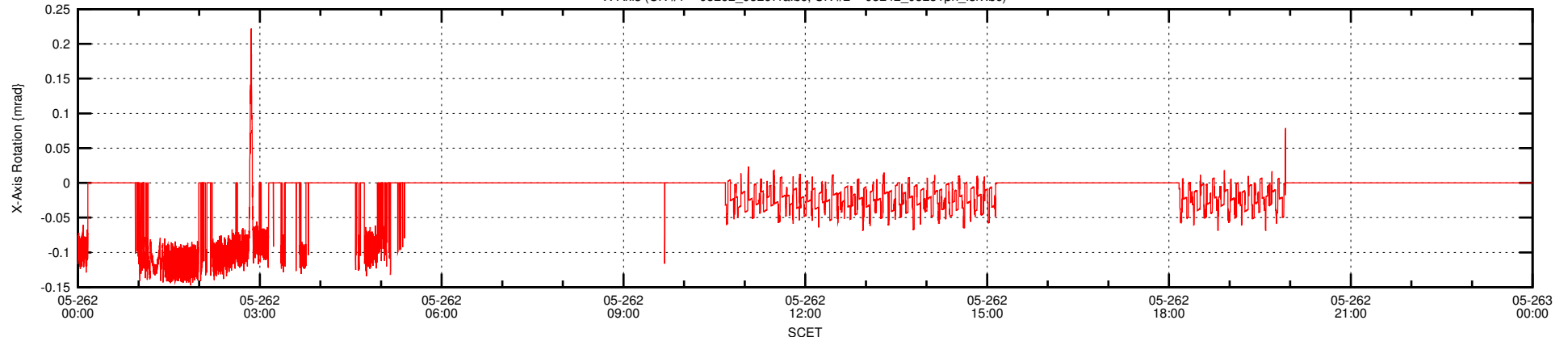
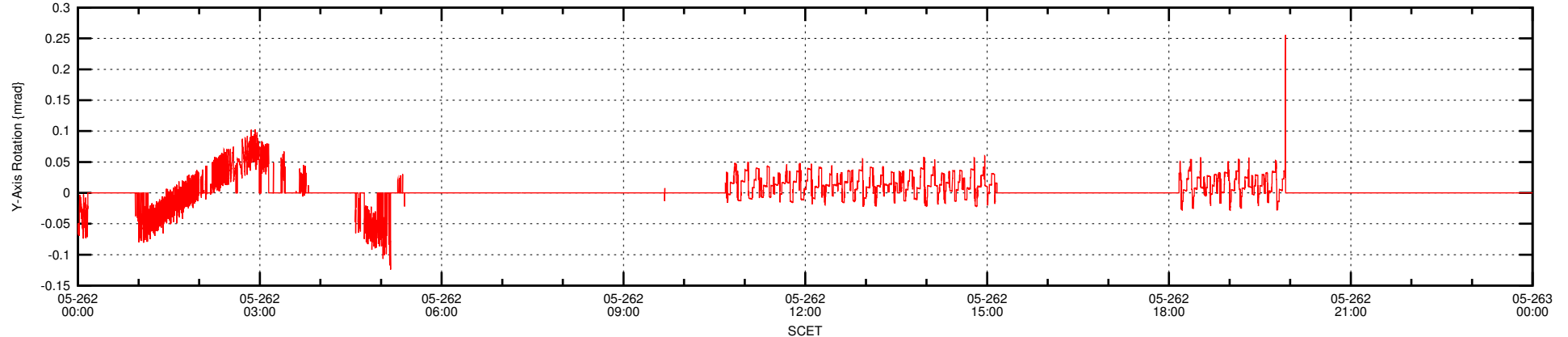


# Rotation From CK #2 to CK #1 (DOY 262-263)

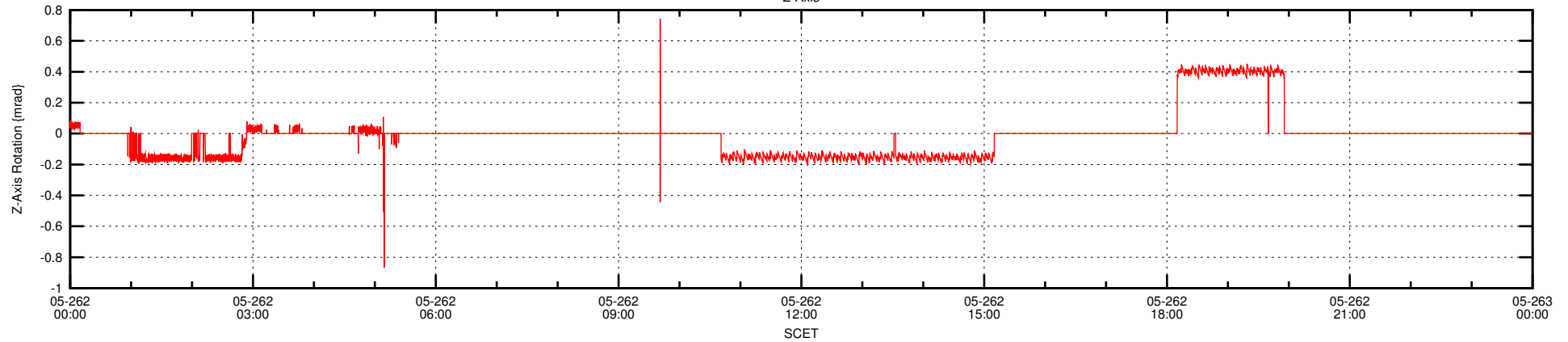
X-Axis (CK #1 = 05262\_05267ra.bc; CK #2 = 05242\_05281ph\_fsiv.bc)



