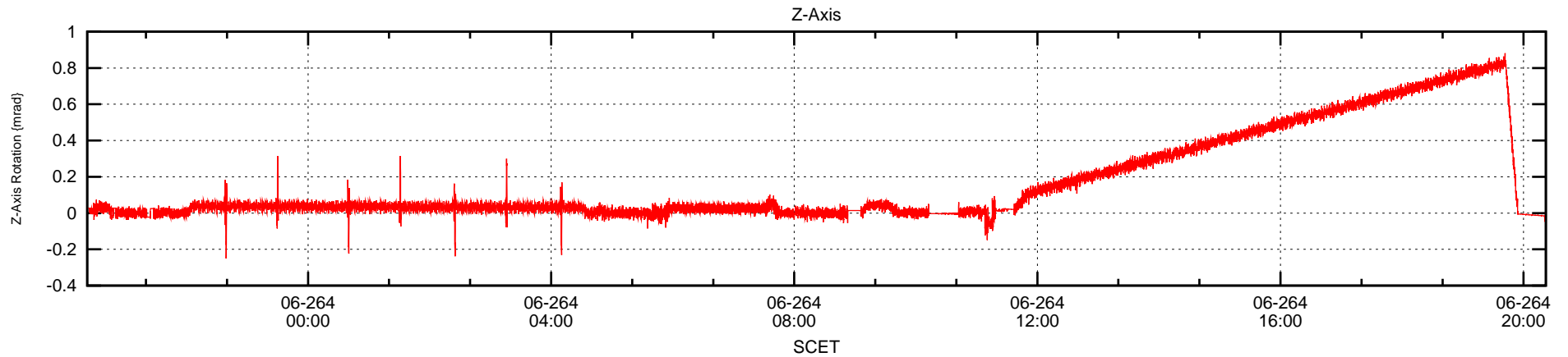
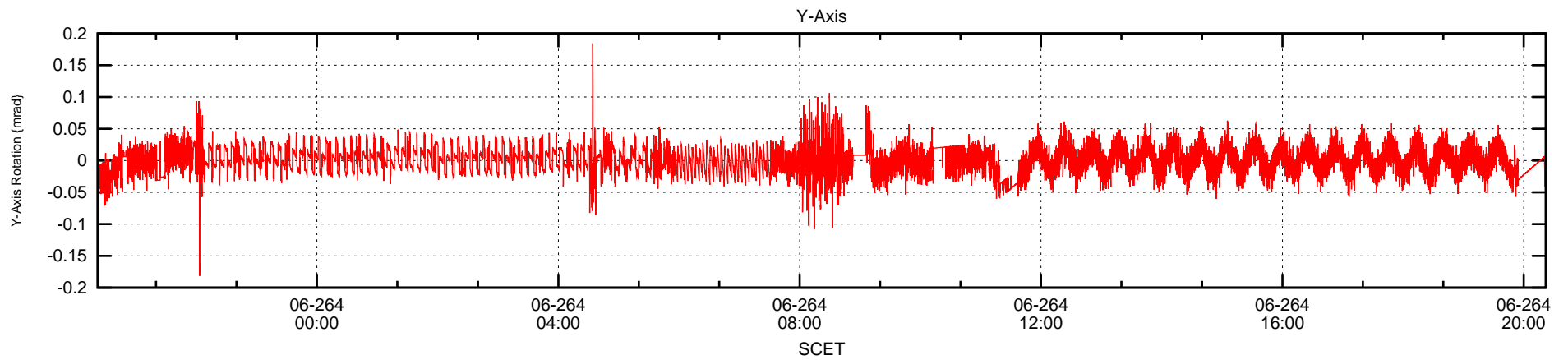
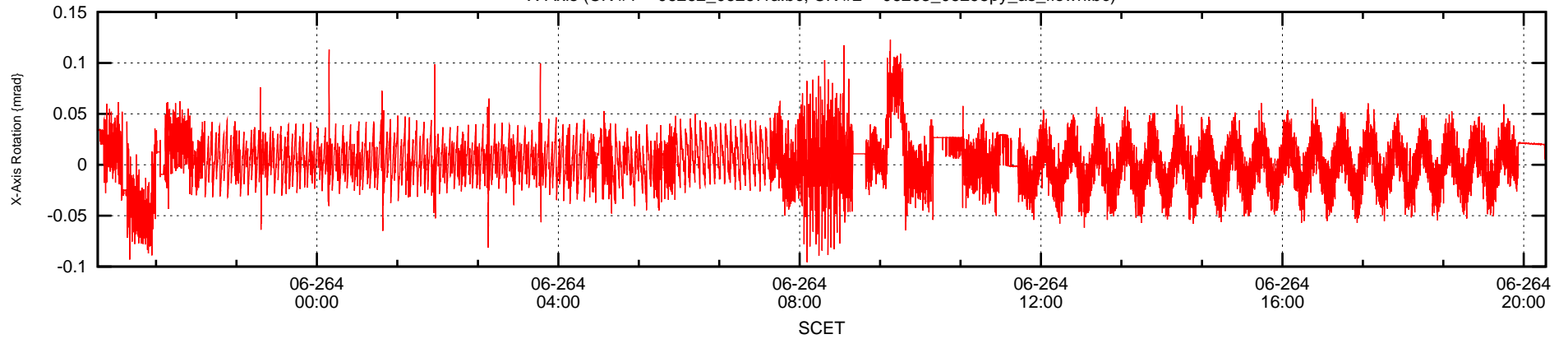


