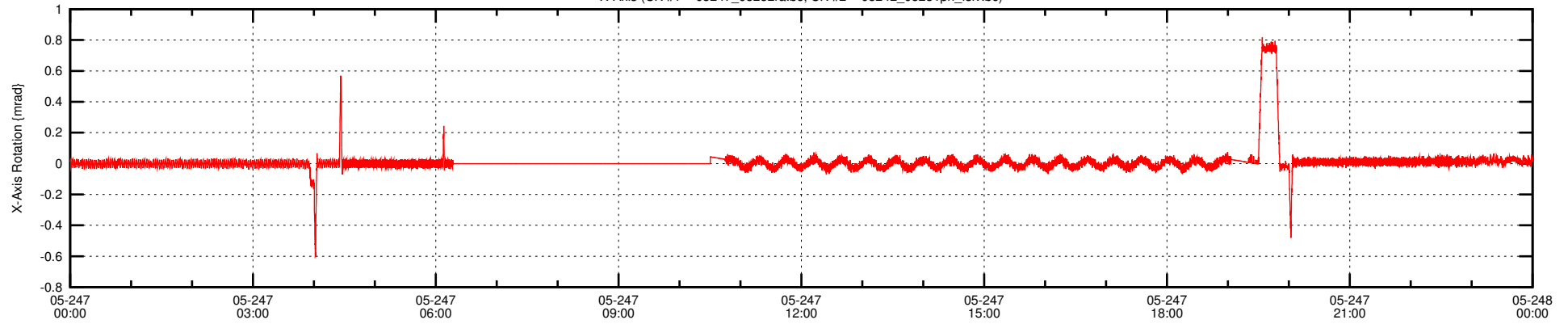
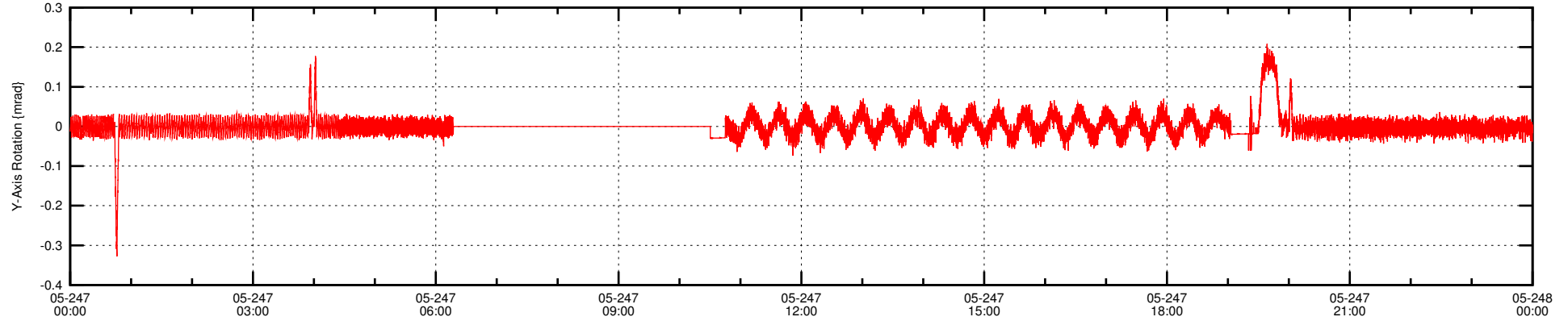


Rotation From CK #2 to CK #1 (DOY 247-248)

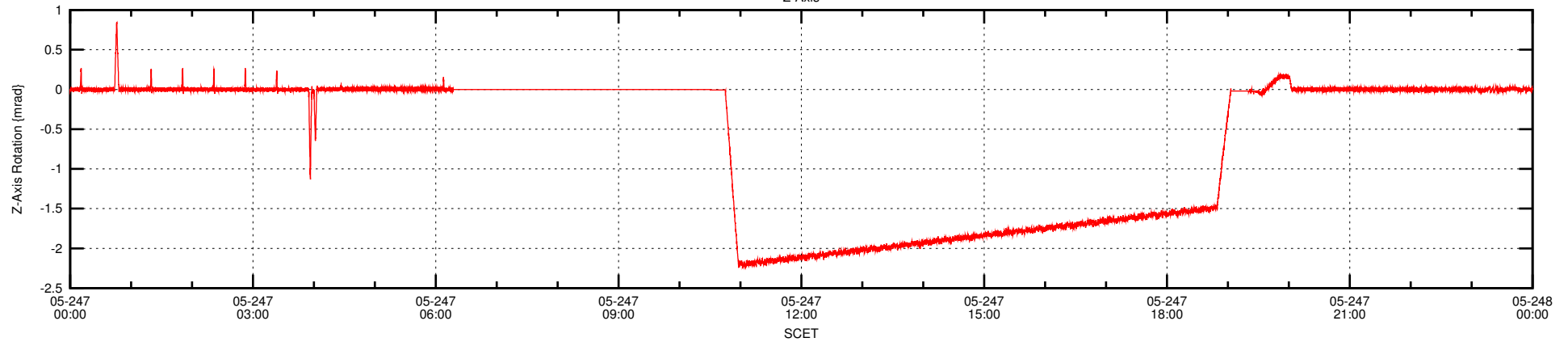
X-Axis (CK #1 = 05247_05252ra.bc; CK #2 = 05242_05281ph_fsiv.bc)



