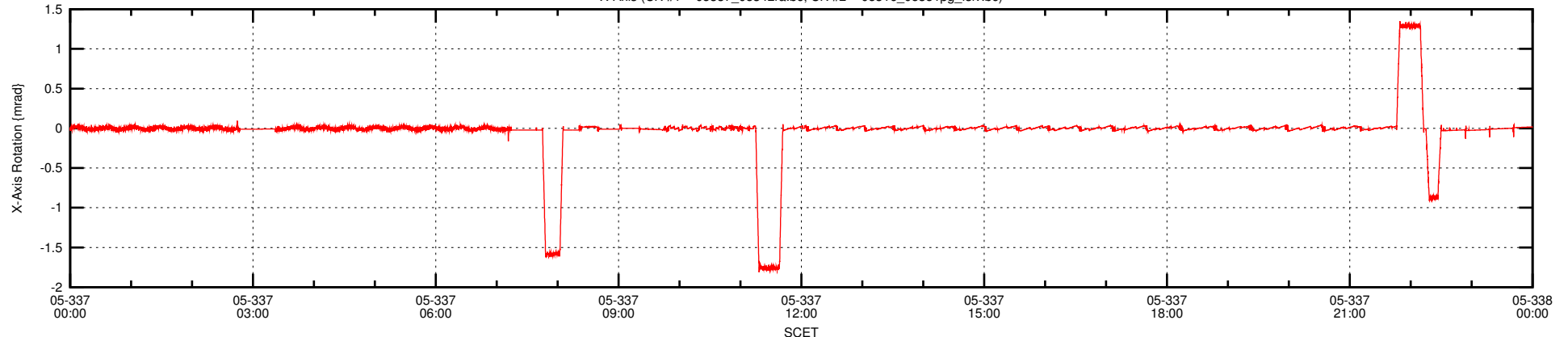
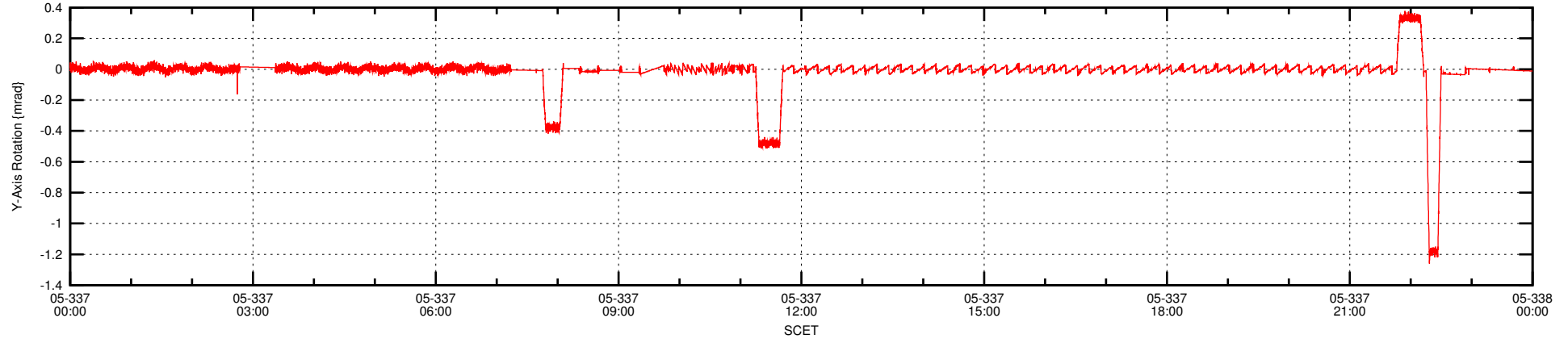


# Rotation From CK #2 to CK #1 (DOY 337-338)

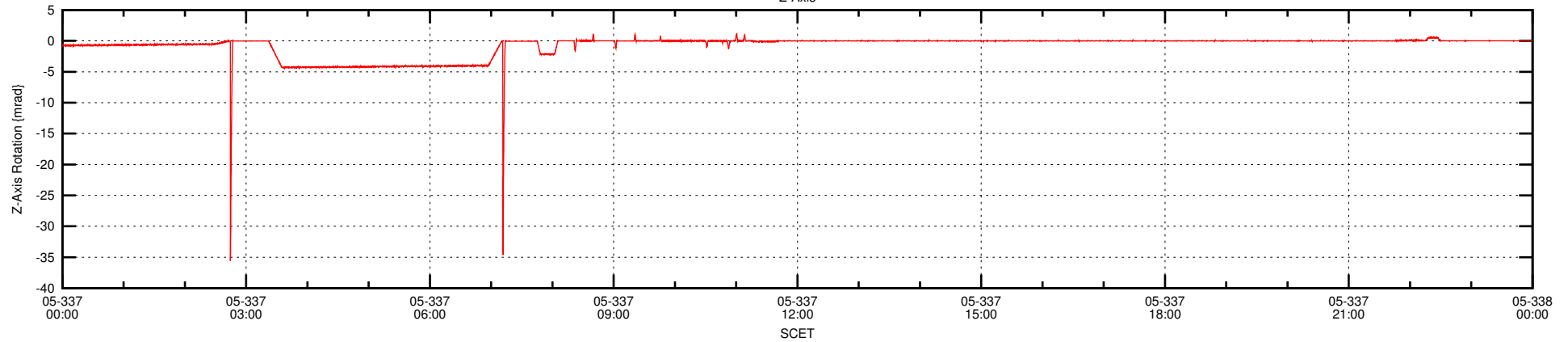
X-Axis (CK #1 = 05337\_05342ra.bc; CK #2 = 05316\_05351pg\_fsiv.bc)



