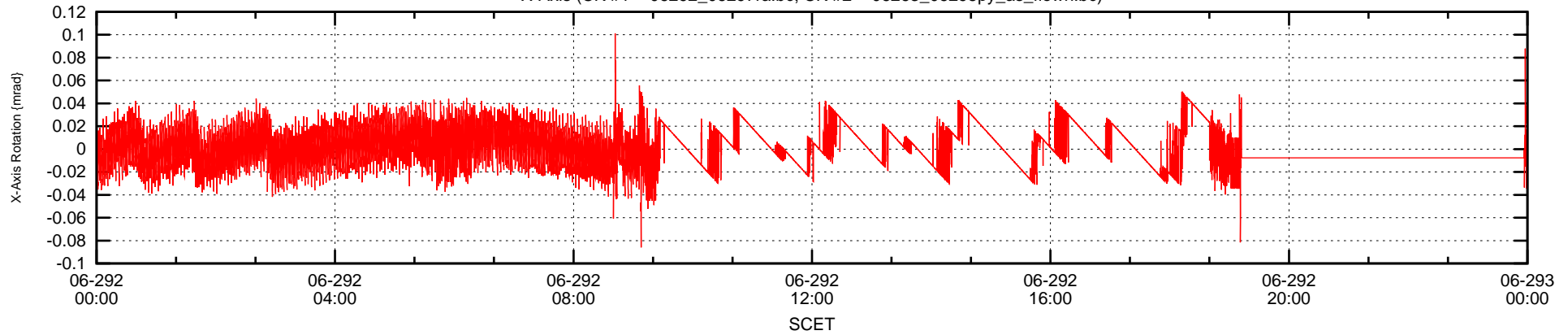
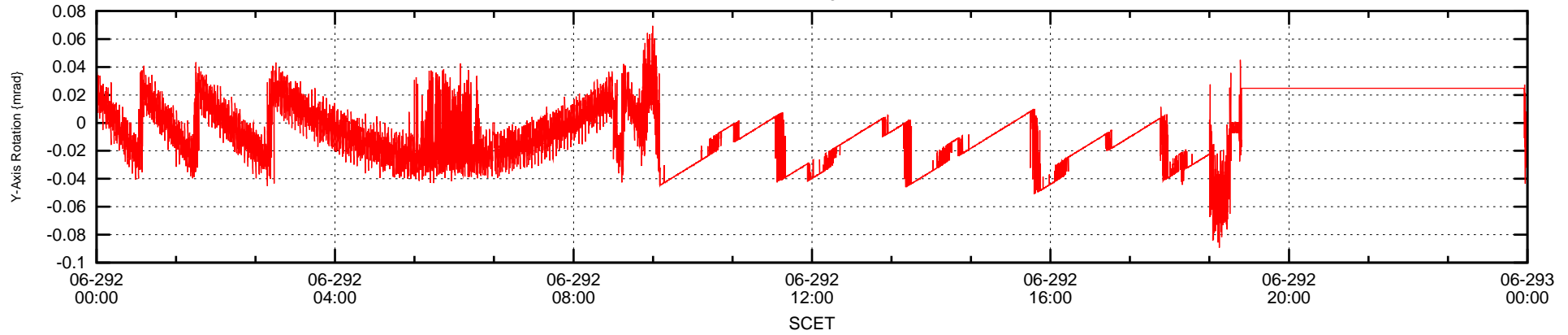


Rotation From CK #2 to CK #1 (DOY 292-293)

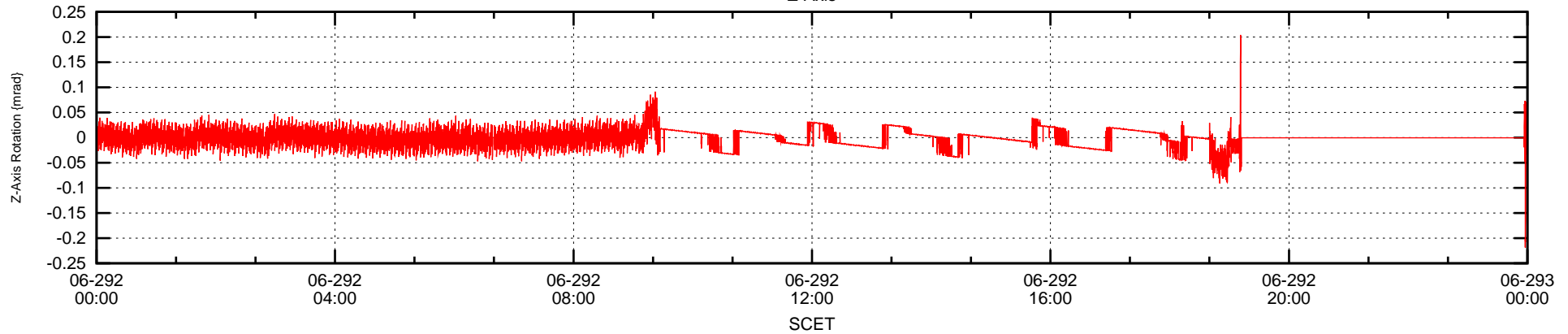
X-Axis (CK #1 = 06292_06297ra.bc; CK #2 = 06263_06295py_as_flowm.bc)