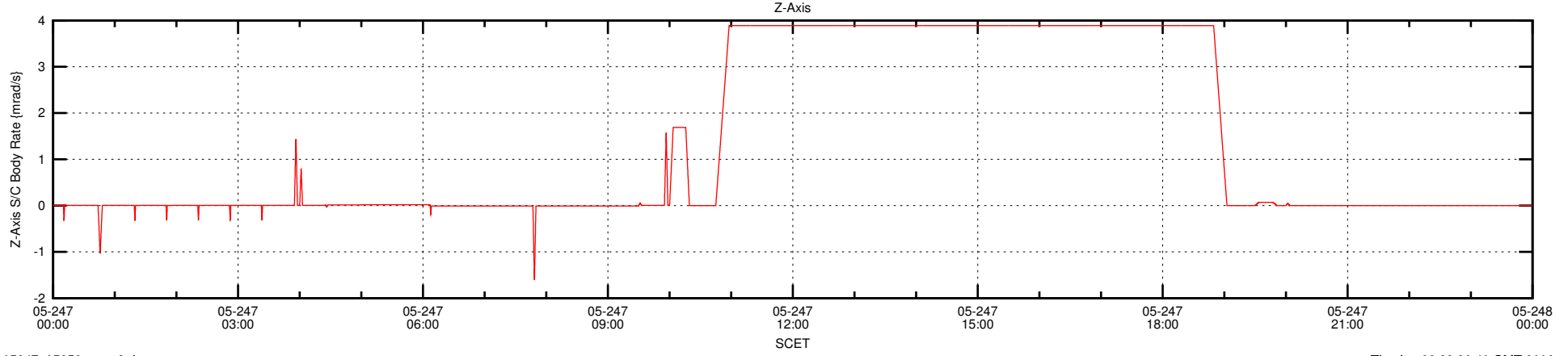
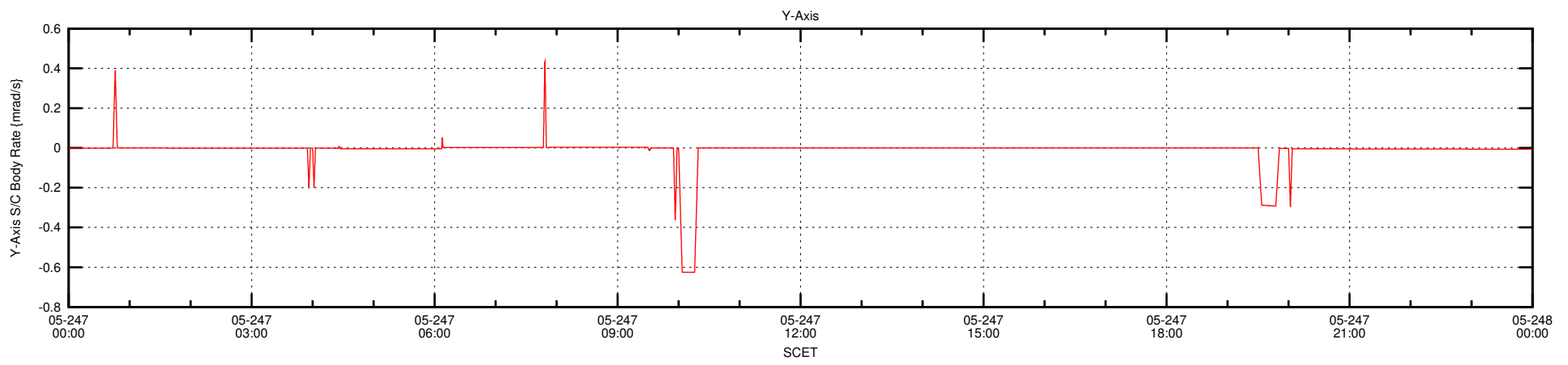
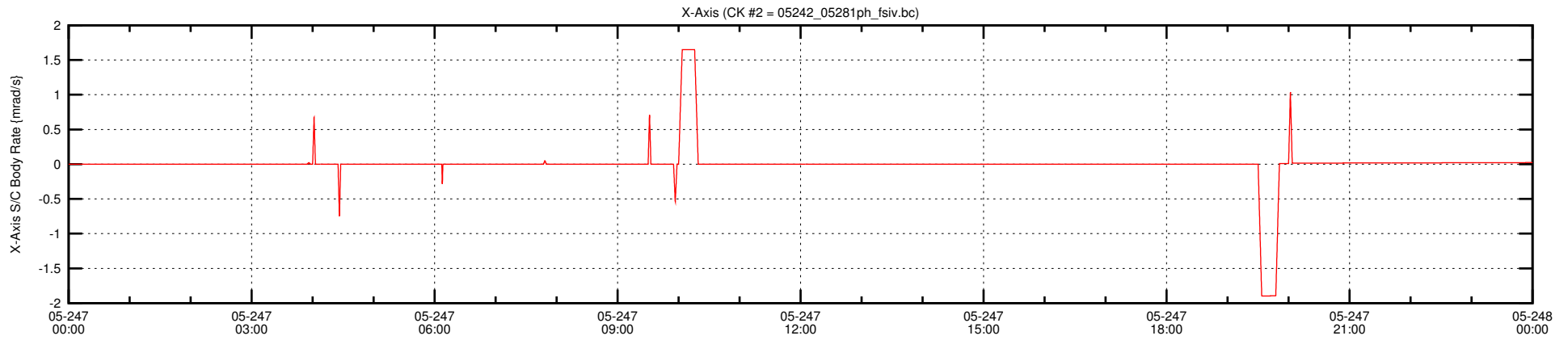
Y-Axis



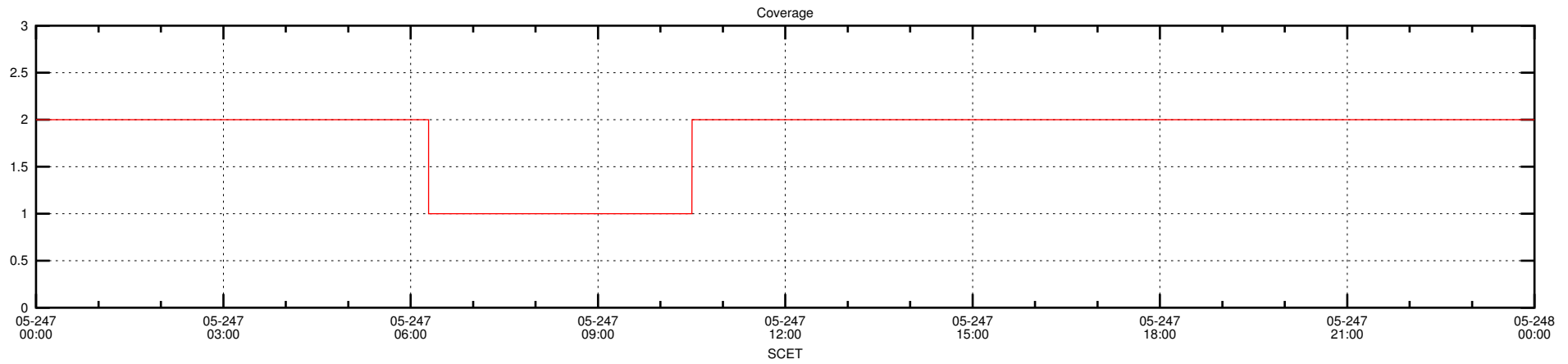
Z-Axis



CK #2 S/C Body Rates (DOY 247-248)

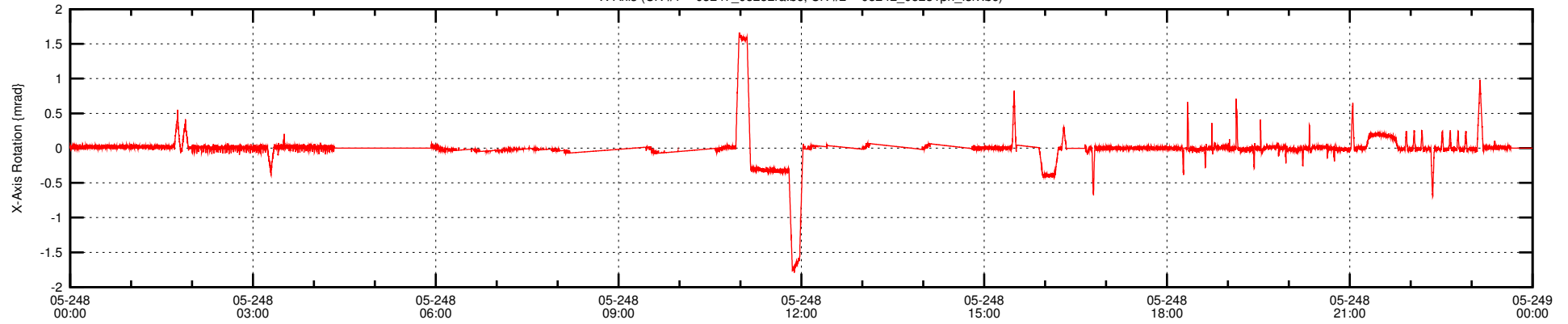


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 247-248)