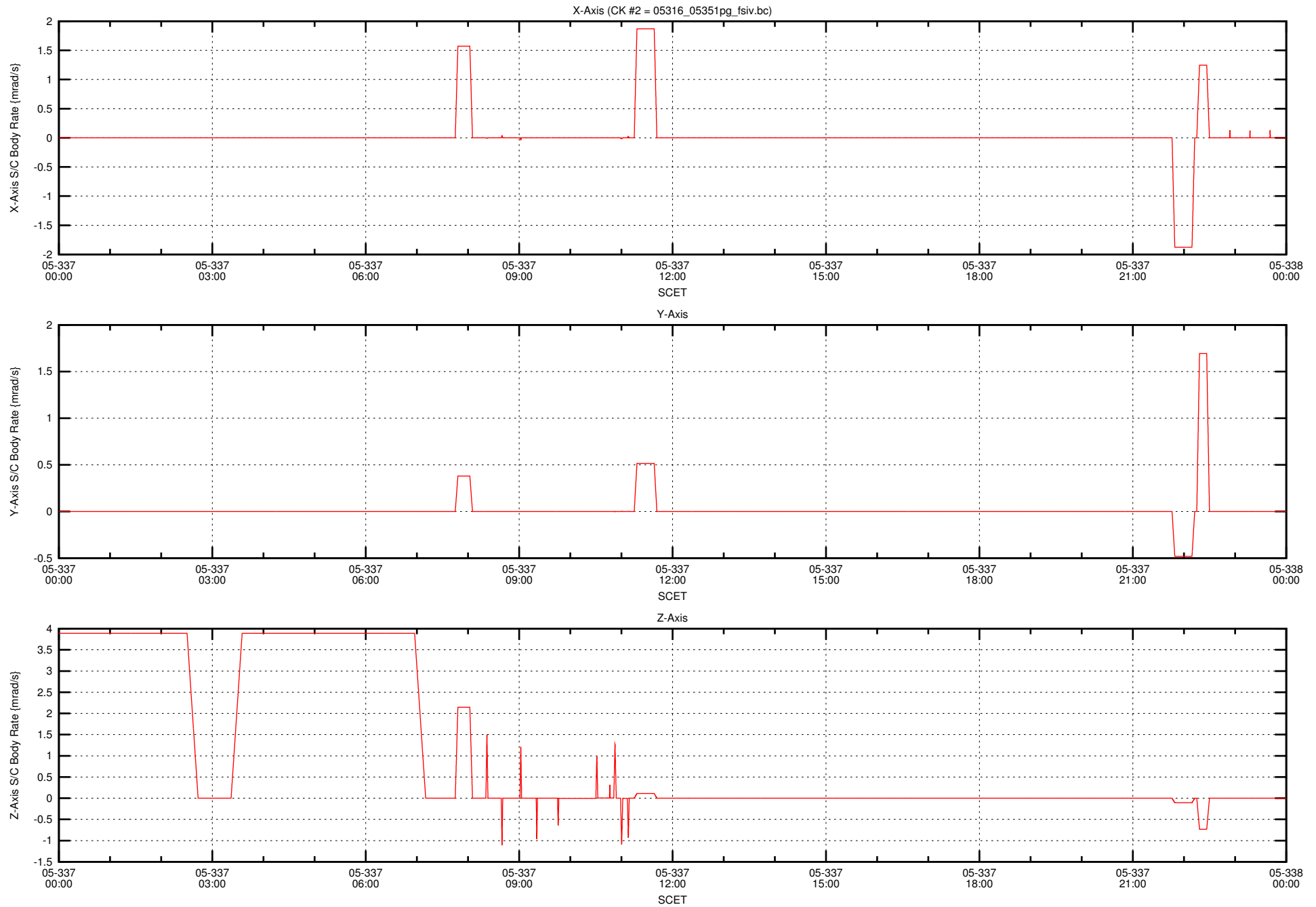
Y-Axis



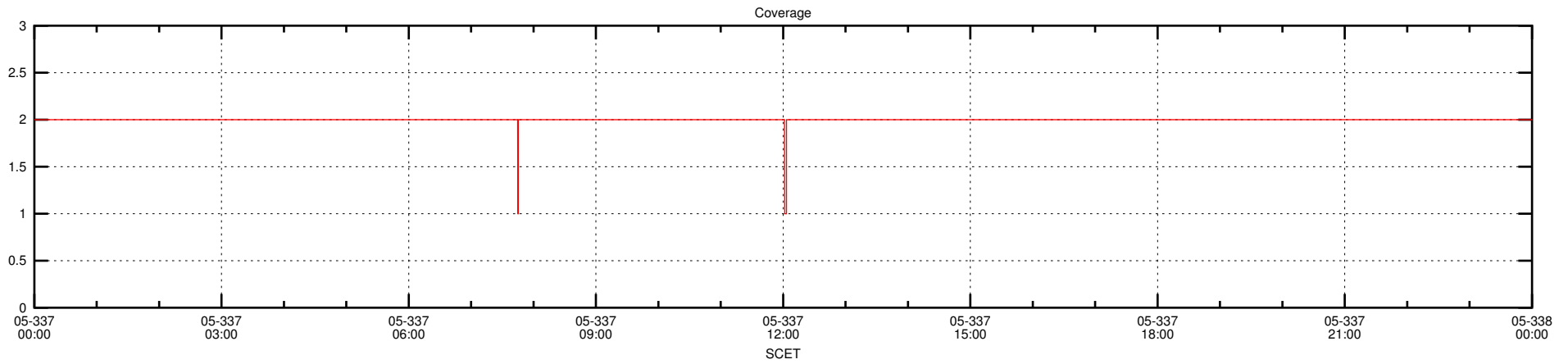
Z-Axis



# CK #2 S/C Body Rates (DOY 337-338)

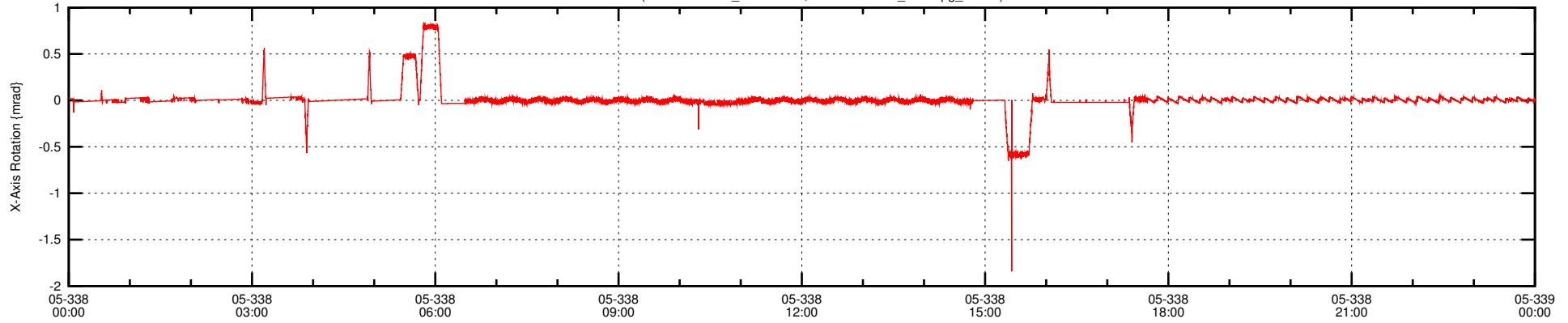


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 337-338)

