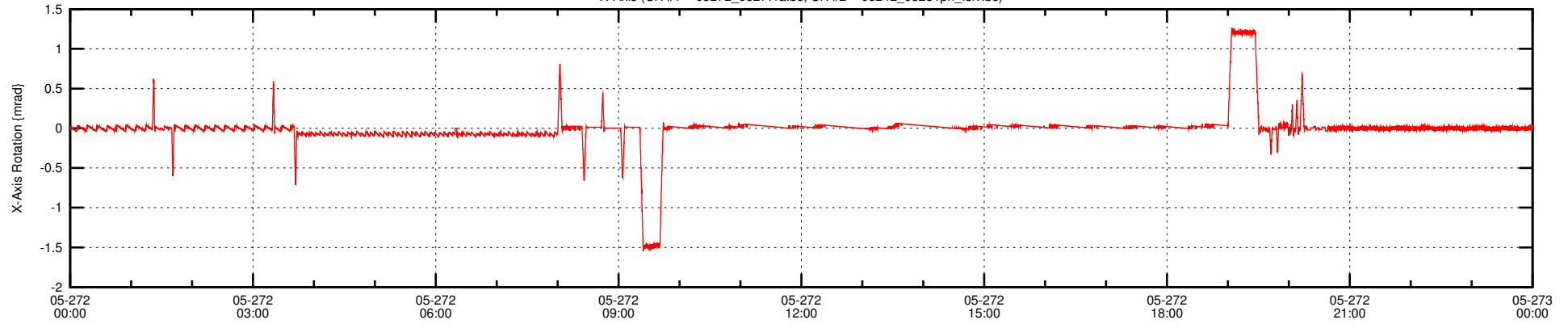
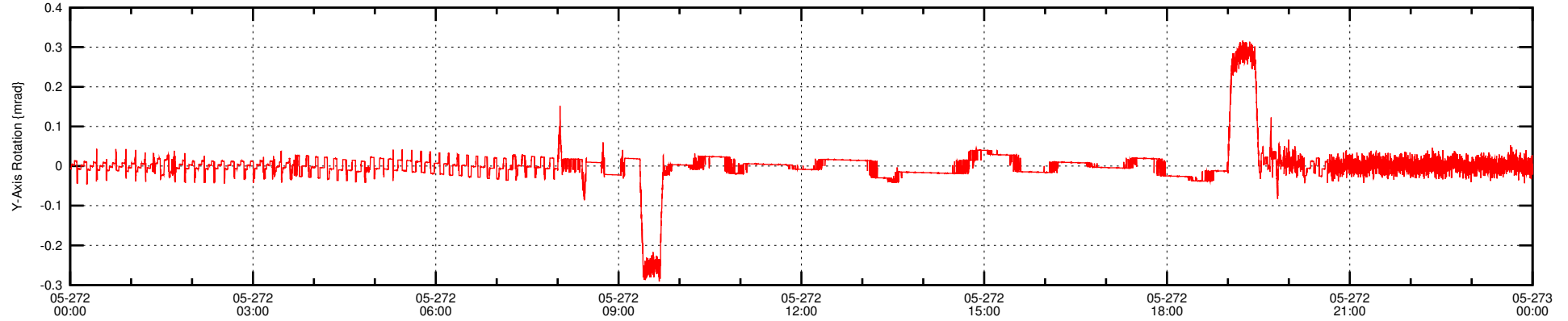


Rotation From CK #2 to CK #1 (DOY 272-273)

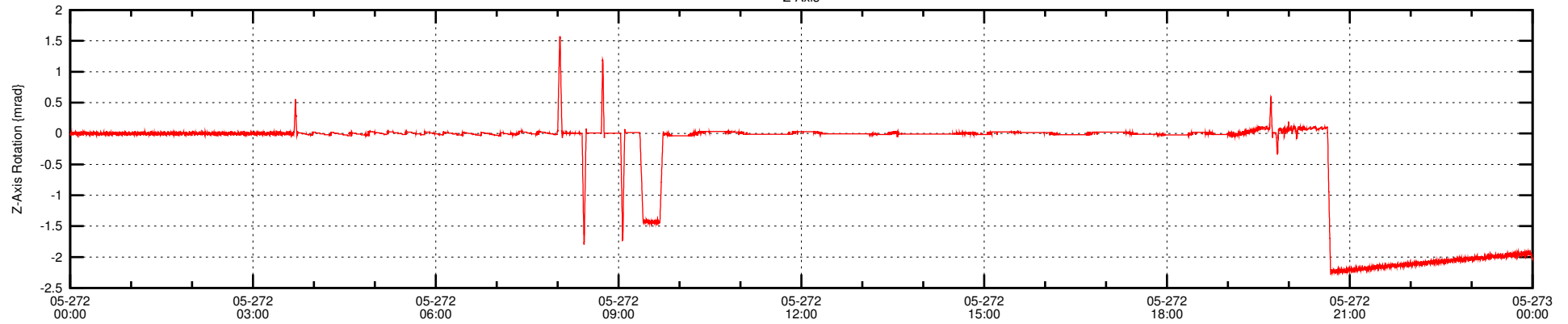
X-Axis (CK #1 = 05272_05277ra.bc; CK #2 = 05242_05281ph_fsiv.bc)



