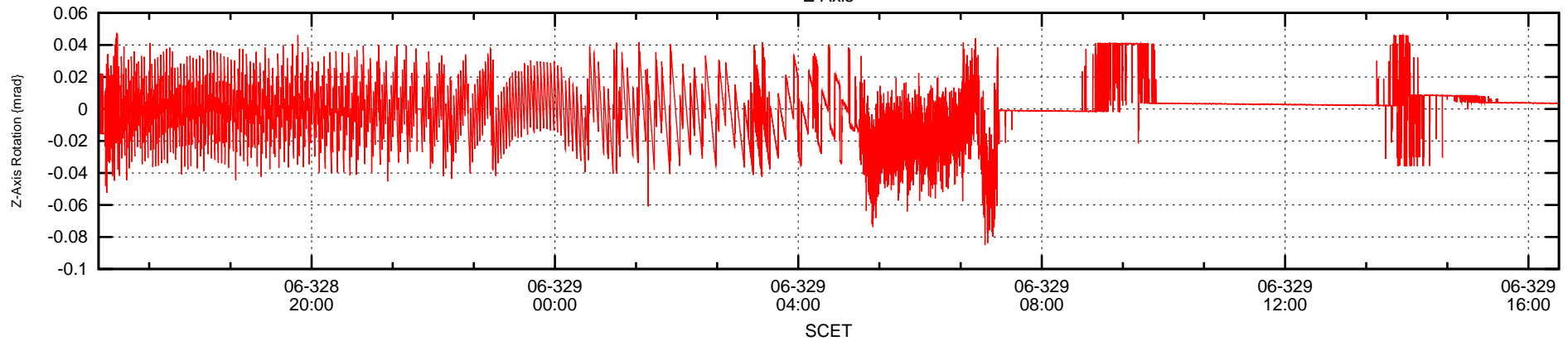
X-Axis (CK #1 = 06327\_06332ra.bc; CK #2 = 06328\_07005py\_as\_flowm.bc)



