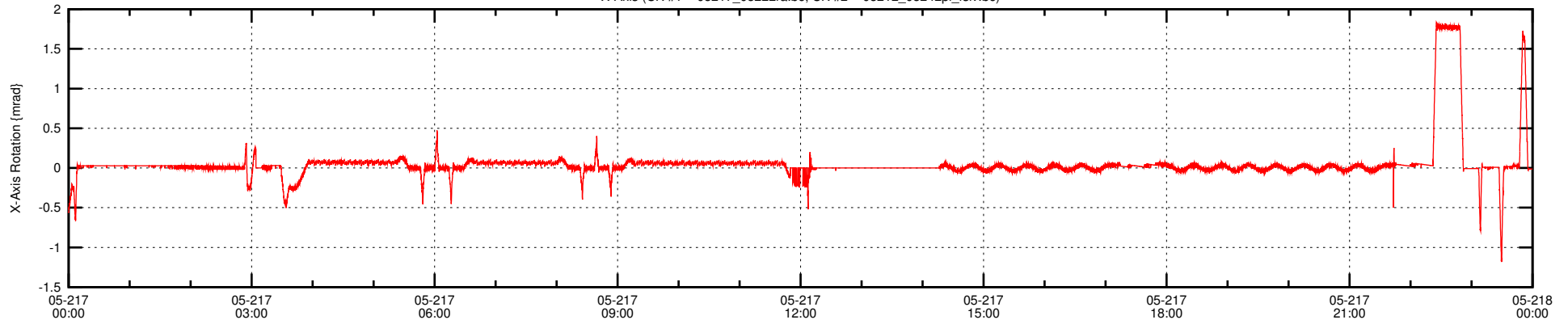
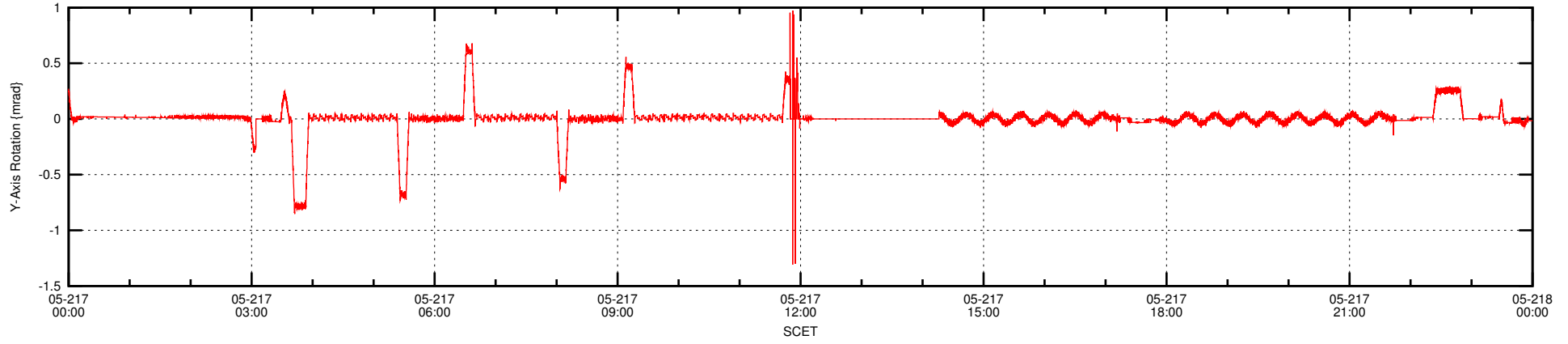


# Rotation From CK #2 to CK #1 (DOY 217-218)

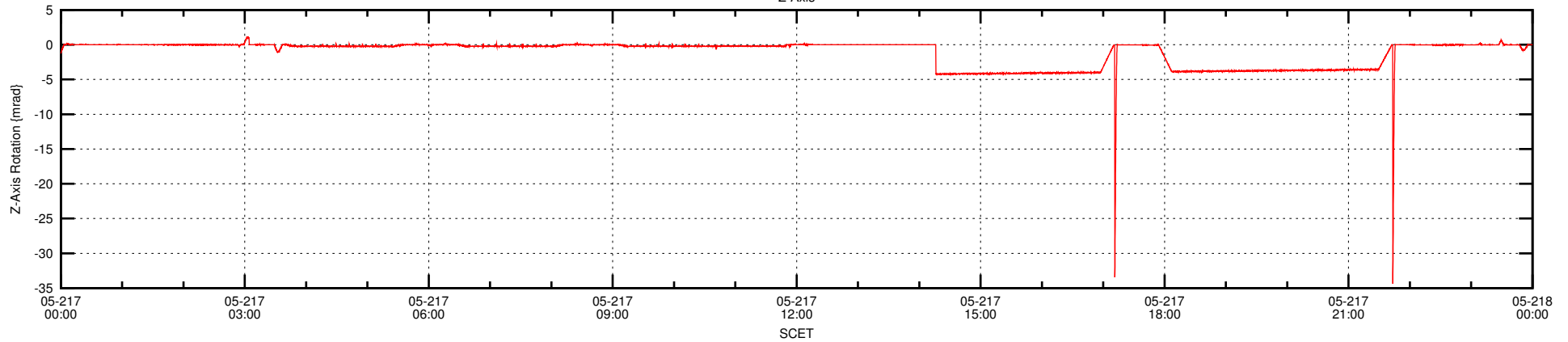
X-Axis (CK #1 = 05217\_05222ra.bc; CK #2 = 05212\_05242pl\_fsiv.bc)



