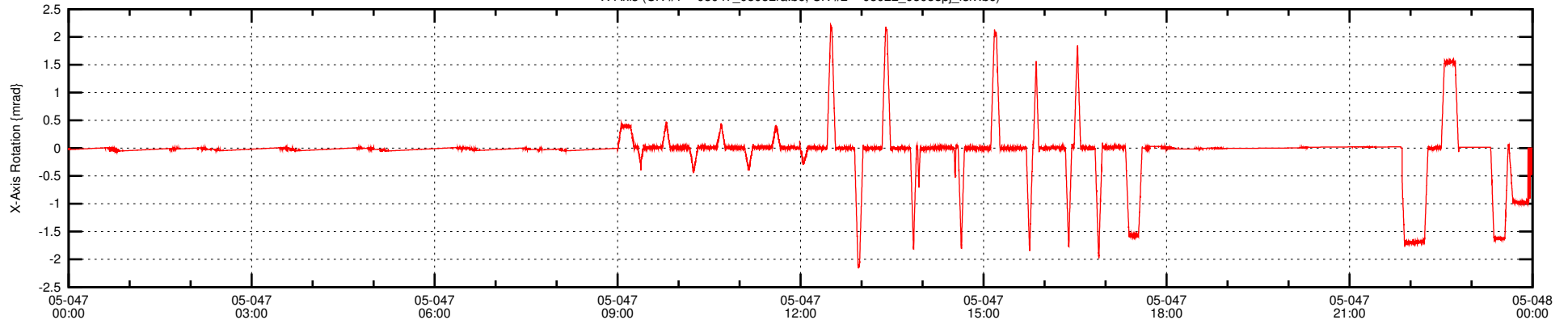
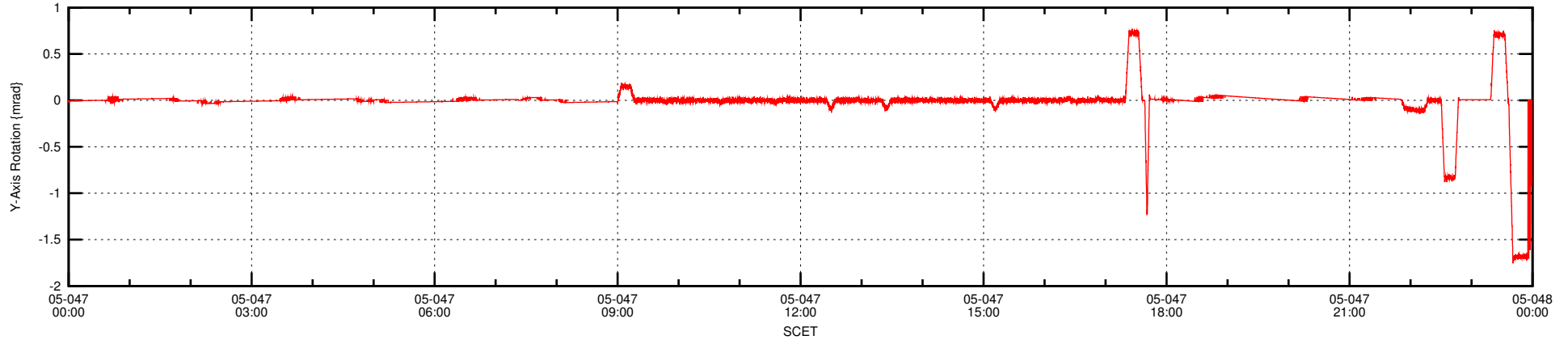