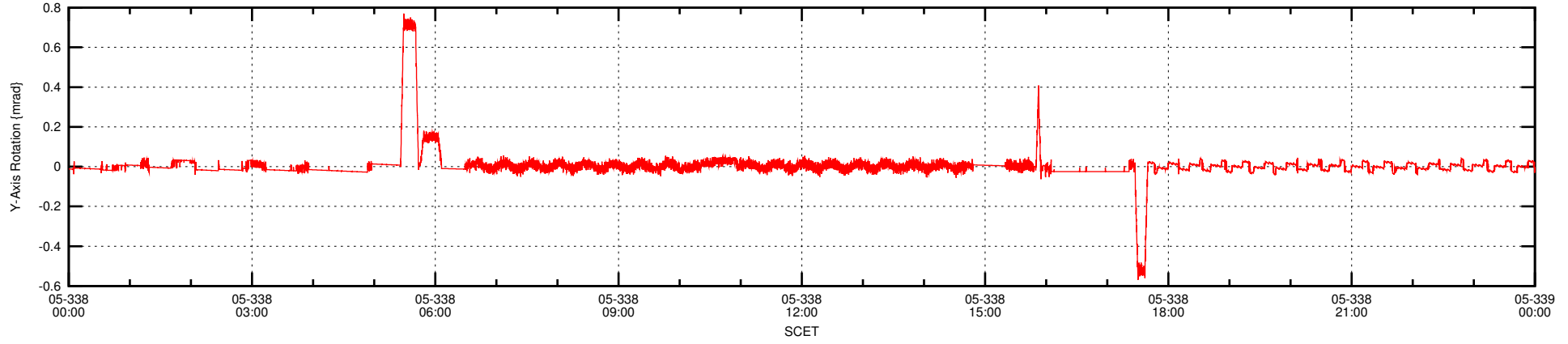


# Rotation From CK #2 to CK #1 (DOY 338-339)

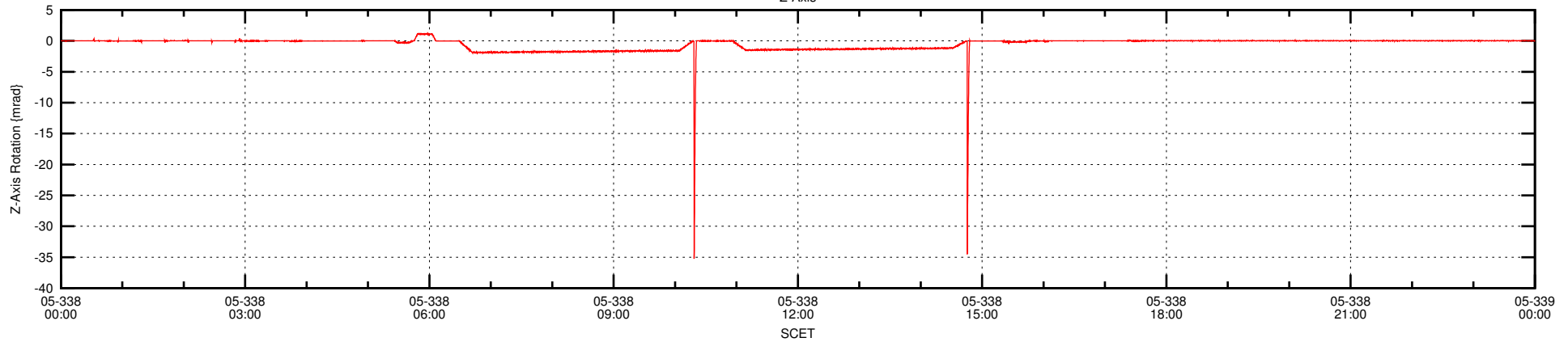
X-Axis (CK #1 = 05337\_05342ra.bc; CK #2 = 05316\_05351pg\_fsiv.bc)



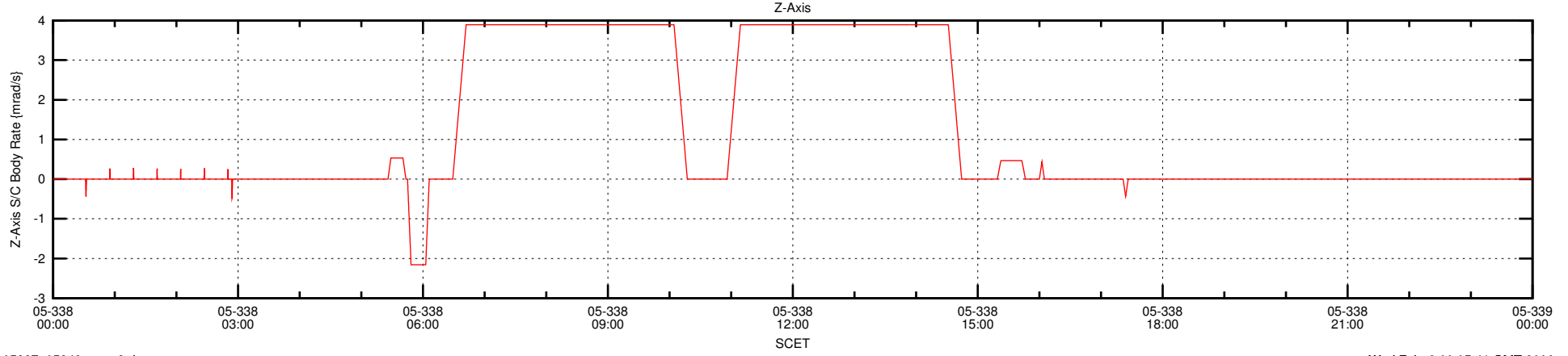
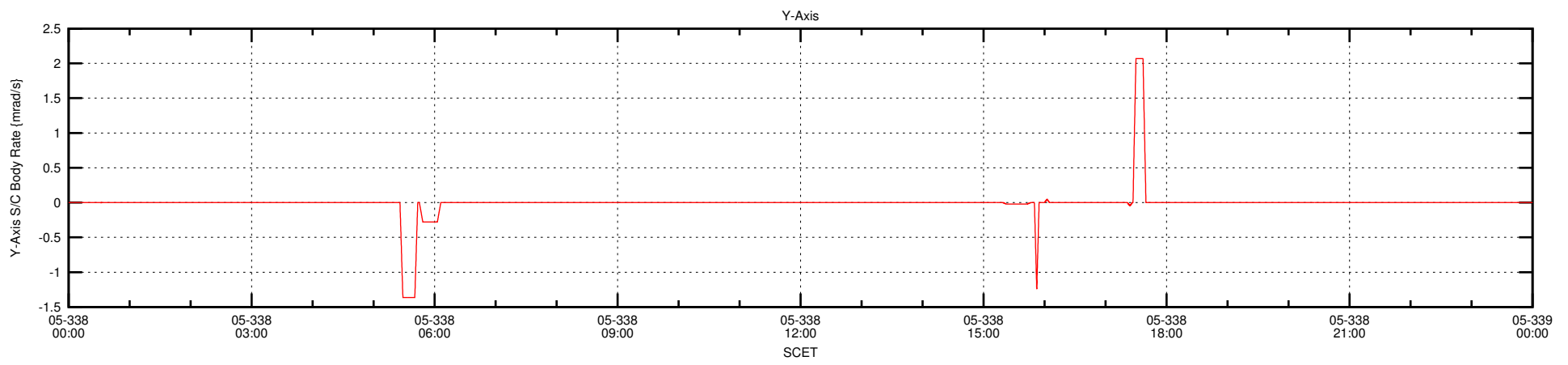
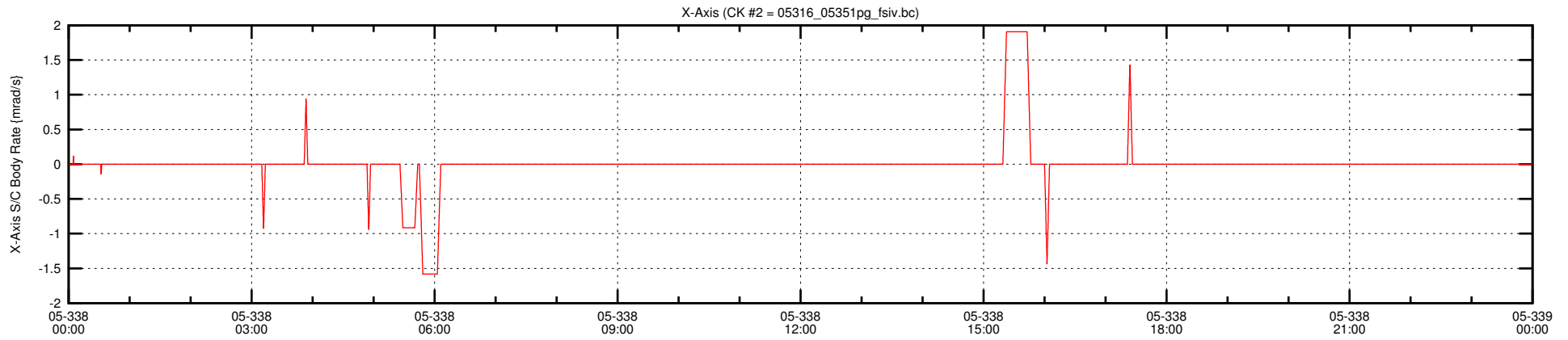
Y-Axis