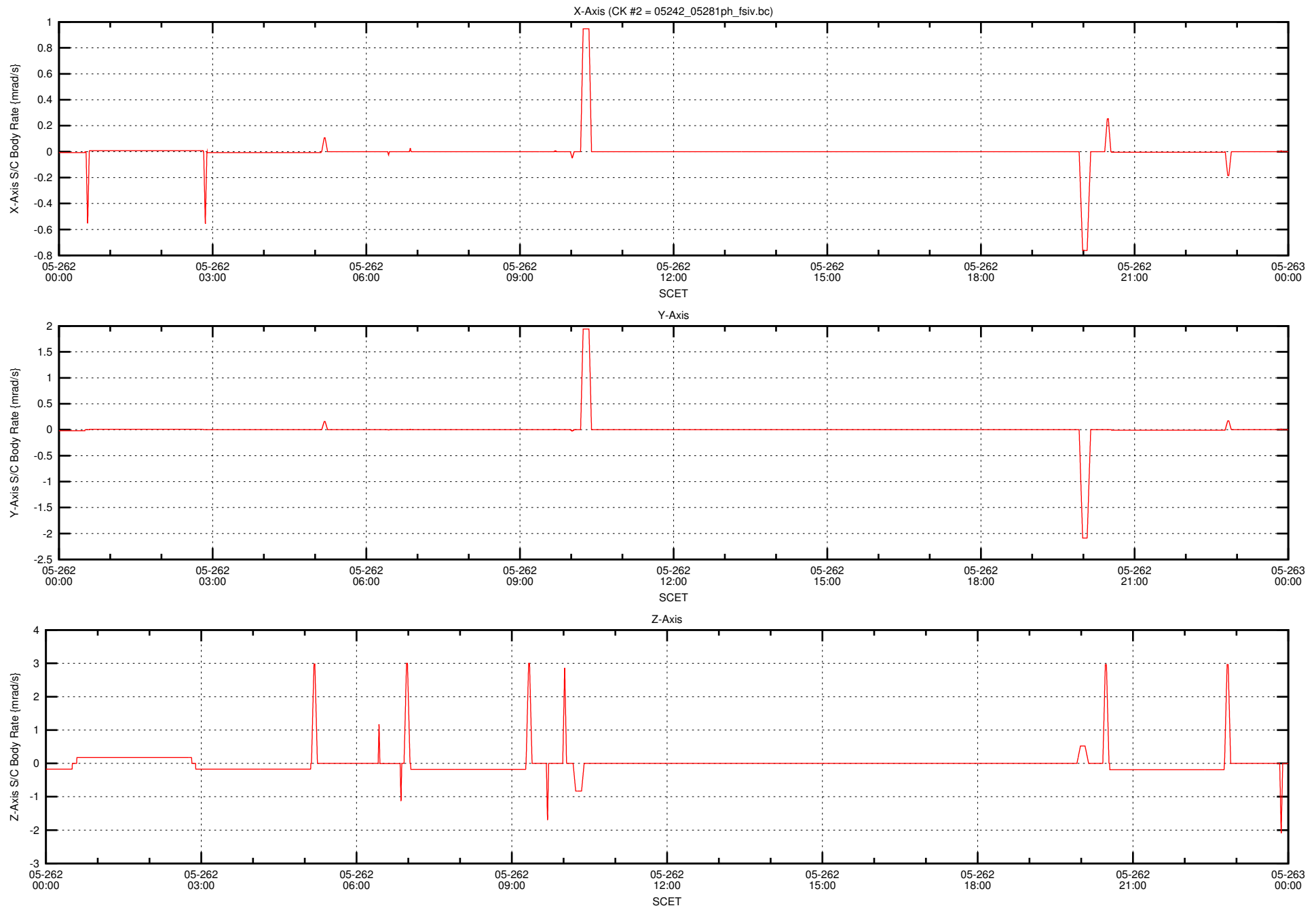
Y-Axis



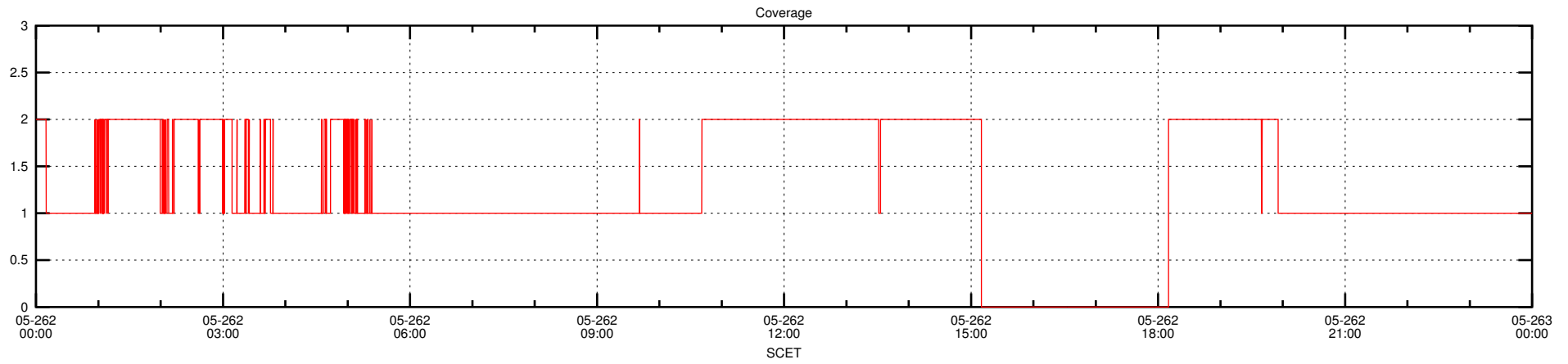
Z-Axis



# CK #2 S/C Body Rates (DOY 262-263)

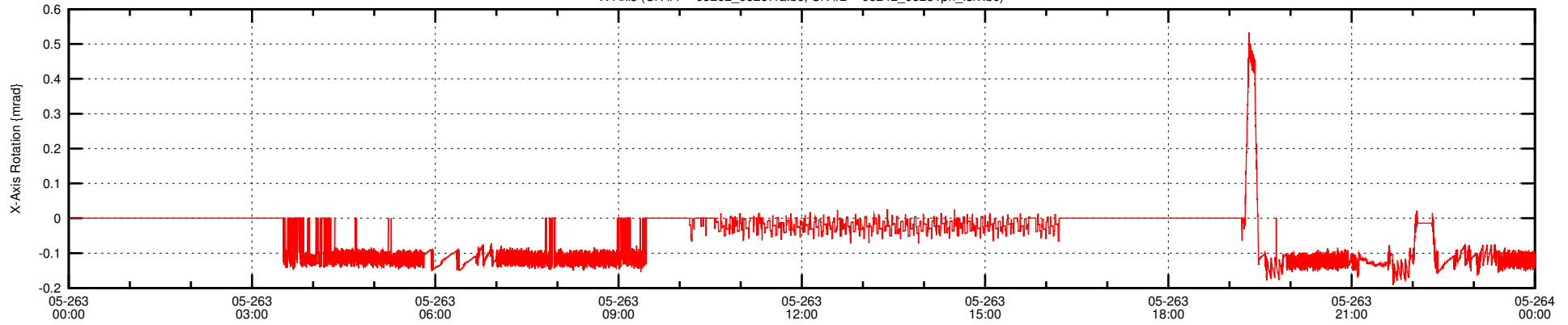


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 262-263)