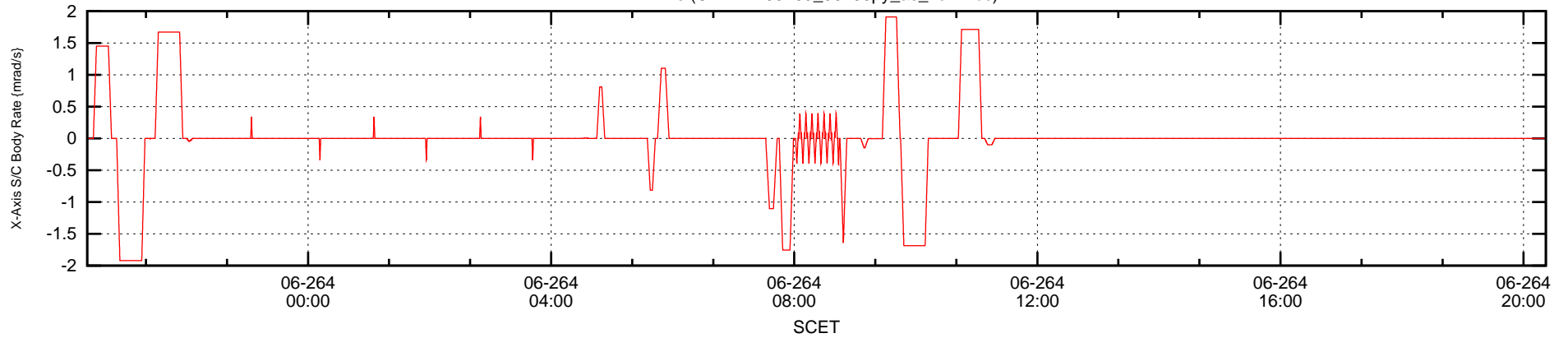
# Rotation From CK #2 to CK #1 (DOY 263-264)

X-Axis (CK #1 = 06262\_06267ra.bc; CK #2 = 06263\_06295py\_as\_flown.bc)

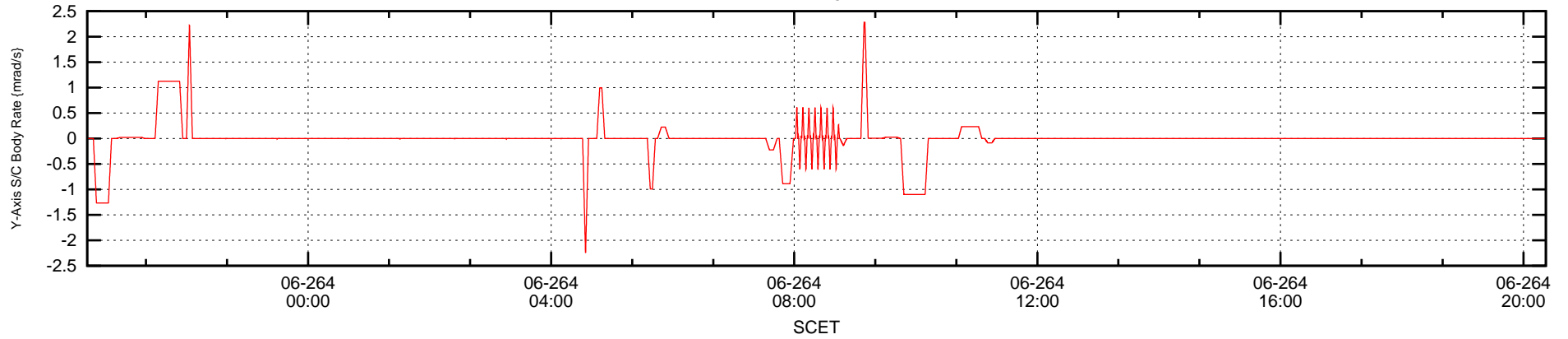


# CK #2 S/C Body Rates (DOY 263-264)

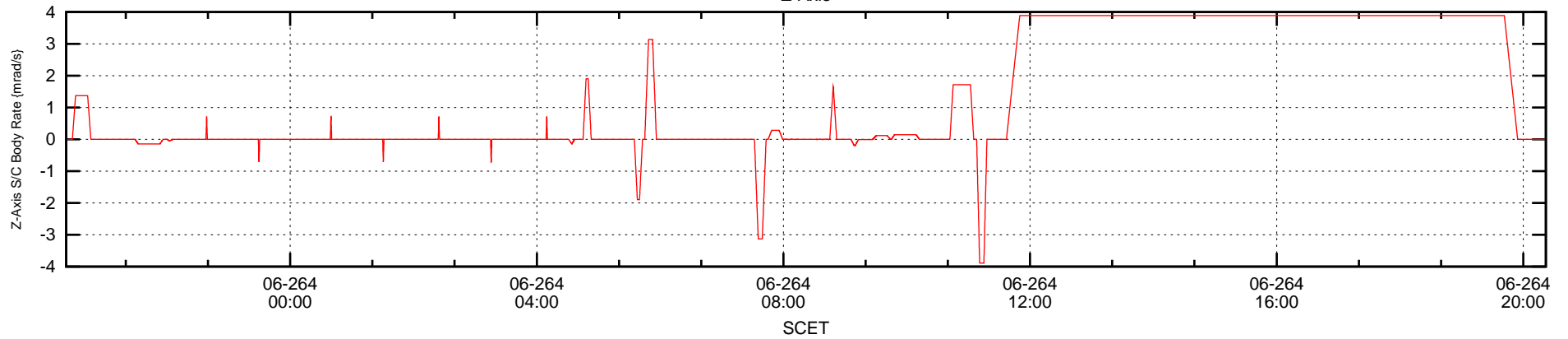
X-Axis (CK #2 = 06263\_06295py\_as\_flown.bc)



