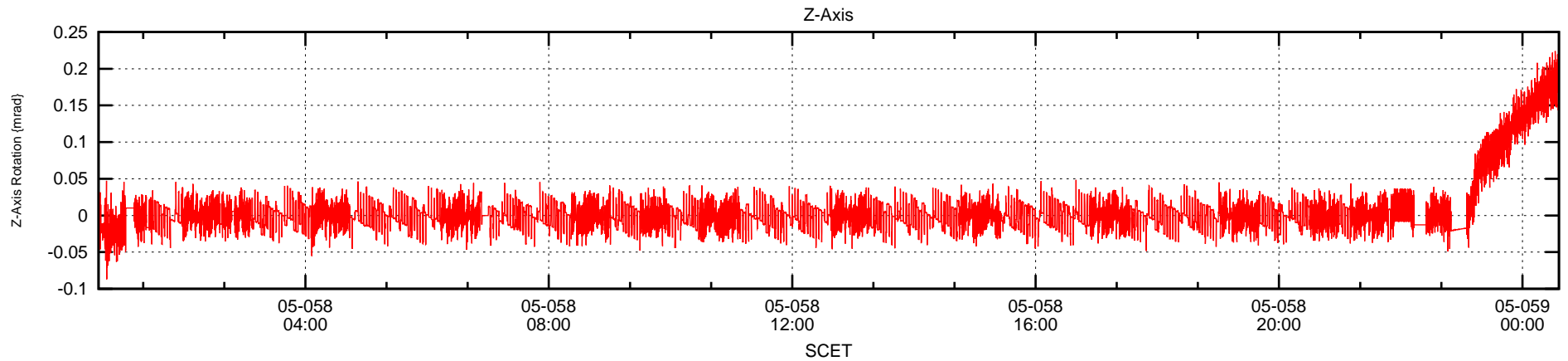
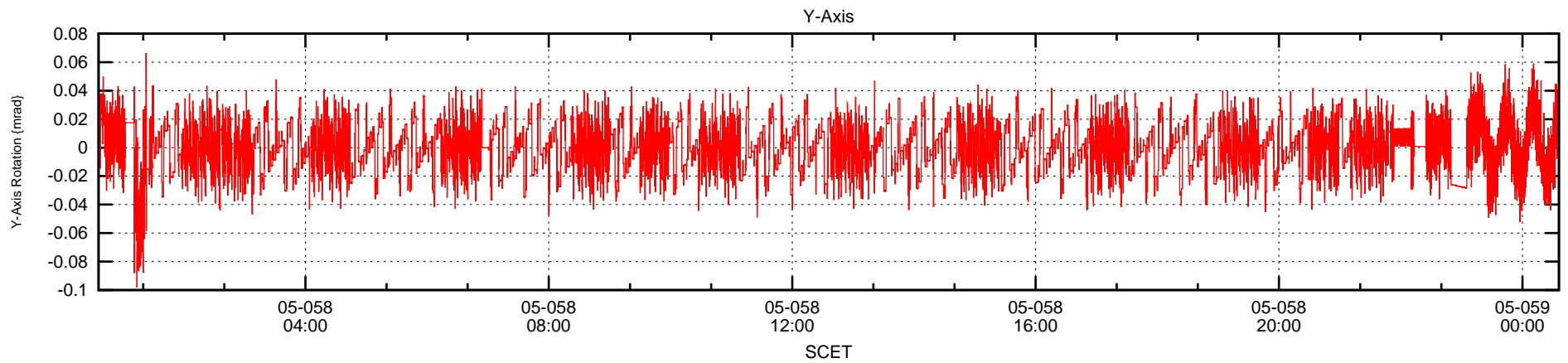
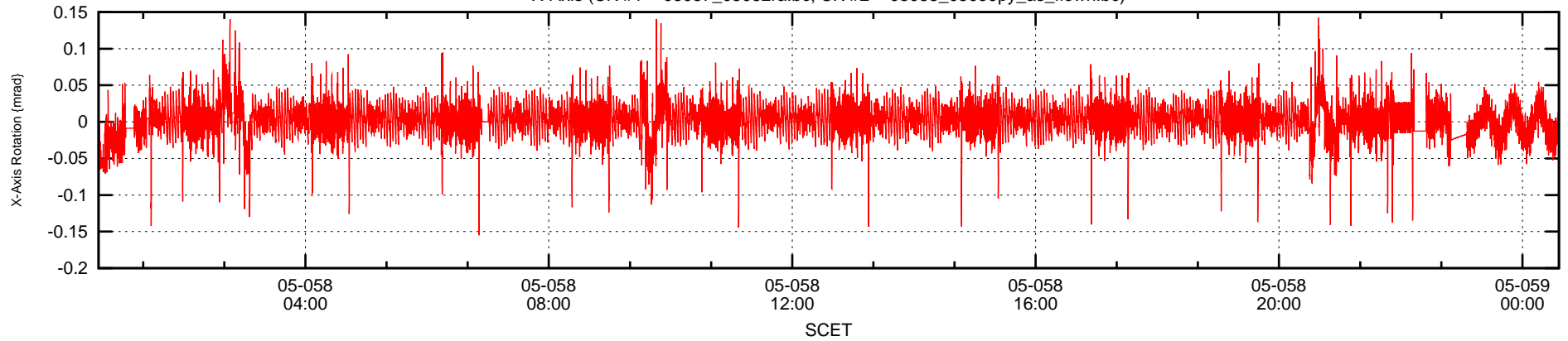


