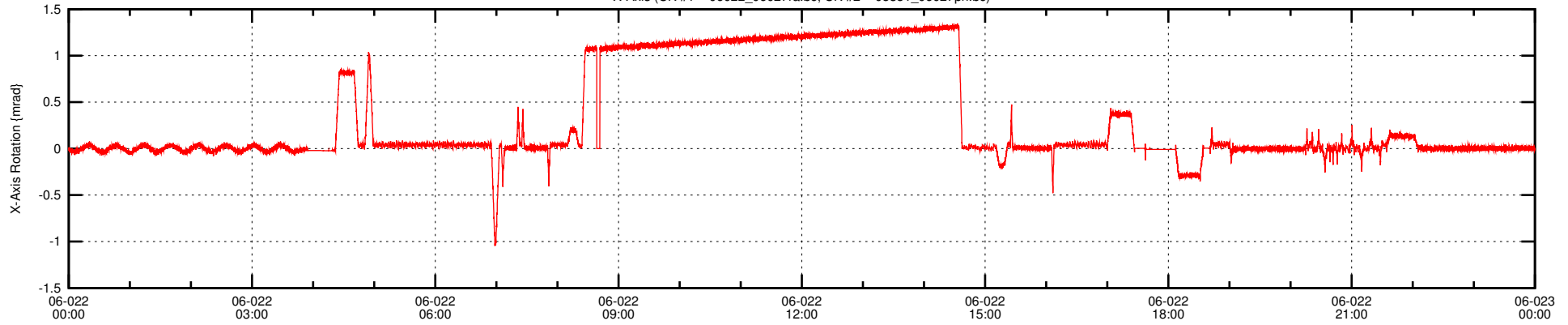
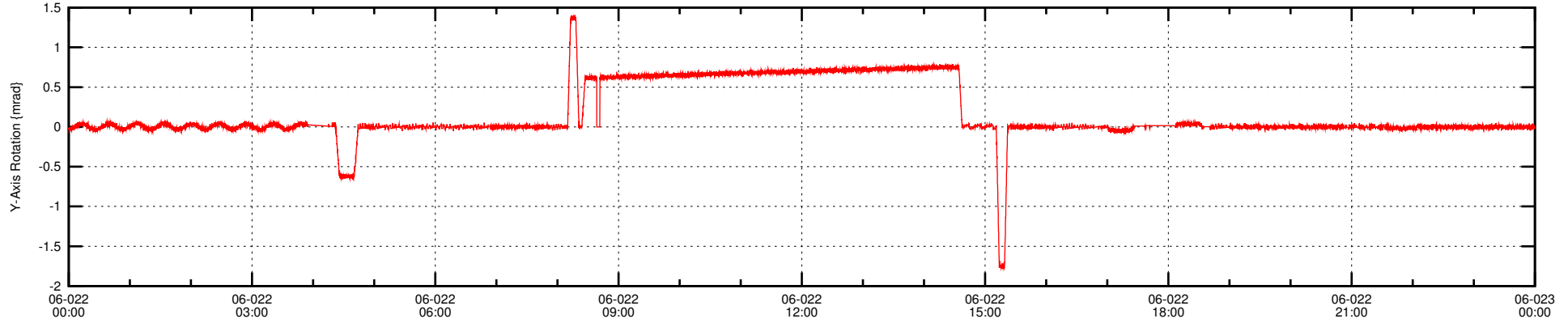


# Rotation From CK #2 to CK #1 (DOY 022-023)

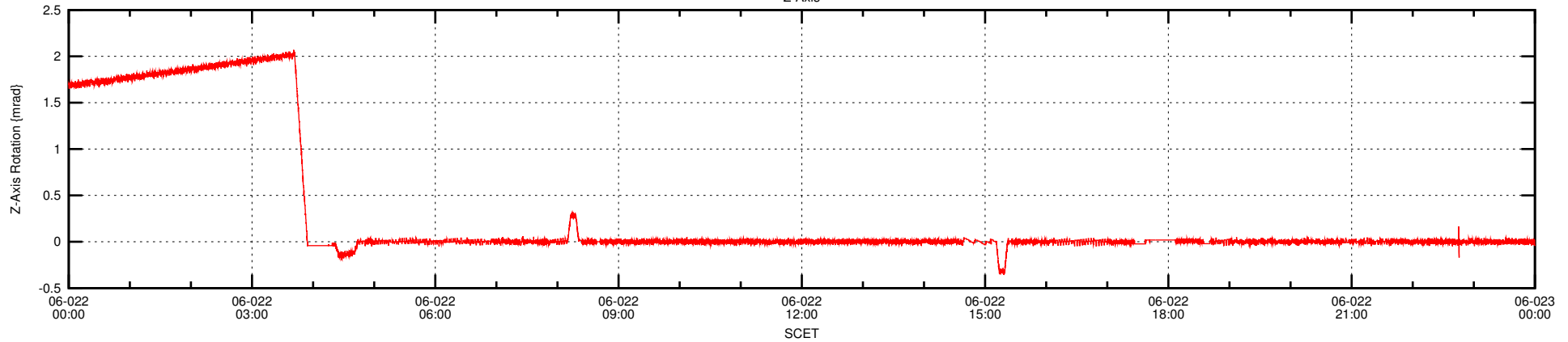
X-Axis (CK #1 = 06022\_06027ra.bc; CK #2 = 05351\_06027ph.bc)