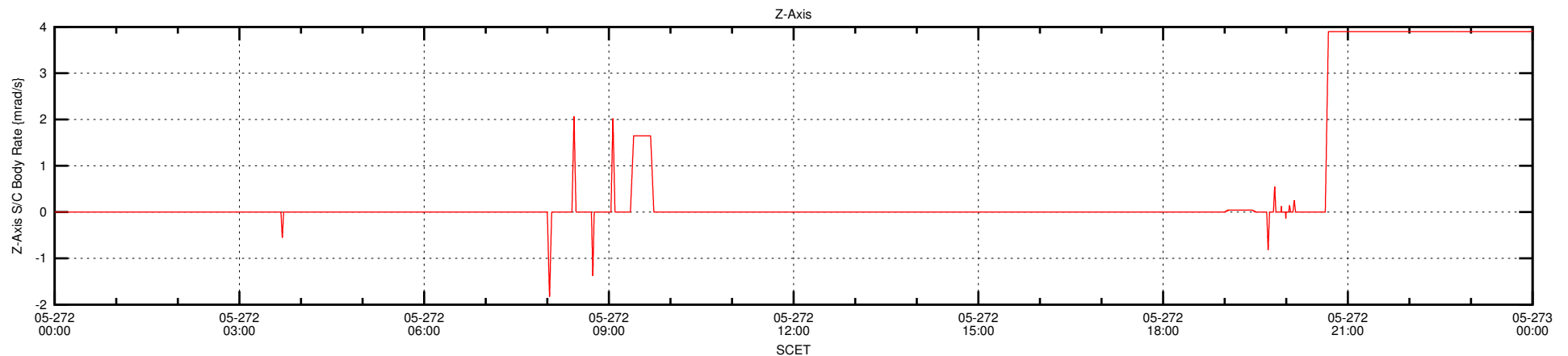
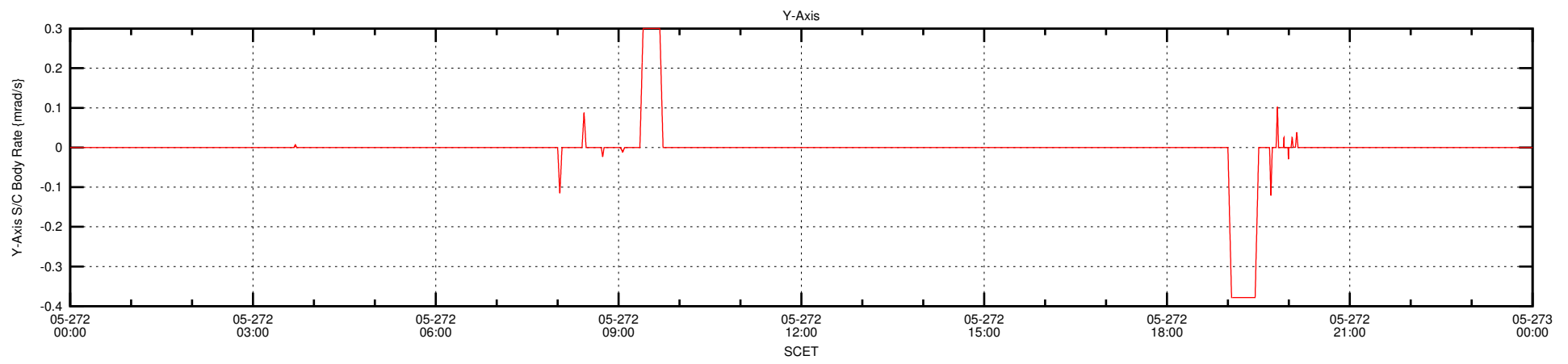
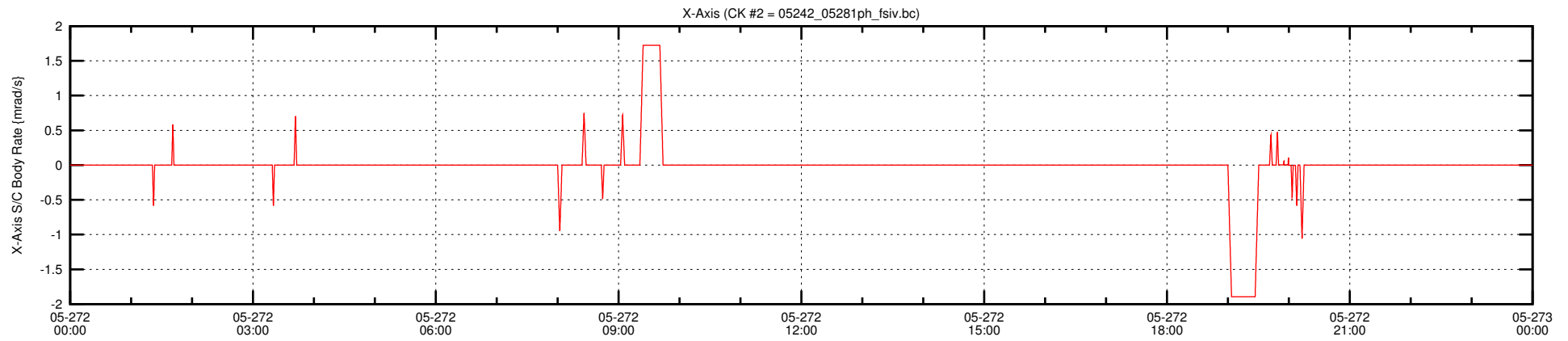
Y-Axis



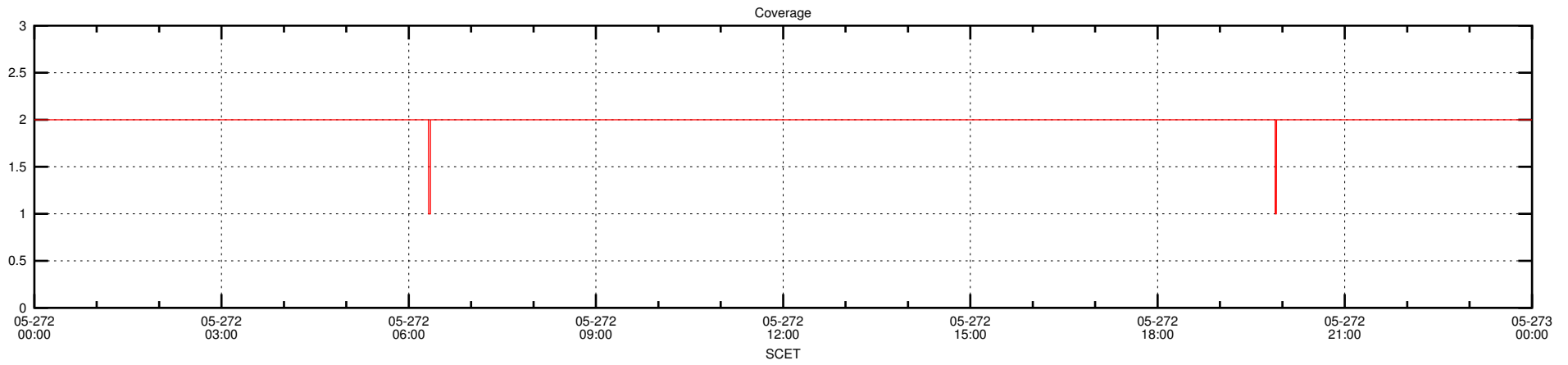
Z-Axis



CK #2 S/C Body Rates (DOY 272-273)

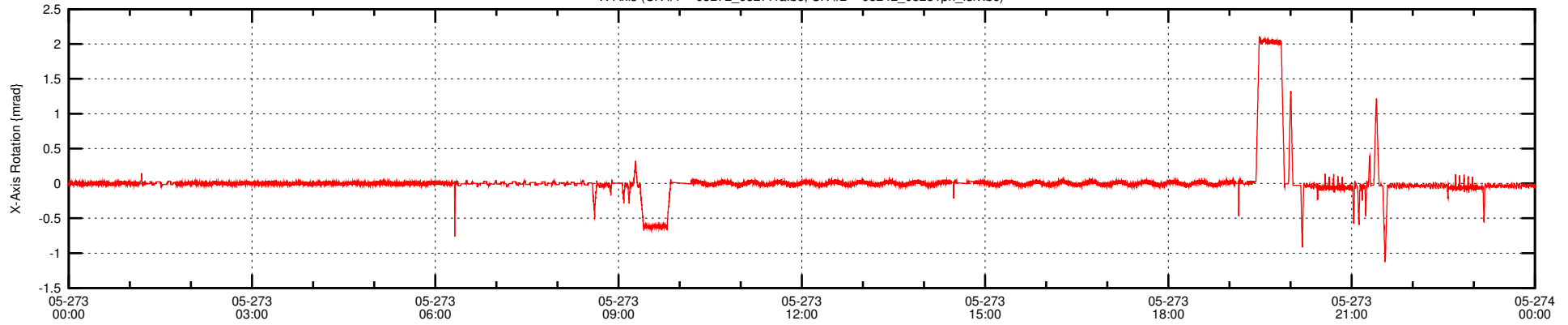


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 272-273)

