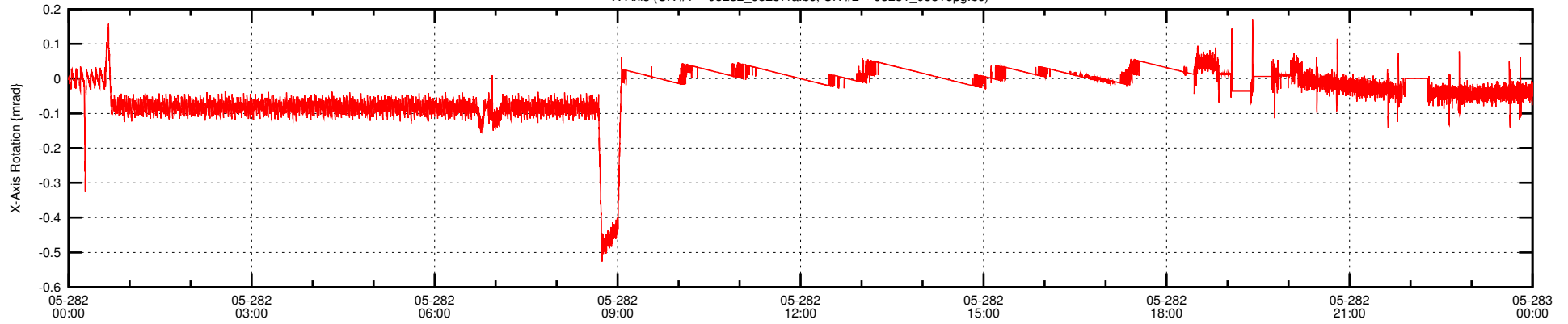
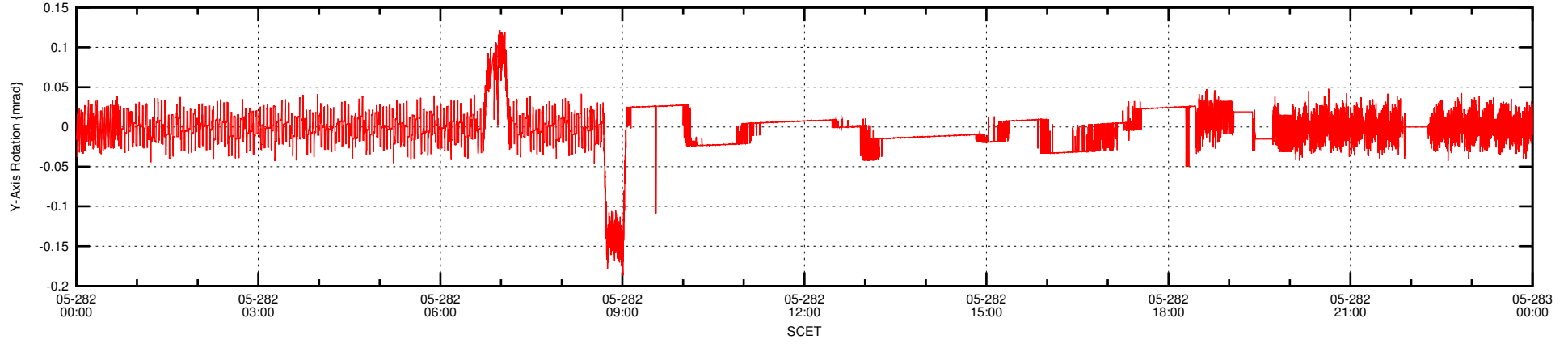


Rotation From CK #2 to CK #1 (DOY 282-283)

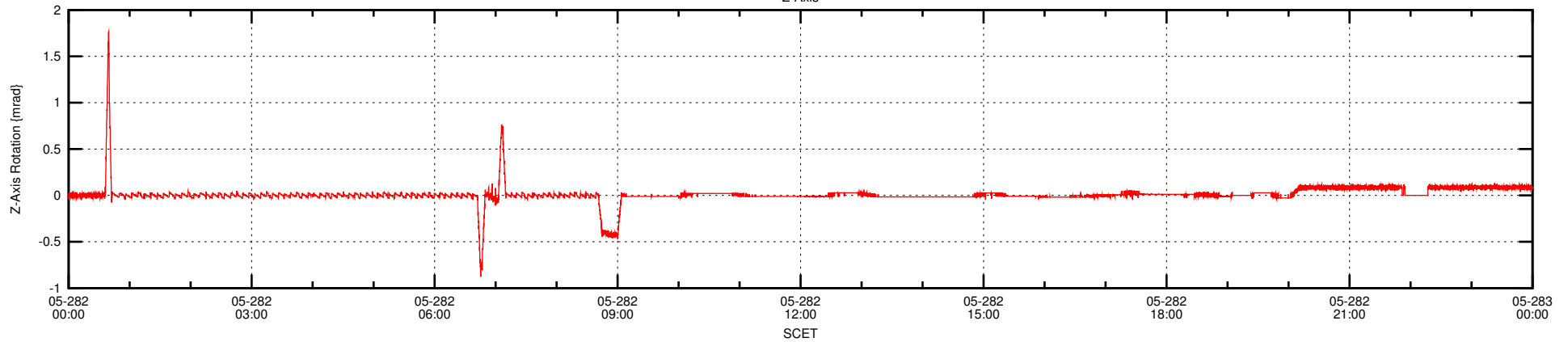
X-Axis (CK #1 = 05282_05287ra.bc; CK #2 = 05281_05316pg.bc)