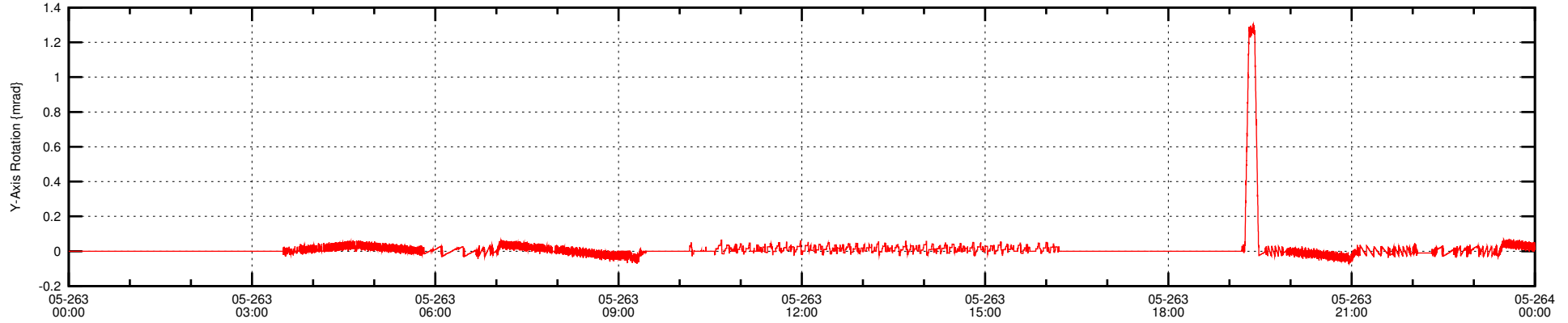


# Rotation From CK #2 to CK #1 (DOY 263-264)

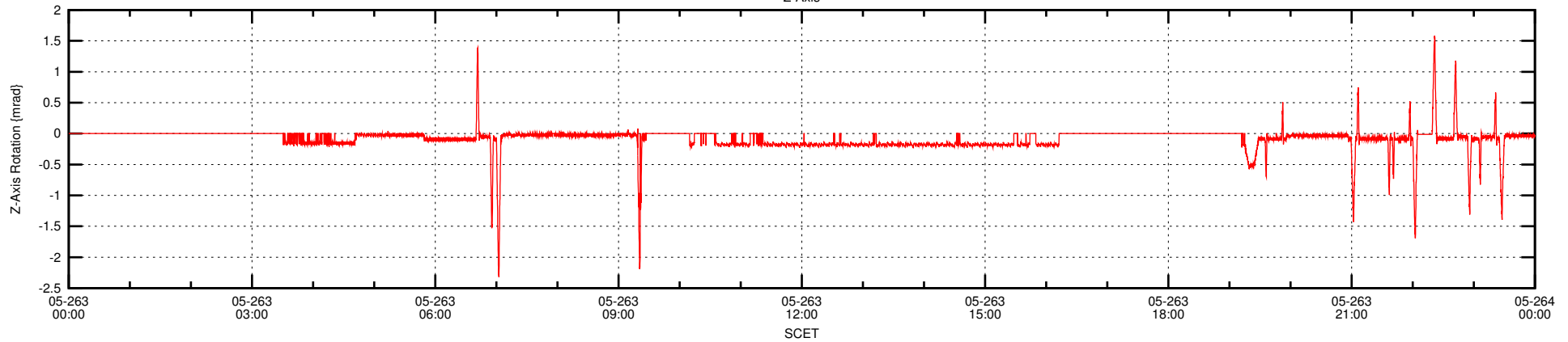
X-Axis (CK #1 = 05262\_05267ra.bc; CK #2 = 05242\_05281ph\_fsiv.bc)



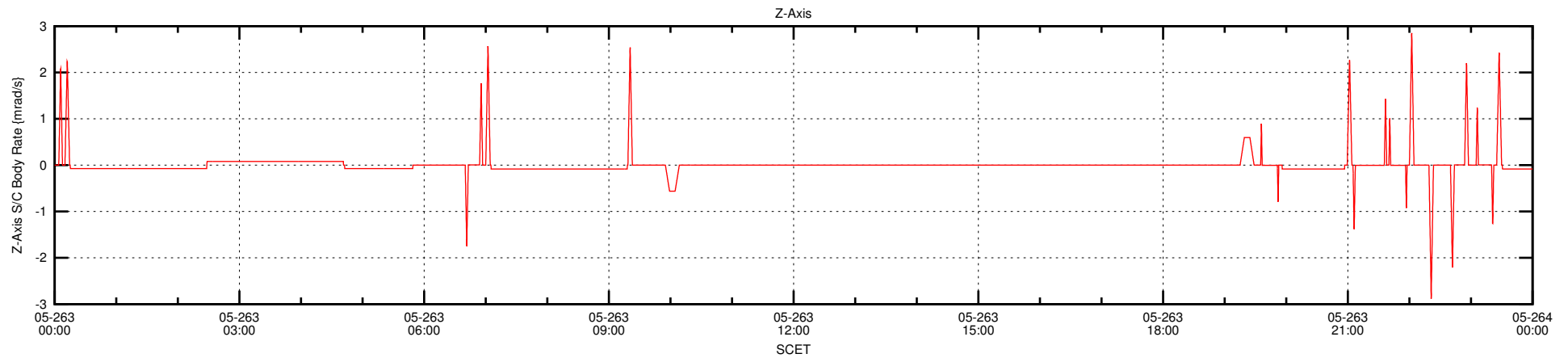
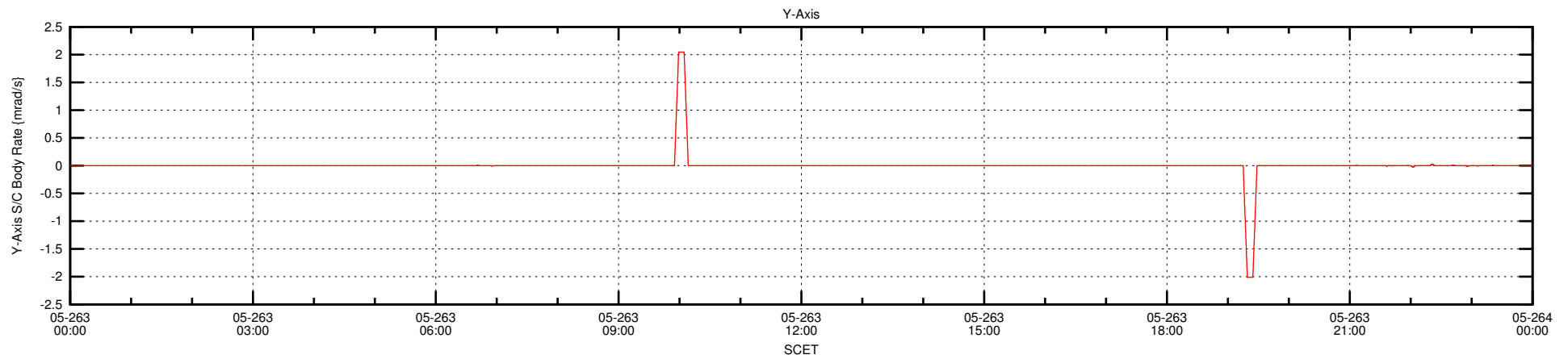
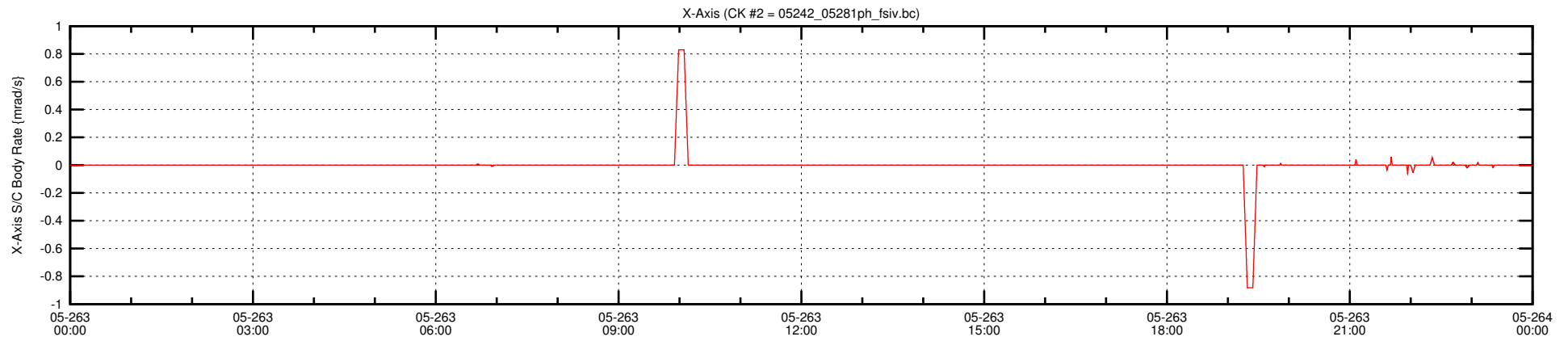
Y-Axis



