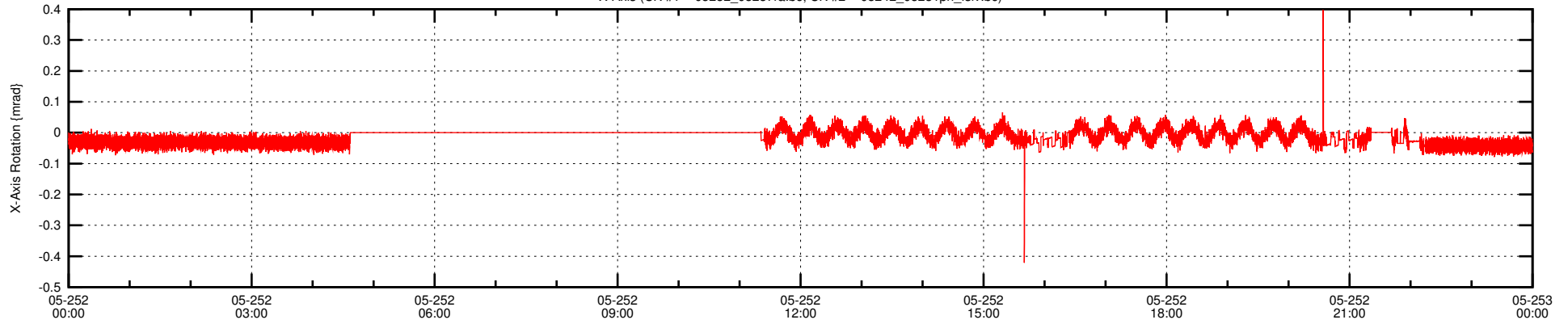
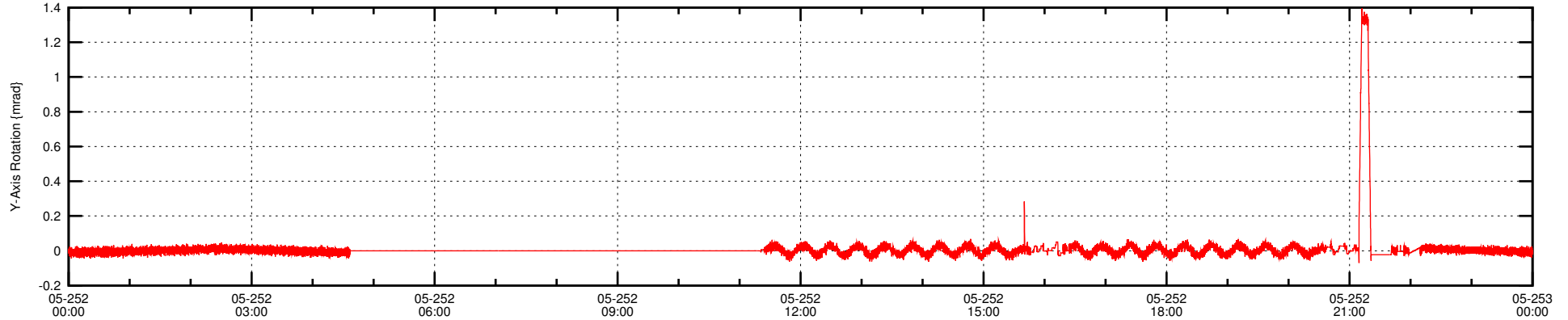


Rotation From CK #2 to CK #1 (DOY 252-253)

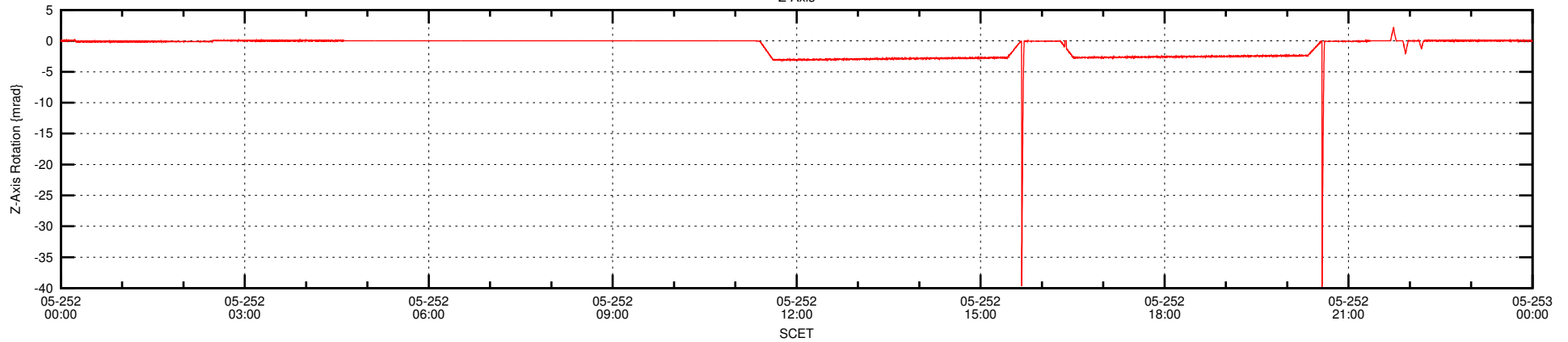
X-Axis (CK #1 = 05252_05257ra.bc; CK #2 = 05242_05281ph_fsiv.bc)