Y-Axis

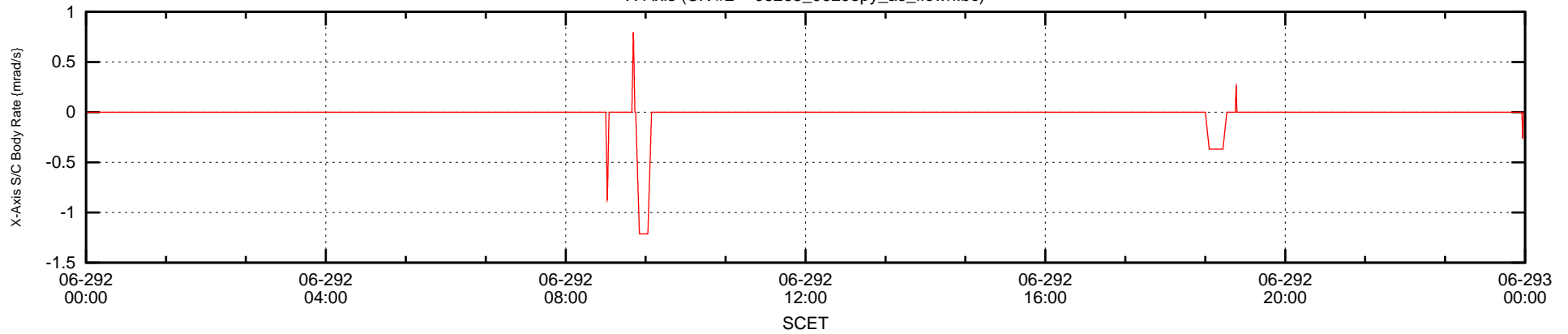


Z-Axis

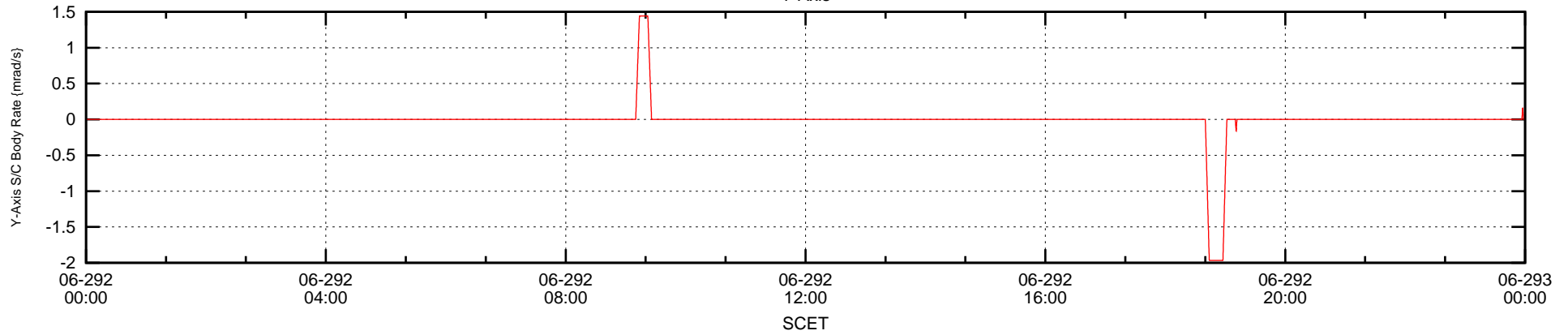


CK #2 S/C Body Rates (DOY 292-293)

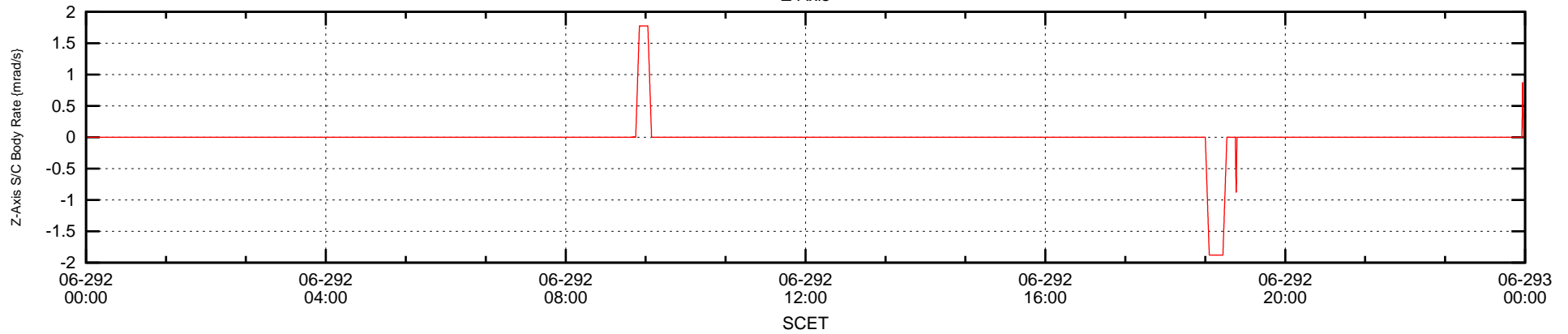
X-Axis (CK #2 = 06263_06295py_as_flowm.bc)