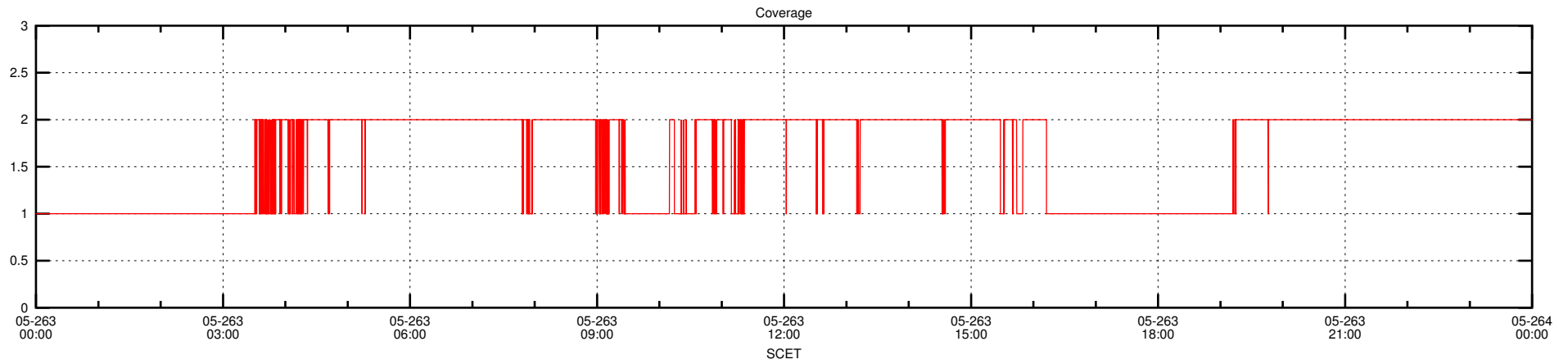
Z-Axis



# CK #2 S/C Body Rates (DOY 263-264)

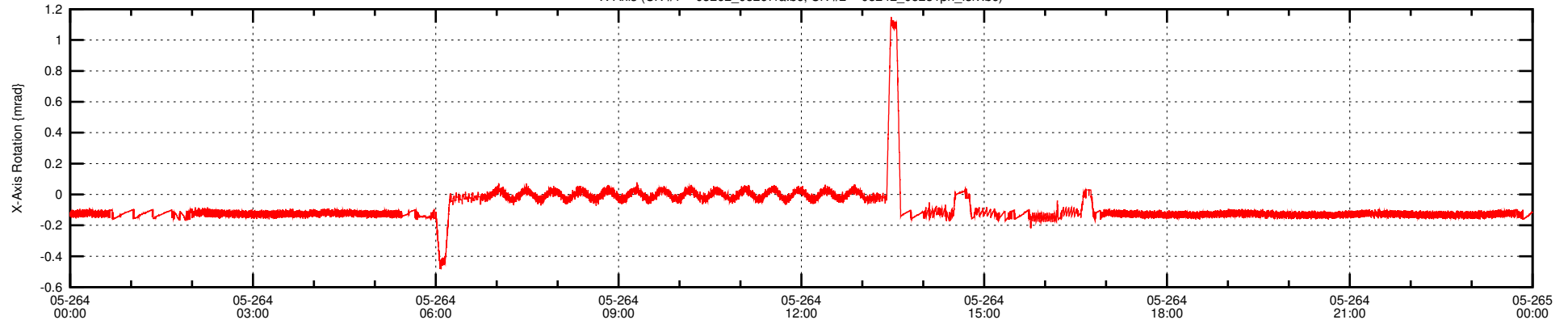


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 263-264)

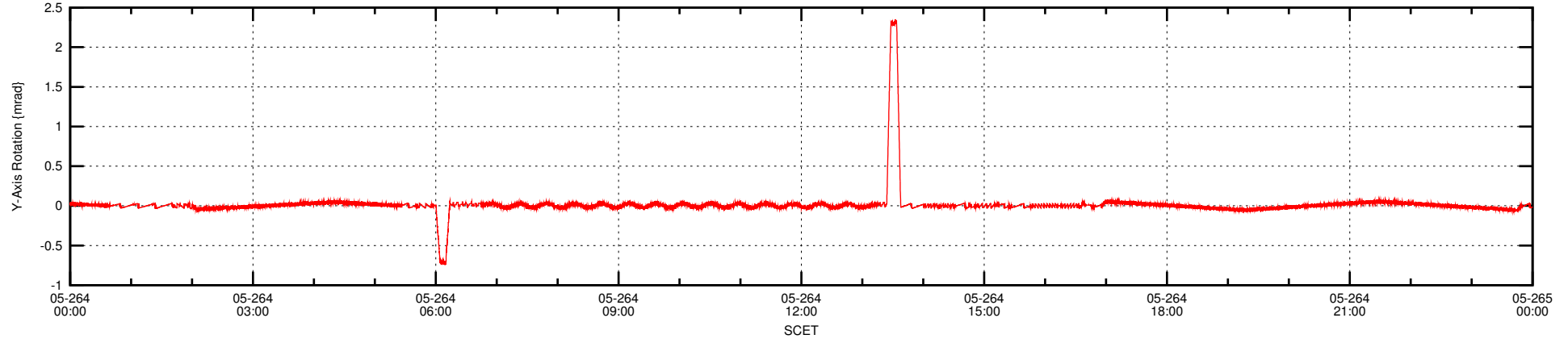


# Rotation From CK #2 to CK #1 (DOY 264-265)

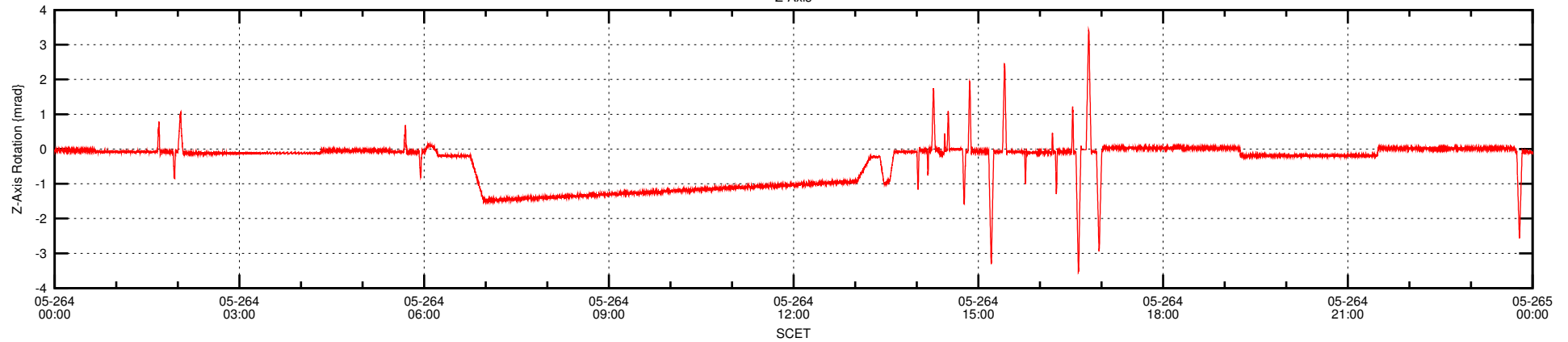
X-Axis (CK #1 = 05262\_05267ra.bc; CK #2 = 05242\_05281ph\_fsiv.bc)