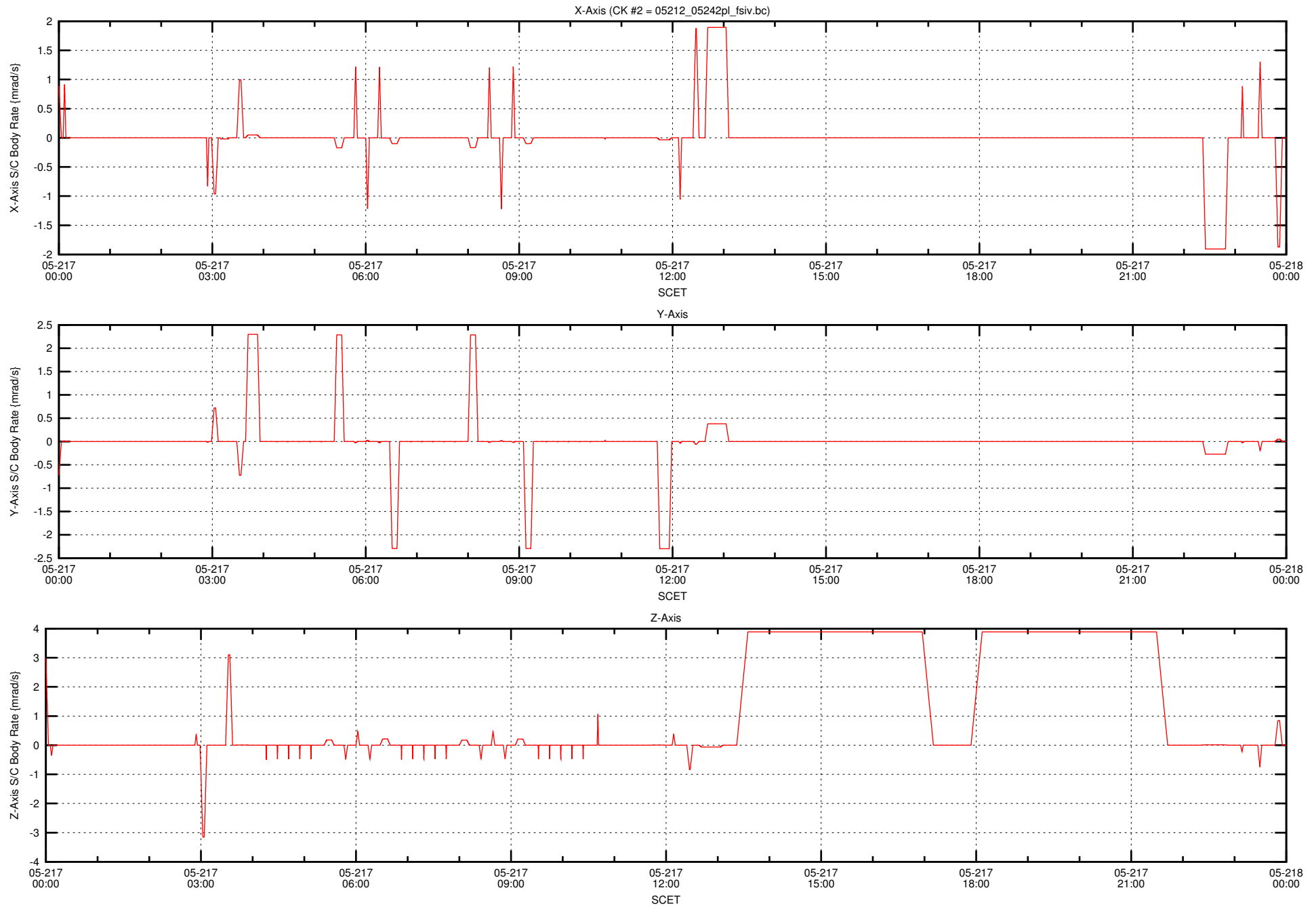
Y-Axis



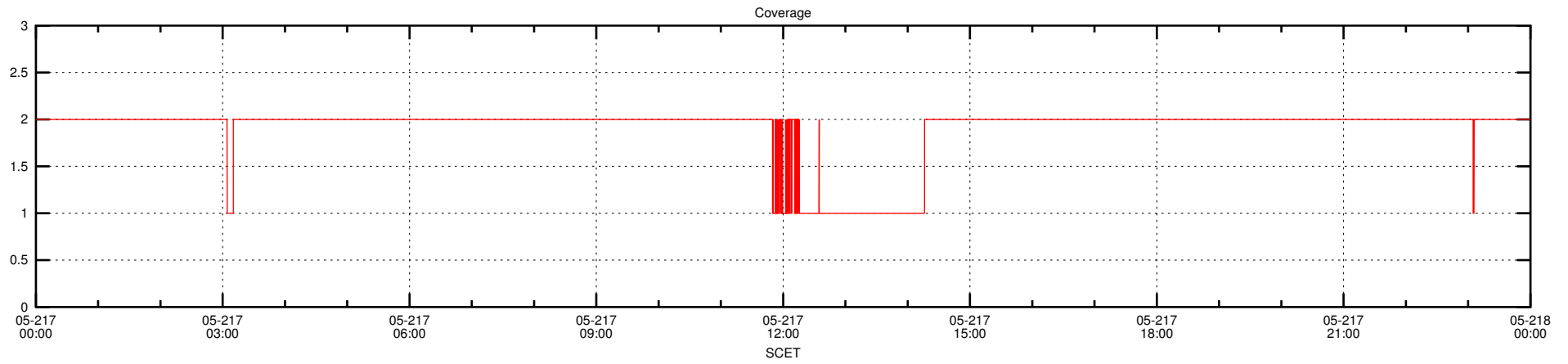
Z-Axis



# CK #2 S/C Body Rates (DOY 217-218)

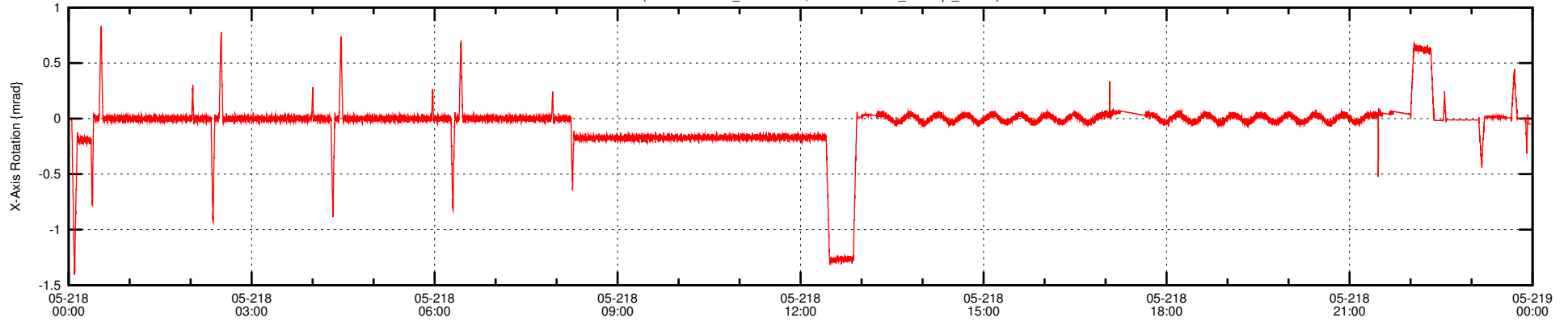


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 217-218)