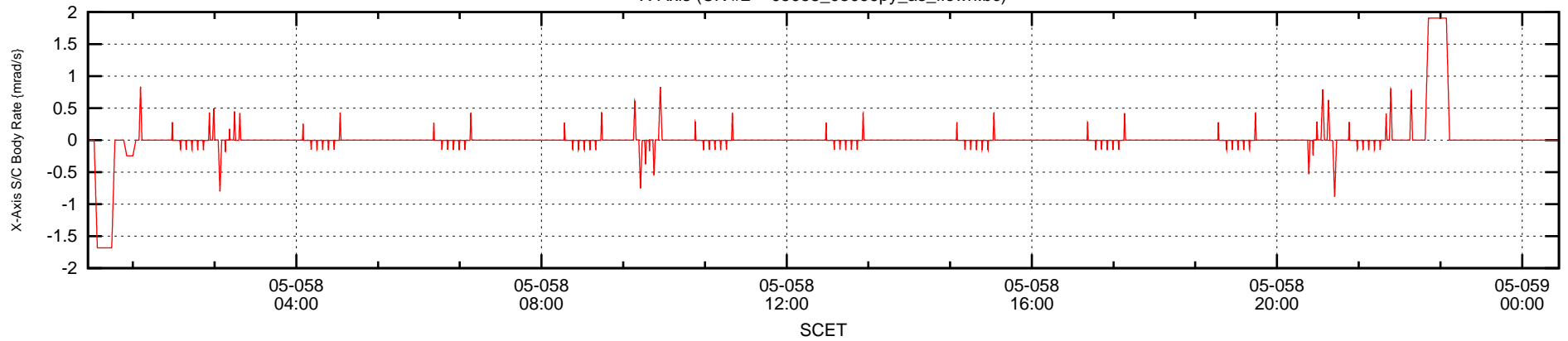
# Rotation From CK #2 to CK #1 (DOY 058-059)

X-Axis (CK #1 = 05057\_05062ra.bc; CK #2 = 05058\_05099py\_as\_flown.bc)

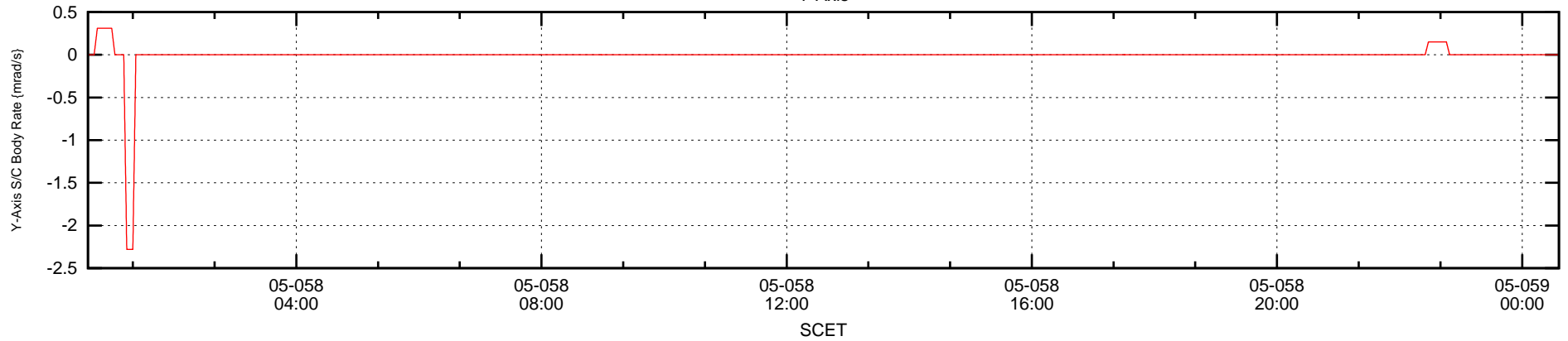


# CK #2 S/C Body Rates (DOY 058-059)

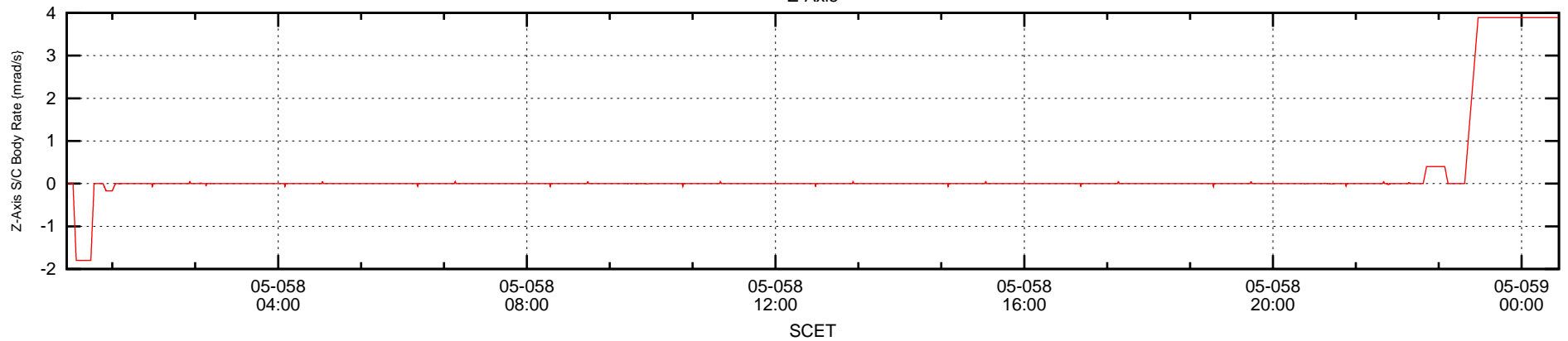
X-Axis (CK #2 = 05058\_05099py\_as\_flow.n.bc)



