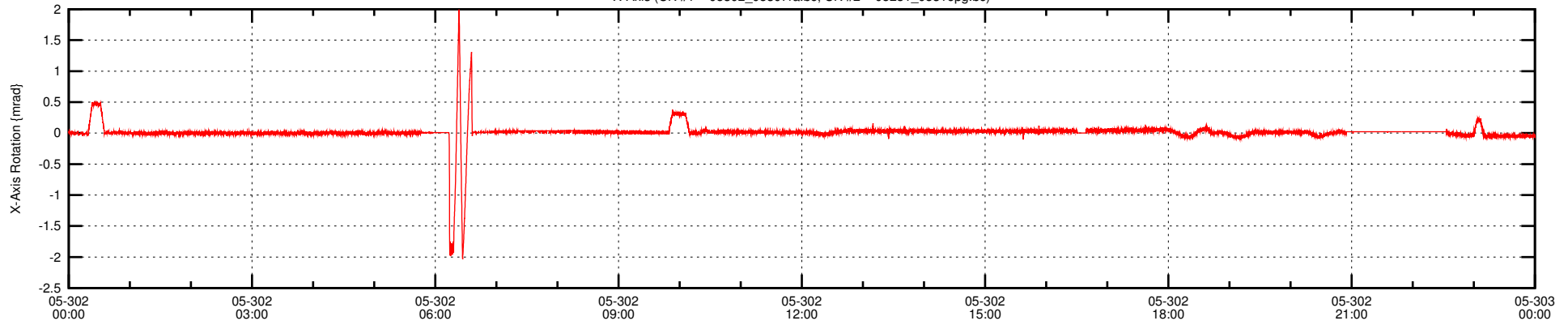
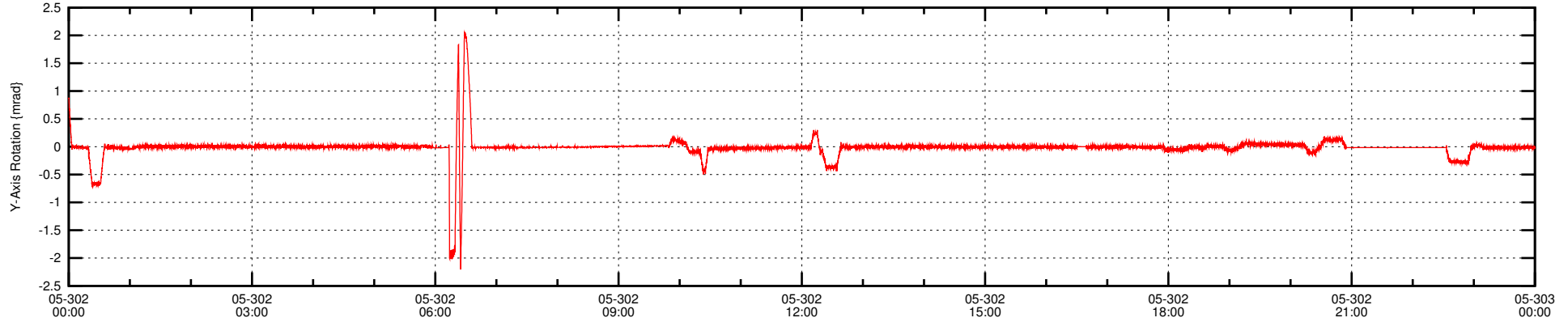


Rotation From CK #2 to CK #1 (DOY 302-303)

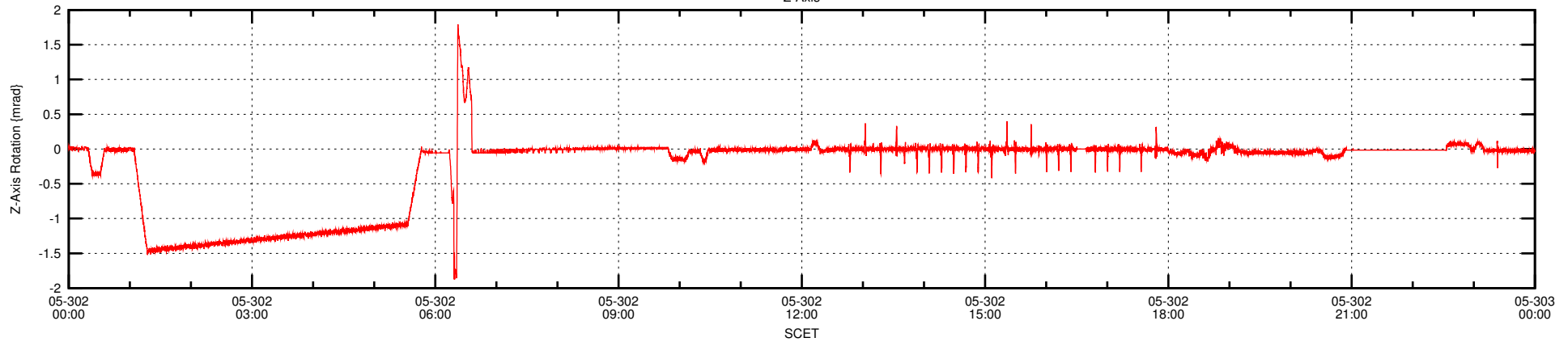
X-Axis (CK #1 = 05302_05307ra.bc; CK #2 = 05281_05316pg.bc)