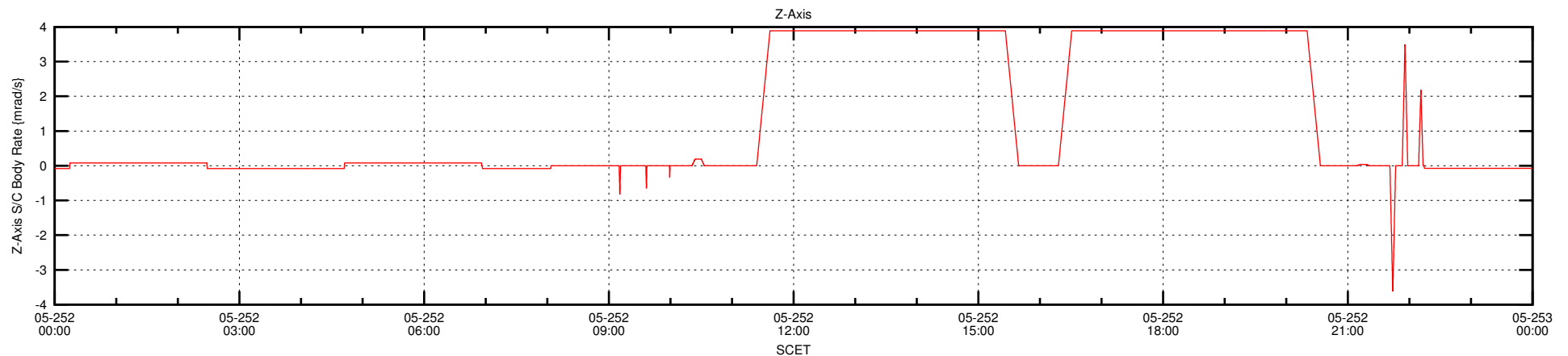
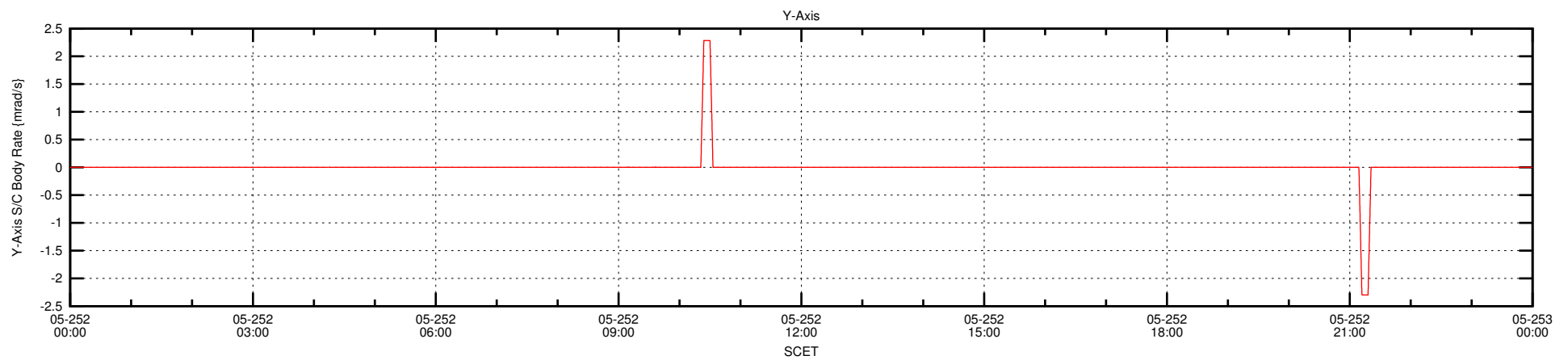
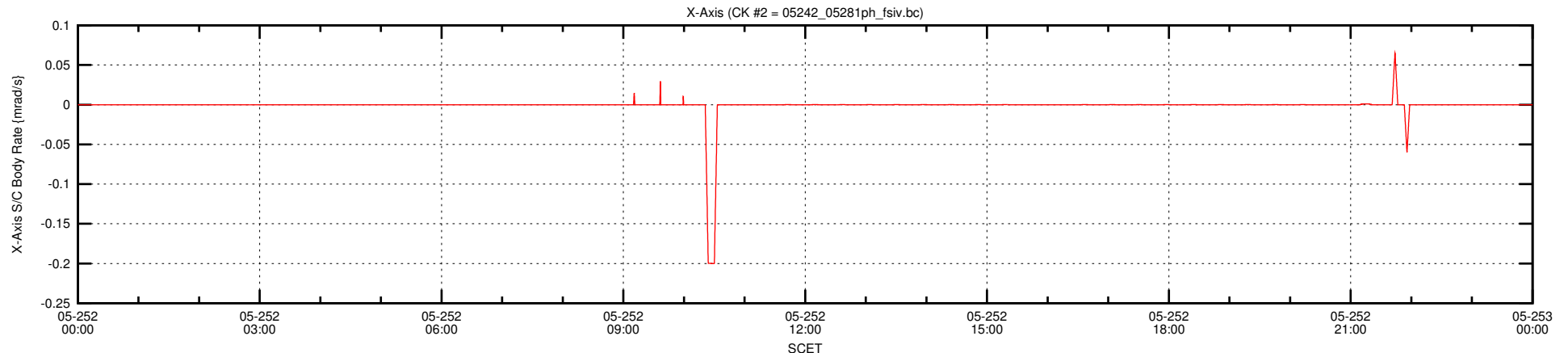
Y-Axis



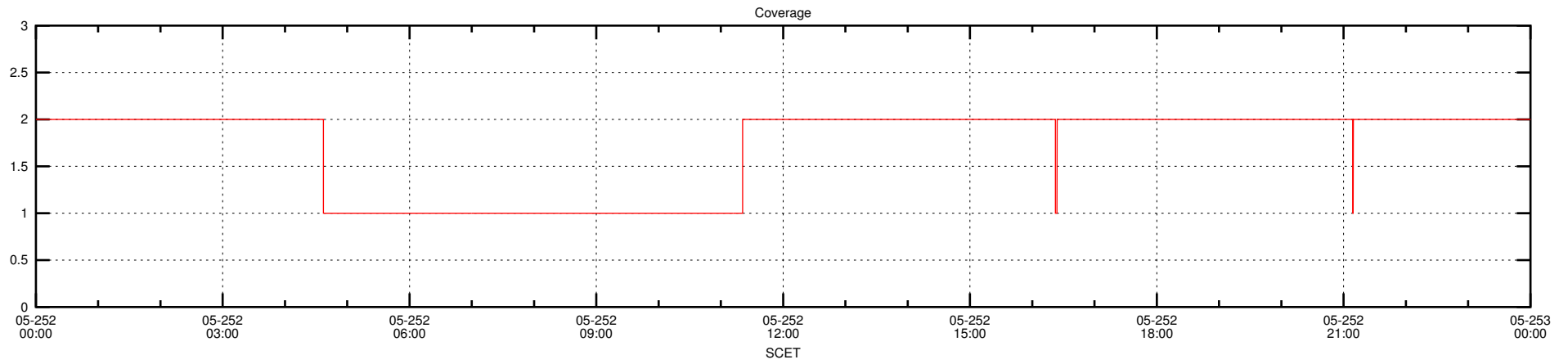
Z-Axis



CK #2 S/C Body Rates (DOY 252-253)

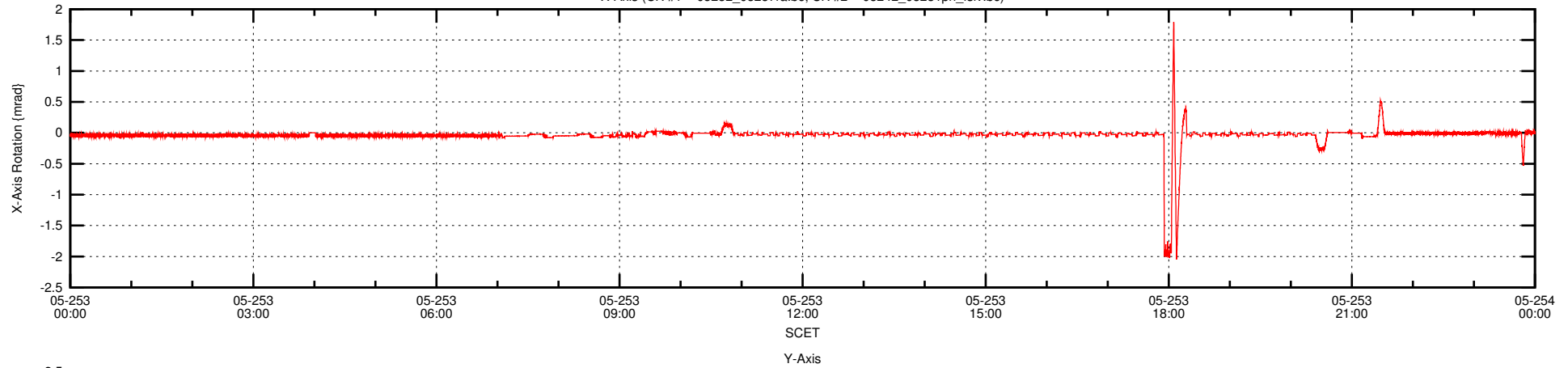


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 252-253)

