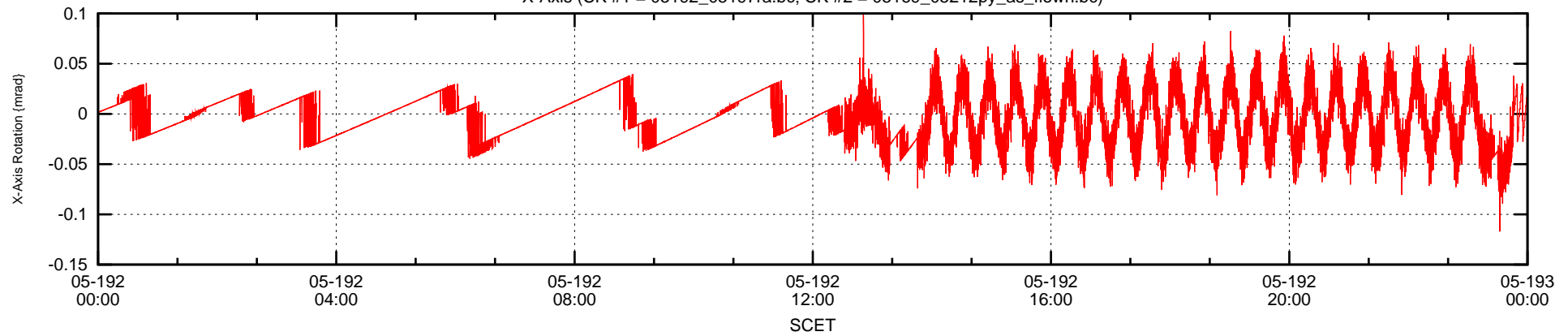
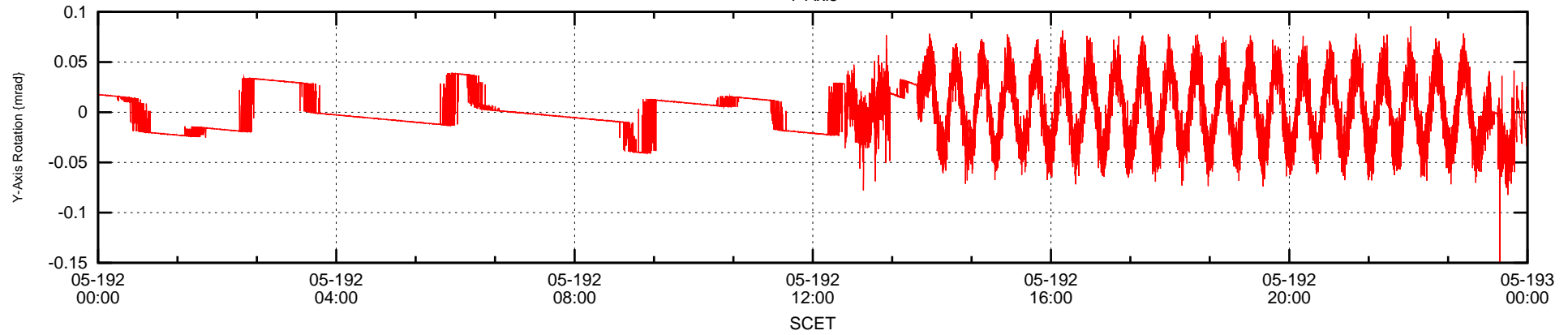


Rotation From CK #2 to CK #1 (DOY 192-193)

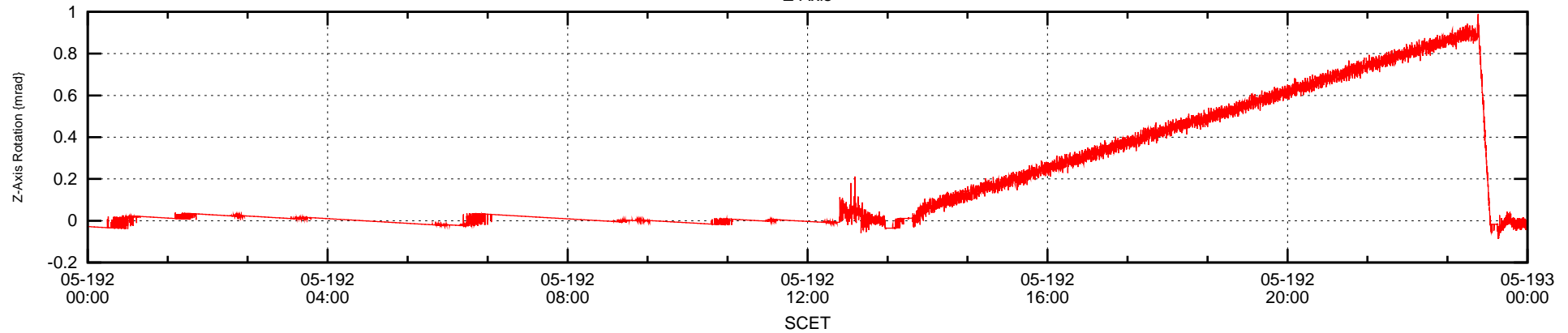
X-Axis (CK #1 = 05192_05197ra.bc; CK #2 = 05169_05212py_as_flown.bc)