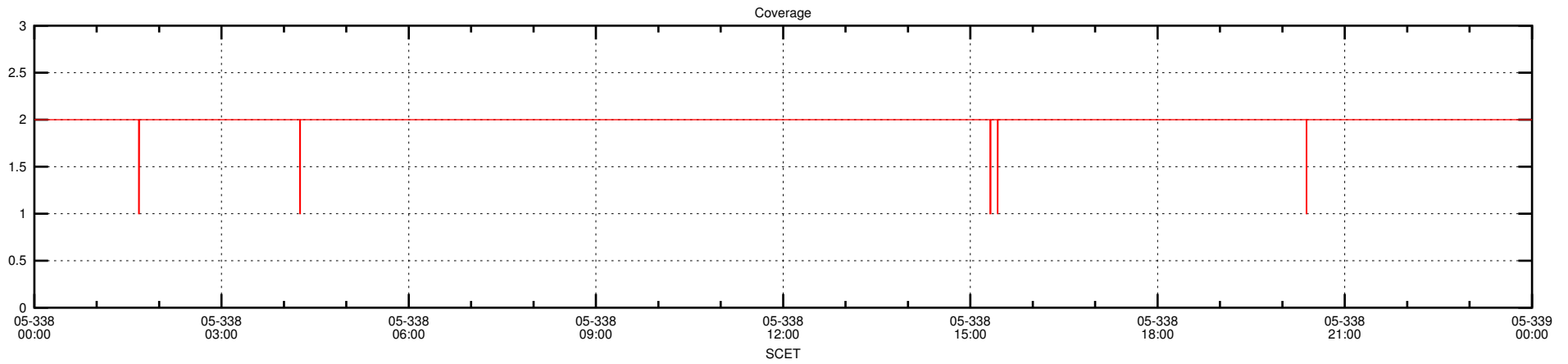
Z-Axis



# CK #2 S/C Body Rates (DOY 338-339)

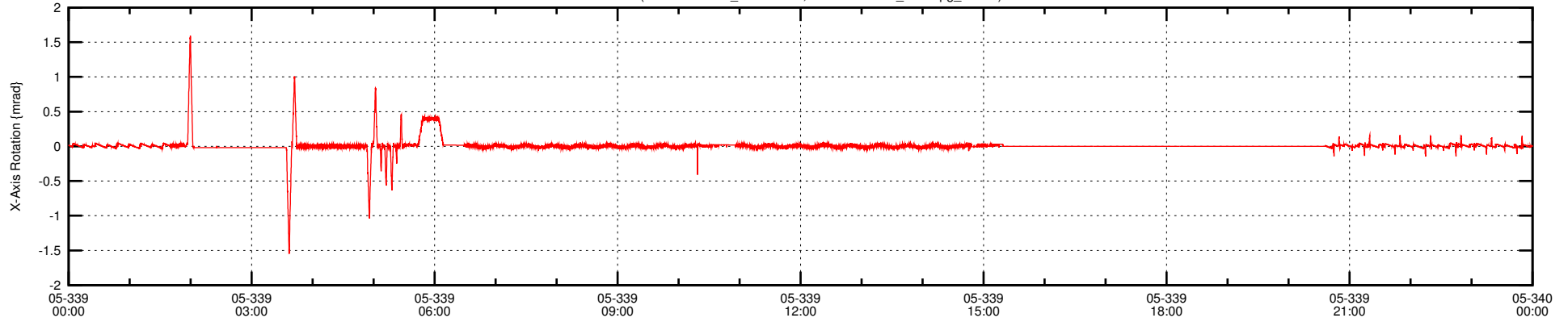


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 338-339)

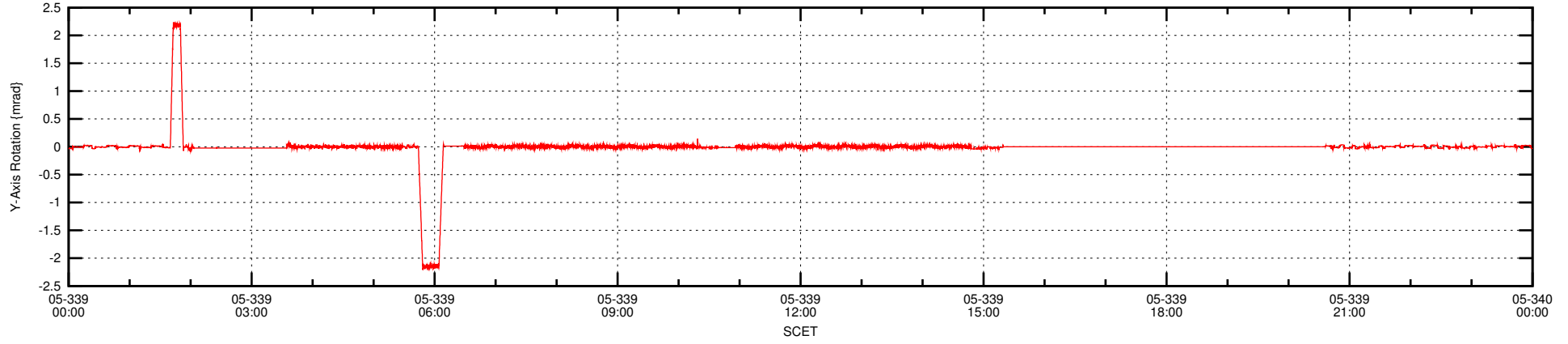


# Rotation From CK #2 to CK #1 (DOY 339-340)

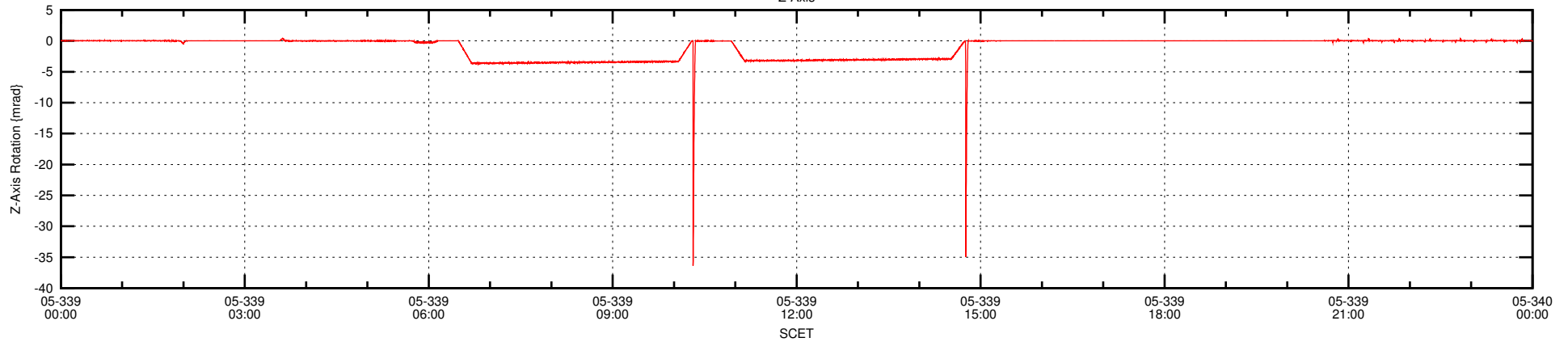
X-Axis (CK #1 = 05337\_05342ra.bc; CK #2 = 05316\_05351pg\_fsiv.bc)