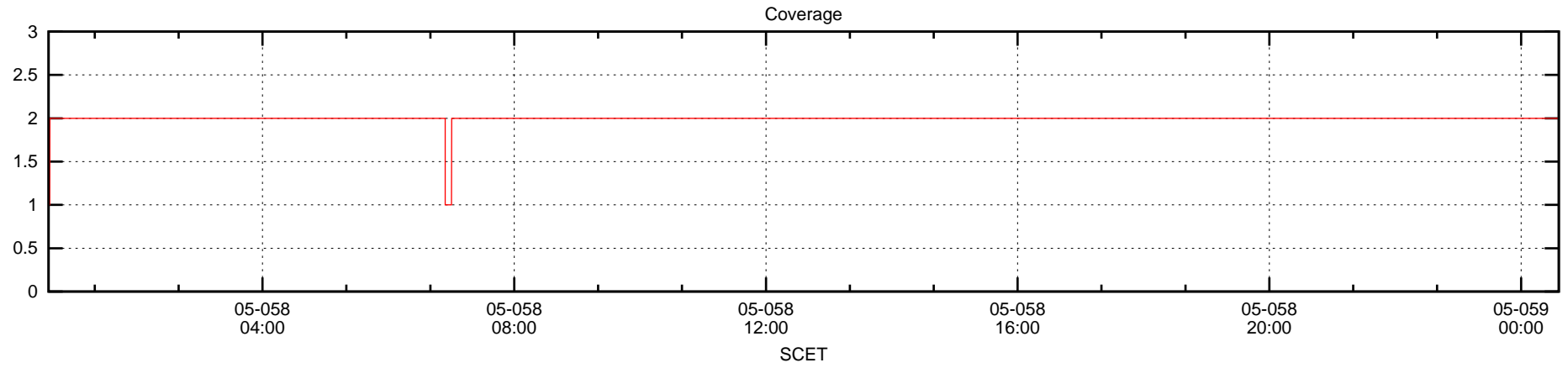
Y-Axis



Z-Axis

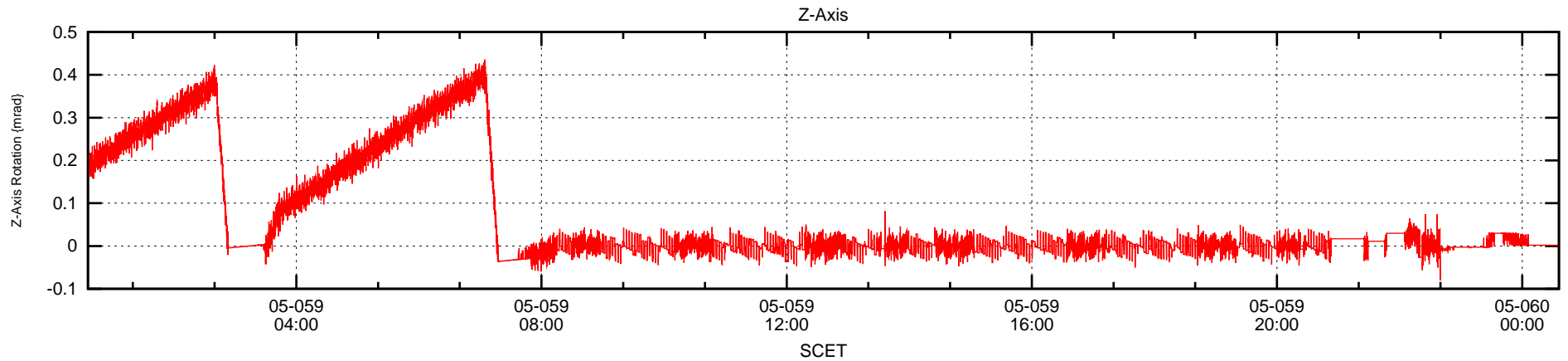
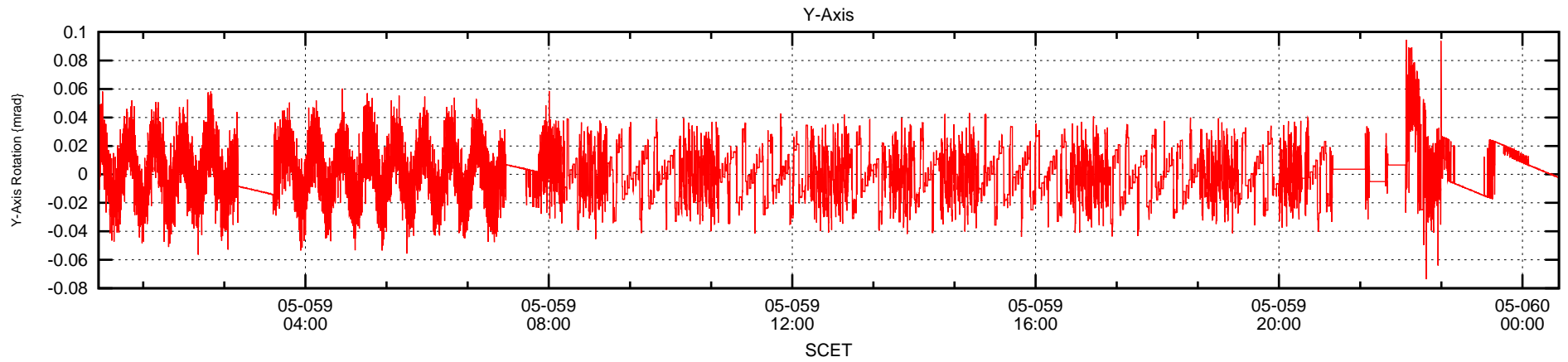
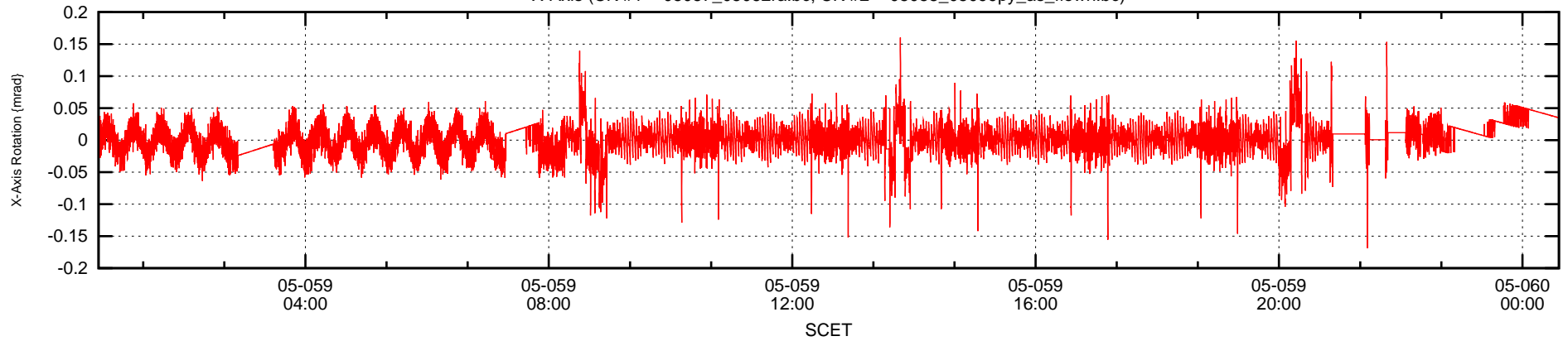


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 058-059)



