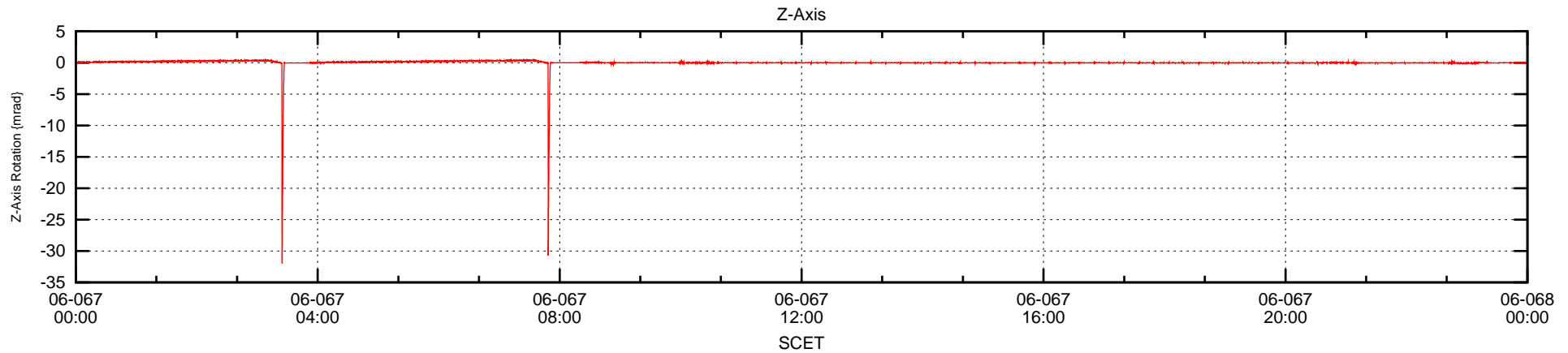
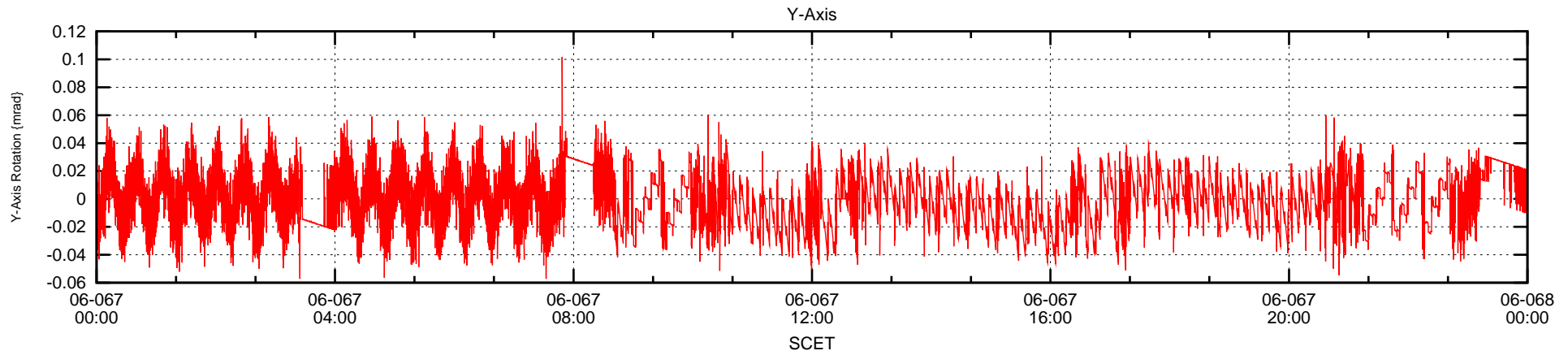
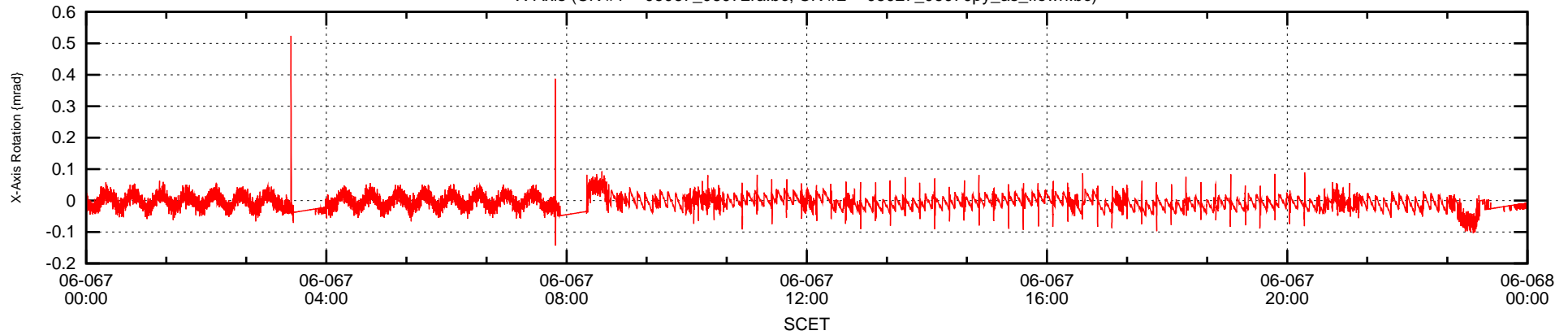


