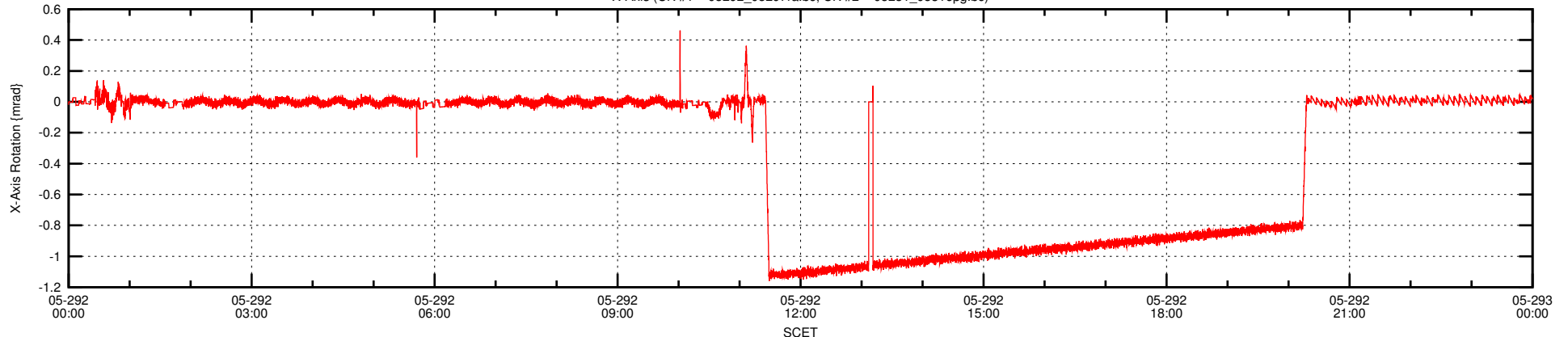
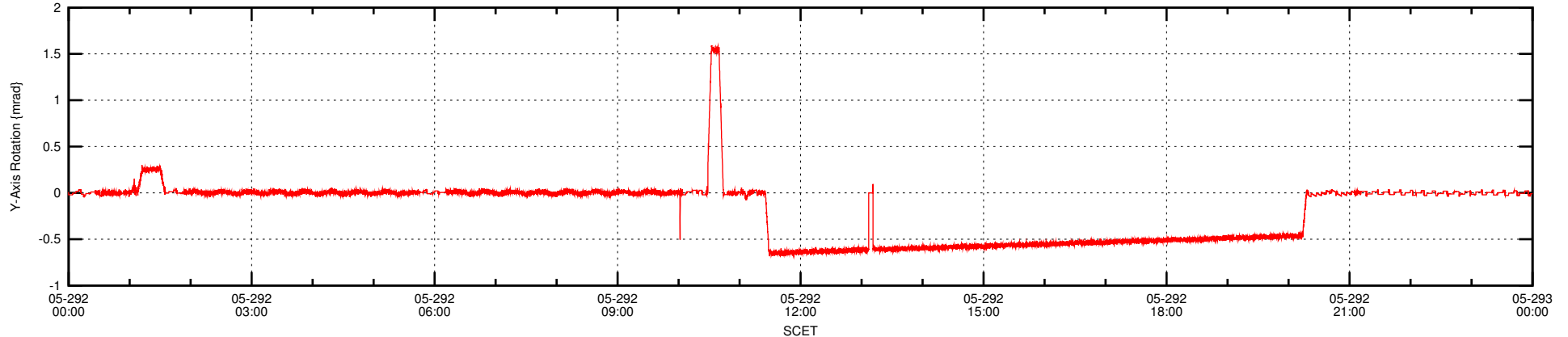


Rotation From CK #2 to CK #1 (DOY 292-293)

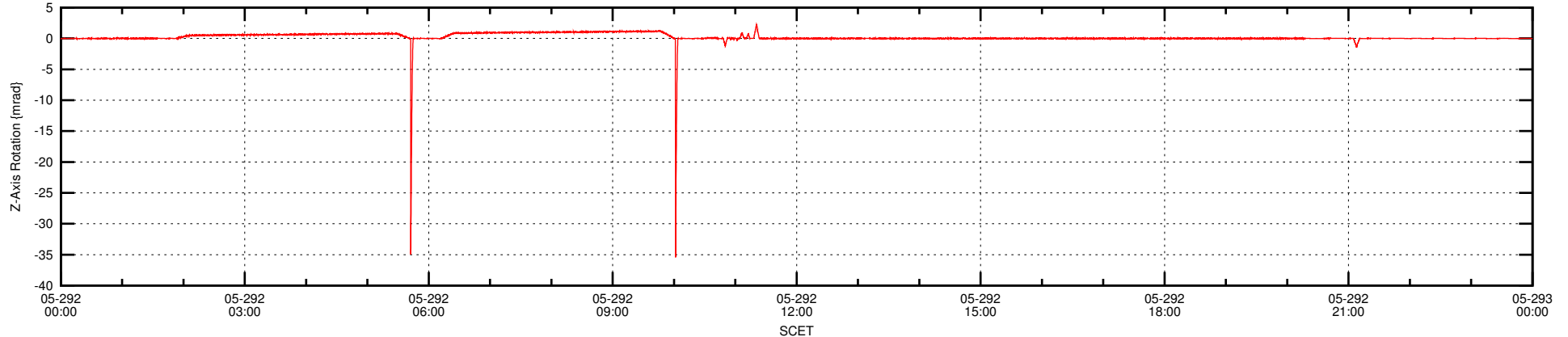
X-Axis (CK #1 = 05292_05297ra.bc; CK #2 = 05281_05316pg.bc)