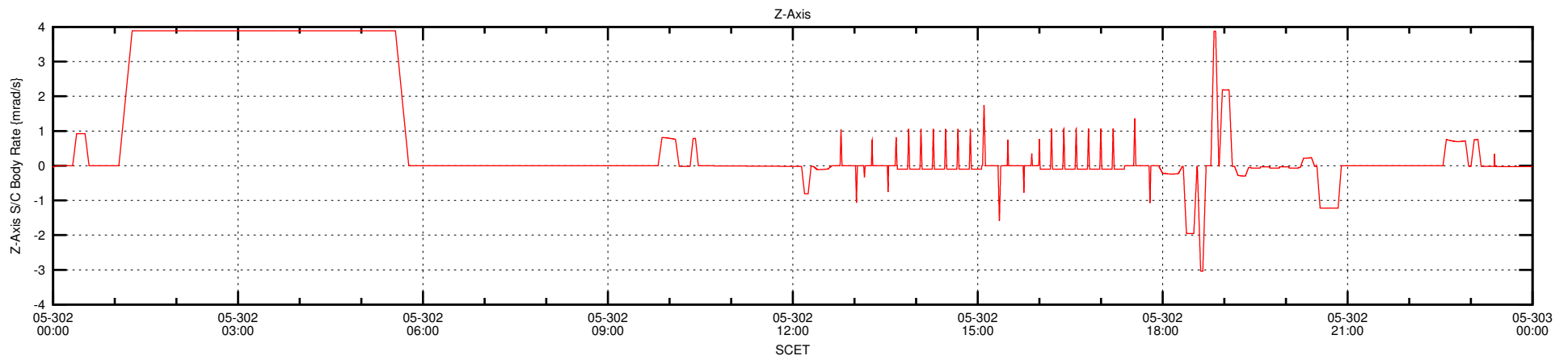
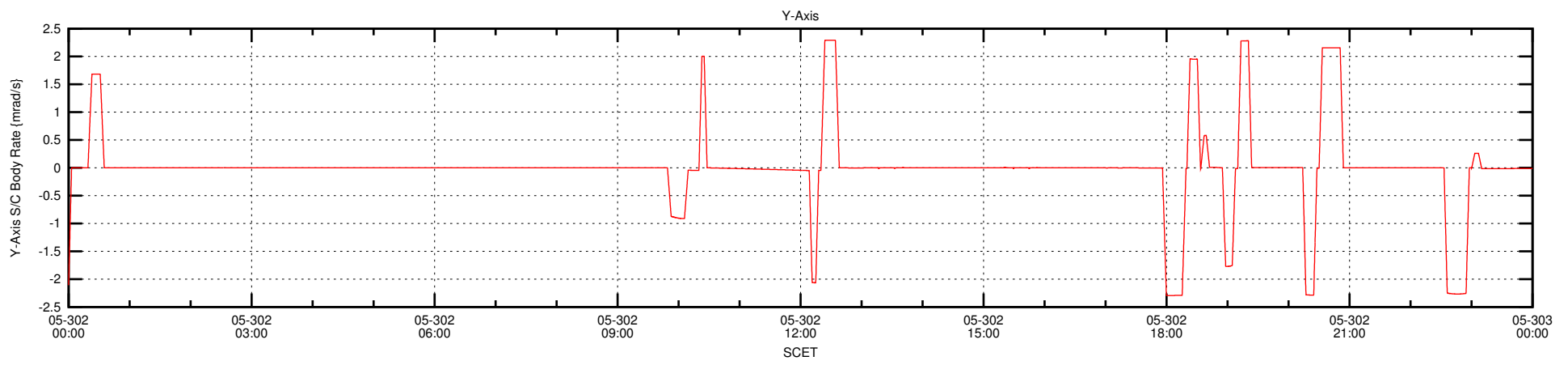
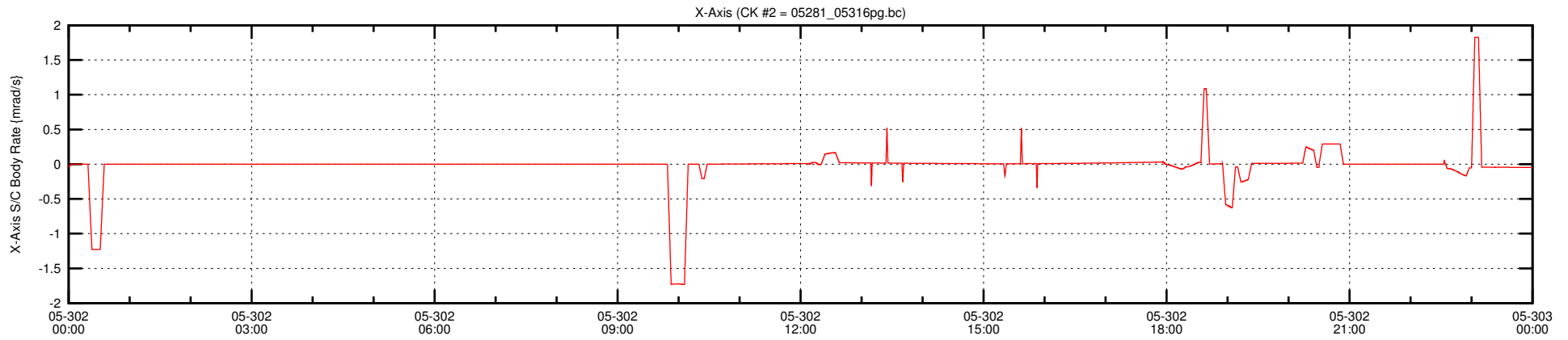
Y-Axis



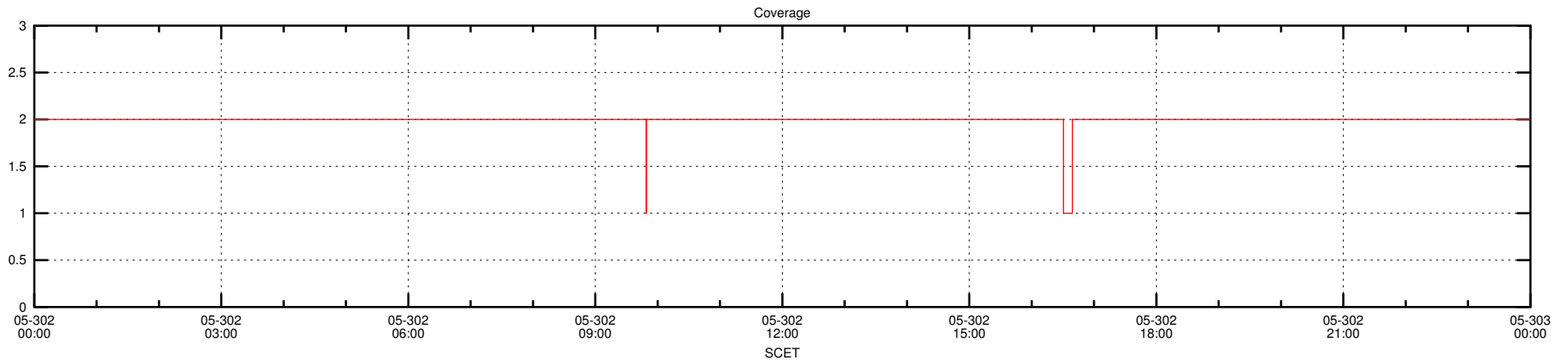
Z-Axis



CK #2 S/C Body Rates (DOY 302-303)

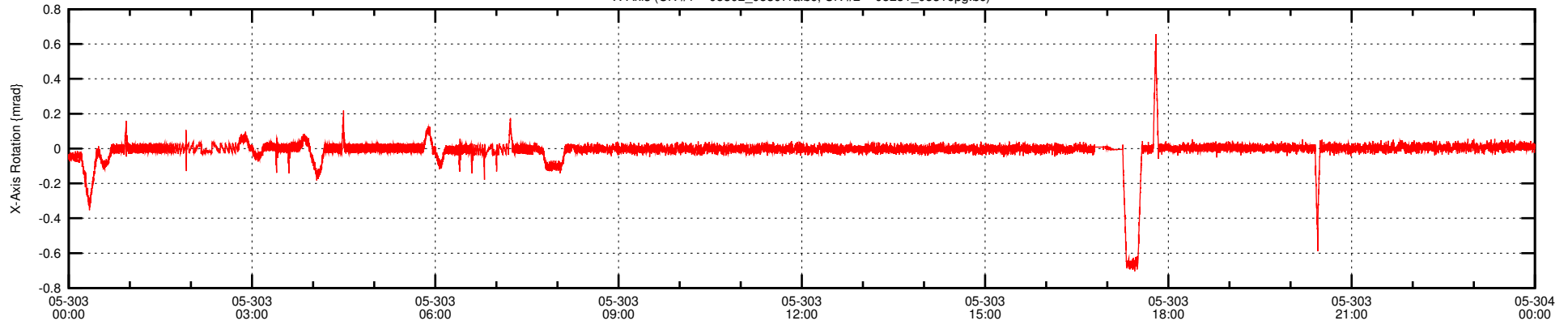


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 302-303)