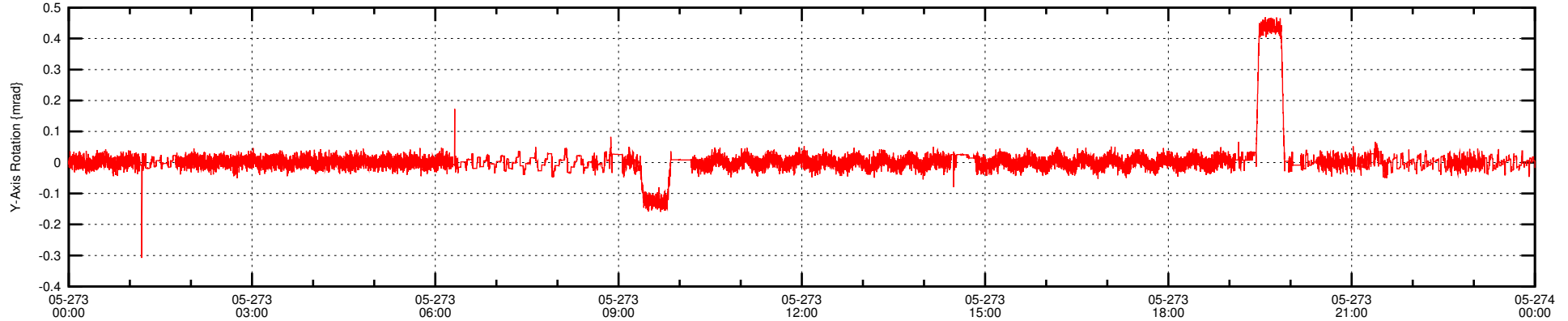


Rotation From CK #2 to CK #1 (DOY 273-274)

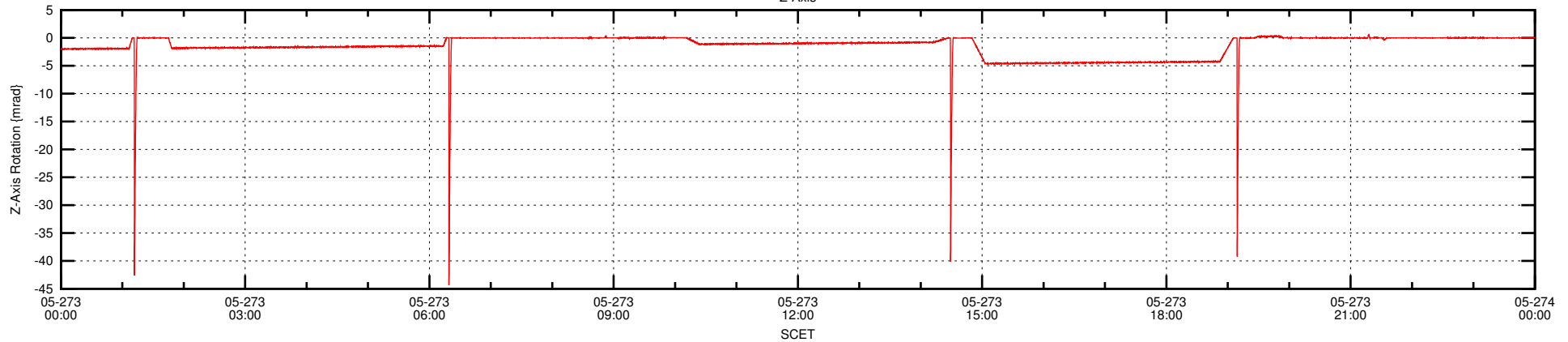
X-Axis (CK #1 = 05272_05277ra.bc; CK #2 = 05242_05281ph_fsiv.bc)