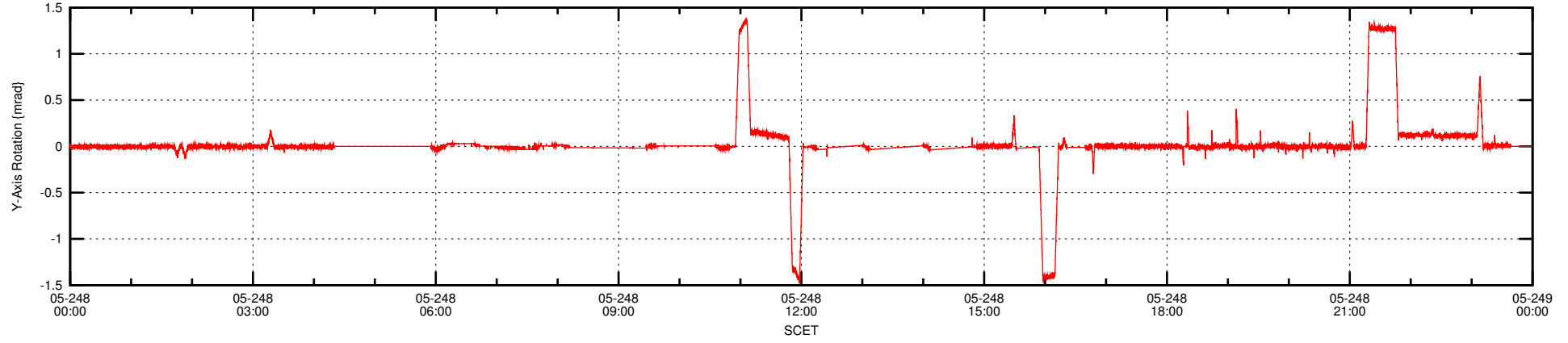


Rotation From CK #2 to CK #1 (DOY 248-249)

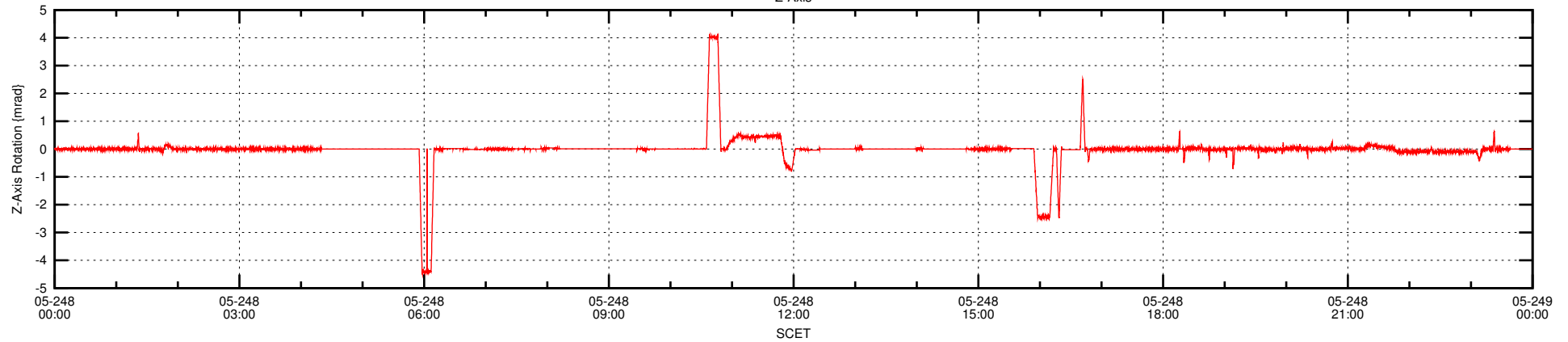
X-Axis (CK #1 = 05247_05252ra.bc; CK #2 = 05242_05281ph_fsiv.bc)