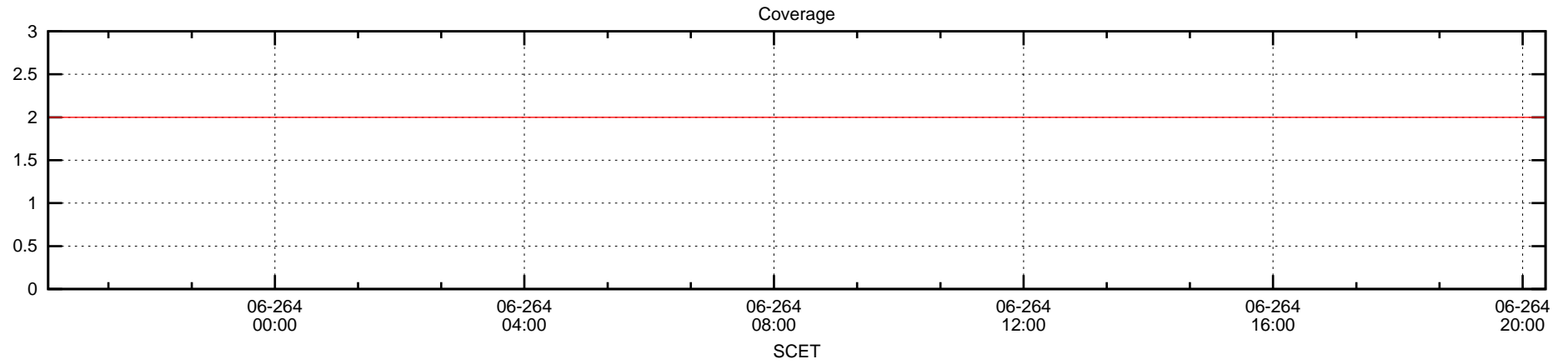
Y-Axis



Z-Axis

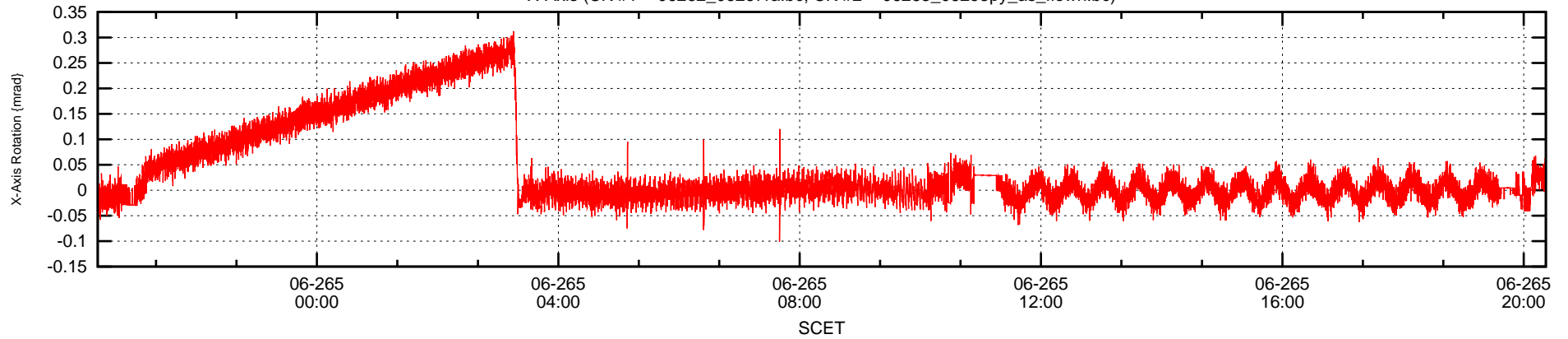


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 263-264)

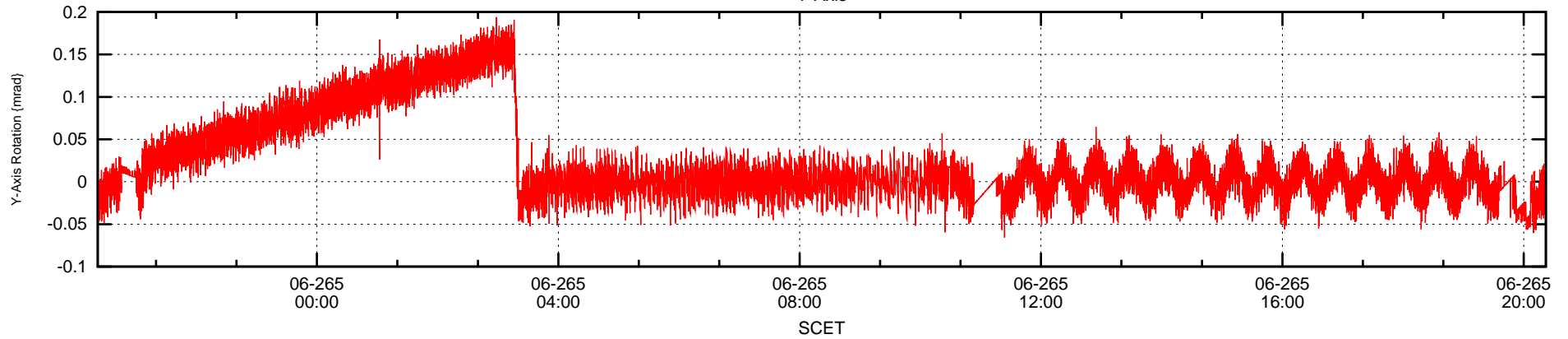


# Rotation From CK #2 to CK #1 (DOY 264-265)

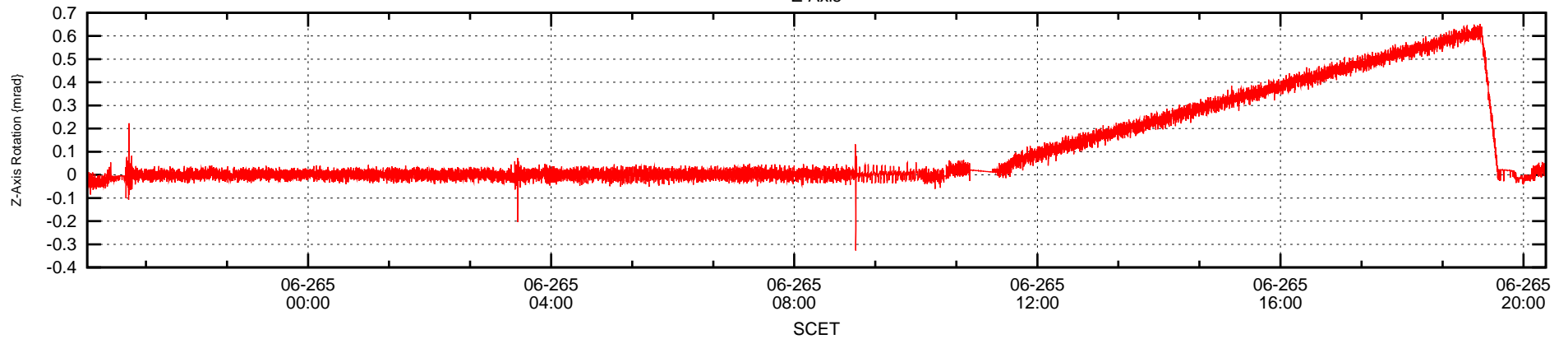
X-Axis (CK #1 = 06262\_06267ra.bc; CK #2 = 06263\_06295py\_as\_flown.bc)