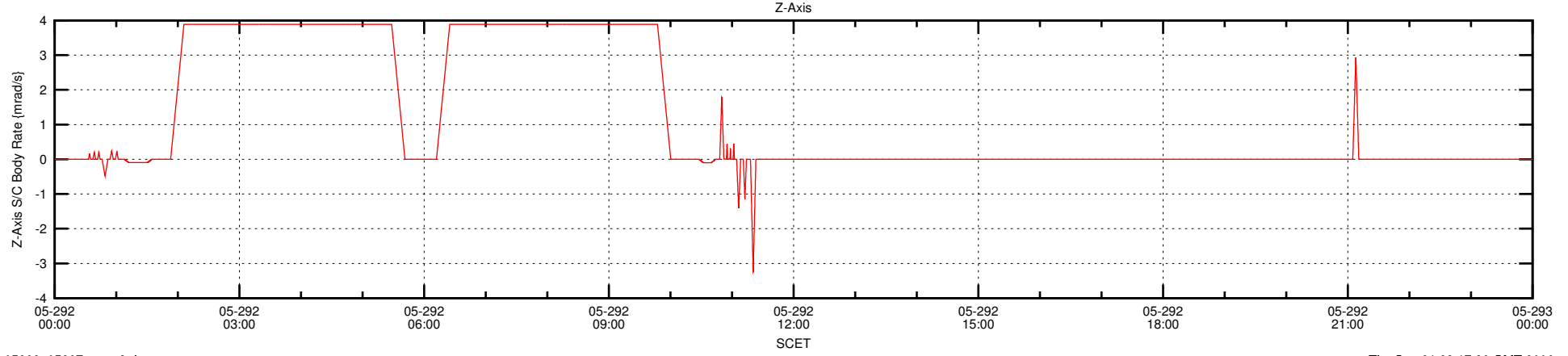
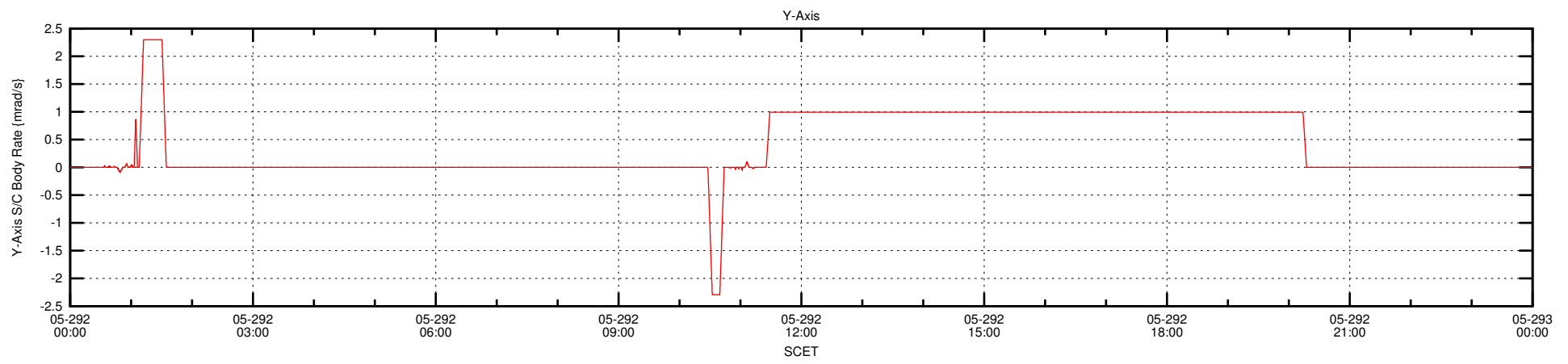
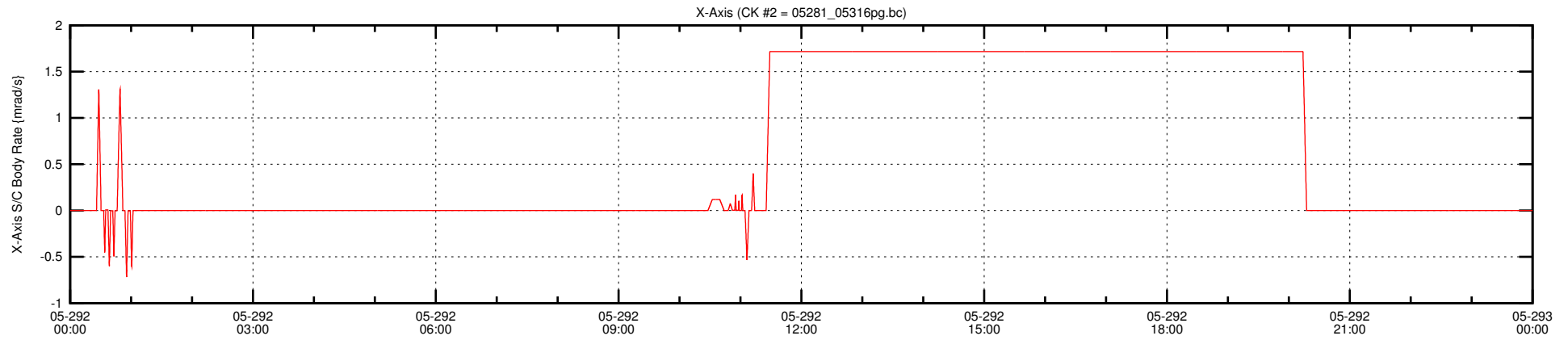
Y-Axis



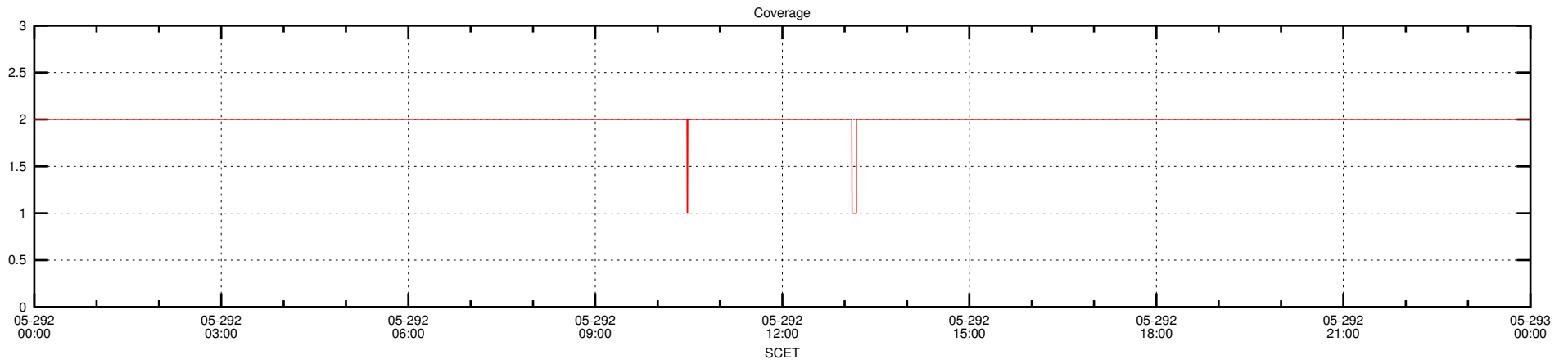
Z-Axis



CK #2 S/C Body Rates (DOY 292-293)

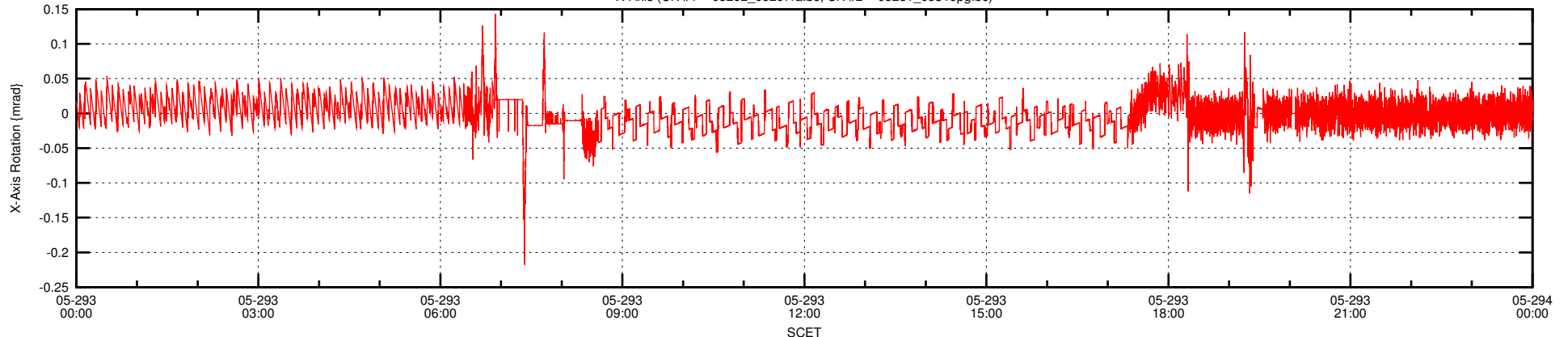


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 292-293)