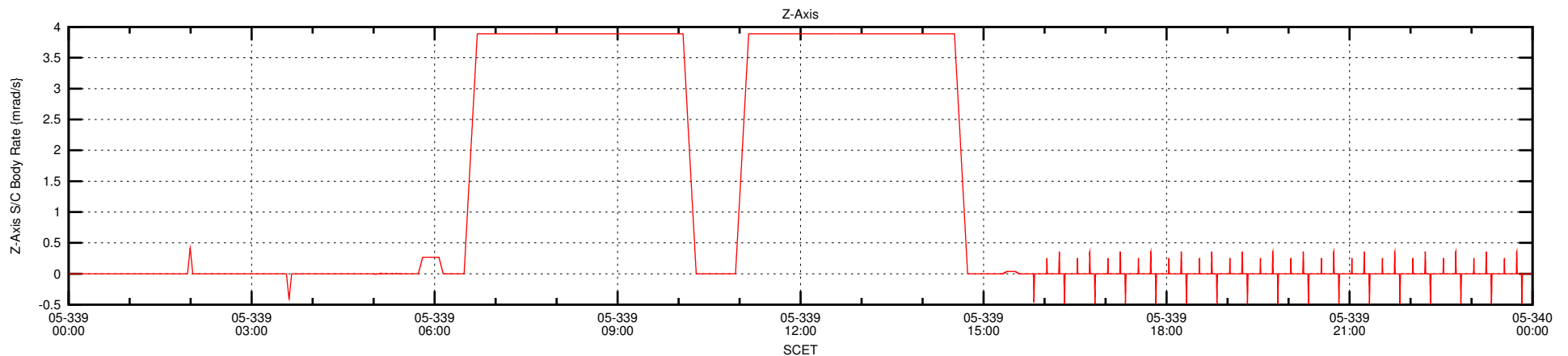
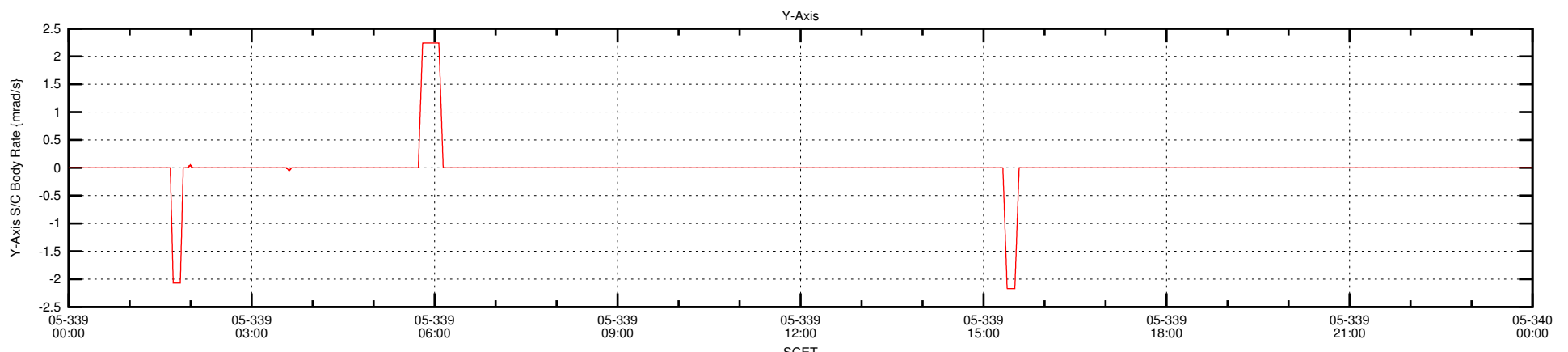
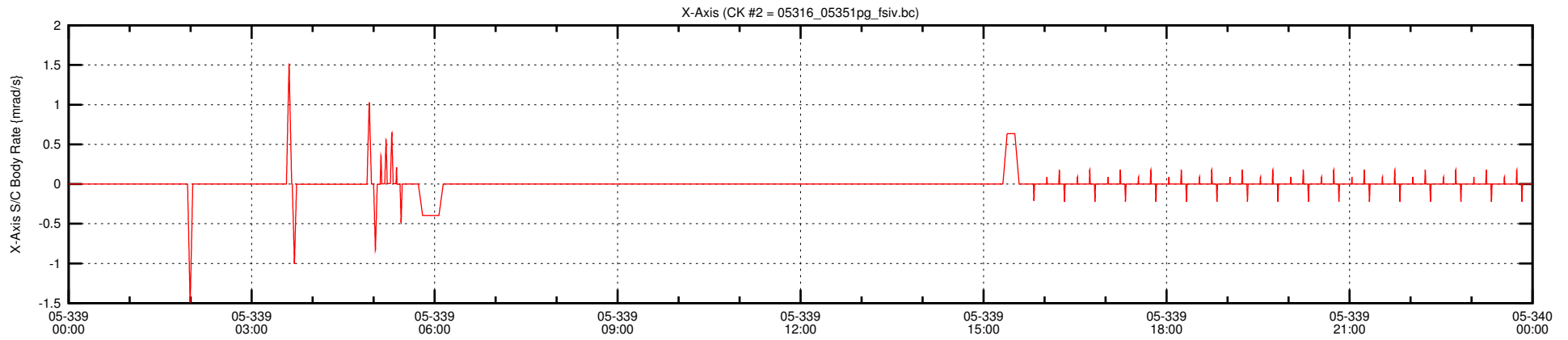
Y-Axis