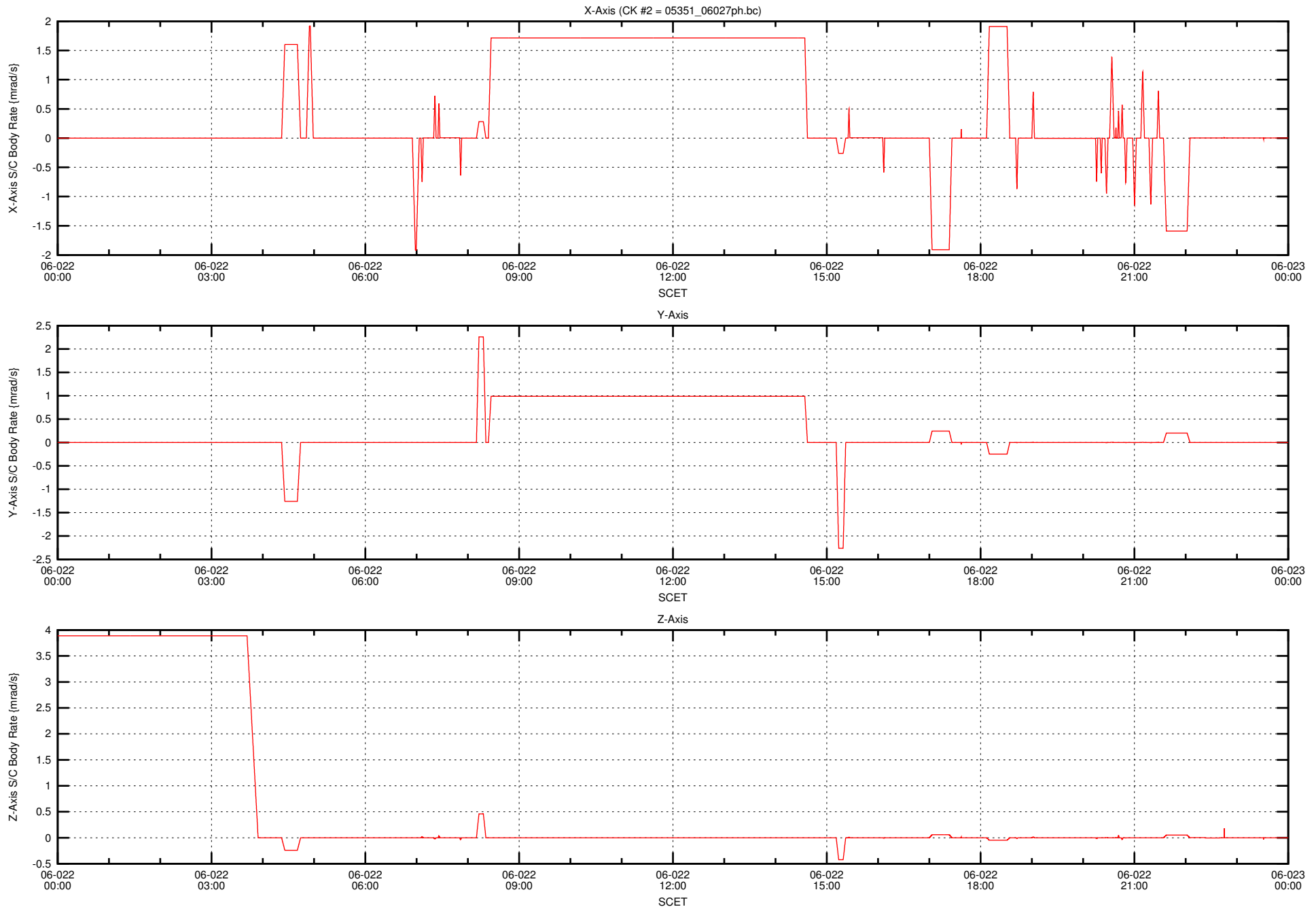
Y-Axis



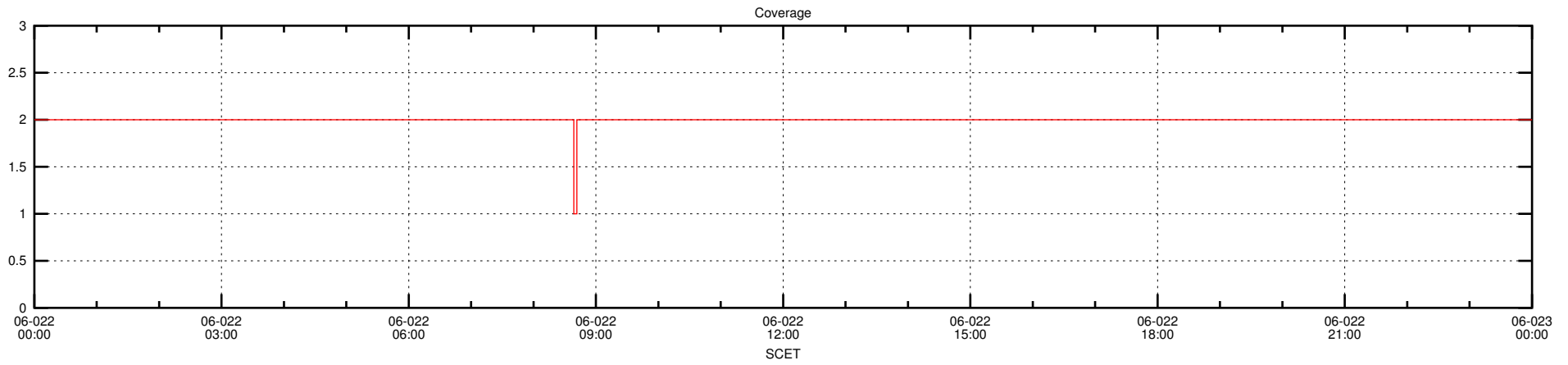
Z-Axis



# CK #2 S/C Body Rates (DOY 022-023)

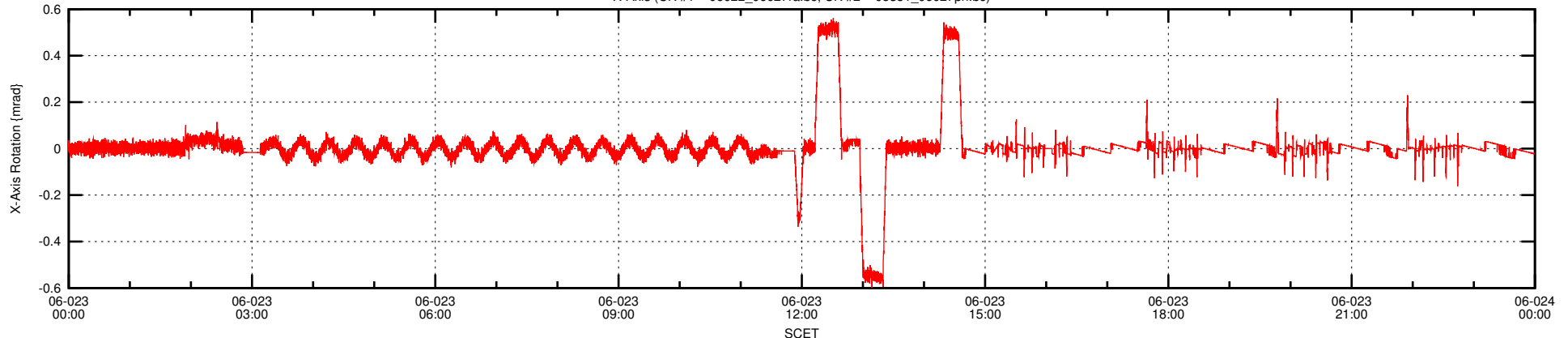


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 022-023)