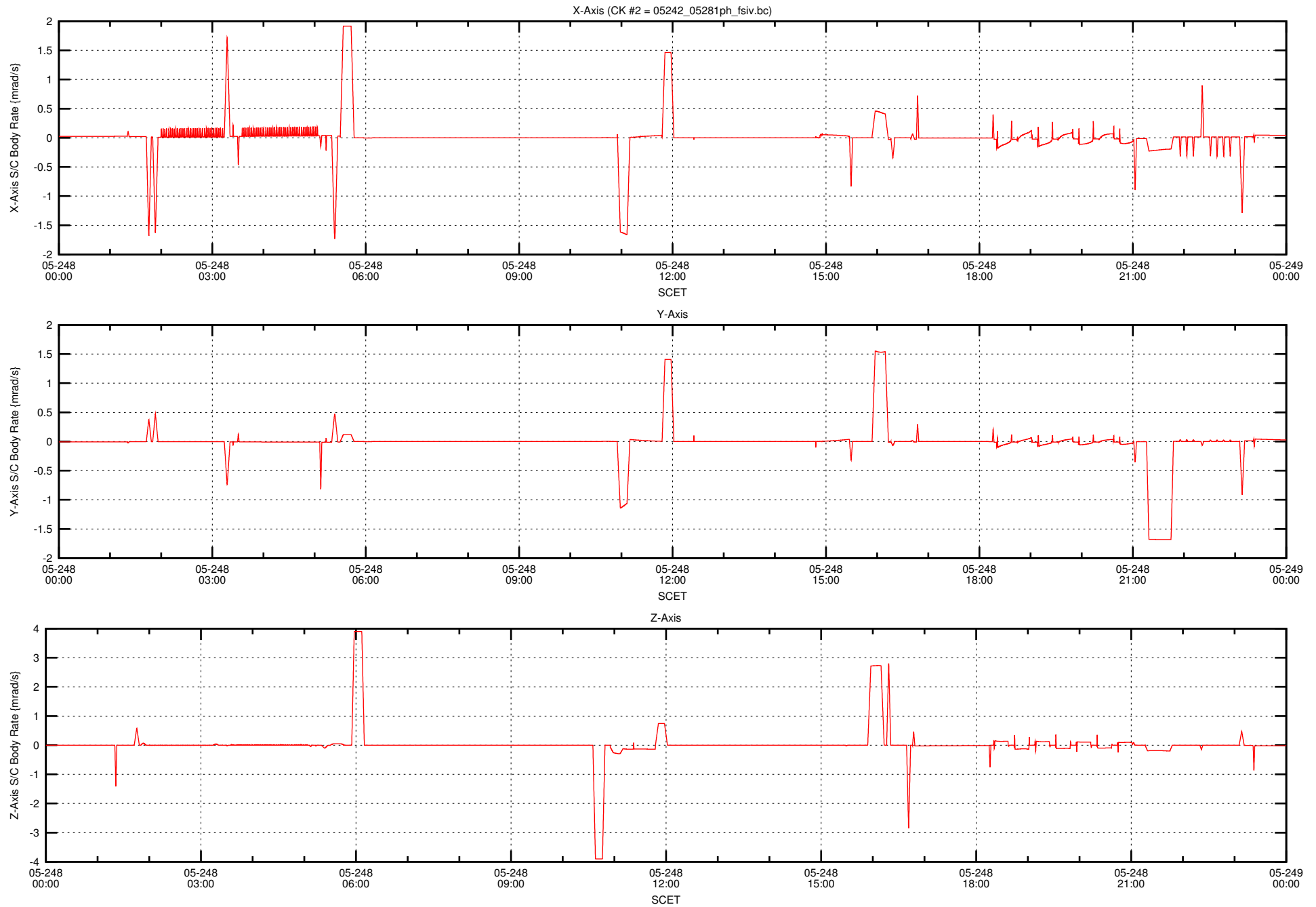
Y-Axis



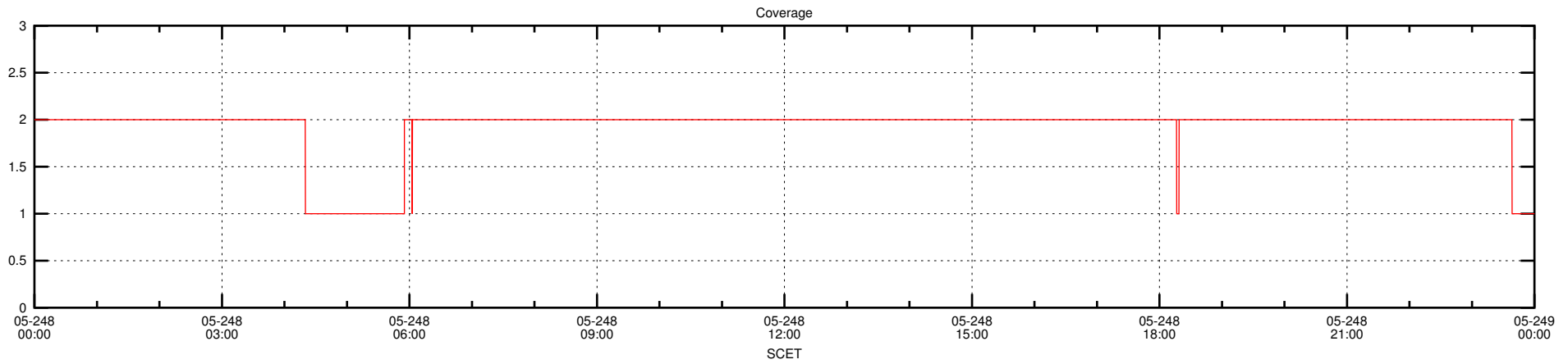
Z-Axis



CK #2 S/C Body Rates (DOY 248-249)

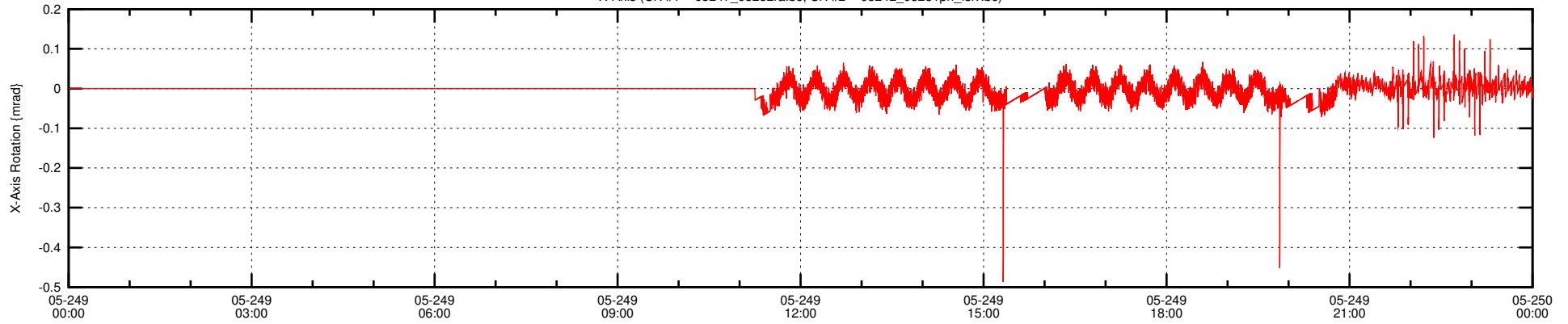


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 248-249)

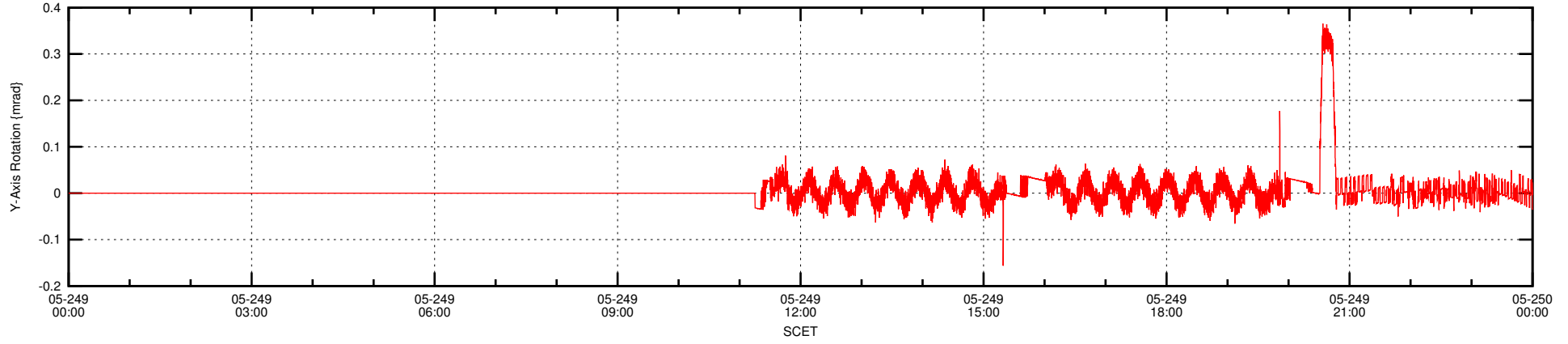


Rotation From CK #2 to CK #1 (DOY 249-250)

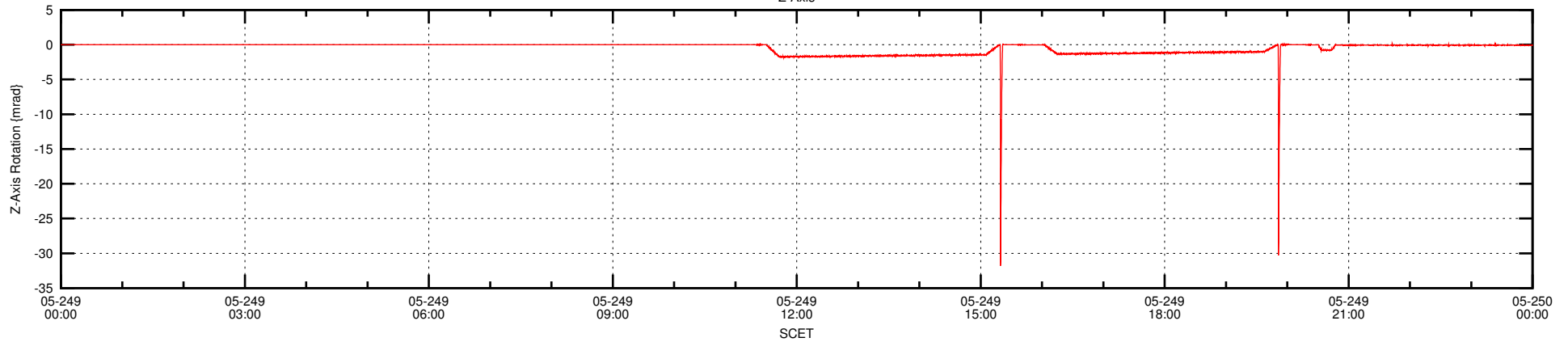
X-Axis (CK #1 = 05247_05252ra.bc; CK #2 = 05242_05281ph_fsiv.bc)