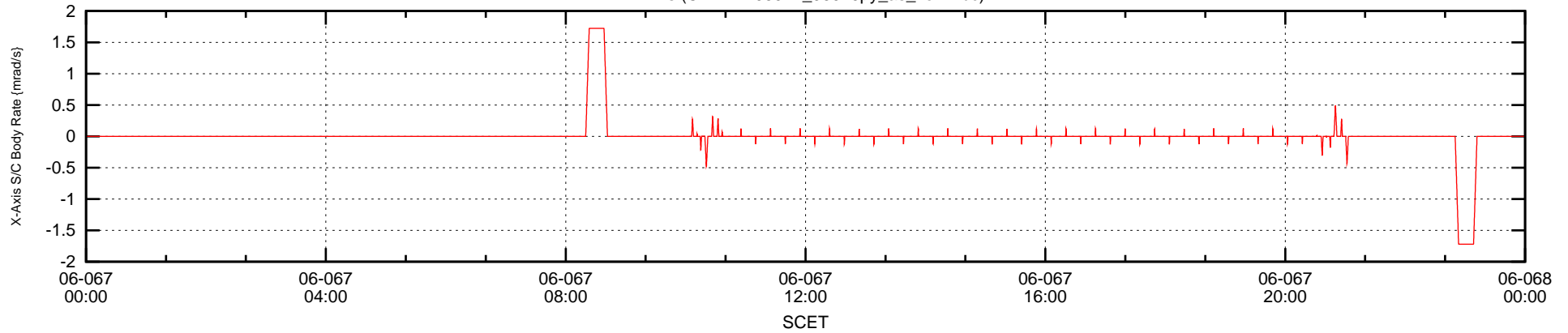
Rotation From CK #2 to CK #1 (DOY 067-068)

X-Axis (CK #1 = 06067_06072ra.bc; CK #2 = 06027_06070py_as_flown.bc)

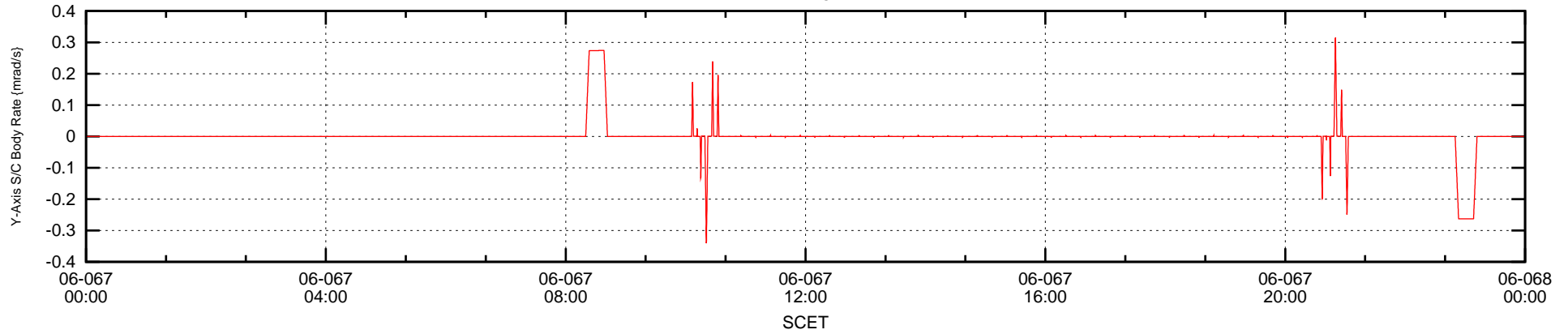


CK #2 S/C Body Rates (DOY 067-068)

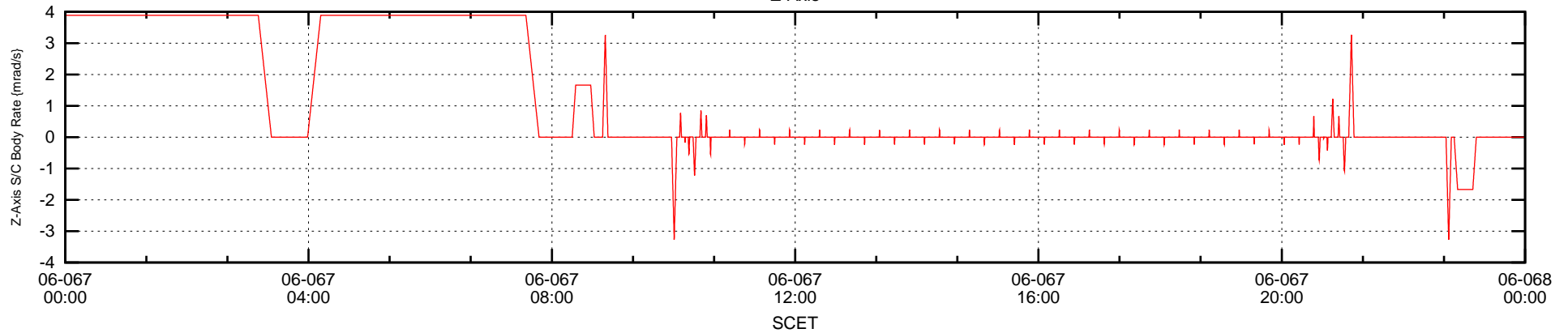
X-Axis (CK #2 = 06027_06070py_as_flown.bc)