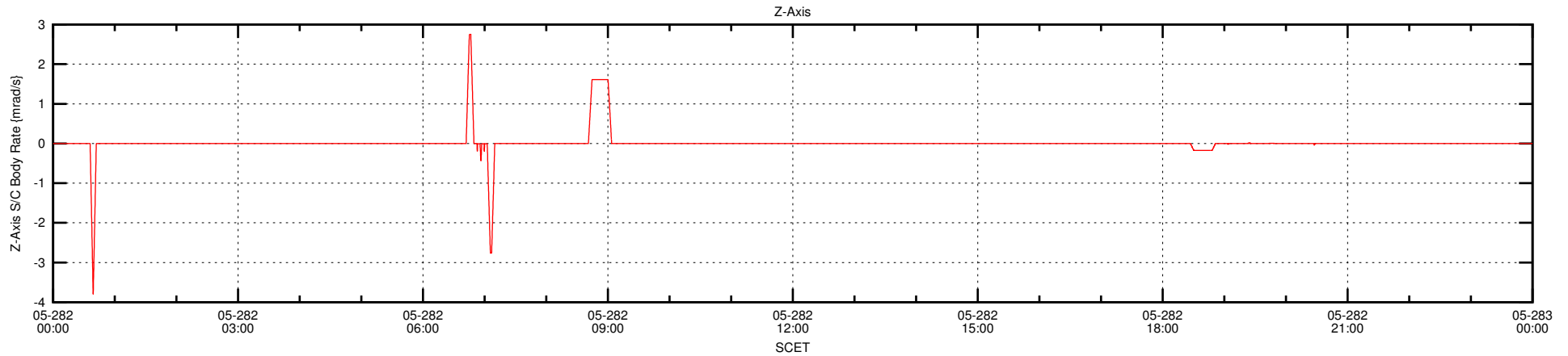
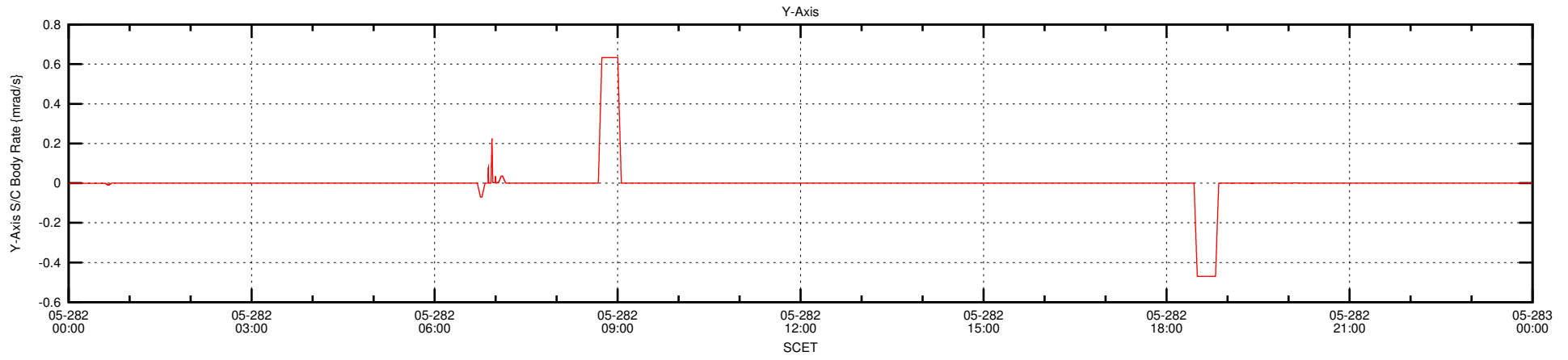
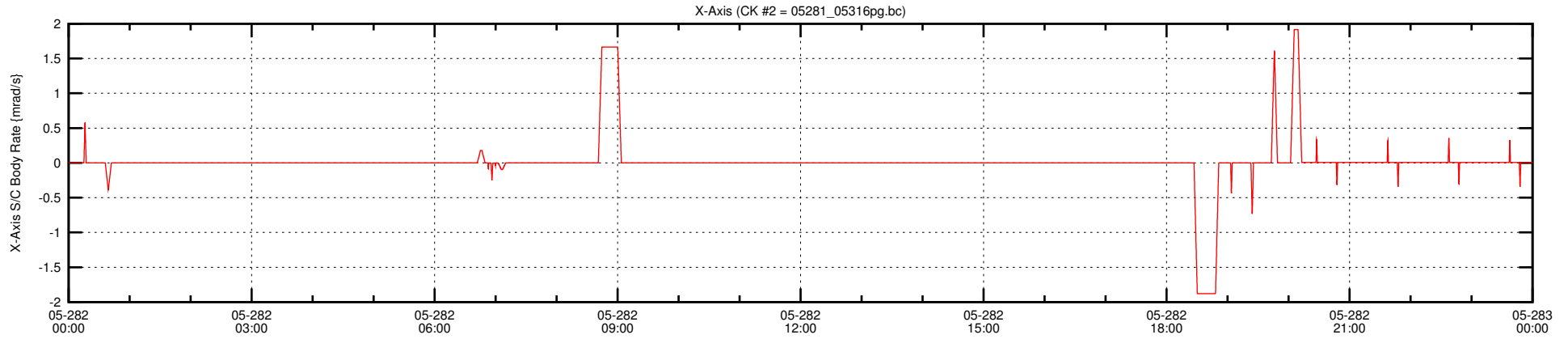
Y-Axis



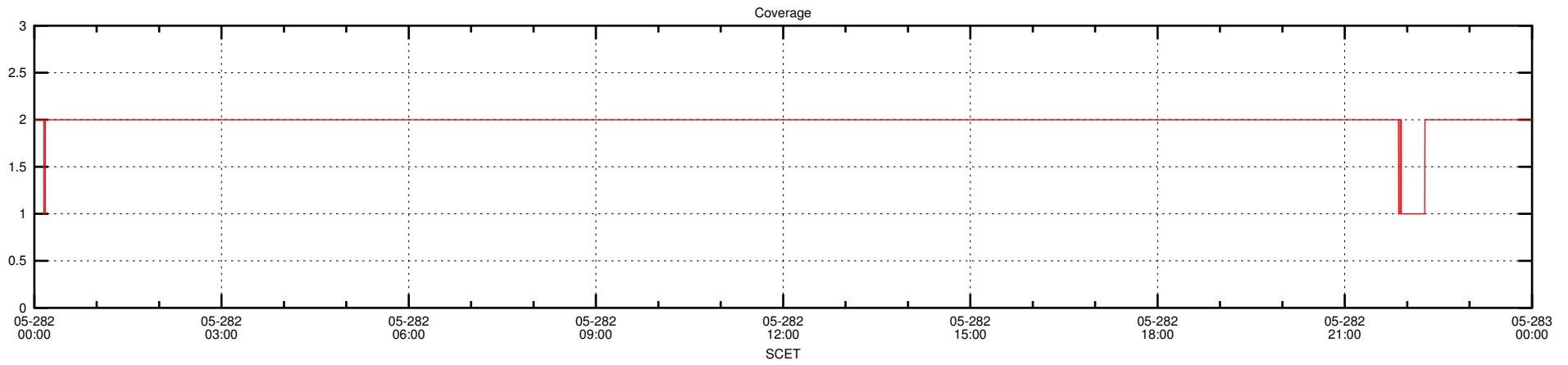
Z-Axis



CK #2 S/C Body Rates (DOY 282-283)

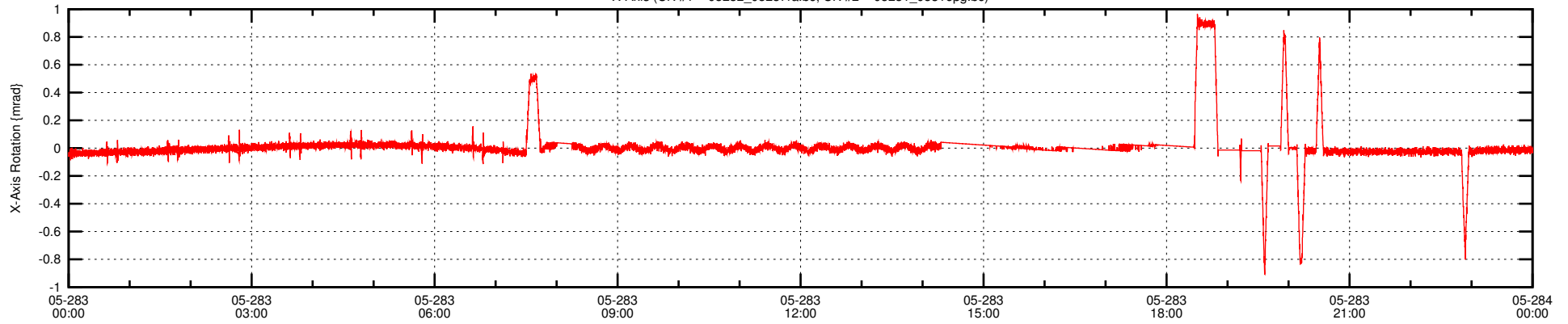


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 282-283)