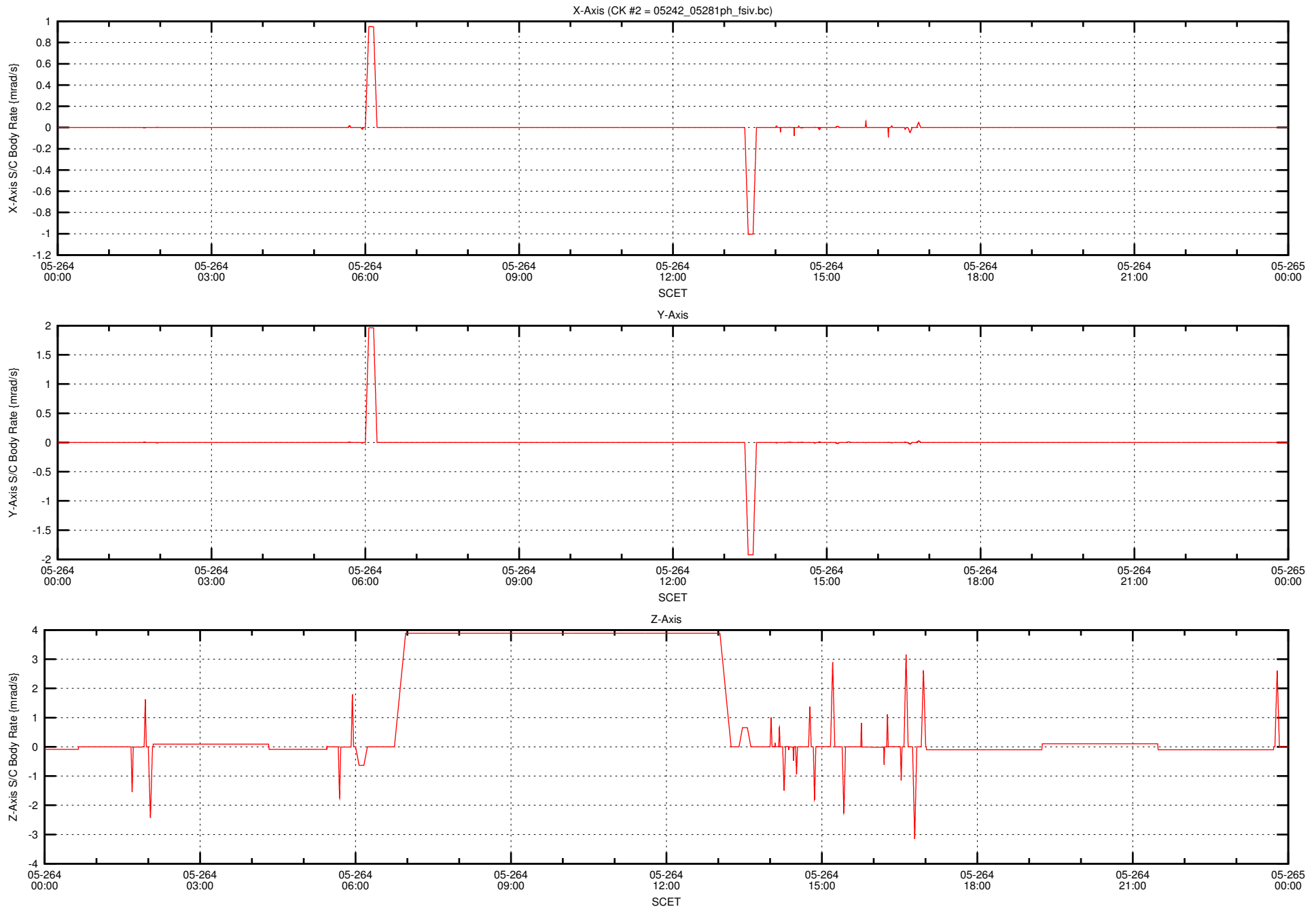
Y-Axis



Z-Axis

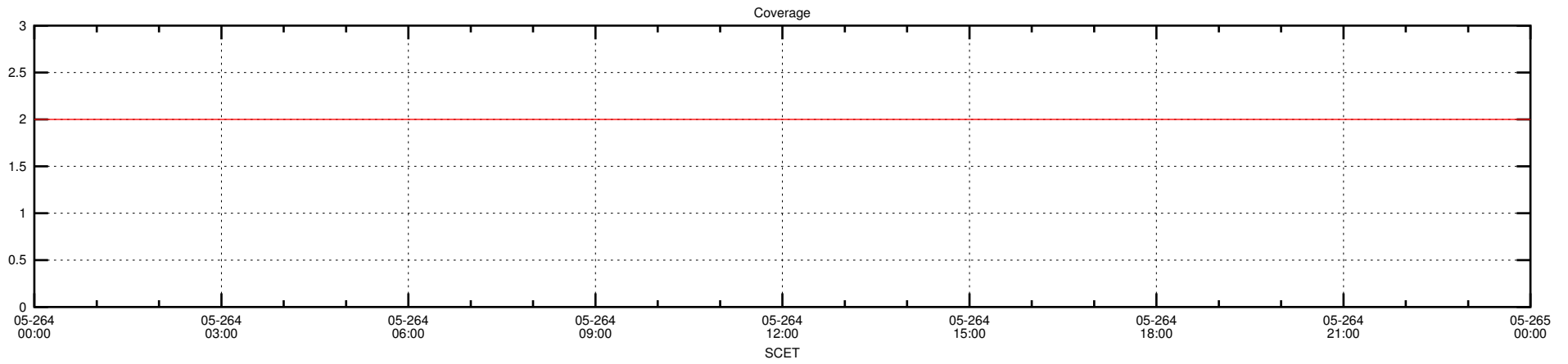


# CK #2 S/C Body Rates (DOY 264-265)



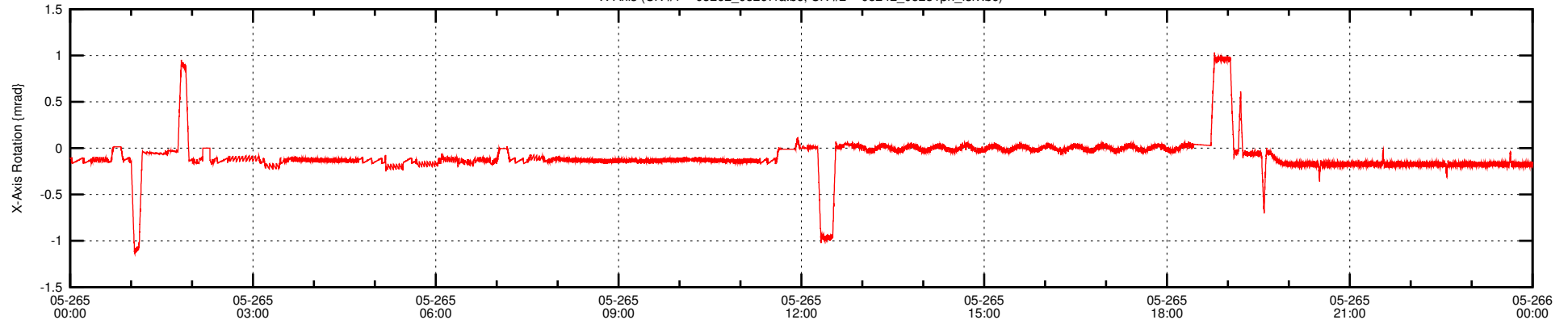


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 264-265)