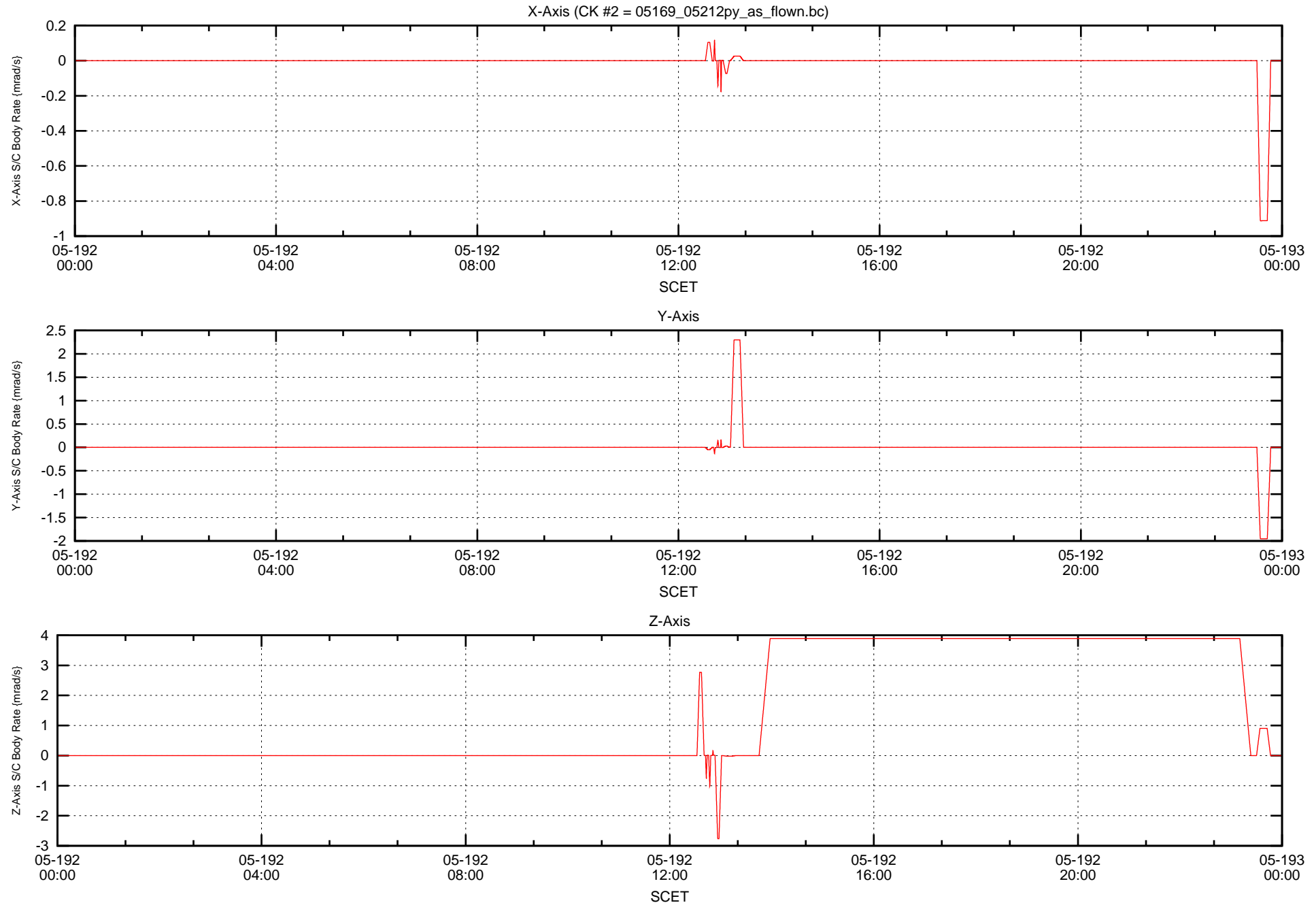
Y-Axis



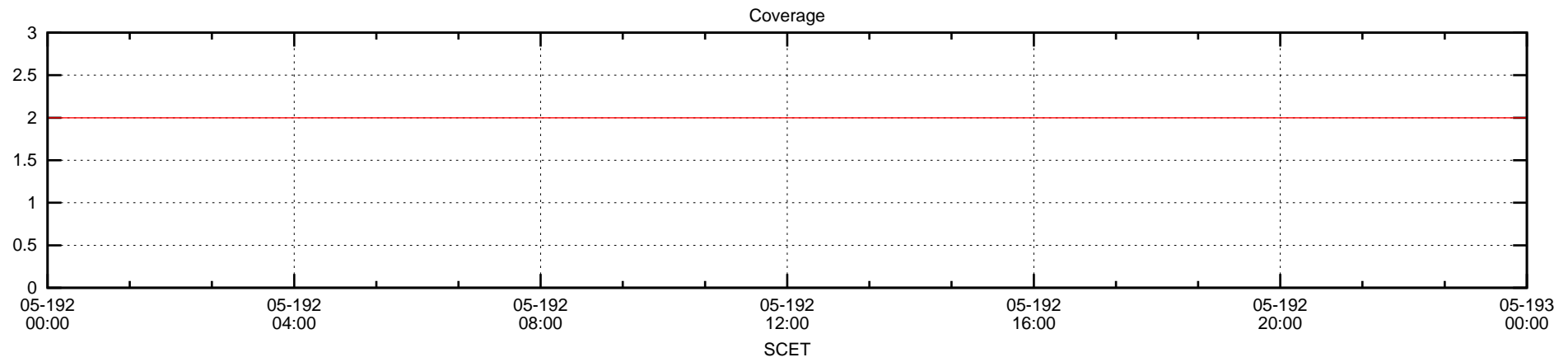
Z-Axis



CK #2 S/C Body Rates (DOY 192-193)

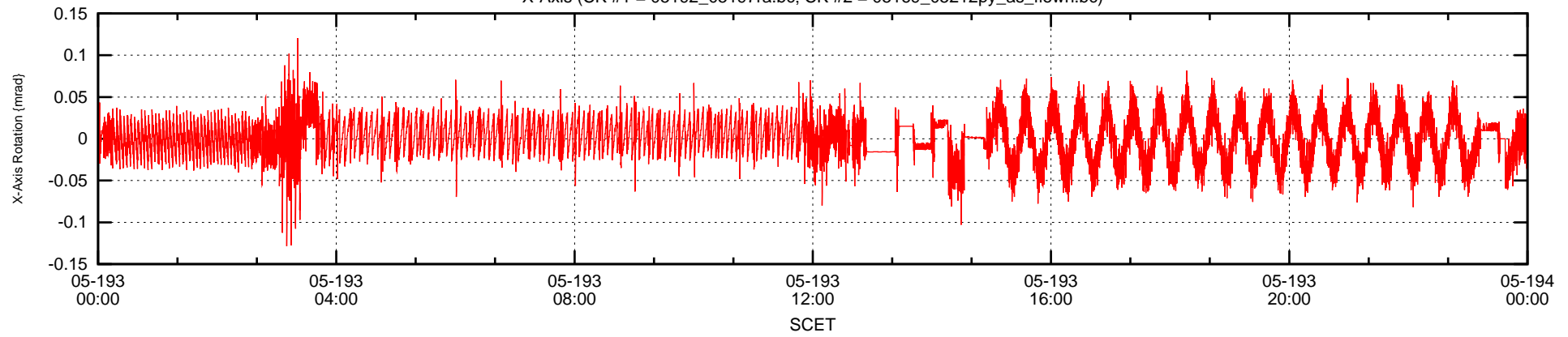


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 192-193)

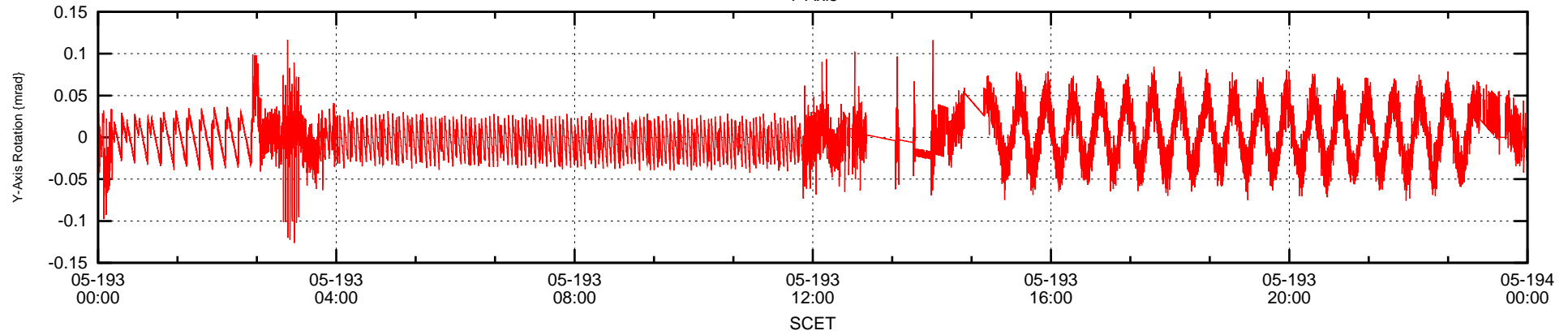


Rotation From CK #2 to CK #1 (DOY 193-194)