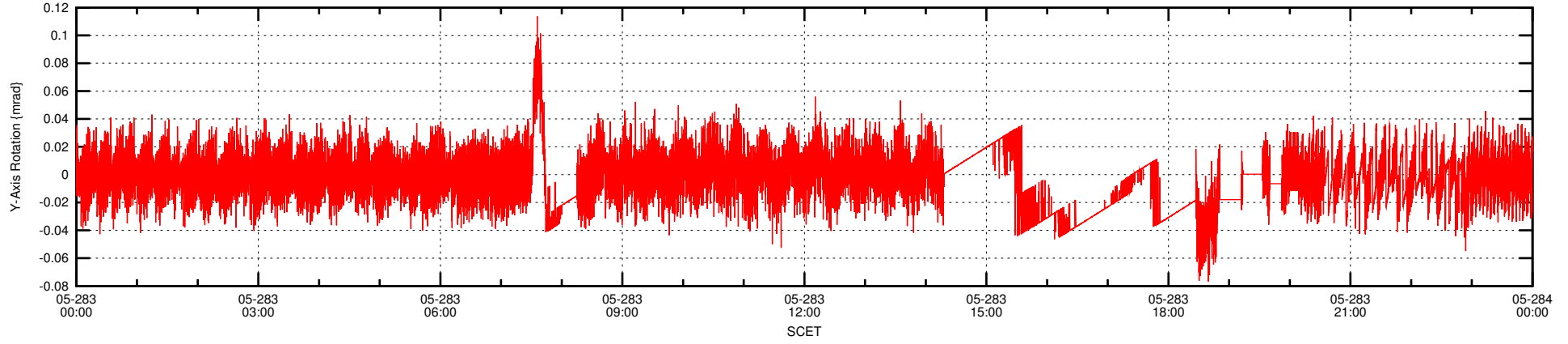


Rotation From CK #2 to CK #1 (DOY 283-284)

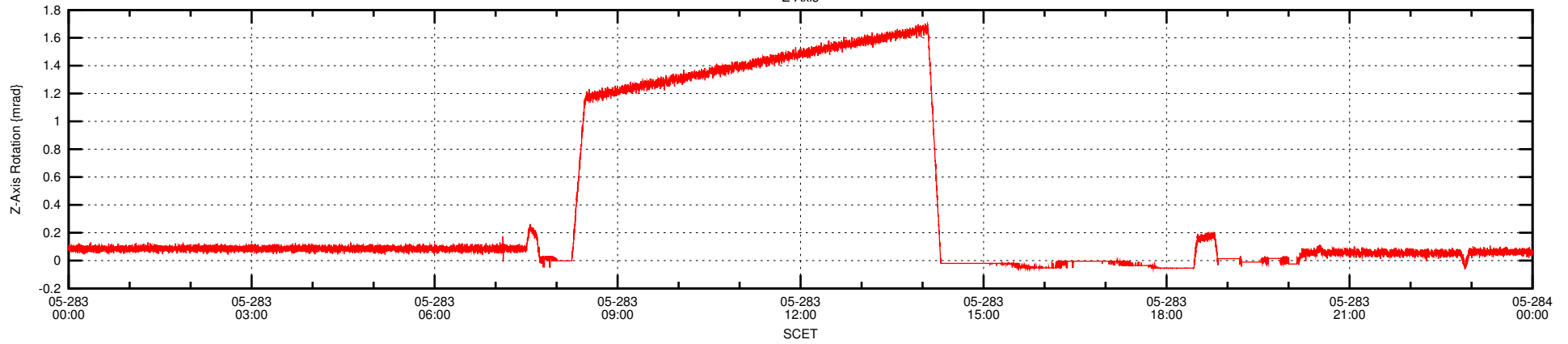
X-Axis (CK #1 = 05282_05287ra.bc; CK #2 = 05281_05316pg.bc)