# Rotation From CK #2 to CK #1 (DOY 047-048)

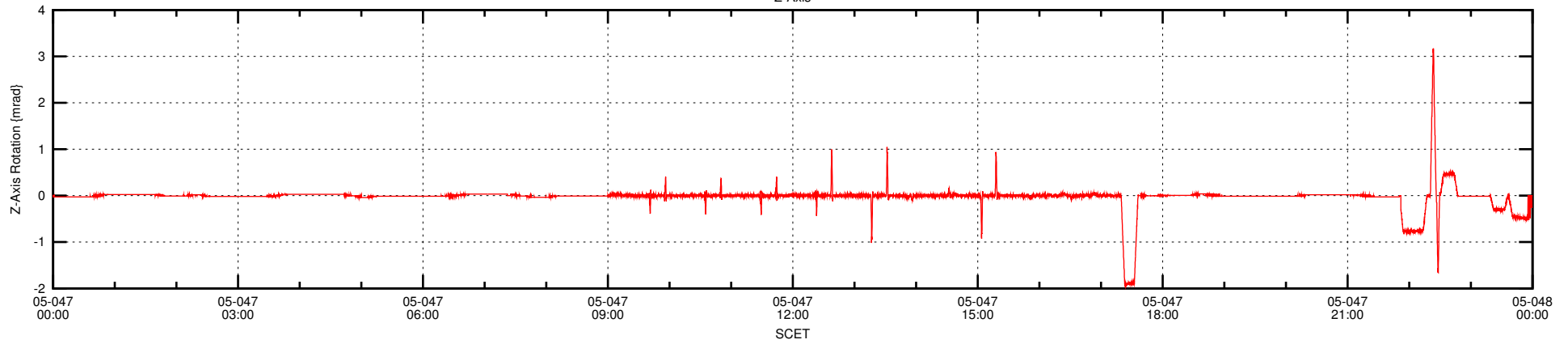
X-Axis (CK #1 = 05047\_05052ra.bc; CK #2 = 05022\_05058pj\_fsiv.bc)