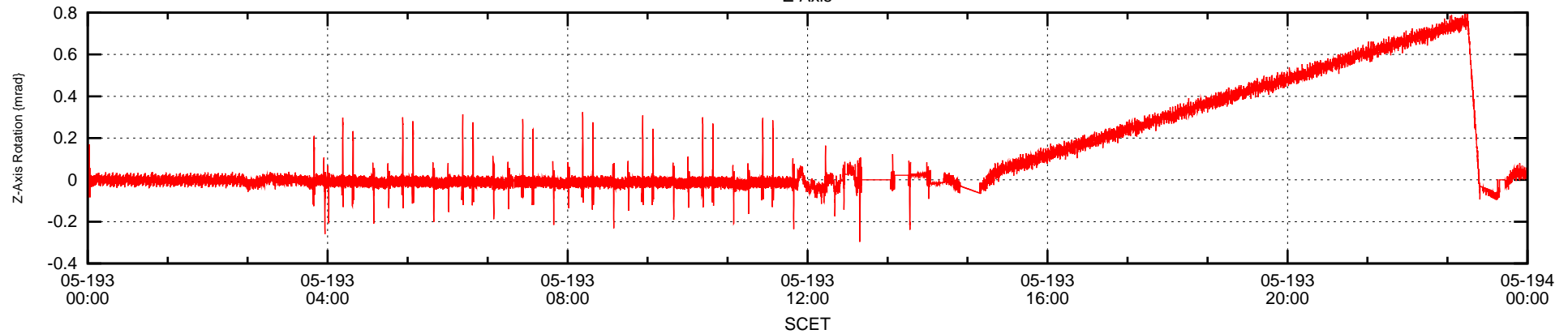
X-Axis (CK #1 = 05192_05197ra.bc; CK #2 = 05169_05212py_as_flownd.bc)