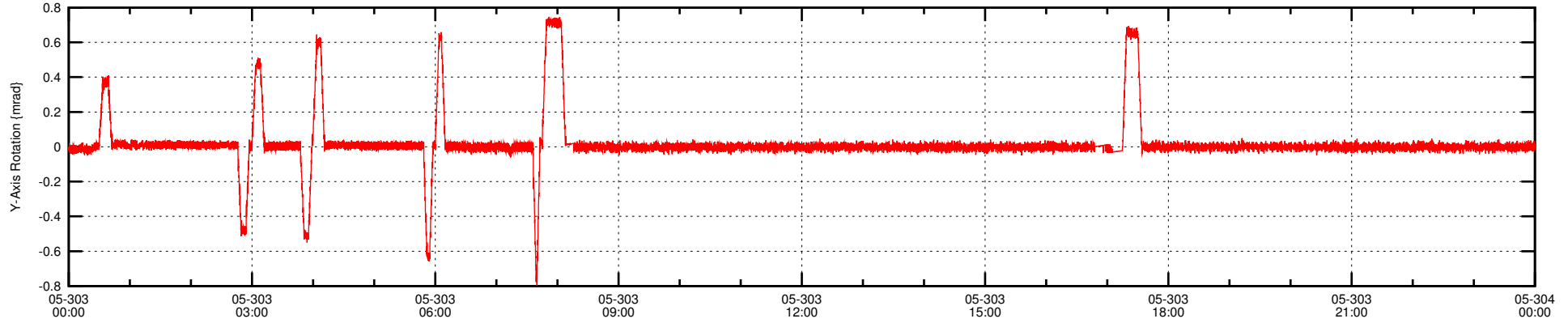


Rotation From CK #2 to CK #1 (DOY 303-304)

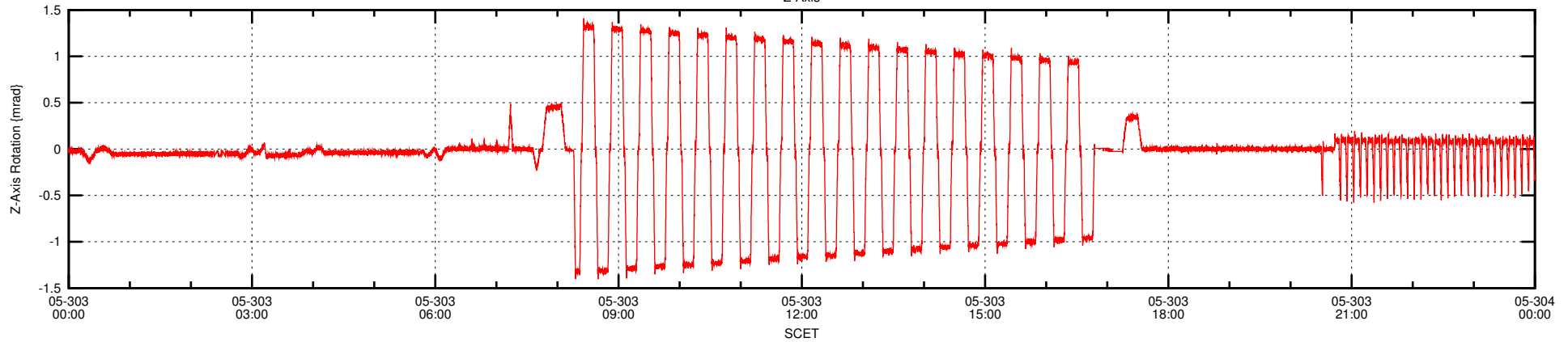
X-Axis (CK #1 = 05302_05307ra.bc; CK #2 = 05281_05316pg.bc)



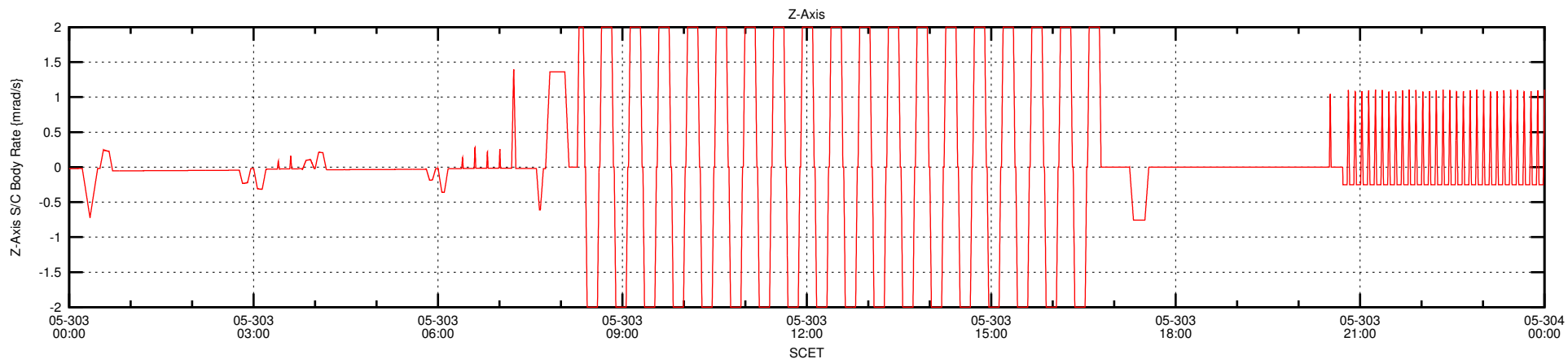
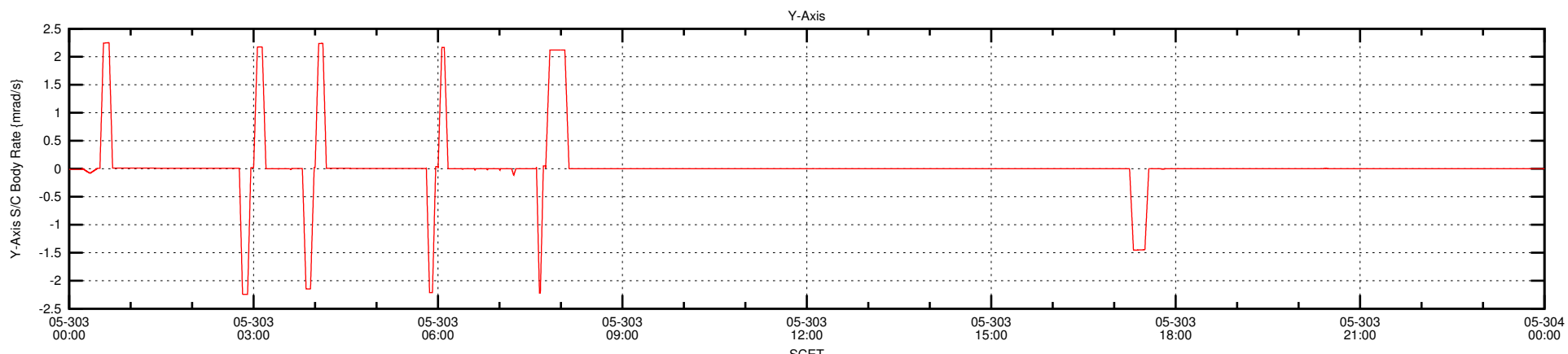
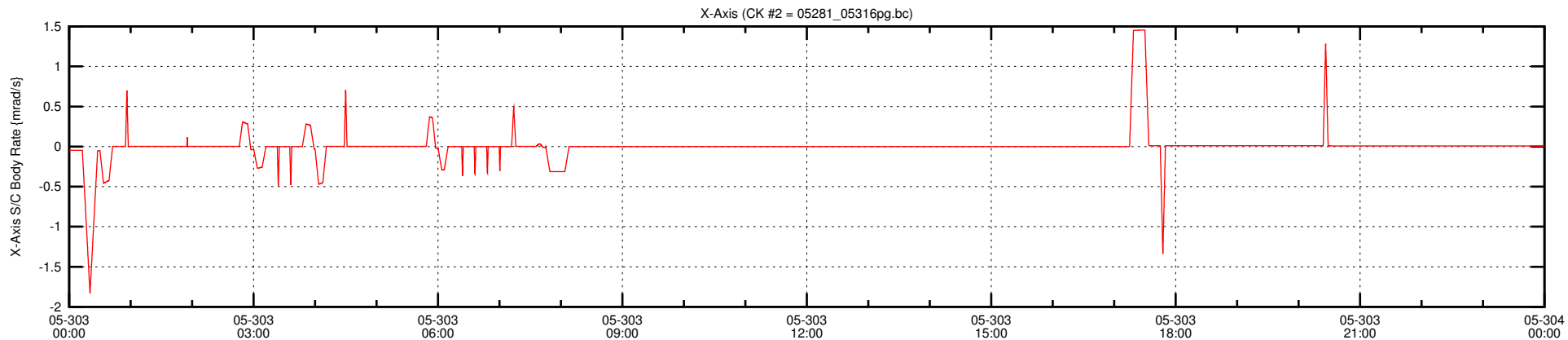
Y-Axis