Y-Axis

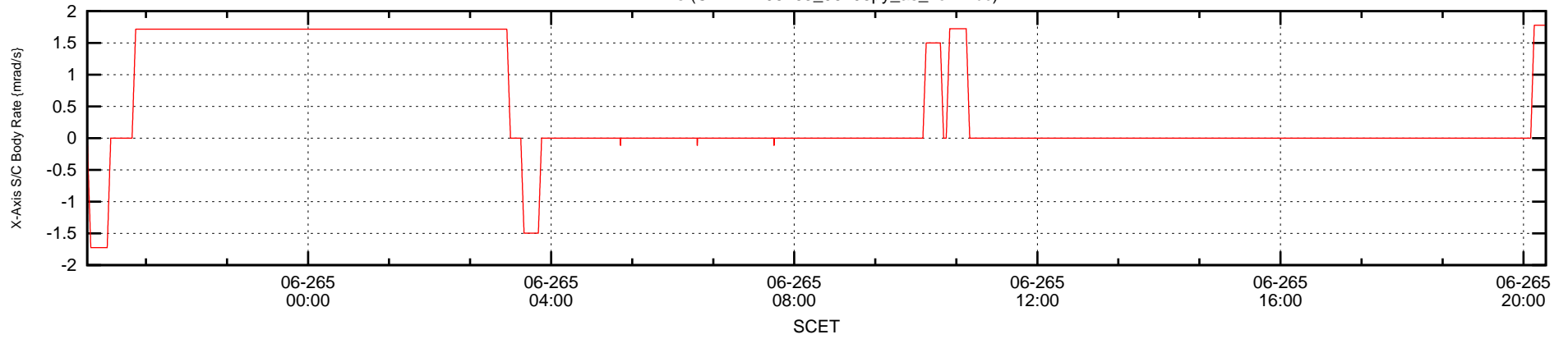


Z-Axis

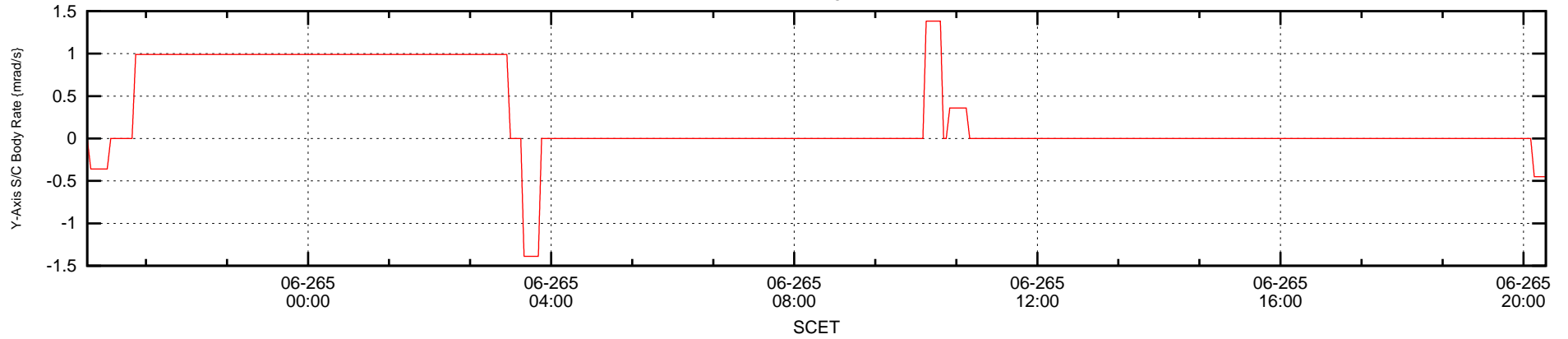


# CK #2 S/C Body Rates (DOY 264-265)

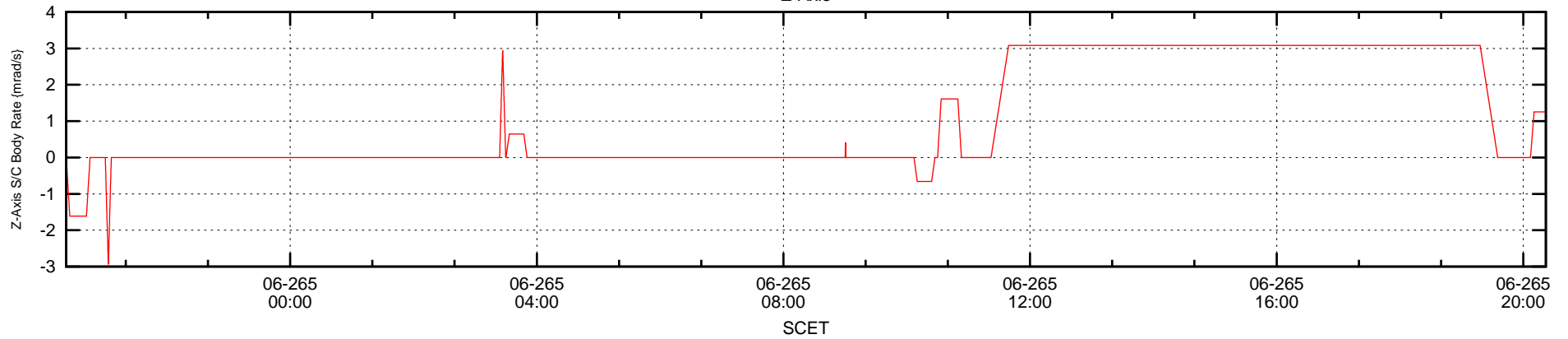
X-Axis (CK #2 = 06263\_06295py\_as\_flown.bc)