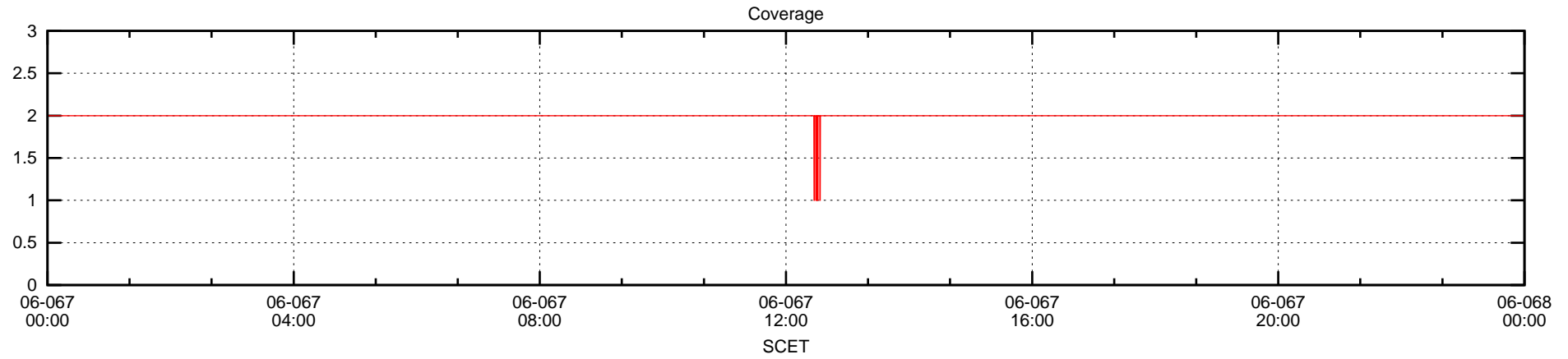
Y-Axis



Z-Axis

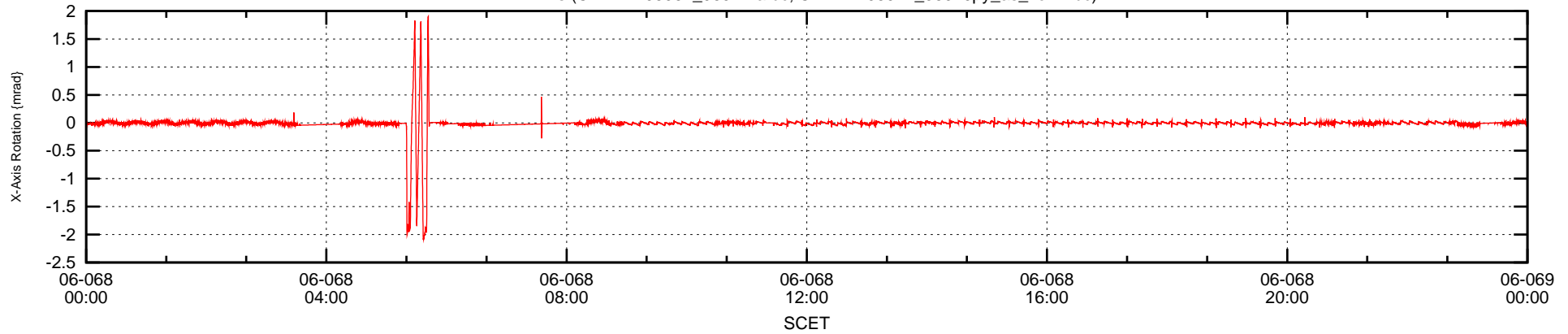


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 067-068)

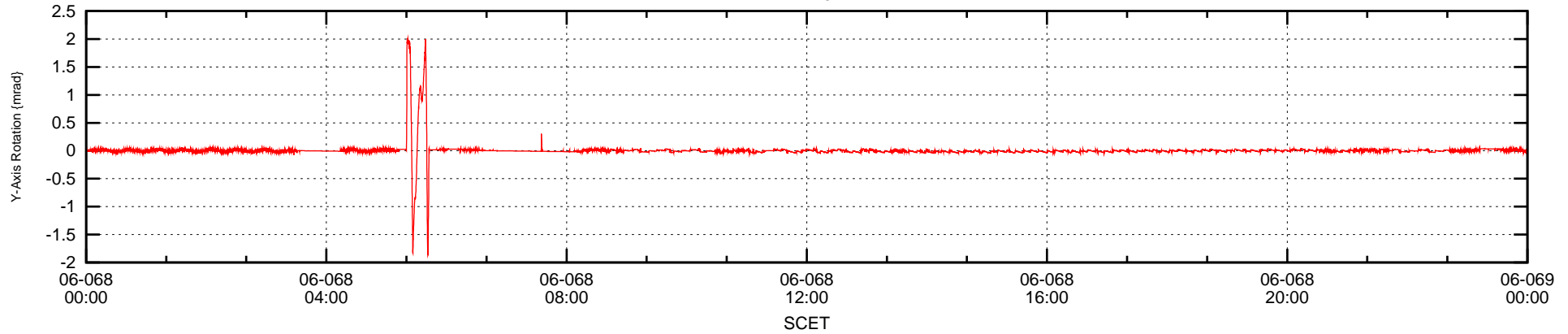


Rotation From CK #2 to CK #1 (DOY 068-069)

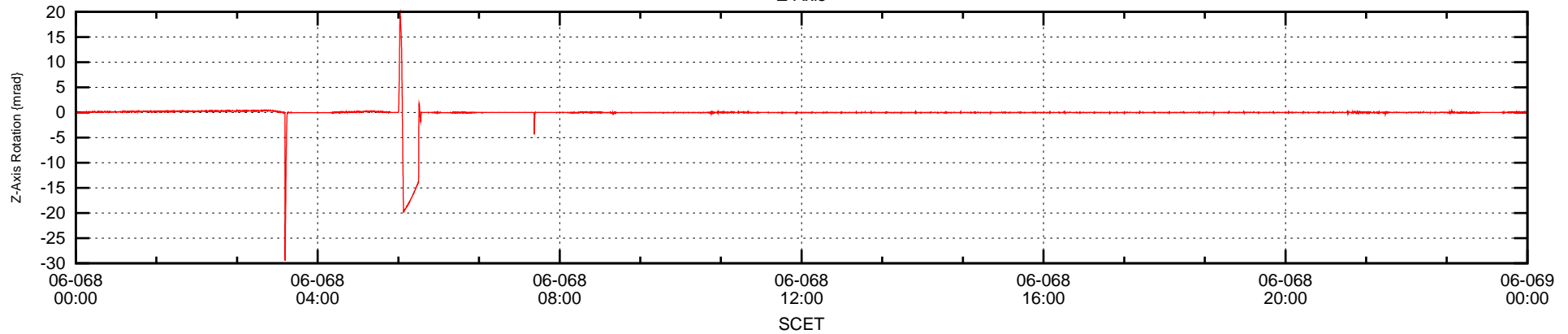
X-Axis (CK #1 = 06067_06072ra.bc; CK #2 = 06027_06070py_as_flown.bc)