Y-Axis

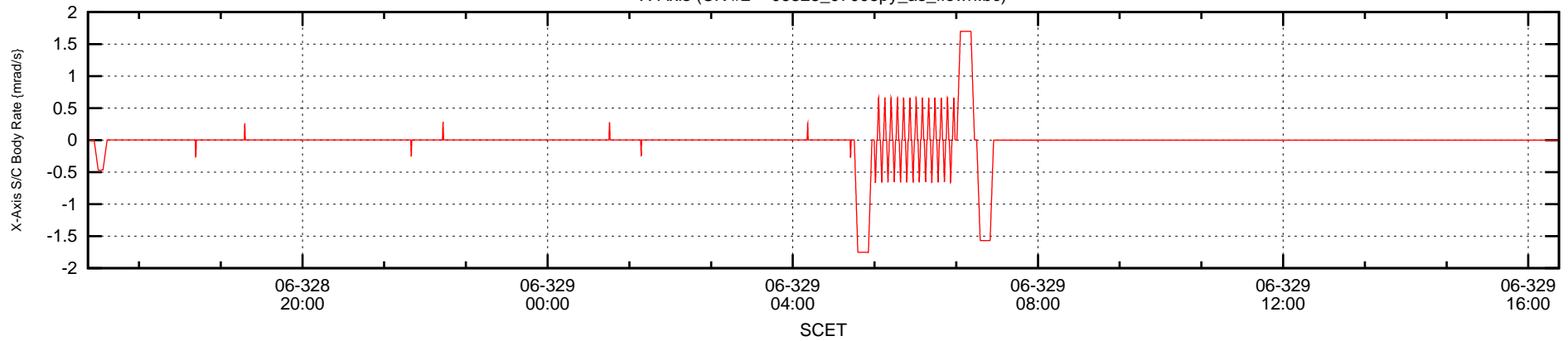


Z-Axis

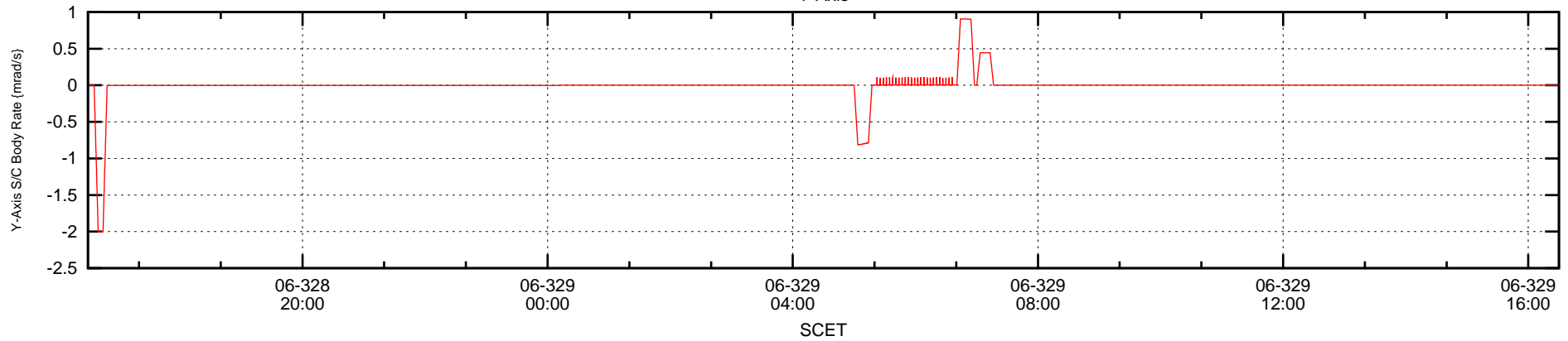


# CK #2 S/C Body Rates (DOY 328-329)

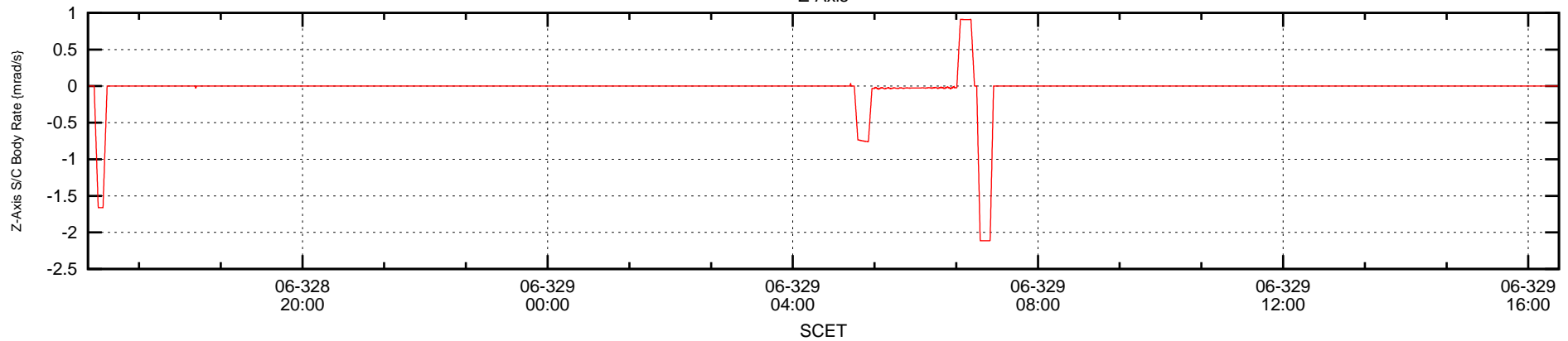
X-Axis (CK #2 = 06328\_07005py\_as\_flowm.bc)