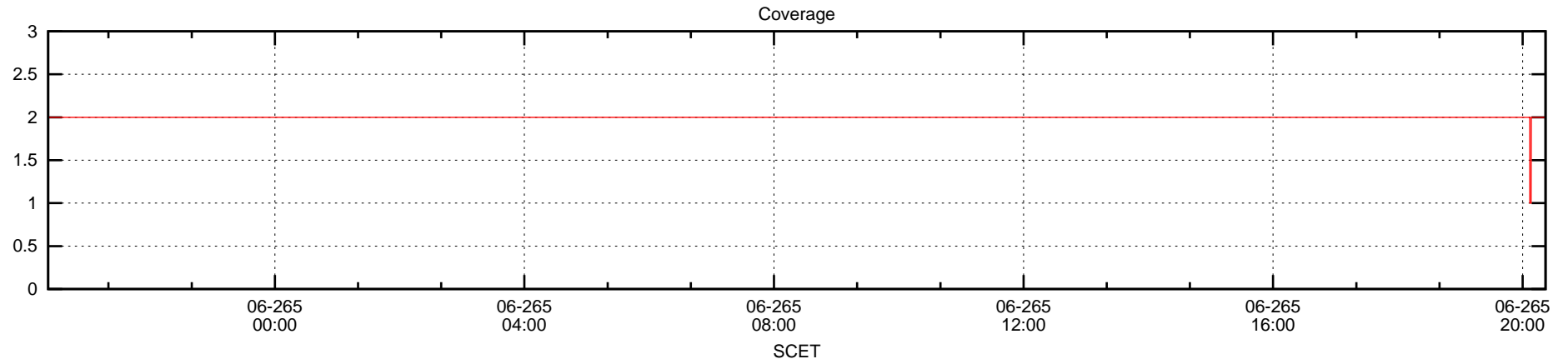
Y-Axis



Z-Axis

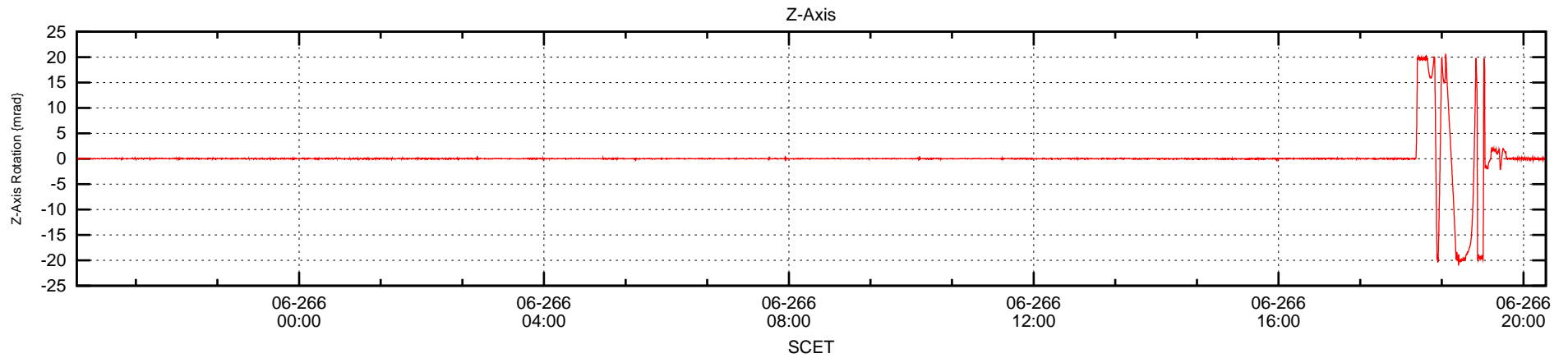
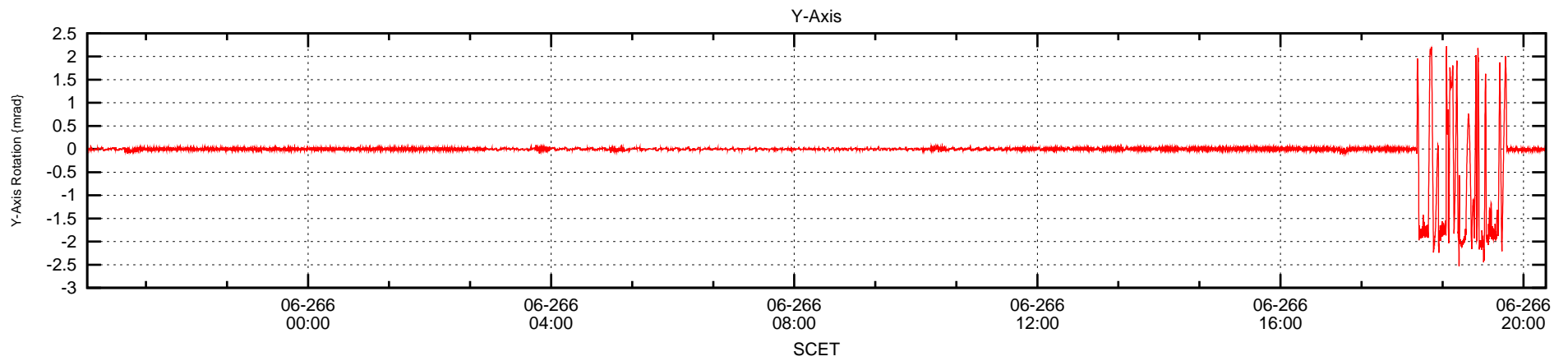
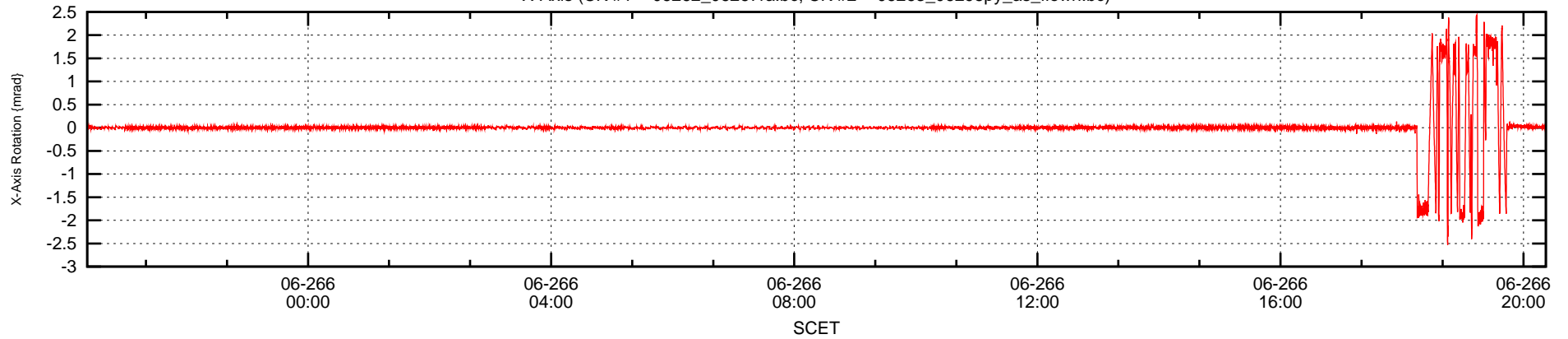