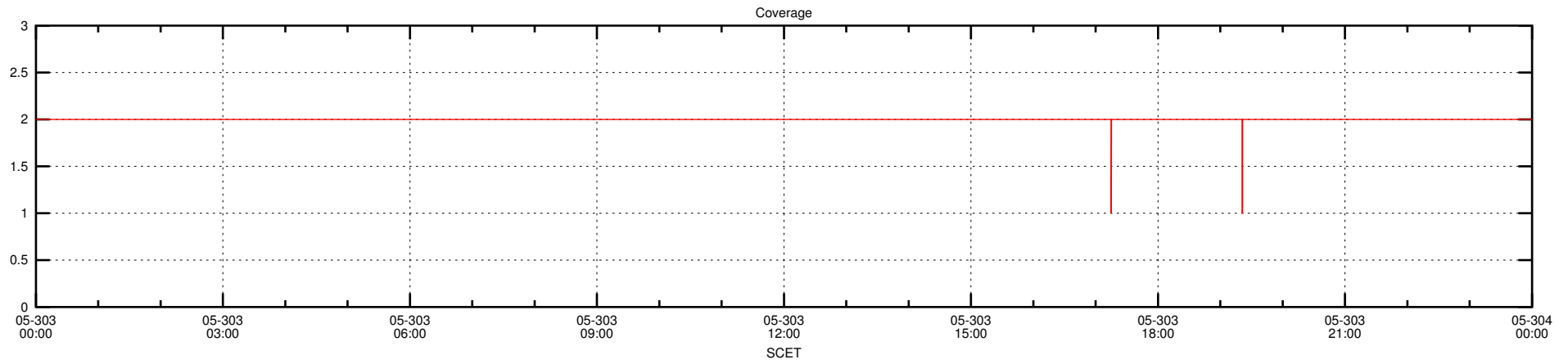
Z-Axis



CK #2 S/C Body Rates (DOY 303-304)

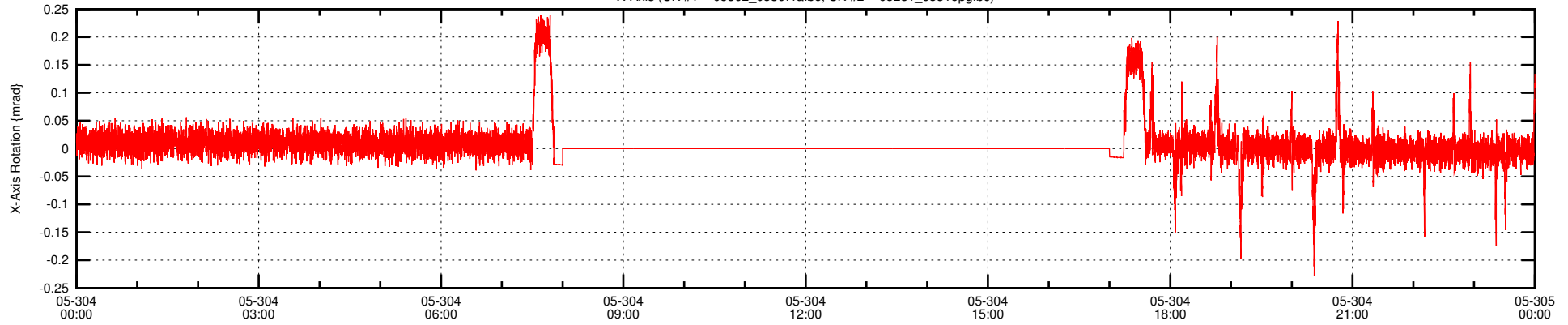


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 303-304)

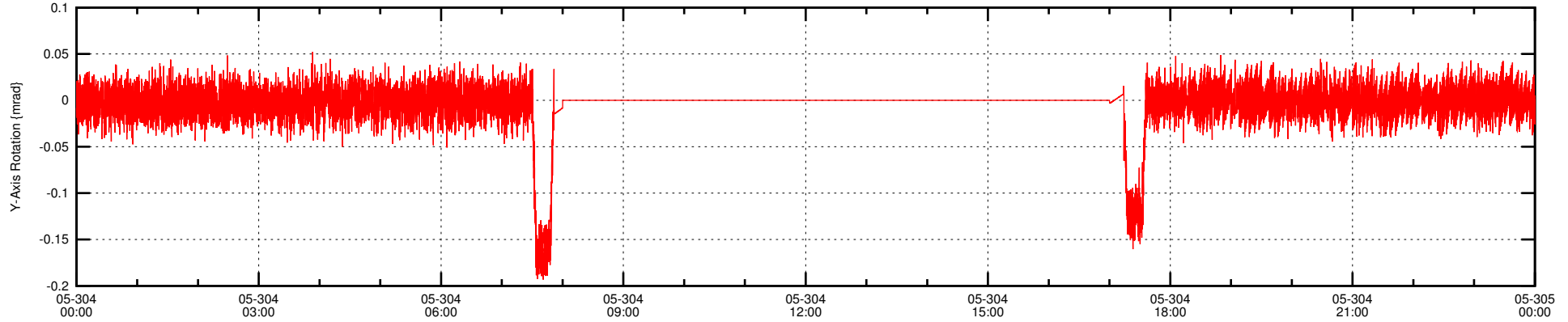


Rotation From CK #2 to CK #1 (DOY 304-305)

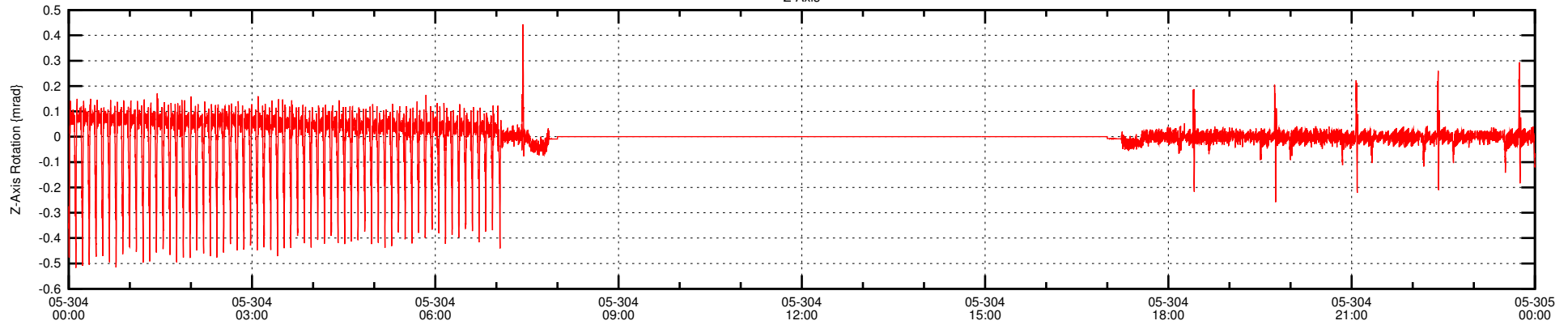
X-Axis (CK #1 = 05302_05307ra.bc; CK #2 = 05281_05316pg.bc)