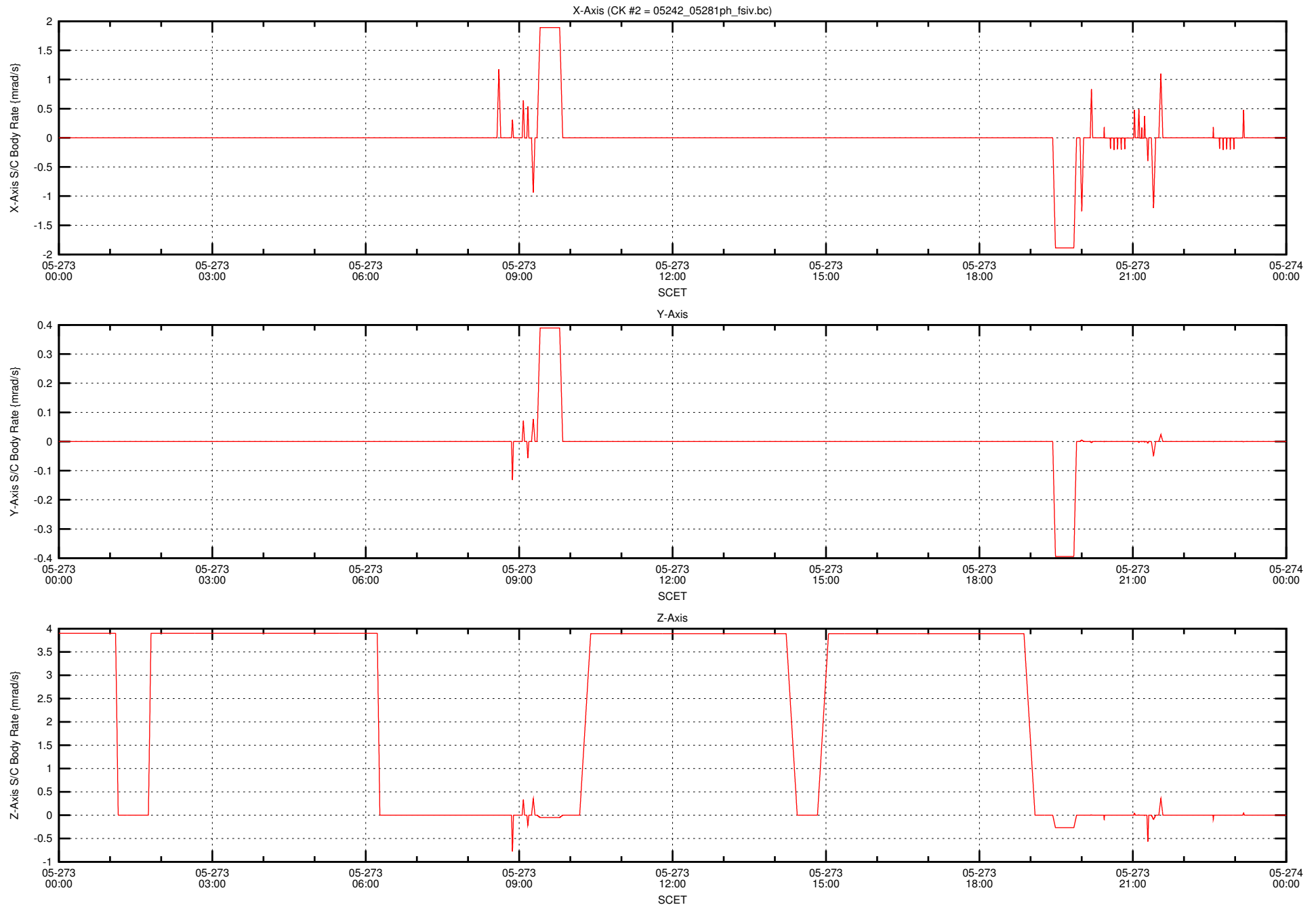
Y-Axis



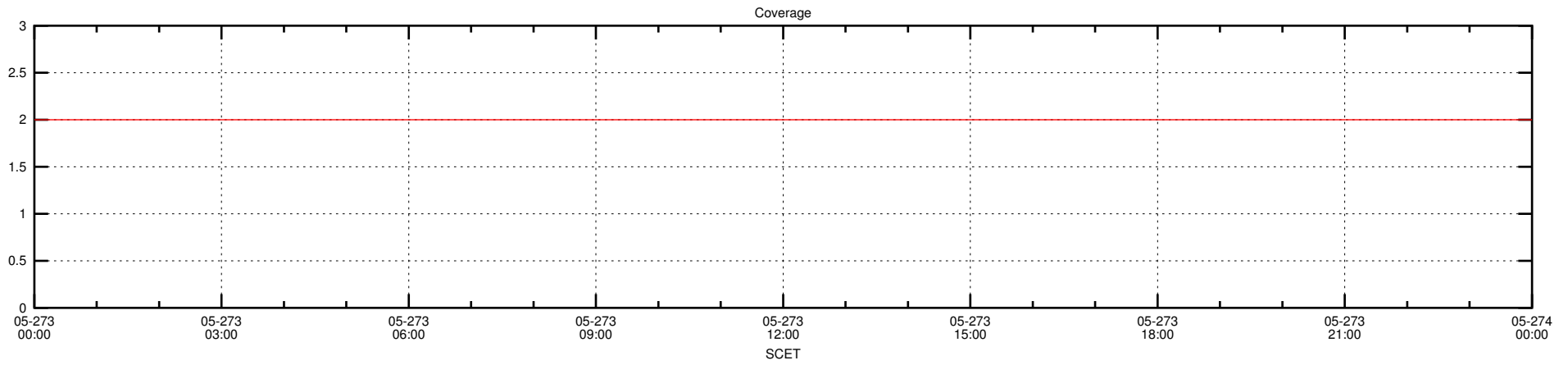
Z-Axis



CK #2 S/C Body Rates (DOY 273-274)

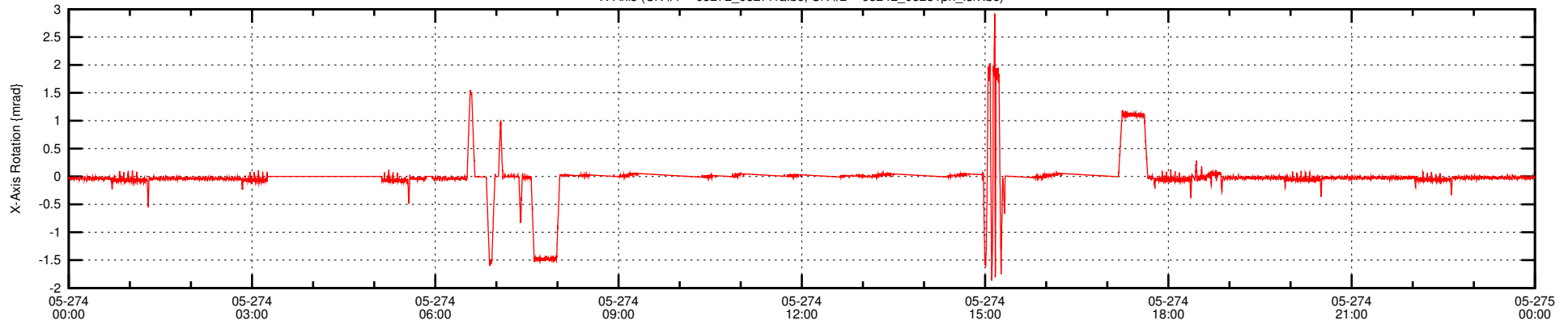


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 273-274)

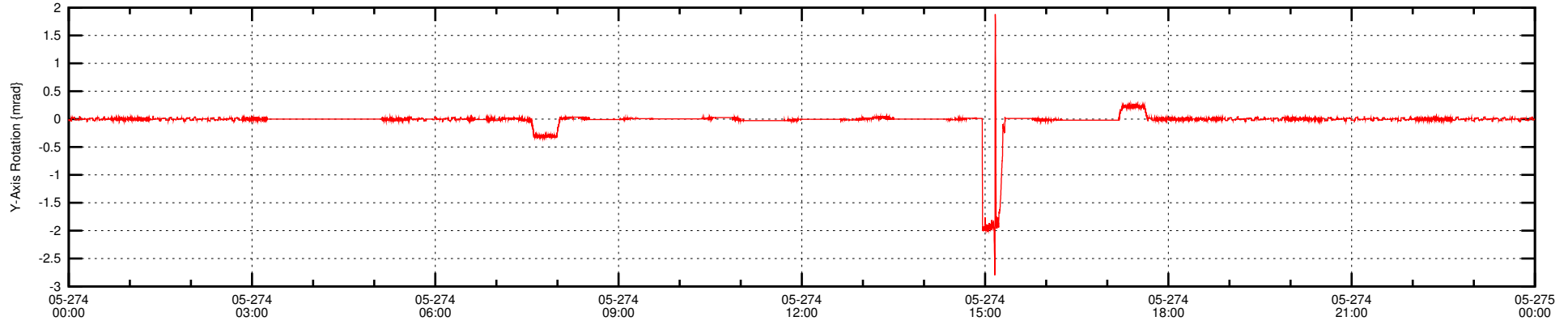


Rotation From CK #2 to CK #1 (DOY 274-275)

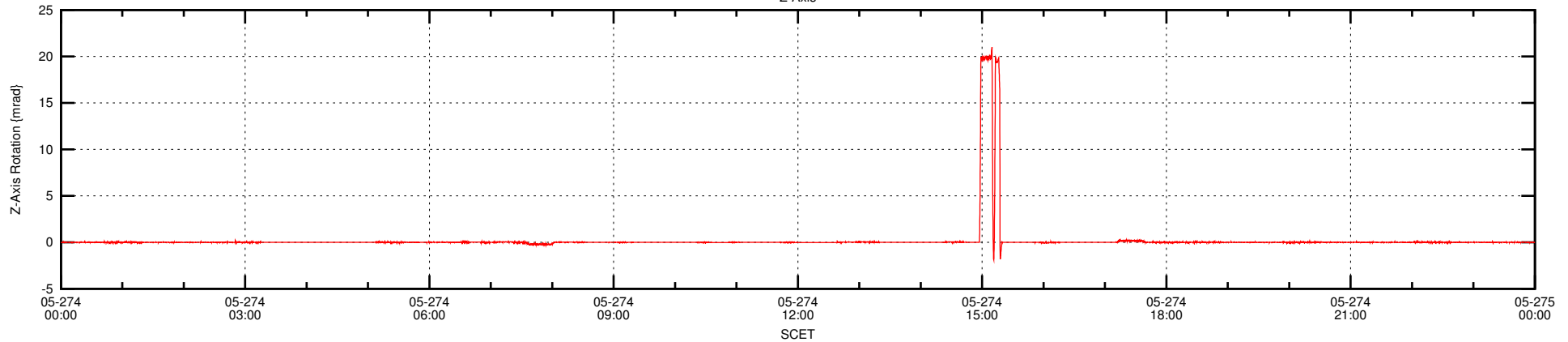
X-Axis (CK #1 = 05272_05277ra.bc; CK #2 = 05242_05281ph_fsiv.bc)