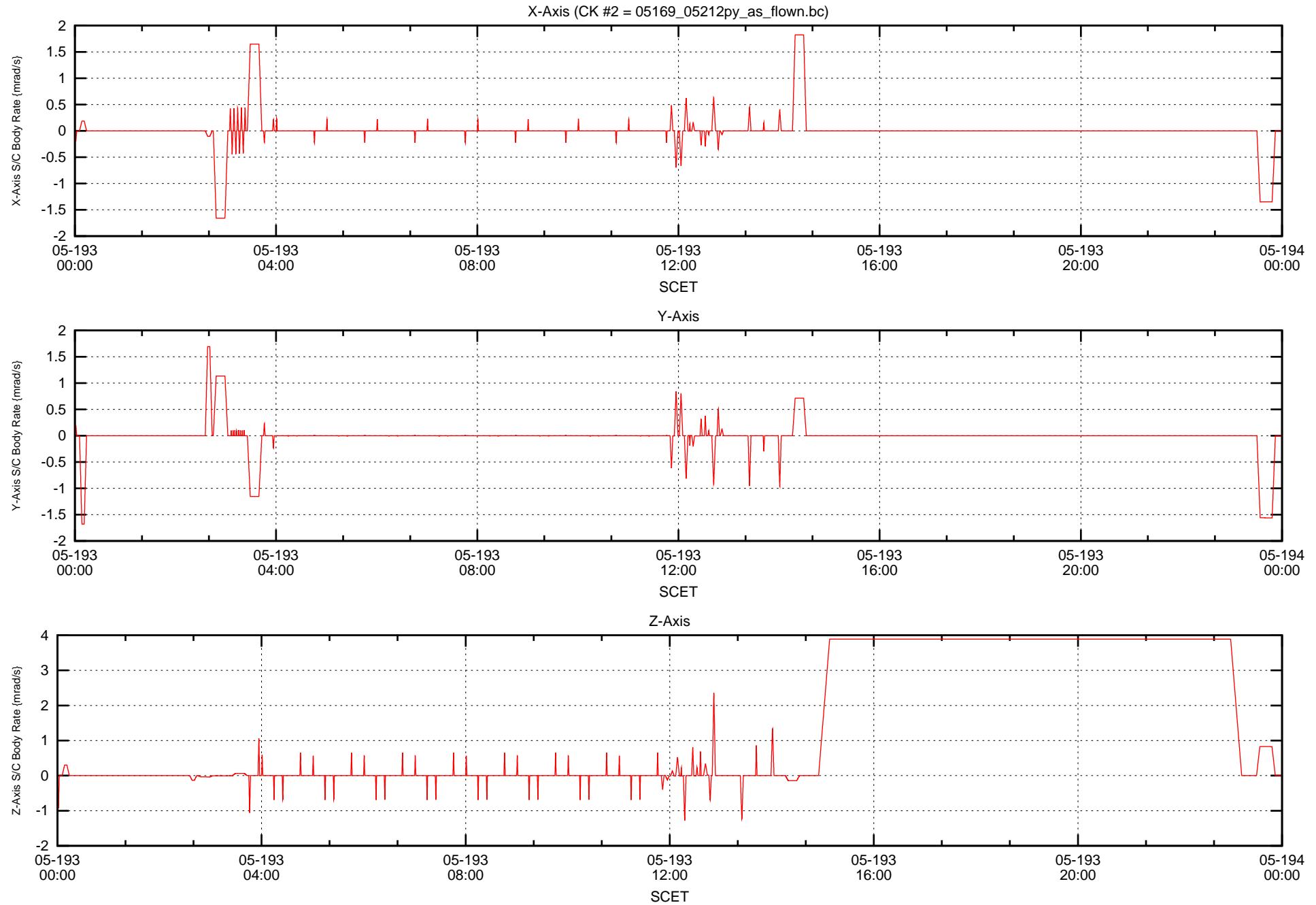
Y-Axis



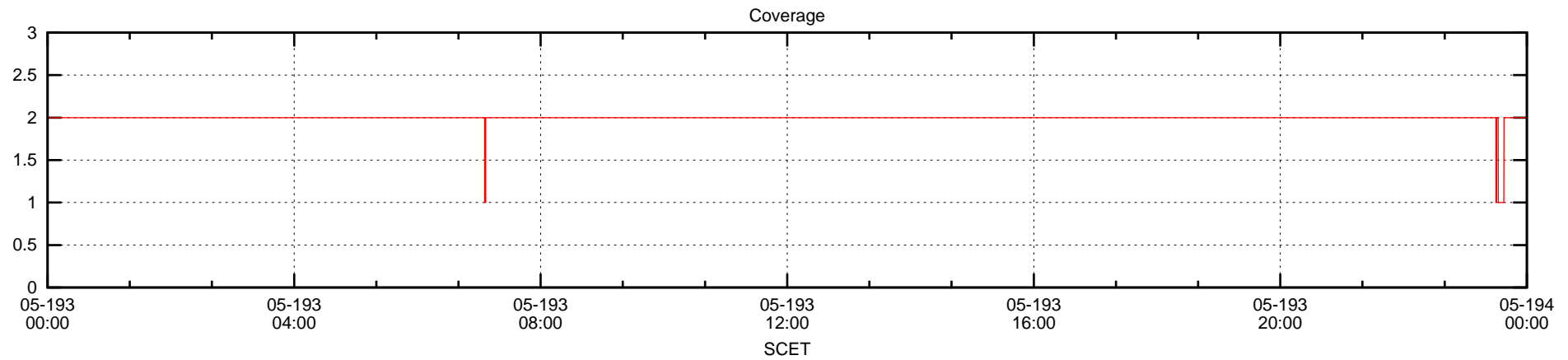
Z-Axis



CK #2 S/C Body Rates (DOY 193-194)

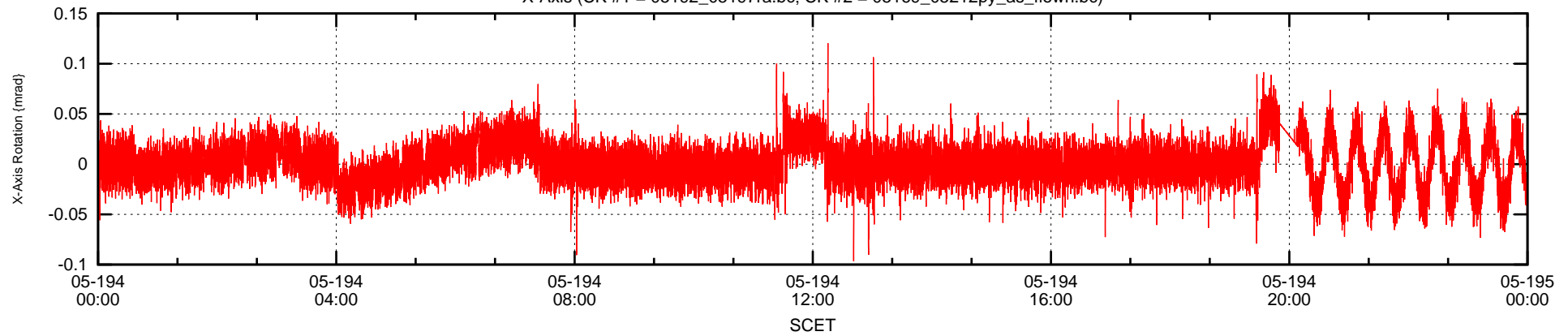


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 193-194)

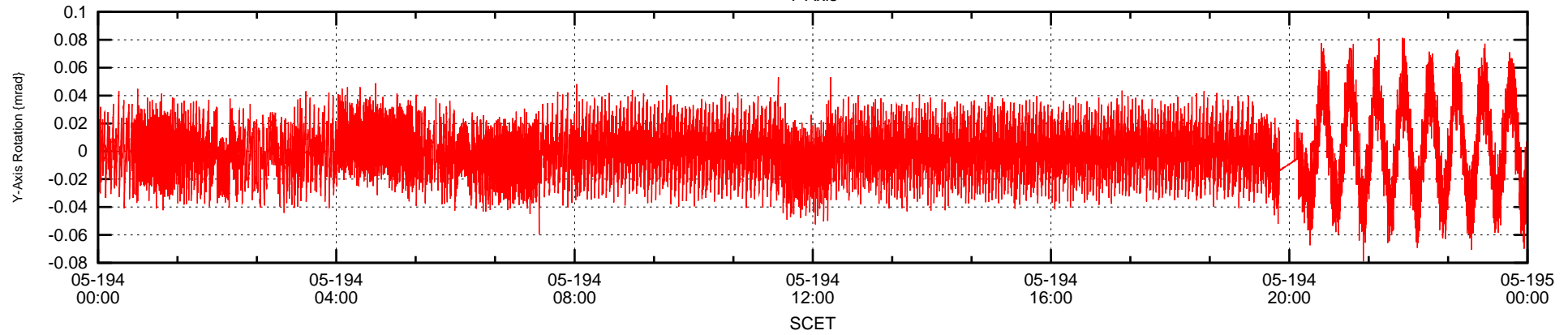


Rotation From CK #2 to CK #1 (DOY 194-195)

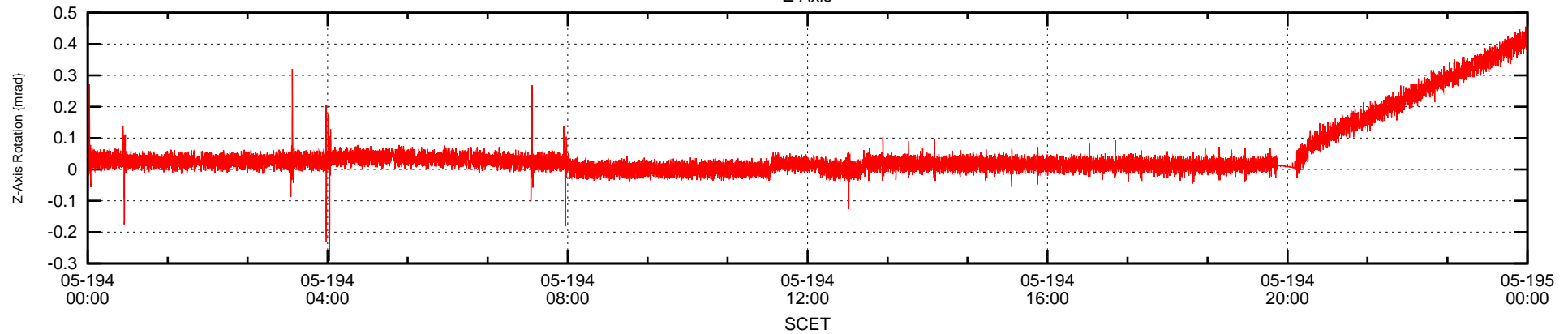
X-Axis (CK #1 = 05192_05197ra.bc; CK #2 = 05169_05212py_as_flownd.bc)