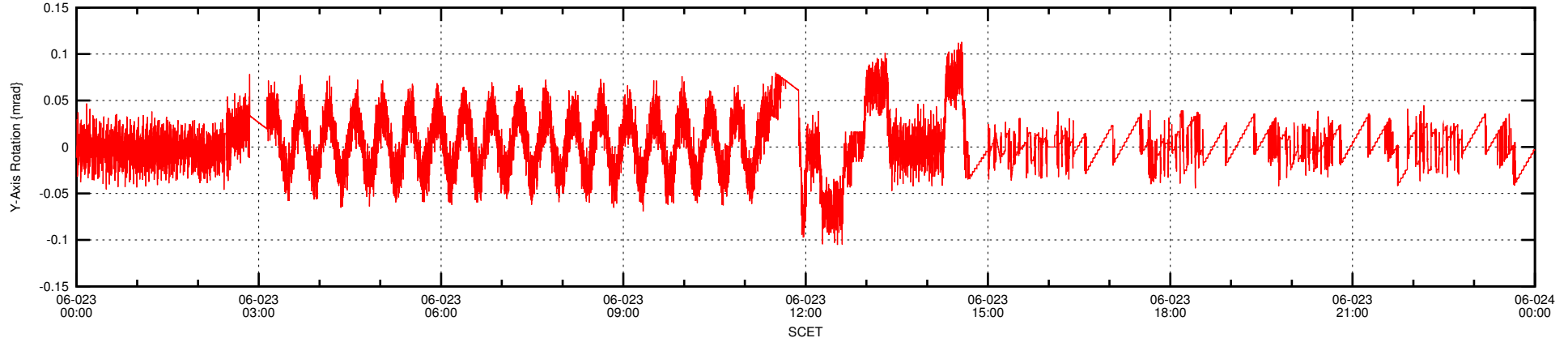


# Rotation From CK #2 to CK #1 (DOY 023-024)

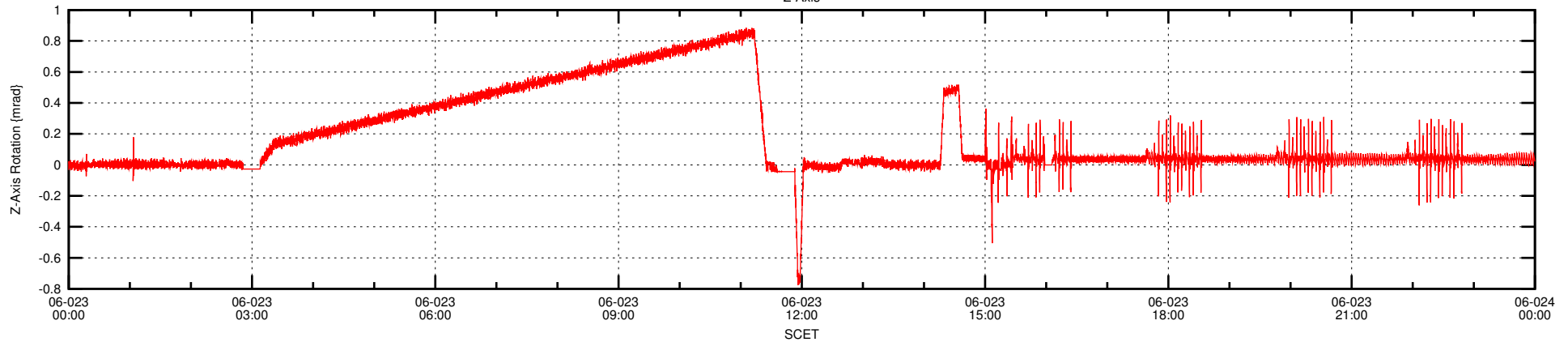
X-Axis (CK #1 = 06022\_06027ra.bc; CK #2 = 05351\_06027ph.bc)