Z-Axis

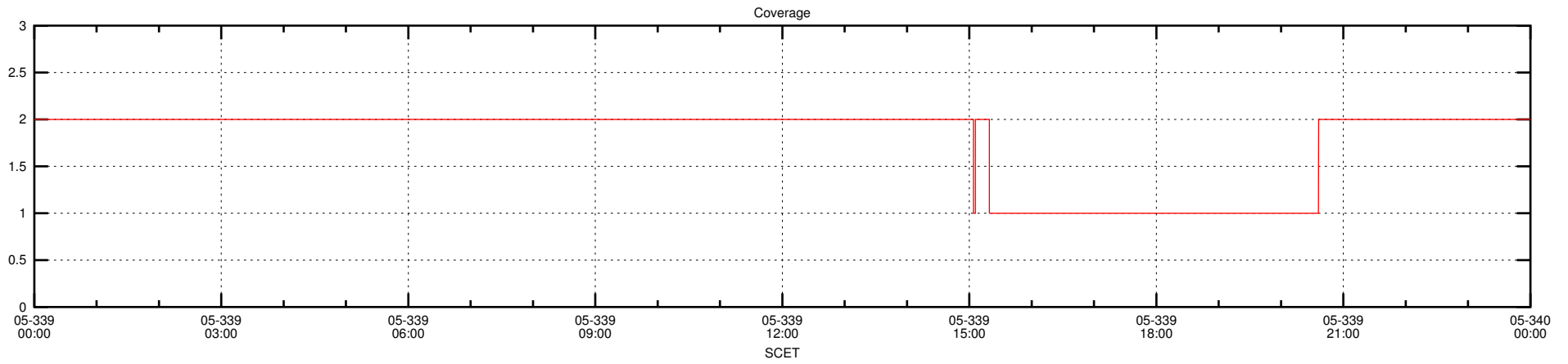


# CK #2 S/C Body Rates (DOY 339-340)



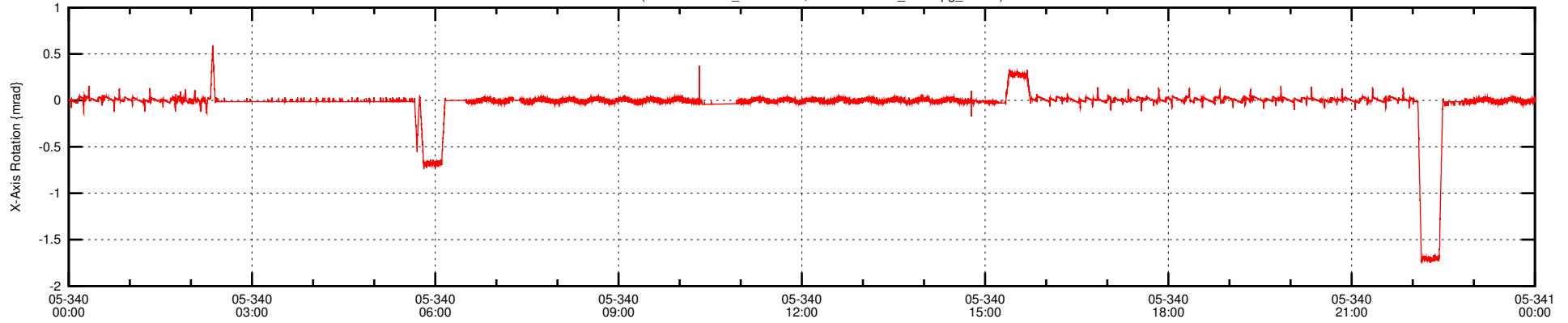


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 339-340)

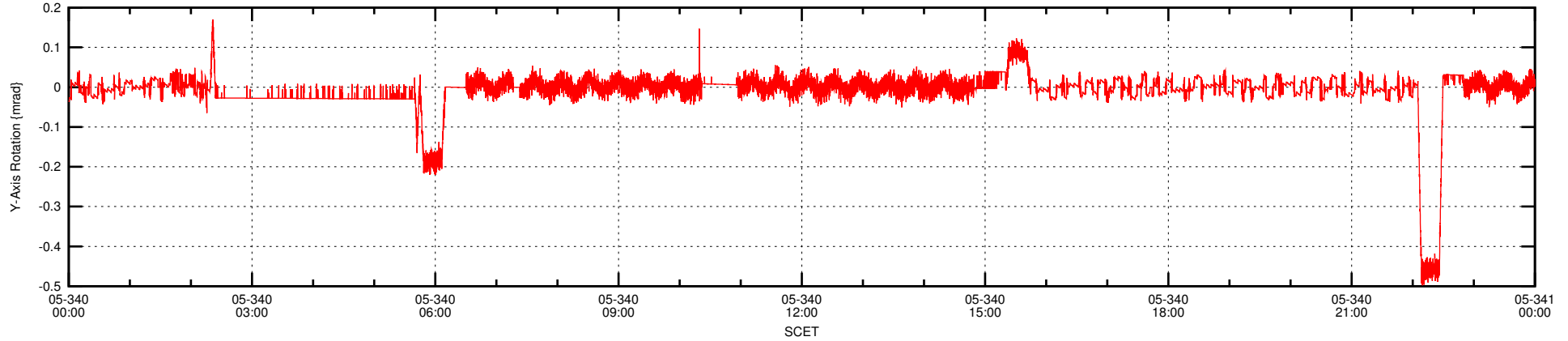


# Rotation From CK #2 to CK #1 (DOY 340-341)

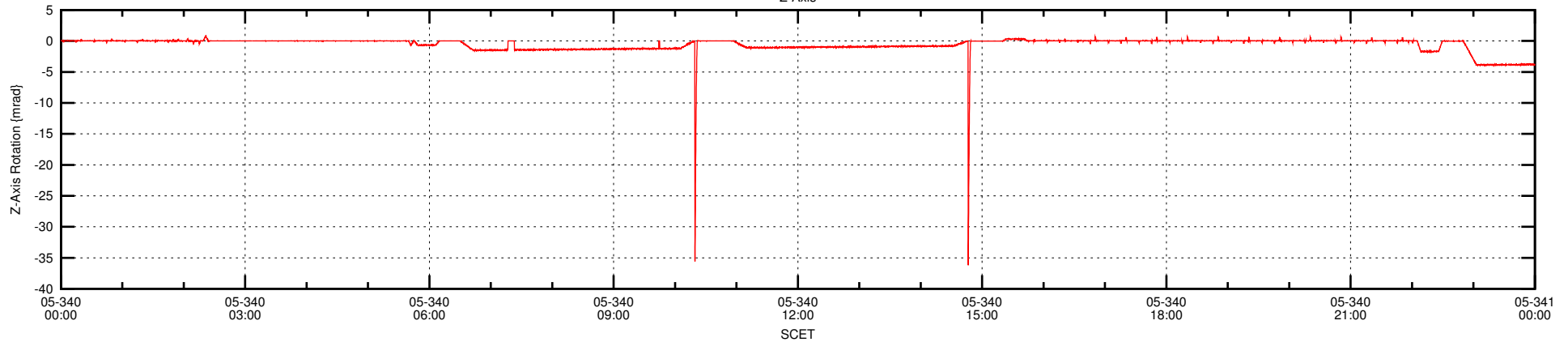
X-Axis (CK #1 = 05337\_05342ra.bc; CK #2 = 05316\_05351pg\_fsiv.bc)