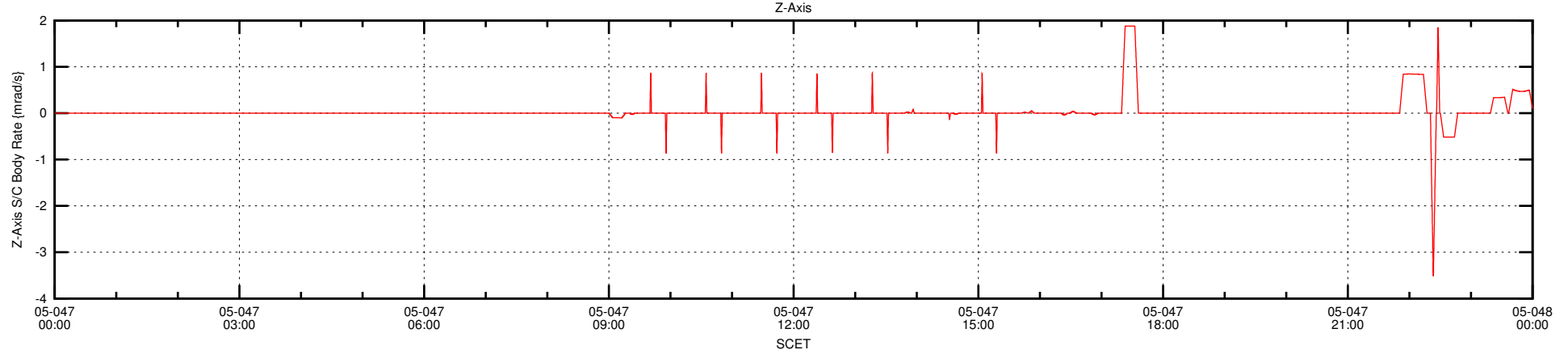
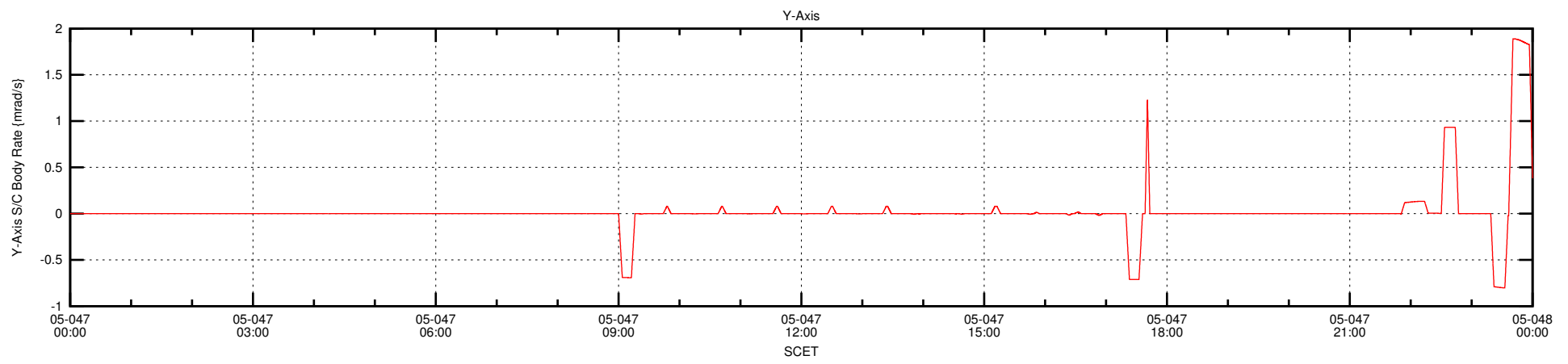
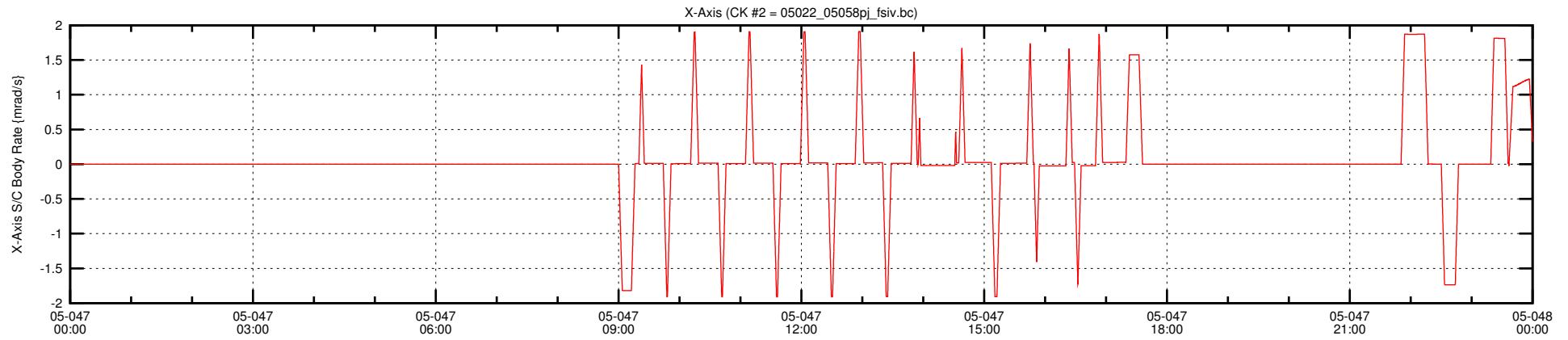
Y-Axis