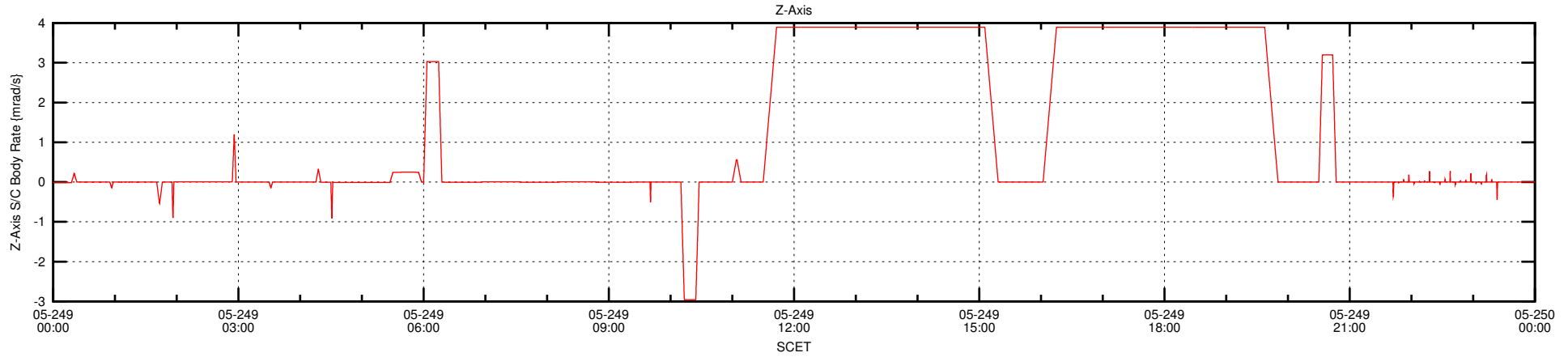
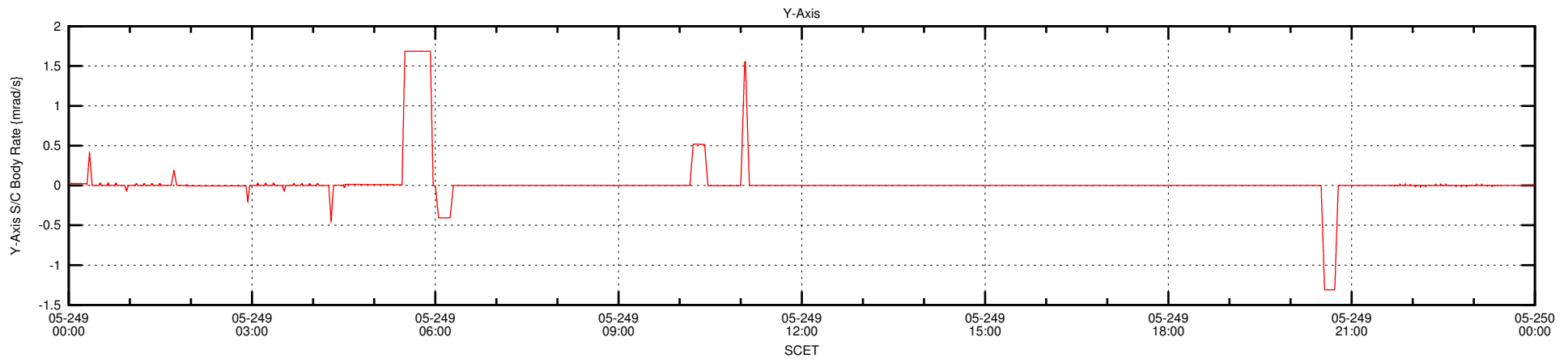
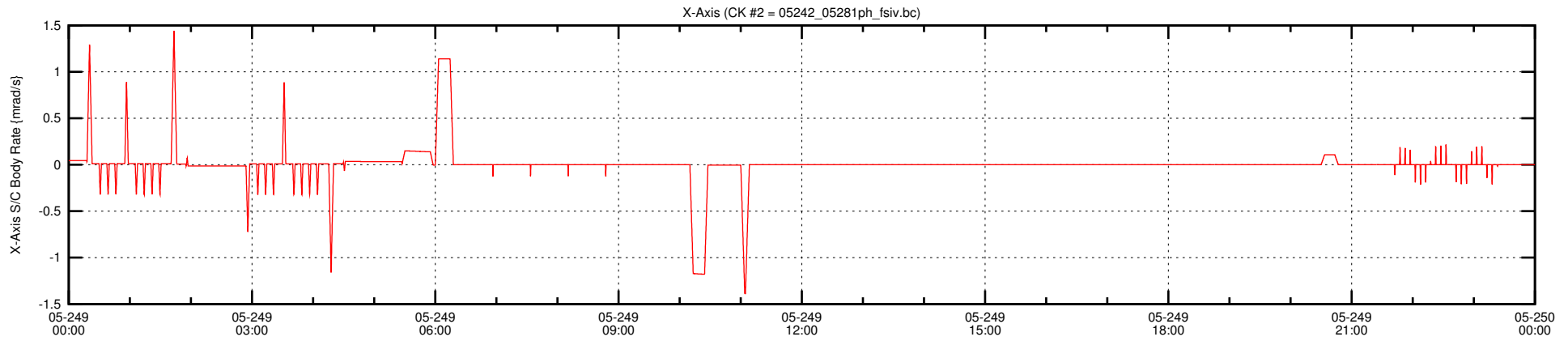
Y-Axis



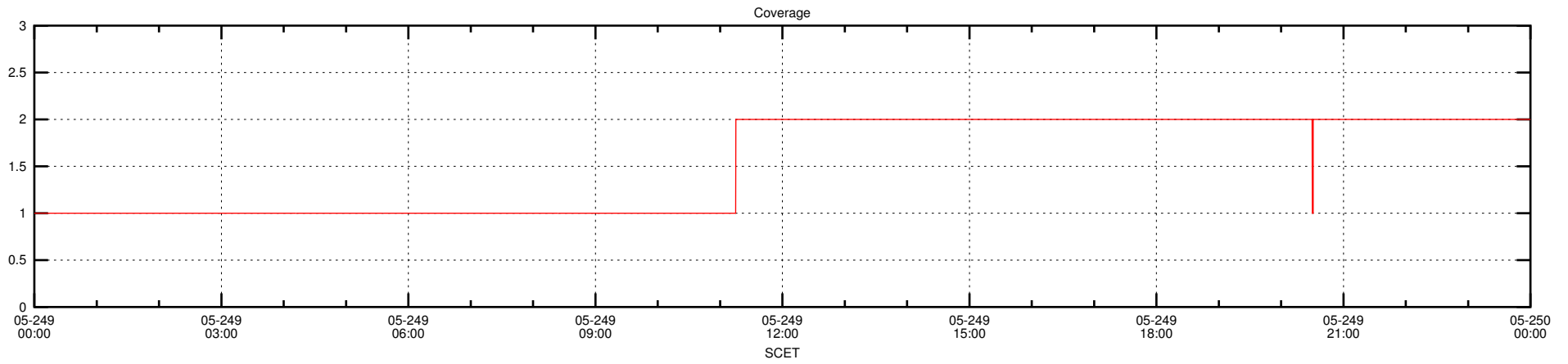
Z-Axis



CK #2 S/C Body Rates (DOY 249-250)