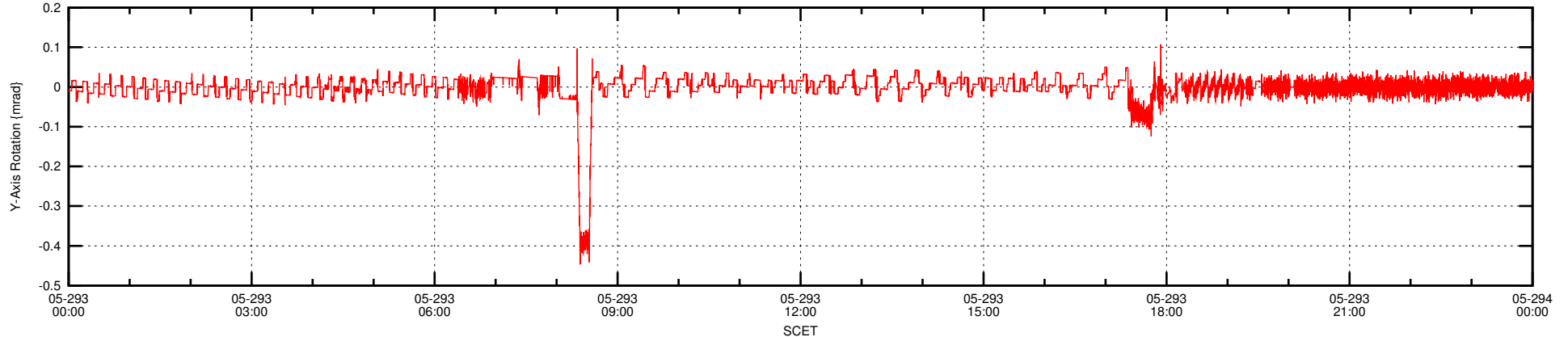


Rotation From CK #2 to CK #1 (DOY 293-294)

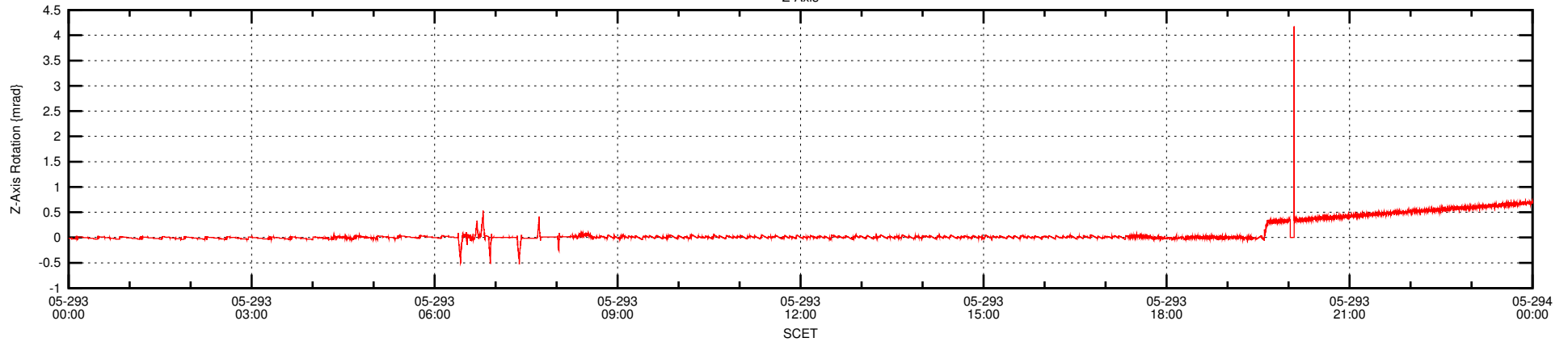
X-Axis (CK #1 = 05292_05297ra.bc; CK #2 = 05281_05316pg.bc)



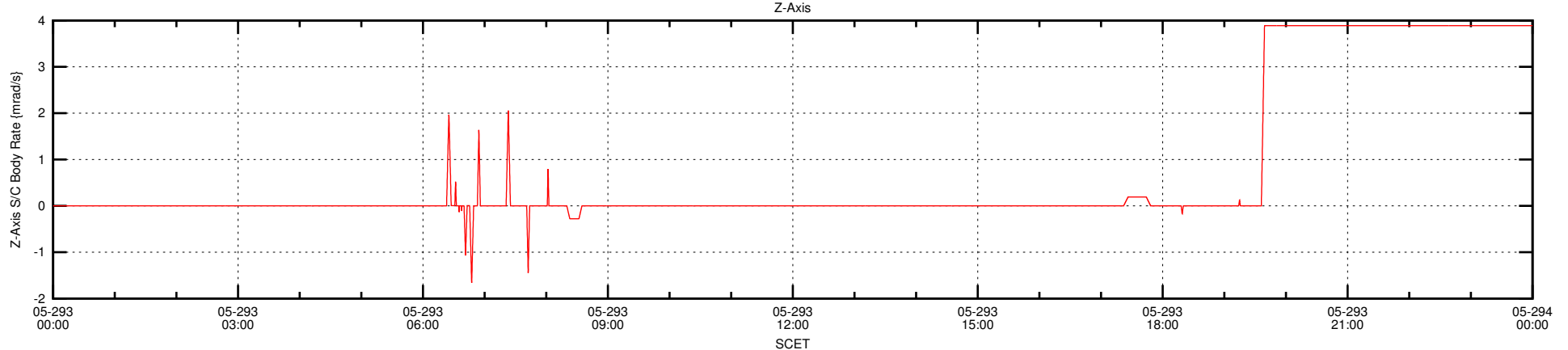
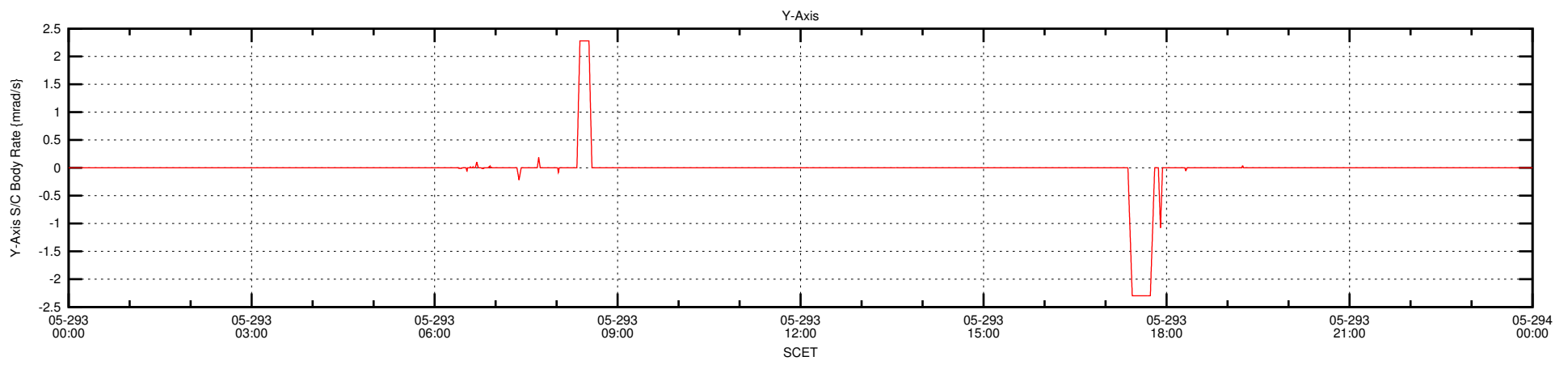
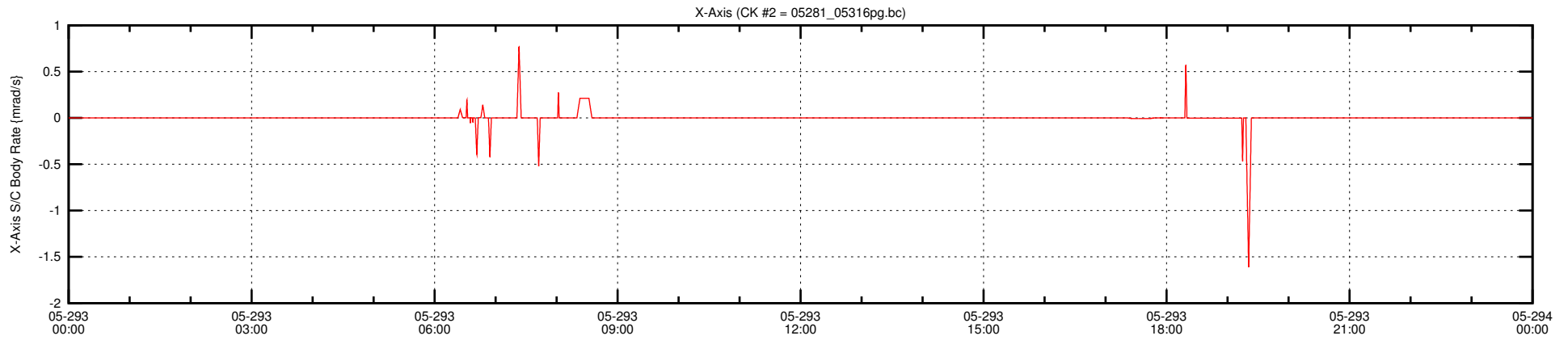
Y-Axis