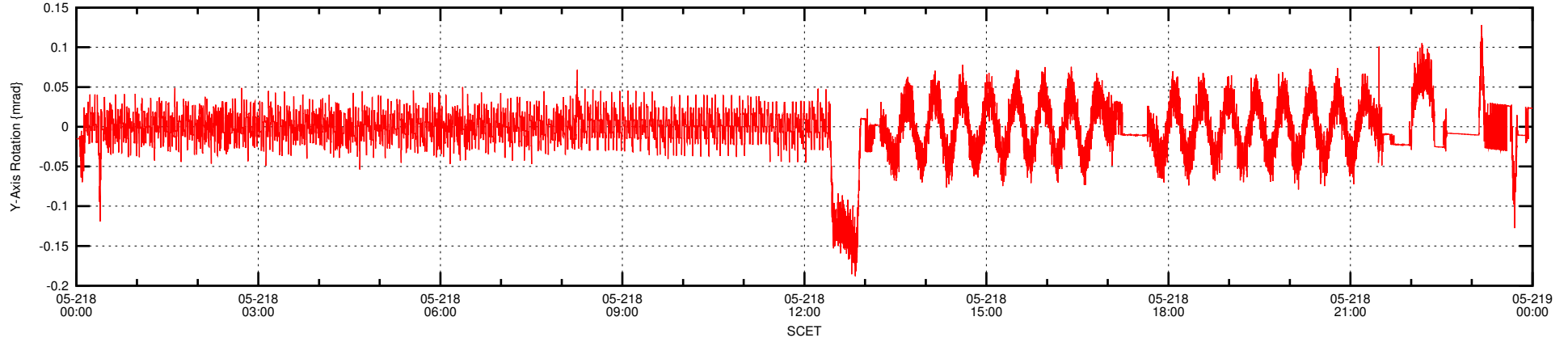


# Rotation From CK #2 to CK #1 (DOY 218-219)

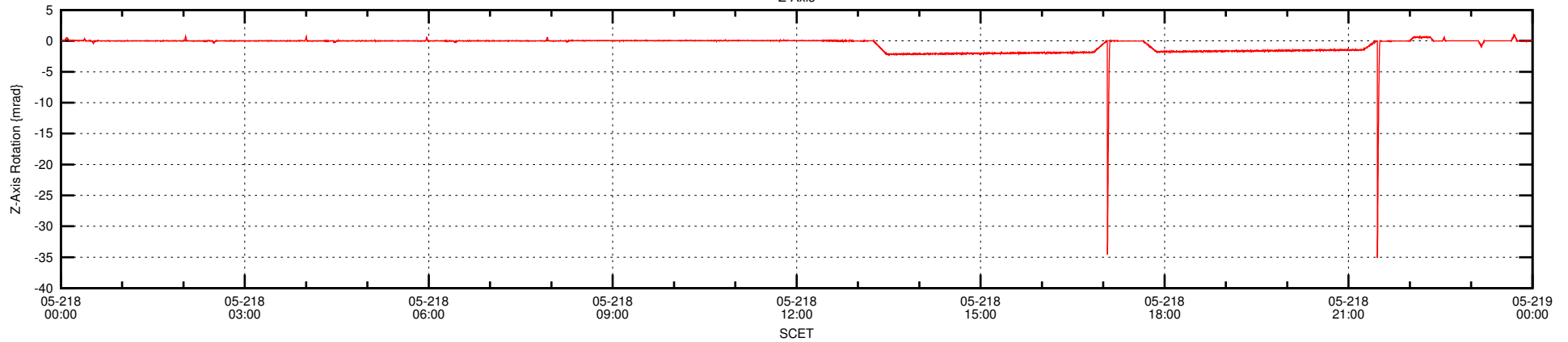
X-Axis (CK #1 = 05217\_05222ra.bc; CK #2 = 05212\_05242pl\_fsiv.bc)