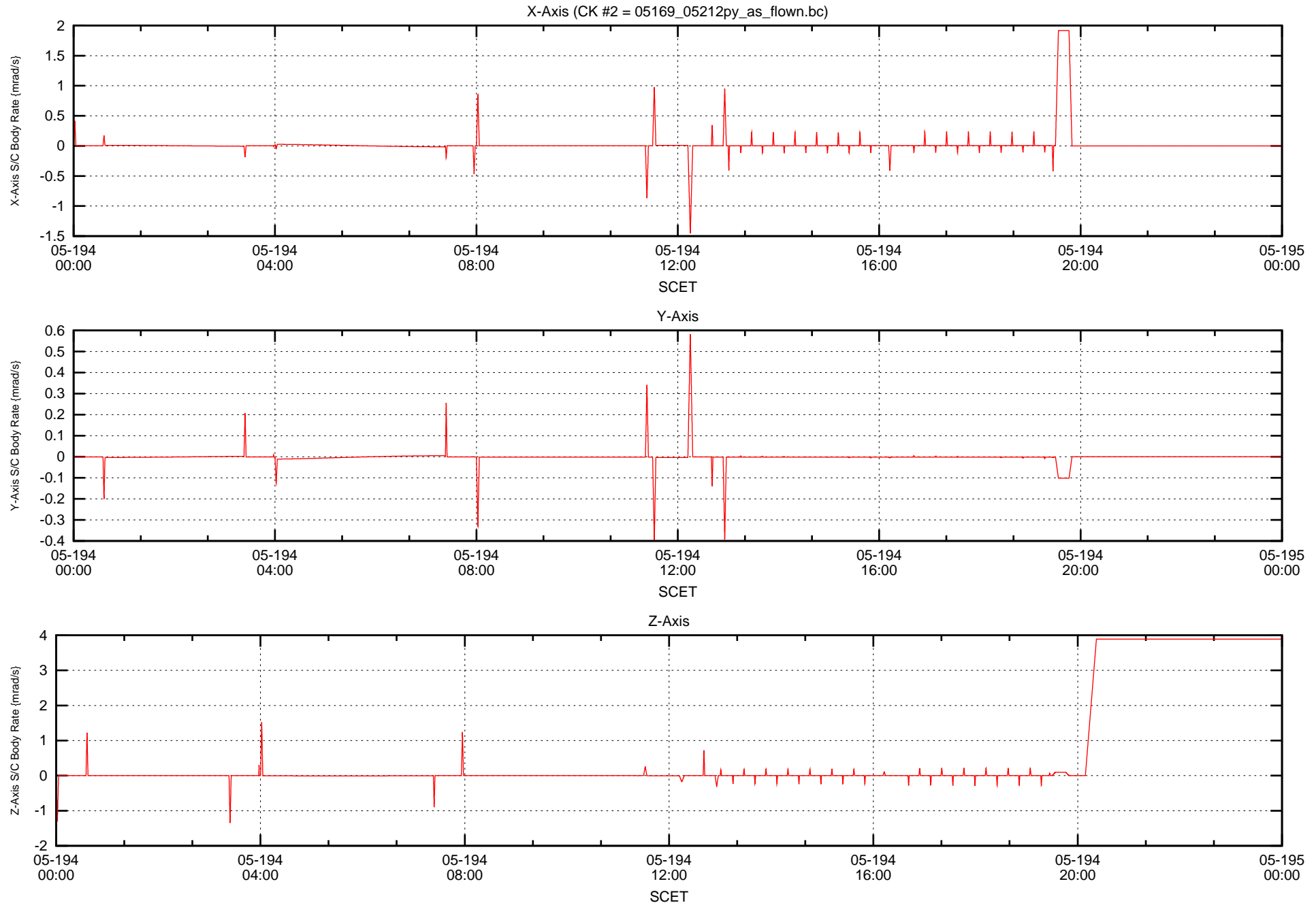
Y-Axis



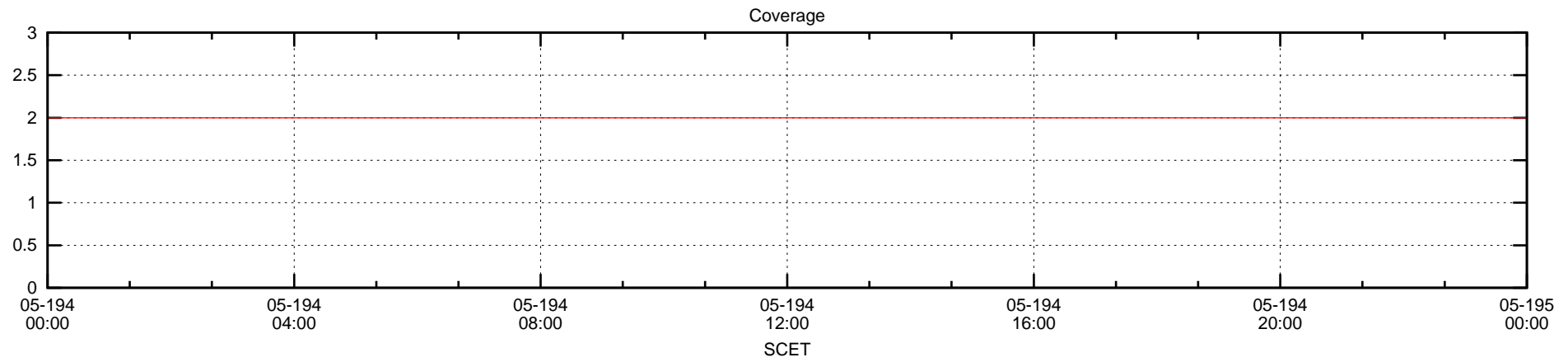
Z-Axis



CK #2 S/C Body Rates (DOY 194-195)

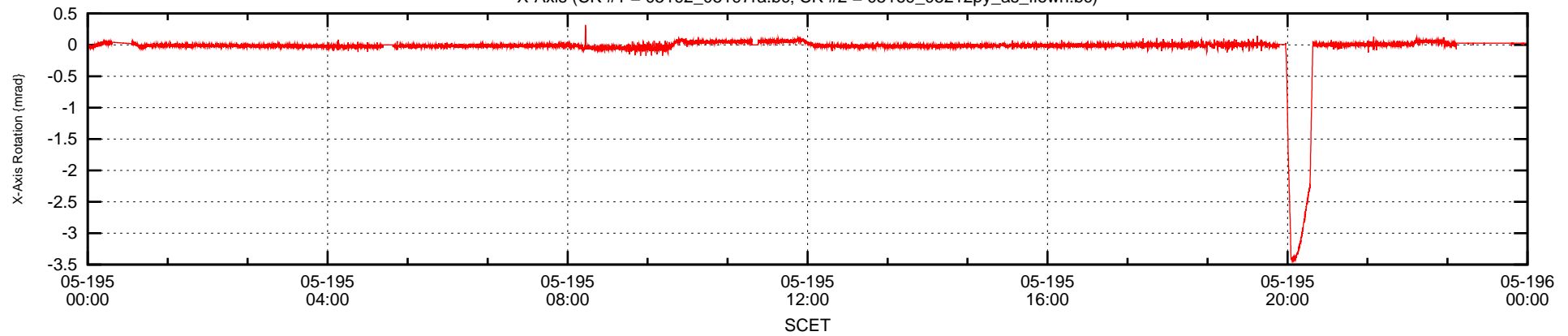


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 194-195)