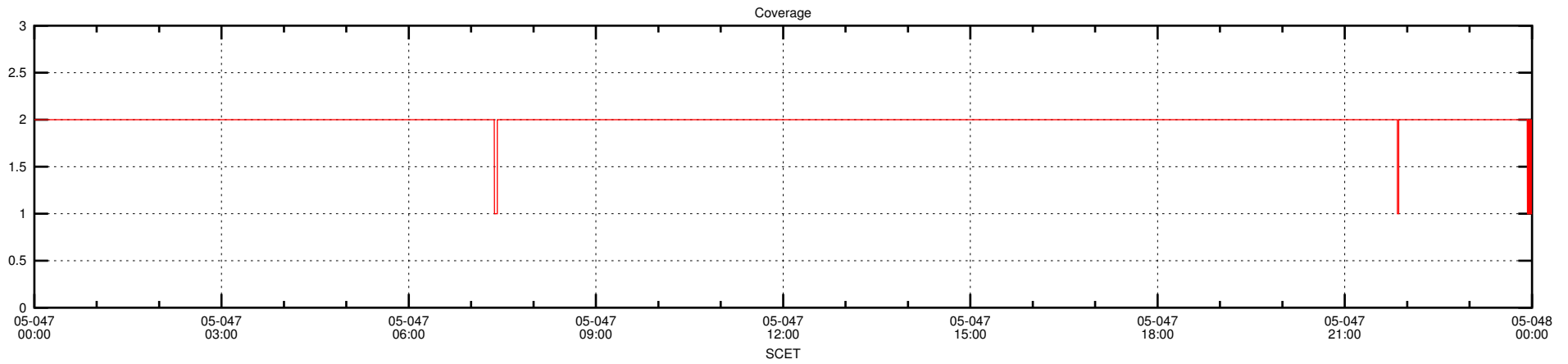
Z-Axis



# CK #2 S/C Body Rates (DOY 047-048)

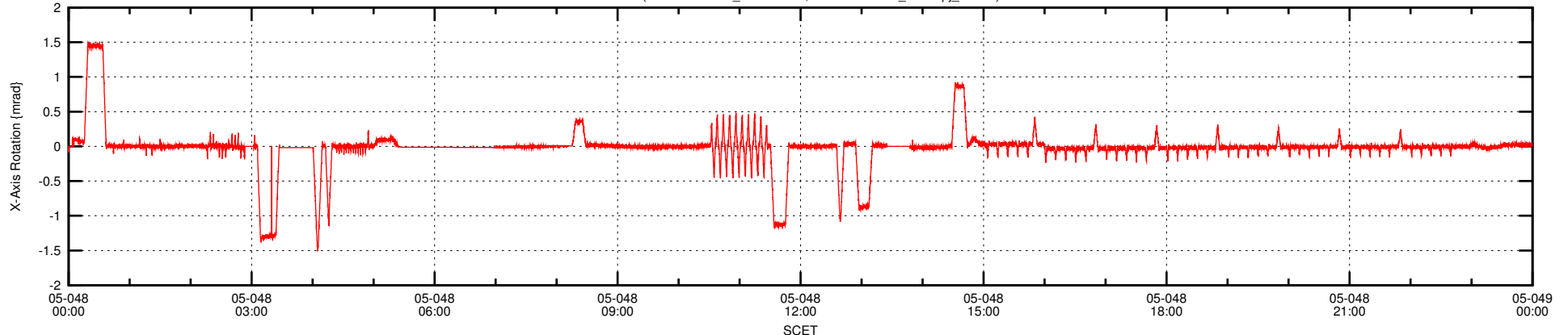


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 047-048)