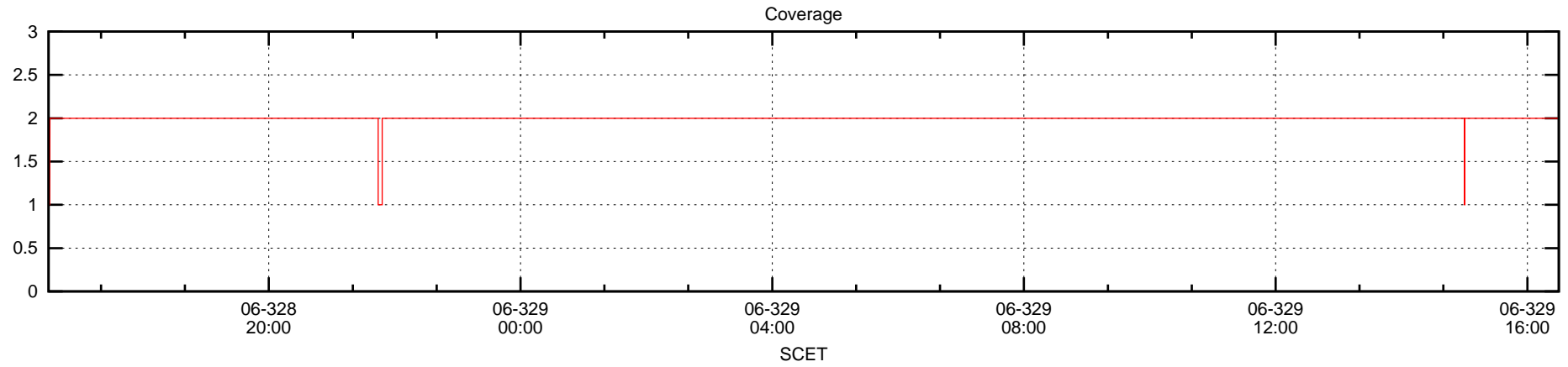
Y-Axis



Z-Axis

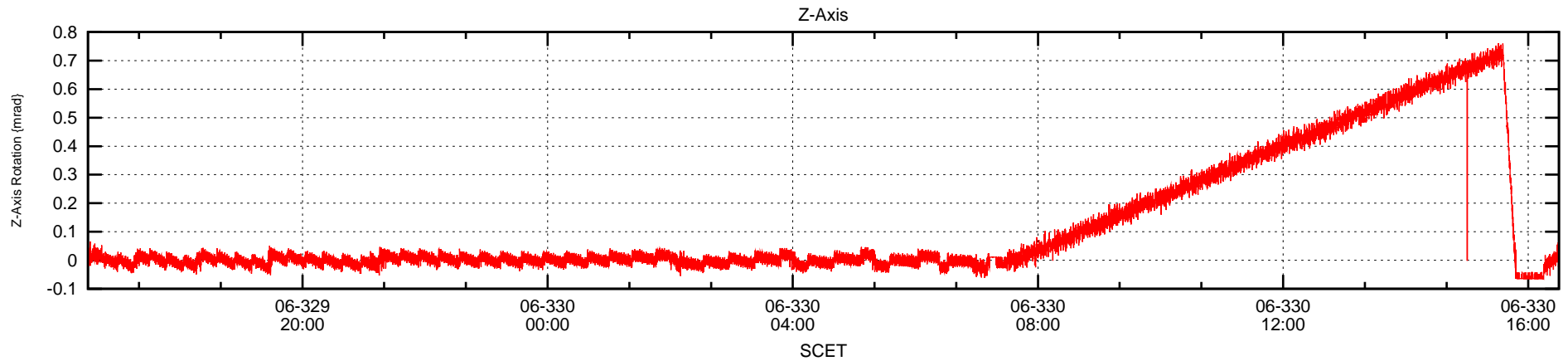
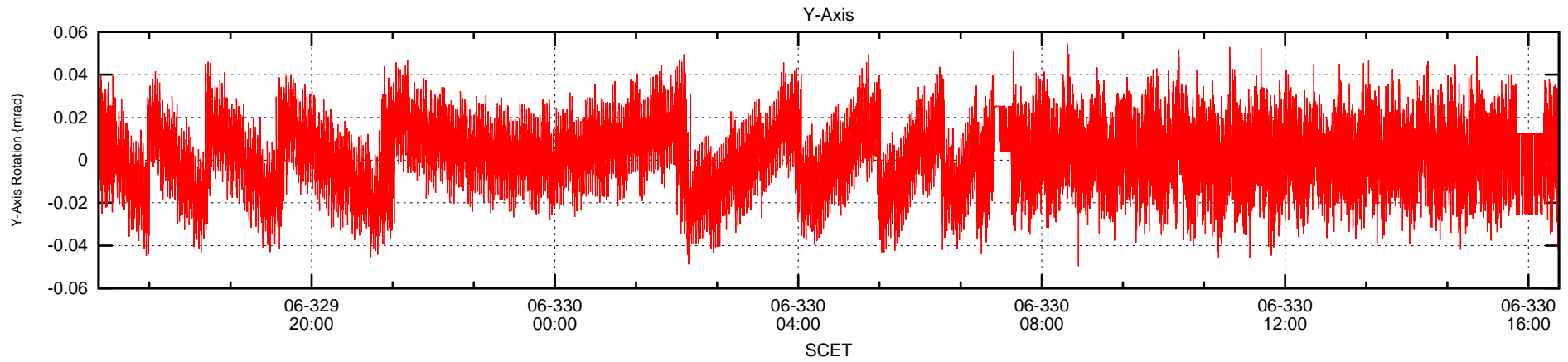
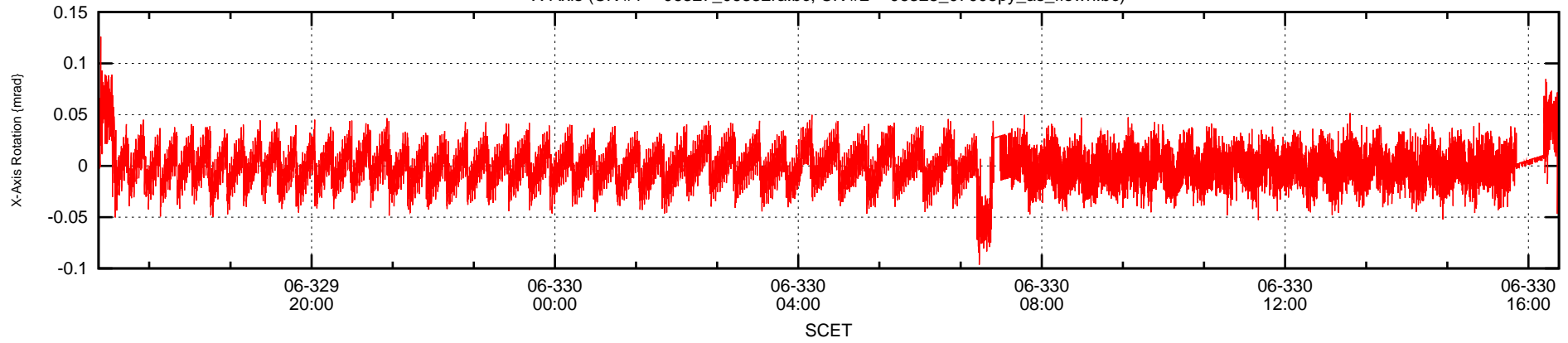


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 328-329)



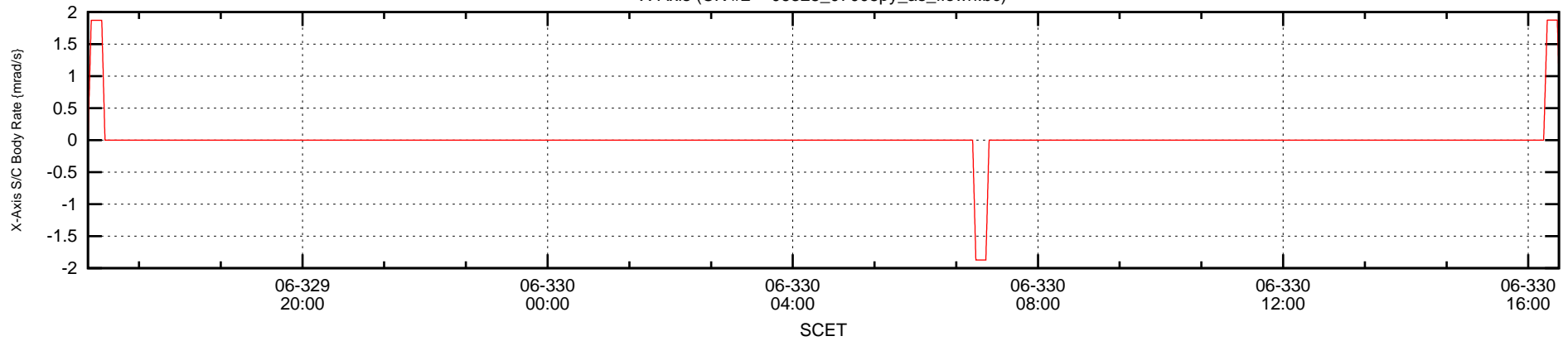
# Rotation From CK #2 to CK #1 (DOY 329-330)

X-Axis (CK #1 = 06327\_06332ra.bc; CK #2 = 06328\_07005py\_as\_flowm.bc)