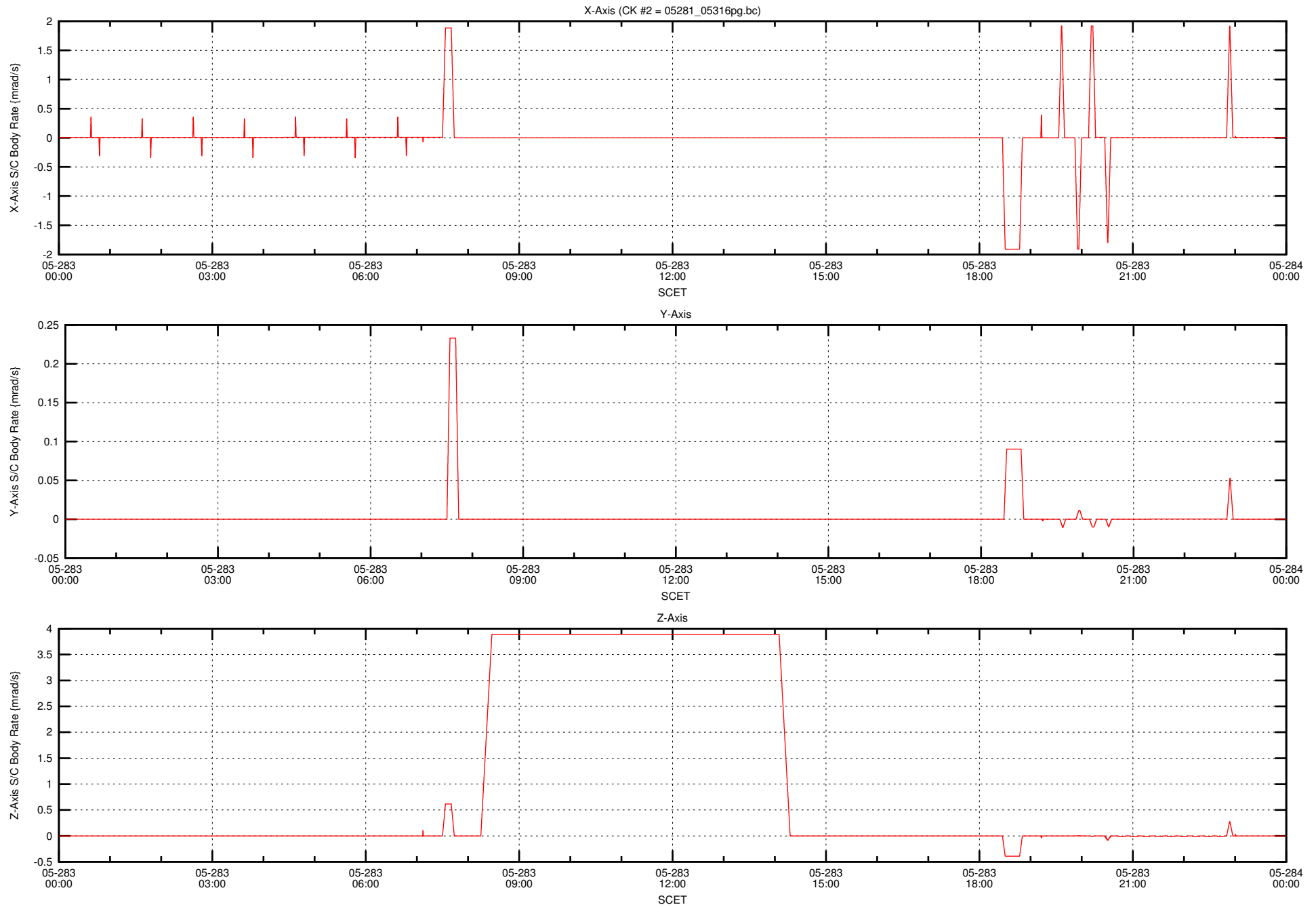
Y-Axis



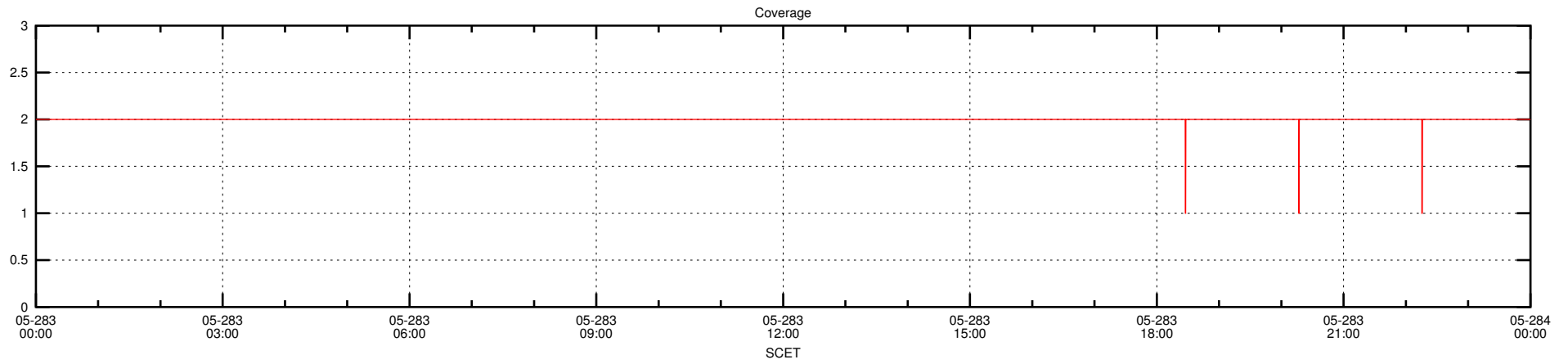
Z-Axis



CK #2 S/C Body Rates (DOY 283-284)

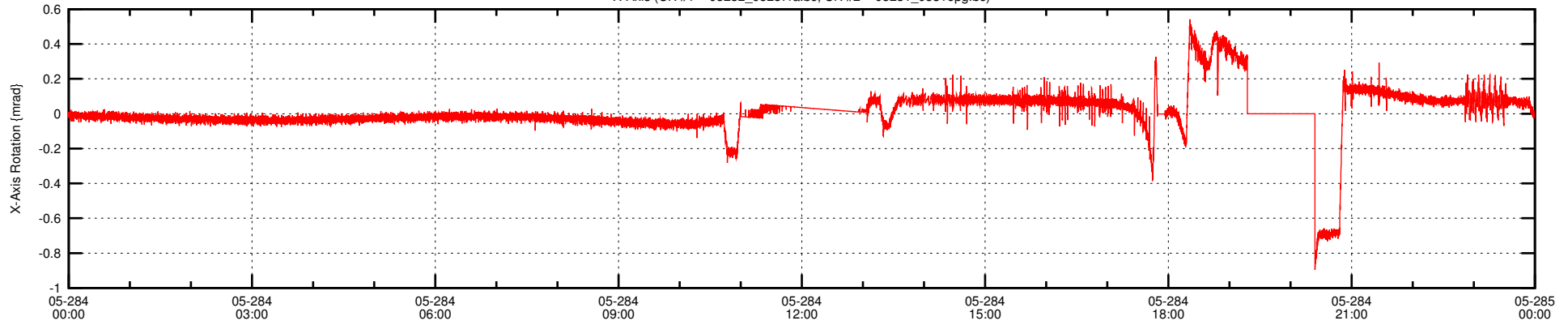


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 283-284)

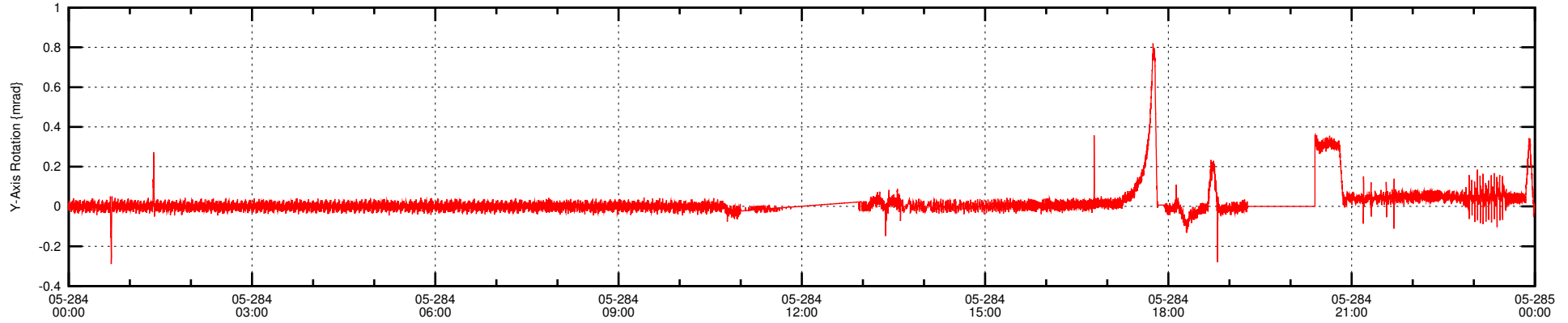


Rotation From CK #2 to CK #1 (DOY 284-285)

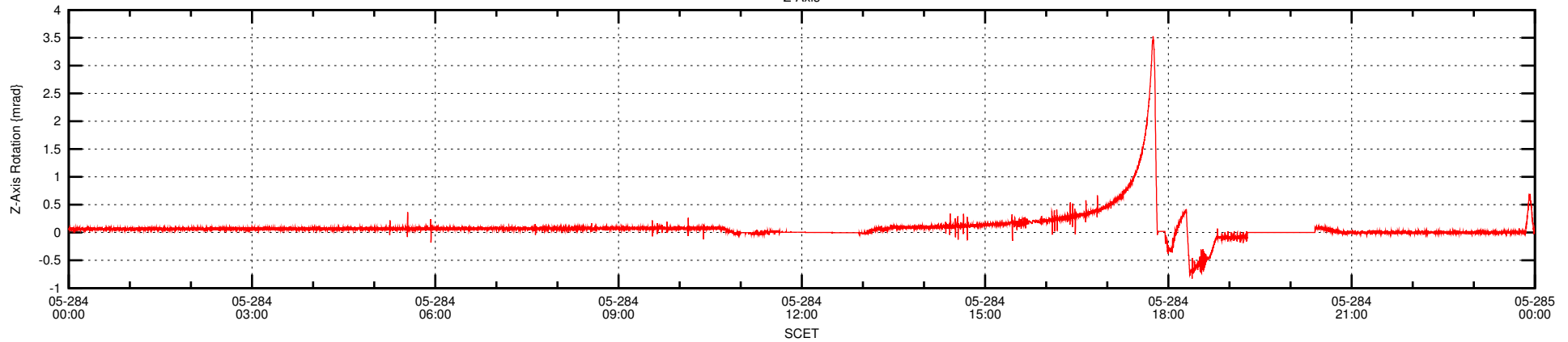
X-Axis (CK #1 = 05282_05287ra.bc; CK #2 = 05281_05316pg.bc)