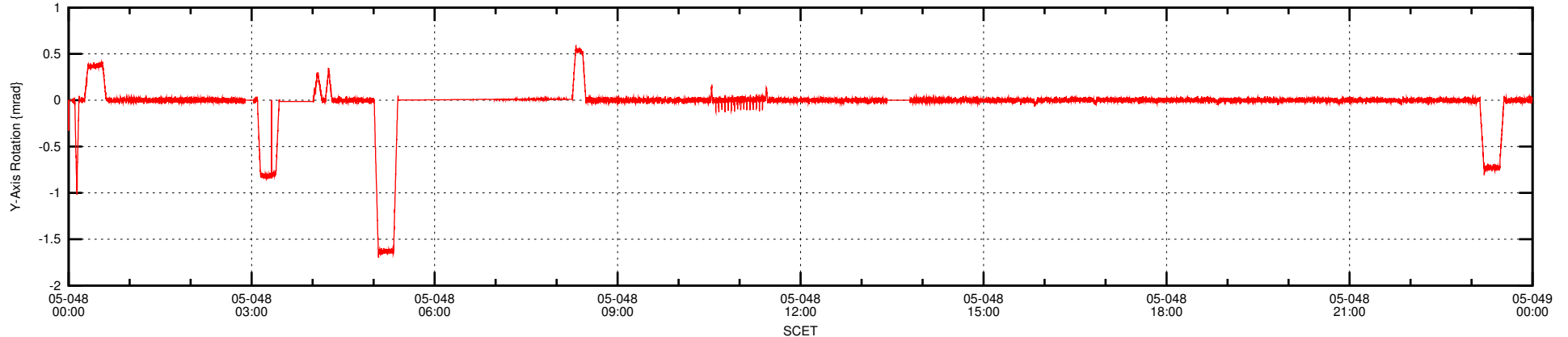


# Rotation From CK #2 to CK #1 (DOY 048-049)

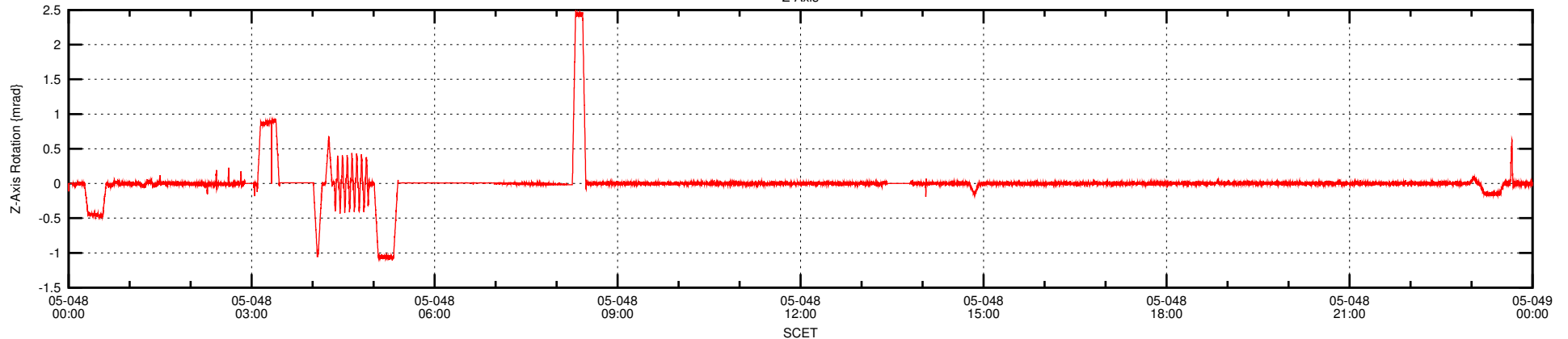
X-Axis (CK #1 = 05047\_05052ra.bc; CK #2 = 05022\_05058pj\_fsiv.bc)