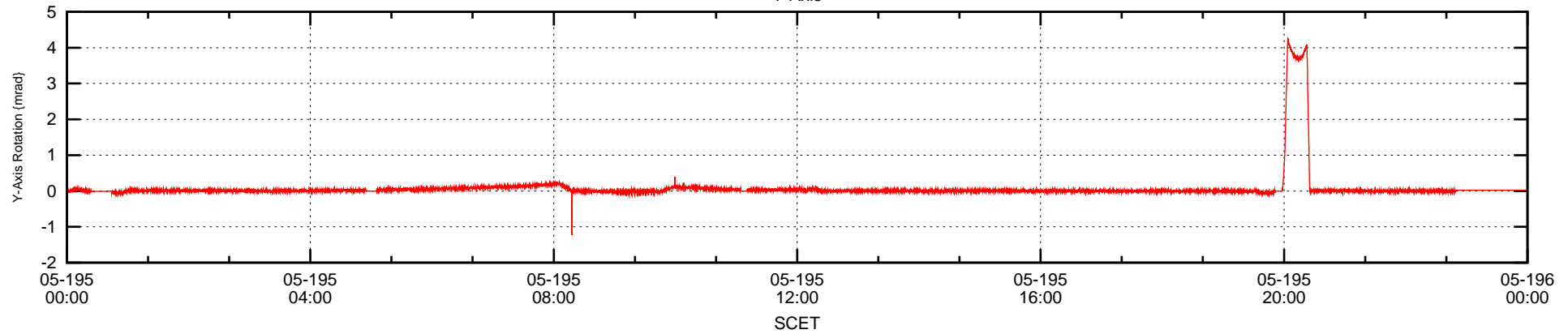


Rotation From CK #2 to CK #1 (DOY 195-196)

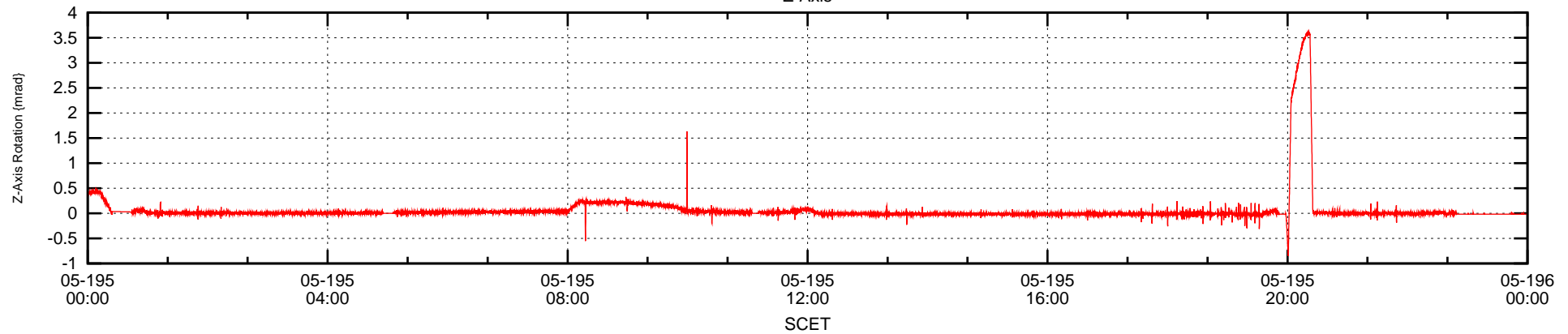
X-Axis (CK #1 = 05192_05197ra.bc; CK #2 = 05169_05212py_as_flown.bc)