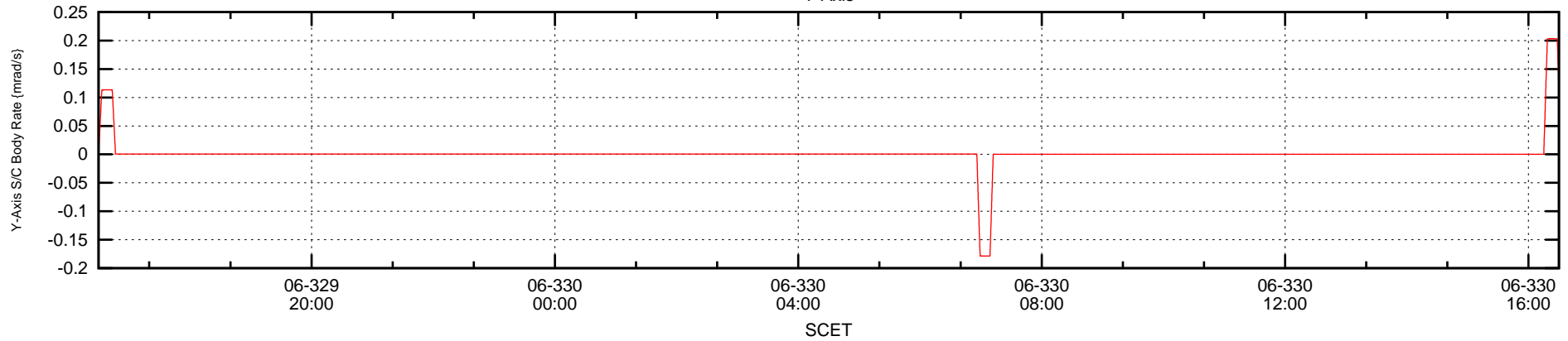


# CK #2 S/C Body Rates (DOY 329-330)

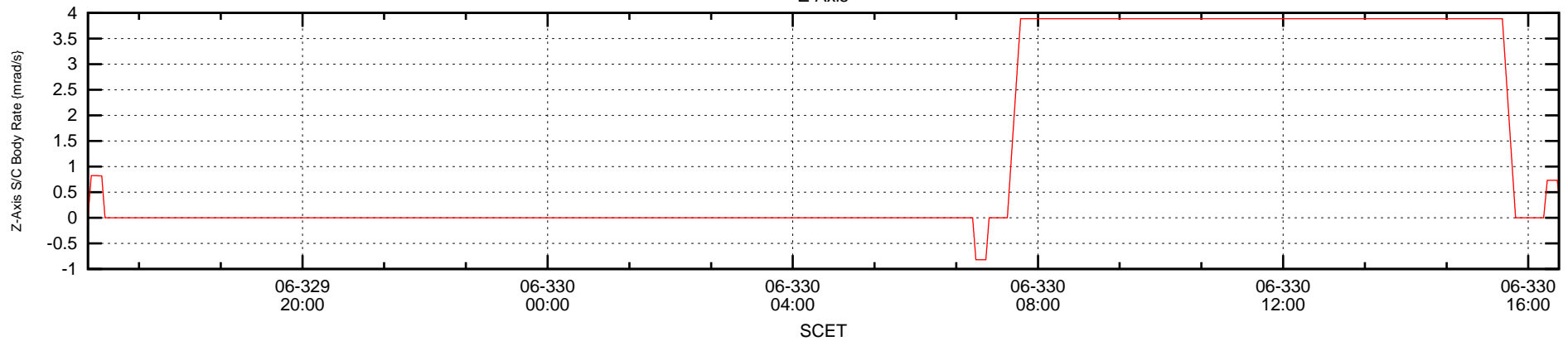
X-Axis (CK #2 = 06328\_07005py\_as\_flowm.bc)