Y-Axis

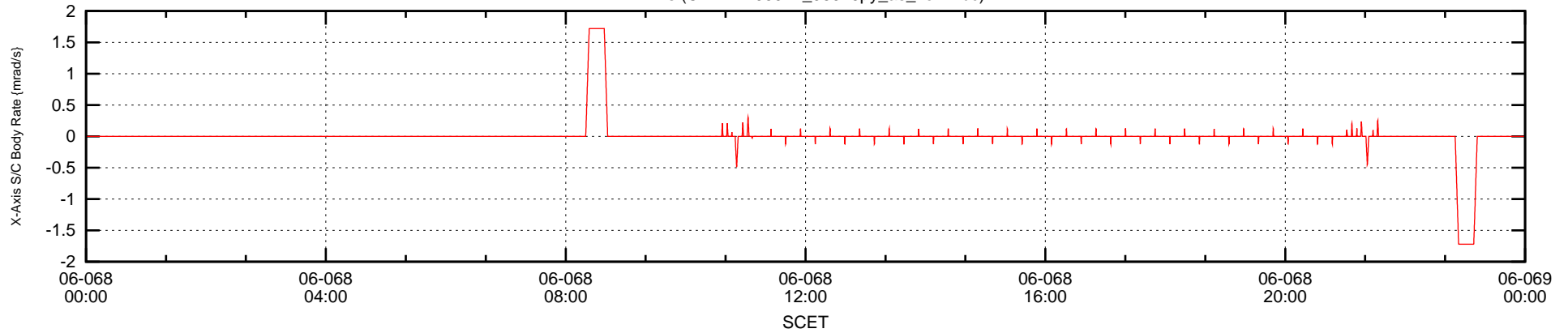


Z-Axis

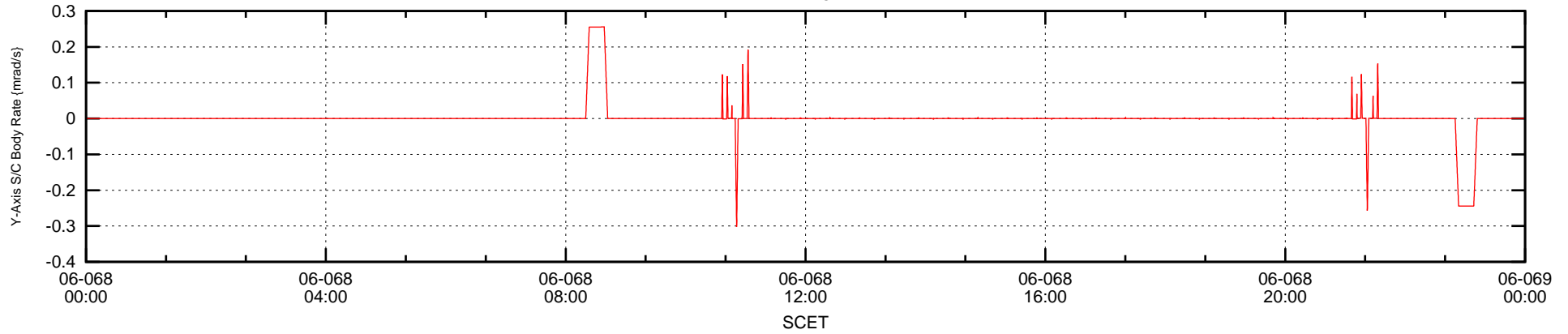


CK #2 S/C Body Rates (DOY 068-069)

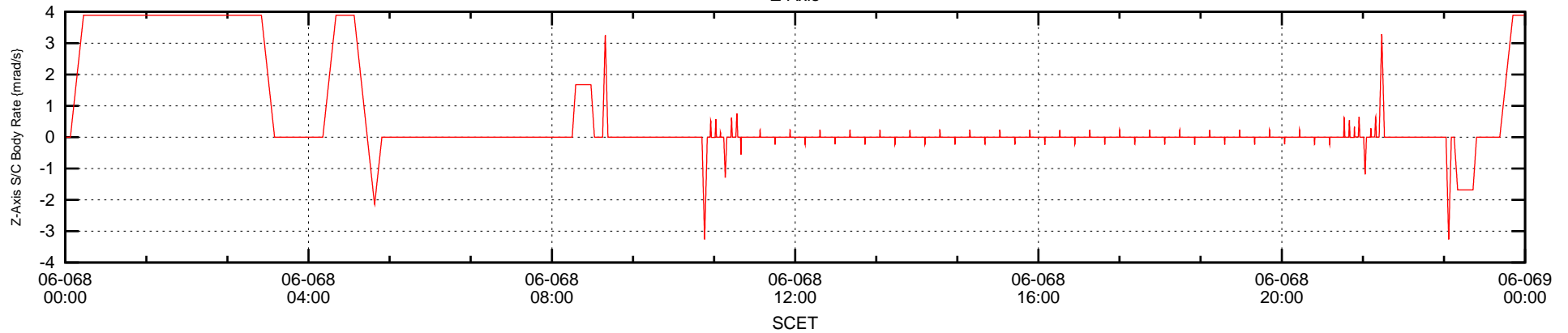
X-Axis (CK #2 = 06027_06070py_as_flown.bc)