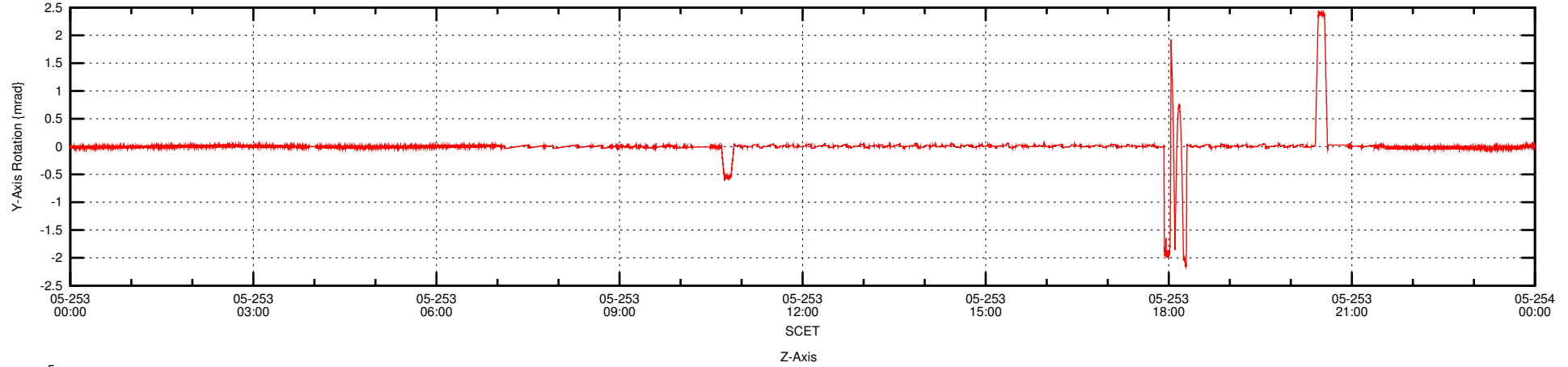


Rotation From CK #2 to CK #1 (DOY 253-254)

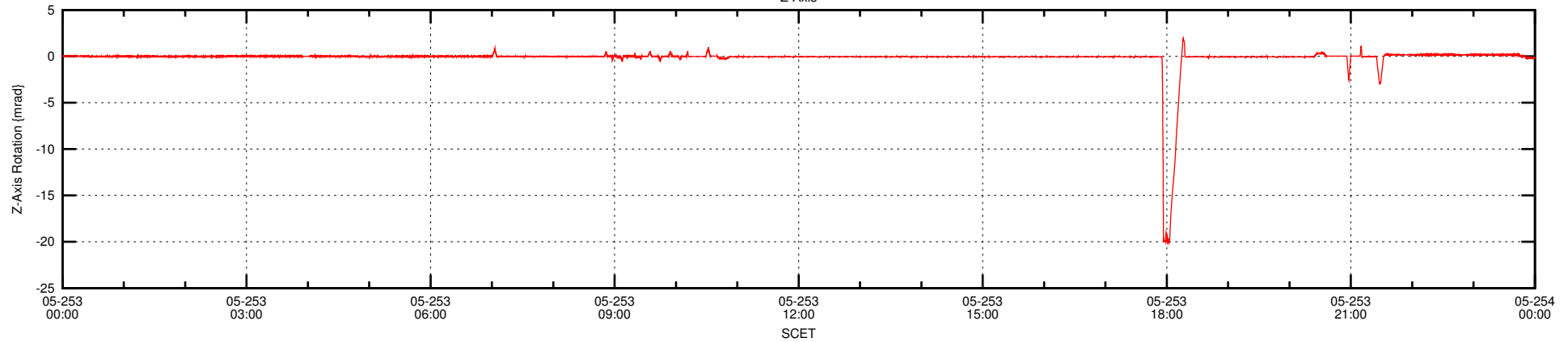
X-Axis (CK #1 = 05252_05257ra.bc; CK #2 = 05242_05281ph_fsiv.bc)



Y-Axis

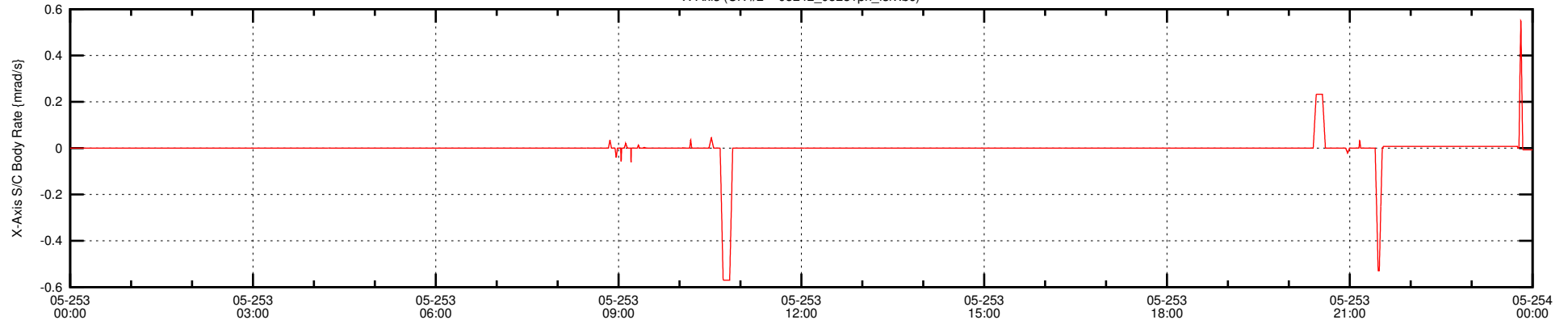


Z-Axis

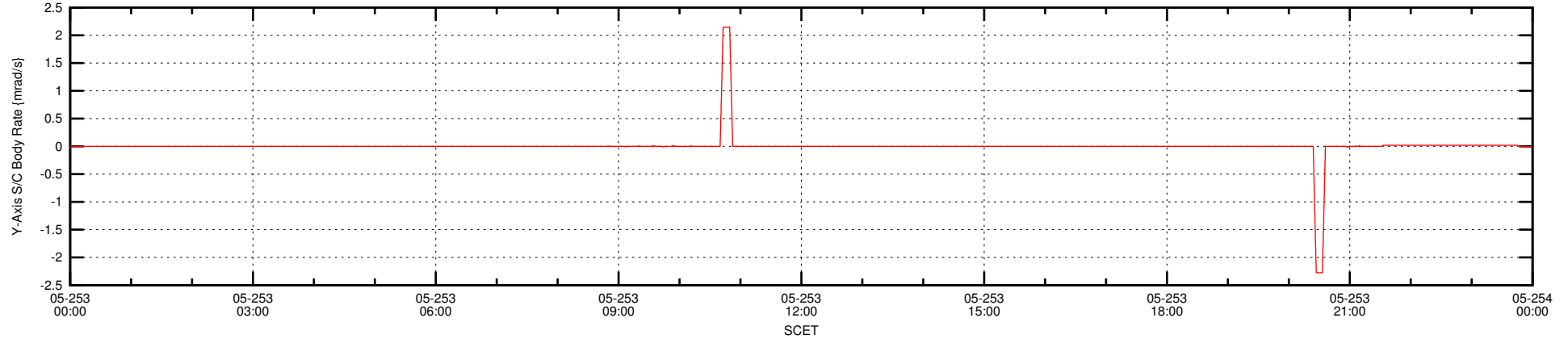


CK #2 S/C Body Rates (DOY 253-254)