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 264-265)



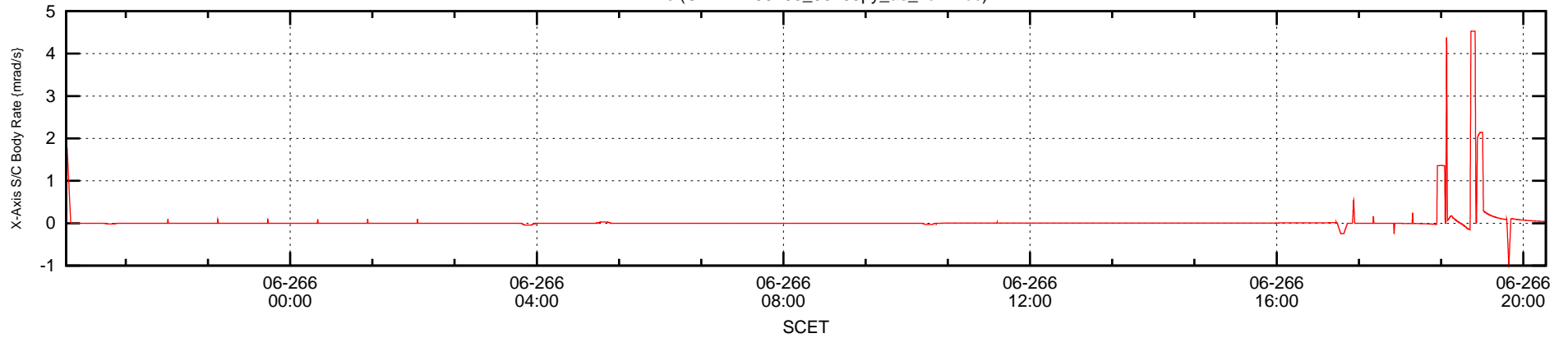
# Rotation From CK #2 to CK #1 (DOY 265-266)

X-Axis (CK #1 = 06262\_06267ra.bc; CK #2 = 06263\_06295py\_as\_flowm.bc)

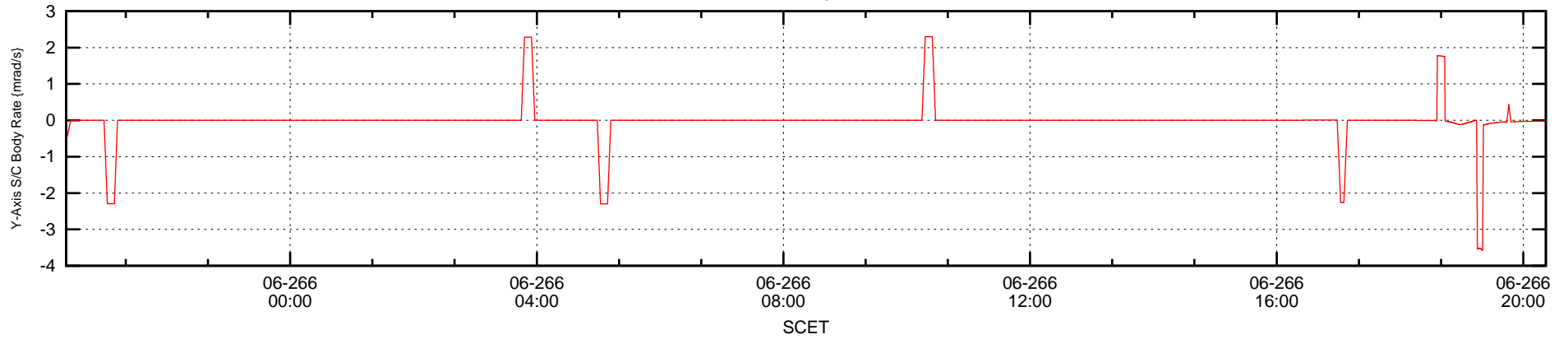


# CK #2 S/C Body Rates (DOY 265-266)

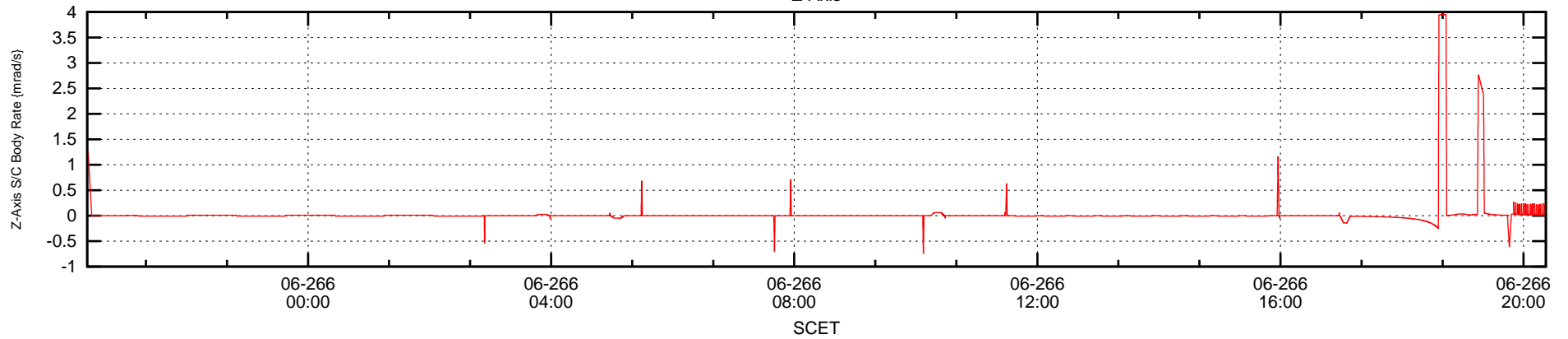
X-Axis (CK #2 = 06263\_06295py\_as\_flown.bc)