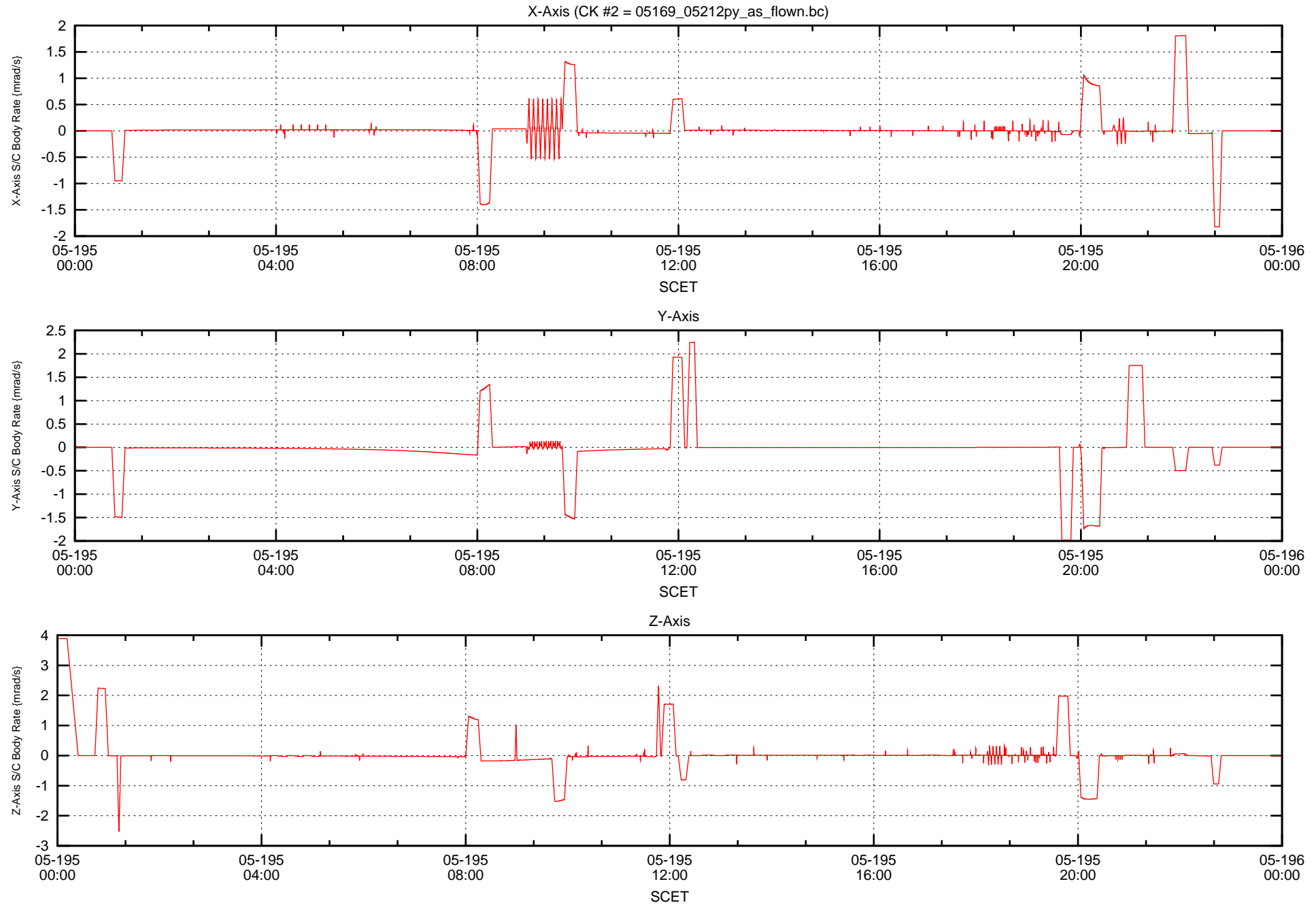
Y-Axis



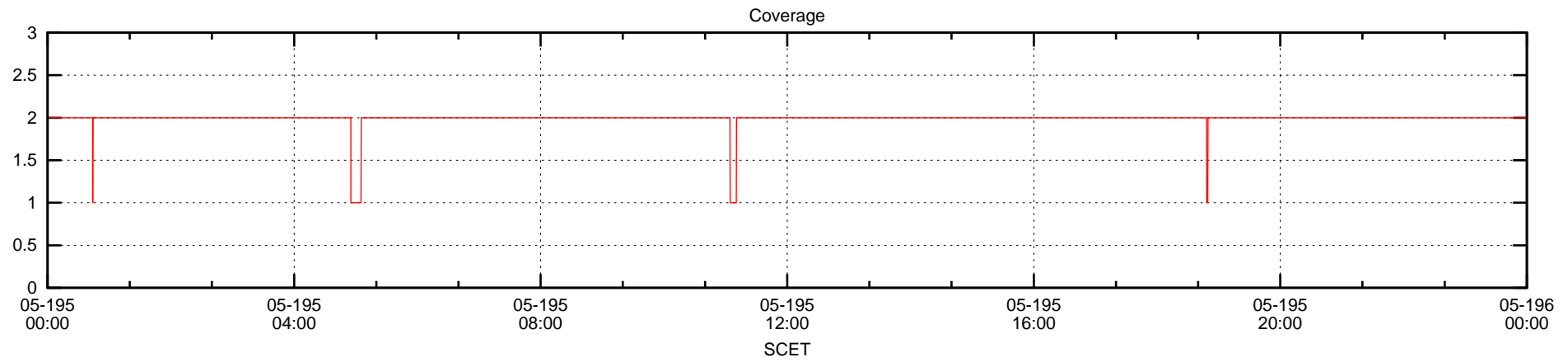
Z-Axis



CK #2 S/C Body Rates (DOY 195-196)

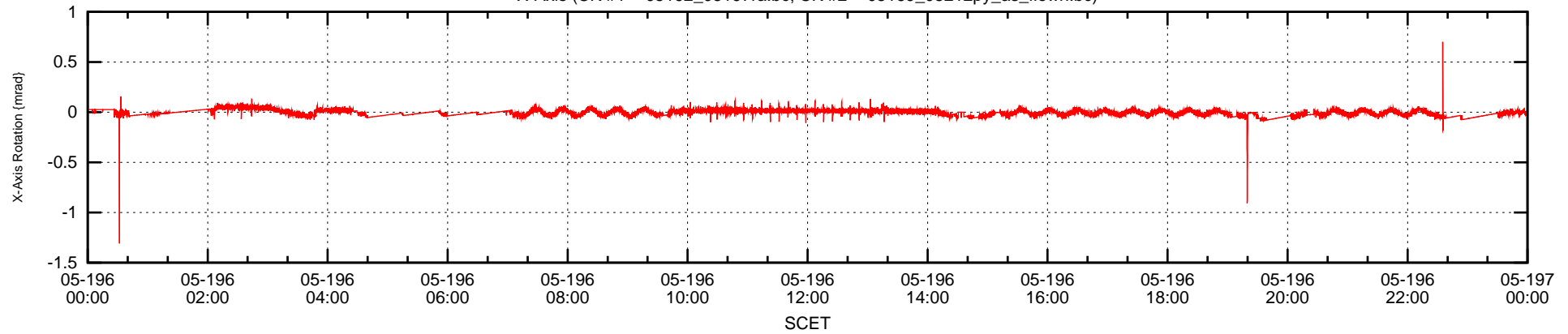


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 195-196)

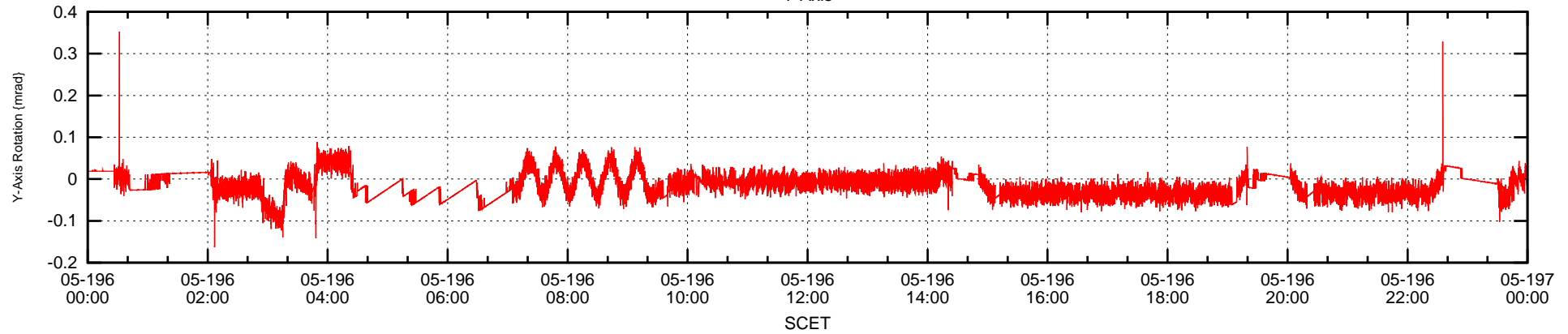


Rotation From CK #2 to CK #1 (DOY 196-196)