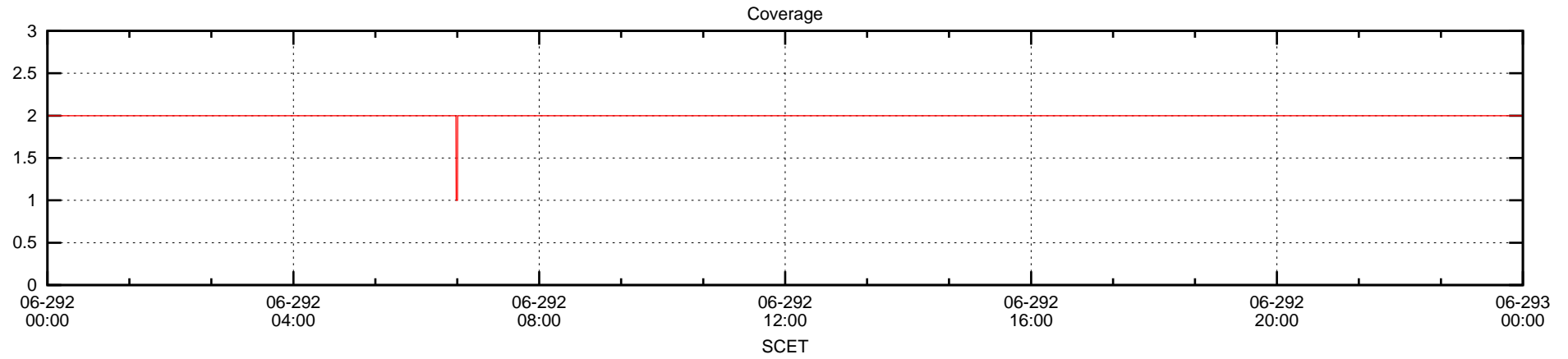
Y-Axis



Z-Axis

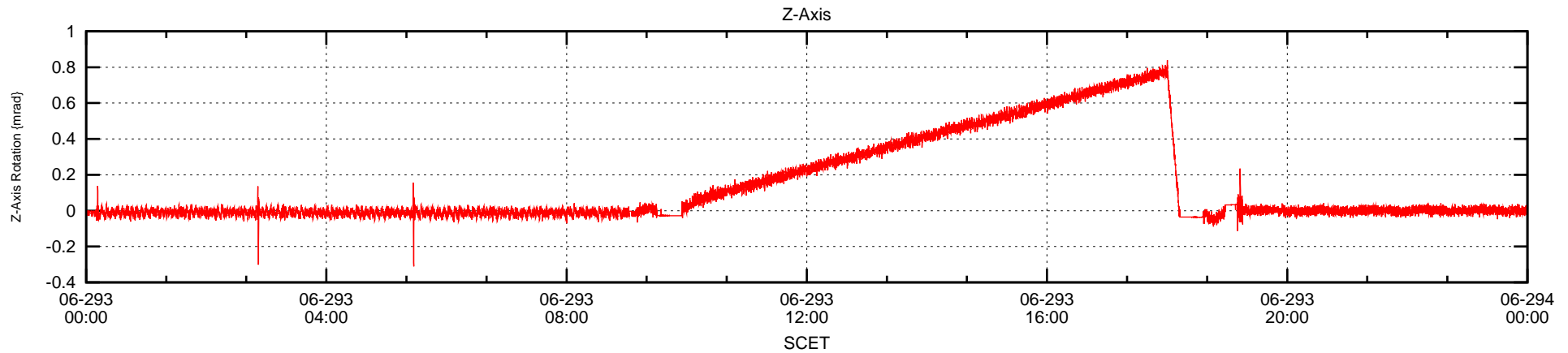
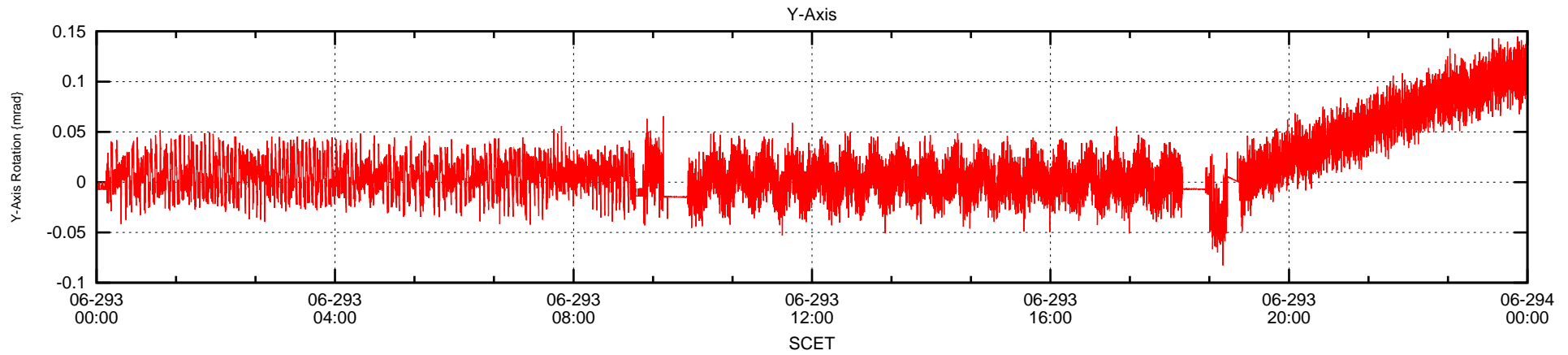
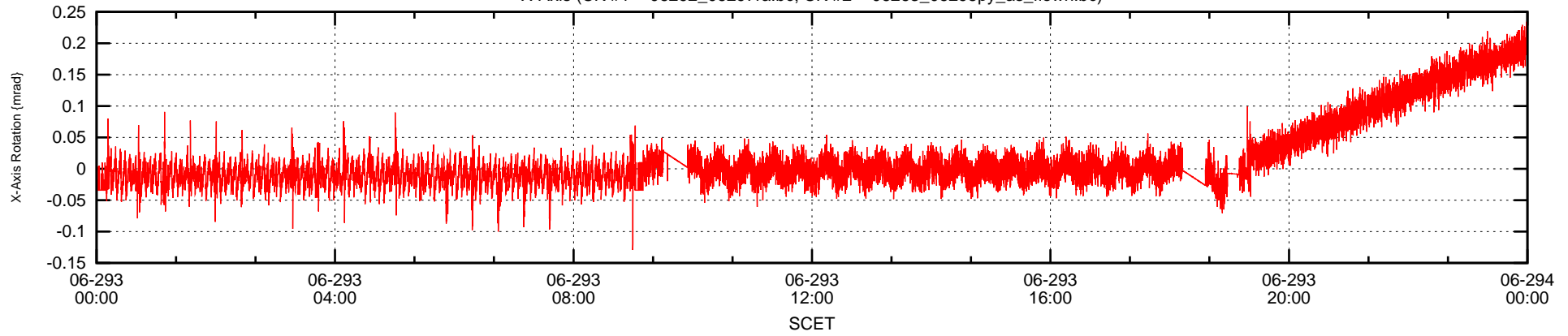


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 292-293)