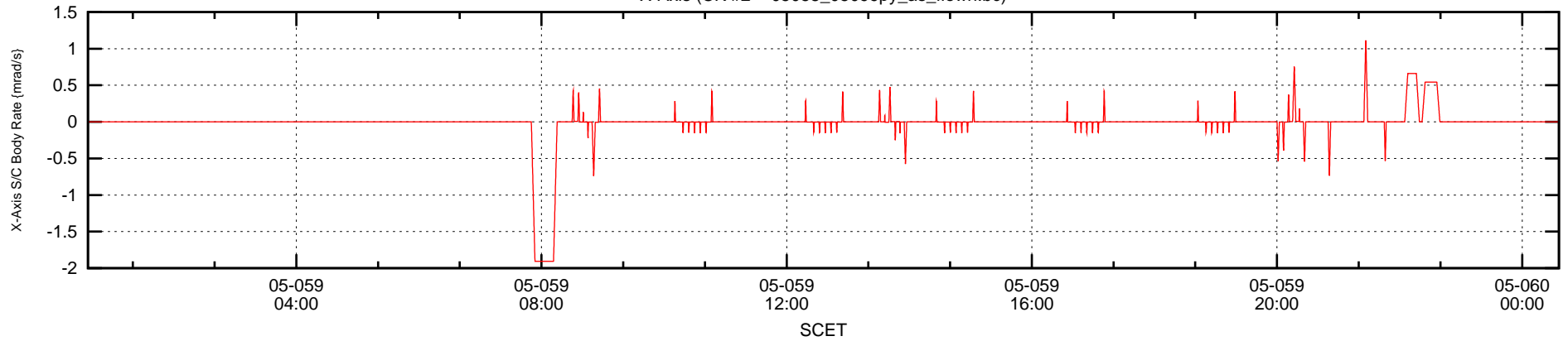
# Rotation From CK #2 to CK #1 (DOY 059-060)

X-Axis (CK #1 = 05057\_05062ra.bc; CK #2 = 05058\_05099py\_as\_flowm.bc)

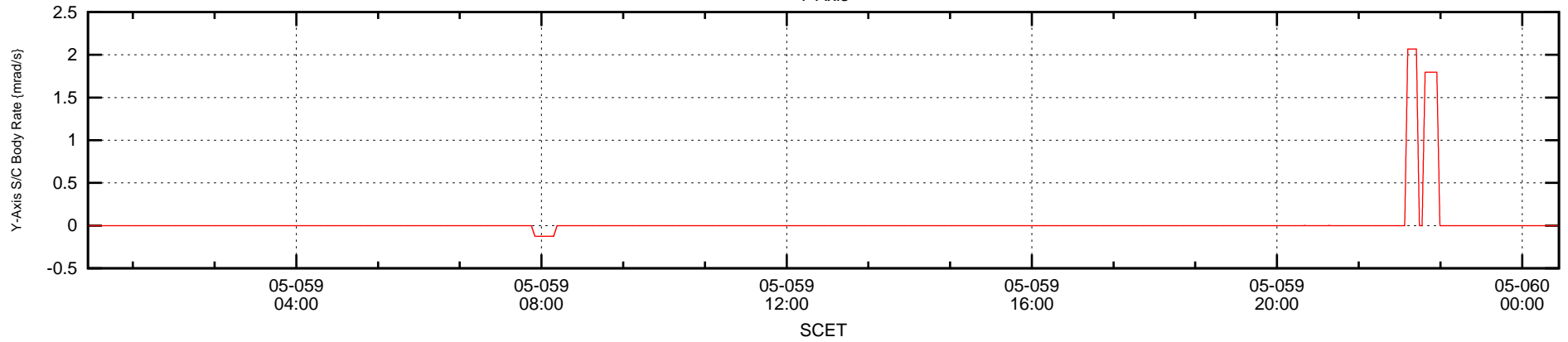


# CK #2 S/C Body Rates (DOY 059-060)

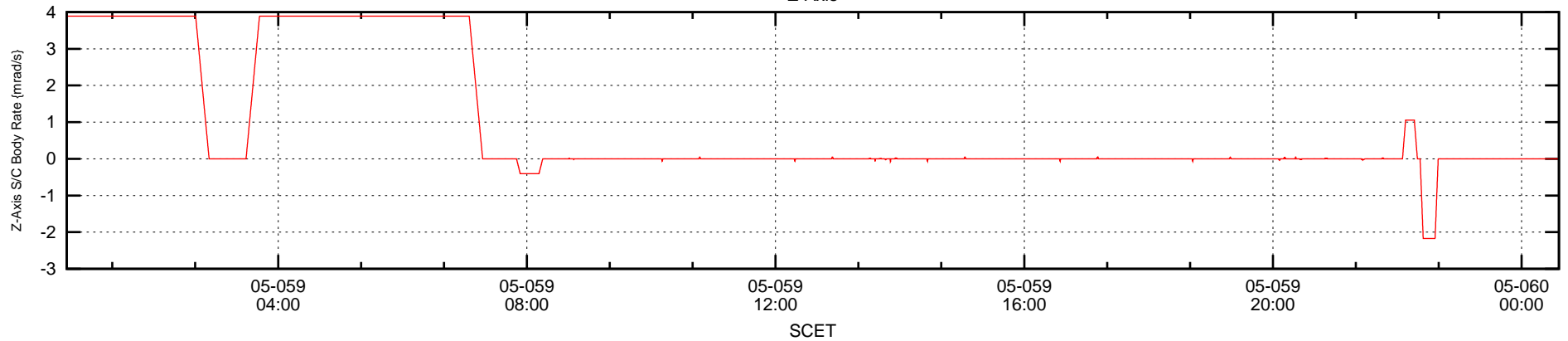
X-Axis (CK #2 = 05058\_05099py\_as\_flowm.bc)