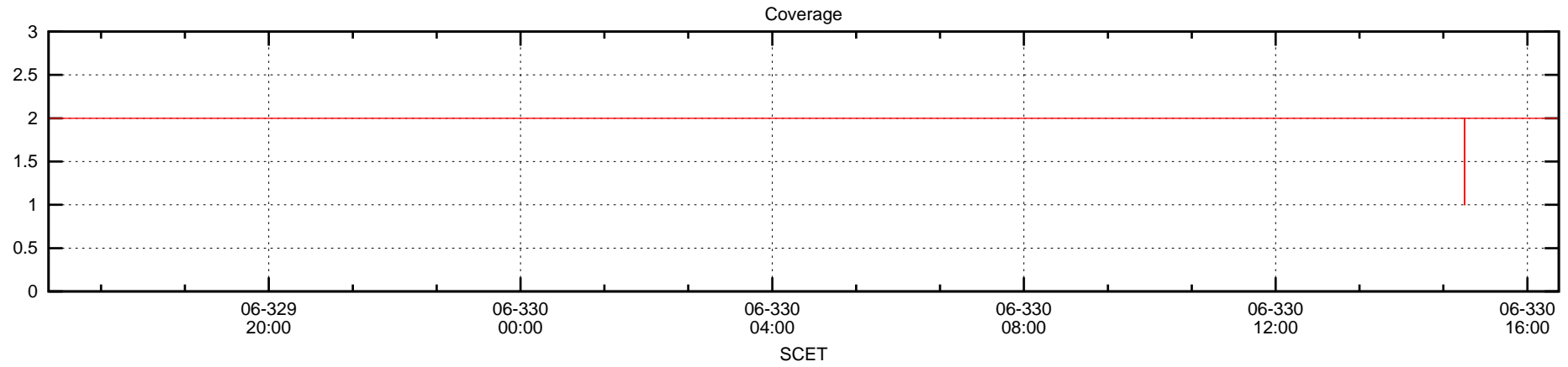
Y-Axis



Z-Axis

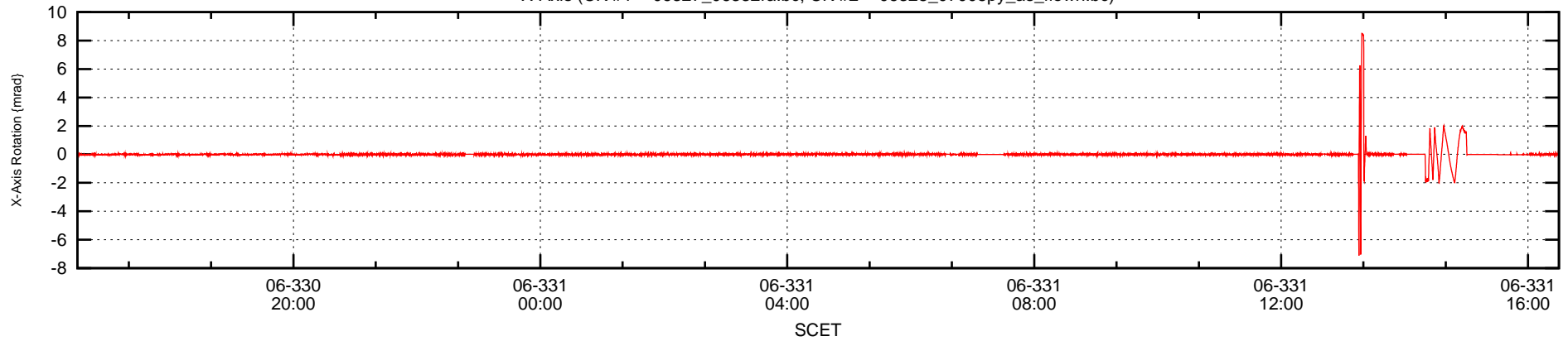


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 329-330)

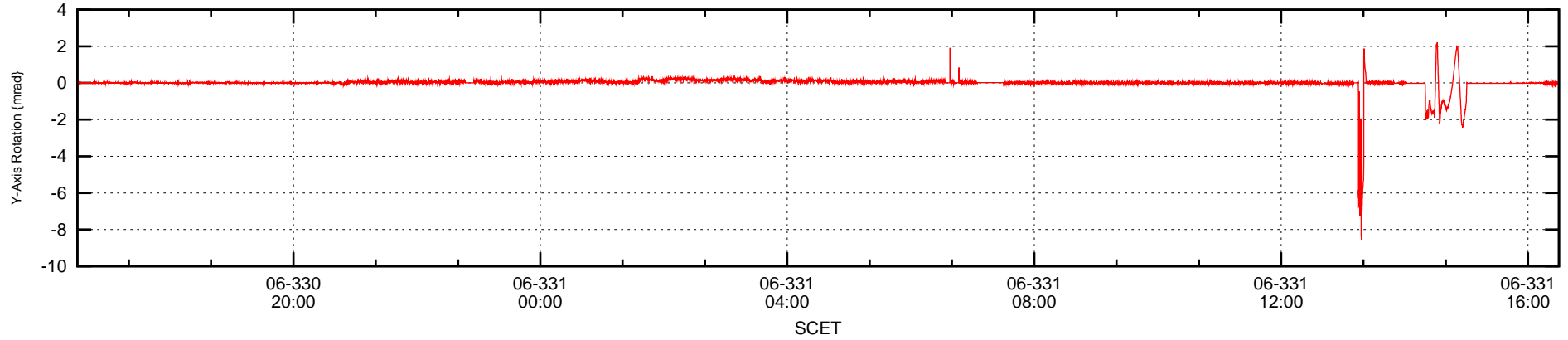


# Rotation From CK #2 to CK #1 (DOY 330-331)

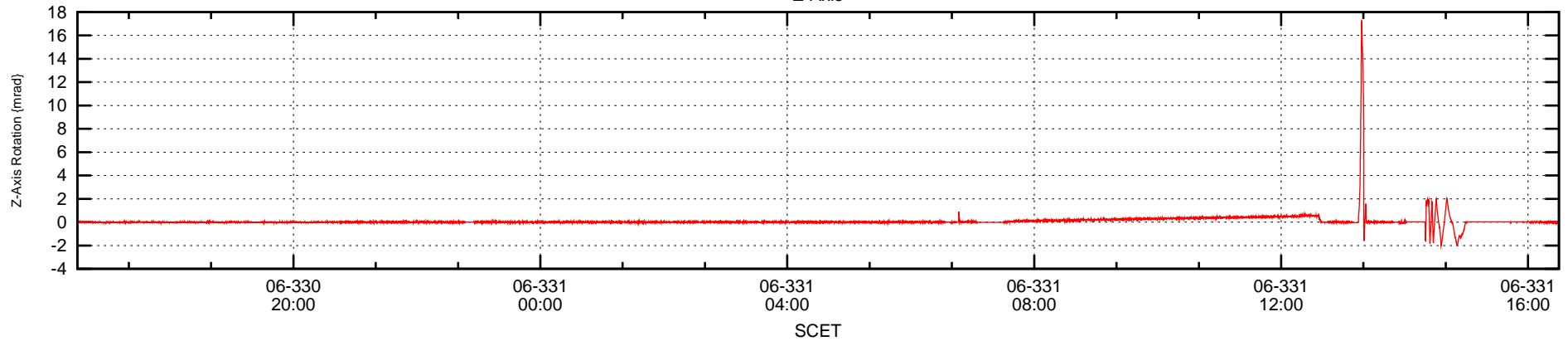
X-Axis (CK #1 = 06327\_06332ra.bc; CK #2 = 06328\_07005py\_as\_flown.bc)