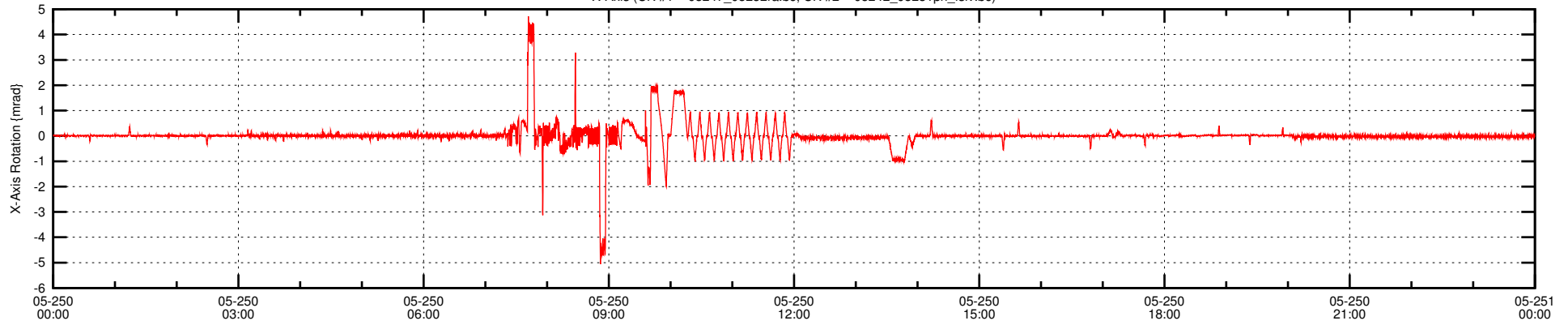


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 249-250)

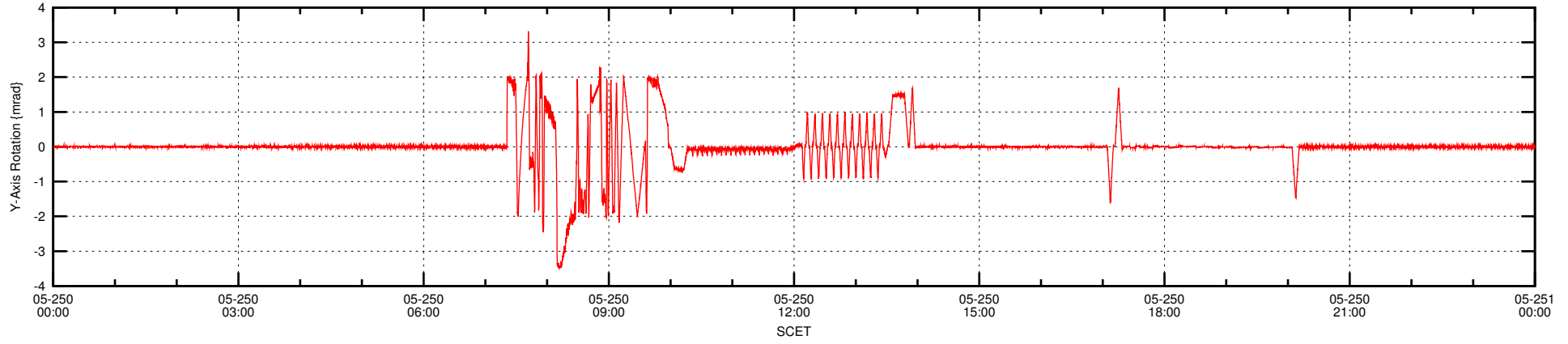


Rotation From CK #2 to CK #1 (DOY 250-251)

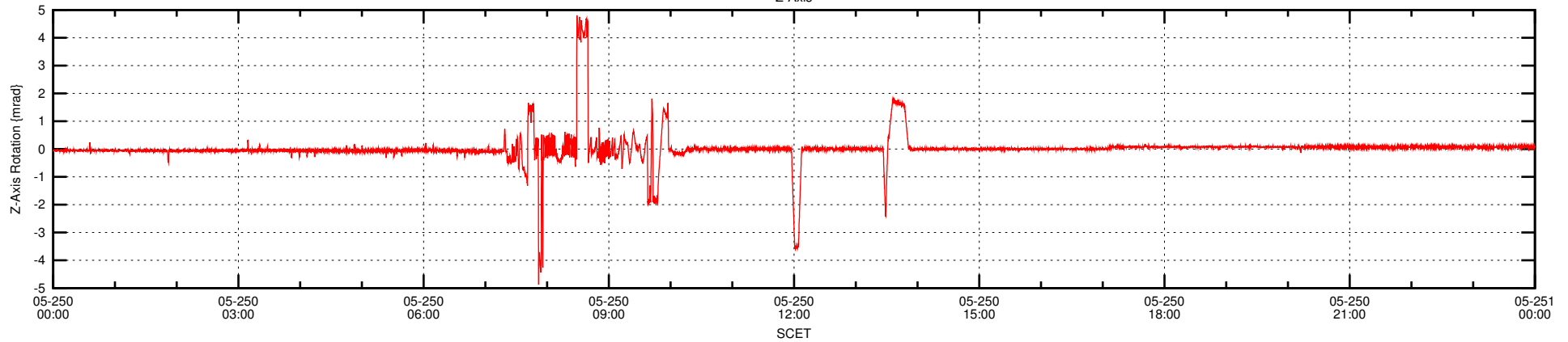
X-Axis (CK #1 = 05247_05252ra.bc; CK #2 = 05242_05281ph_fsiv.bc)