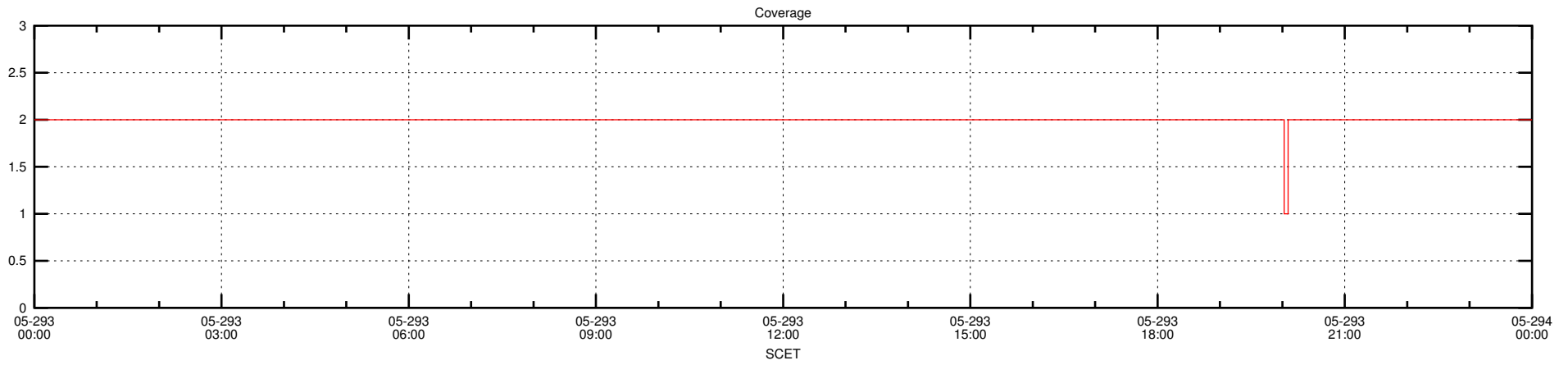
Z-Axis



CK #2 S/C Body Rates (DOY 293-294)

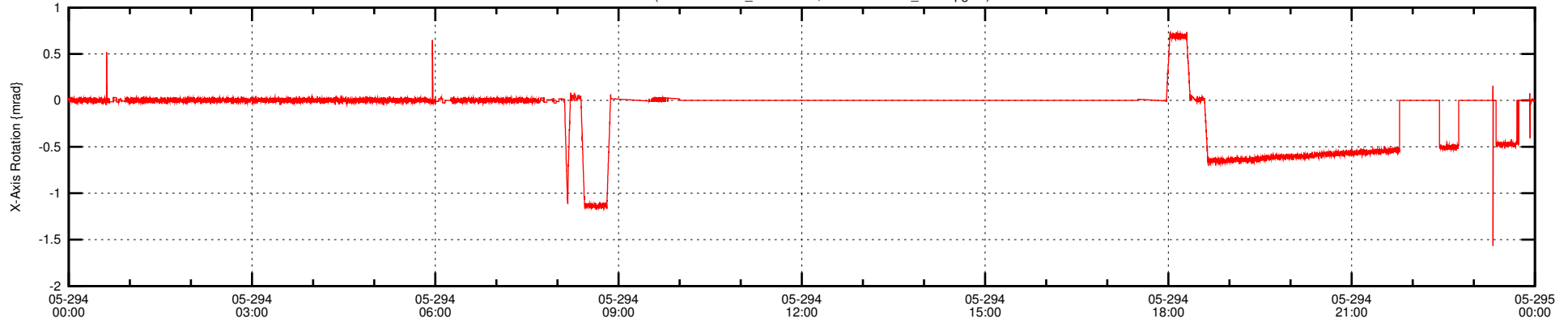


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 293-294)

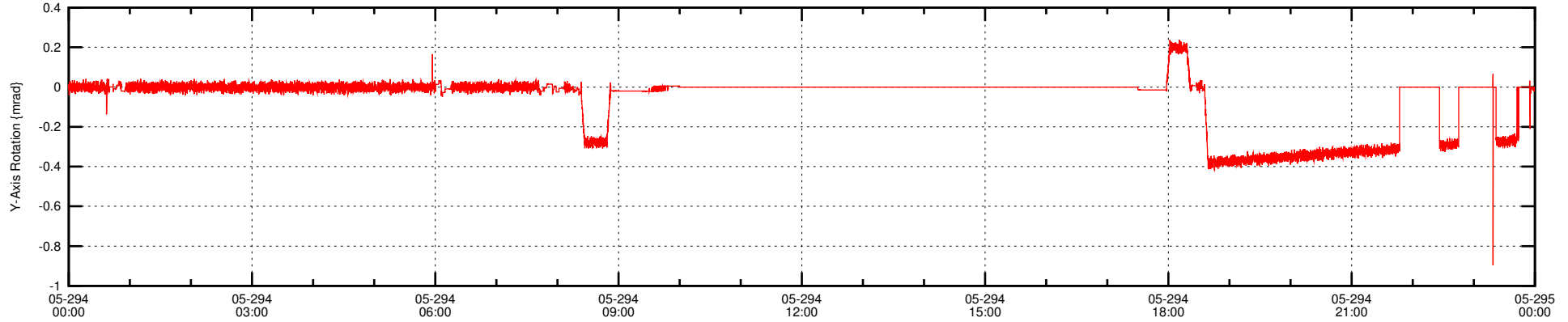


Rotation From CK #2 to CK #1 (DOY 294-295)