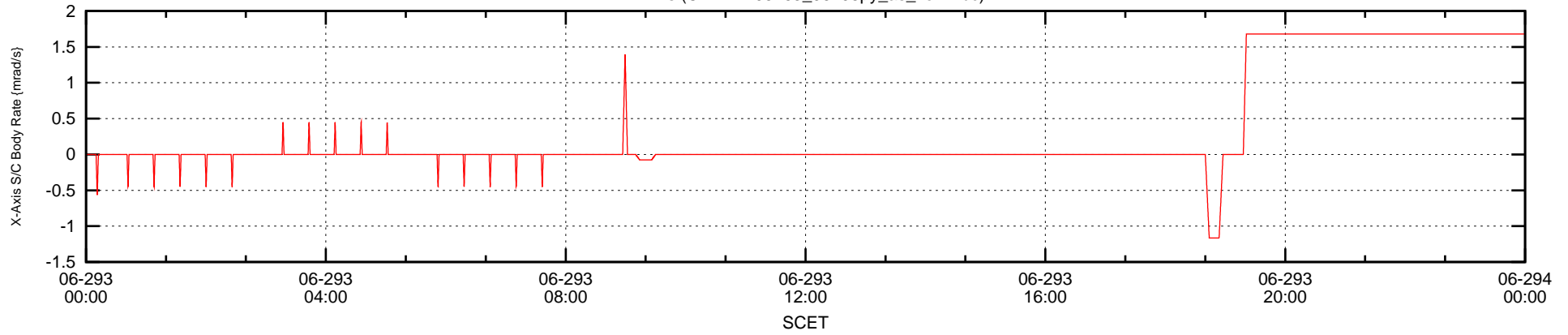
Rotation From CK #2 to CK #1 (DOY 293-294)

X-Axis (CK #1 = 06292_06297ra.bc; CK #2 = 06263_06295py_as_flowm.bc)

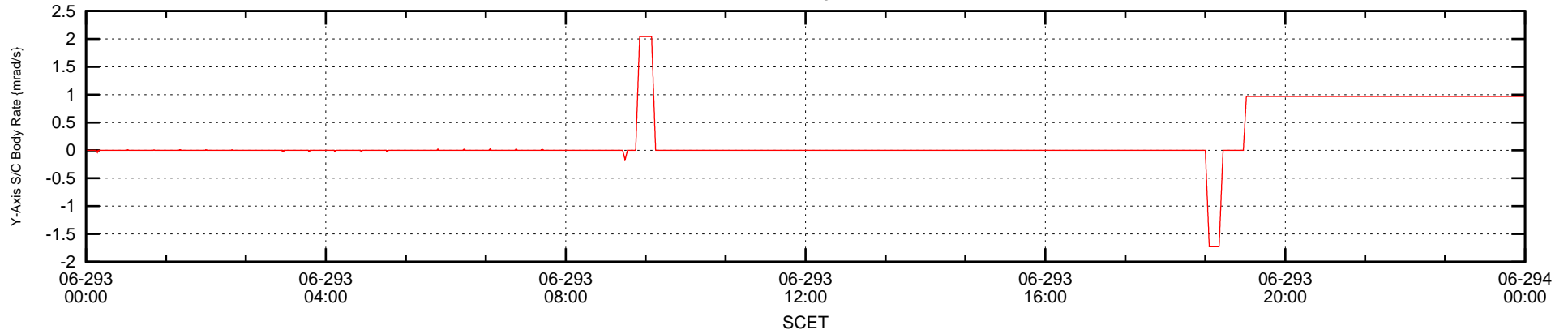


CK #2 S/C Body Rates (DOY 293-294)

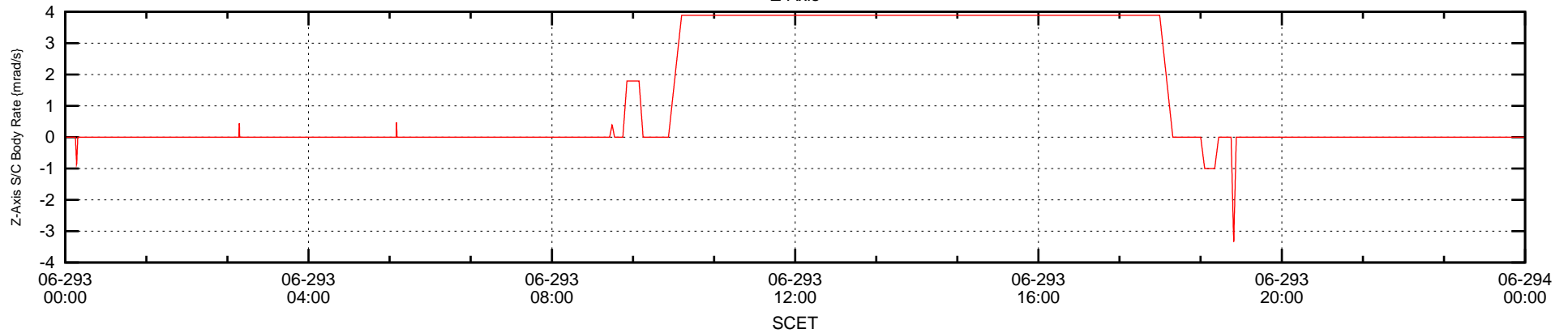
X-Axis (CK #2 = 06263_06295py_as_flowm.bc)