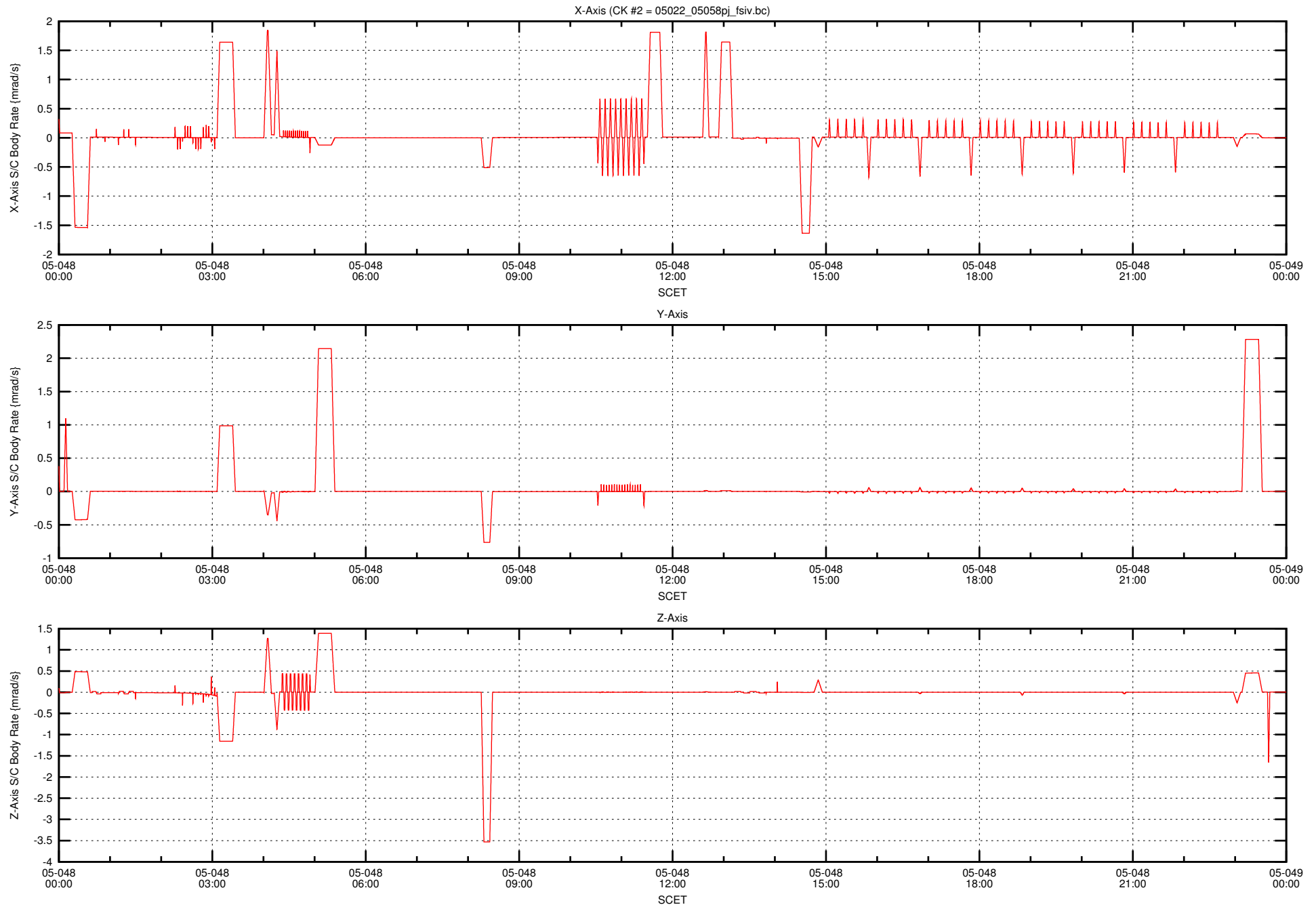
Y-Axis



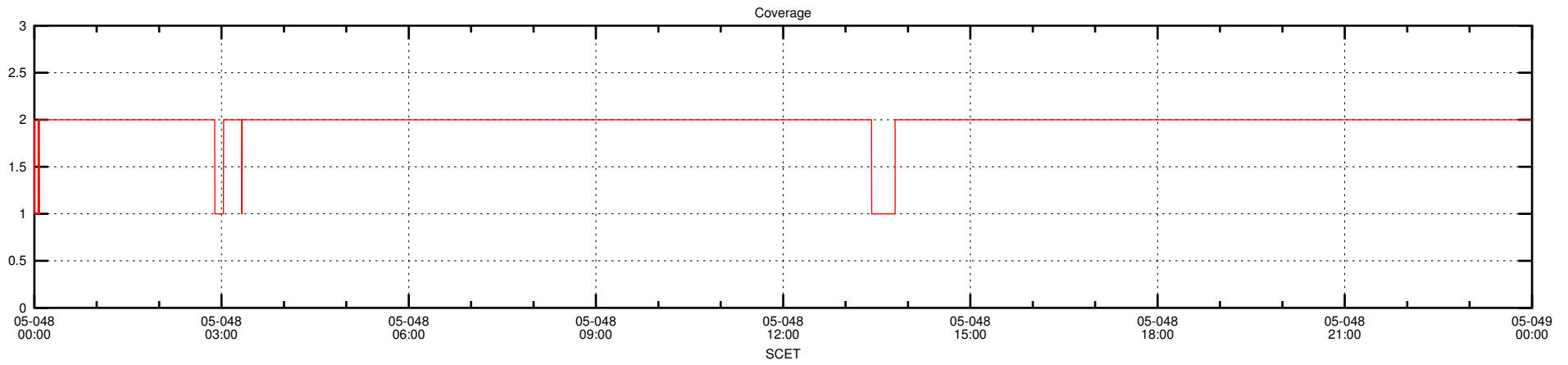
Z-Axis



# CK #2 S/C Body Rates (DOY 048-049)

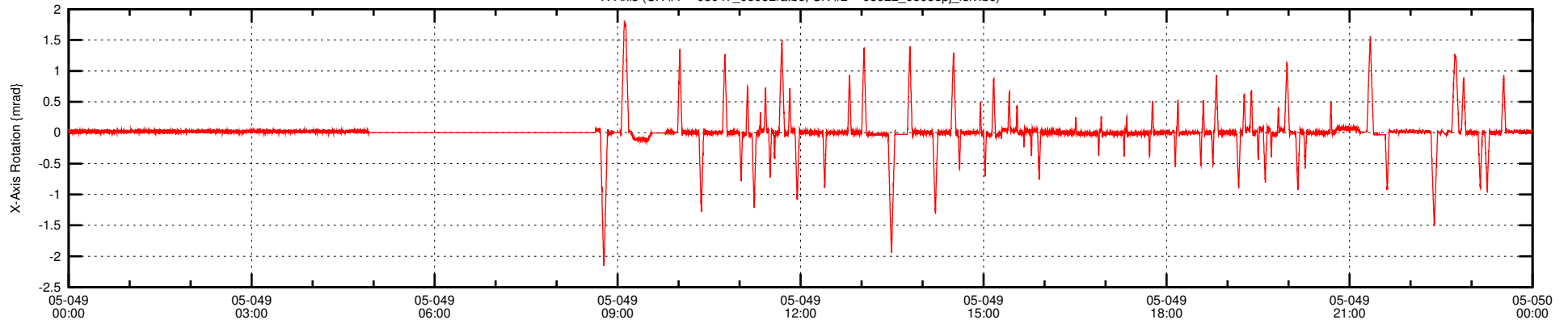


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 048-049)