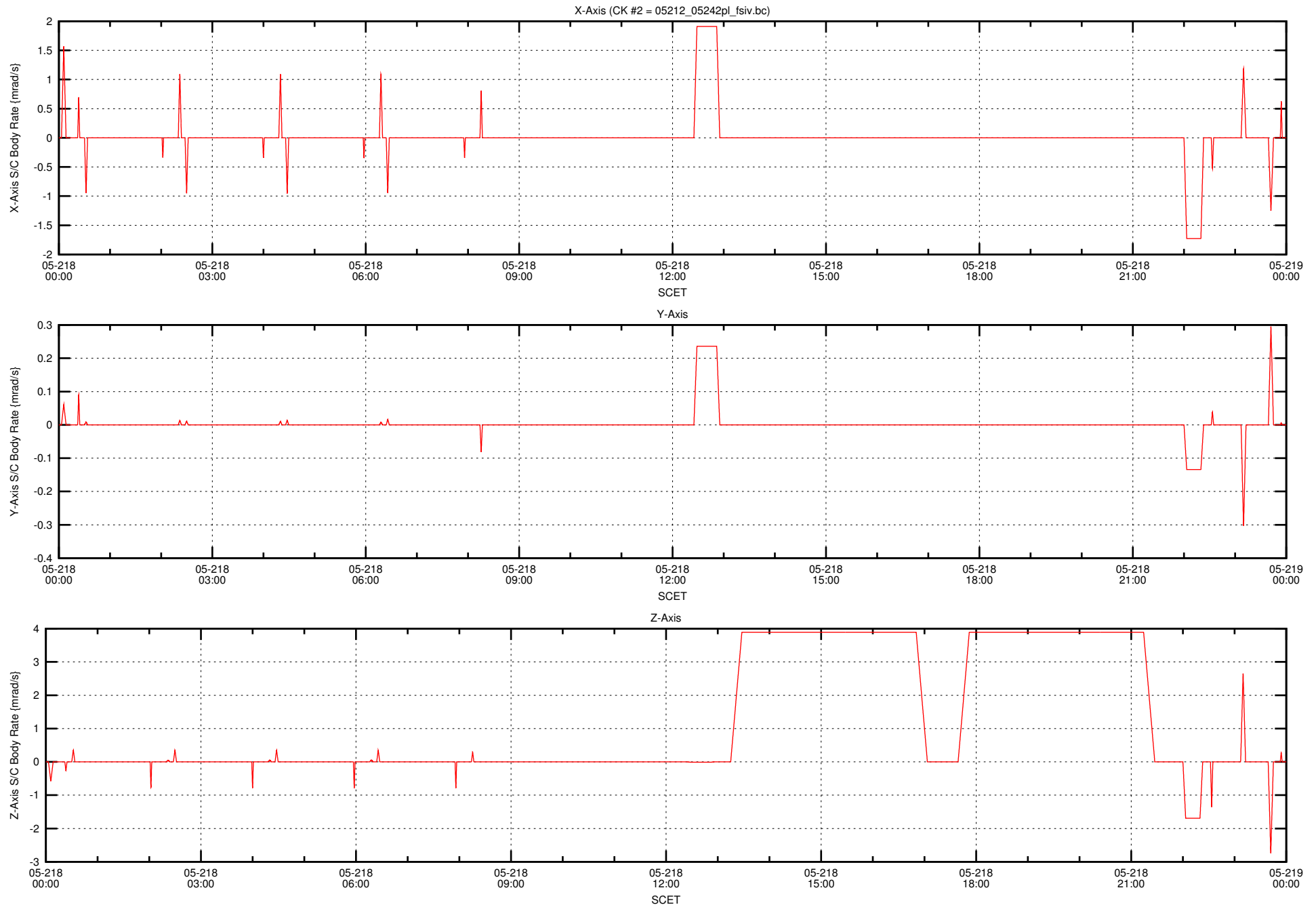
Y-Axis



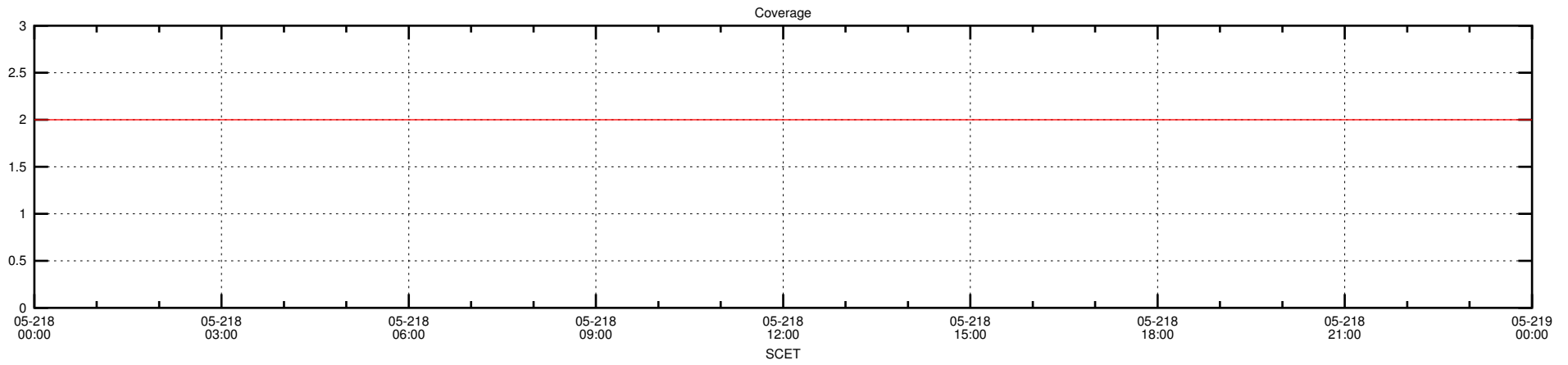
Z-Axis



# CK #2 S/C Body Rates (DOY 218-219)

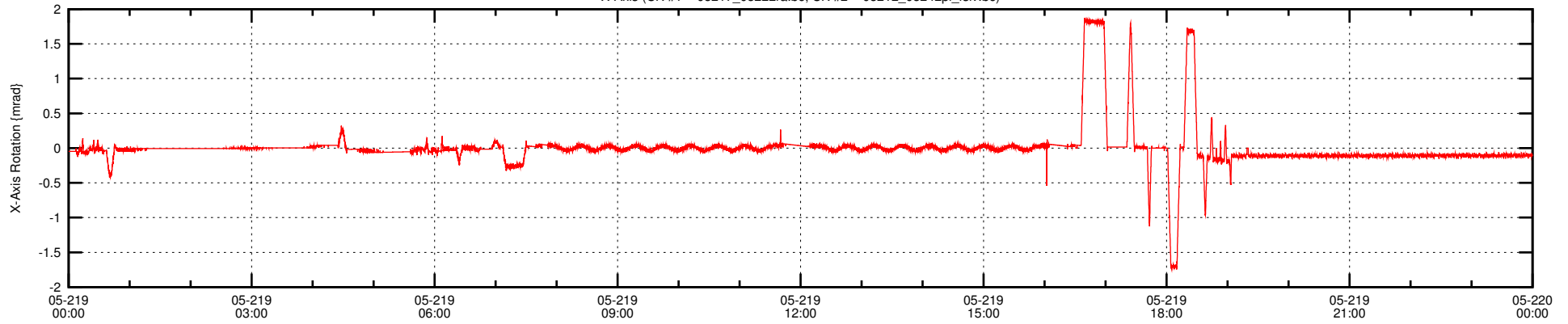


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 218-219)

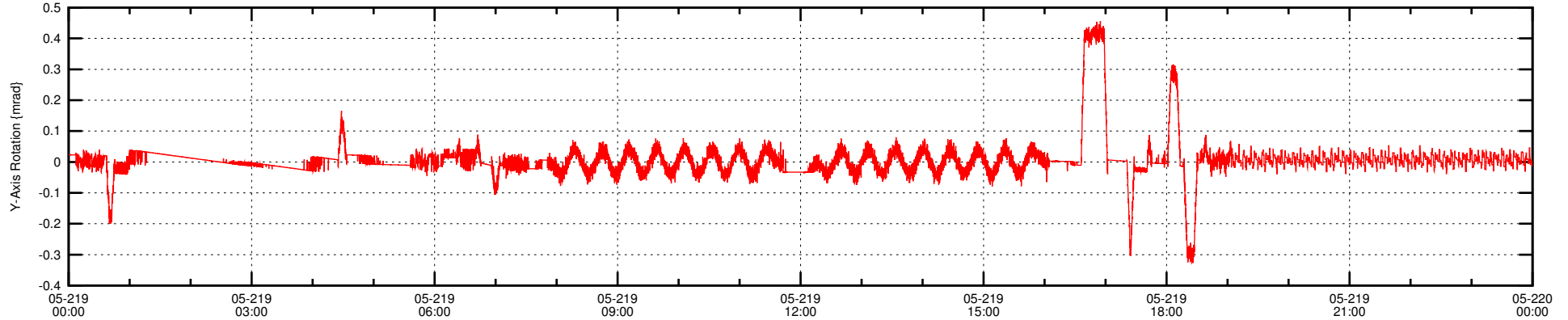


# Rotation From CK #2 to CK #1 (DOY 219-220)

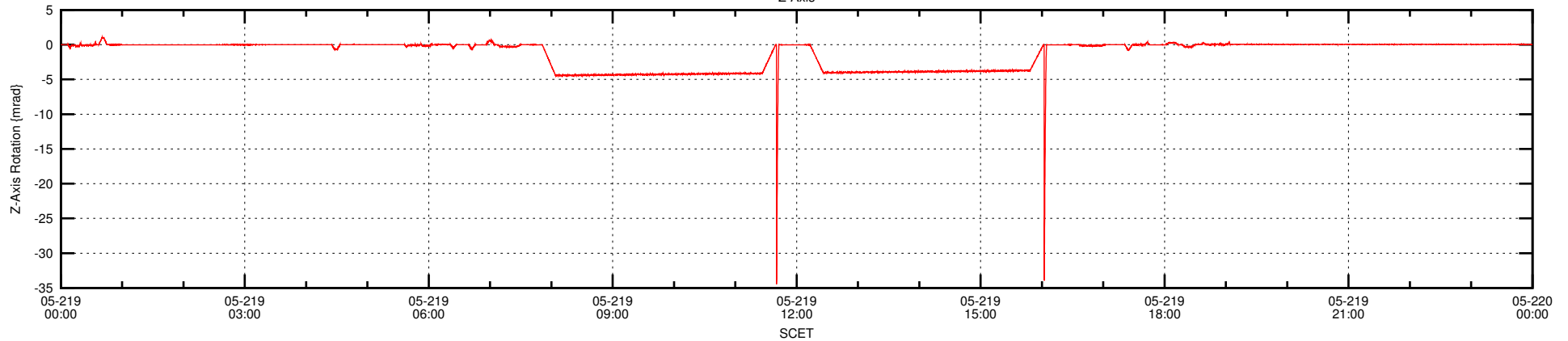
X-Axis (CK #1 = 05217\_05222ra.bc; CK #2 = 05212\_05242pl\_fsiv.bc)