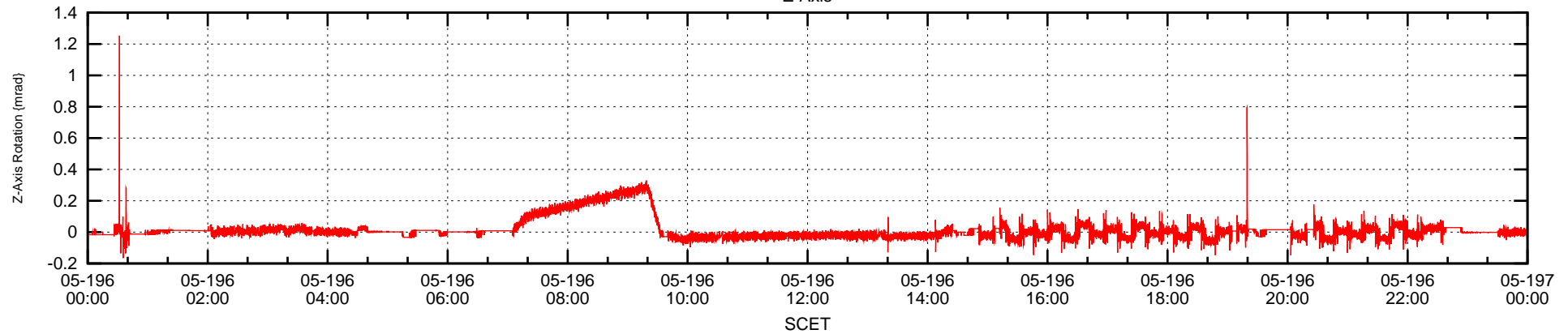
X-Axis (CK #1 = 05192_05197ra.bc; CK #2 = 05169_05212py_as_flown.bc)



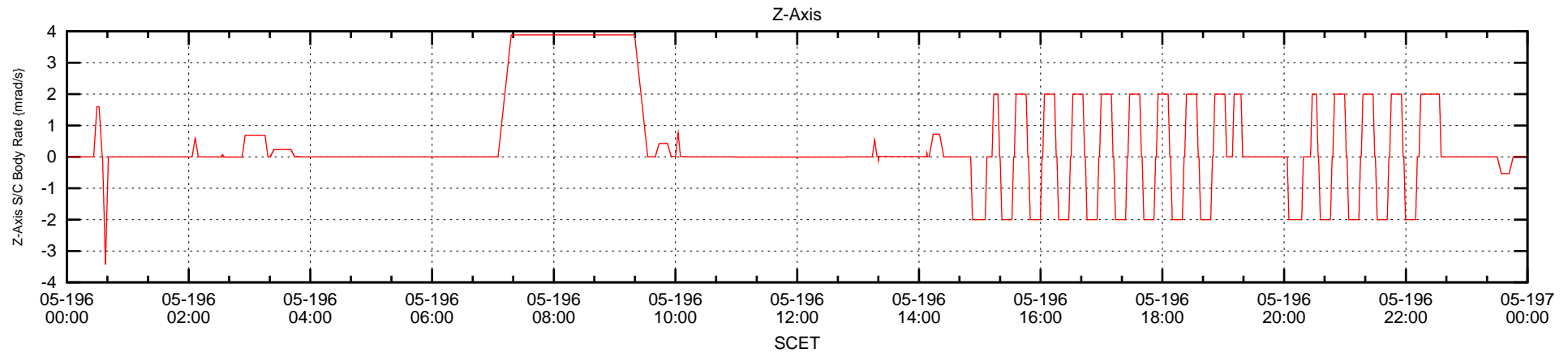
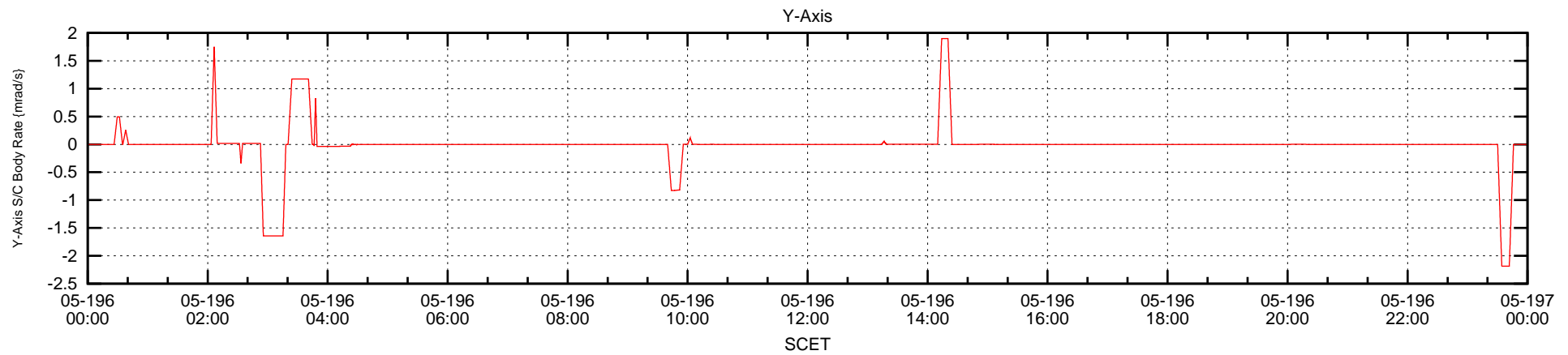
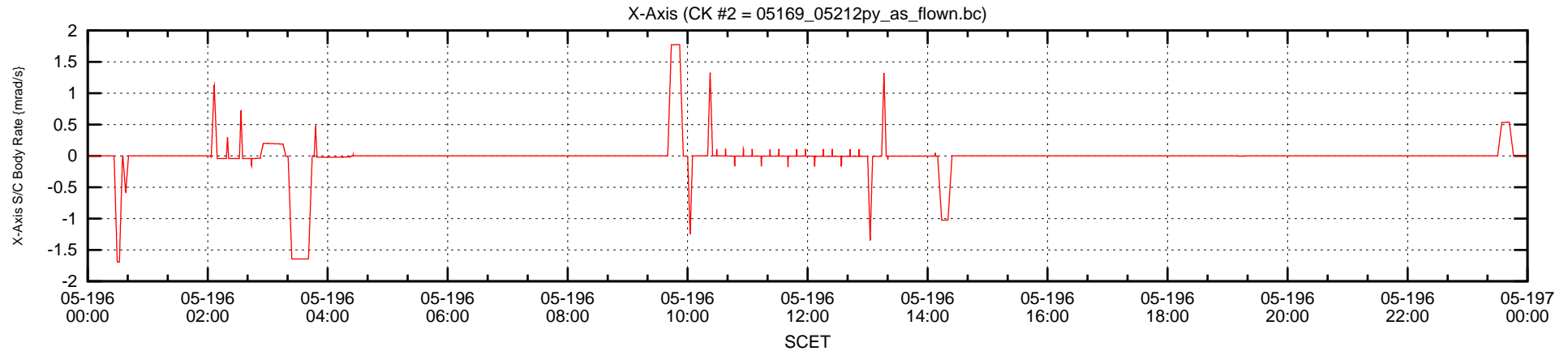
Y-Axis



Z-Axis



CK #2 S/C Body Rates (DOY 196-196)



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 196-196)