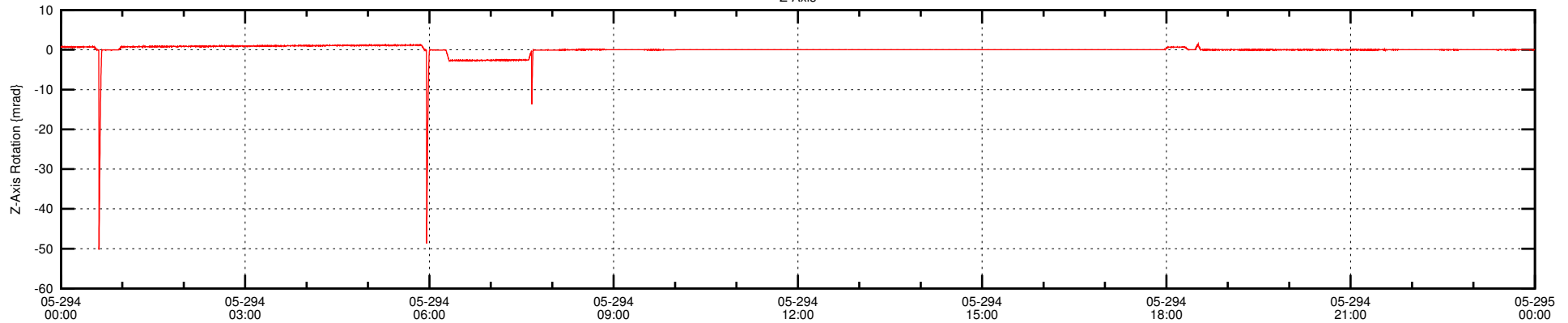
X-Axis (CK #1 = 05292_05297ra.bc; CK #2 = 05281_05316pg.bc)



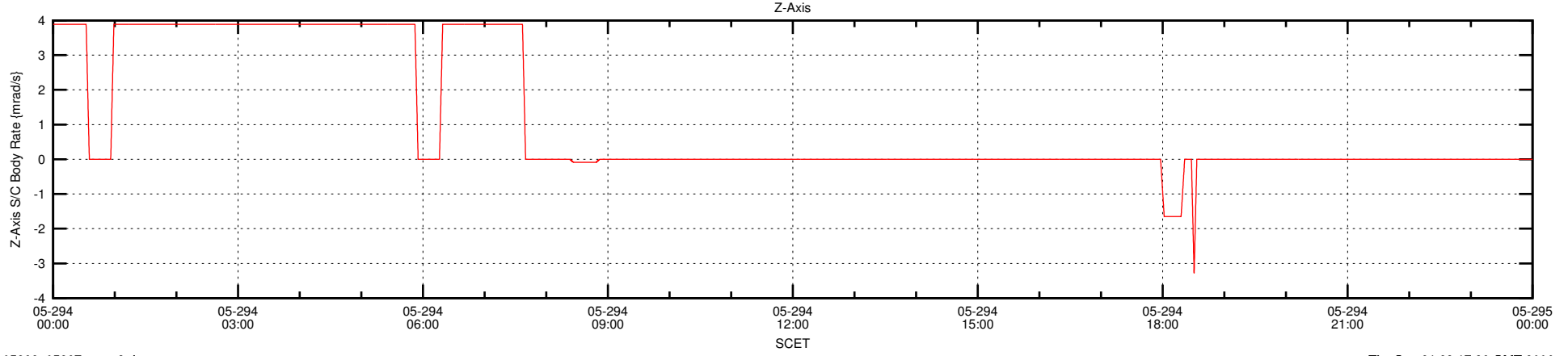
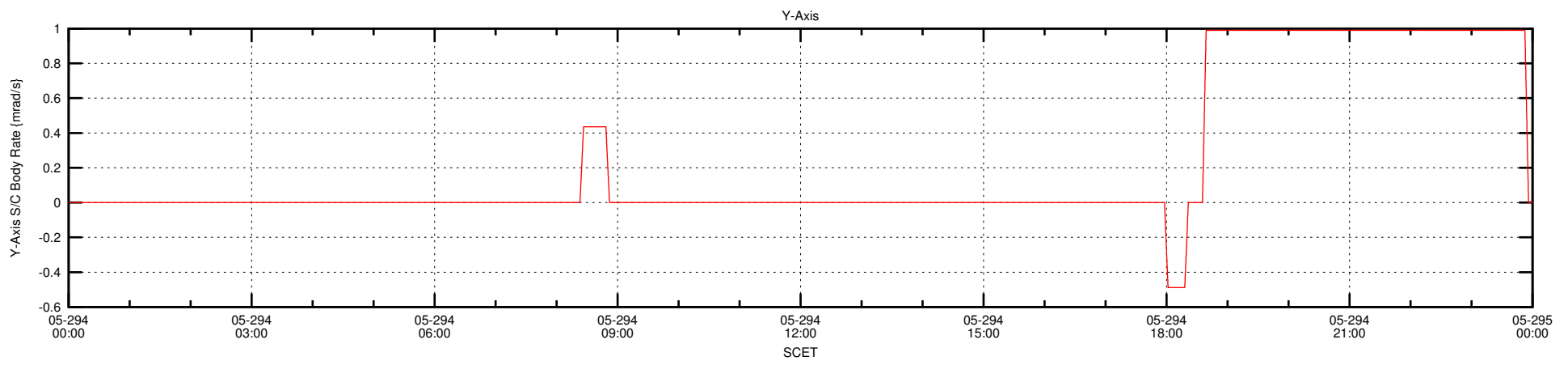
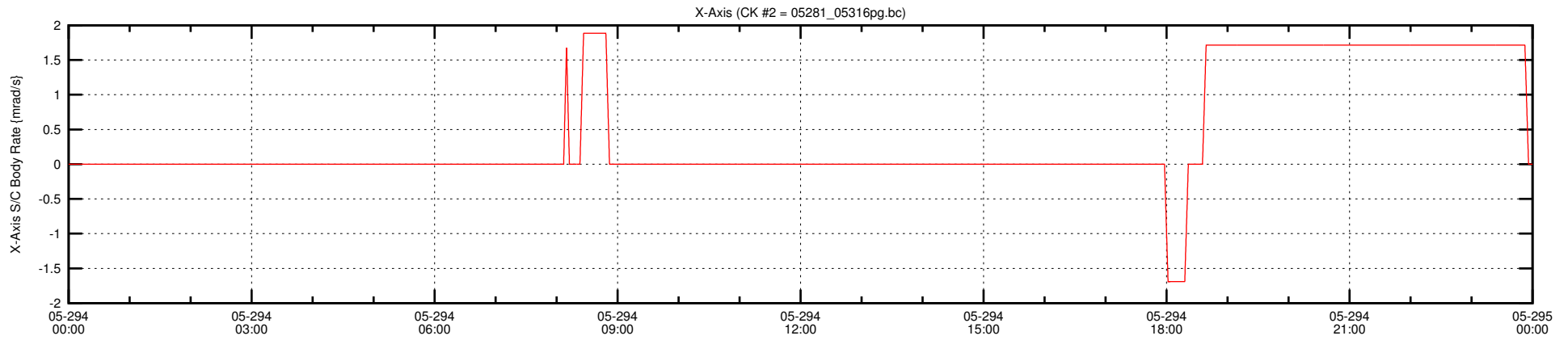
Y-Axis