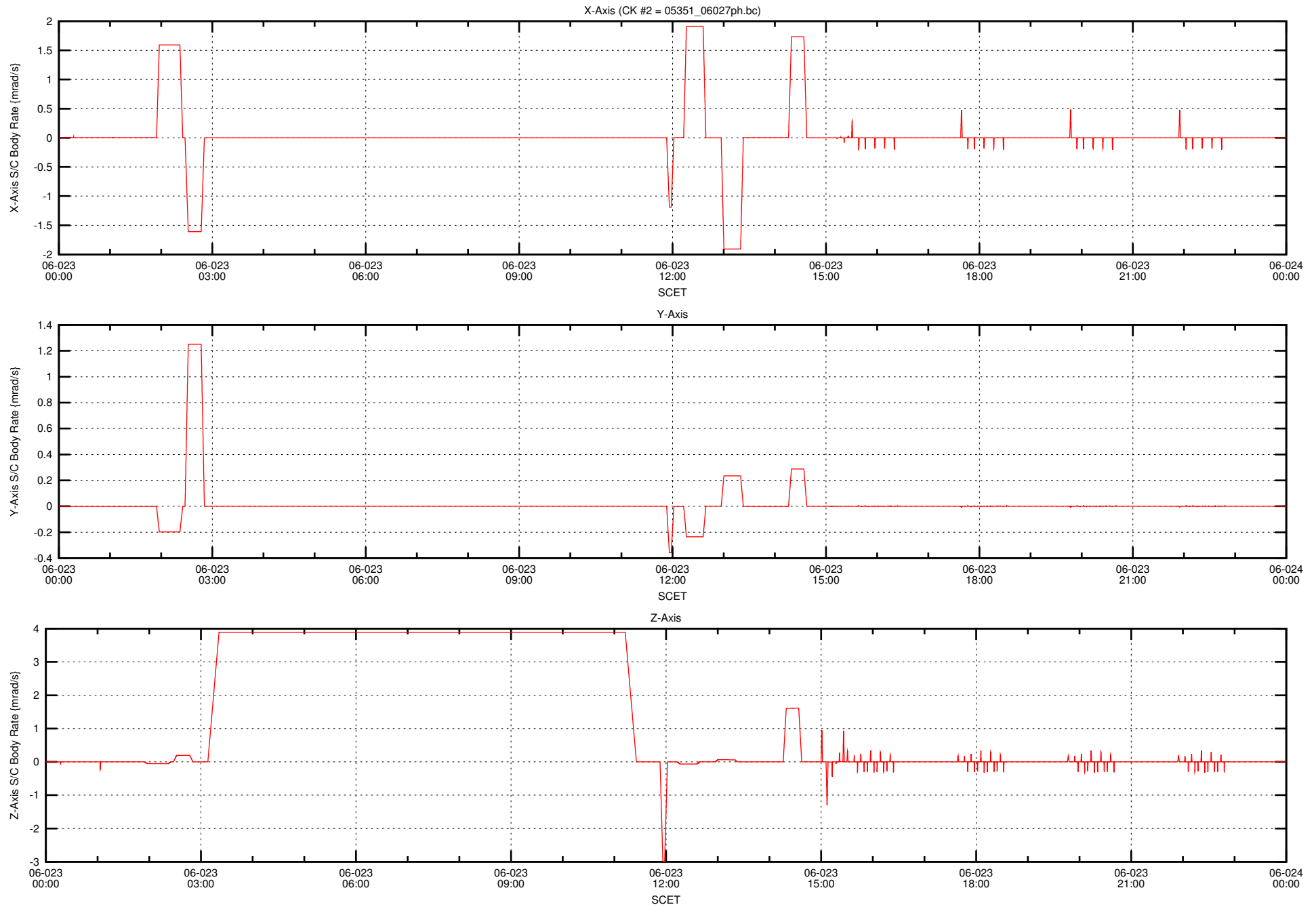
Y-Axis



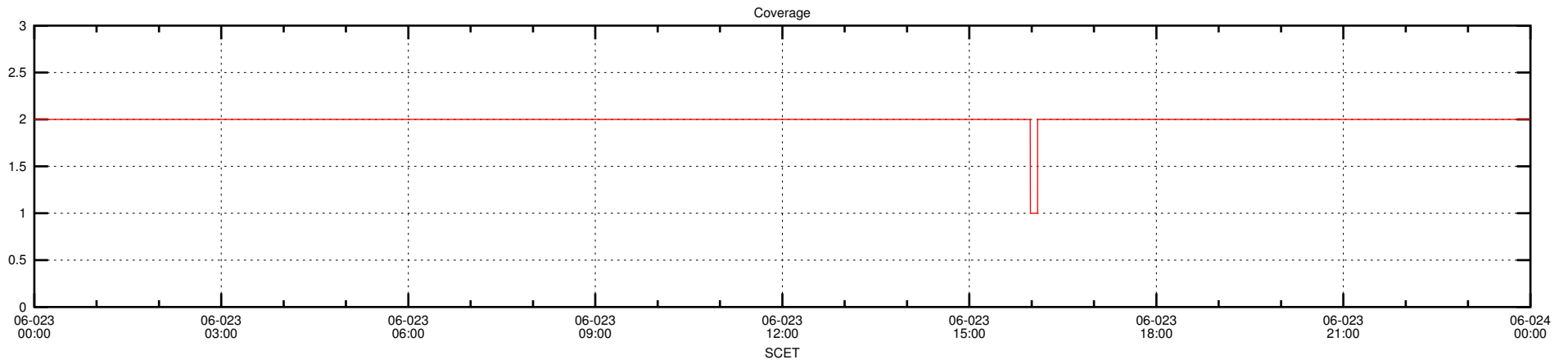
Z-Axis



# CK #2 S/C Body Rates (DOY 023-024)

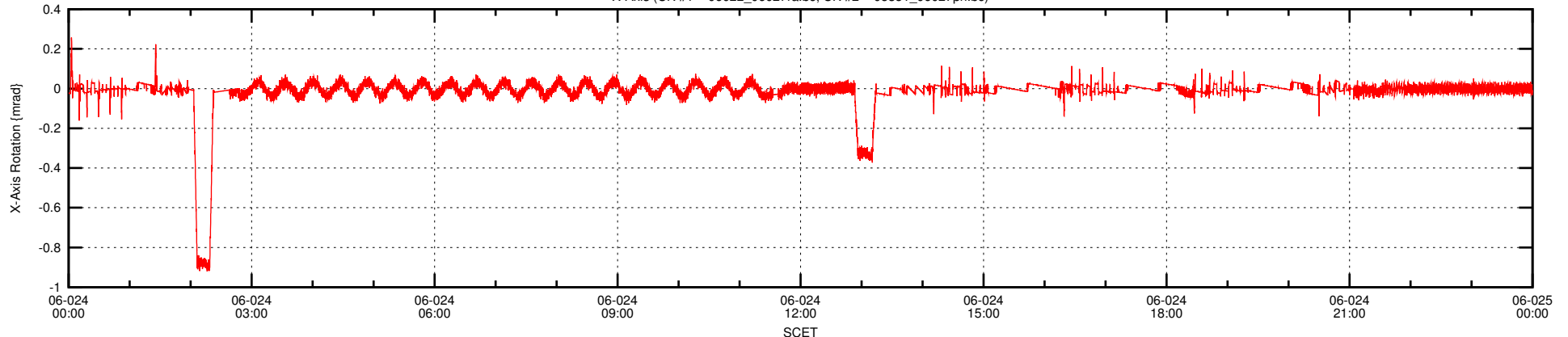


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 023-024)

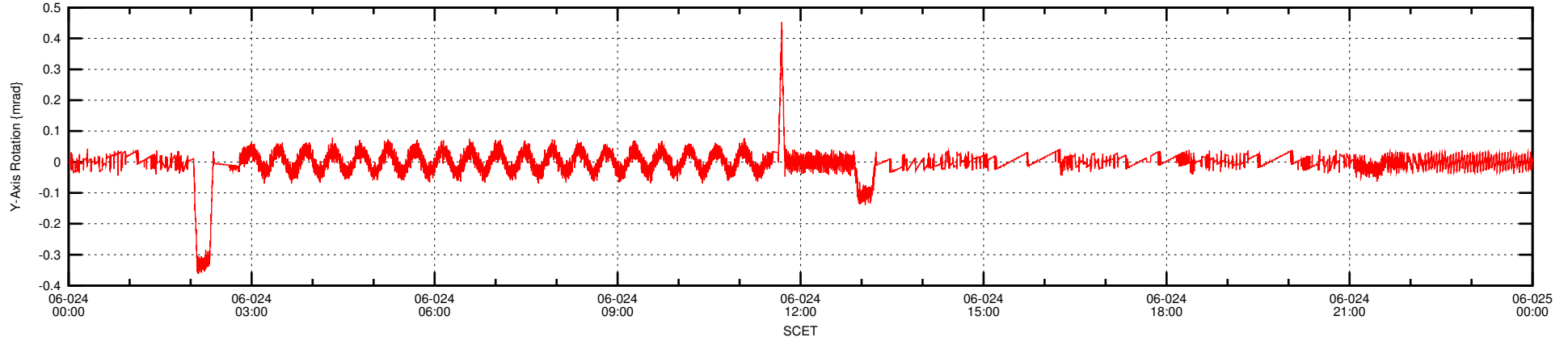


# Rotation From CK #2 to CK #1 (DOY 024-025)

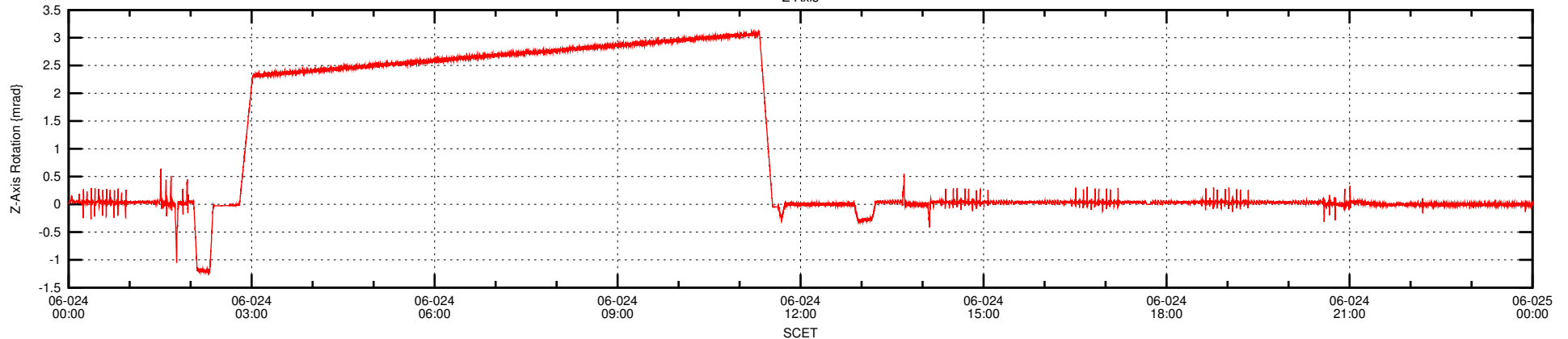
X-Axis (CK #1 = 06022\_06027ra.bc; CK #2 = 05351\_06027ph.bc)