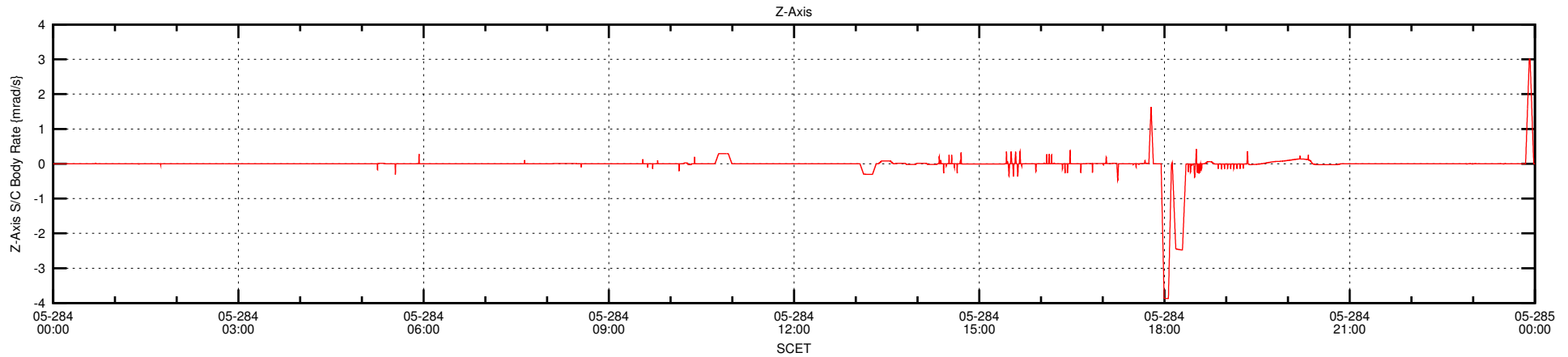
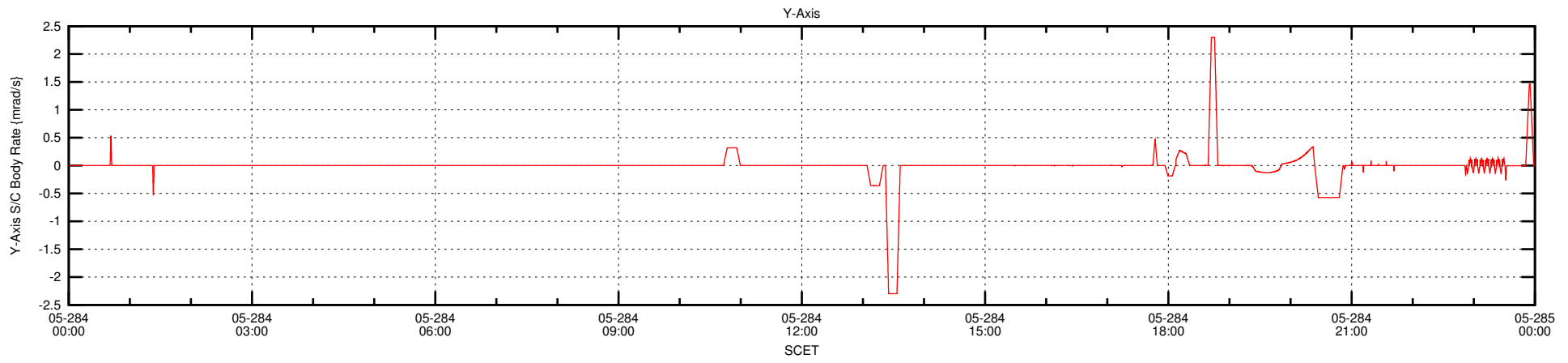
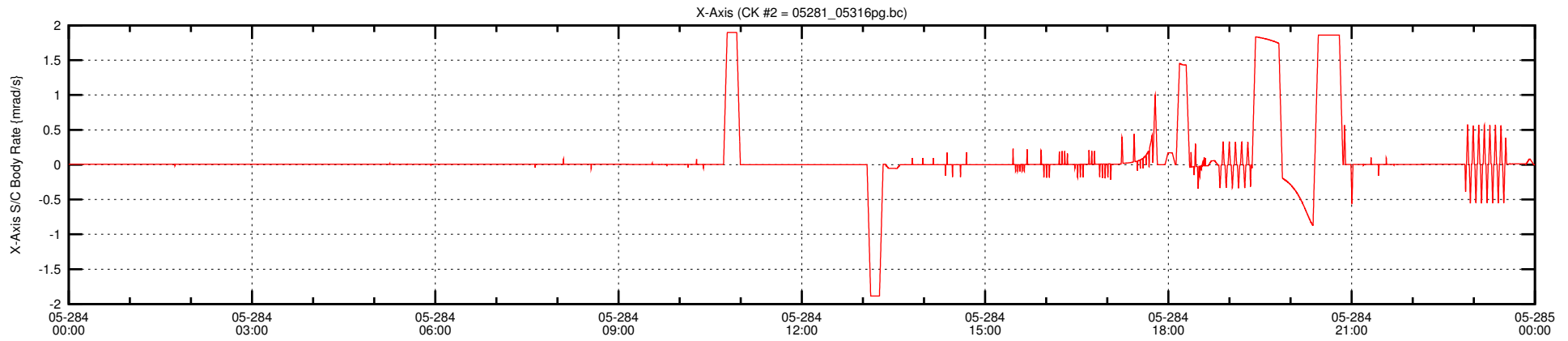
Y-Axis



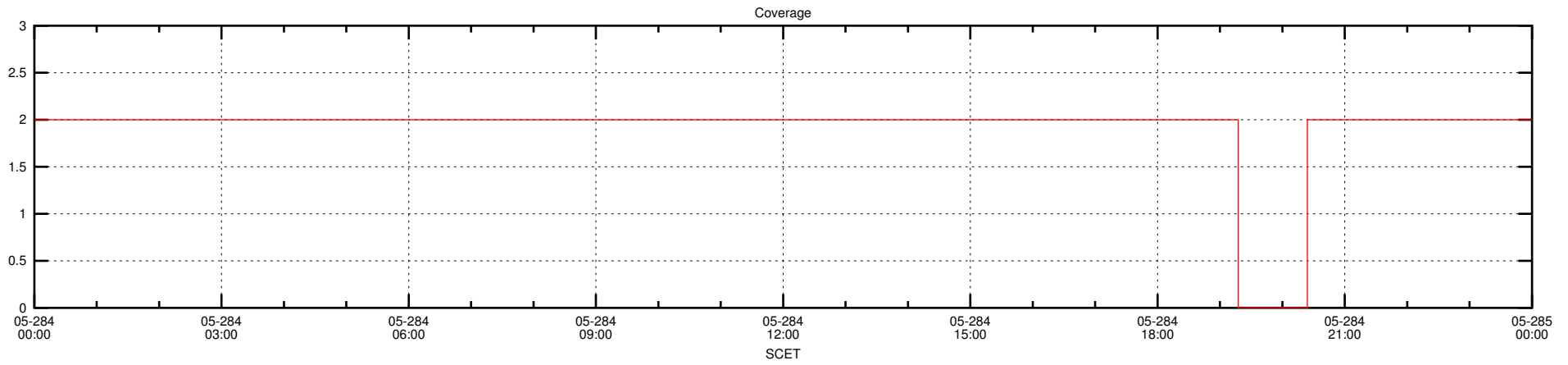
Z-Axis



CK #2 S/C Body Rates (DOY 284-285)