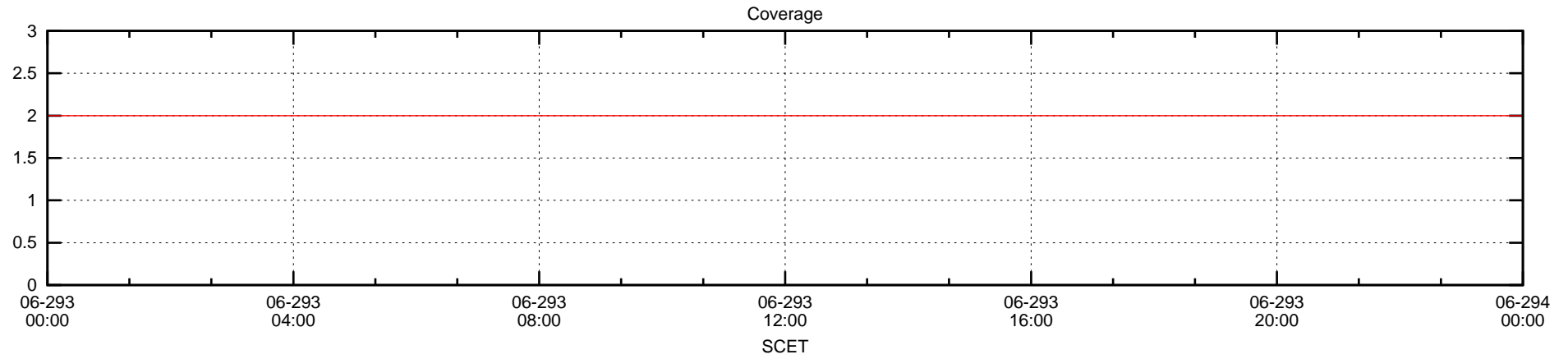
Y-Axis



Z-Axis

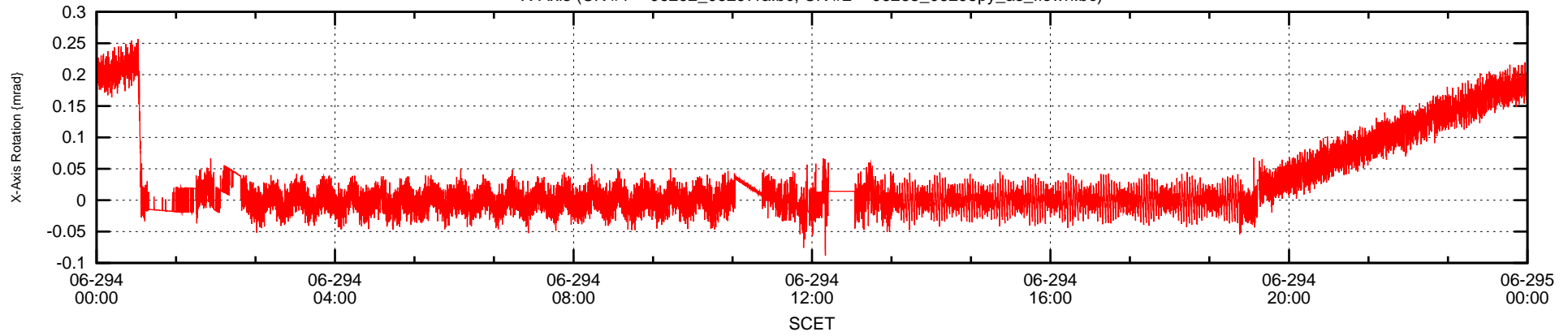


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 293-294)

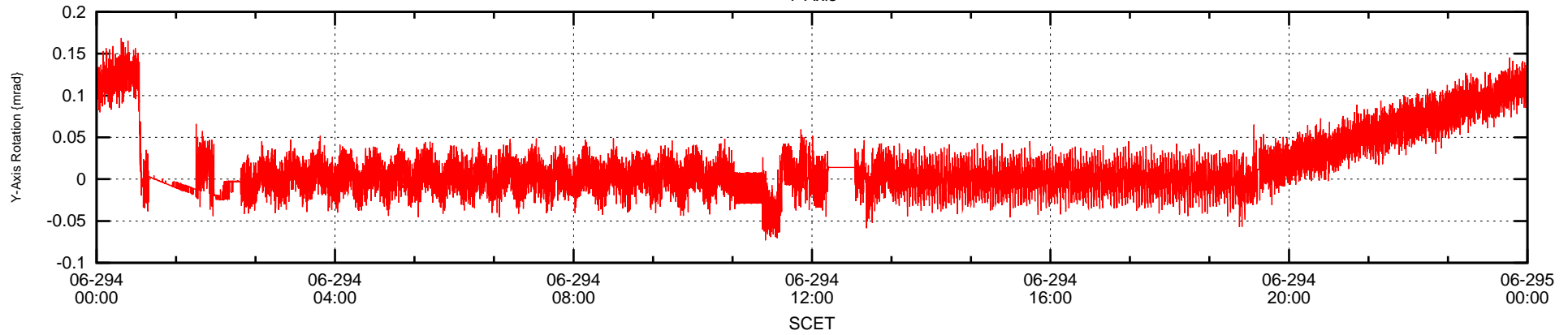


Rotation From CK #2 to CK #1 (DOY 294-295)

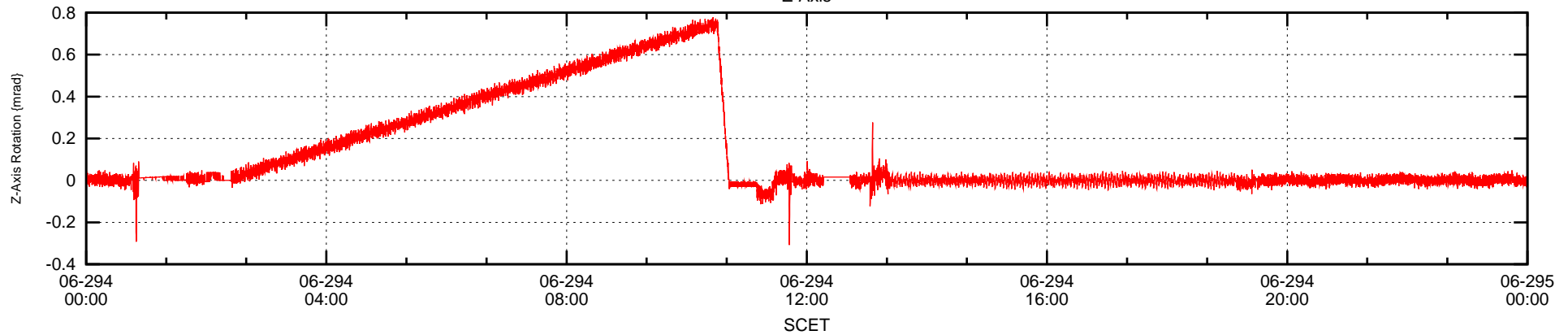
X-Axis (CK #1 = 06292_06297ra.bc; CK #2 = 06263_06295py_as_flowm.bc)