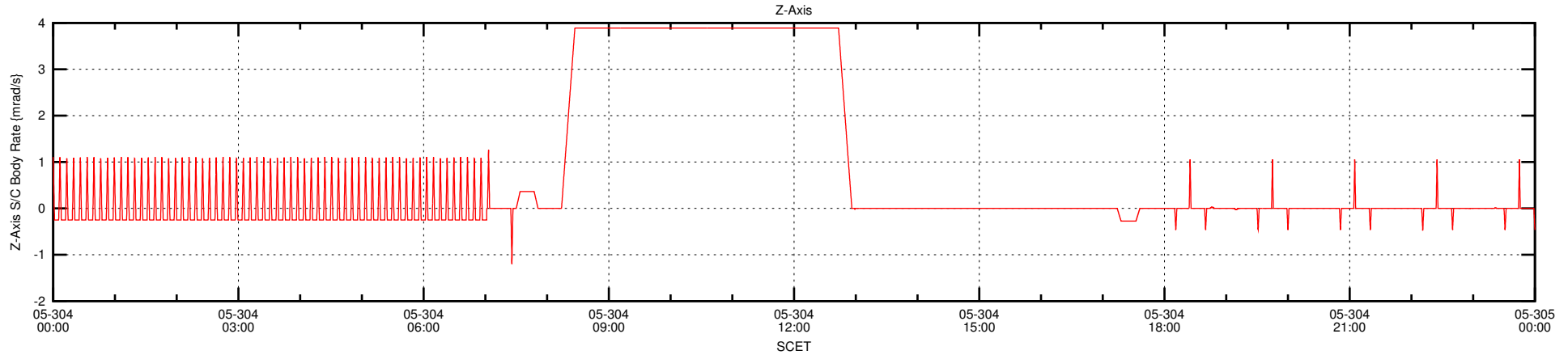
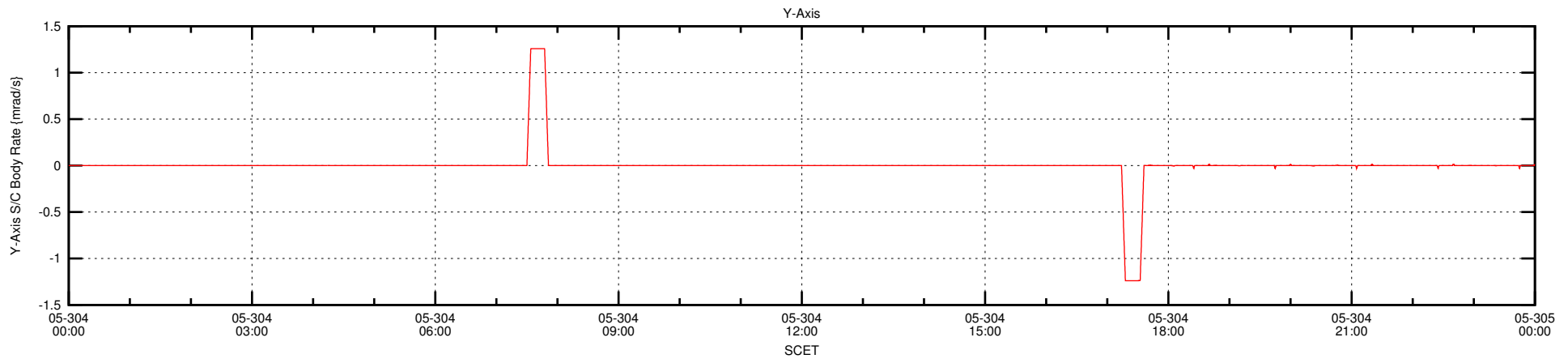
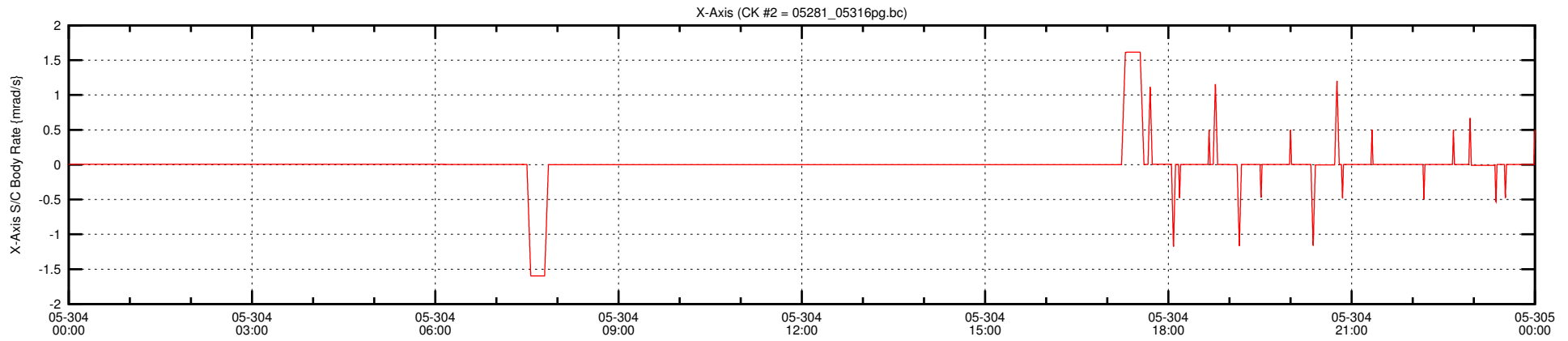
Y-Axis



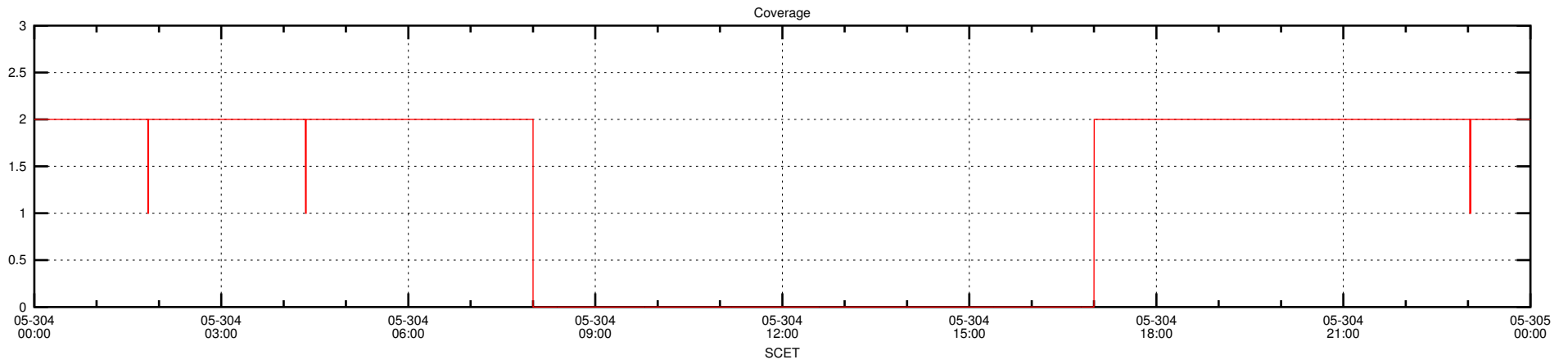
Z-Axis



CK #2 S/C Body Rates (DOY 304-305)