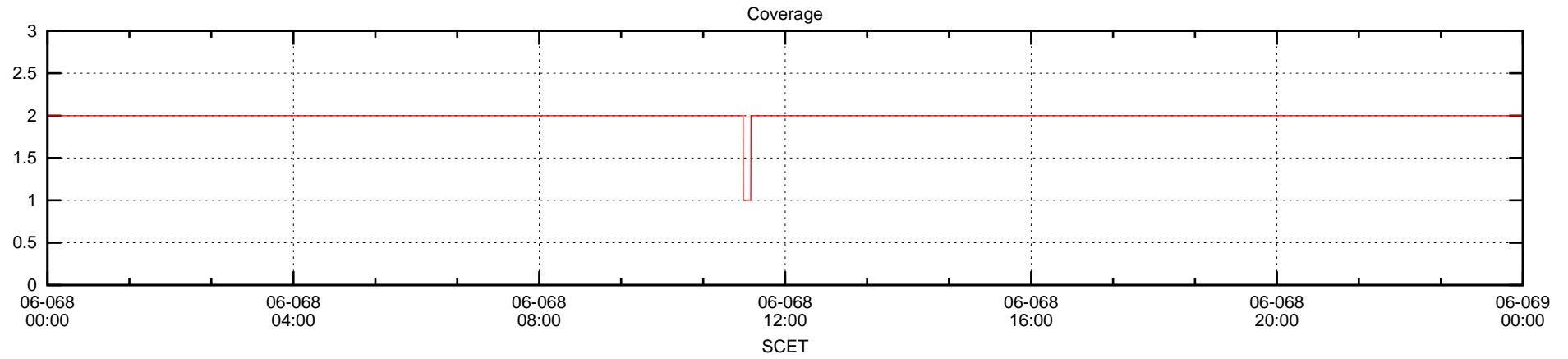
Y-Axis



Z-Axis

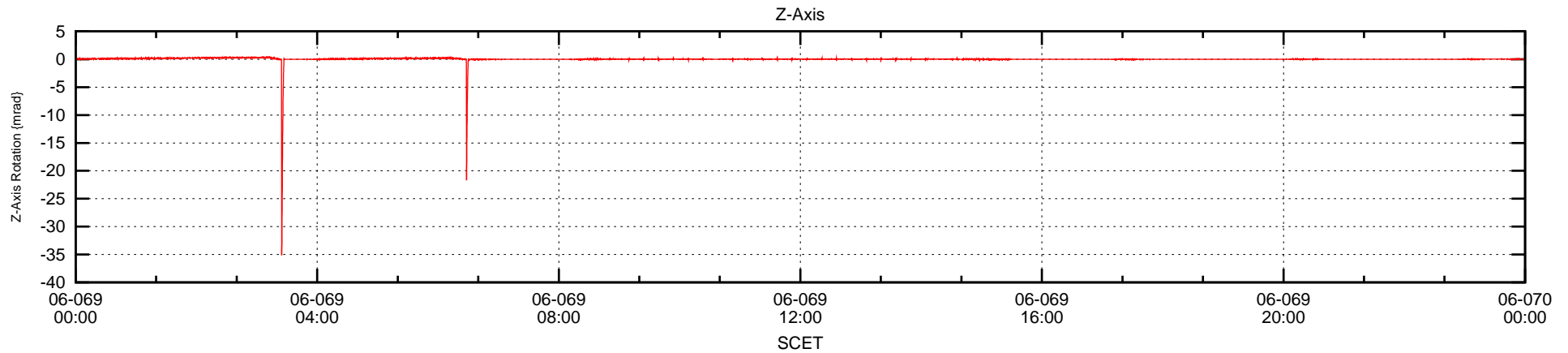
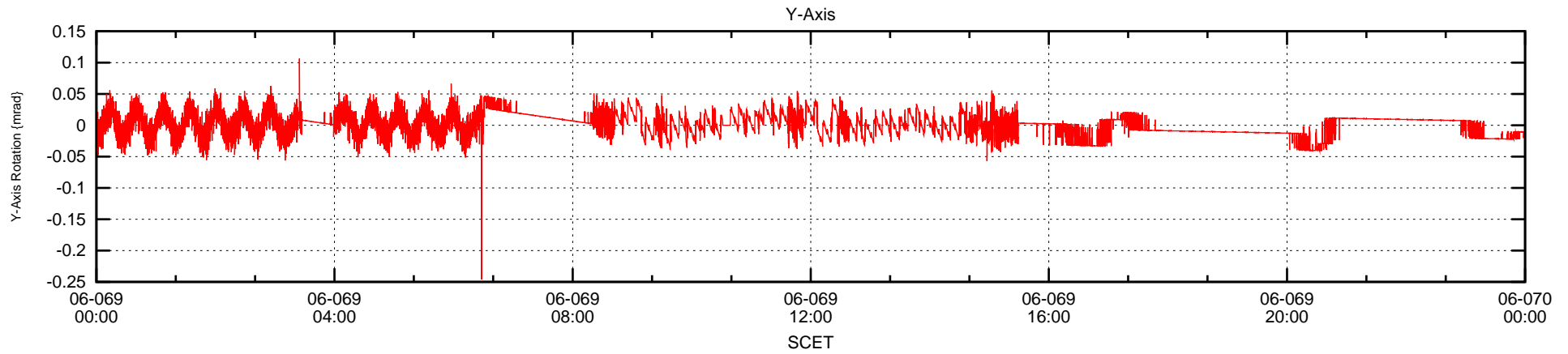
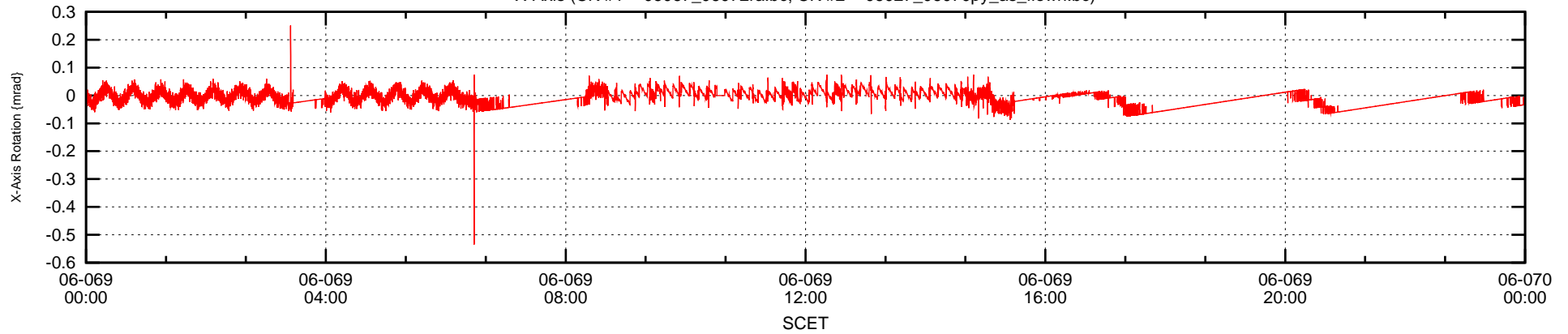


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 068-069)