Y-Axis

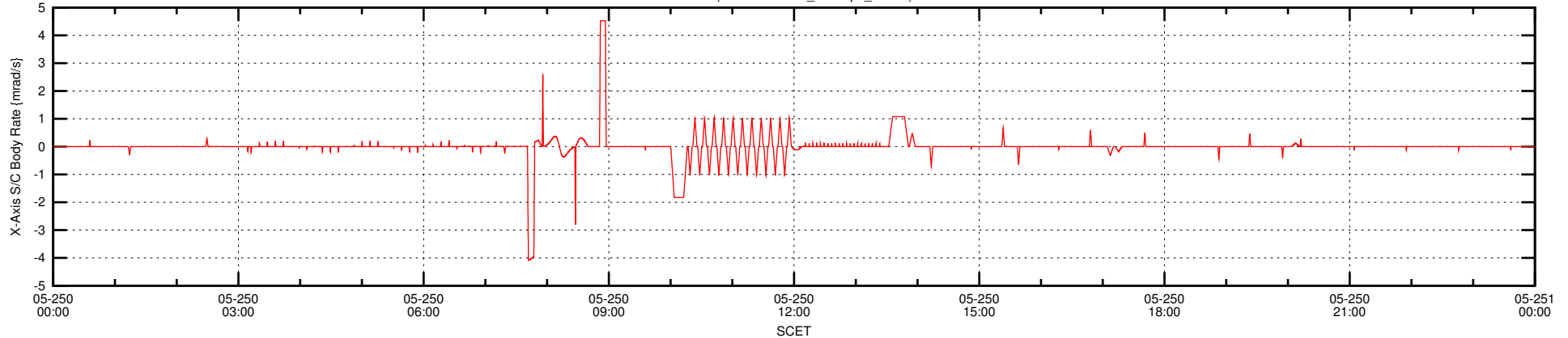


Z-Axis

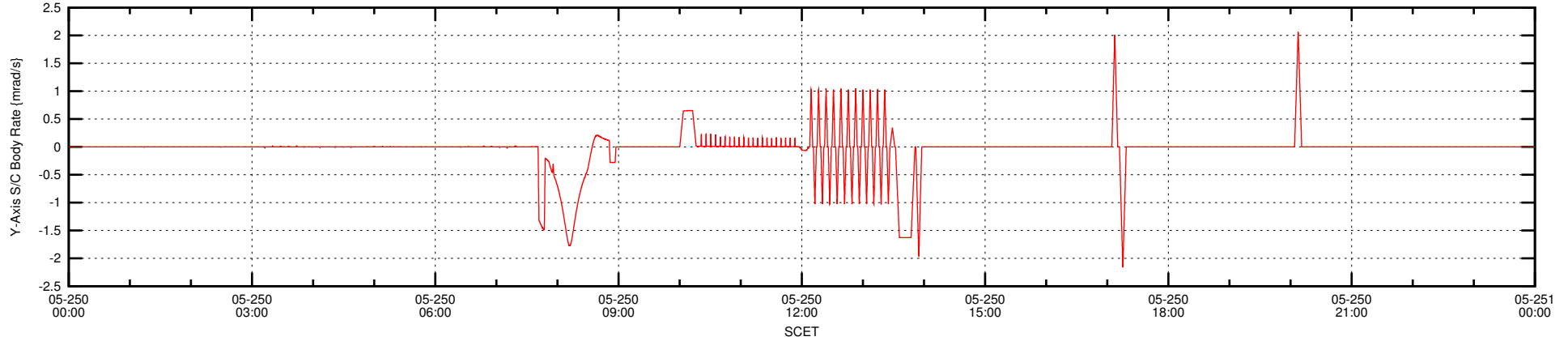


CK #2 S/C Body Rates (DOY 250-251)

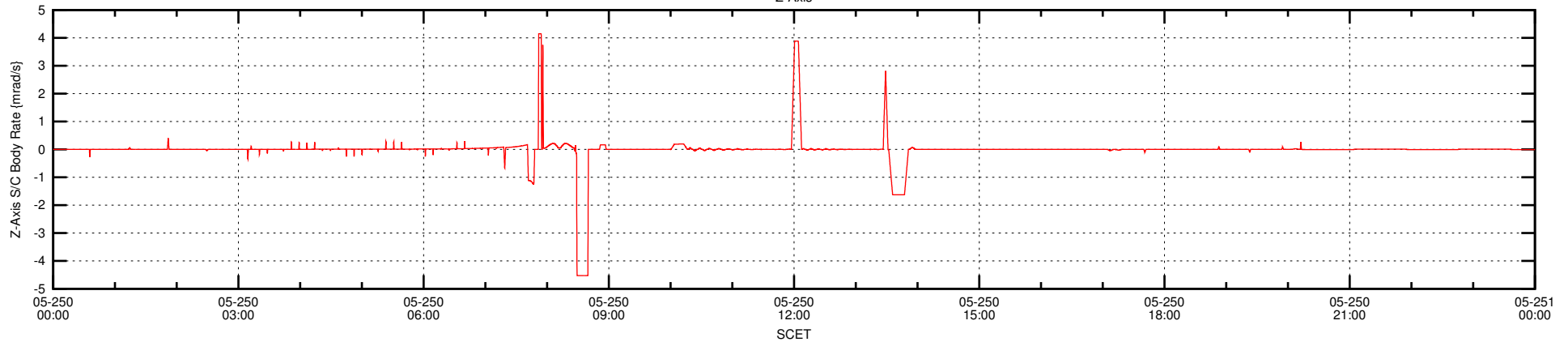
X-Axis (CK #2 = 05242_05281ph_fsiv.bc)



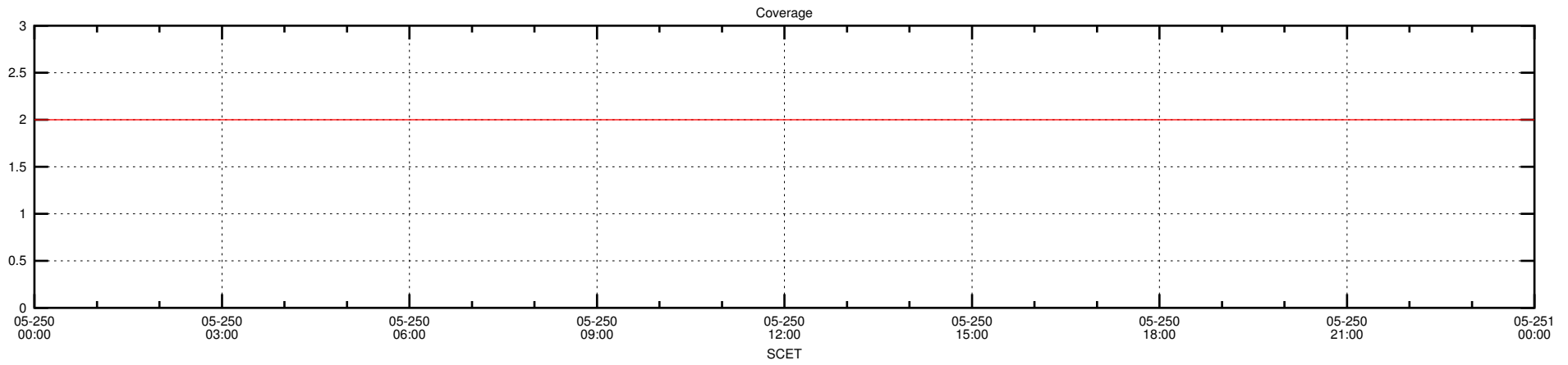
Y-Axis



Z-Axis

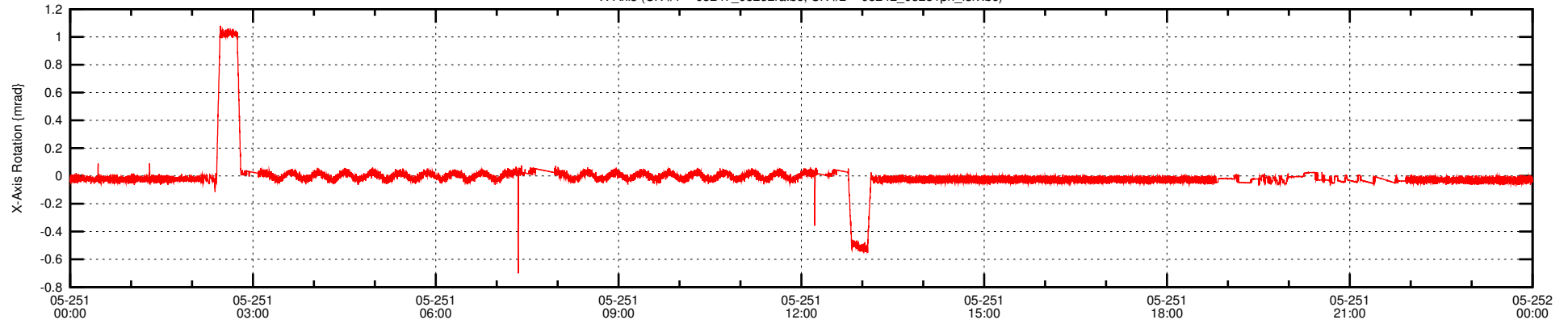


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 250-251)