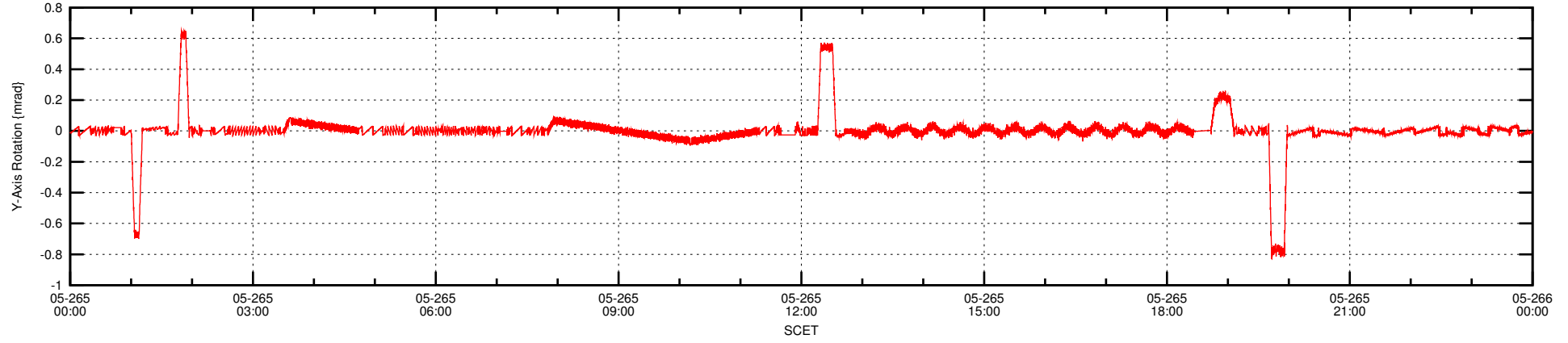


# Rotation From CK #2 to CK #1 (DOY 265-266)

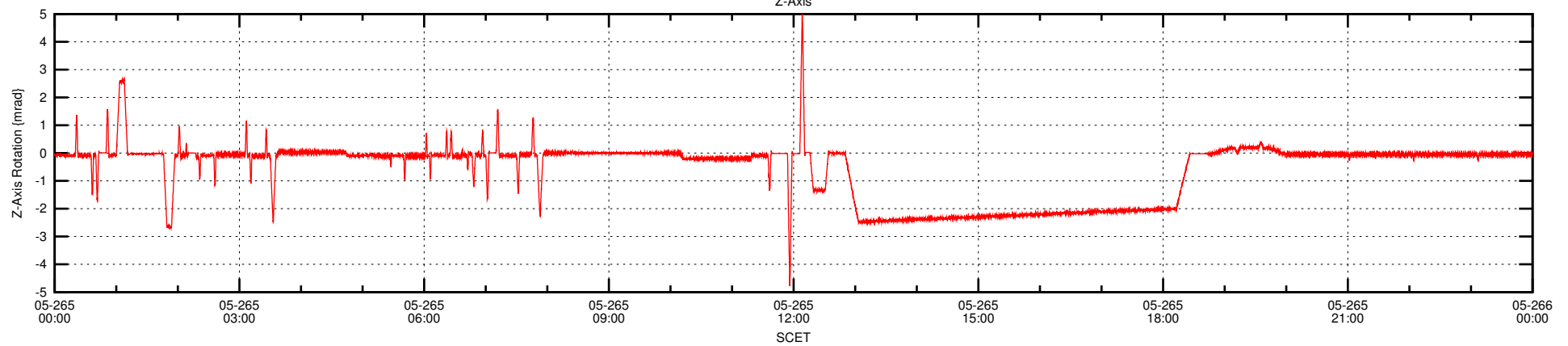
X-Axis (CK #1 = 05262\_05267ra.bc; CK #2 = 05242\_05281ph\_fsiv.bc)