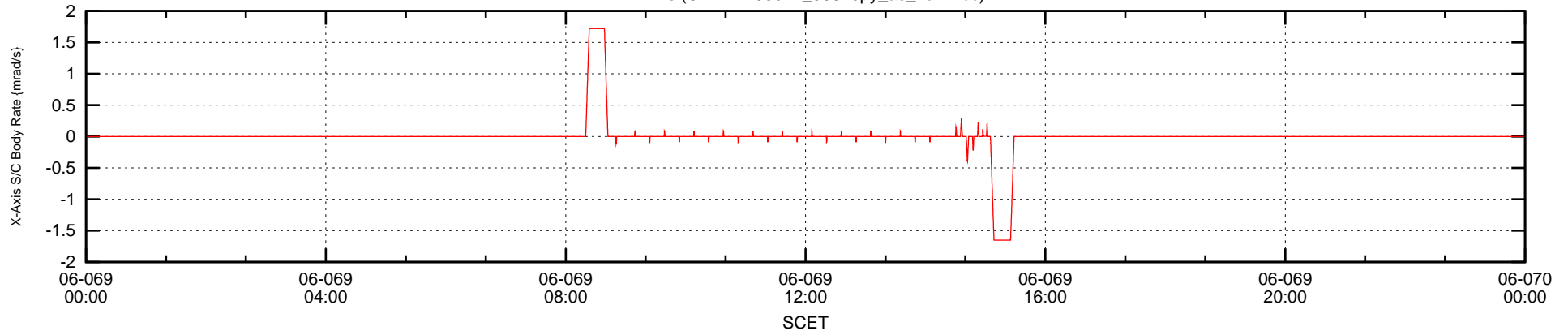
Rotation From CK #2 to CK #1 (DOY 069-070)

X-Axis (CK #1 = 06067_06072ra.bc; CK #2 = 06027_06070py_as_flown.bc)

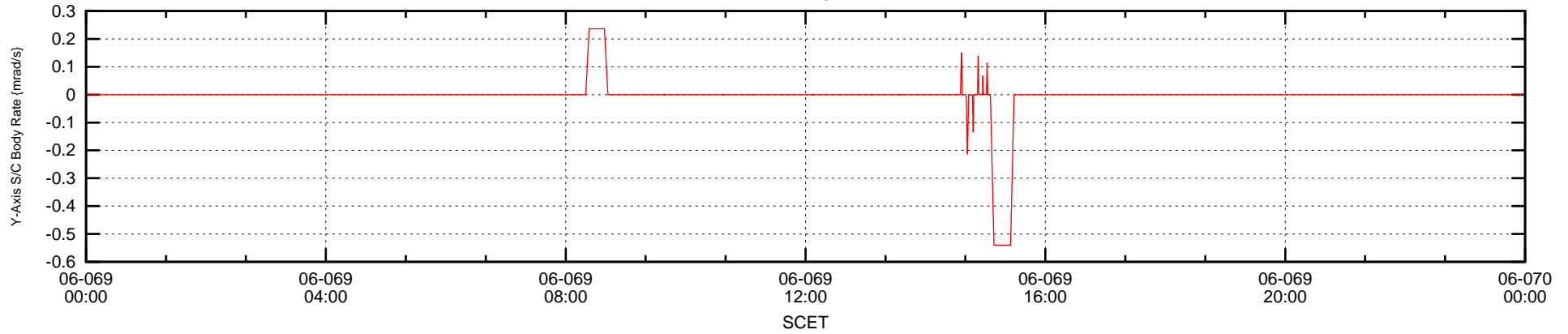


CK #2 S/C Body Rates (DOY 069-070)

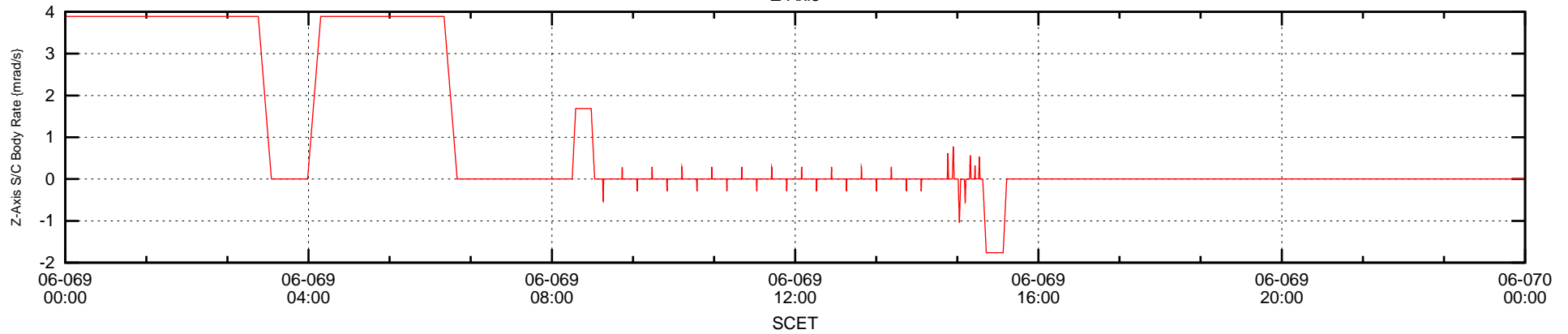
X-Axis (CK #2 = 06027_06070py_as_flown.bc)