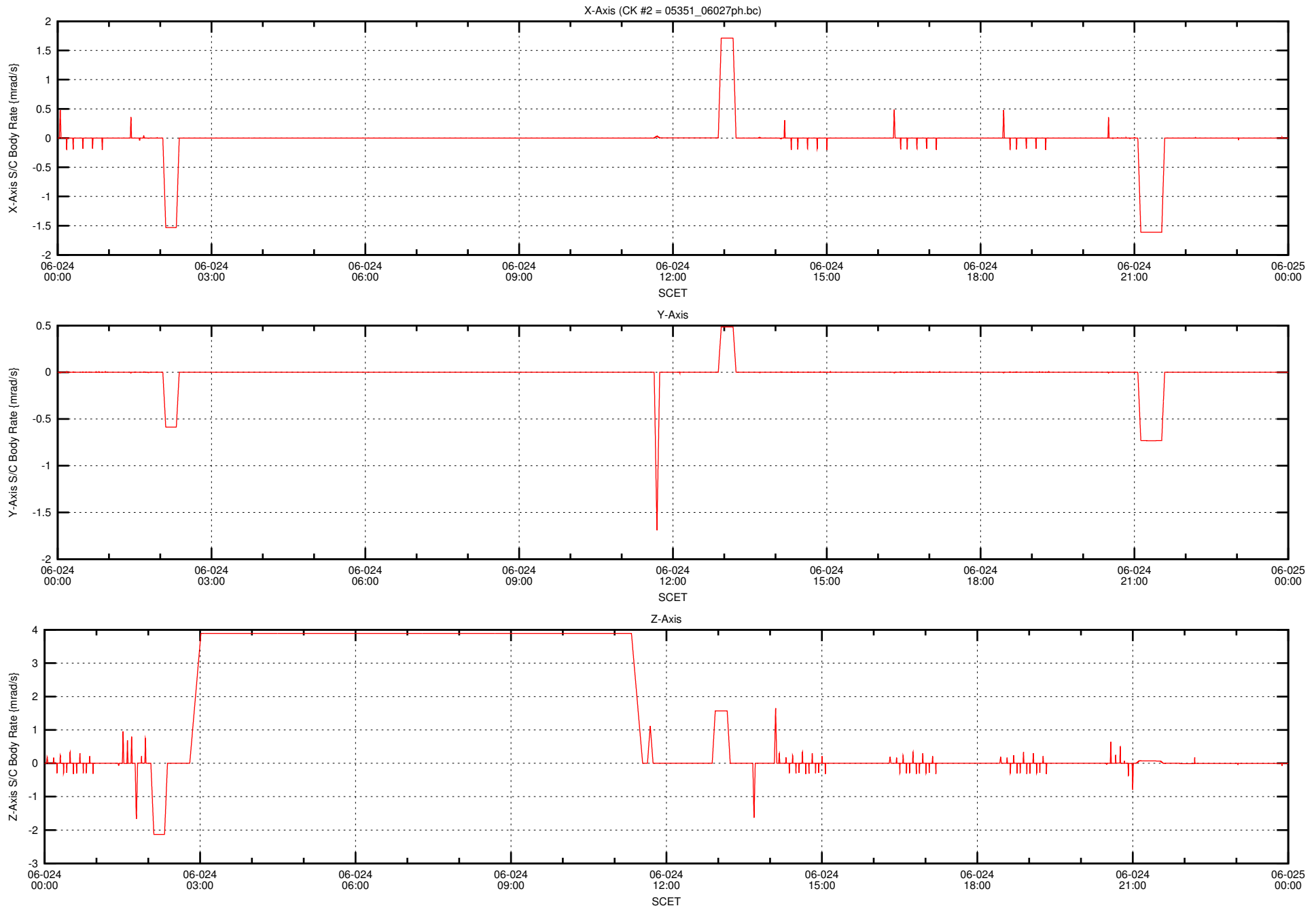
Y-Axis



Z-Axis

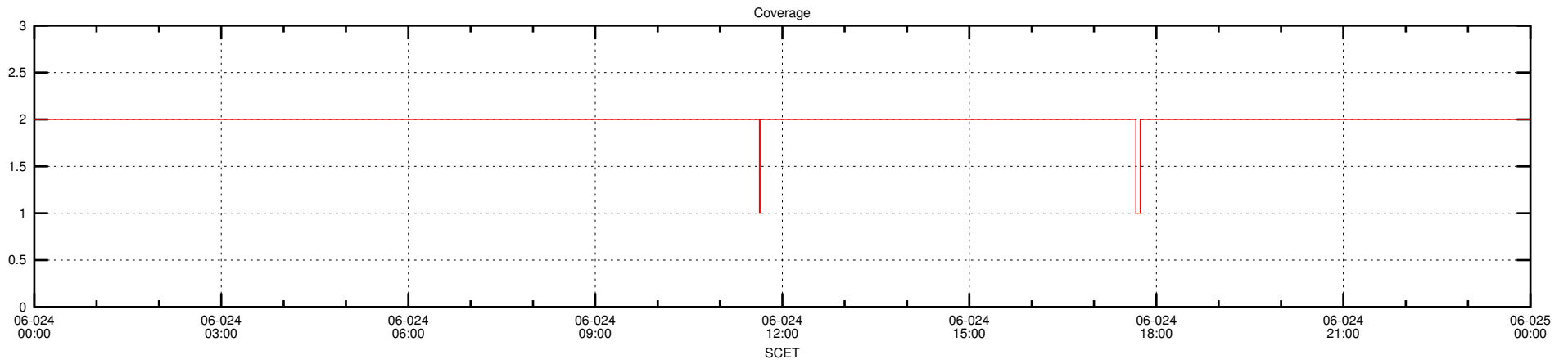


# CK #2 S/C Body Rates (DOY 024-025)



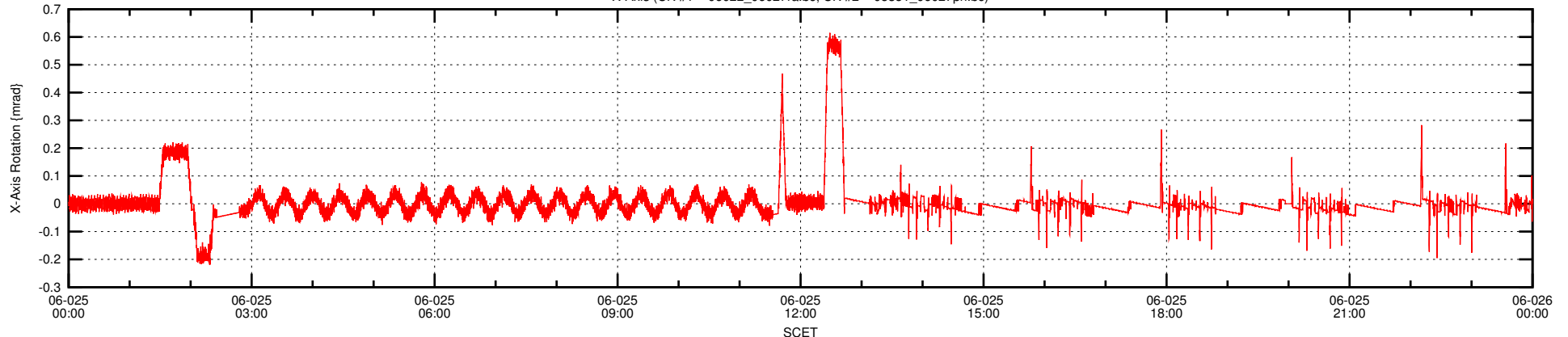


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 024-025)