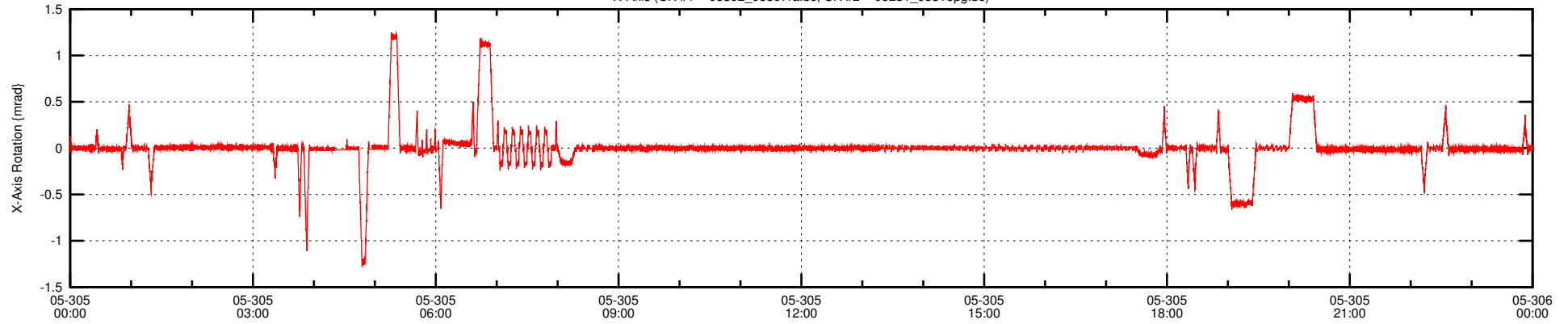


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 304-305)

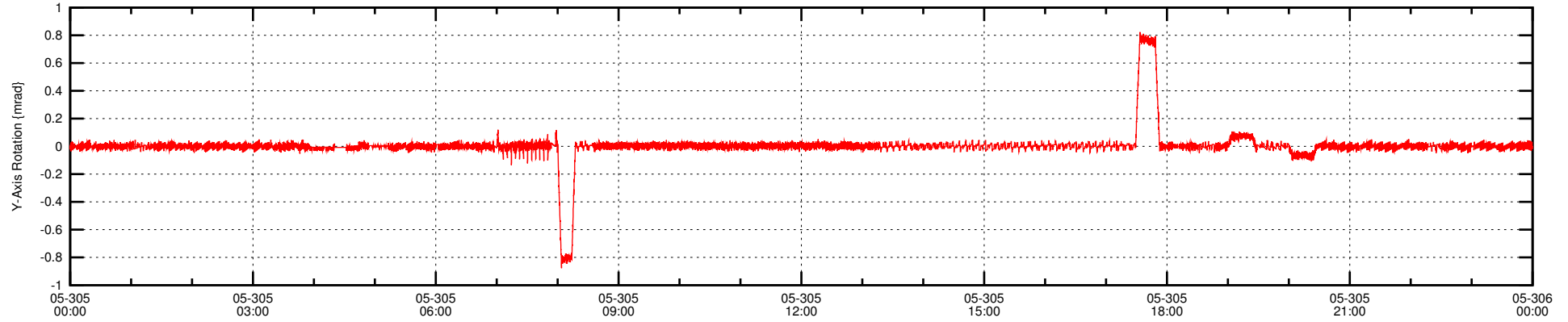


Rotation From CK #2 to CK #1 (DOY 305-306)

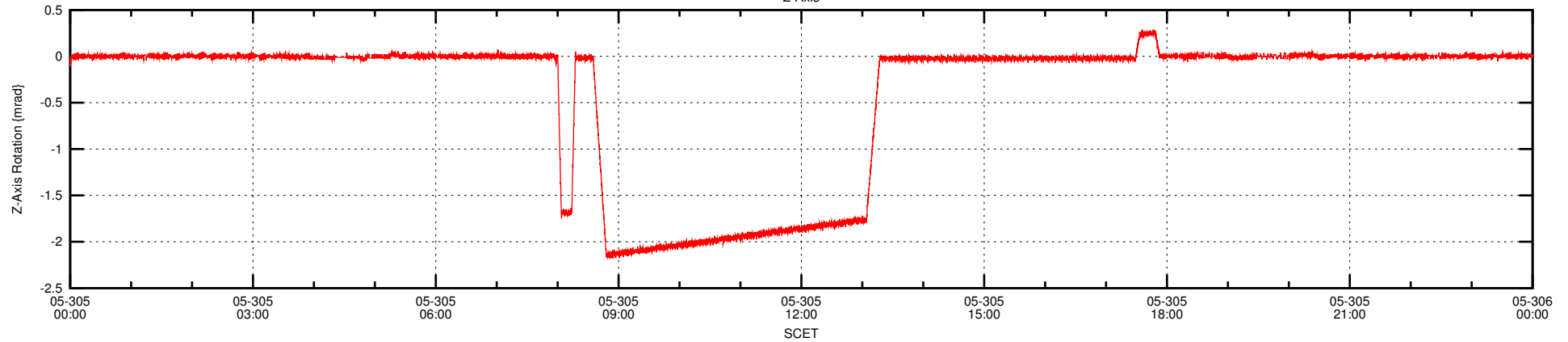
X-Axis (CK #1 = 05302_05307ra.bc; CK #2 = 05281_05316pg.bc)