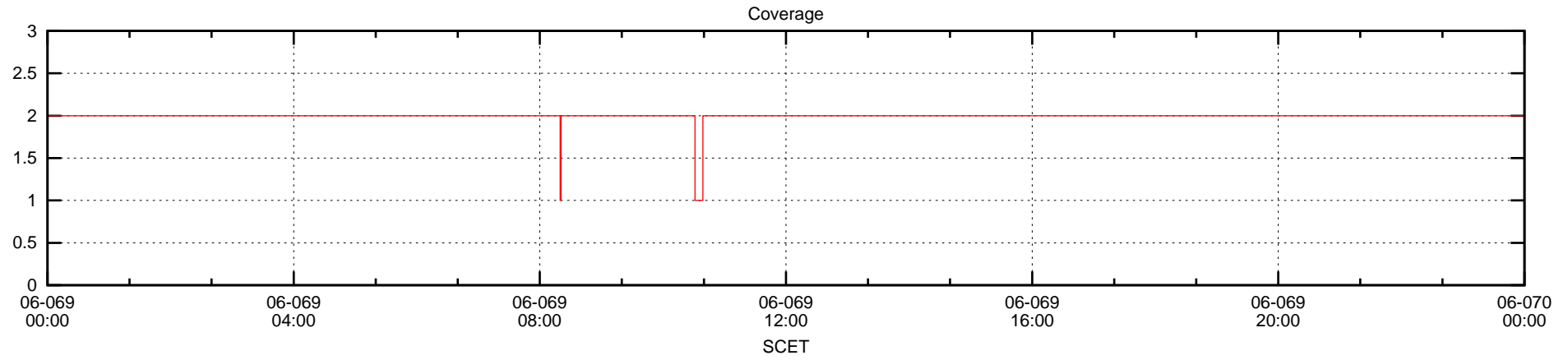
Y-Axis



Z-Axis

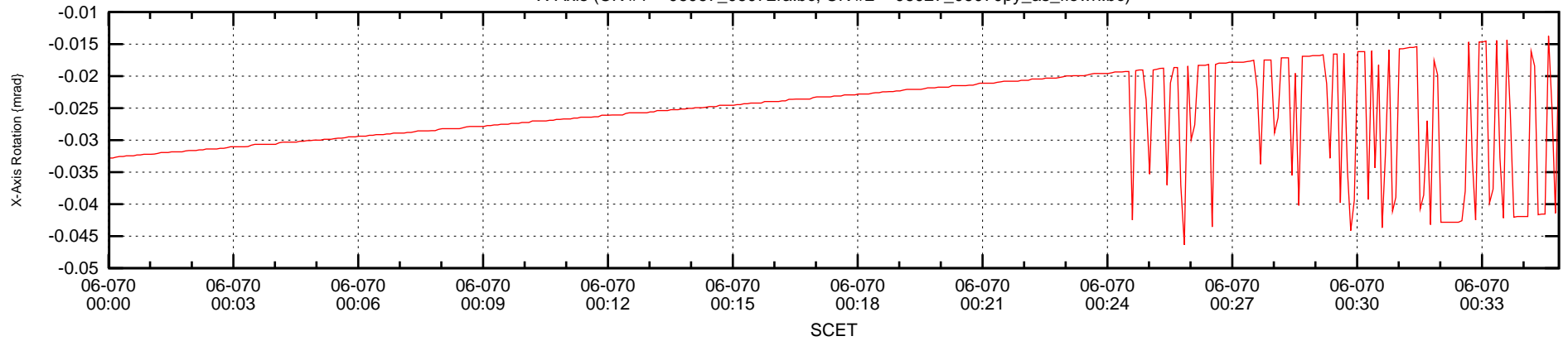


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 069-070)

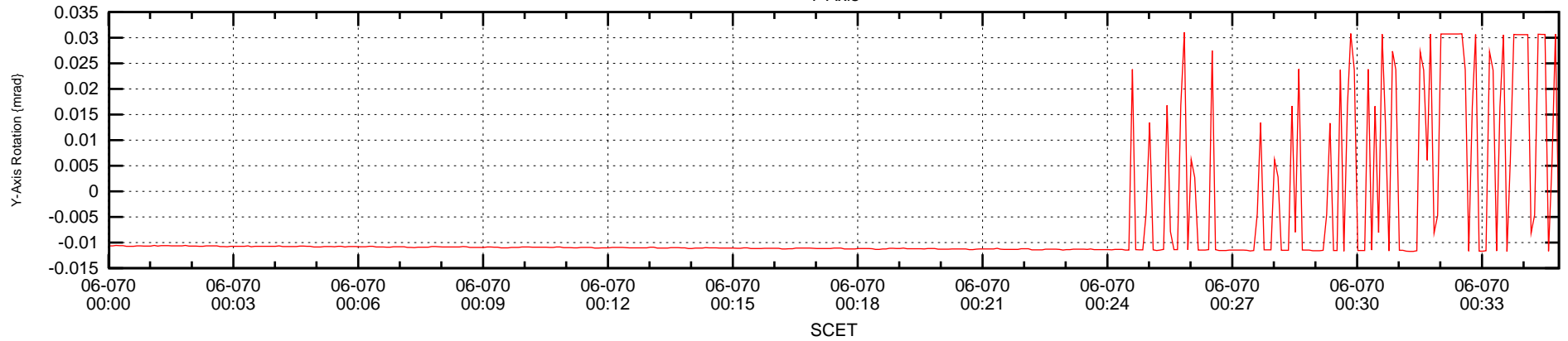


Rotation From CK #2 to CK #1 (DOY 070-070)

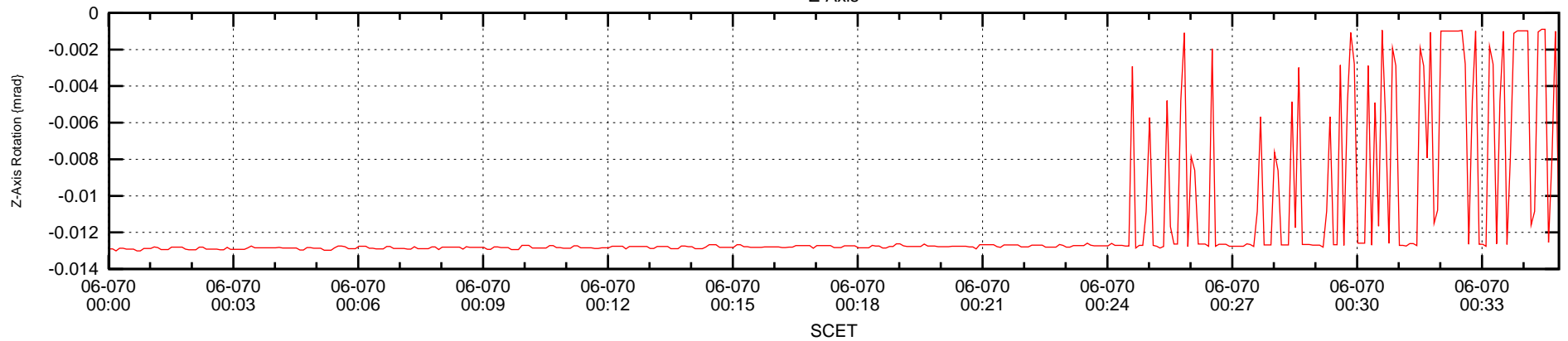
X-Axis (CK #1 = 06067_06072ra.bc; CK #2 = 06027_06070py_as_flowm.bc)