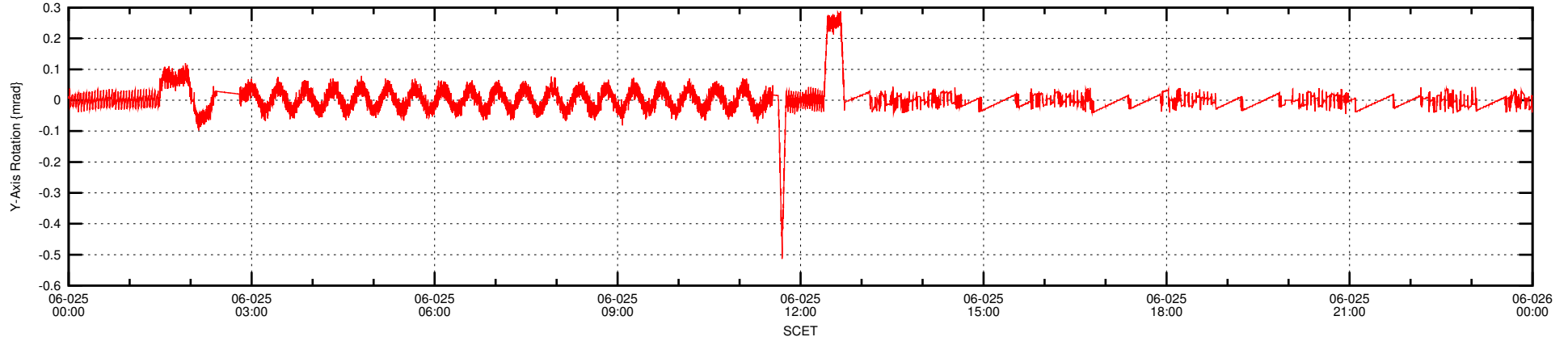


# Rotation From CK #2 to CK #1 (DOY 025-026)

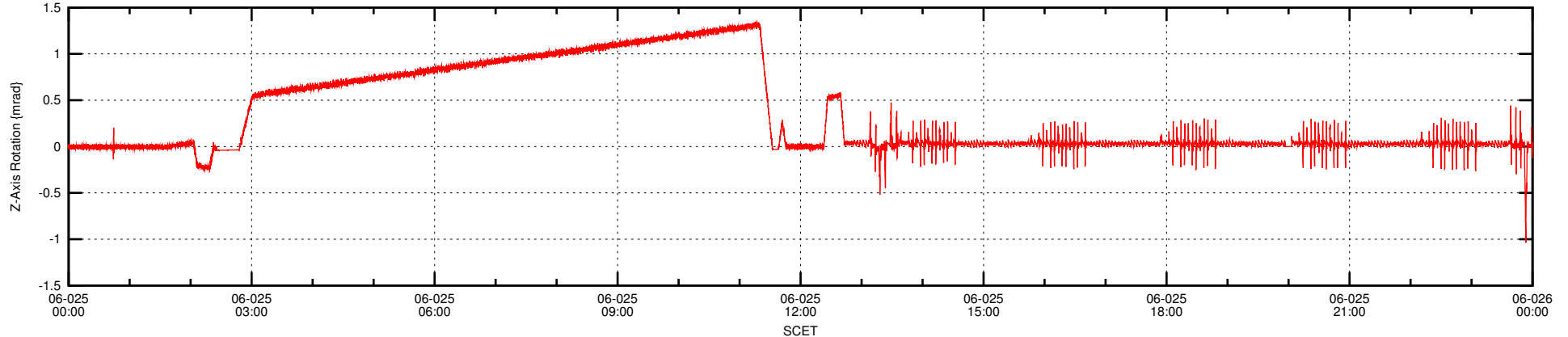
X-Axis (CK #1 = 06022\_06027ra.bc; CK #2 = 05351\_06027ph.bc)



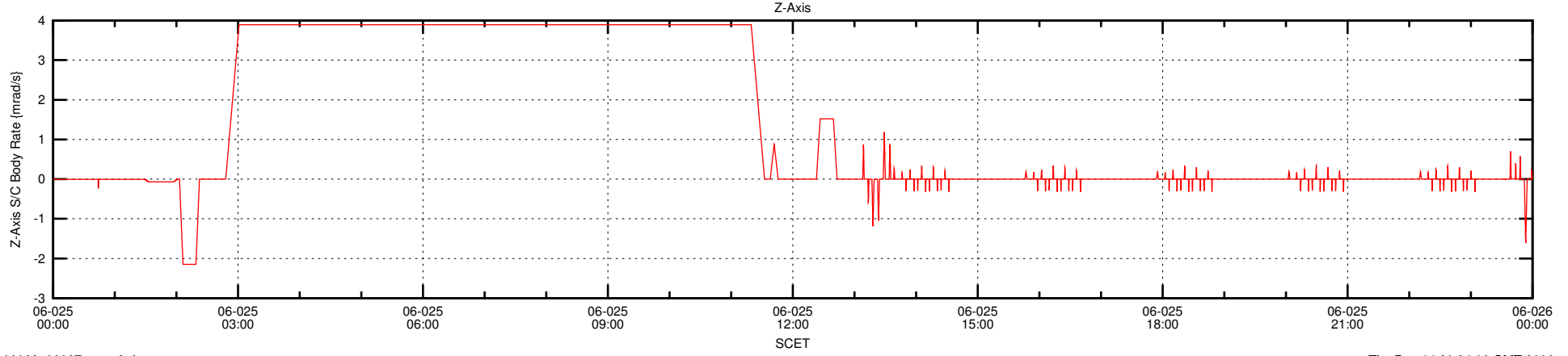
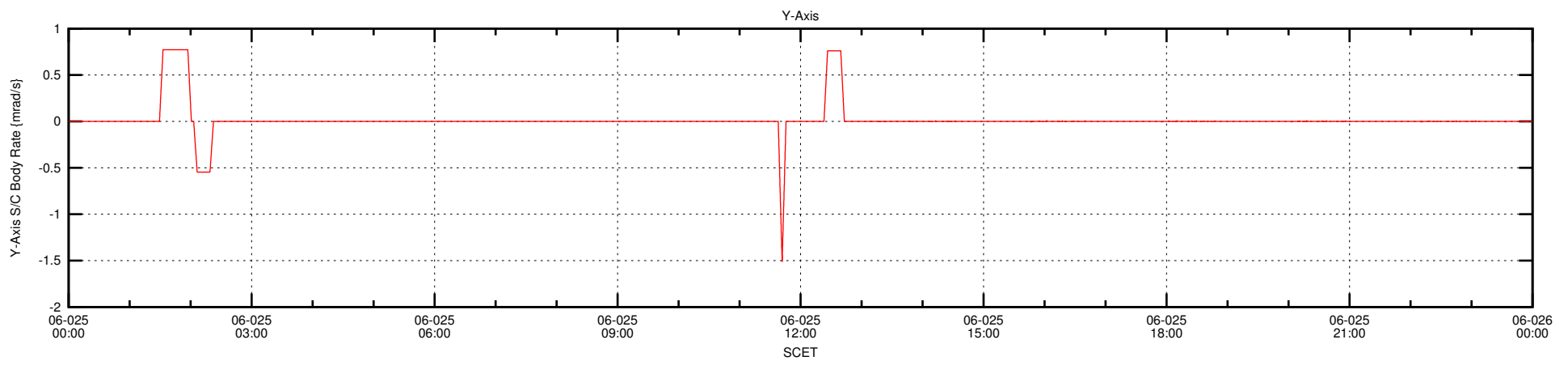
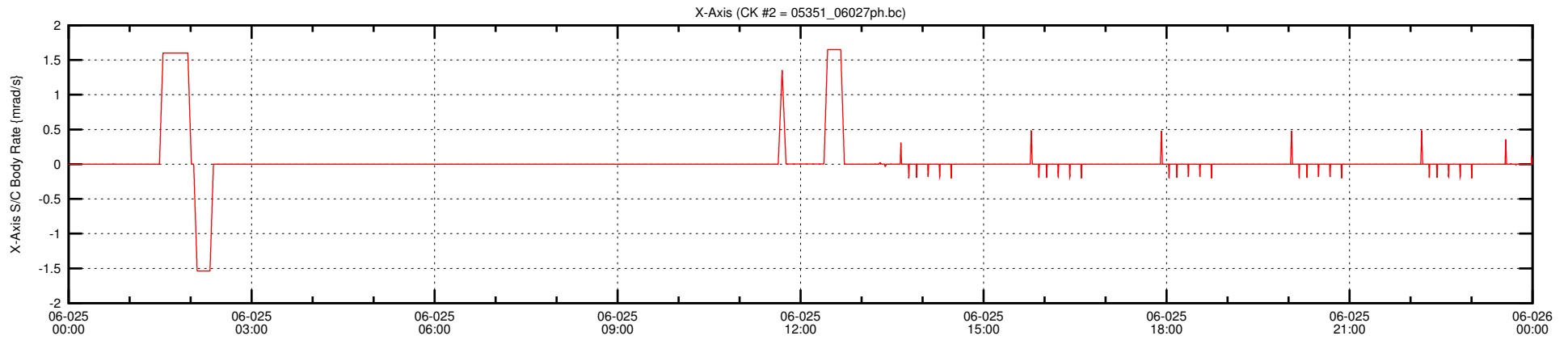
Y-Axis