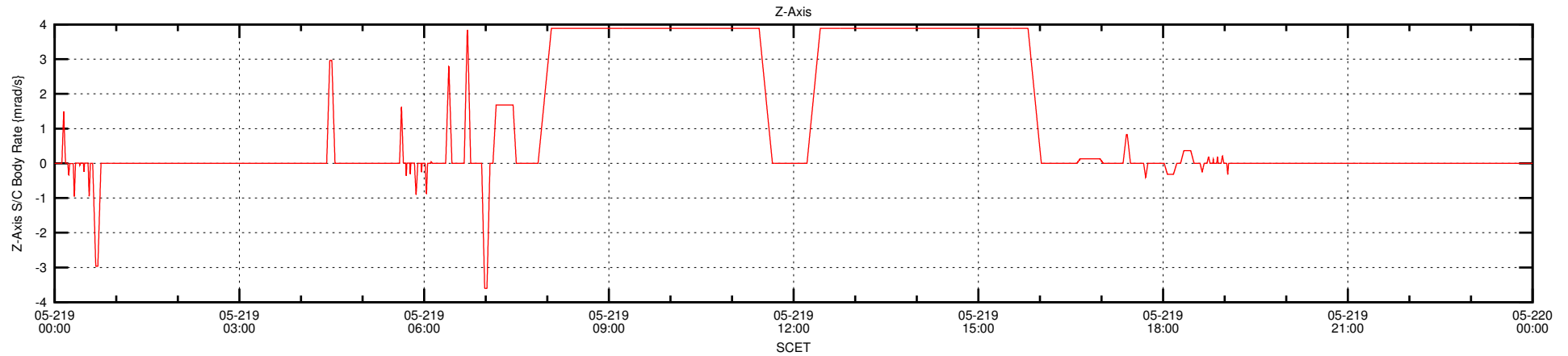
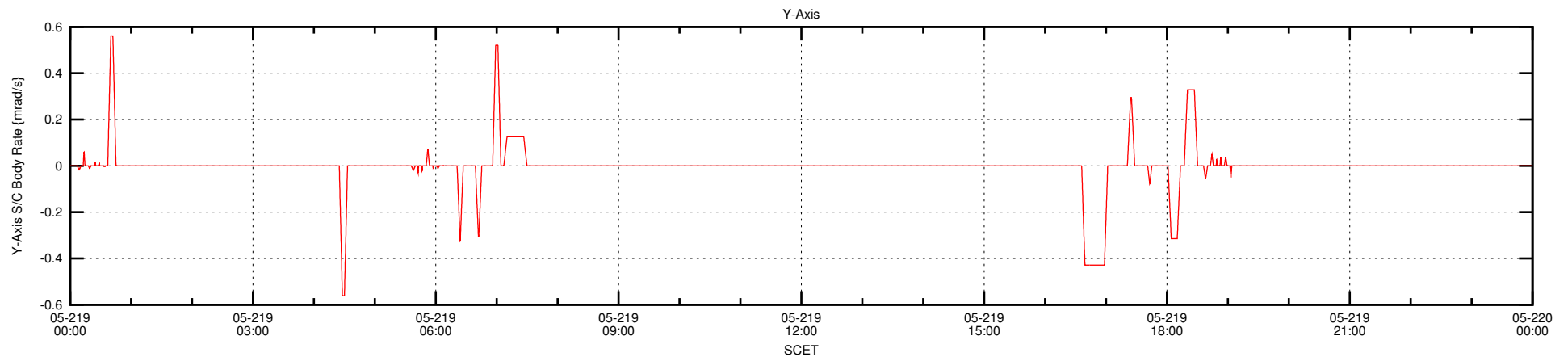
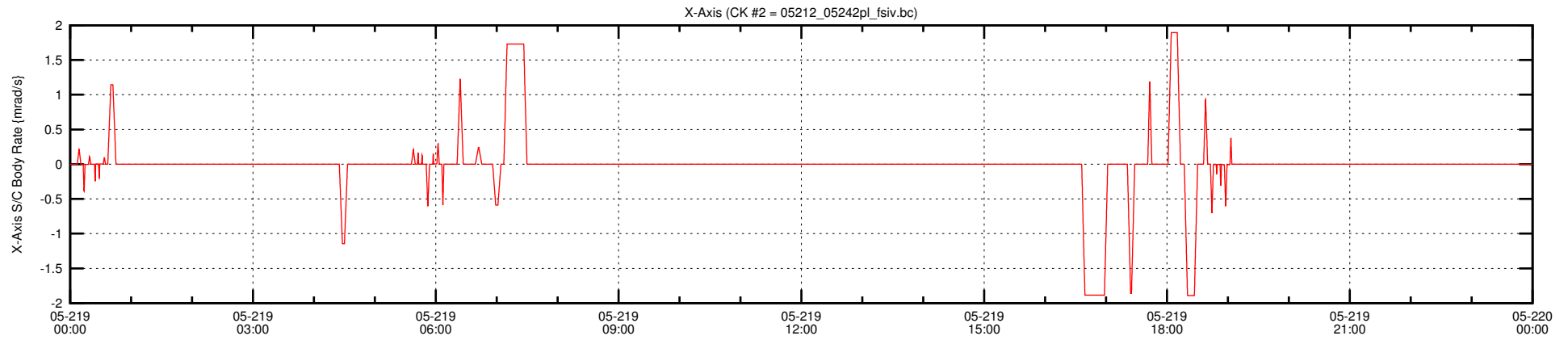
Y-Axis



Z-Axis

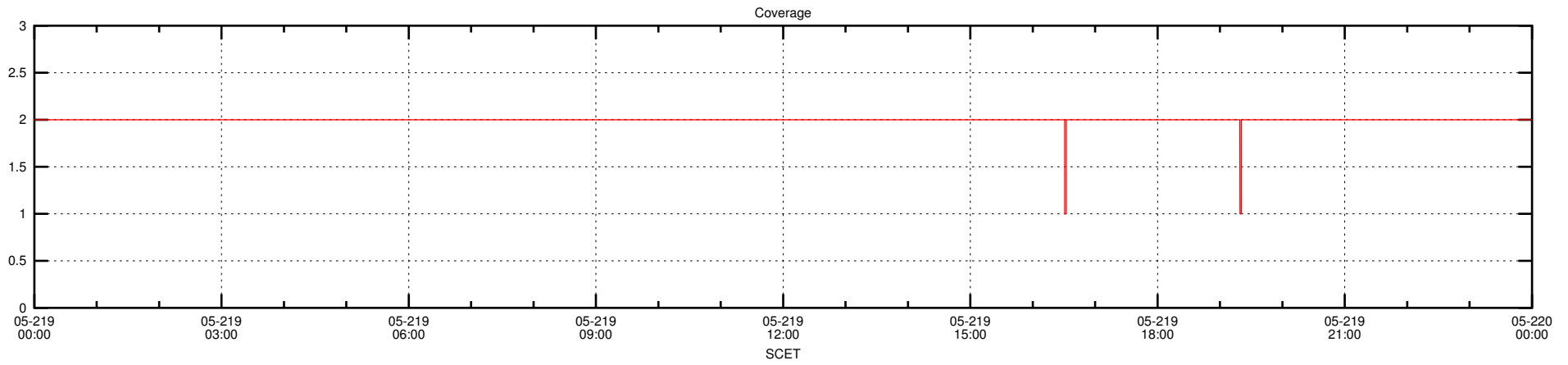


# CK #2 S/C Body Rates (DOY 219-220)



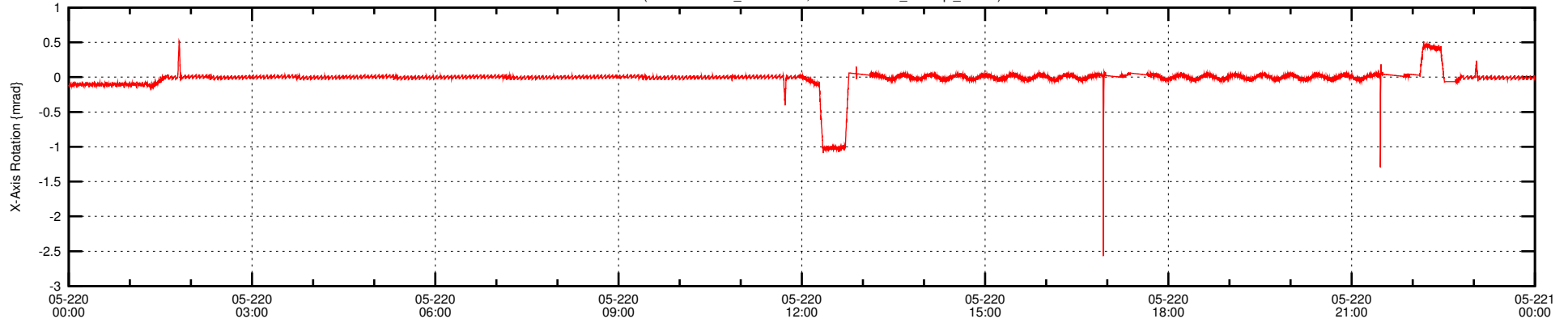


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 219-220)