Y-Axis

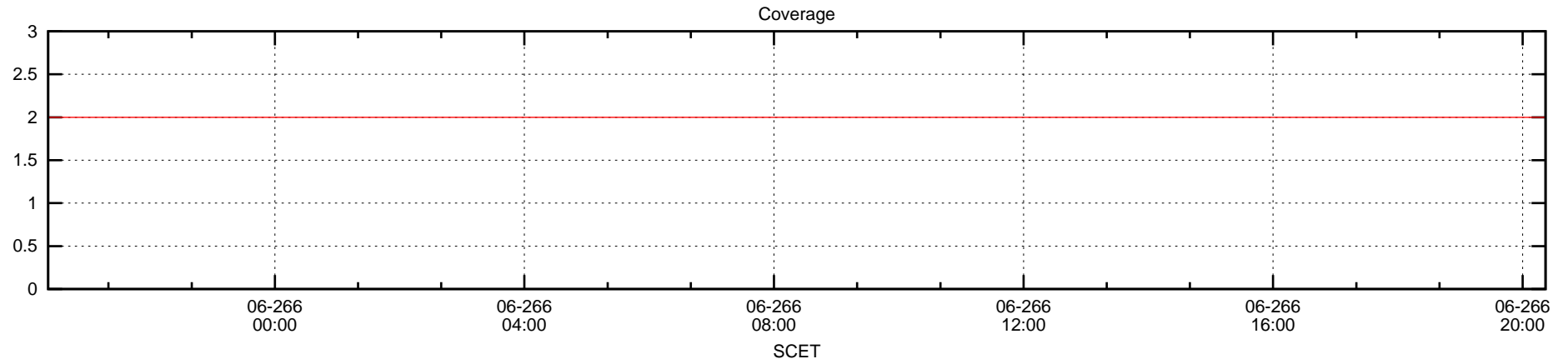


Z-Axis



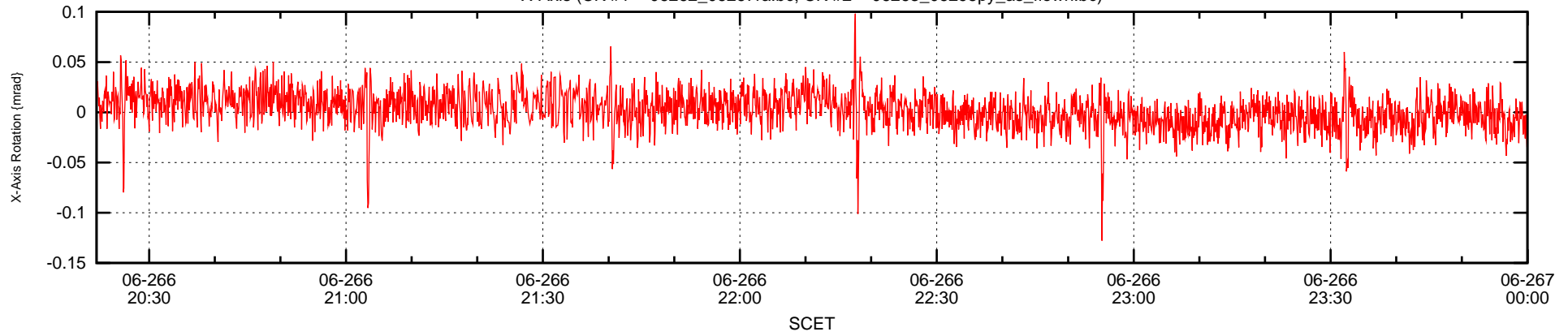


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 265-266)