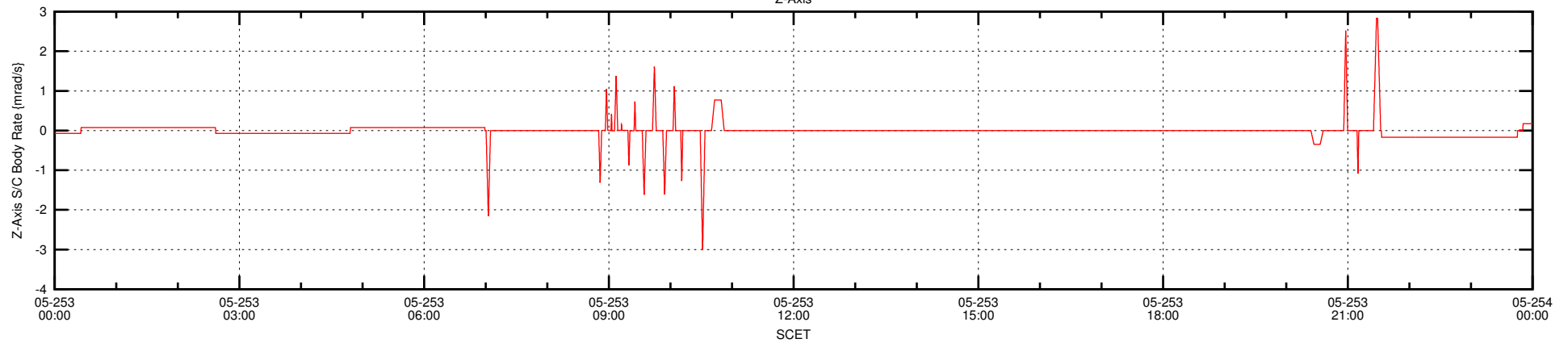
X-Axis (CK #2 = 05242_05281ph_fsiv.bc)



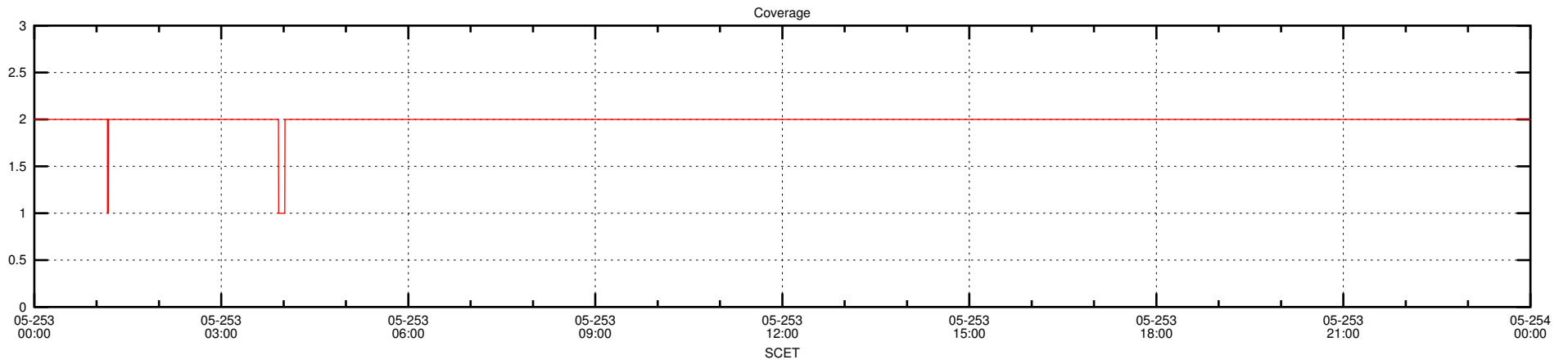
Y-Axis



Z-Axis

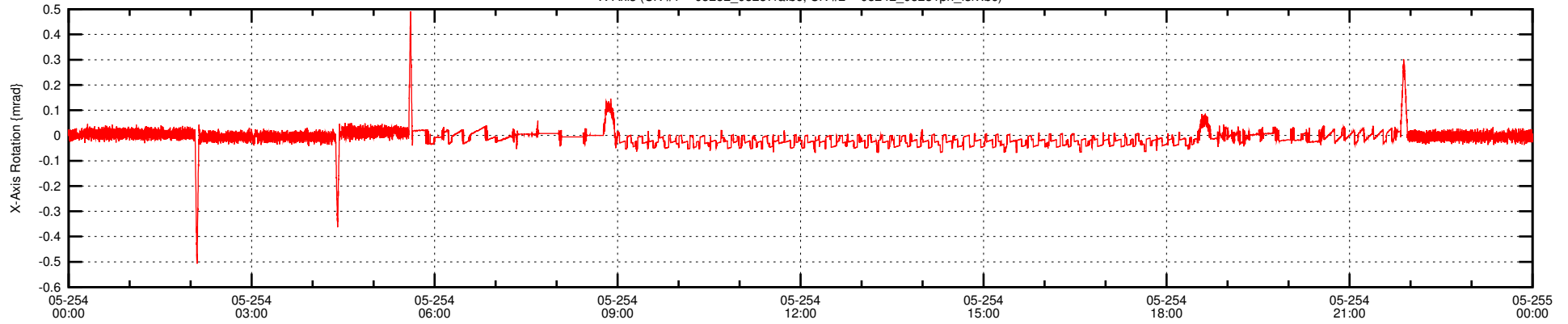


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 253-254)

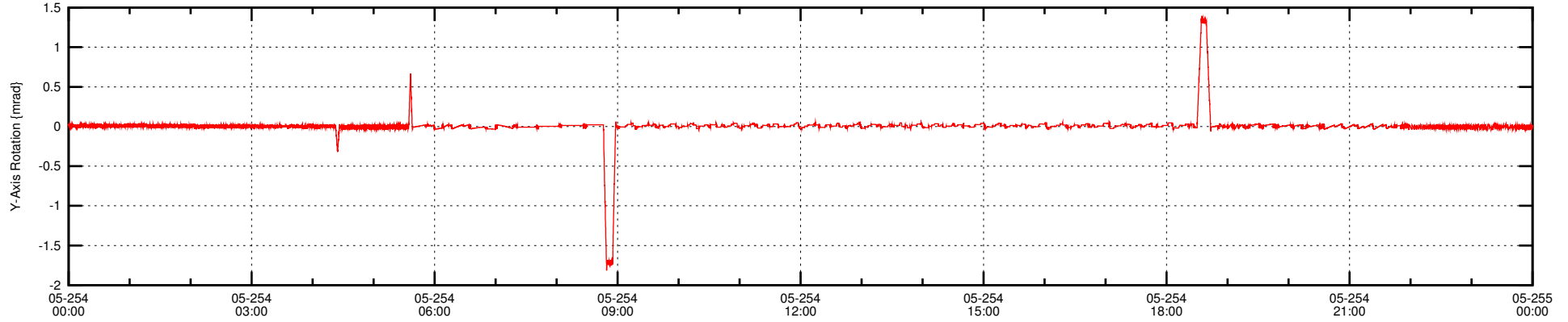


Rotation From CK #2 to CK #1 (DOY 254-255)

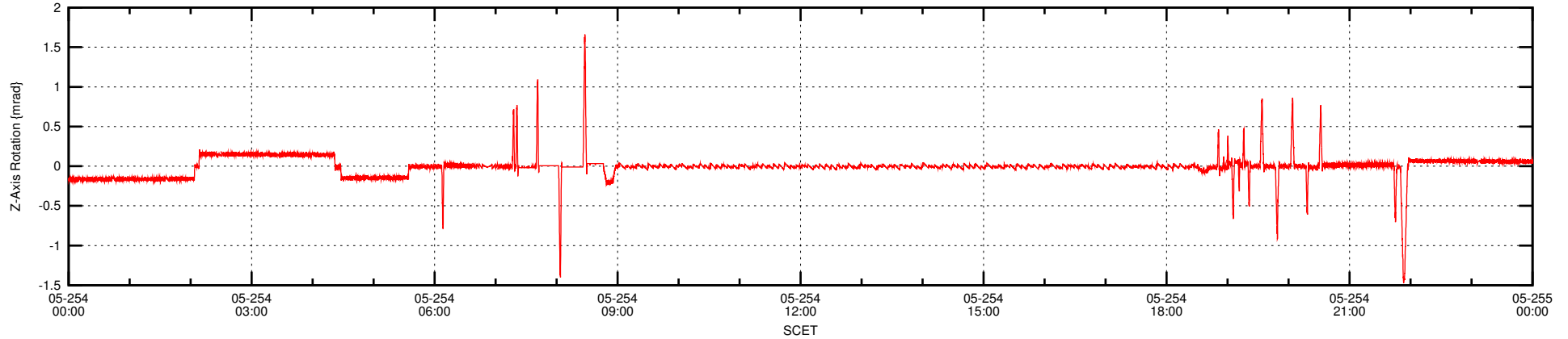
X-Axis (CK #1 = 05252_05257ra.bc; CK #2 = 05242_05281ph_fsiv.bc)