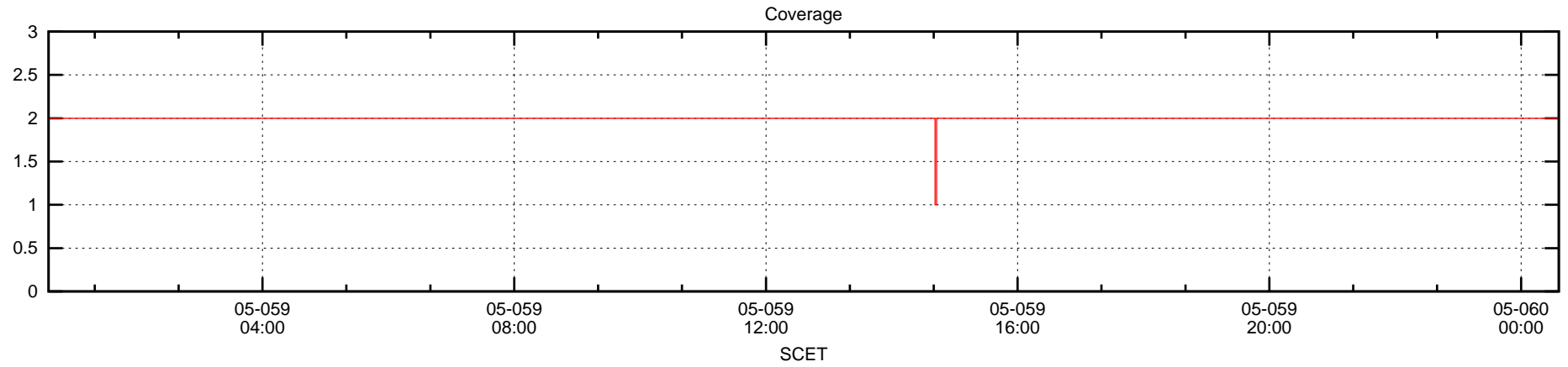
Y-Axis



Z-Axis

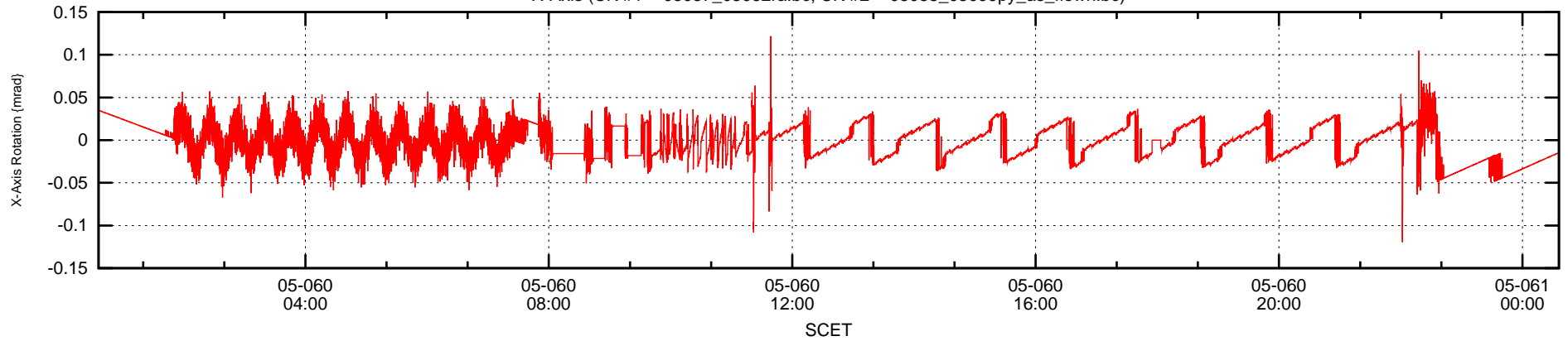


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 059-060)

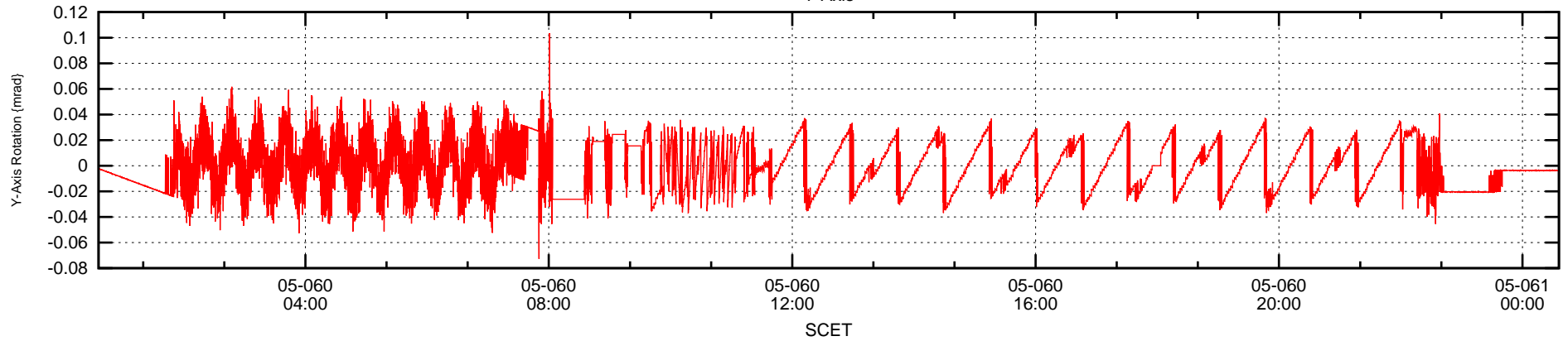


# Rotation From CK #2 to CK #1 (DOY 060-061)

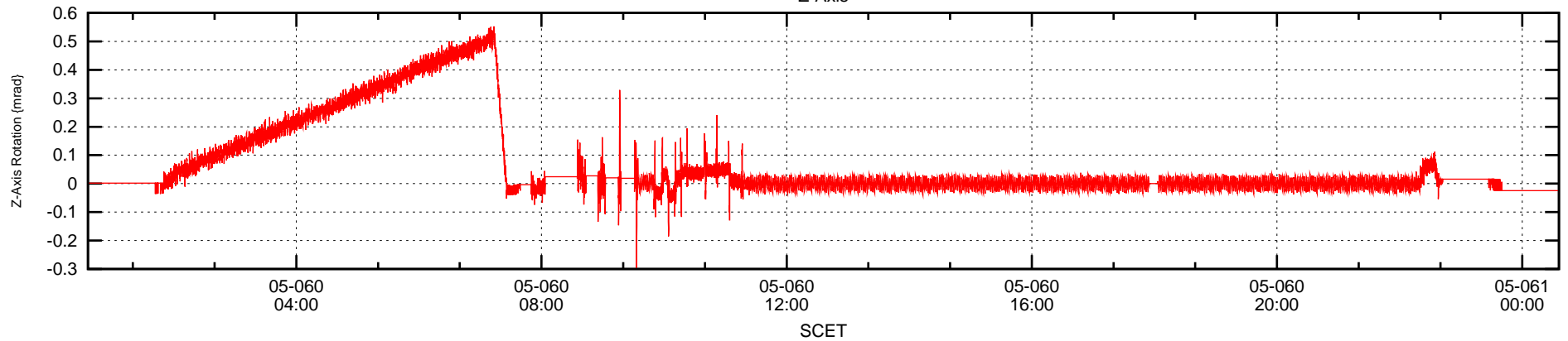
X-Axis (CK #1 = 05057\_05062ra.bc; CK #2 = 05058\_05099py\_as\_flowm.bc)