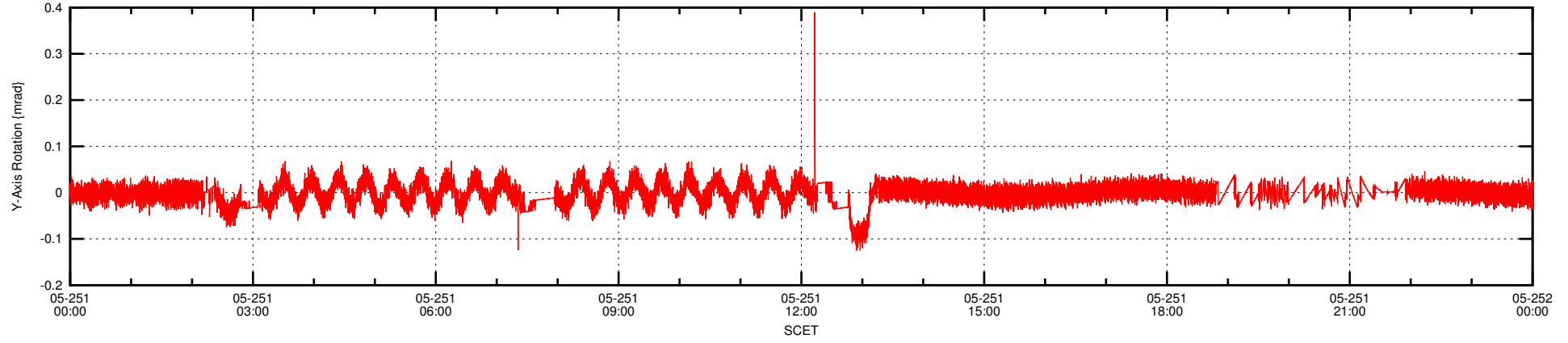


Rotation From CK #2 to CK #1 (DOY 251-251)

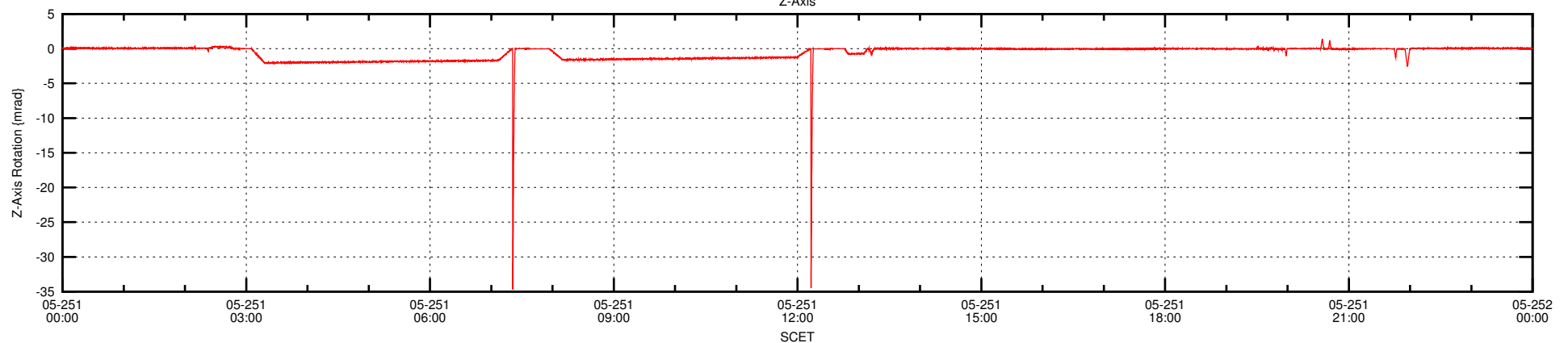
X-Axis (CK #1 = 05247_05252ra.bc; CK #2 = 05242_05281ph_fsiv.bc)



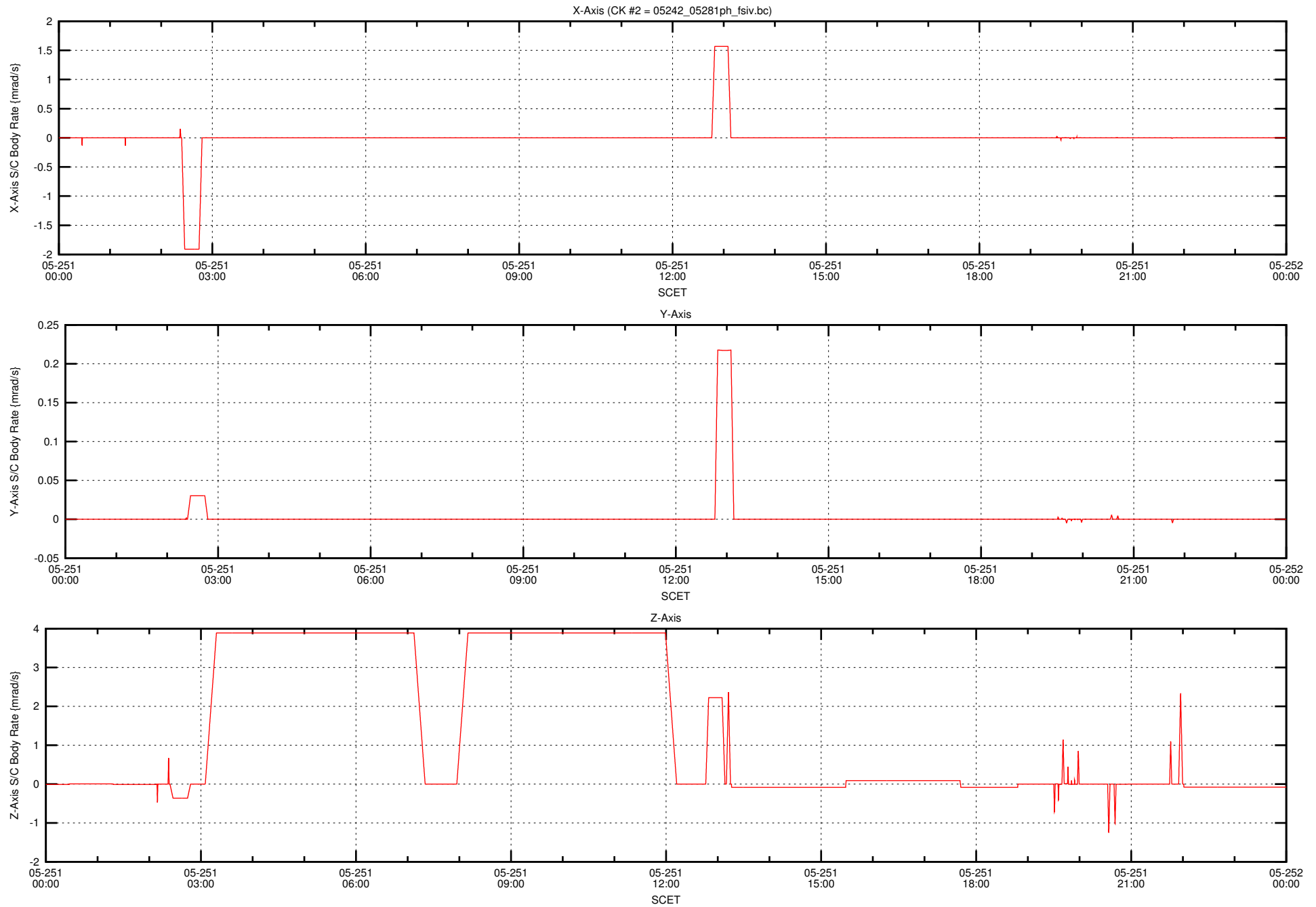
Y-Axis



Z-Axis



CK #2 S/C Body Rates (DOY 251-251)



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 251-251)