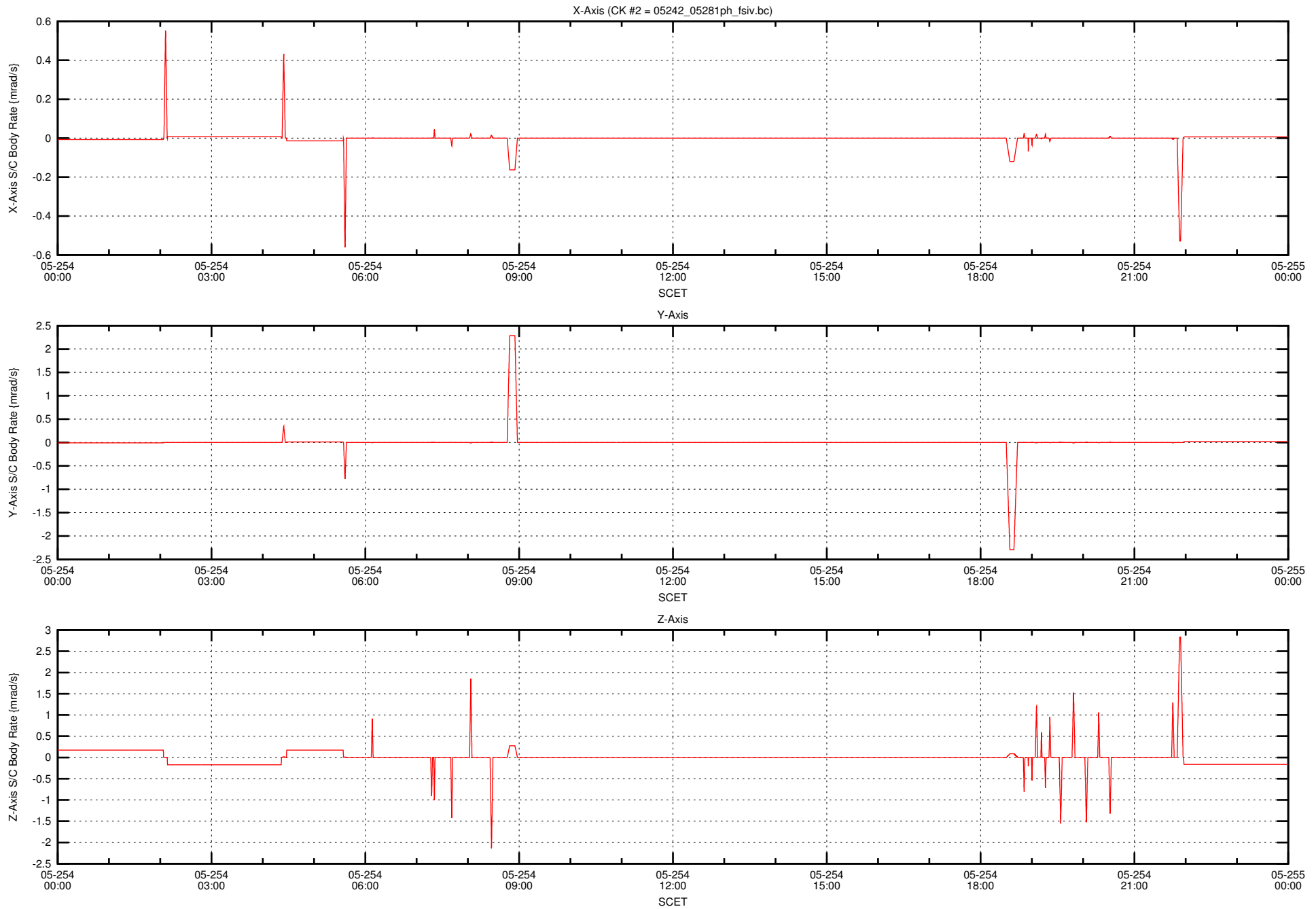
Y-Axis



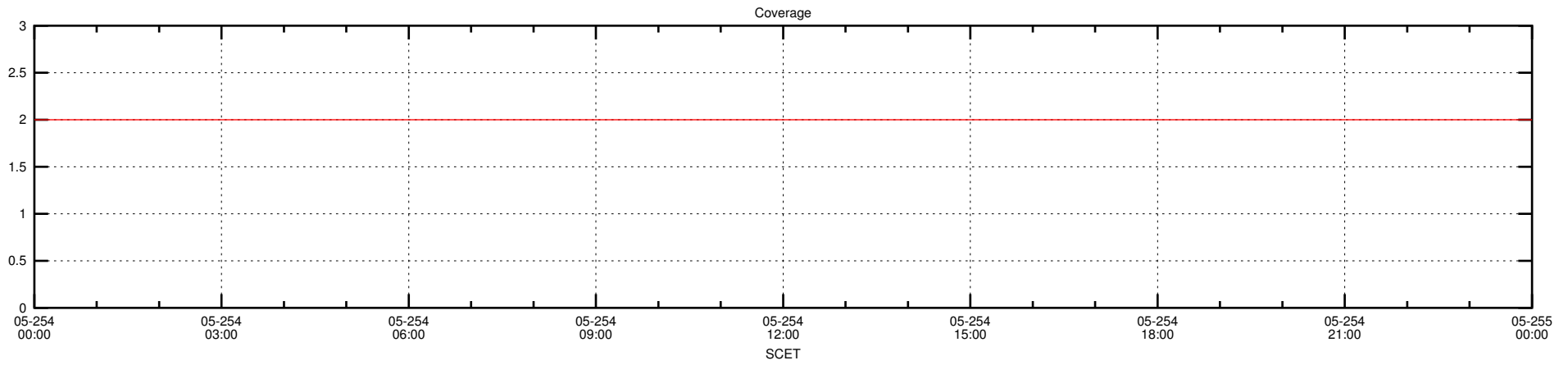
Z-Axis



CK #2 S/C Body Rates (DOY 254-255)

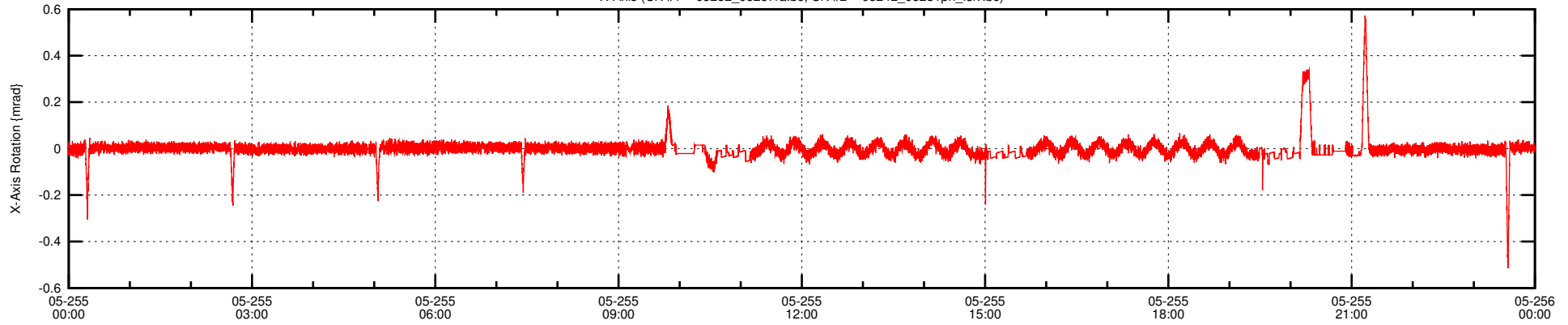


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 254-255)