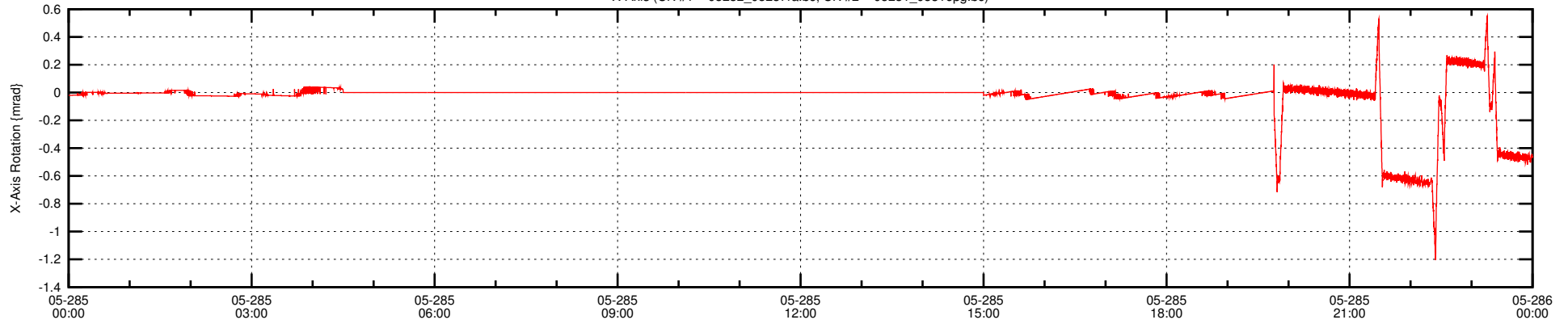


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 284-285)

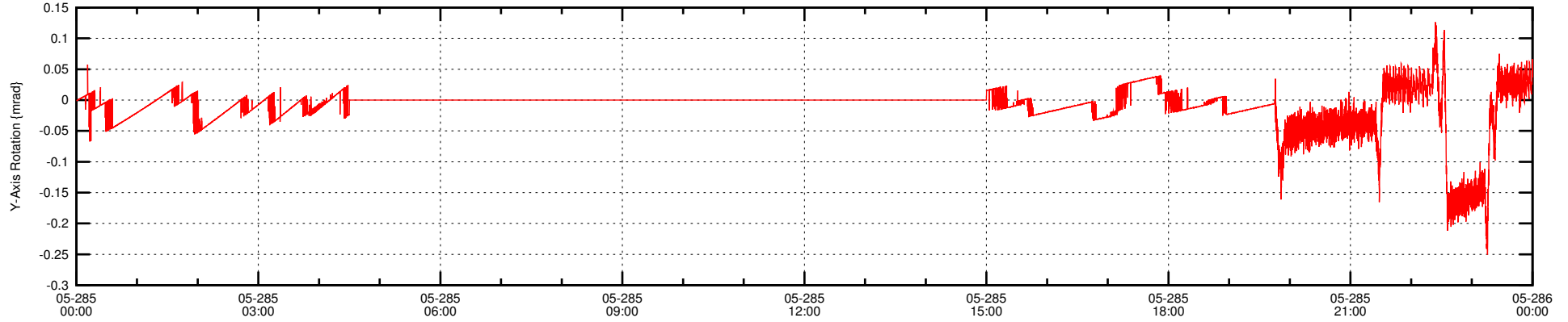


Rotation From CK #2 to CK #1 (DOY 285-286)

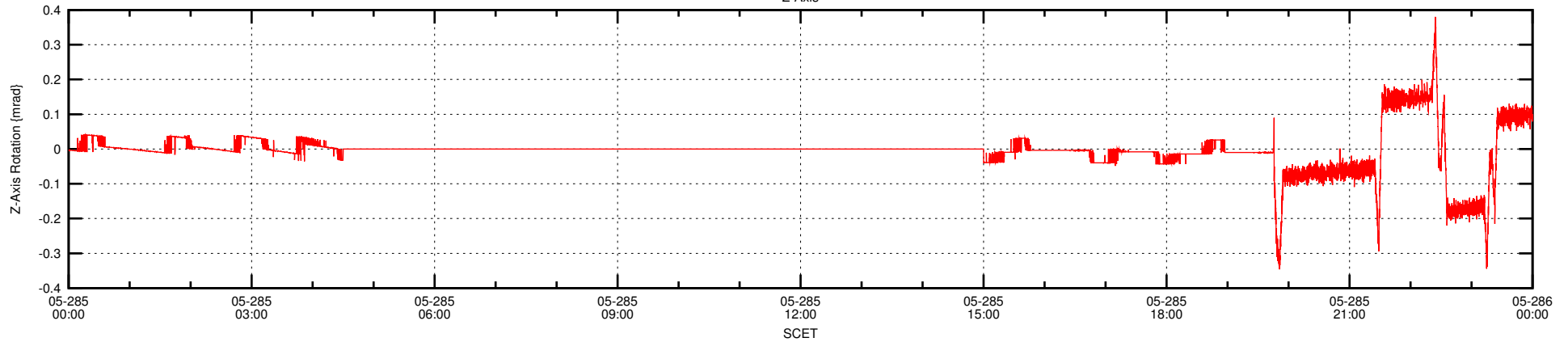
X-Axis (CK #1 = 05282_05287ra.bc; CK #2 = 05281_05316pg.bc)