Y-Axis

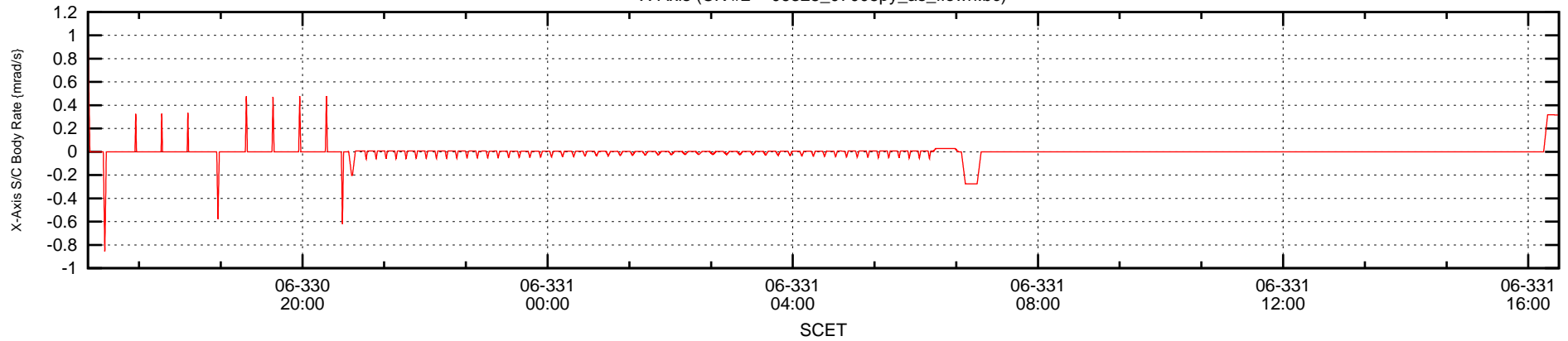


Z-Axis

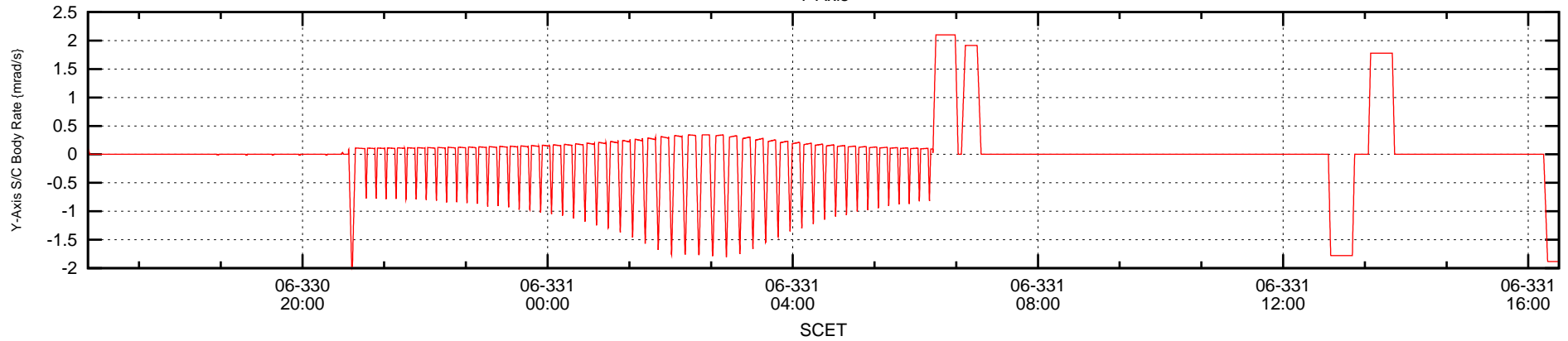


# CK #2 S/C Body Rates (DOY 330-331)

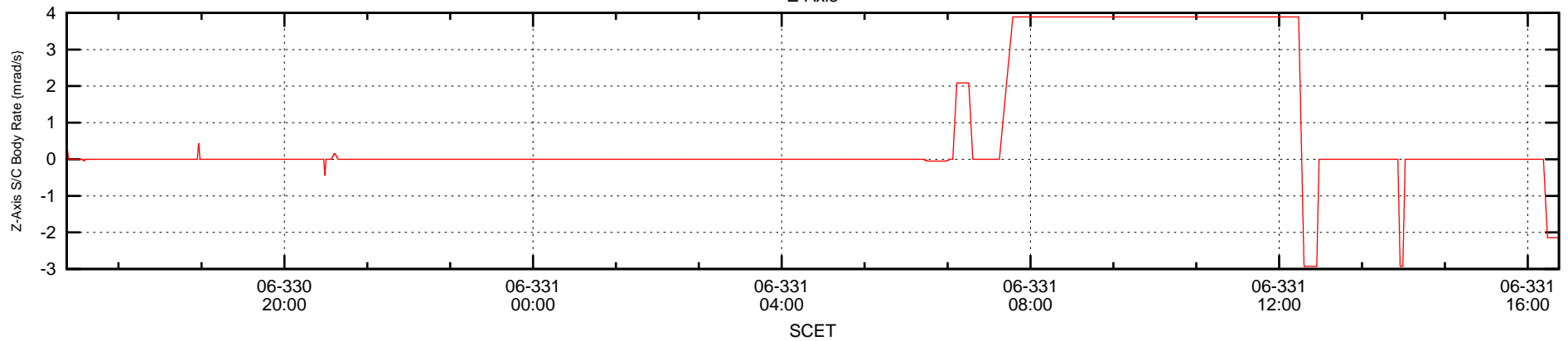
X-Axis (CK #2 = 06328\_07005py\_as\_flown.bc)