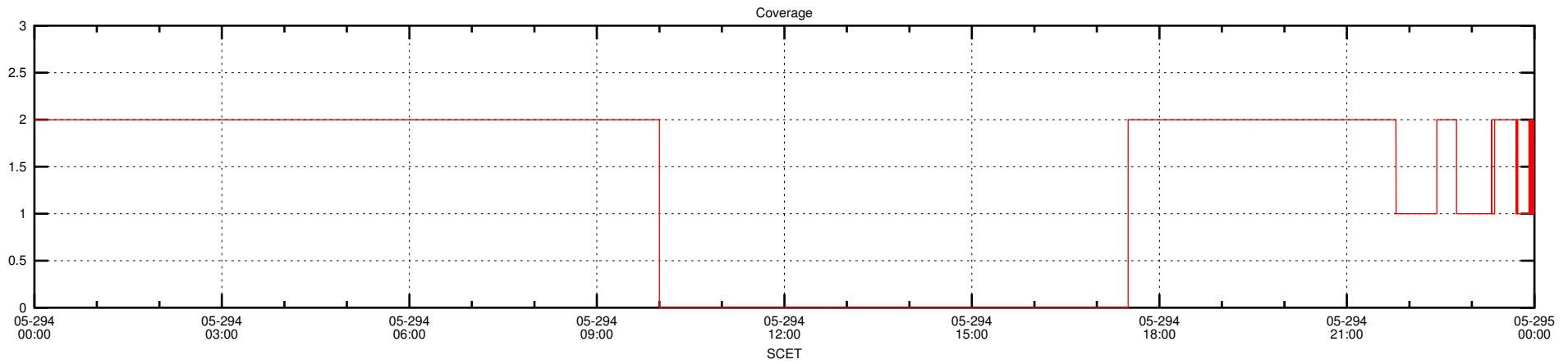
Z-Axis



CK #2 S/C Body Rates (DOY 294-295)

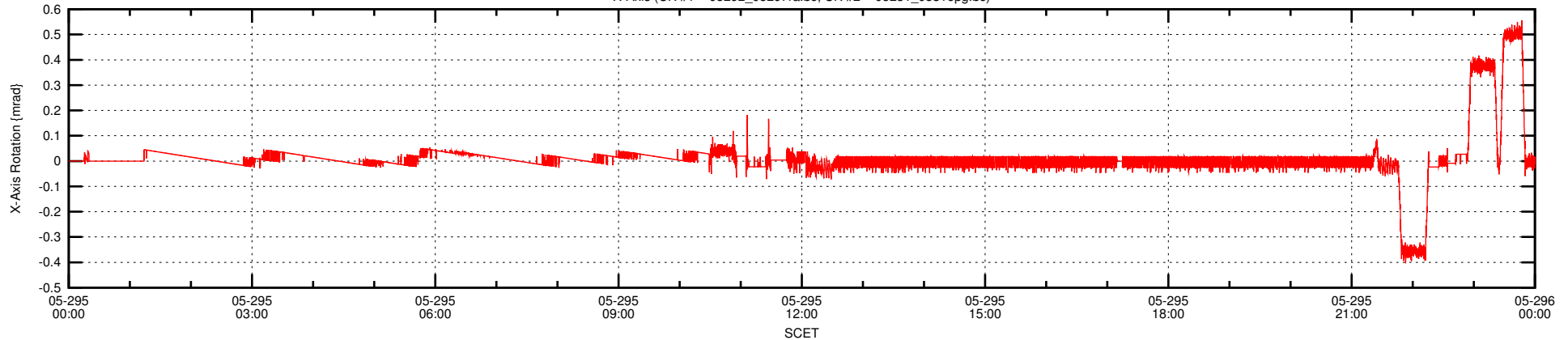


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 294-295)

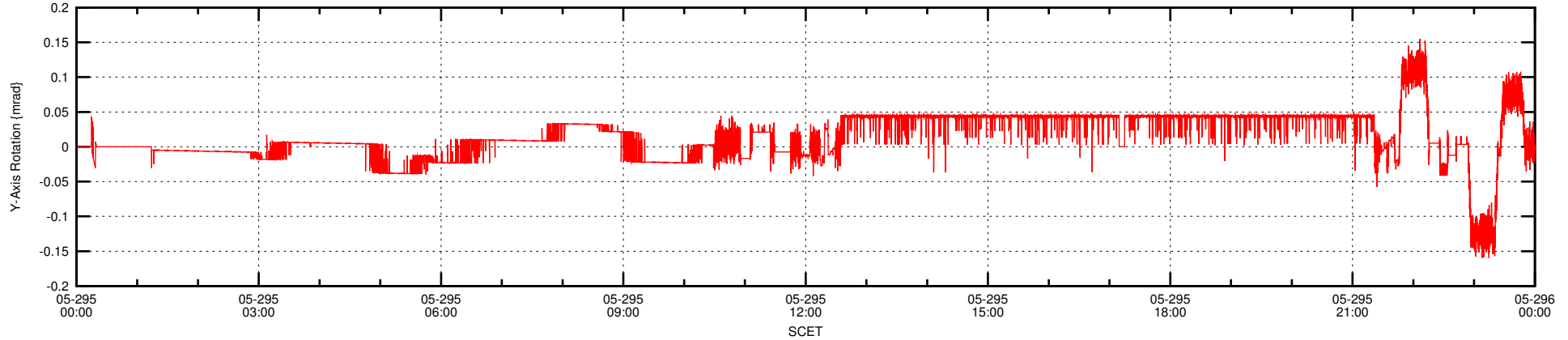


Rotation From CK #2 to CK #1 (DOY 295-296)

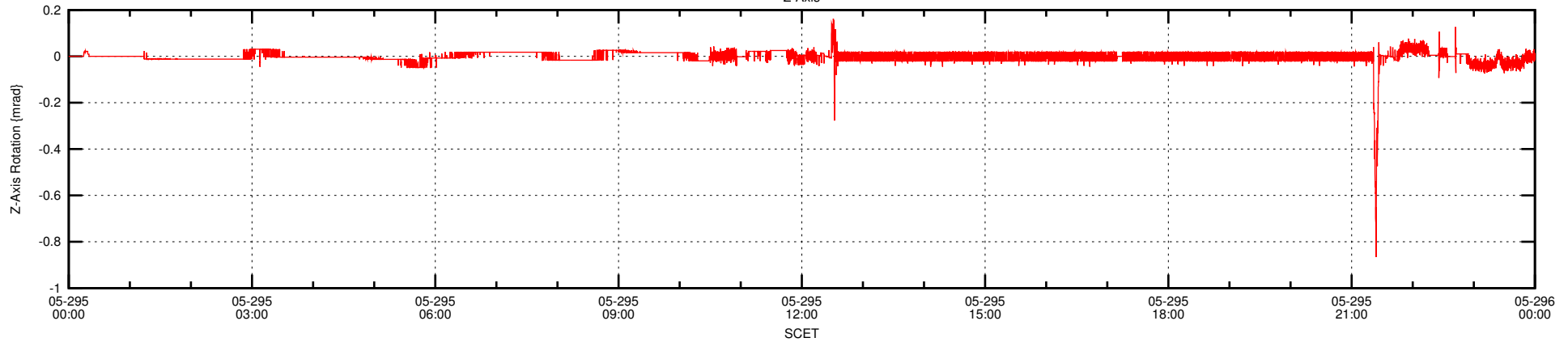
X-Axis (CK #1 = 05292_05297ra.bc; CK #2 = 05281_05316pg.bc)