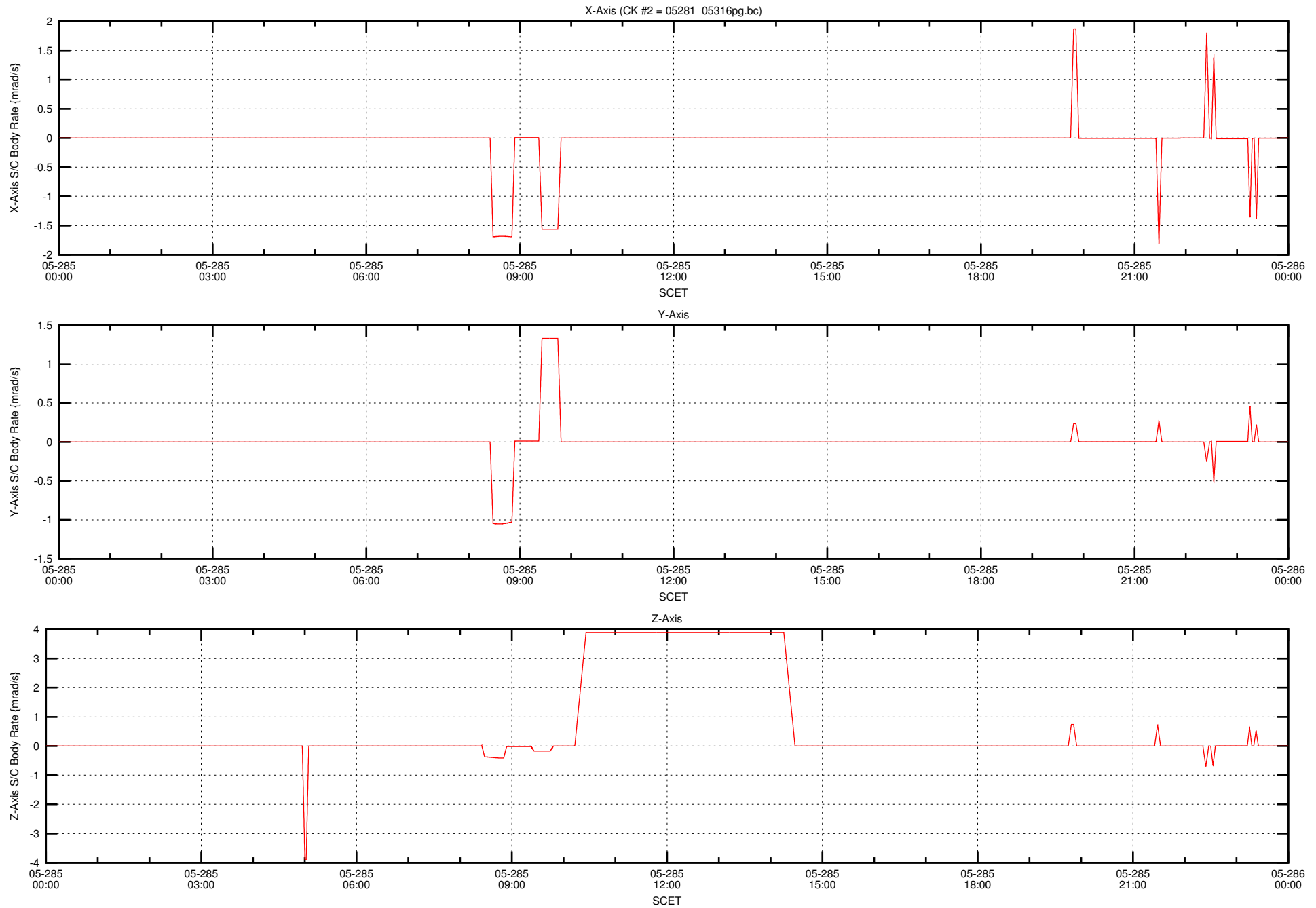
Y-Axis



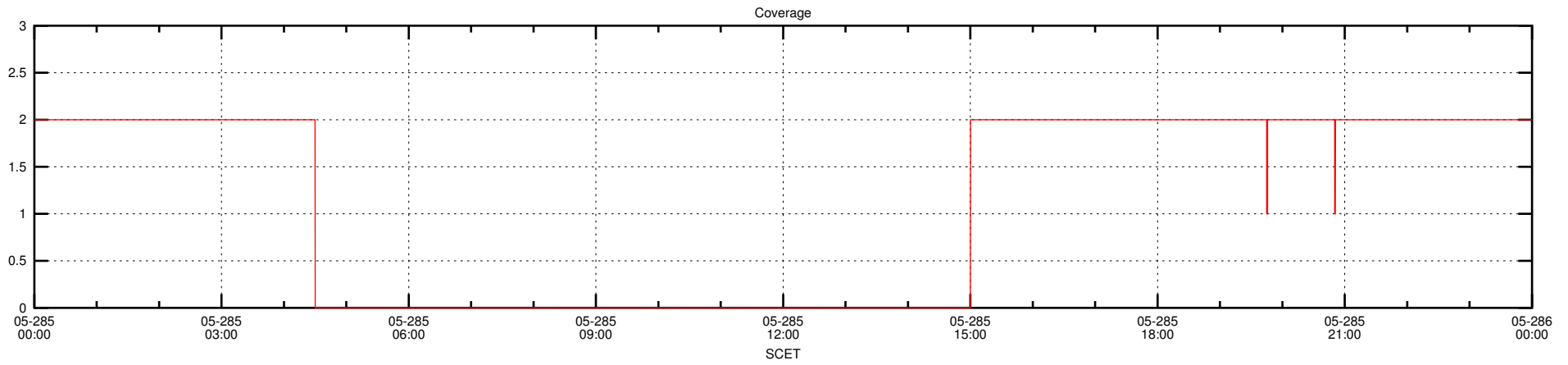
Z-Axis



CK #2 S/C Body Rates (DOY 285-286)

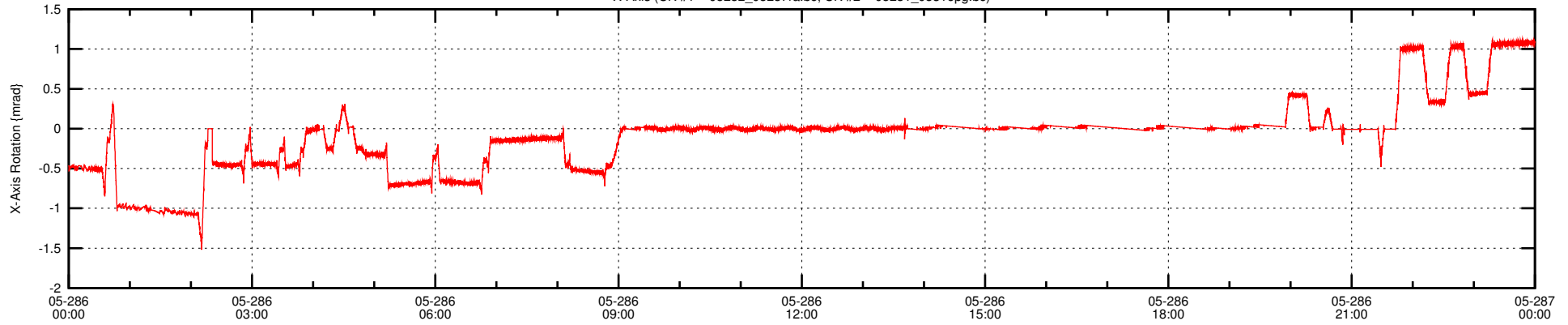


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 285-286)

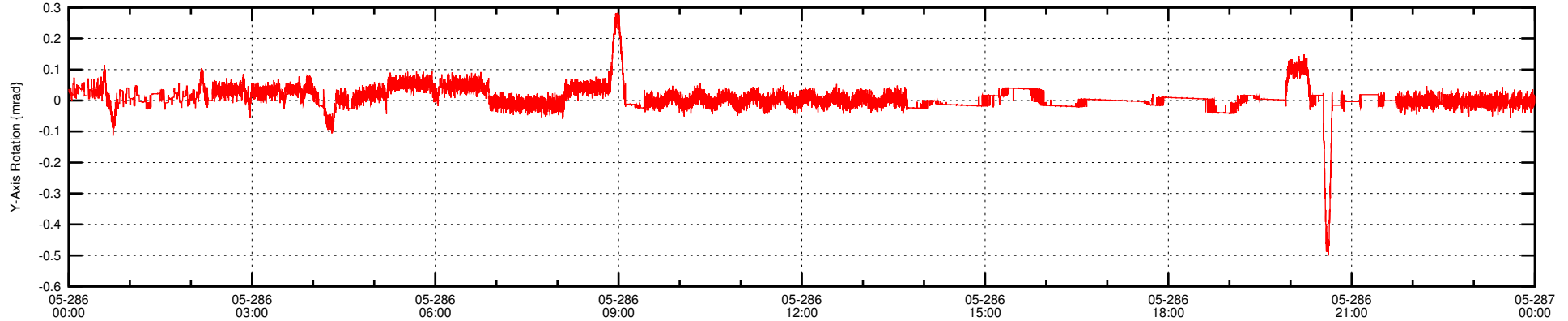


Rotation From CK #2 to CK #1 (DOY 286-286)