Y-Axis

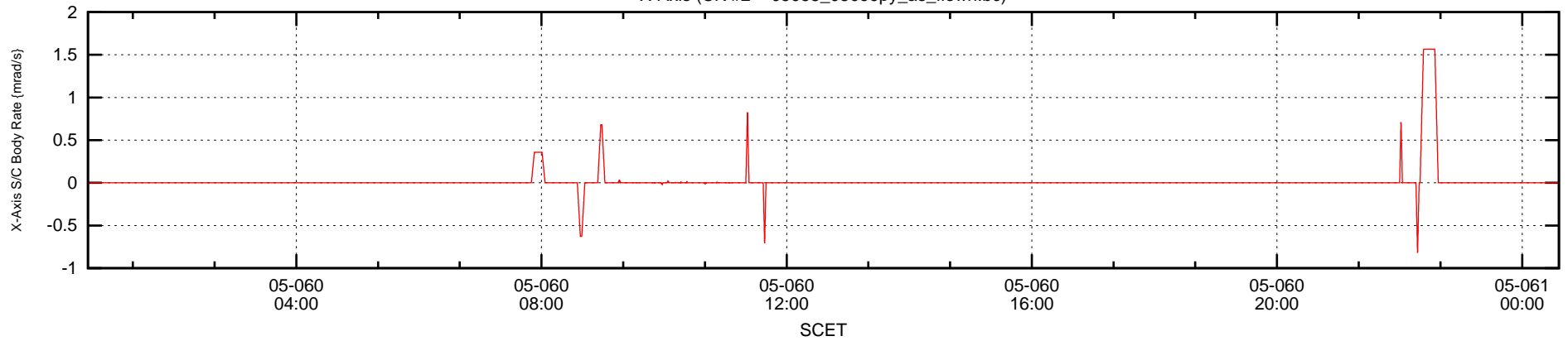


Z-Axis

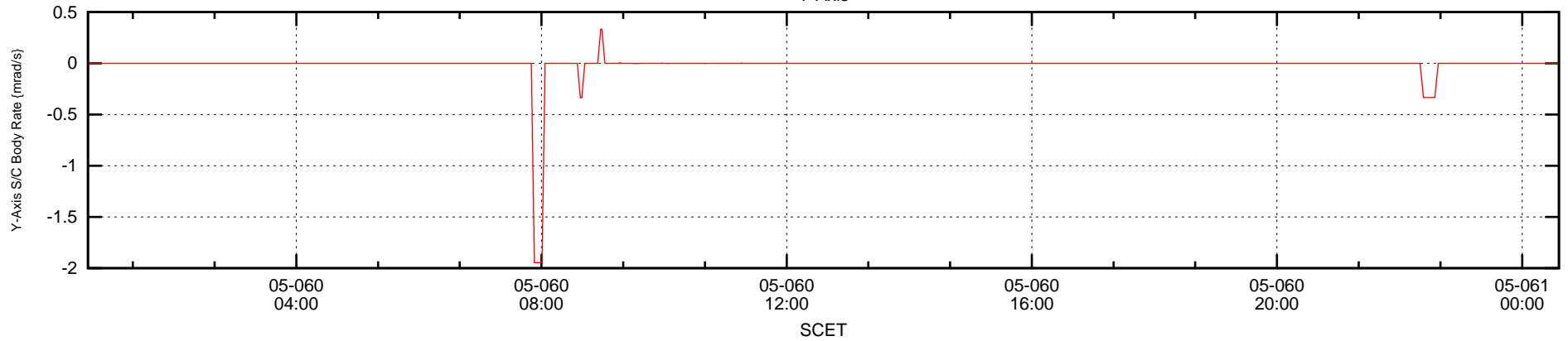


# CK #2 S/C Body Rates (DOY 060-061)

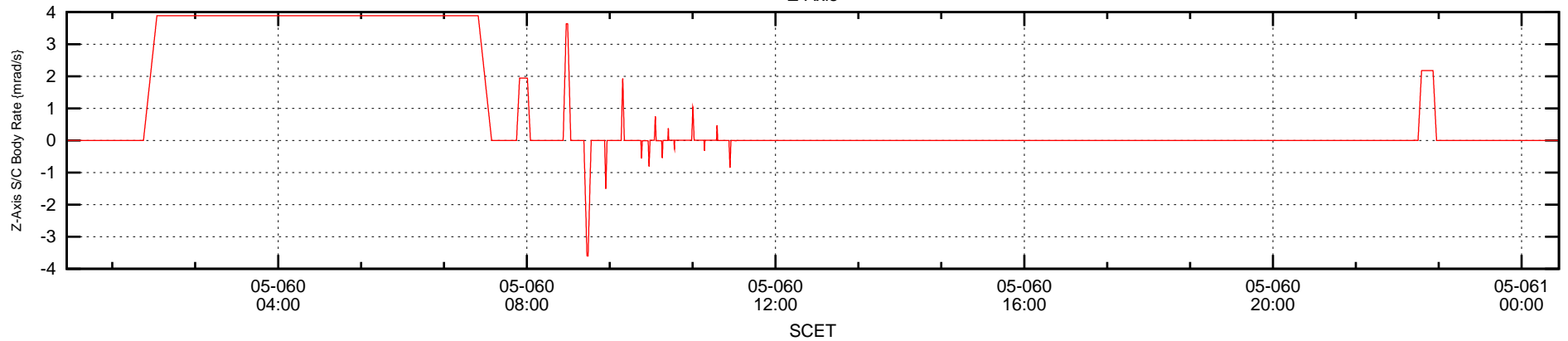
X-Axis (CK #2 = 05058\_05099py\_as\_flown.bc)