Y-Axis

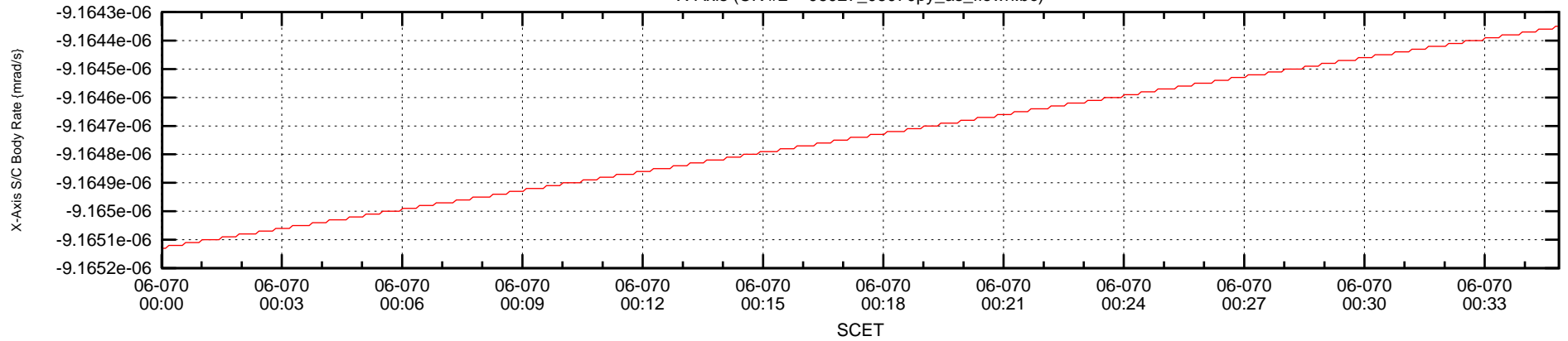


Z-Axis

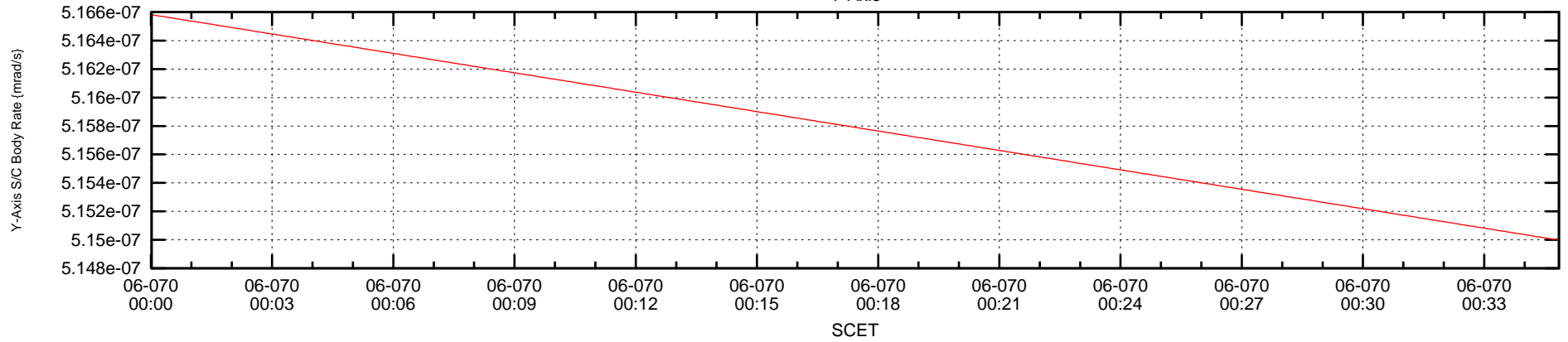


CK #2 S/C Body Rates (DOY 070-070)

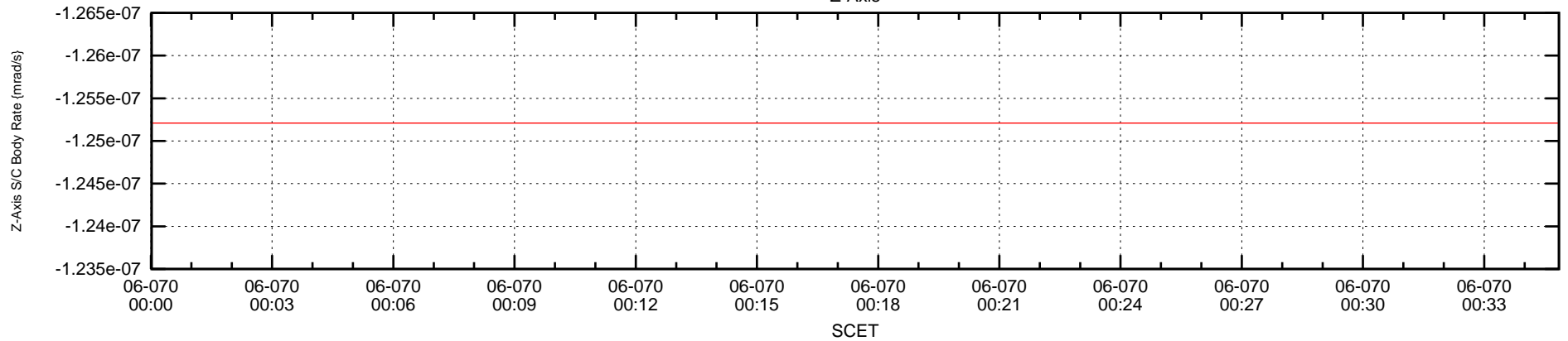
X-Axis (CK #2 = 06027_06070py_as_flowm.bc)



Y-Axis



Z-Axis



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 070-070)