Y-Axis

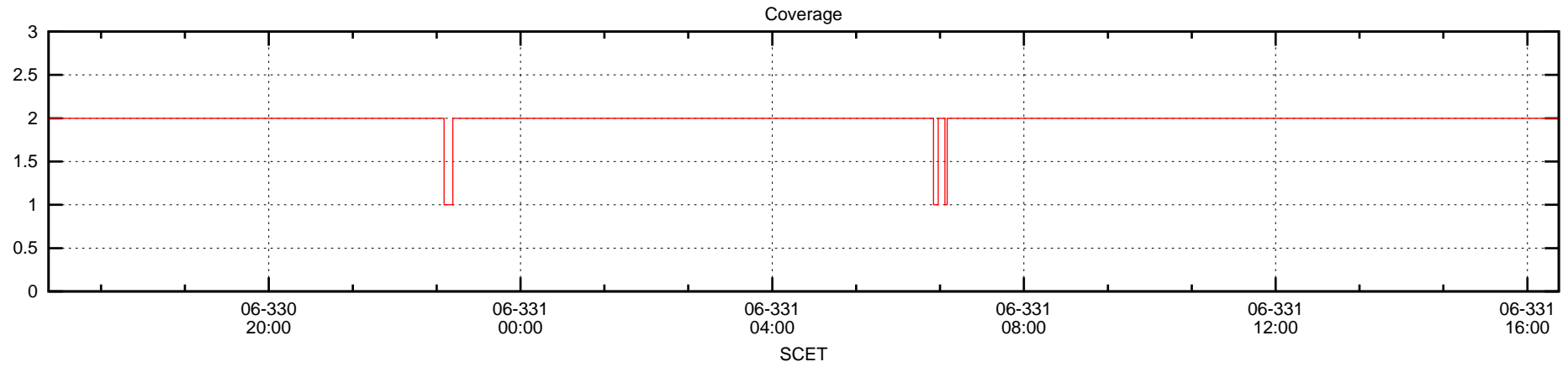


Z-Axis



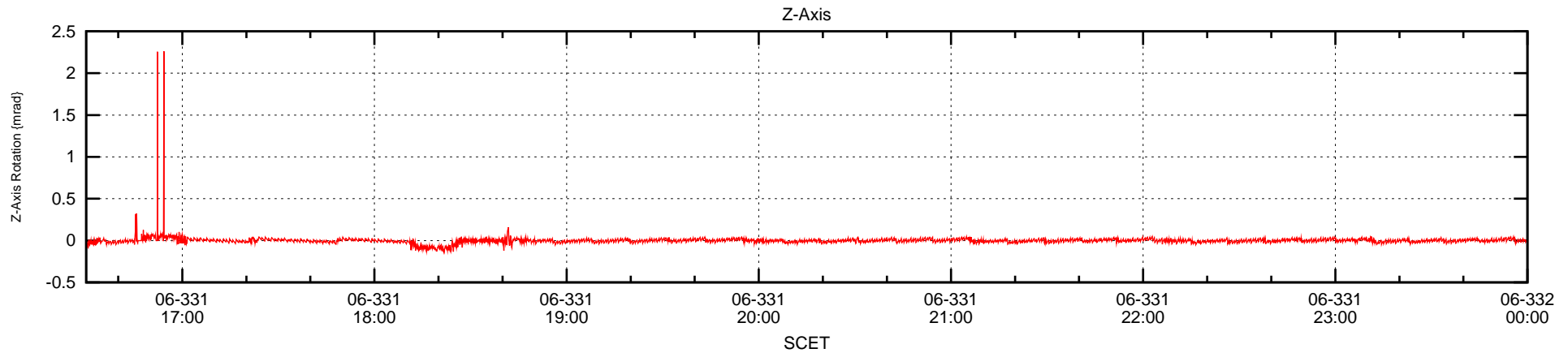
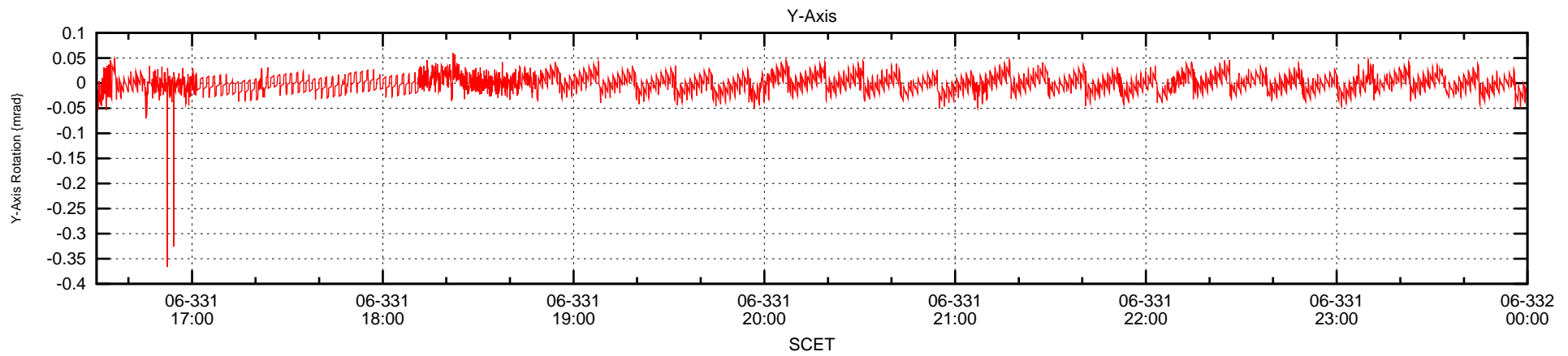
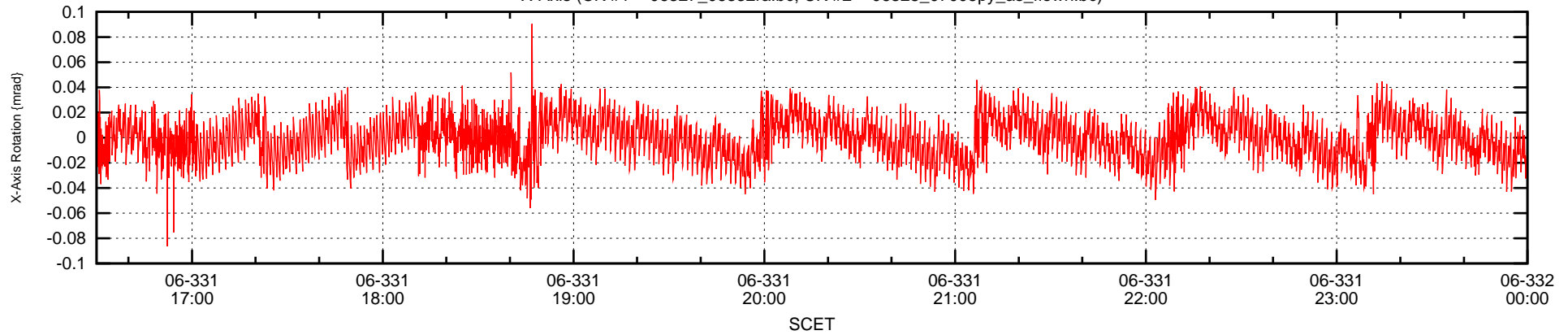