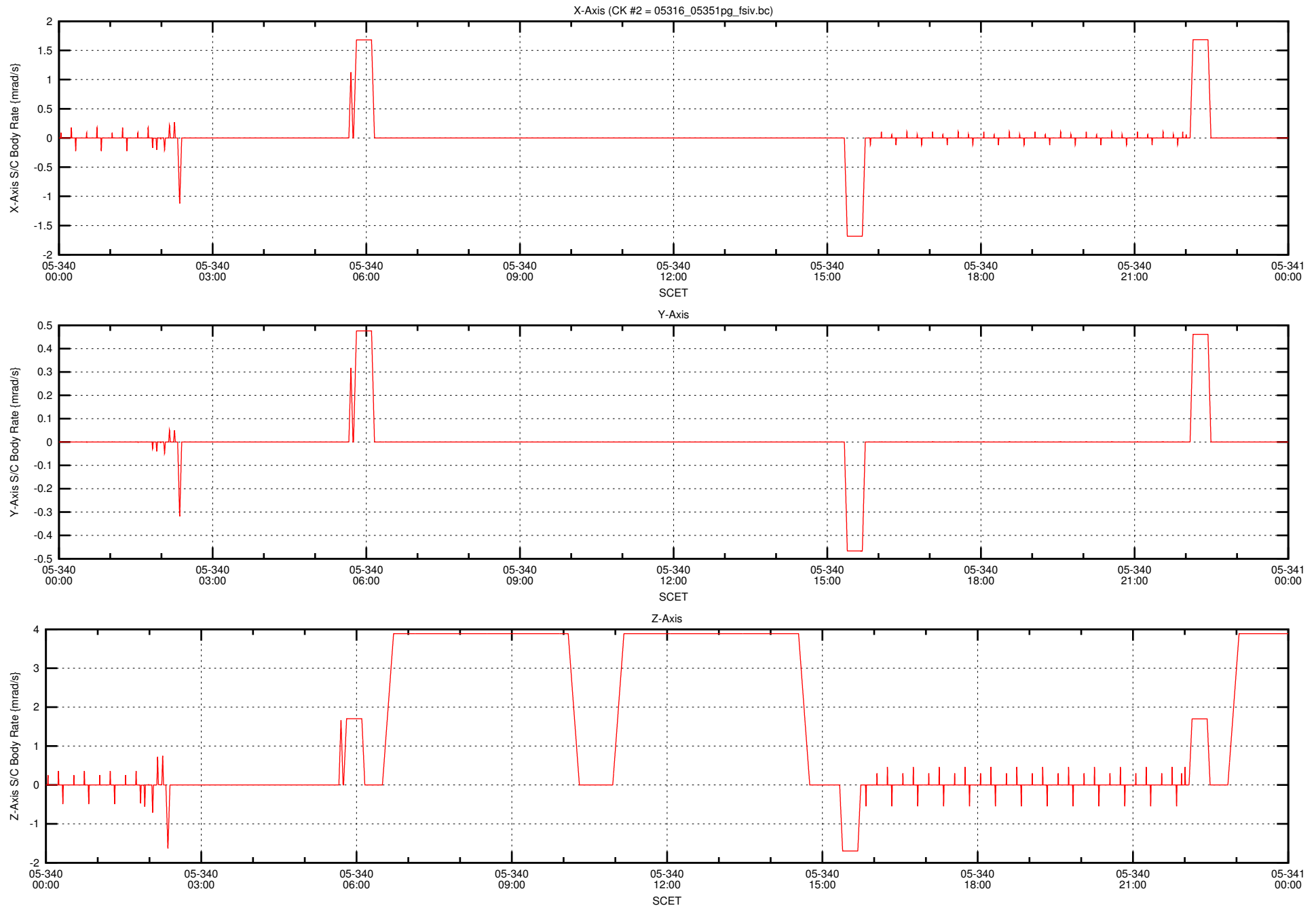
Y-Axis



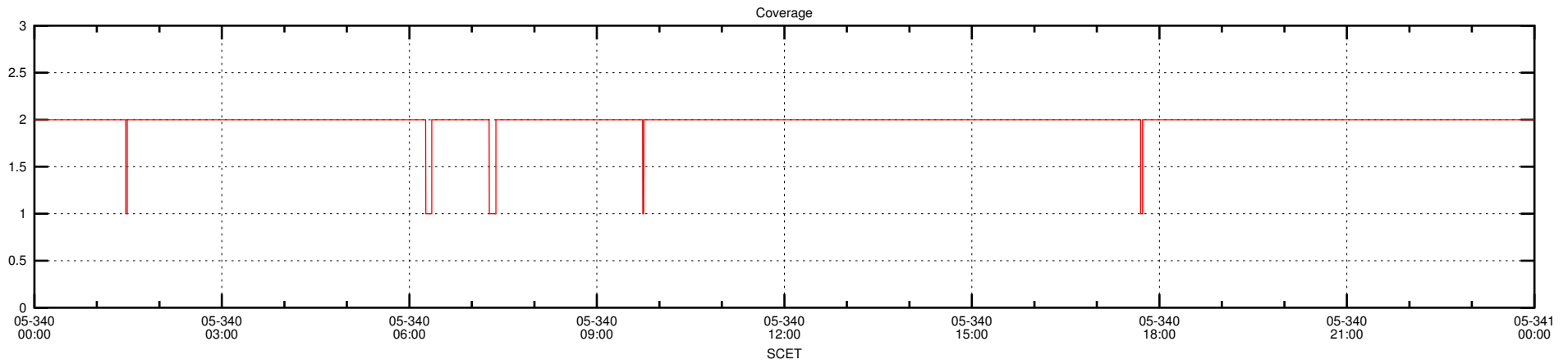
Z-Axis



# CK #2 S/C Body Rates (DOY 340-341)

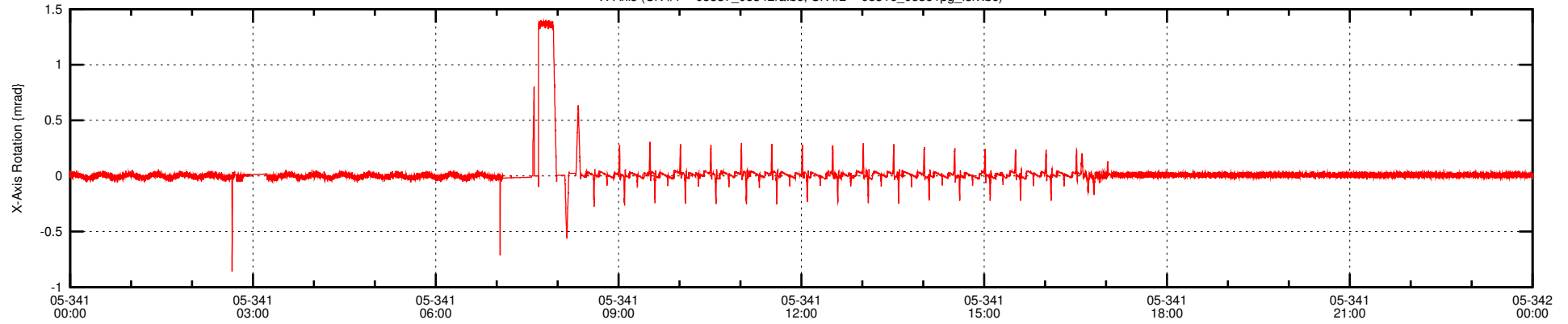


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 340-341)