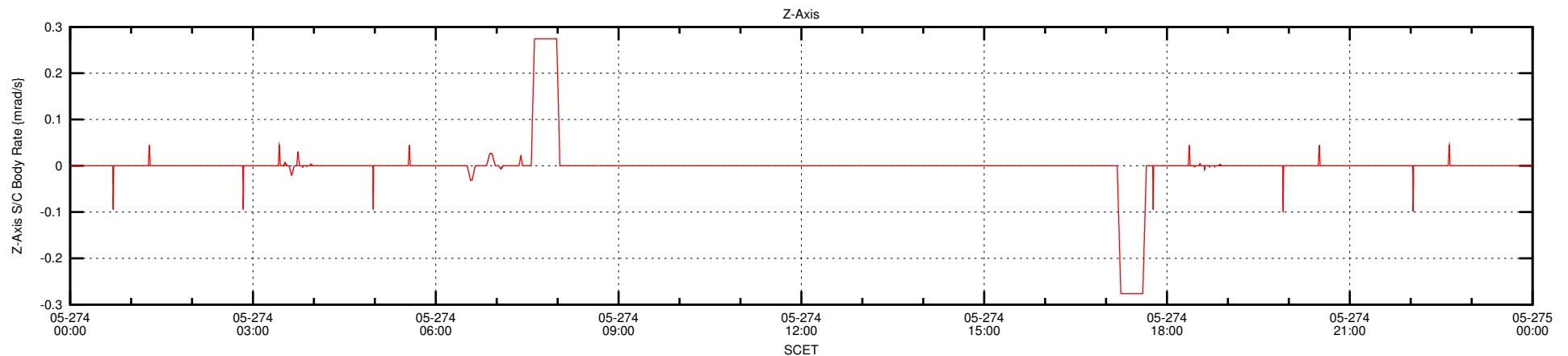
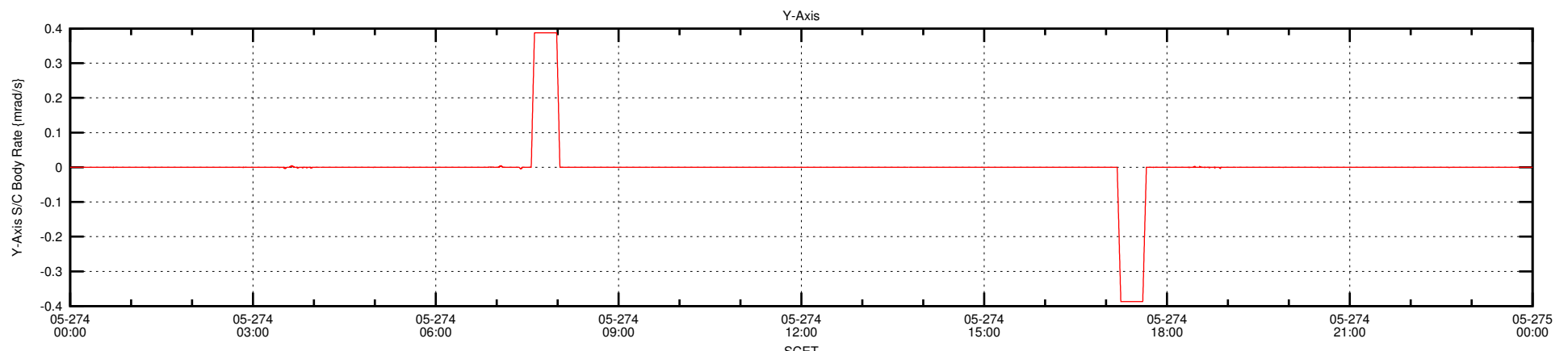
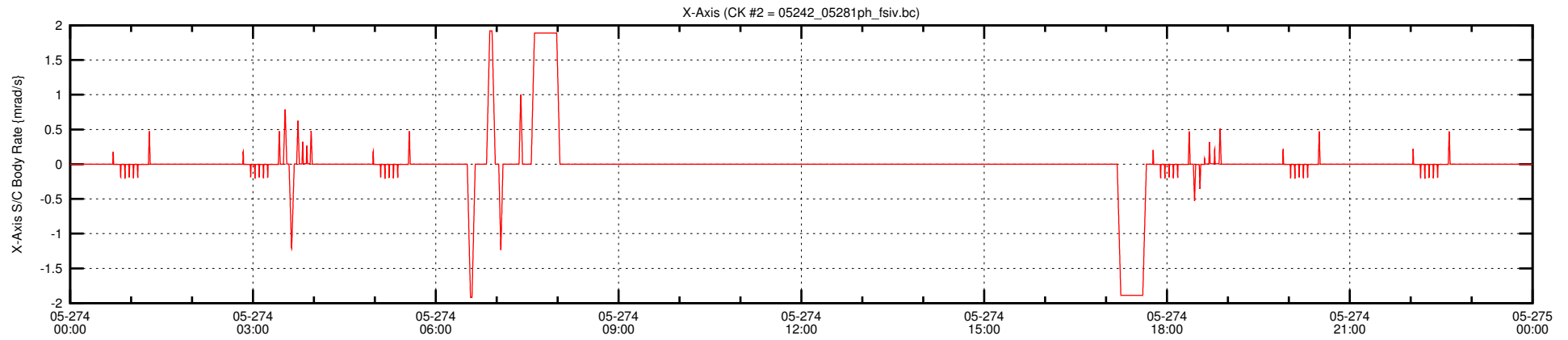
Y-Axis



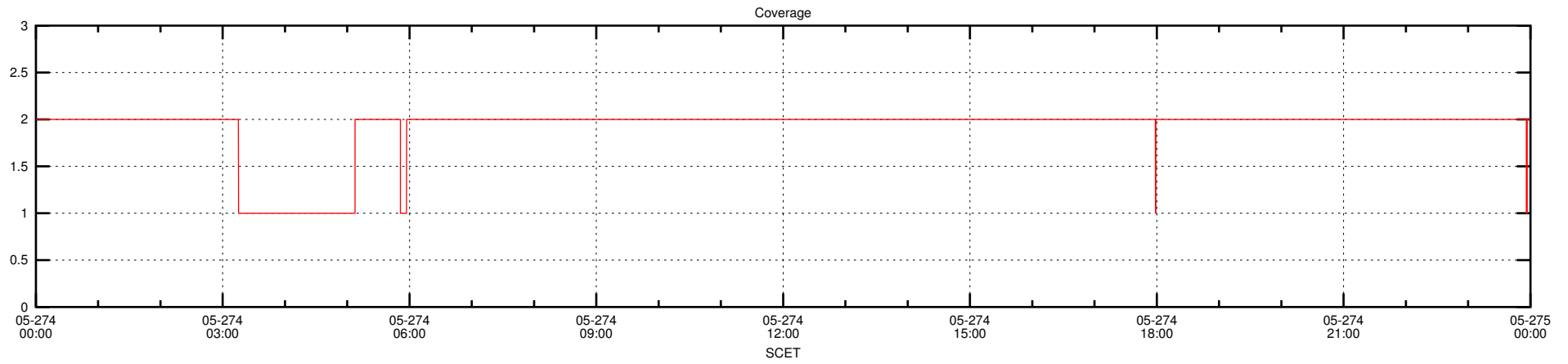
Z-Axis



CK #2 S/C Body Rates (DOY 274-275)