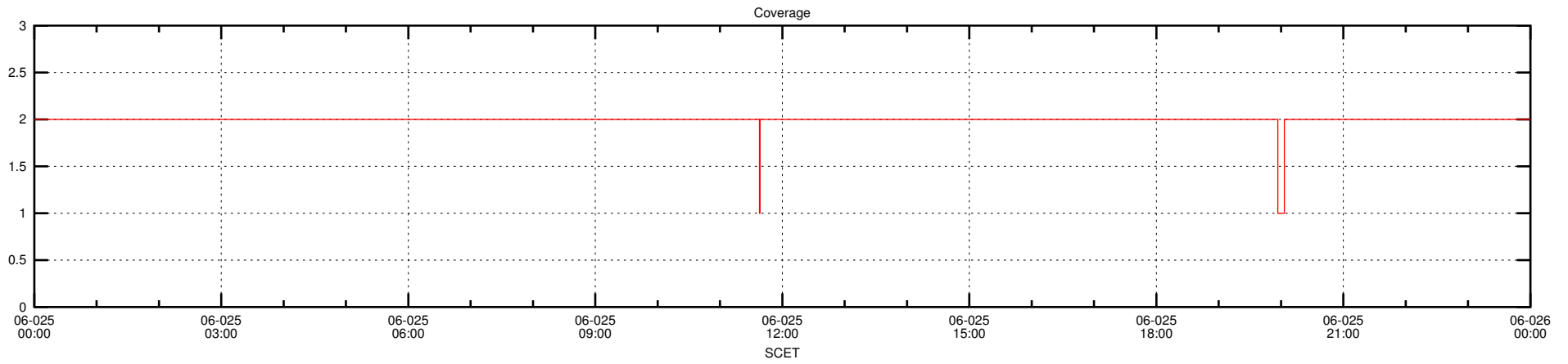
Z-Axis



# CK #2 S/C Body Rates (DOY 025-026)

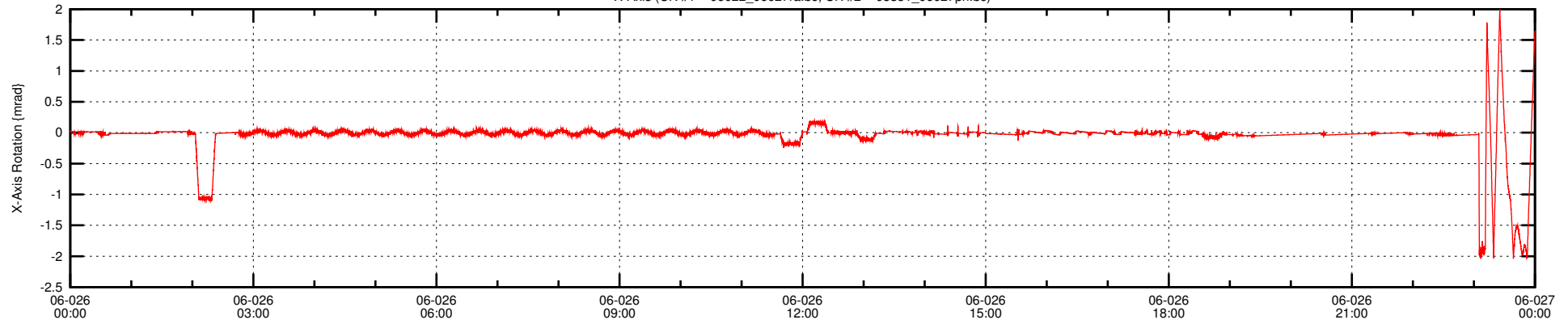


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 025-026)