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 330-331)



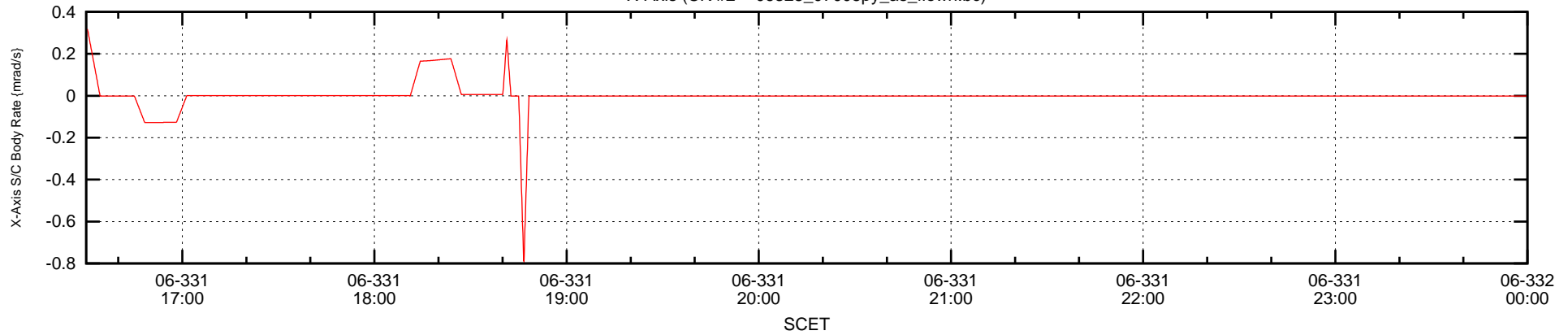
# Rotation From CK #2 to CK #1 (DOY 331-331)

X-Axis (CK #1 = 06327\_06332ra.bc; CK #2 = 06328\_07005py\_as\_flowm.bc)

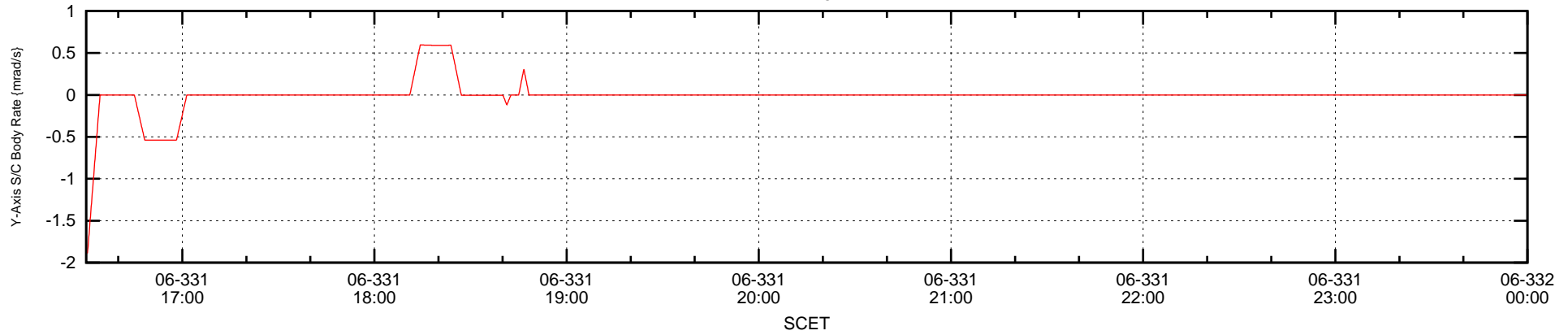


# CK #2 S/C Body Rates (DOY 331-331)

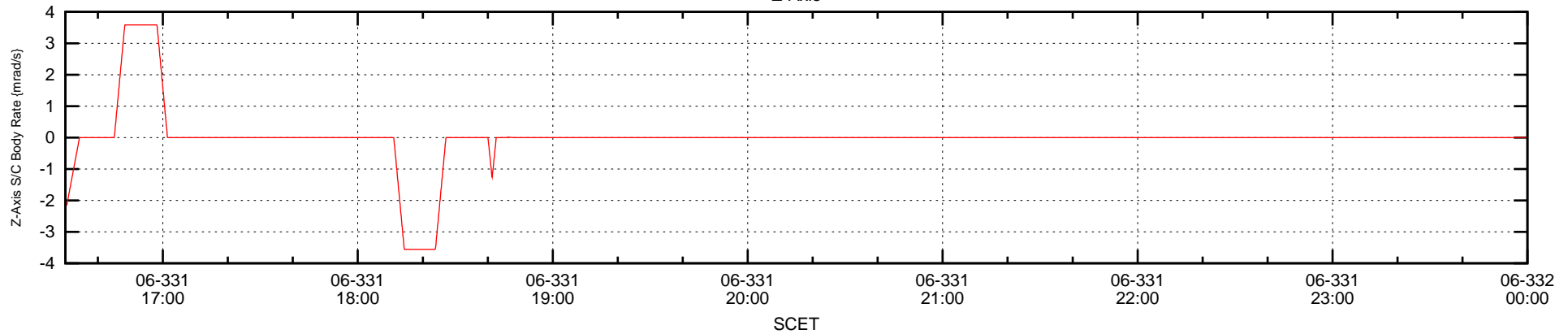
X-Axis (CK #2 = 06328\_07005py\_as\_flowm.bc)



Y-Axis



Z-Axis



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 331-331)