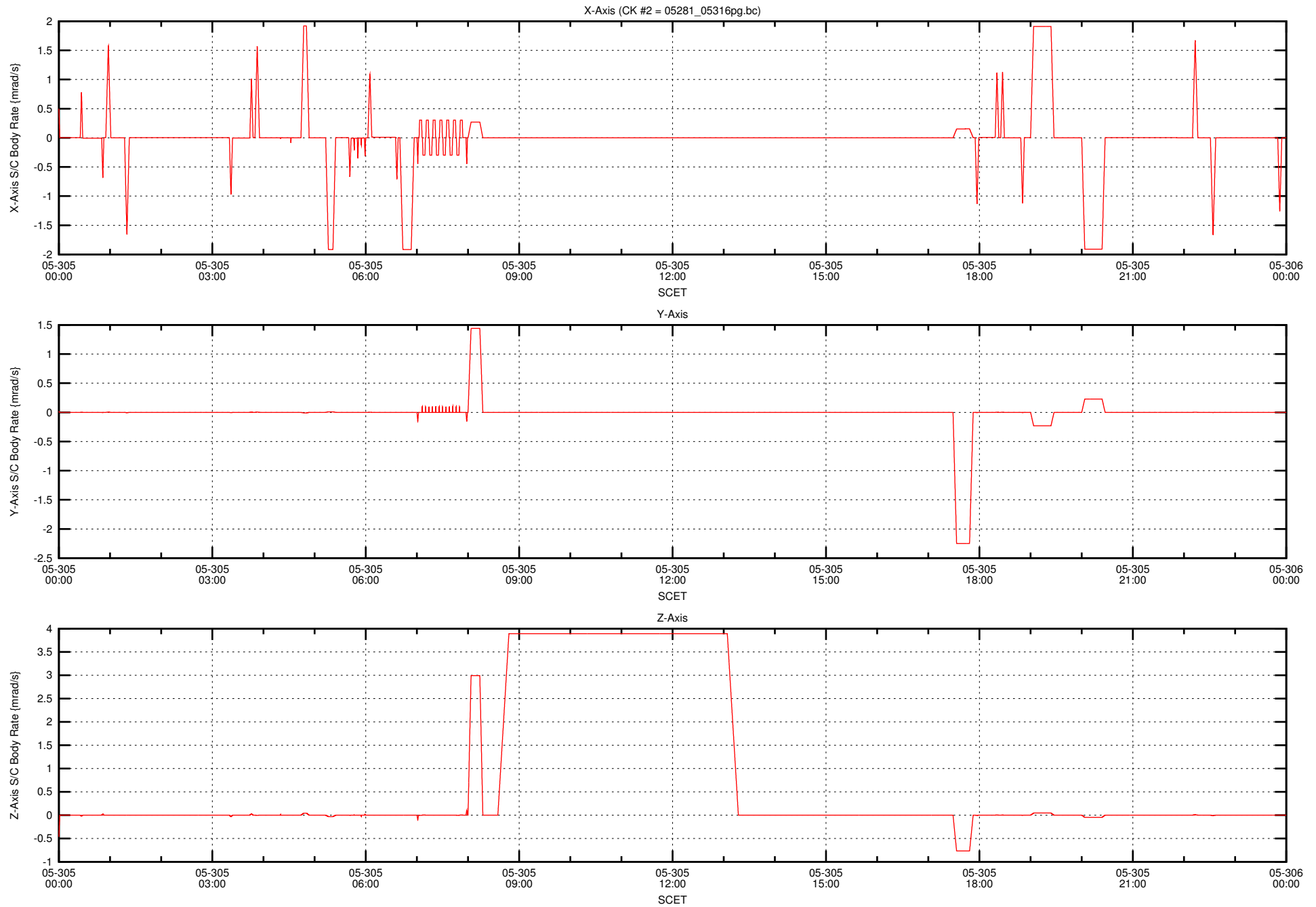
Y-Axis



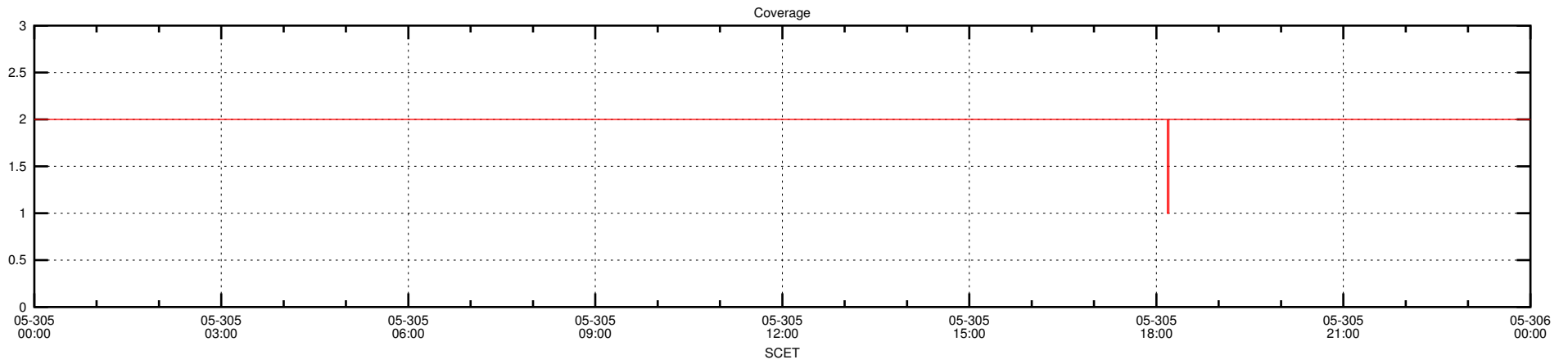
Z-Axis



CK #2 S/C Body Rates (DOY 305-306)

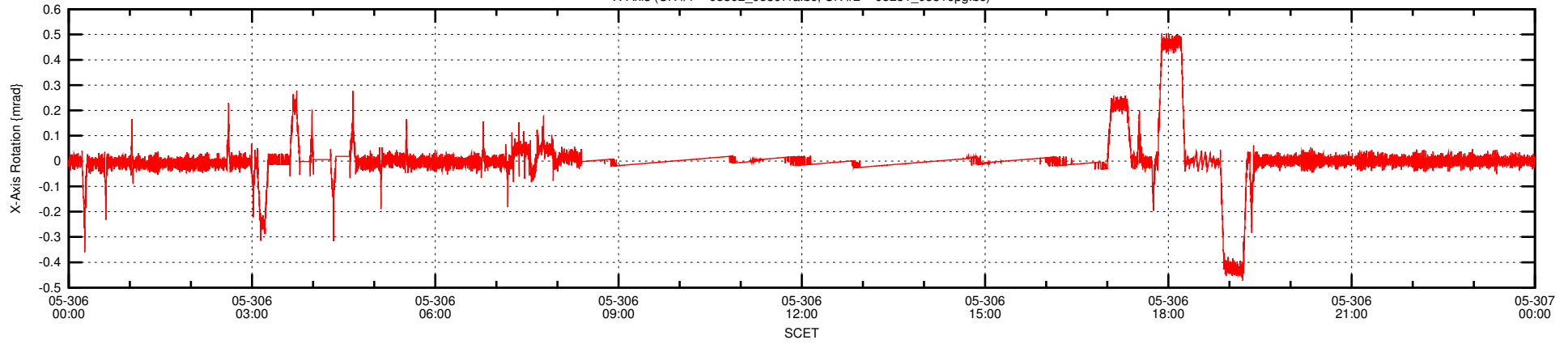


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 305-306)

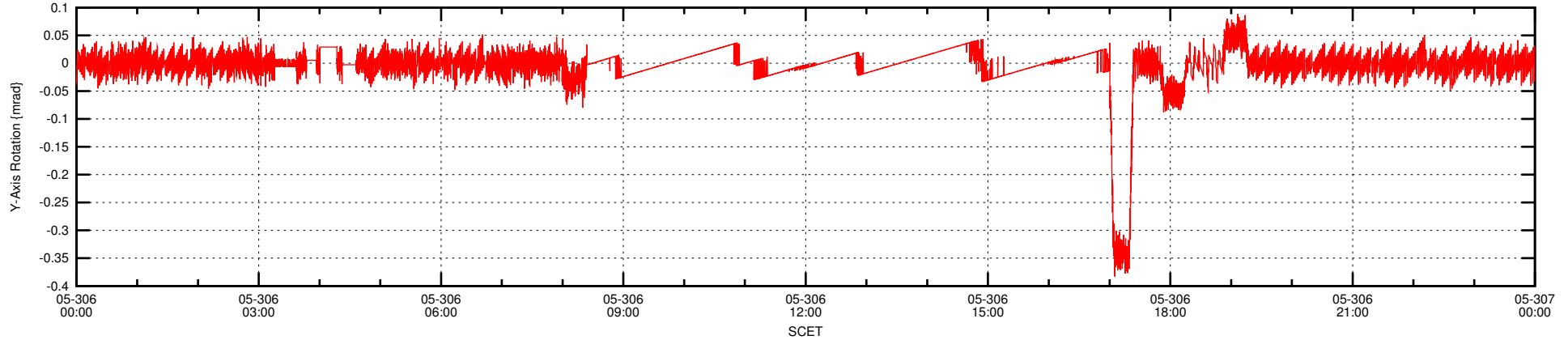


Rotation From CK #2 to CK #1 (DOY 306-306)