Y-Axis

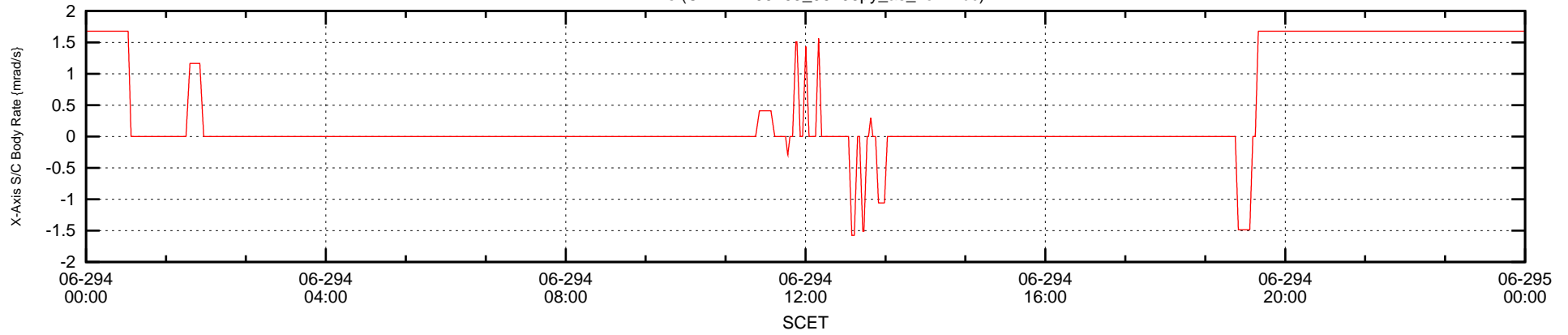


Z-Axis

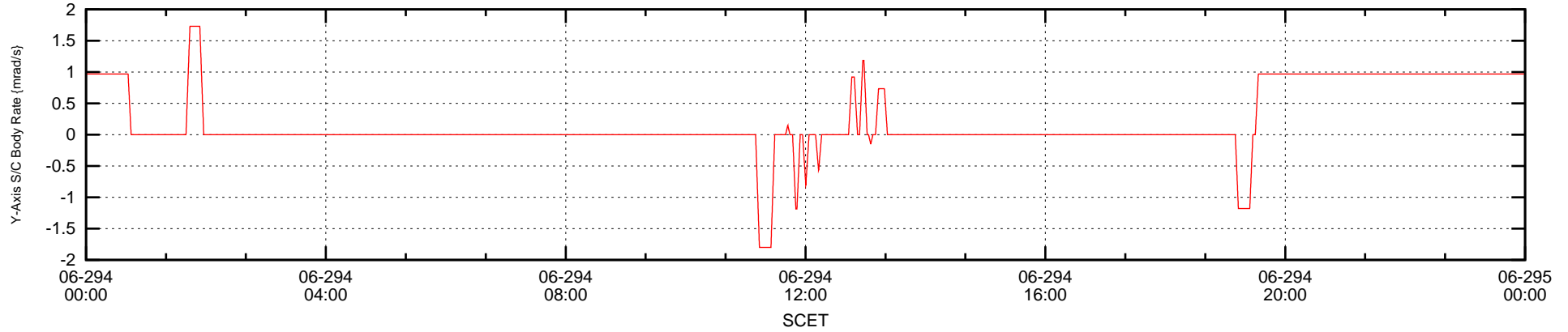


CK #2 S/C Body Rates (DOY 294-295)

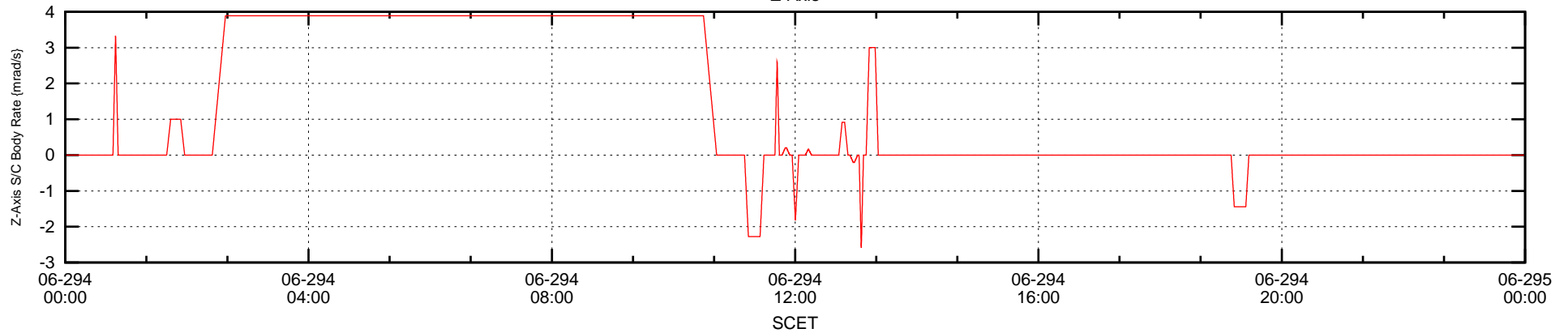
X-Axis (CK #2 = 06263_06295py_as_flown.bc)