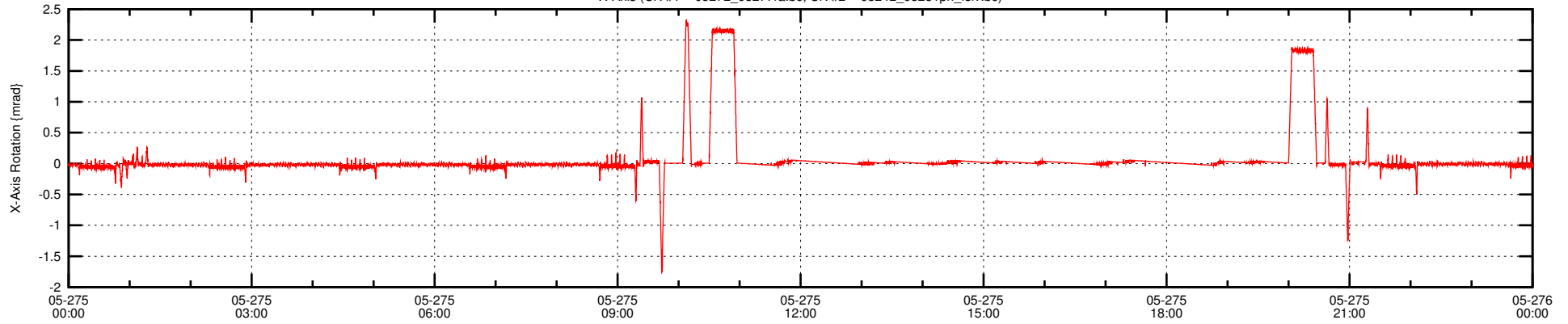


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 274-275)

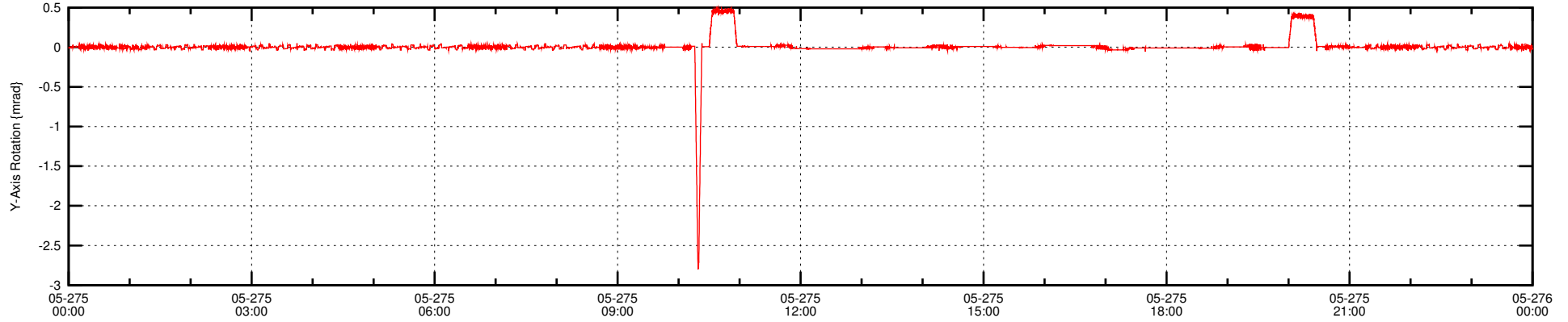


Rotation From CK #2 to CK #1 (DOY 275-276)

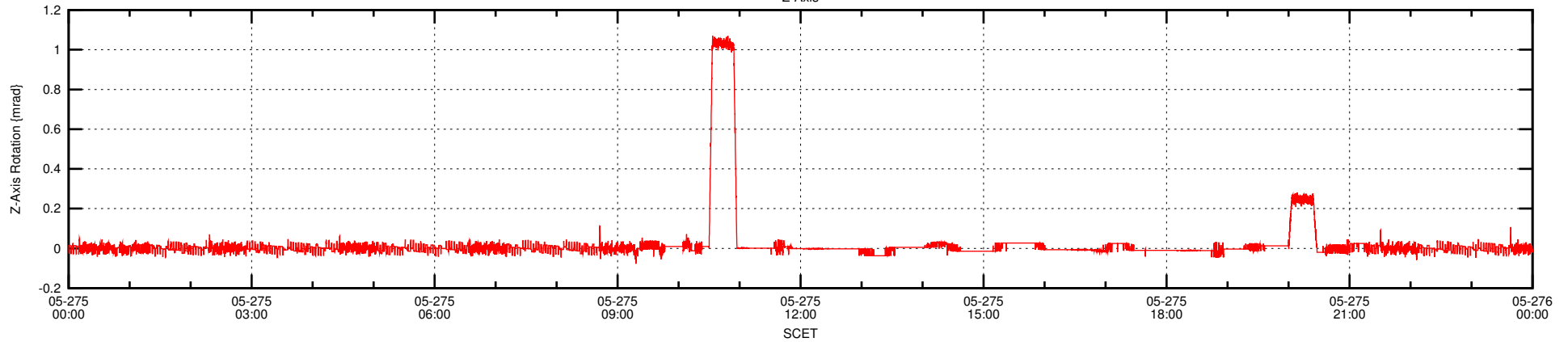
X-Axis (CK #1 = 05272_05277ra.bc; CK #2 = 05242_05281ph_fsiv.bc)