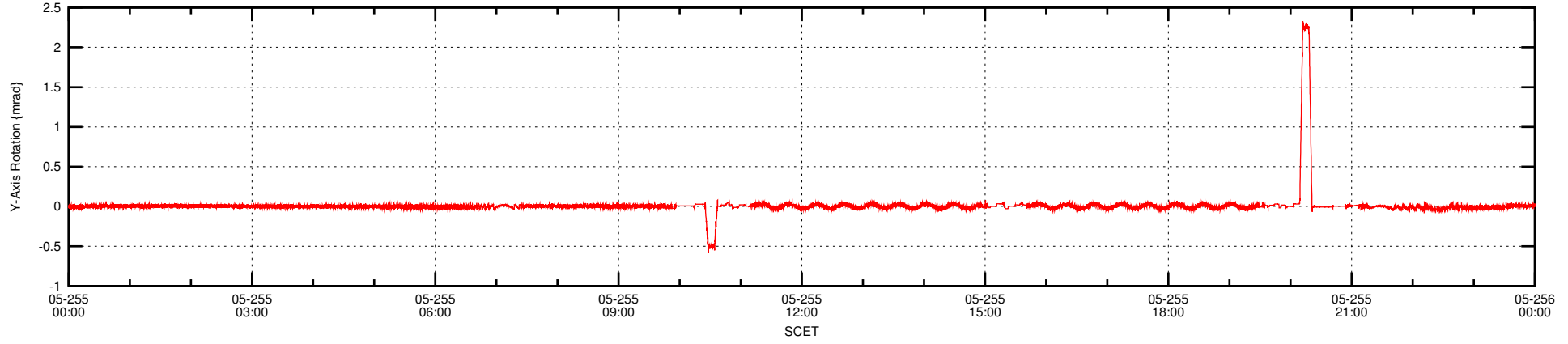


Rotation From CK #2 to CK #1 (DOY 255-256)

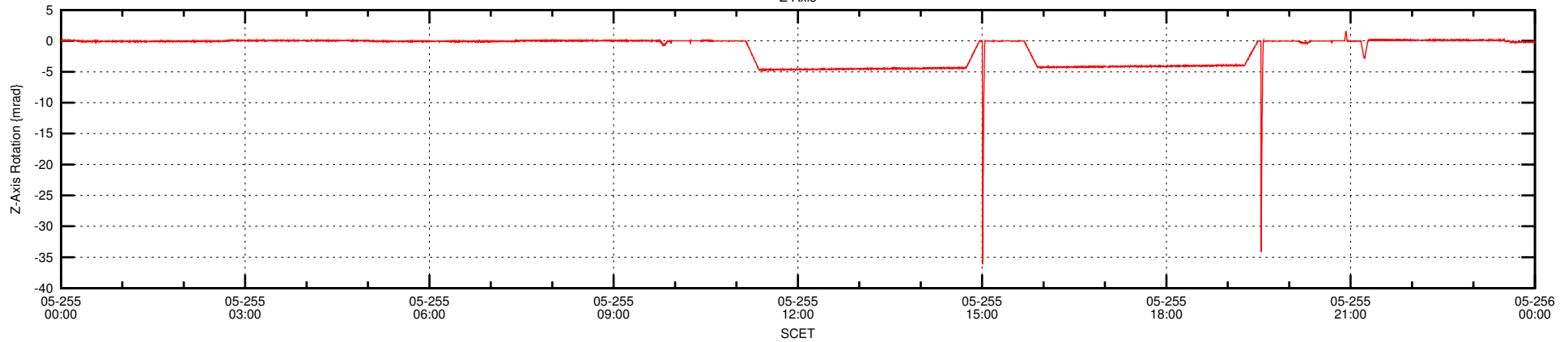
X-Axis (CK #1 = 05252_05257ra.bc; CK #2 = 05242_05281ph_fsiv.bc)



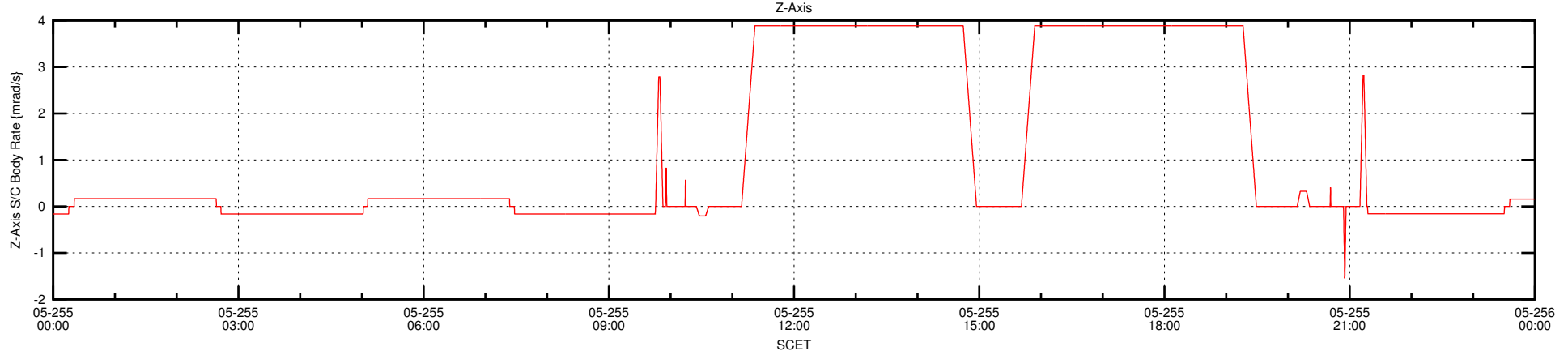
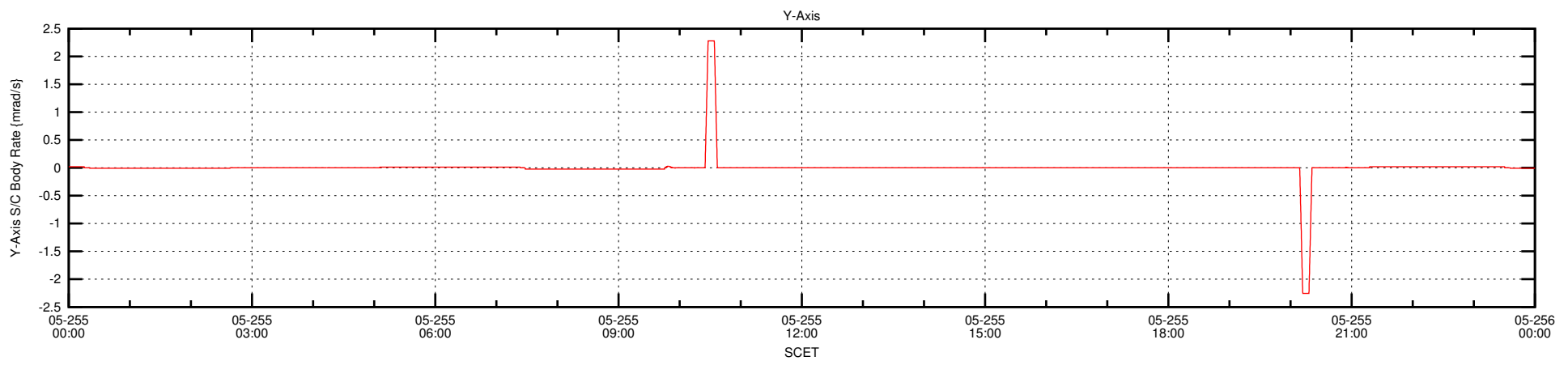
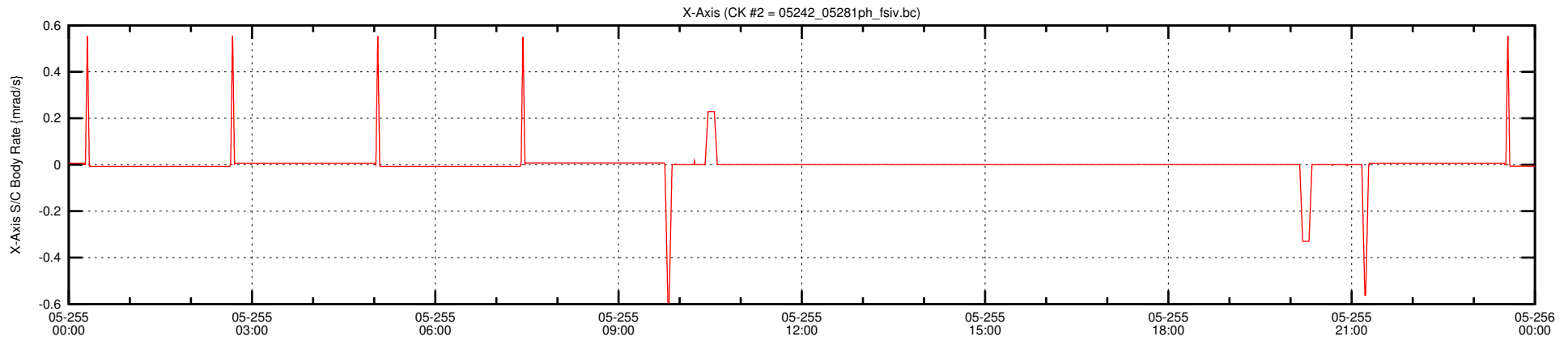
Y-Axis