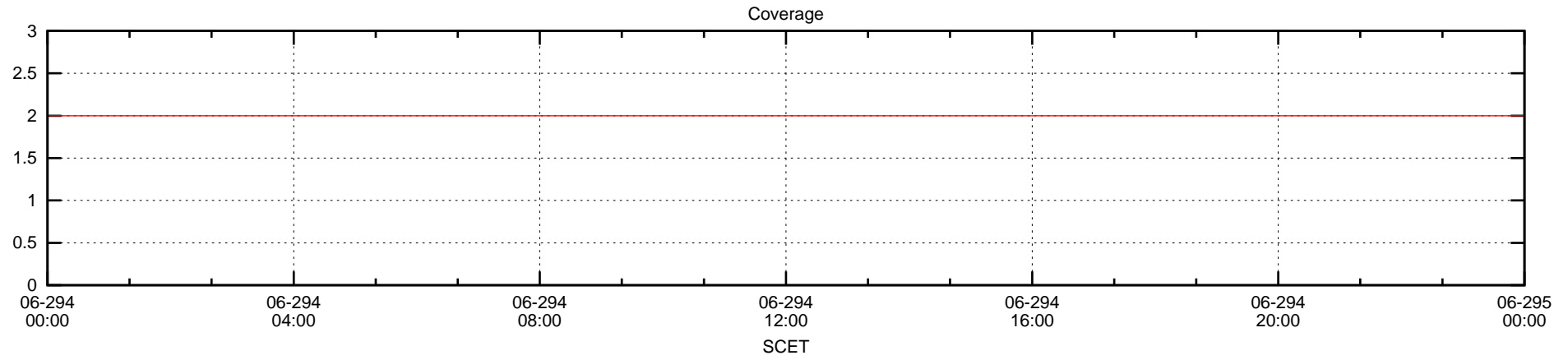
Y-Axis



Z-Axis

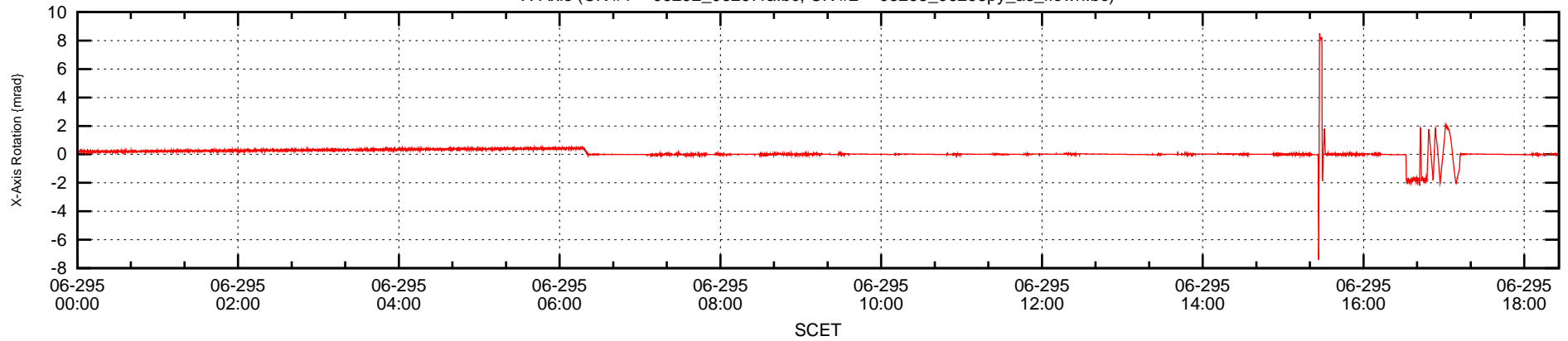


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 294-295)

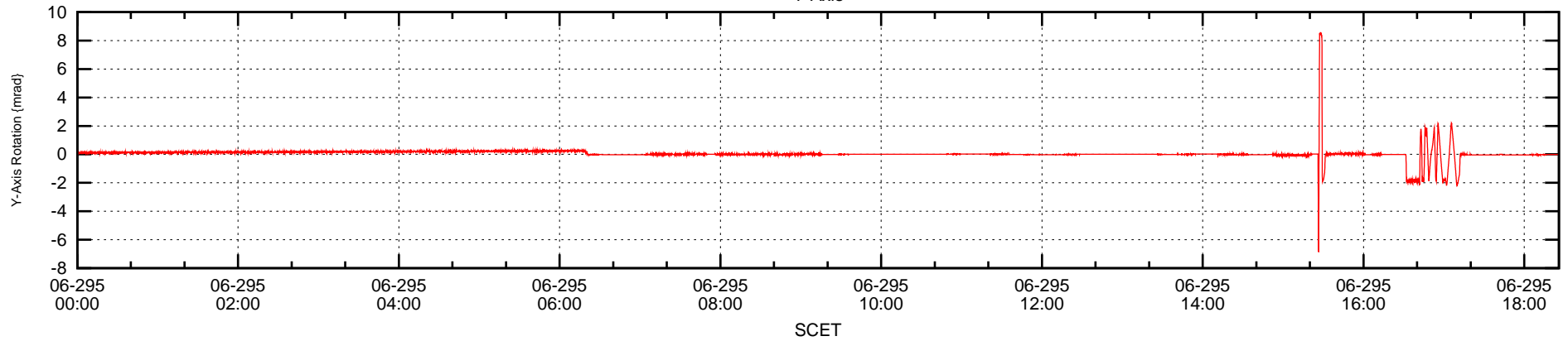


Rotation From CK #2 to CK #1 (DOY 295-295)

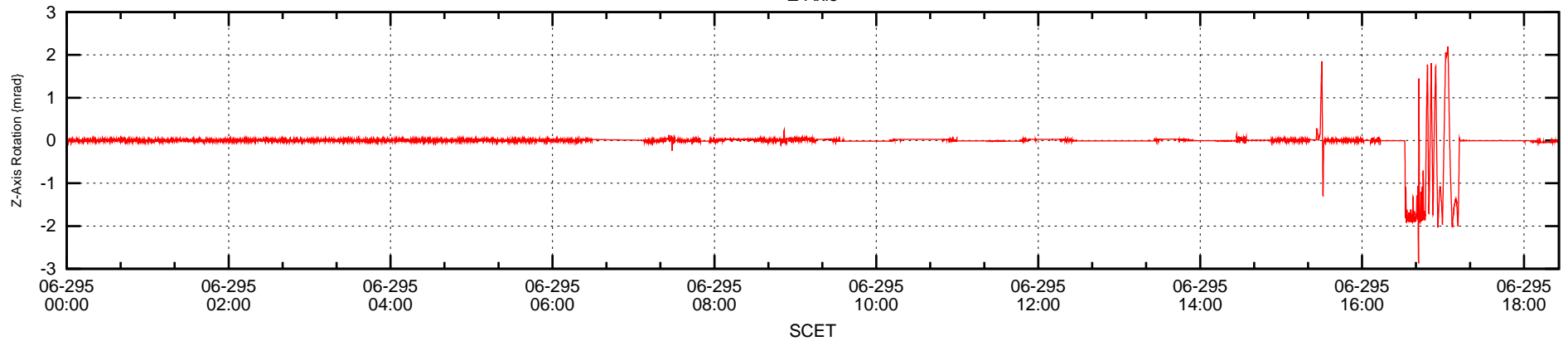
X-Axis (CK #1 = 06292_06297ra.bc; CK #2 = 06263_06295py_as_flowm.bc)