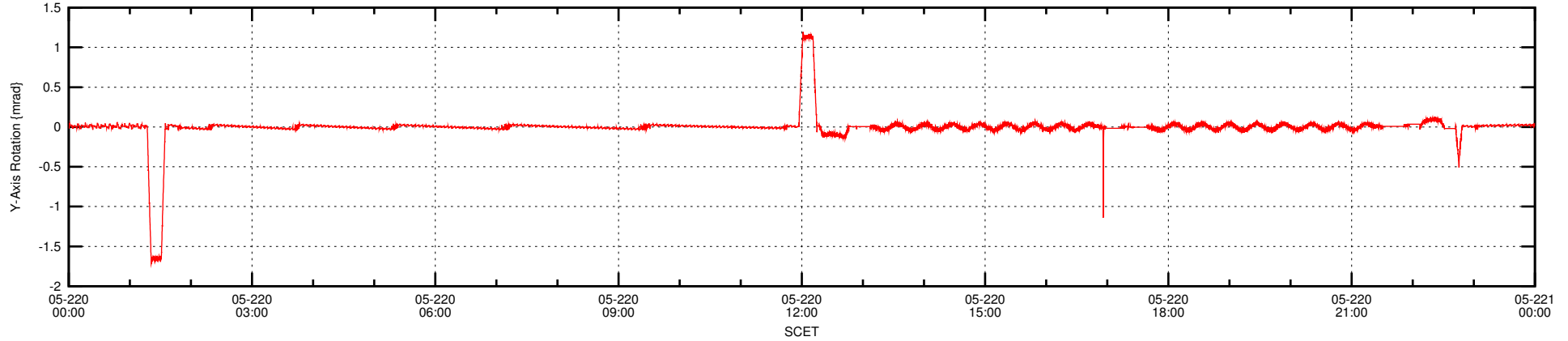


# Rotation From CK #2 to CK #1 (DOY 220-221)

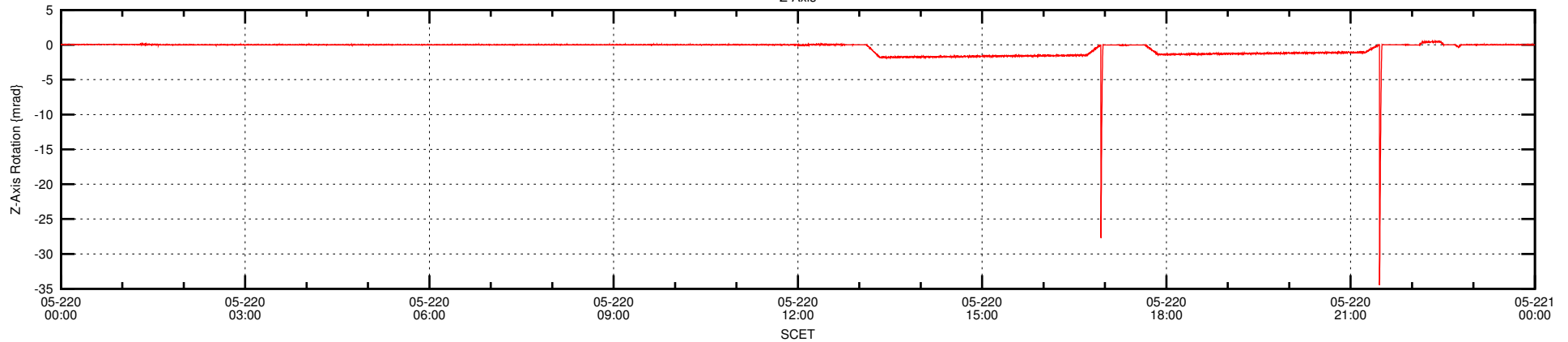
X-Axis (CK #1 = 05217\_05222ra.bc; CK #2 = 05212\_05242pl\_fsiv.bc)