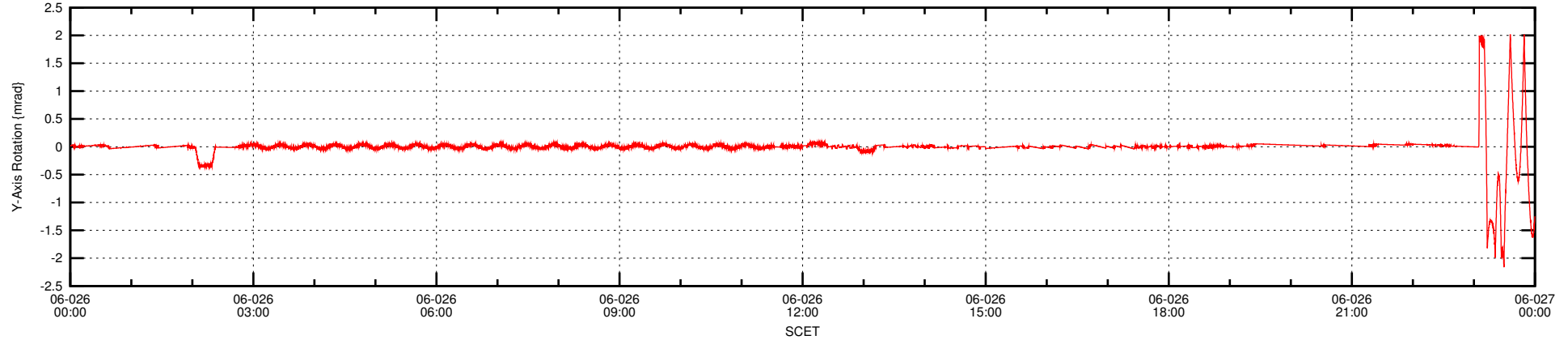


# Rotation From CK #2 to CK #1 (DOY 026-026)

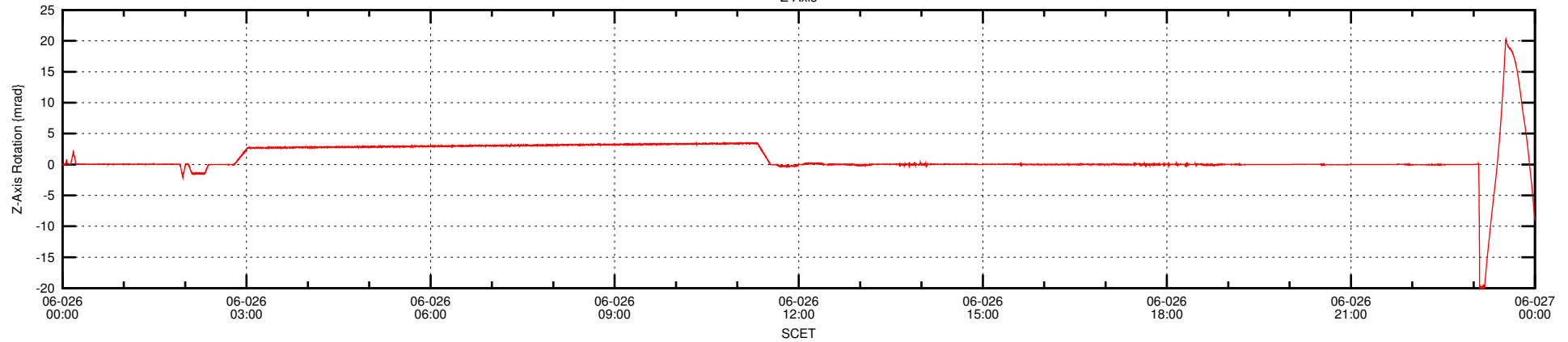
X-Axis (CK #1 = 06022\_06027ra.bc; CK #2 = 05351\_06027ph.bc)



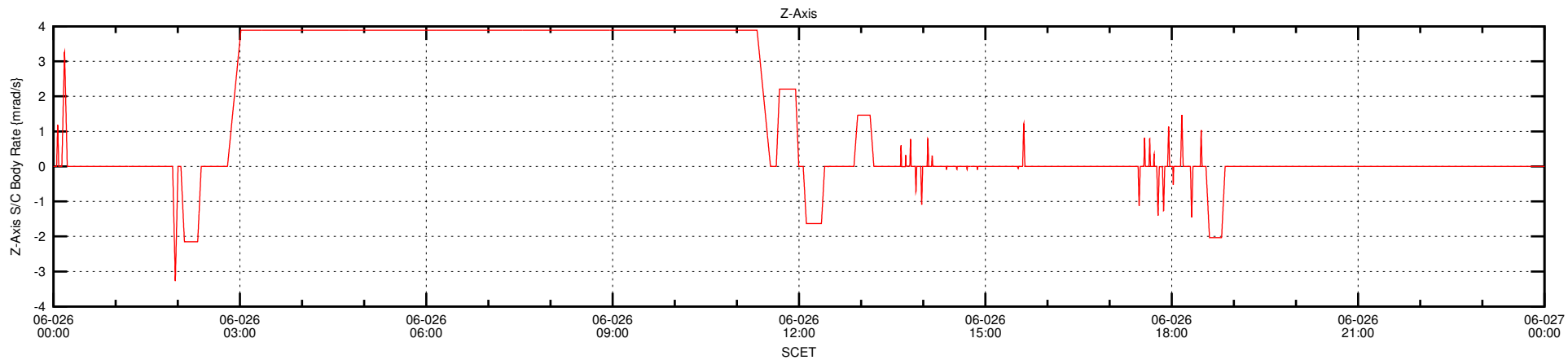
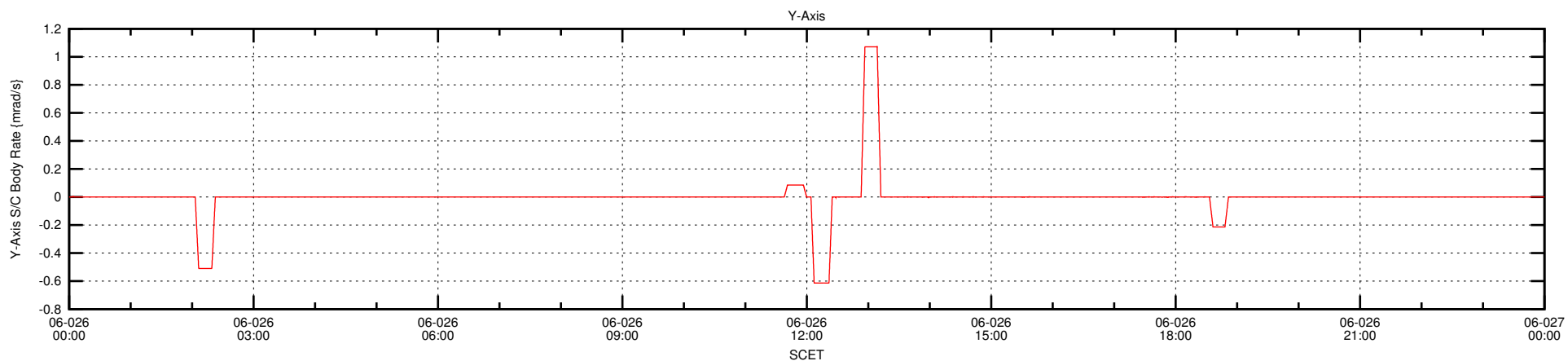
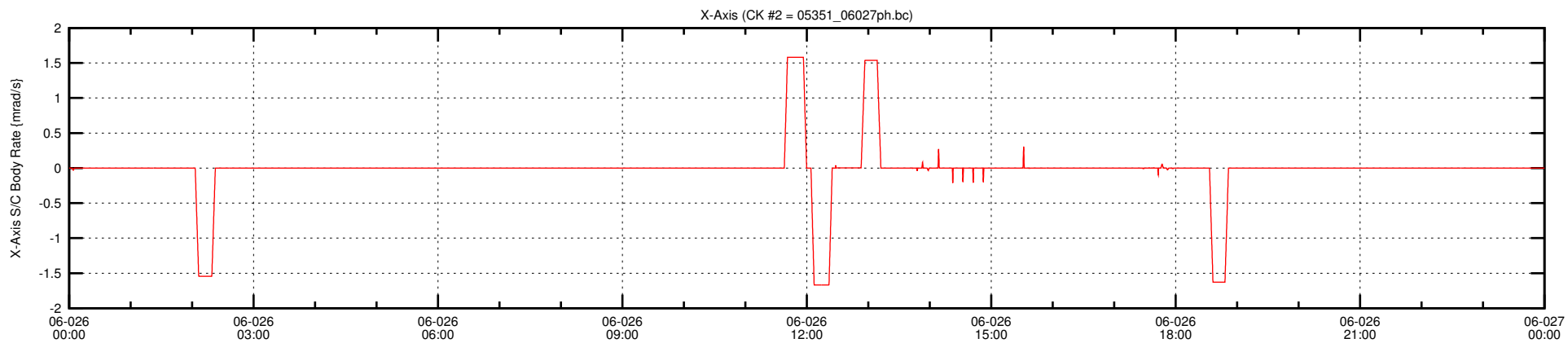
Y-Axis



Z-Axis



# CK #2 S/C Body Rates (DOY 026-026)



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 026-026)