Y-Axis

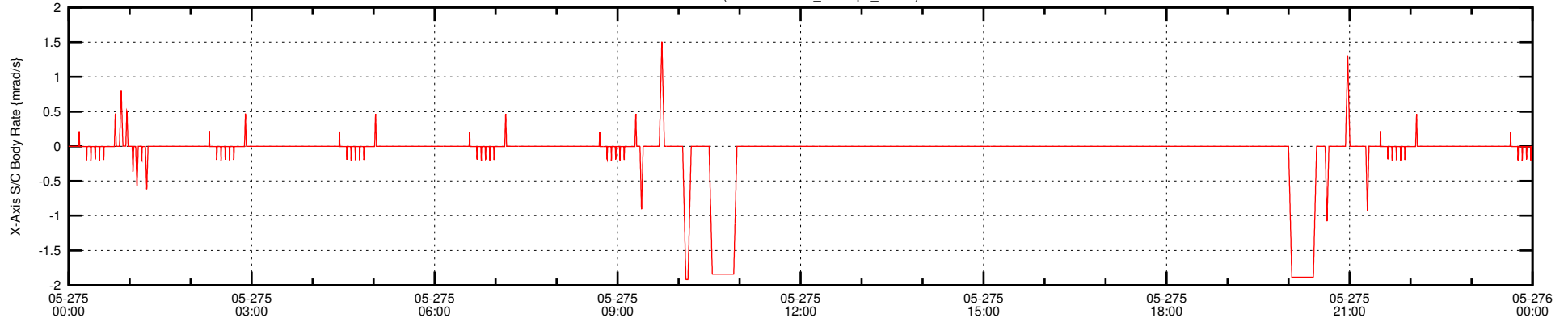


Z-Axis

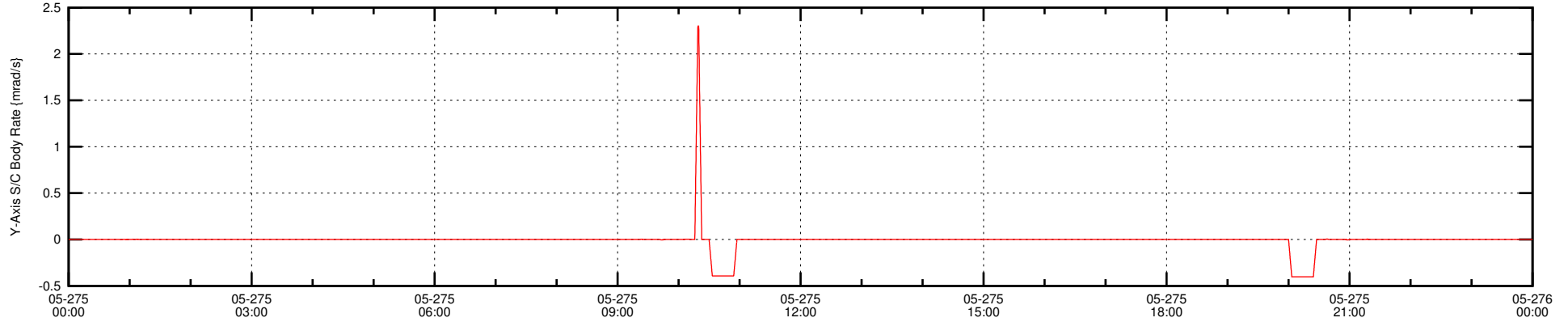


CK #2 S/C Body Rates (DOY 275-276)

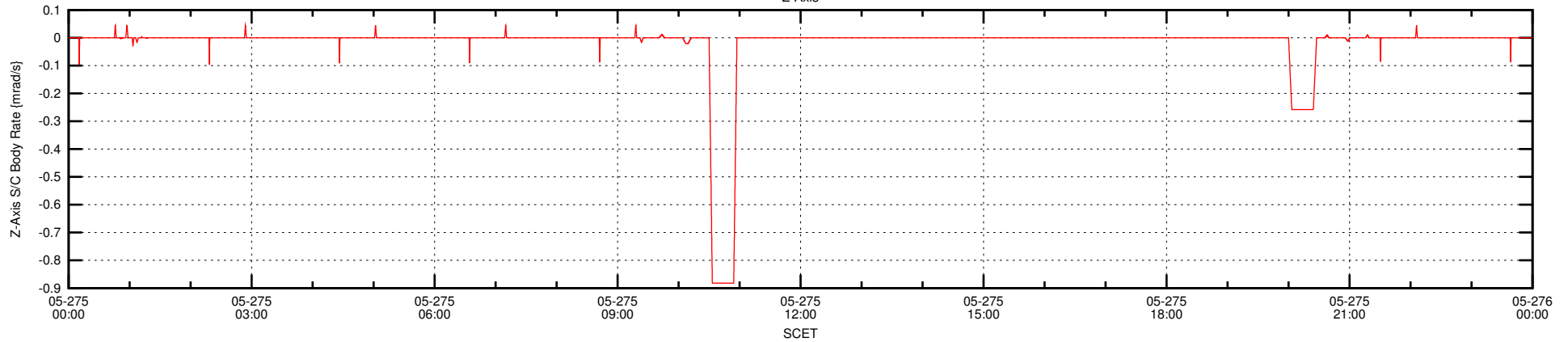
X-Axis (CK #2 = 05242_05281ph_fsiv.bc)



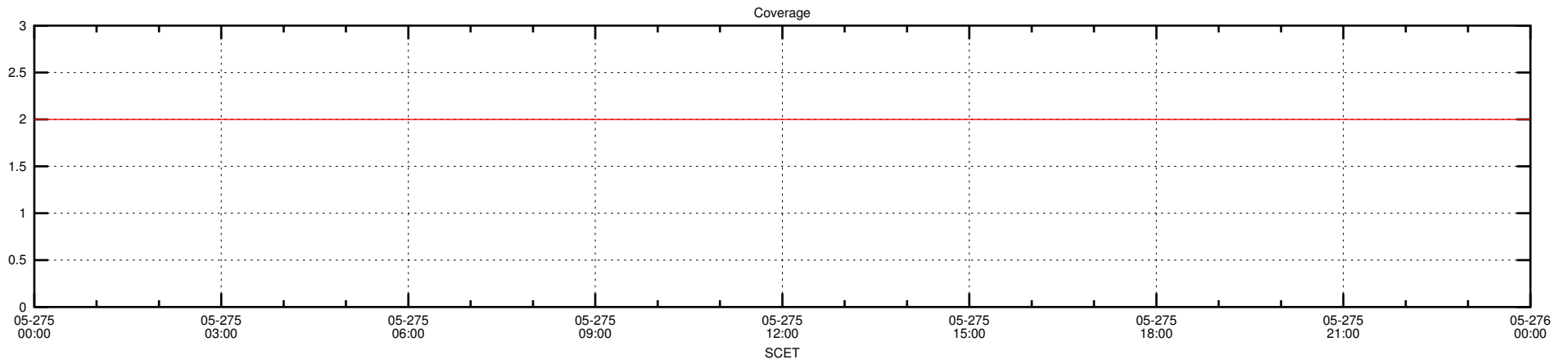
Y-Axis



Z-Axis

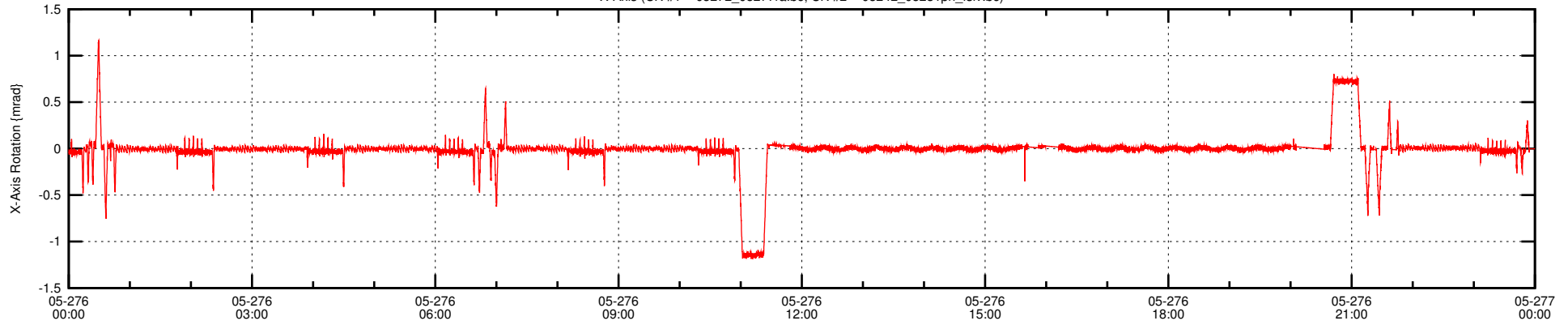


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 275-276)