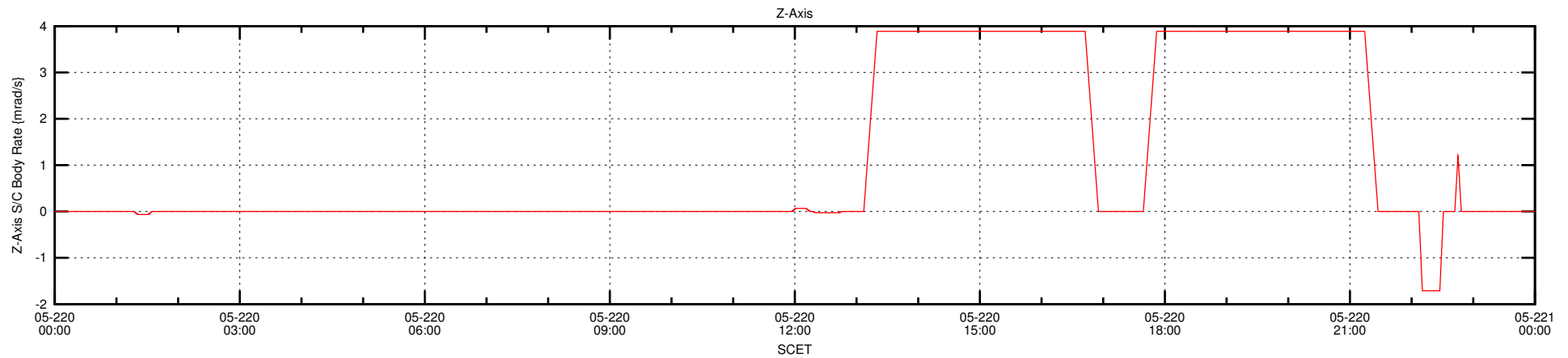
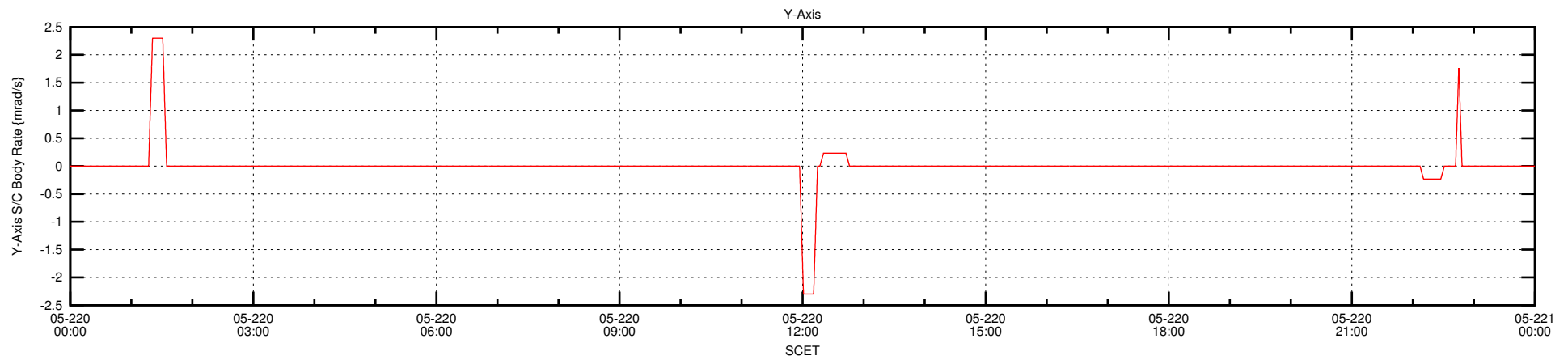
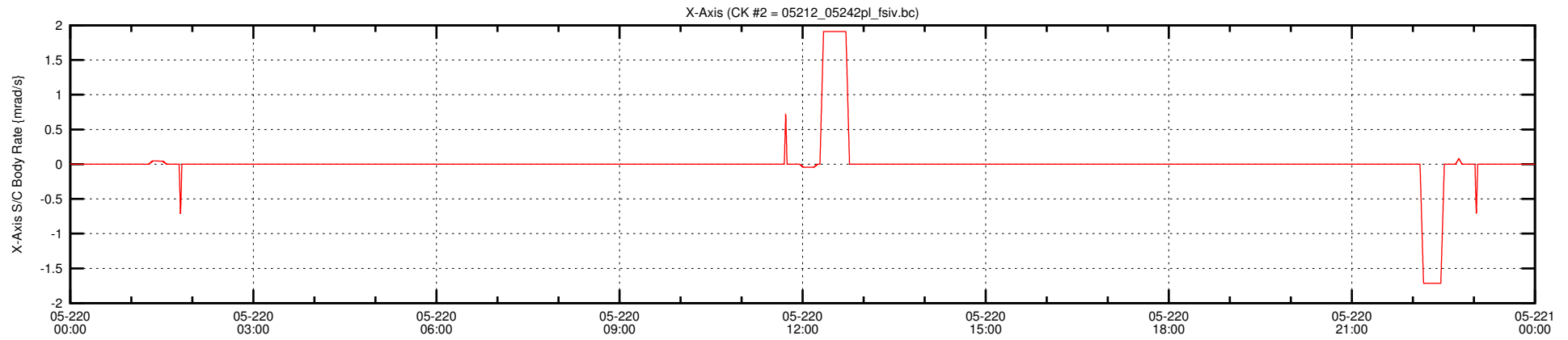
Y-Axis



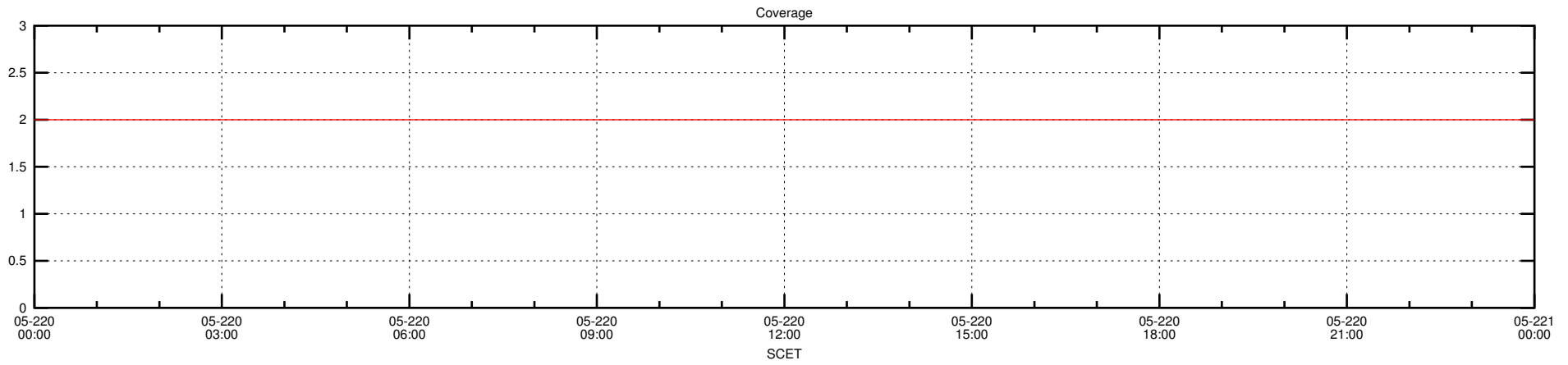
Z-Axis



# CK #2 S/C Body Rates (DOY 220-221)

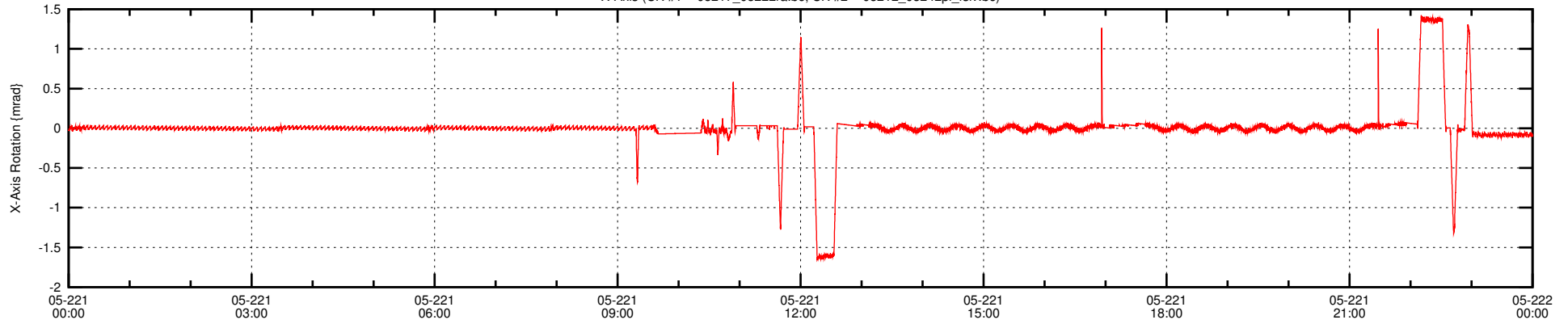


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 220-221)