Y-Axis

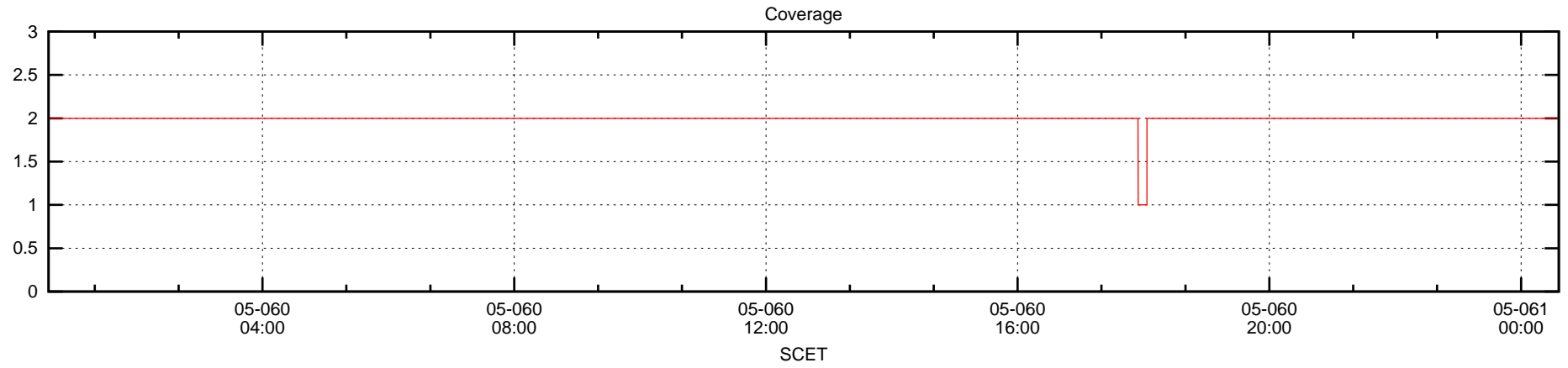


Z-Axis



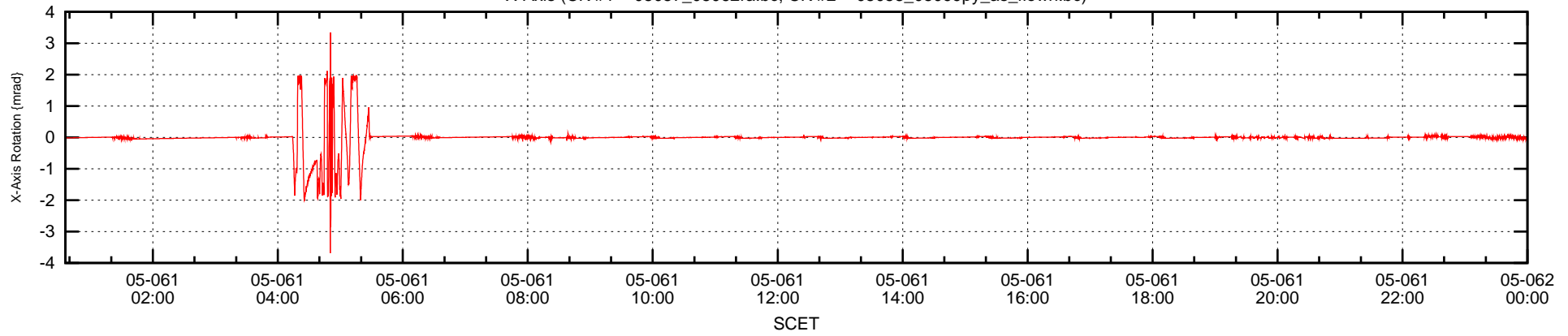


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 060-061)