Y-Axis

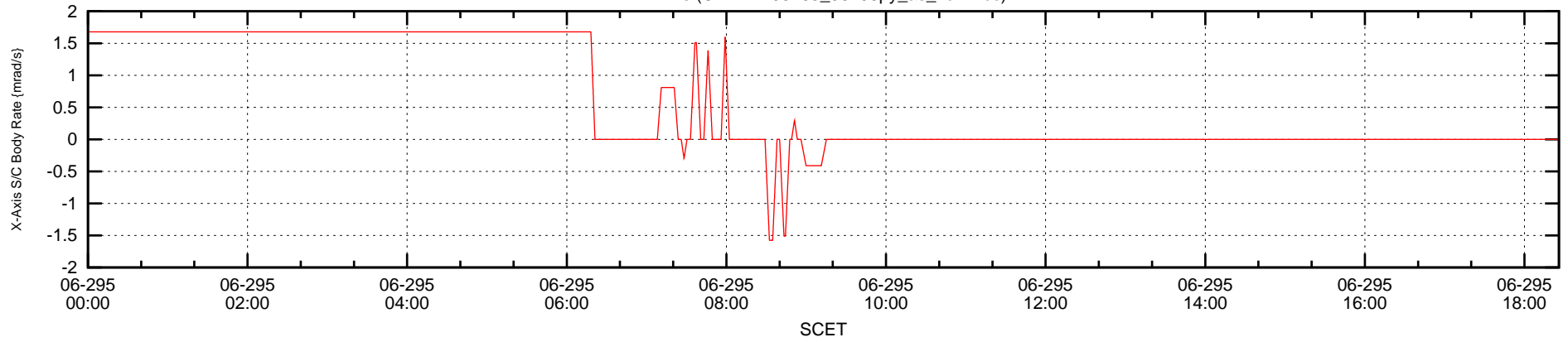


Z-Axis

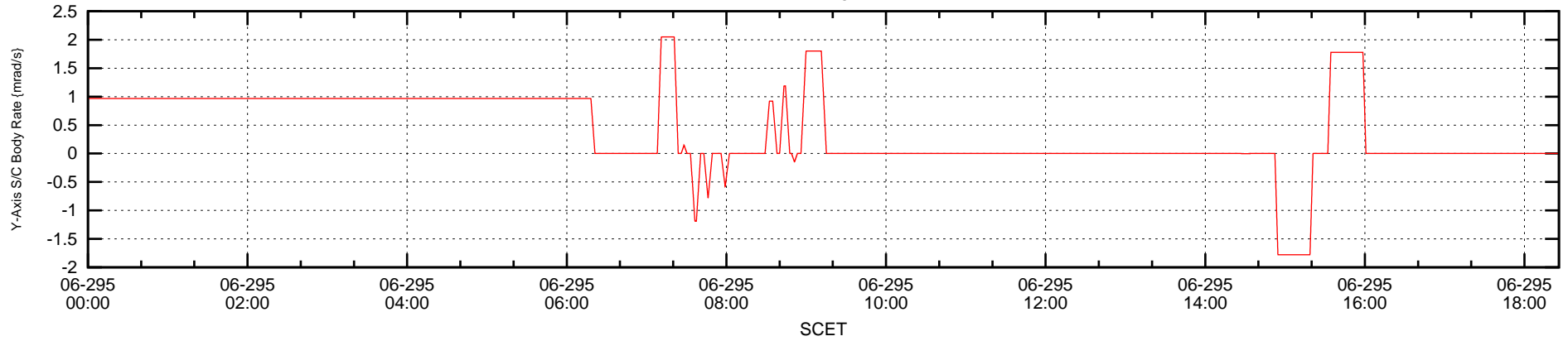


CK #2 S/C Body Rates (DOY 295-295)

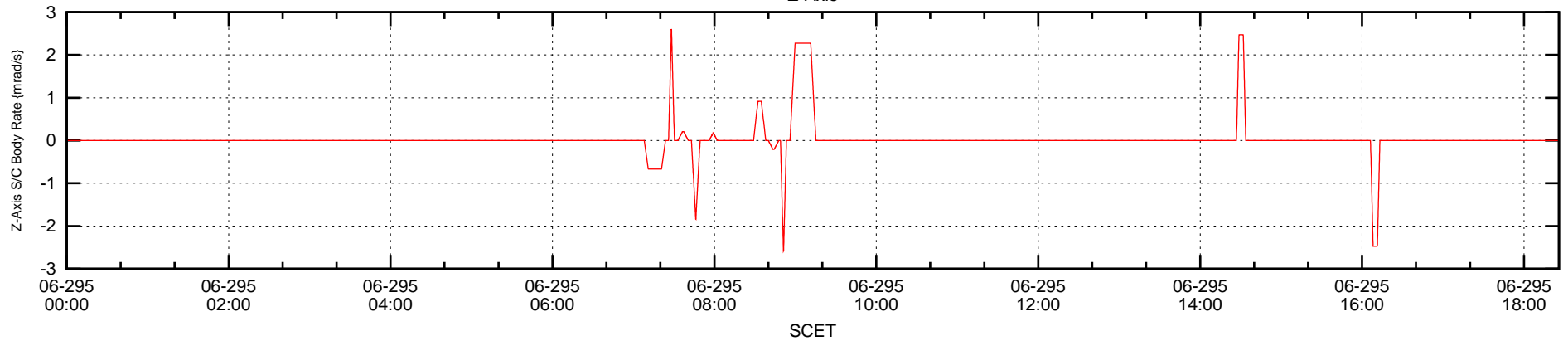
X-Axis (CK #2 = 06263_06295py_as_flowm.bc)



Y-Axis



Z-Axis



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 295-295)