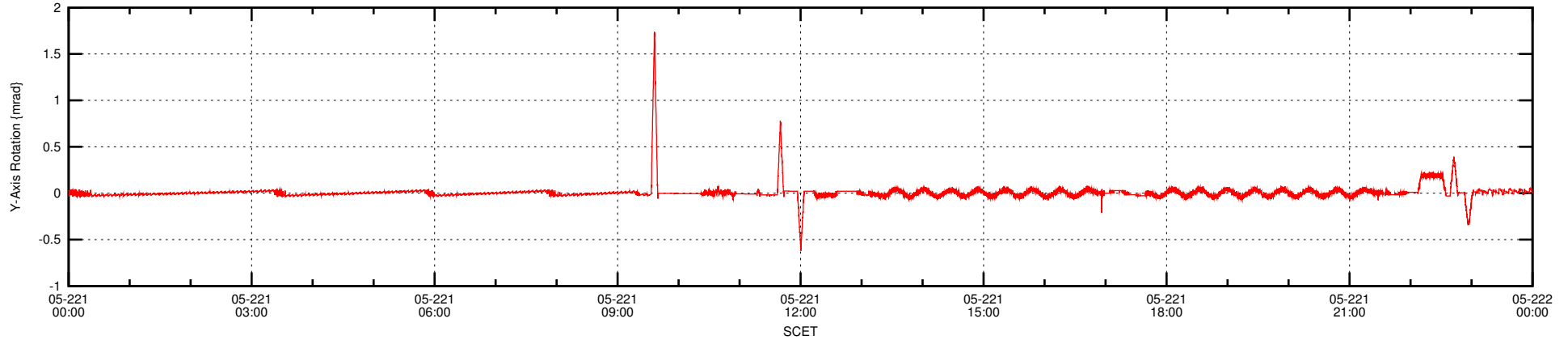


# Rotation From CK #2 to CK #1 (DOY 221-221)

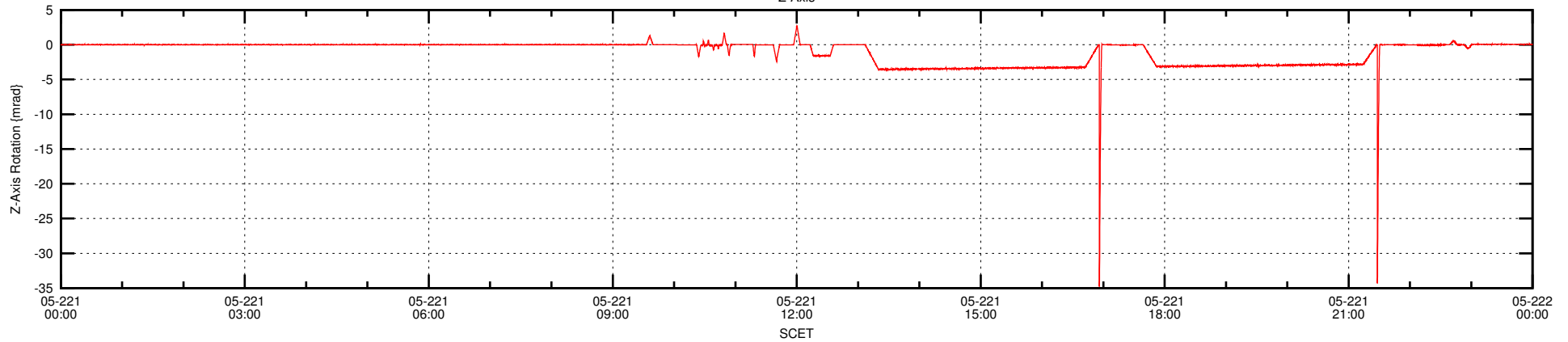
X-Axis (CK #1 = 05217\_05222ra.bc; CK #2 = 05212\_05242pl\_fsiv.bc)



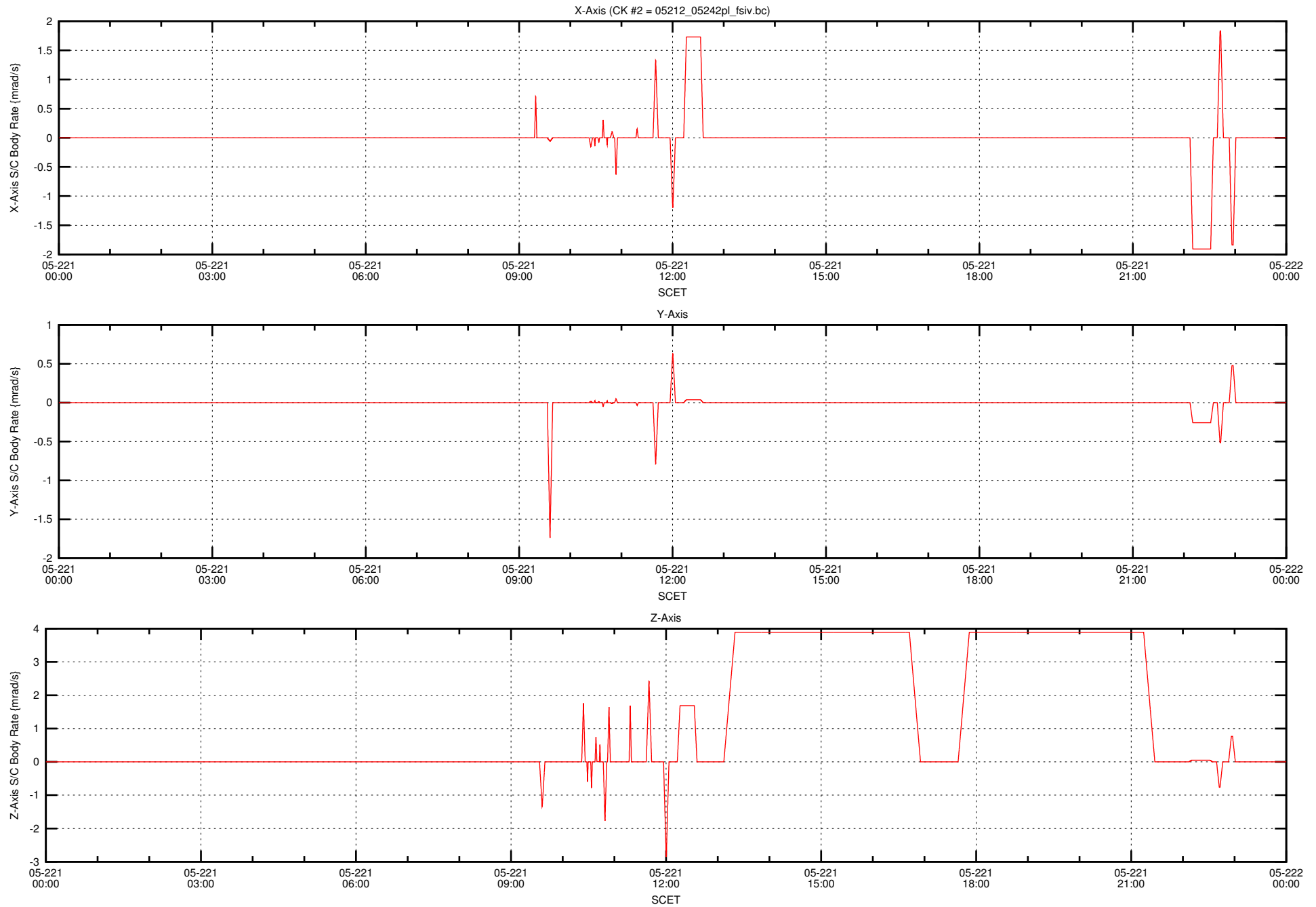
Y-Axis



Z-Axis



# CK #2 S/C Body Rates (DOY 221-221)



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 221-221)