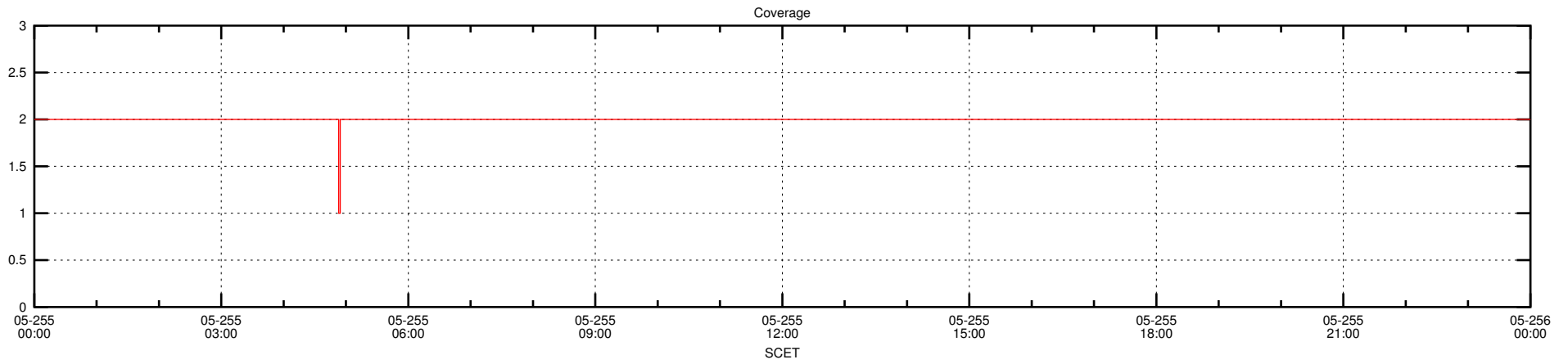
Z-Axis



CK #2 S/C Body Rates (DOY 255-256)

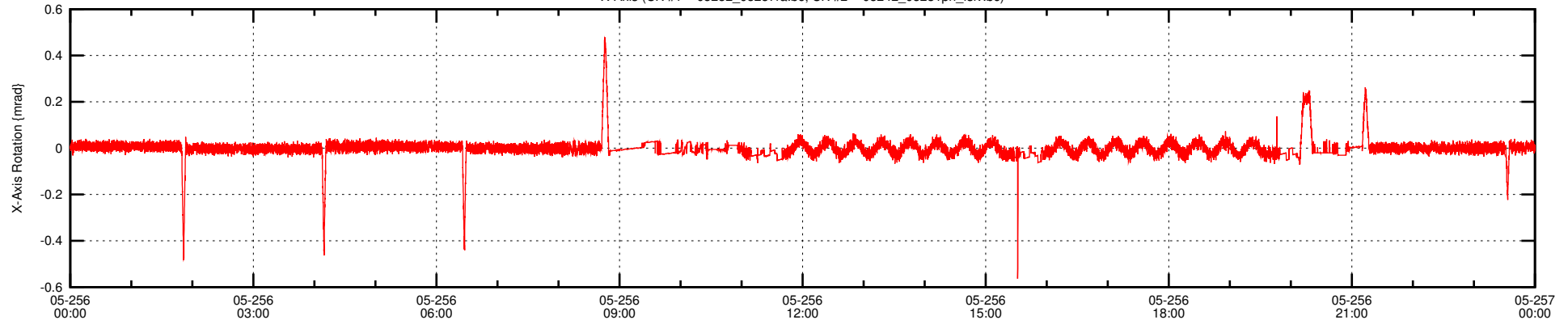


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 255-256)

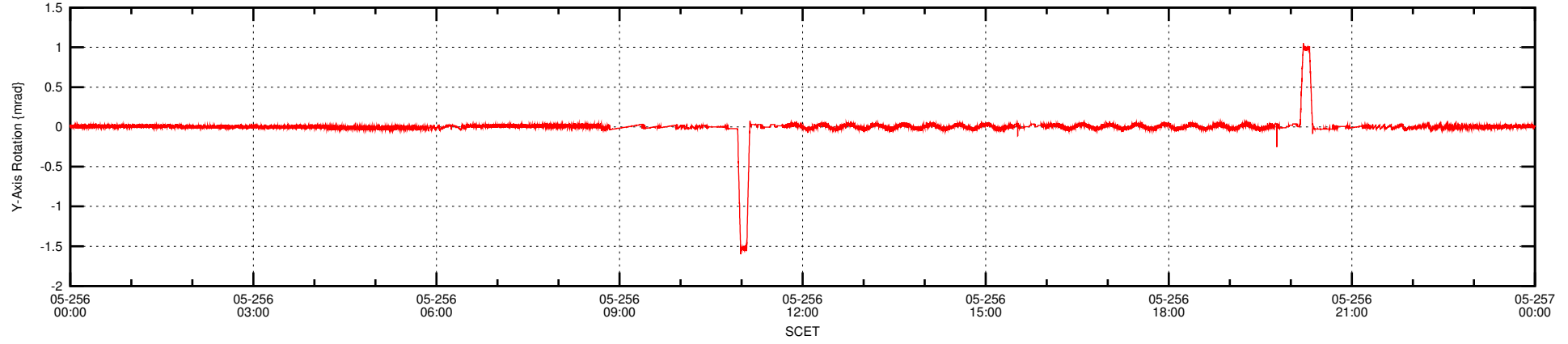


Rotation From CK #2 to CK #1 (DOY 256-256)