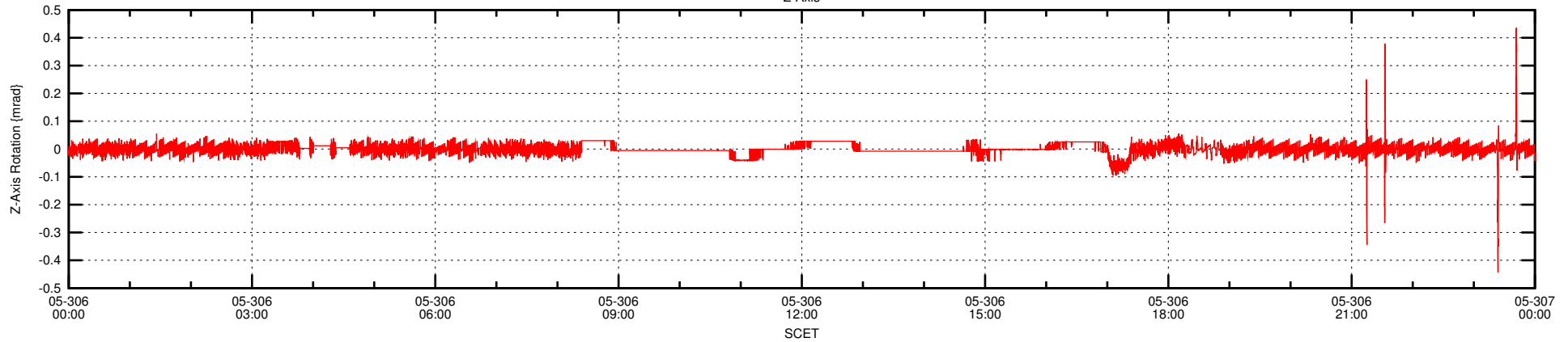
X-Axis (CK #1 = 05302_05307ra.bc; CK #2 = 05281_05316pg.bc)



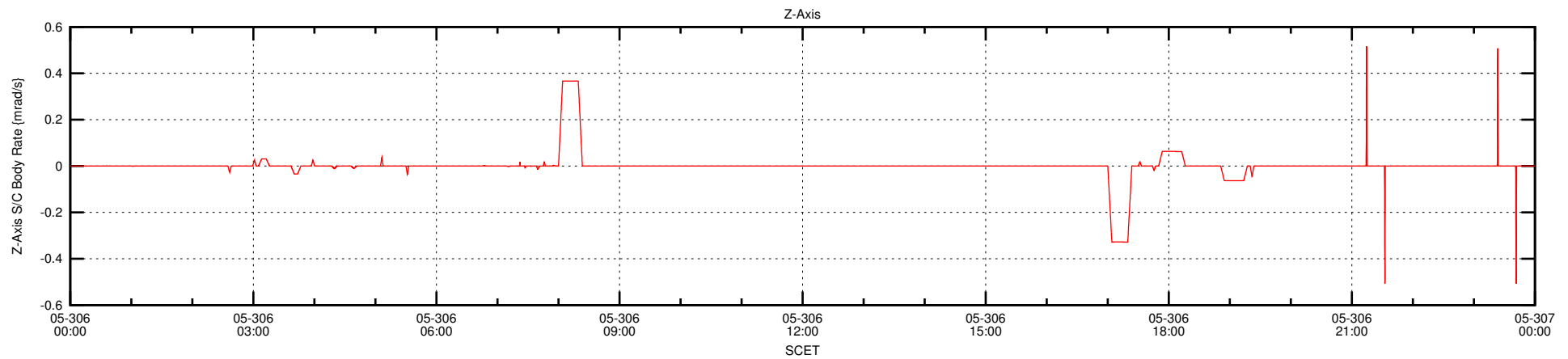
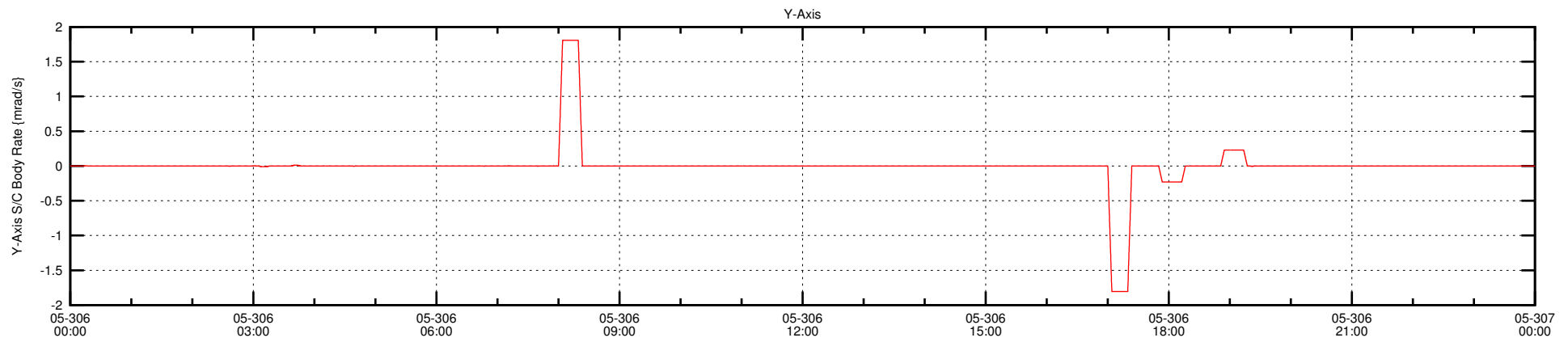
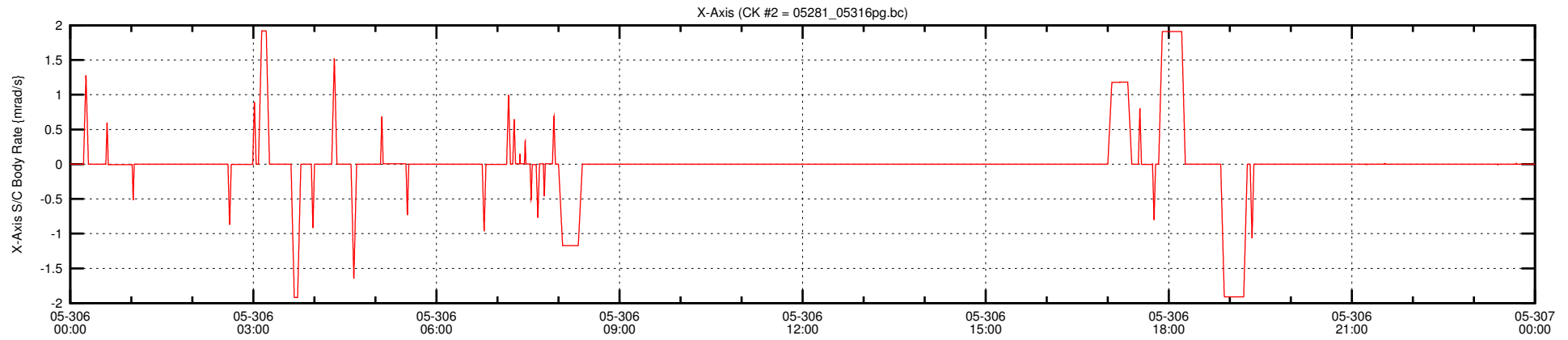
Y-Axis



Z-Axis



CK #2 S/C Body Rates (DOY 306-306)



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 306-306)