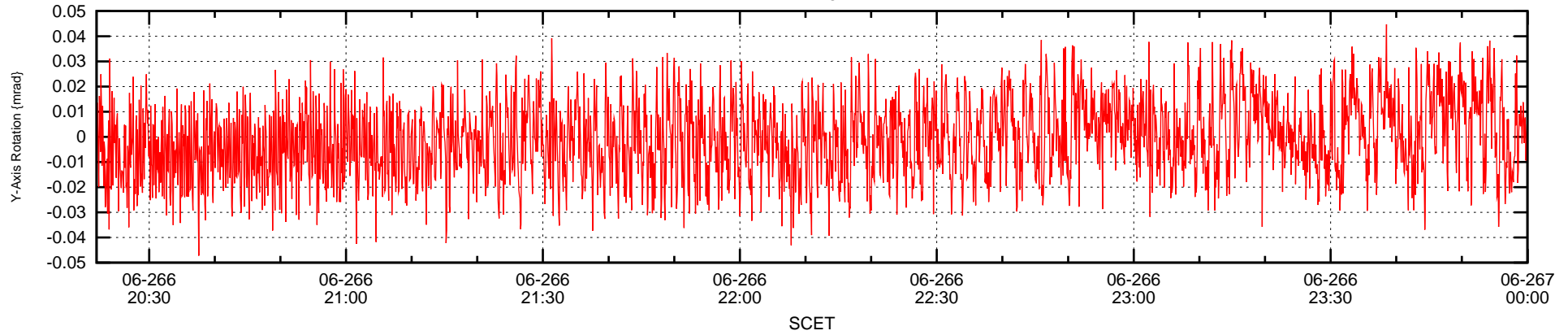


# Rotation From CK #2 to CK #1 (DOY 266-266)

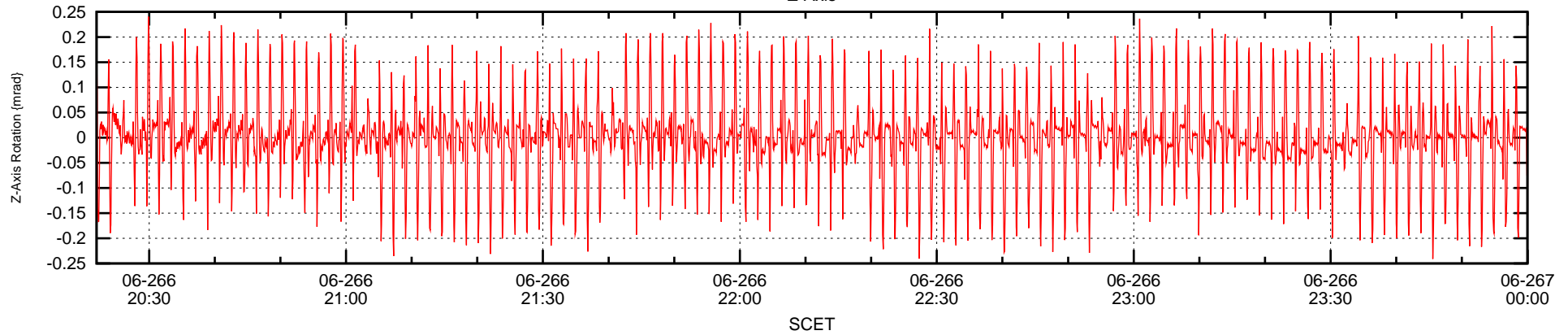
X-Axis (CK #1 = 06262\_06267ra.bc; CK #2 = 06263\_06295py\_as\_flowm.bc)



Y-Axis

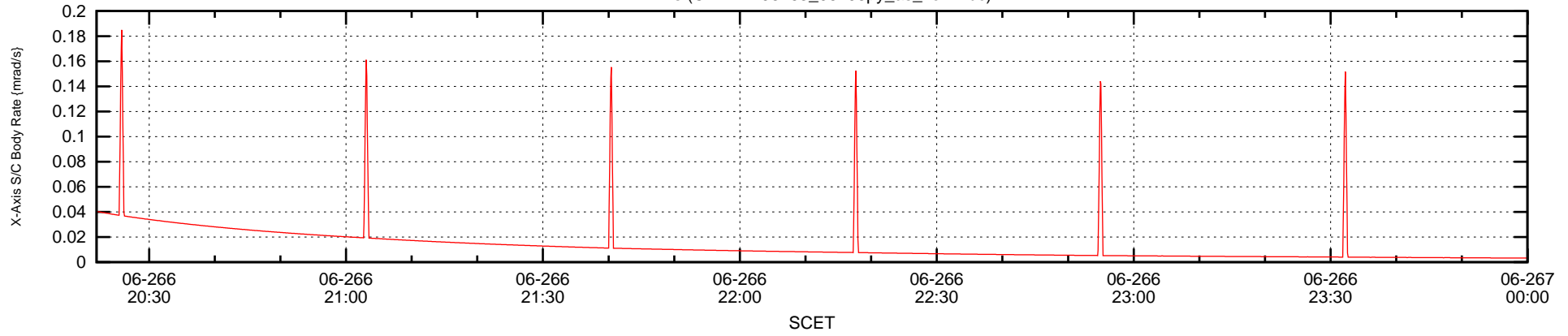


Z-Axis

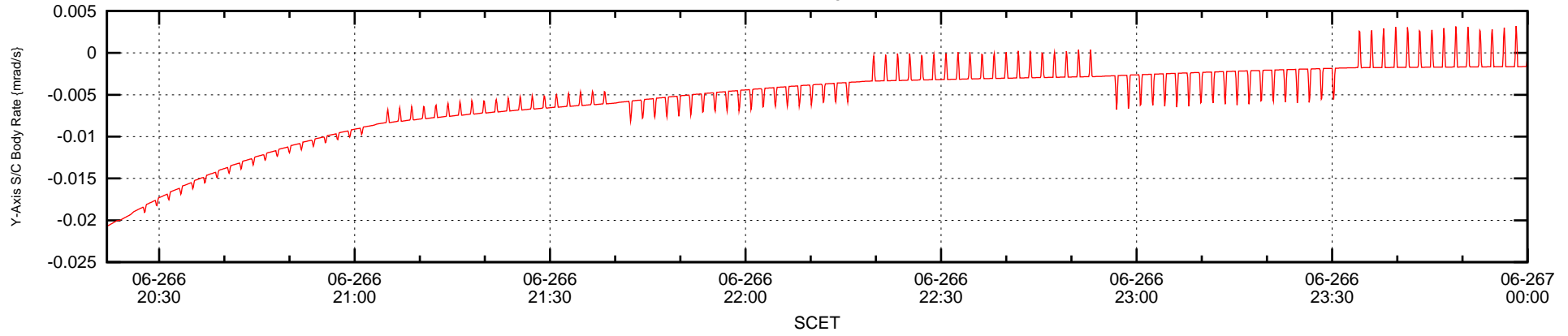


# CK #2 S/C Body Rates (DOY 266-266)

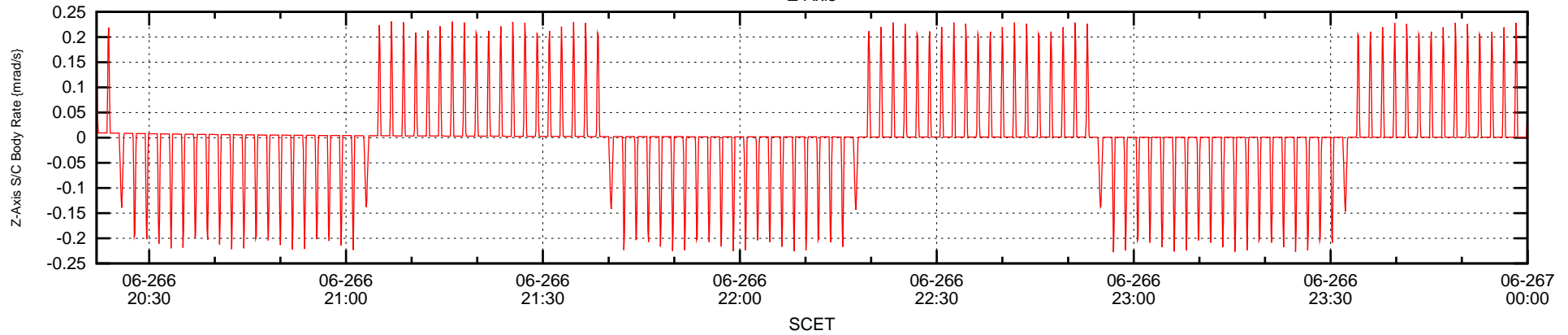
X-Axis (CK #2 = 06263\_06295py\_as\_flown.bc)



Y-Axis



Z-Axis



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 266-266)