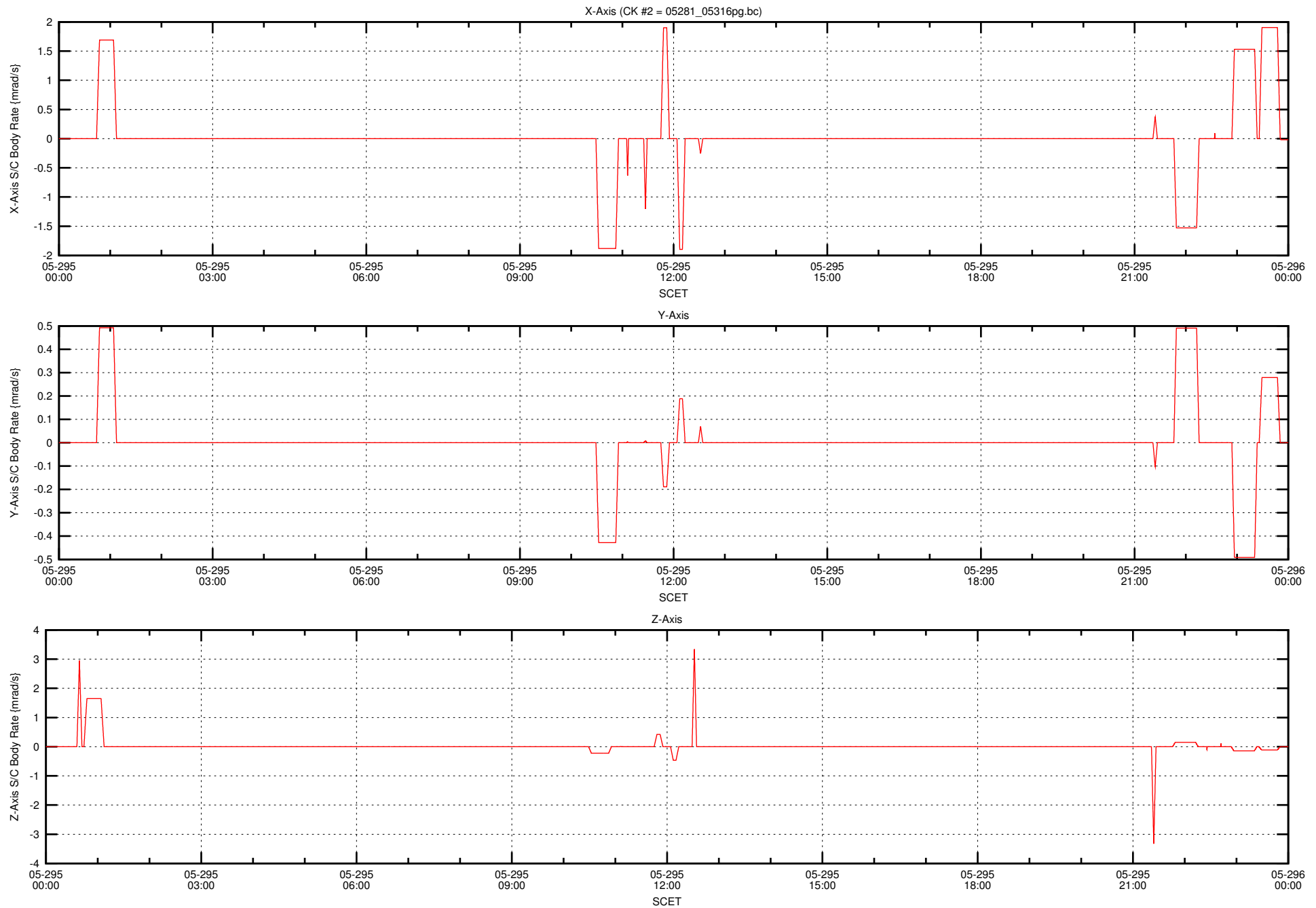
Y-Axis



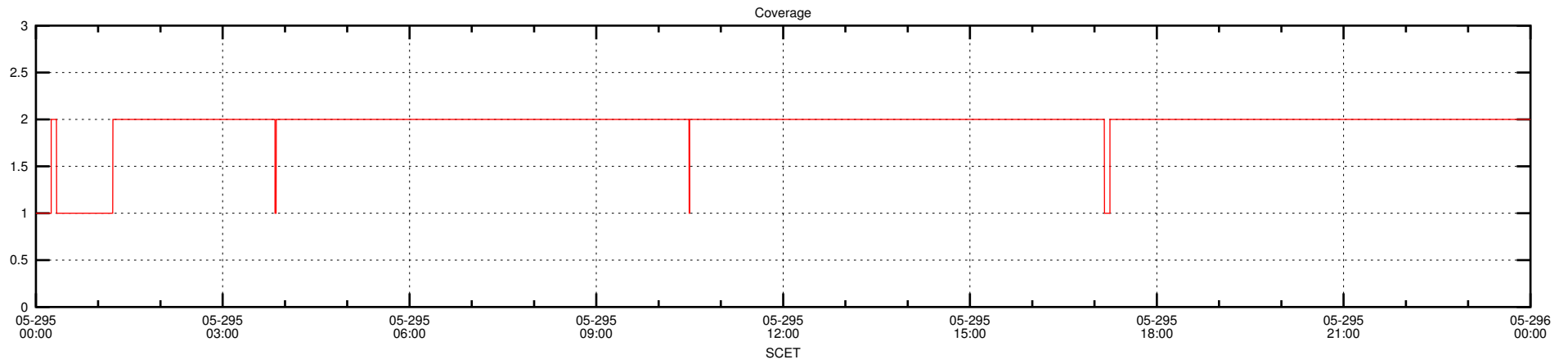
Z-Axis



CK #2 S/C Body Rates (DOY 295-296)

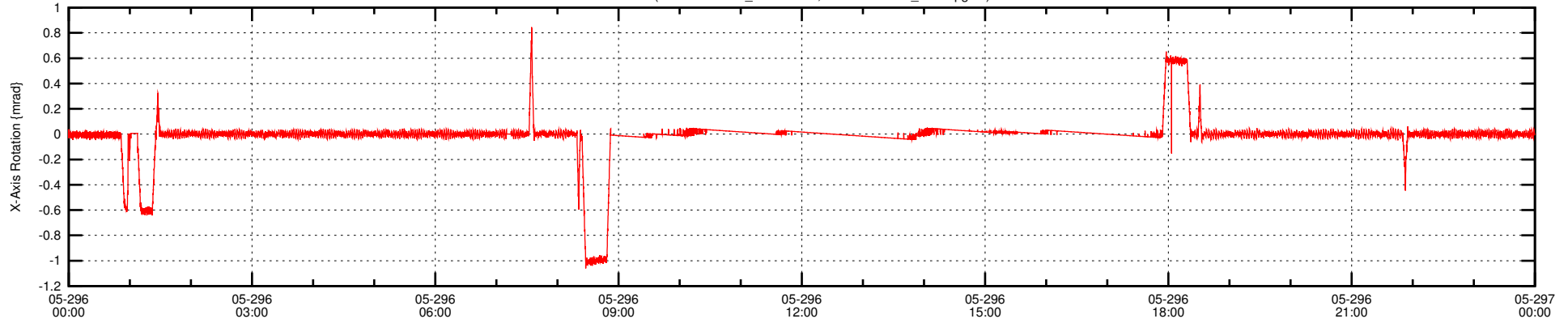


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 295-296)