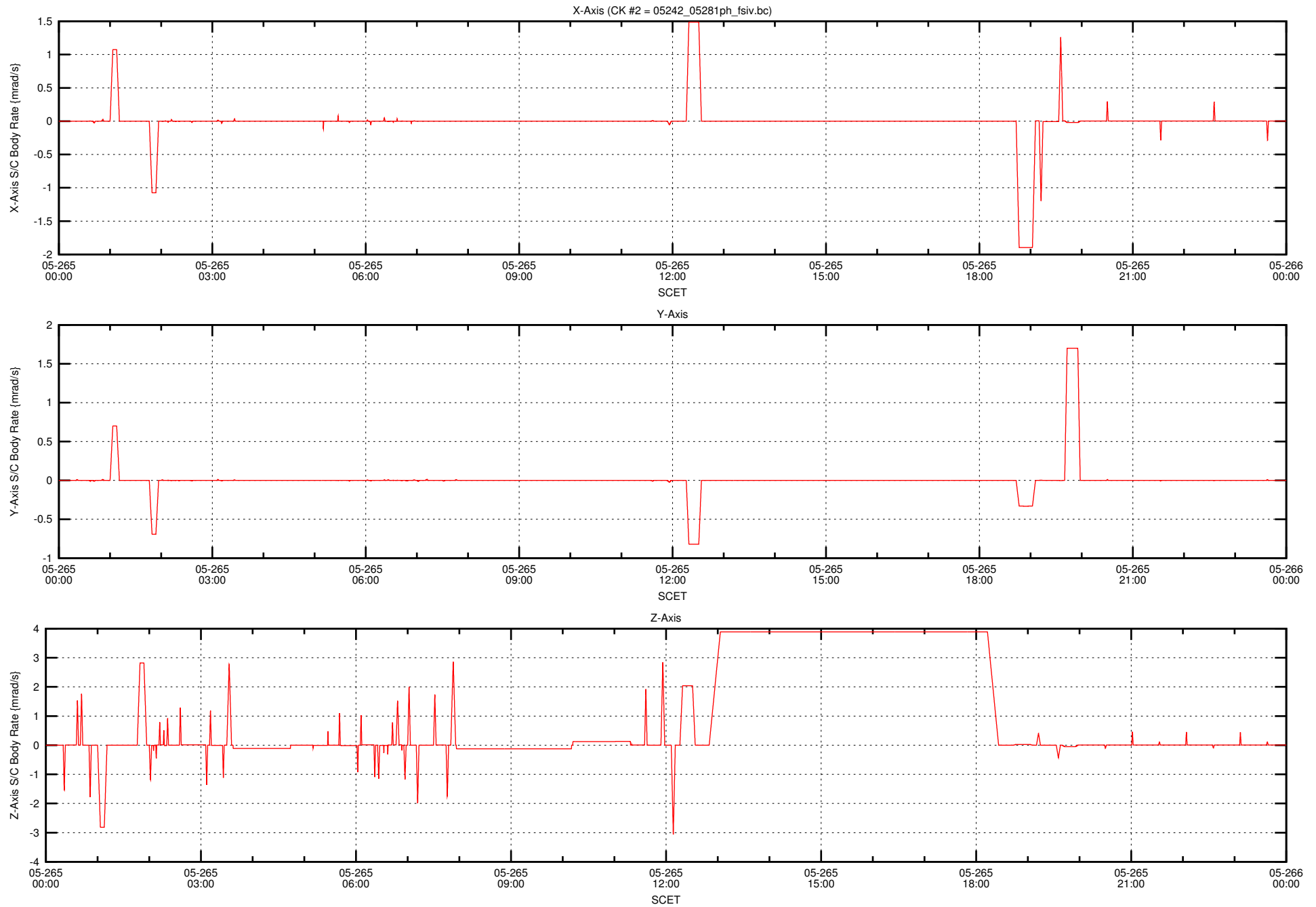
Y-Axis



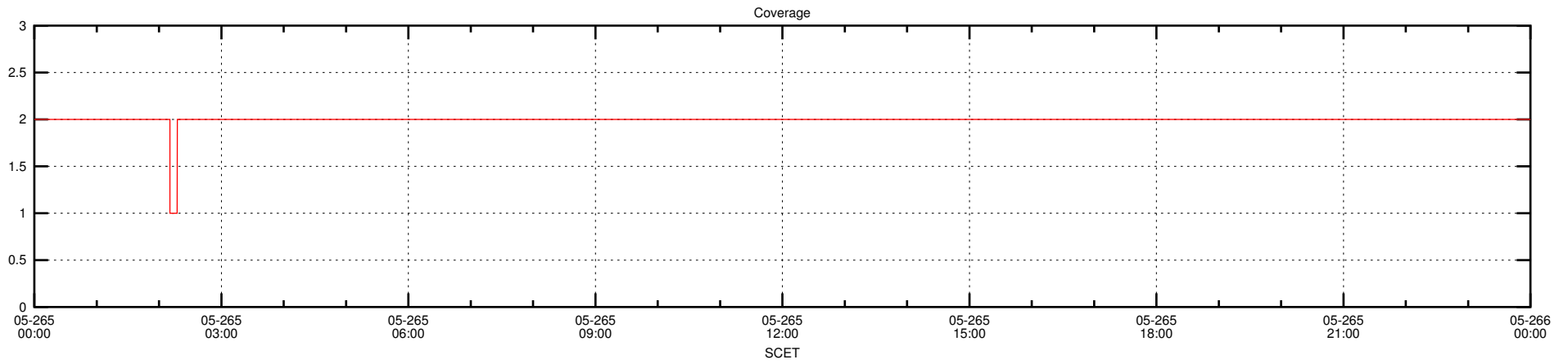
Z-Axis



# CK #2 S/C Body Rates (DOY 265-266)

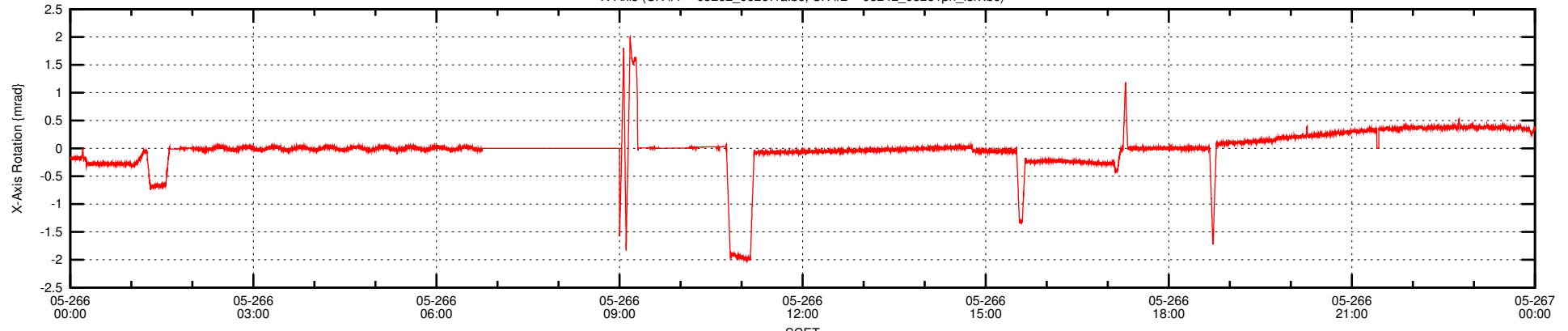


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 265-266)