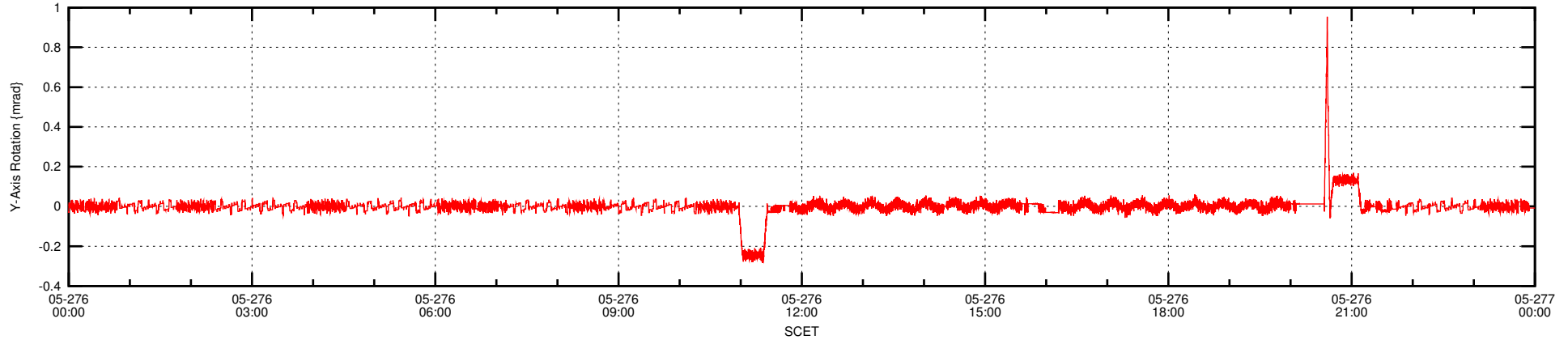


Rotation From CK #2 to CK #1 (DOY 276-276)

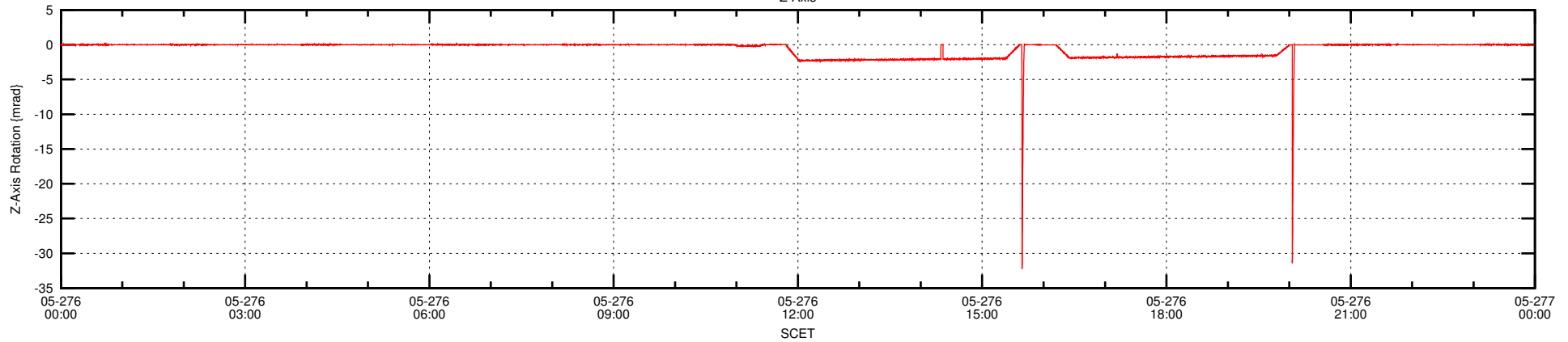
X-Axis (CK #1 = 05272_05277ra.bc; CK #2 = 05242_05281ph_fsiv.bc)



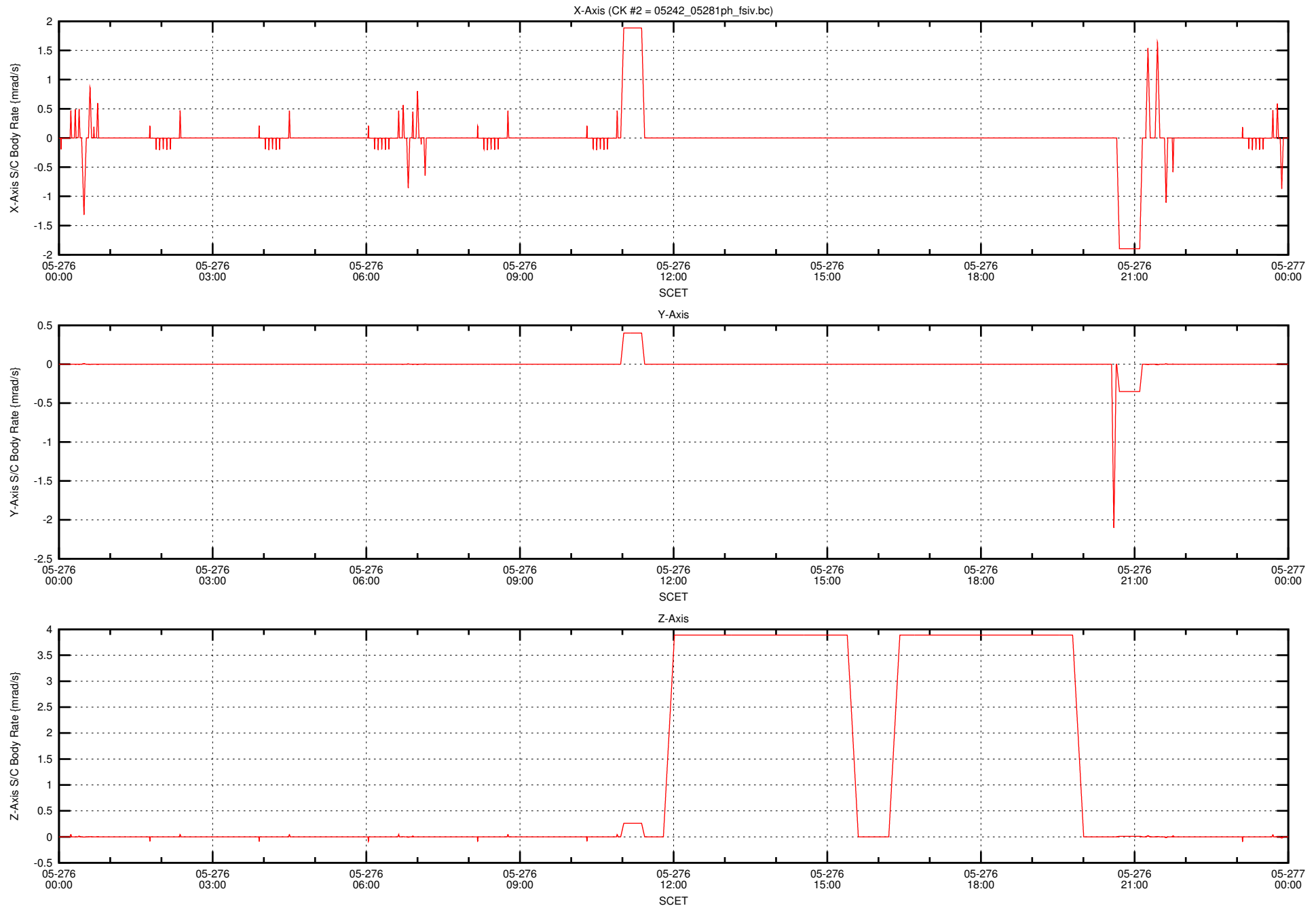
Y-Axis



Z-Axis



CK #2 S/C Body Rates (DOY 276-276)



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 276-276)