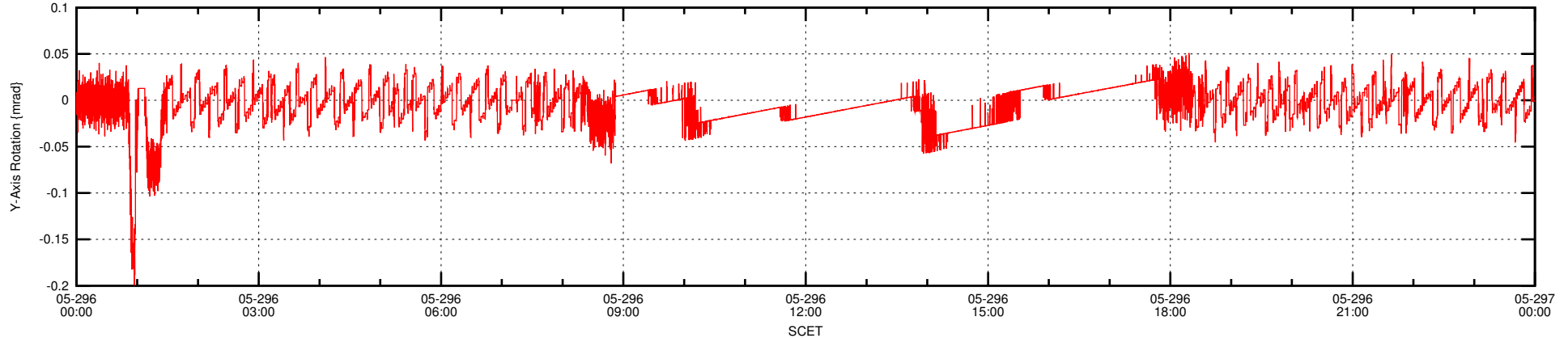


Rotation From CK #2 to CK #1 (DOY 296-296)

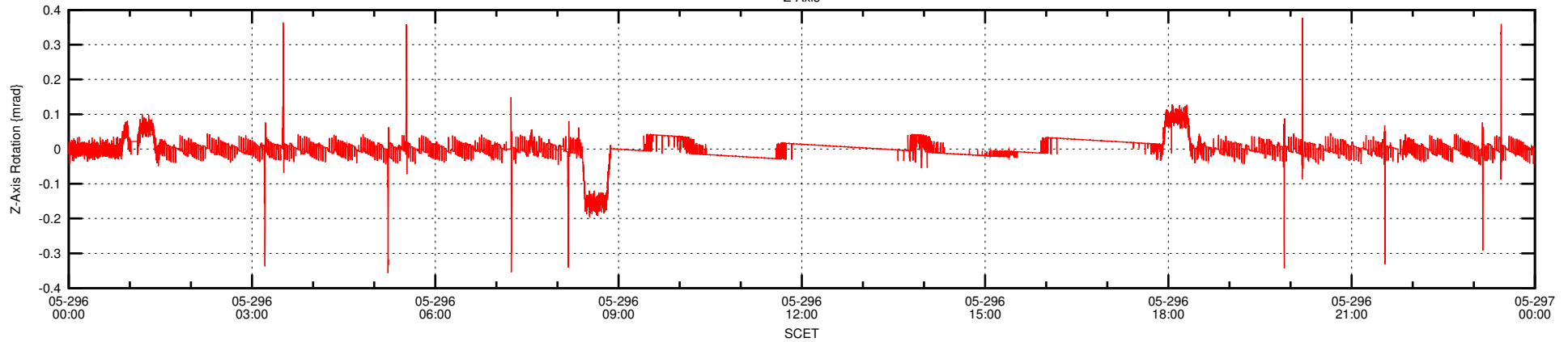
X-Axis (CK #1 = 05292_05297ra.bc; CK #2 = 05281_05316pg.bc)



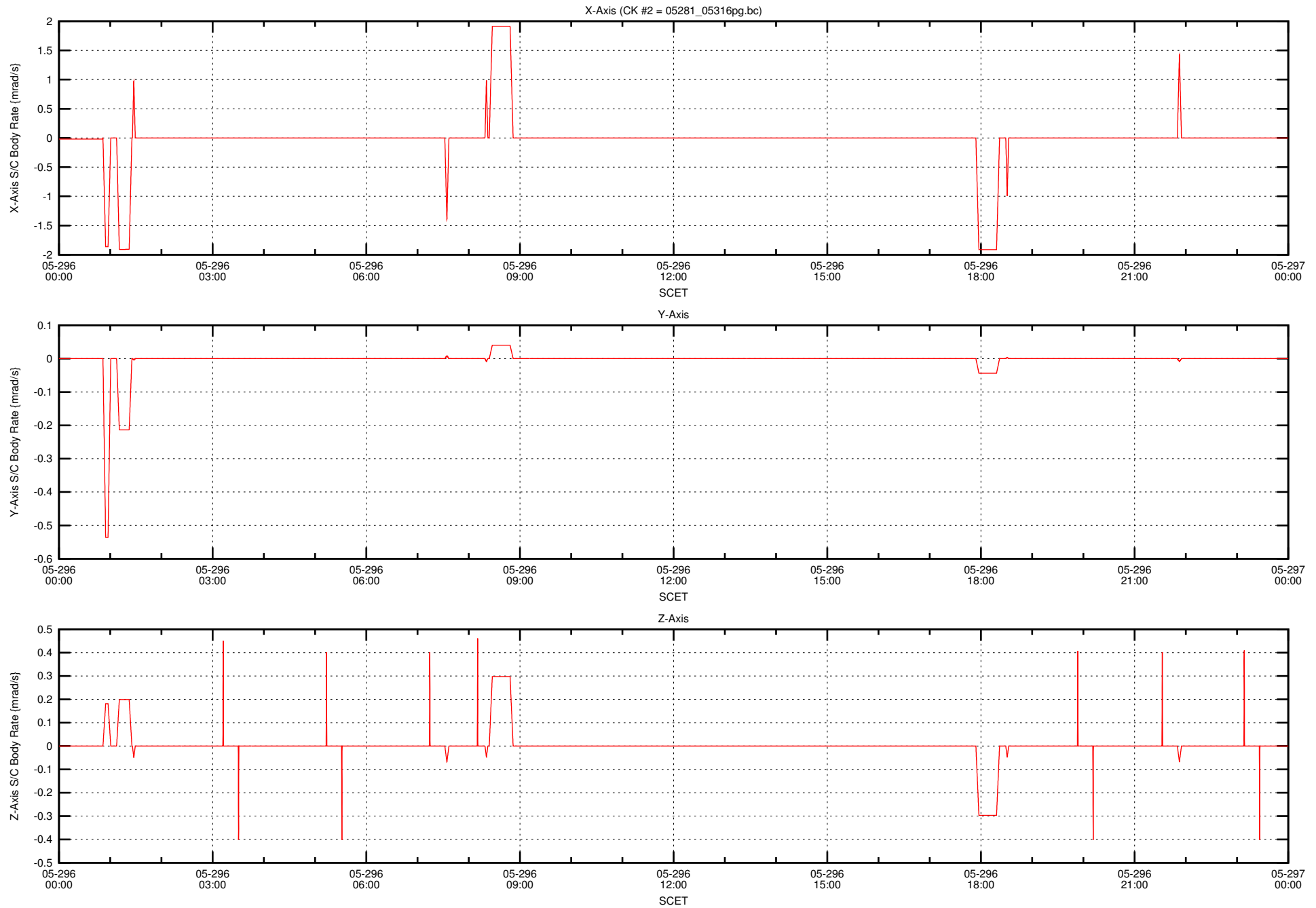
Y-Axis



Z-Axis



CK #2 S/C Body Rates (DOY 296-296)



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 296-296)