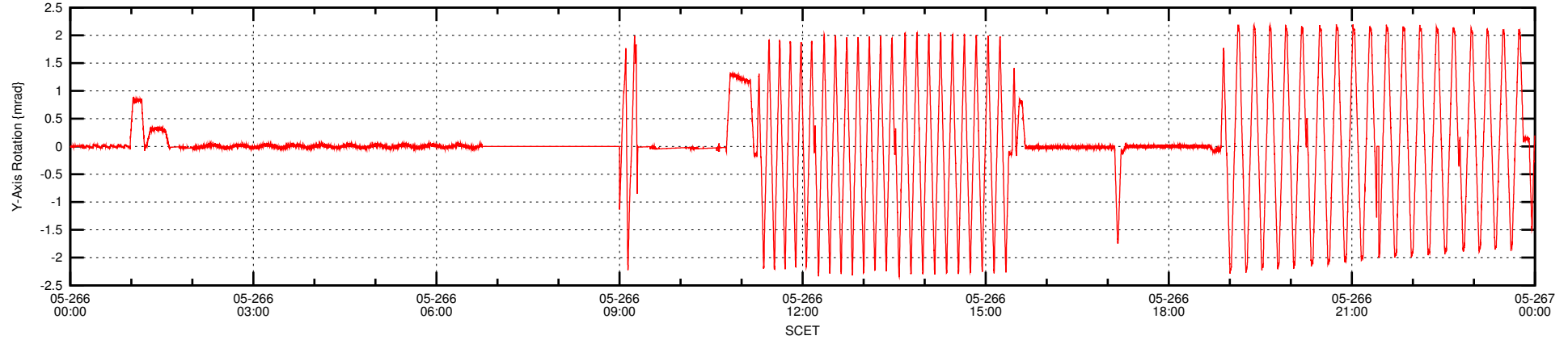


# Rotation From CK #2 to CK #1 (DOY 266-266)

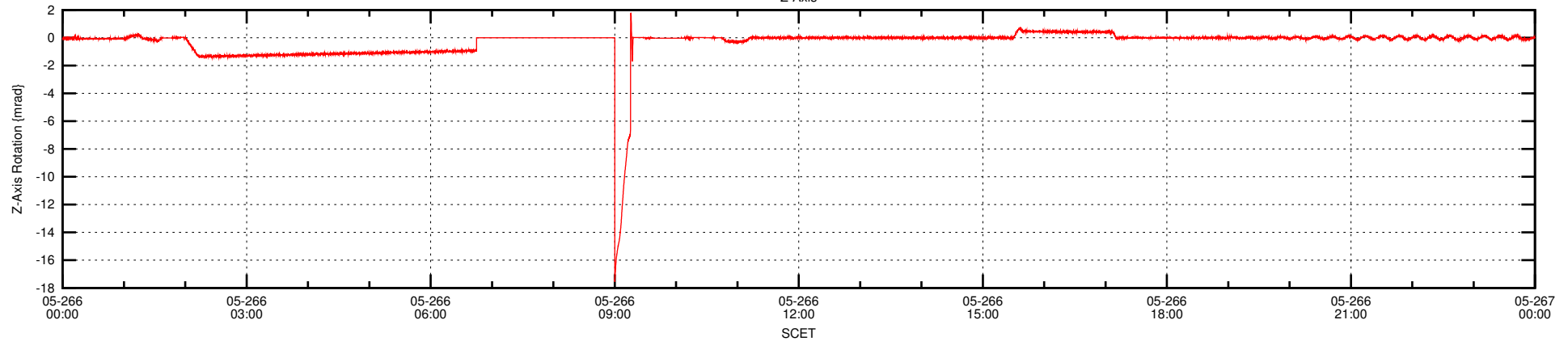
X-Axis (CK #1 = 05262\_05267ra.bc; CK #2 = 05242\_05281ph\_fsiv.bc)



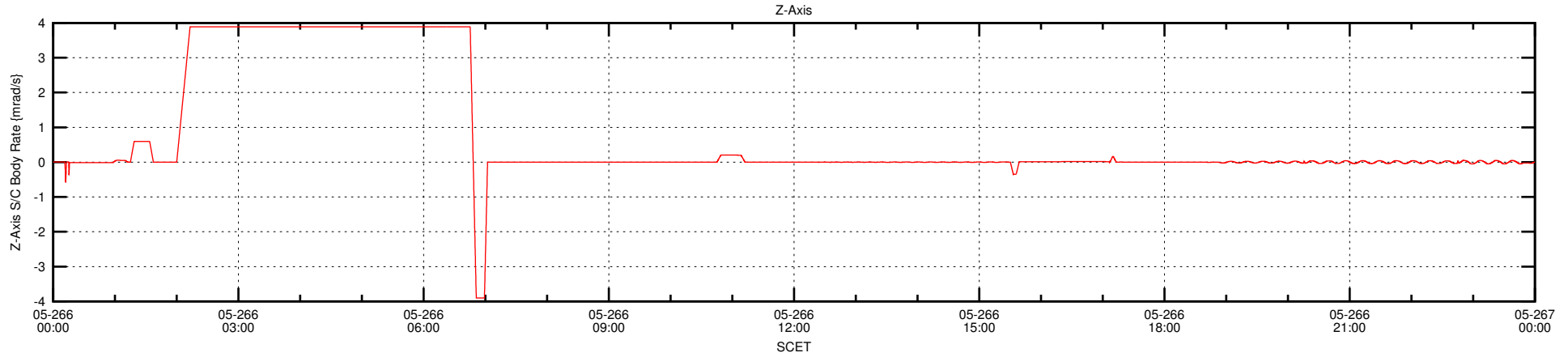
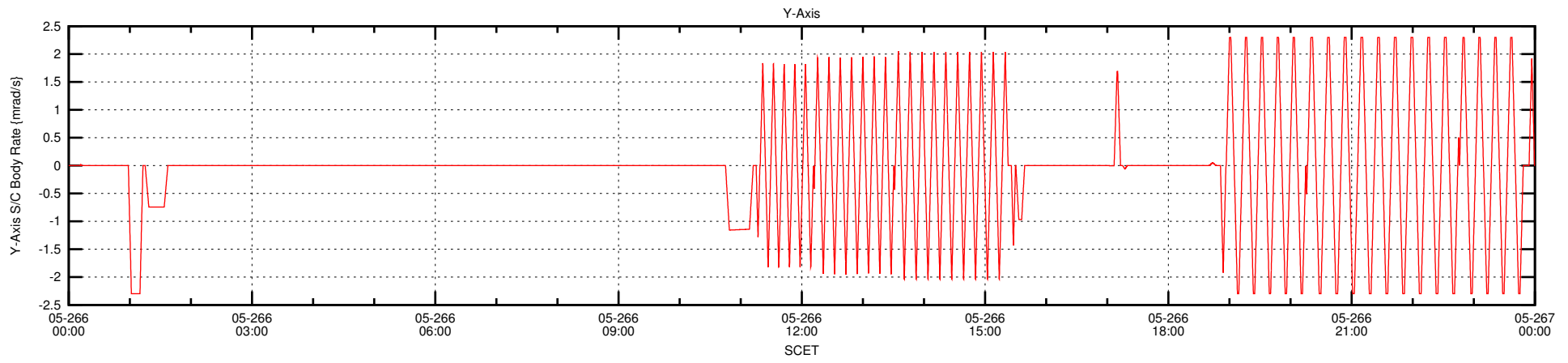
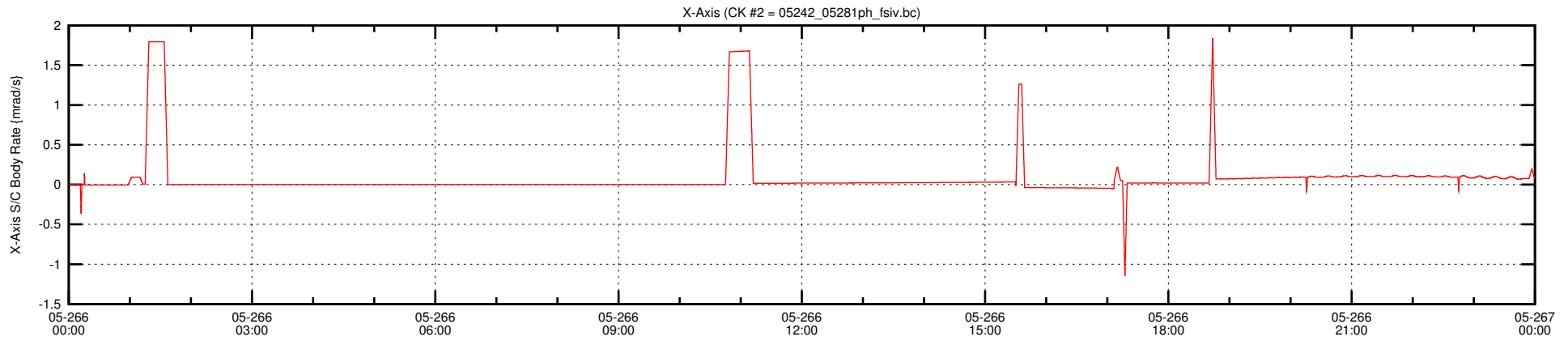
Y-Axis



Z-Axis



# CK #2 S/C Body Rates (DOY 266-266)



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 266-266)