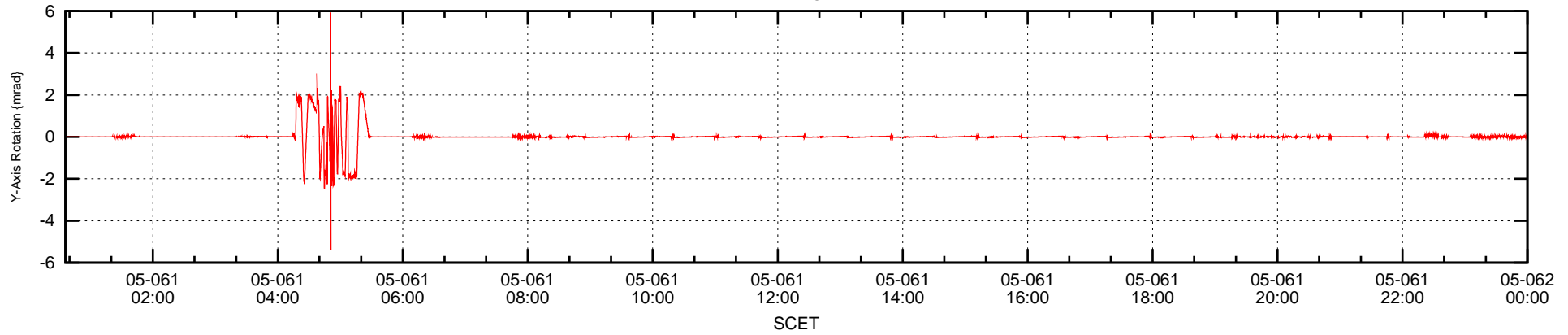


# Rotation From CK #2 to CK #1 (DOY 061-061)

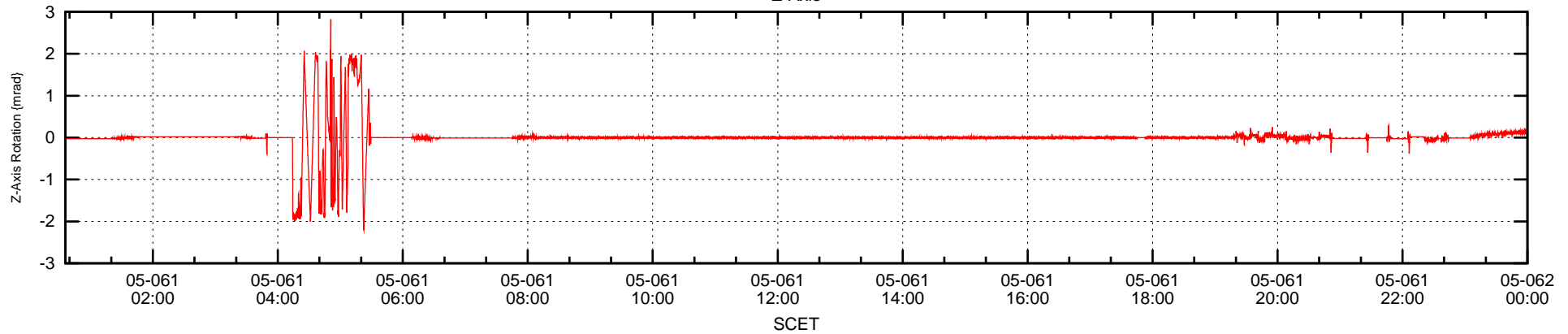
X-Axis (CK #1 = 05057\_05062ra.bc; CK #2 = 05058\_05099py\_as\_flown.bc)



Y-Axis

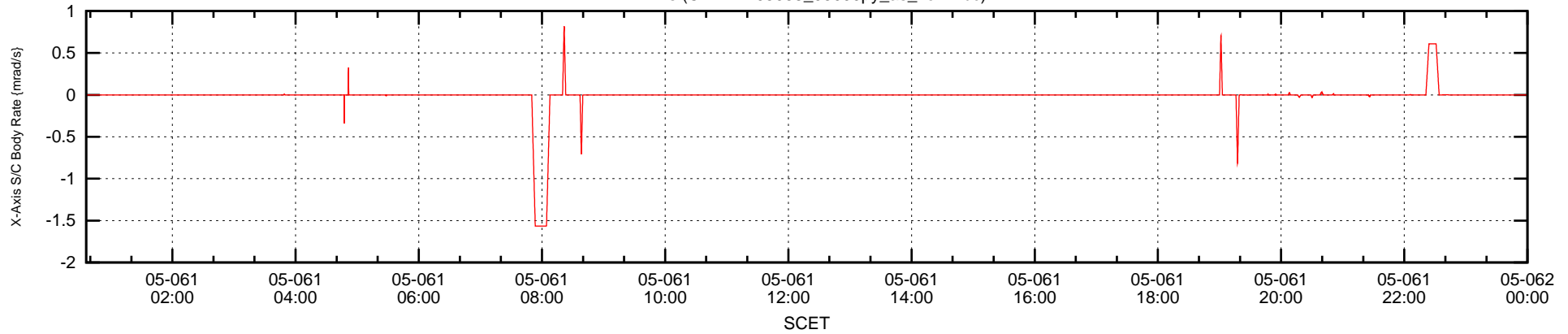


Z-Axis

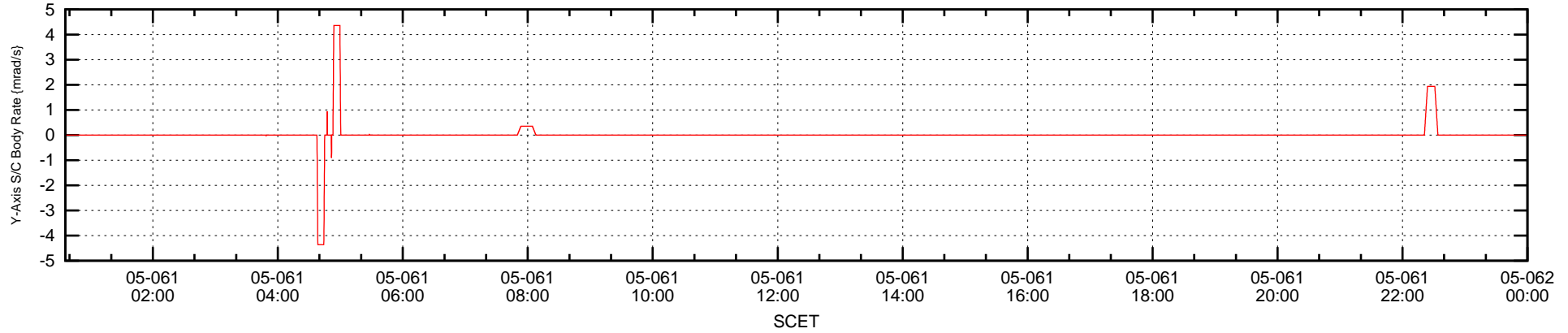


# CK #2 S/C Body Rates (DOY 061-061)

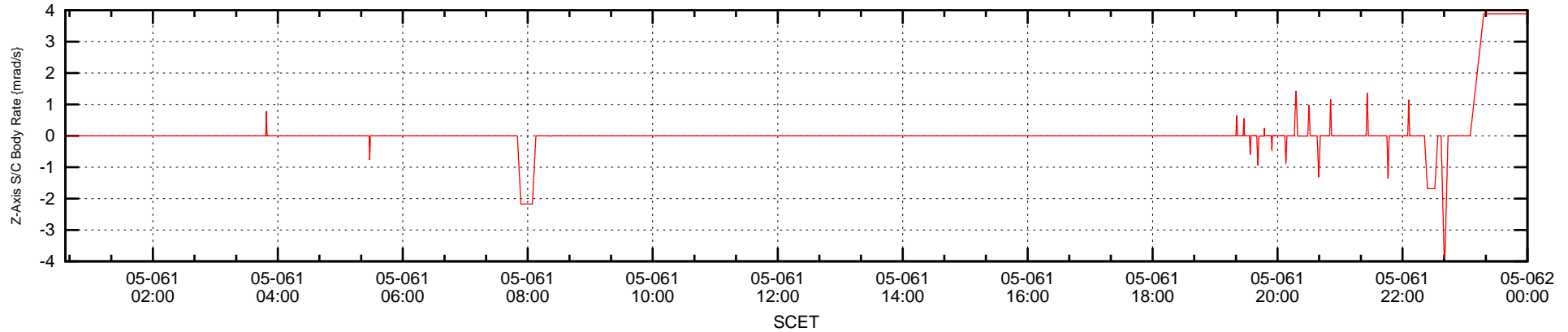
X-Axis (CK #2 = 05058\_05099py\_as\_flown.bc)



Y-Axis



Z-Axis



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 061-061)