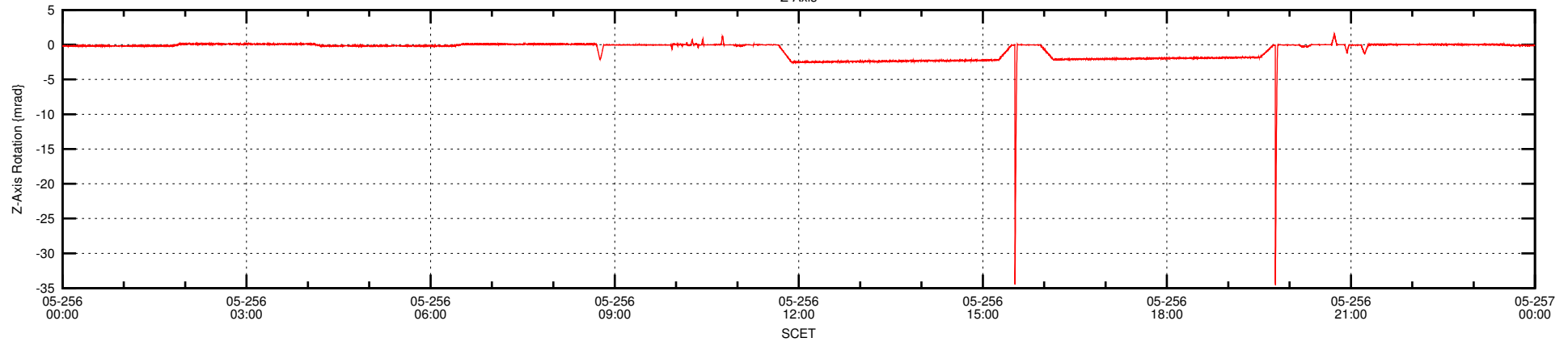
X-Axis (CK #1 = 05252_05257ra.bc; CK #2 = 05242_05281ph_fsiv.bc)



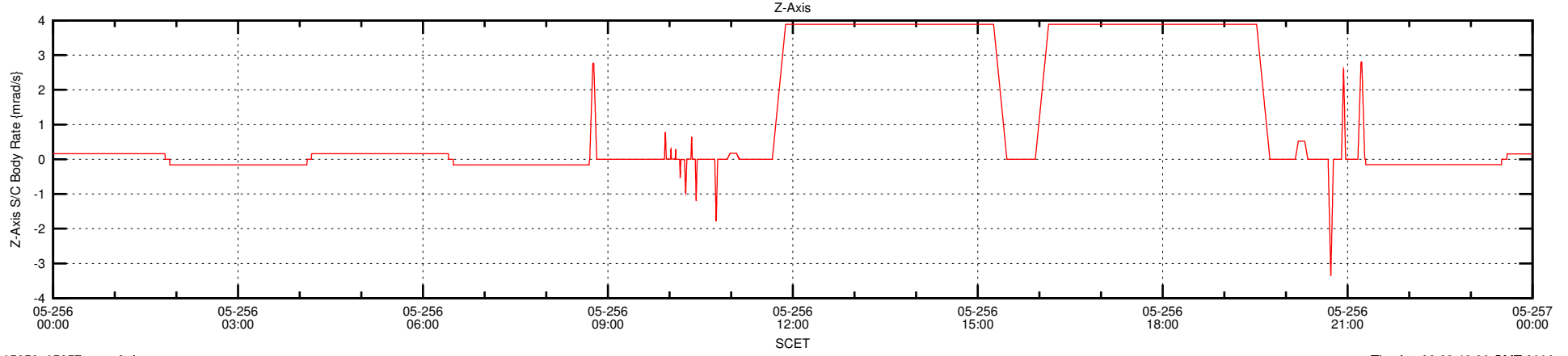
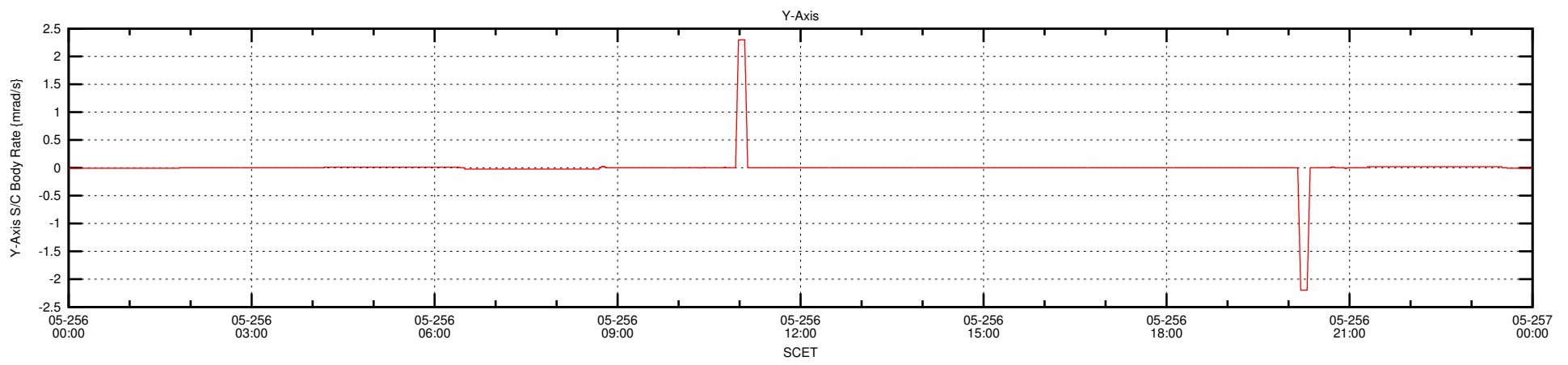
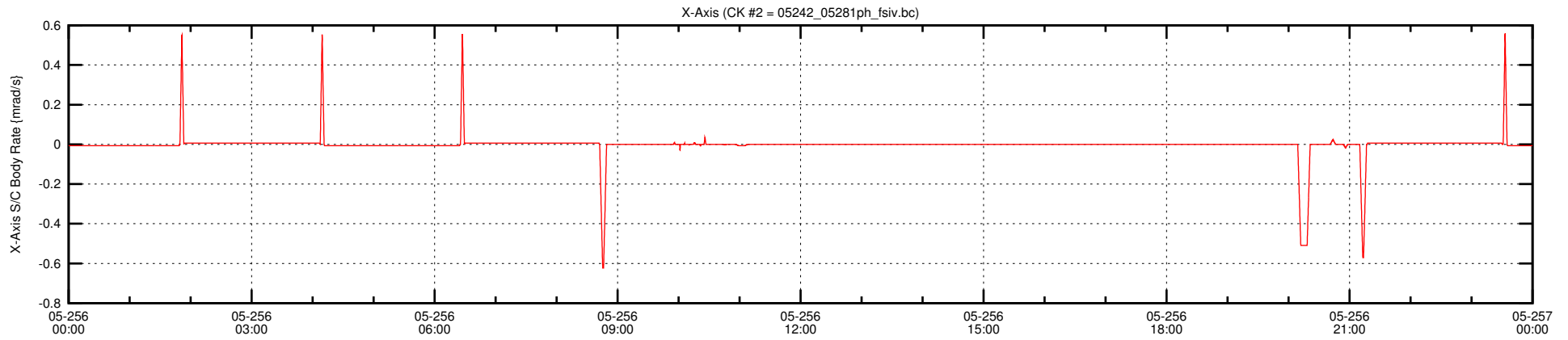
Y-Axis



Z-Axis



CK #2 S/C Body Rates (DOY 256-256)



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 256-256)