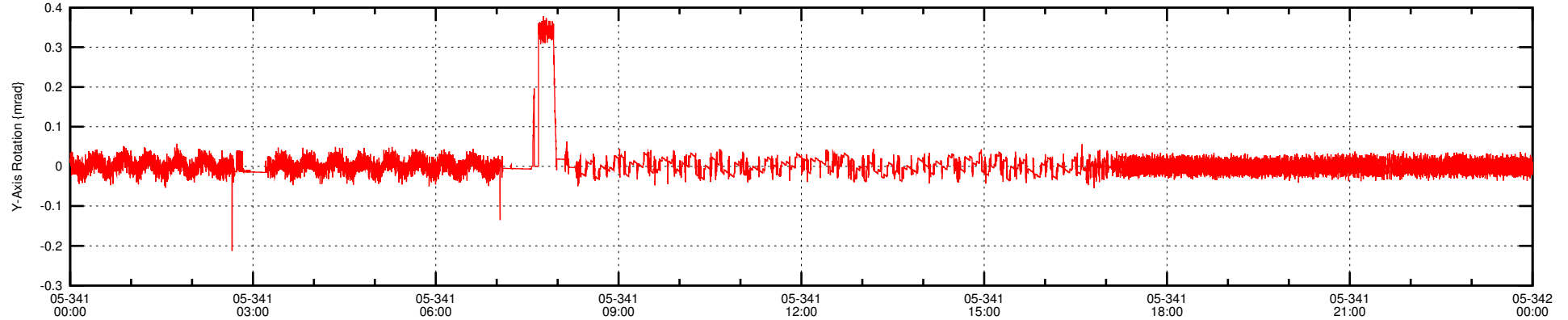


# Rotation From CK #2 to CK #1 (DOY 341-341)

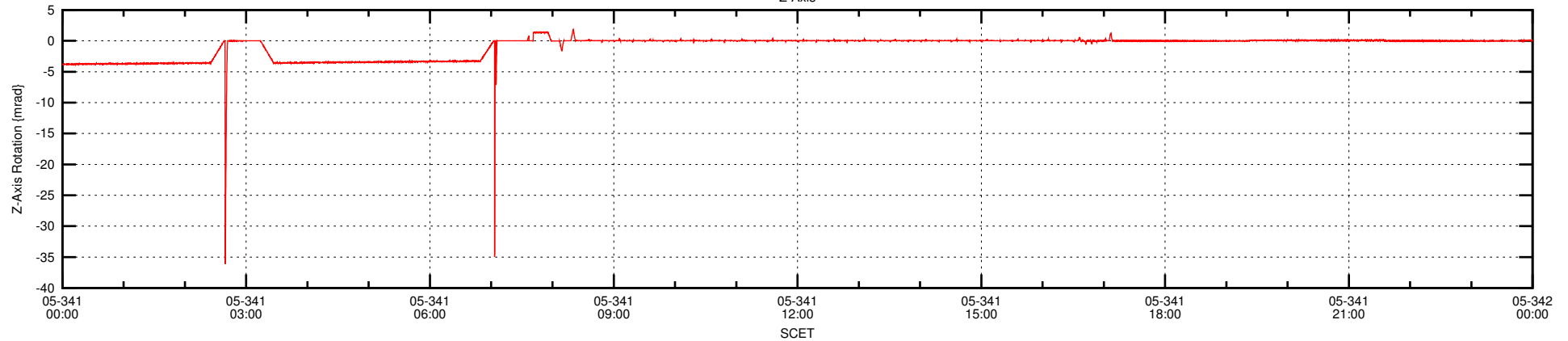
X-Axis (CK #1 = 05337\_05342ra.bc; CK #2 = 05316\_05351pg\_fsiv.bc)



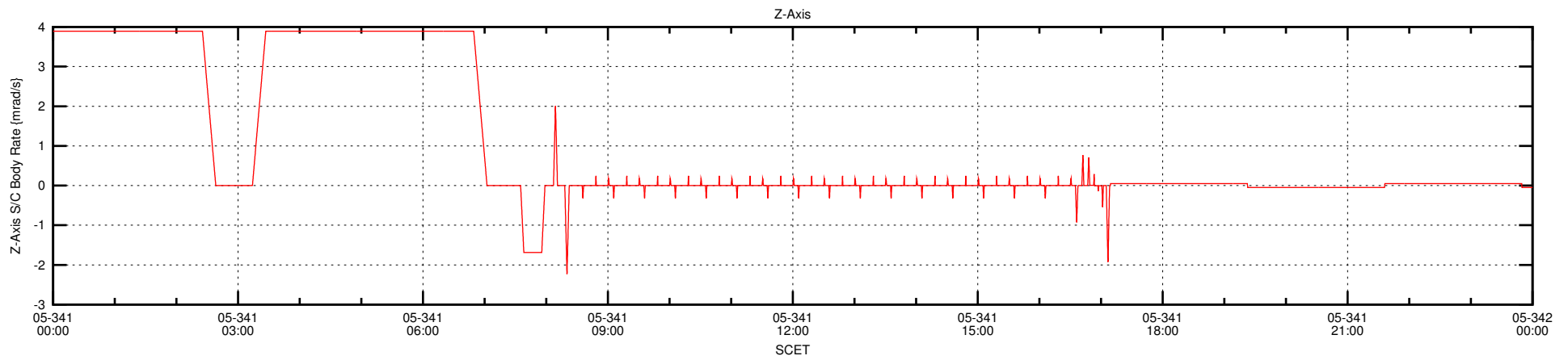
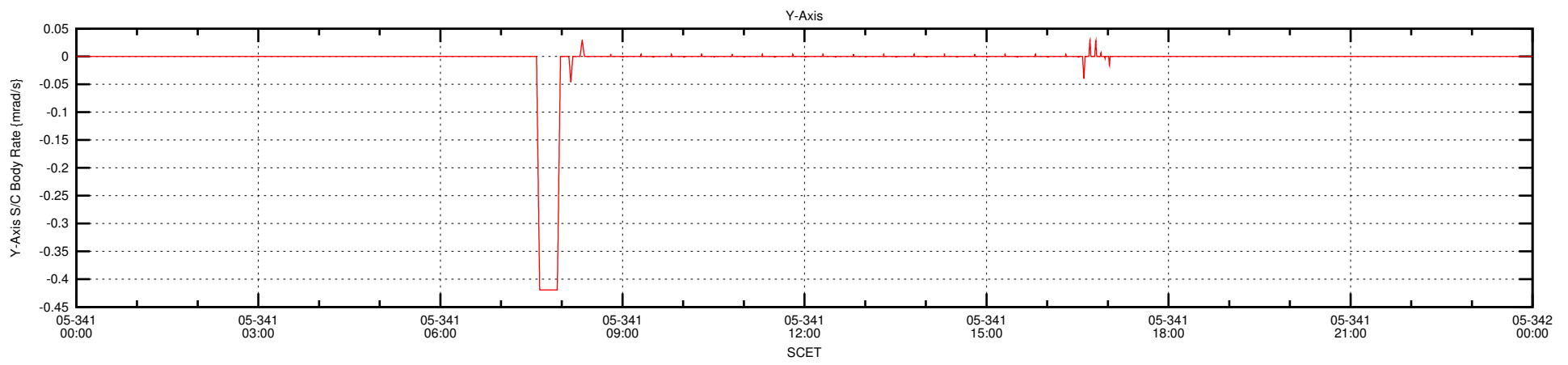
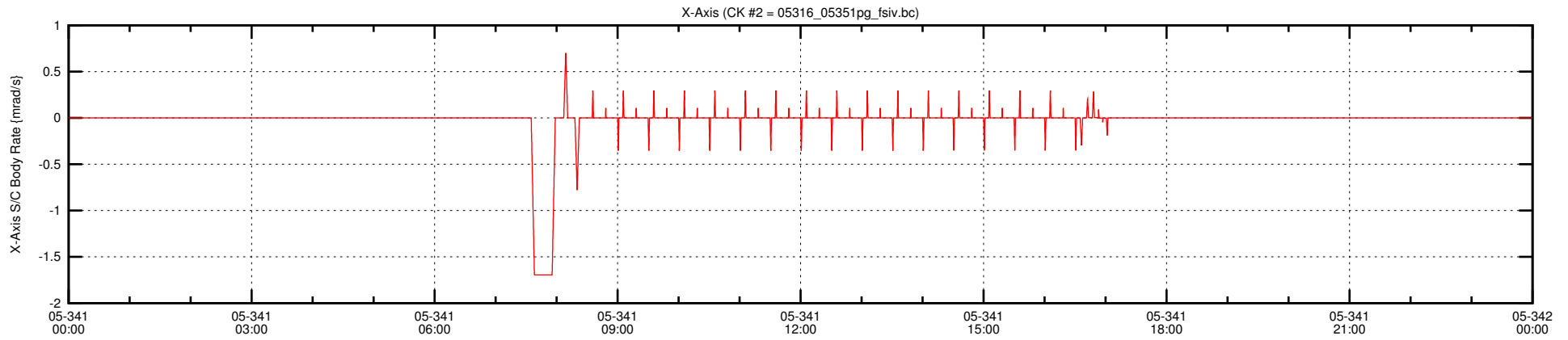
Y-Axis



Z-Axis



# CK #2 S/C Body Rates (DOY 341-341)



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 341-341)