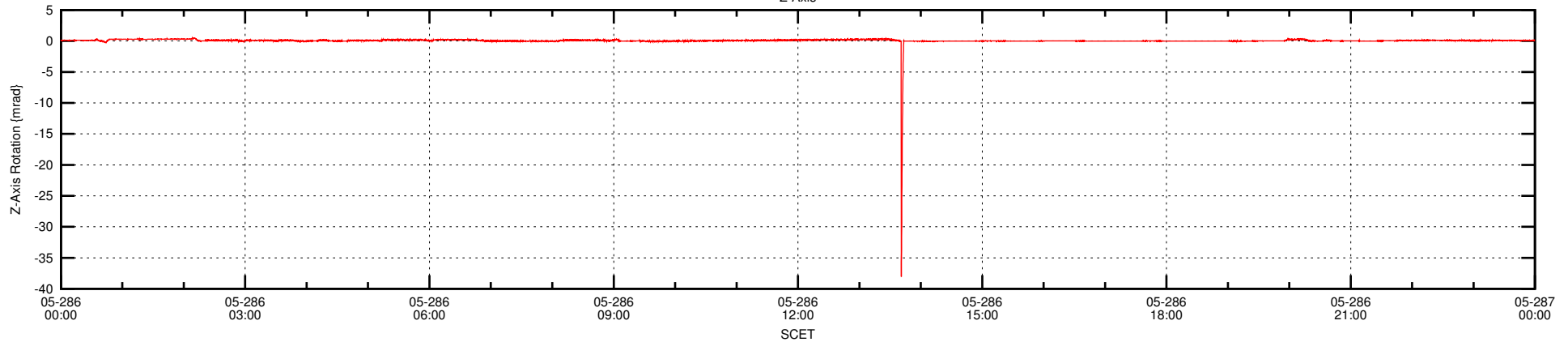
X-Axis (CK #1 = 05282_05287ra.bc; CK #2 = 05281_05316pg.bc)



Y-Axis

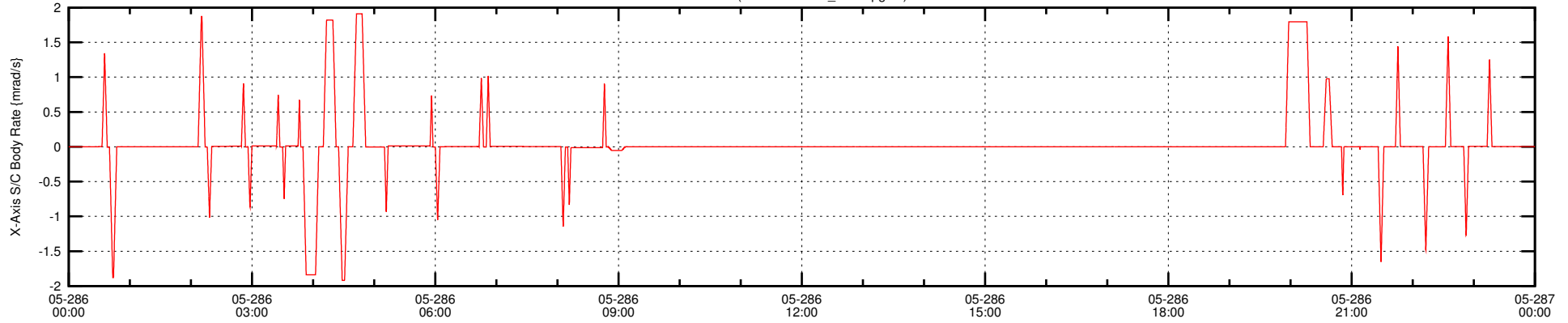


Z-Axis

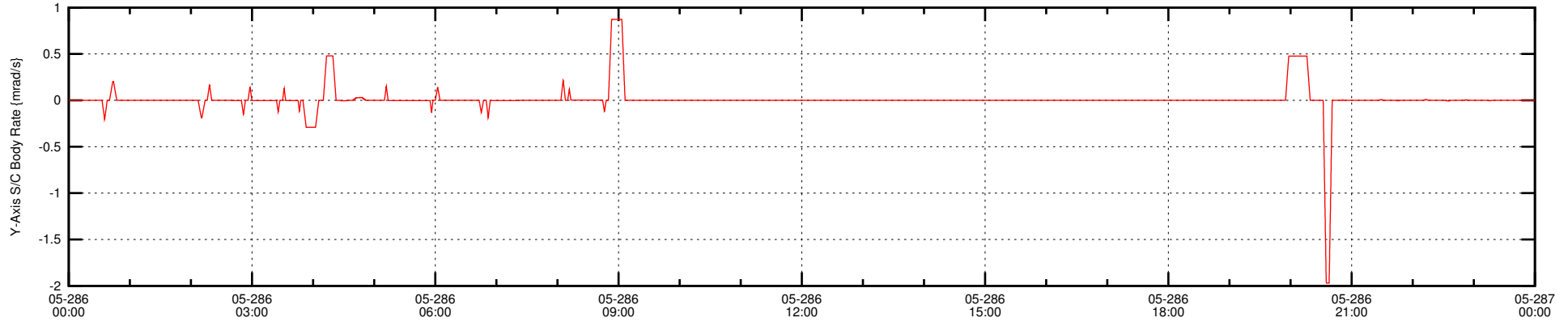


CK #2 S/C Body Rates (DOY 286-286)

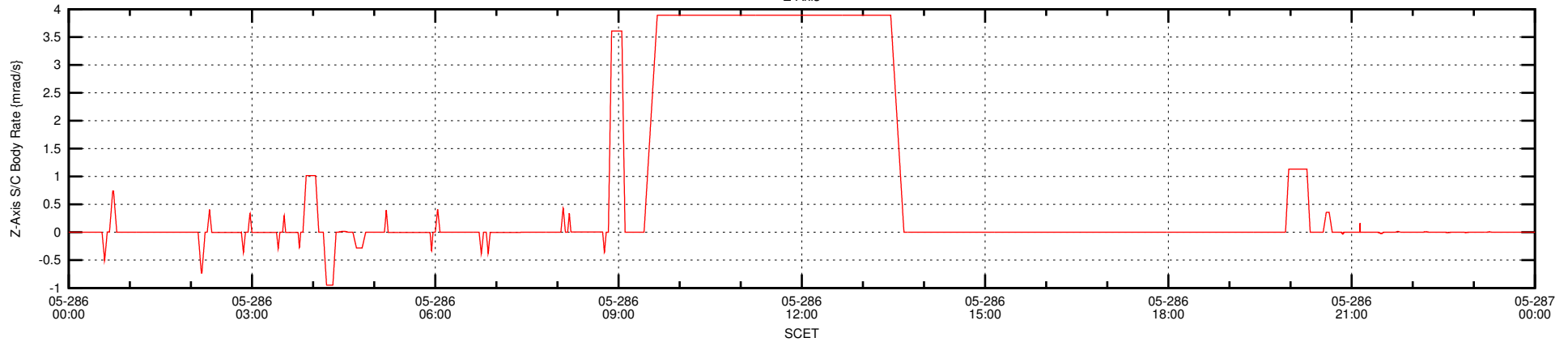
X-Axis (CK #2 = 05281_05316pg.bc)



Y-Axis



Z-Axis



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 286-286)