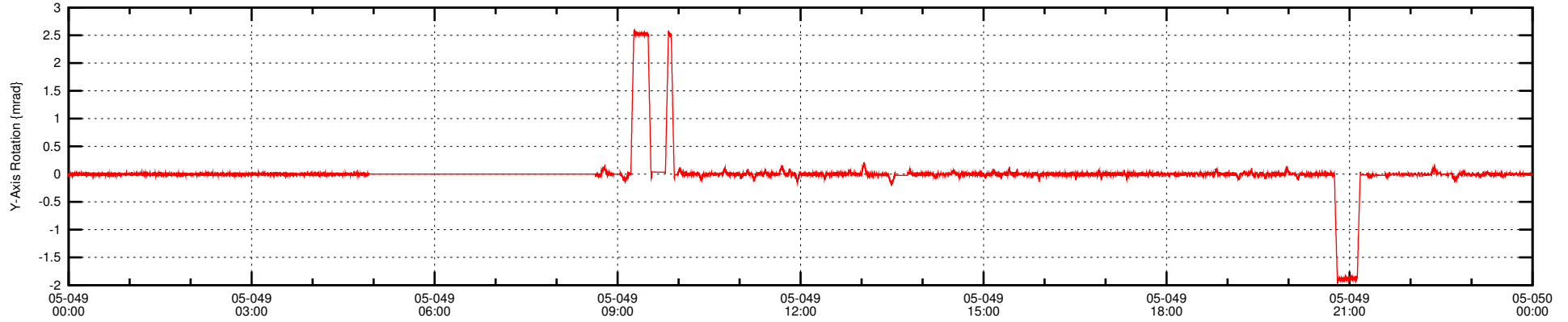


# Rotation From CK #2 to CK #1 (DOY 049-050)

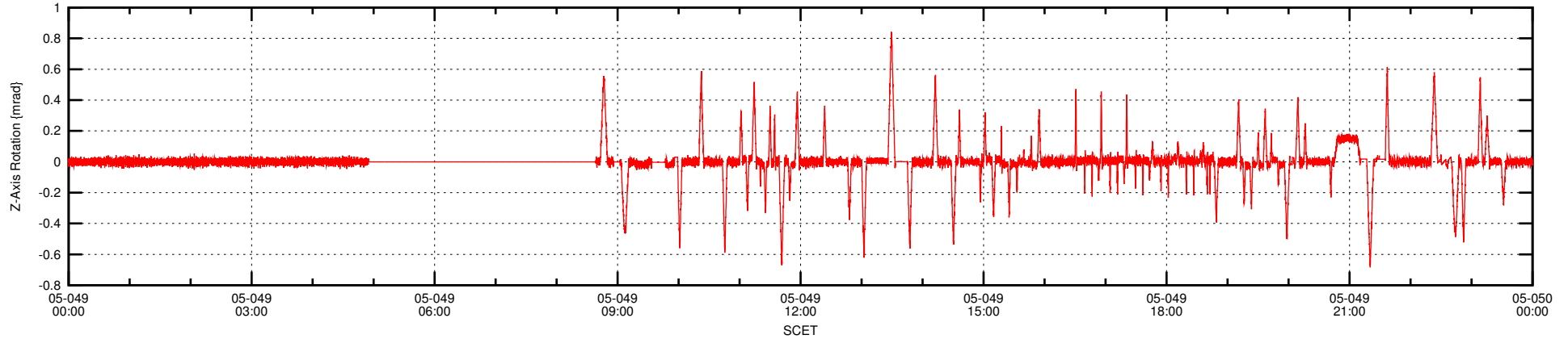
X-Axis (CK #1 = 05047\_05052ra.bc; CK #2 = 05022\_05058pj\_fsiv.bc)



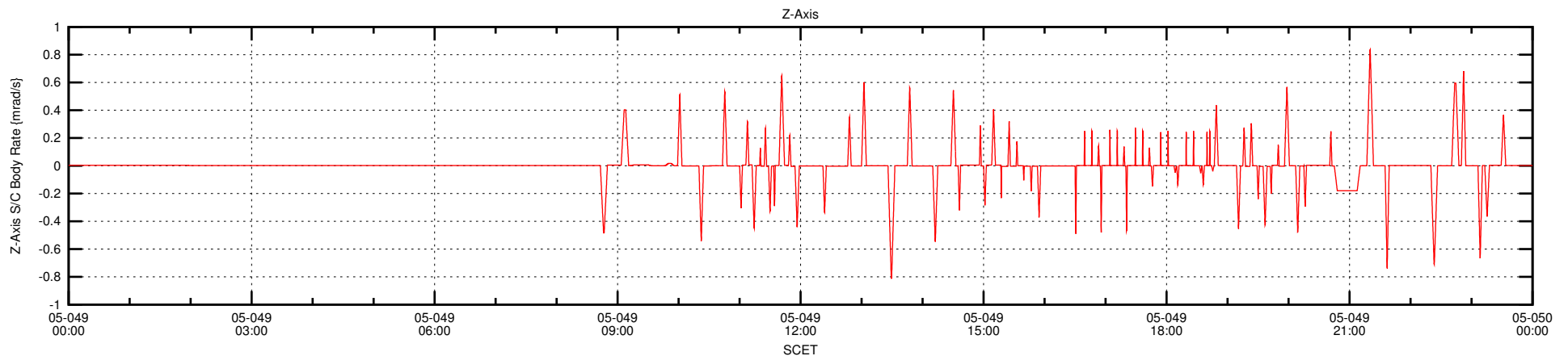
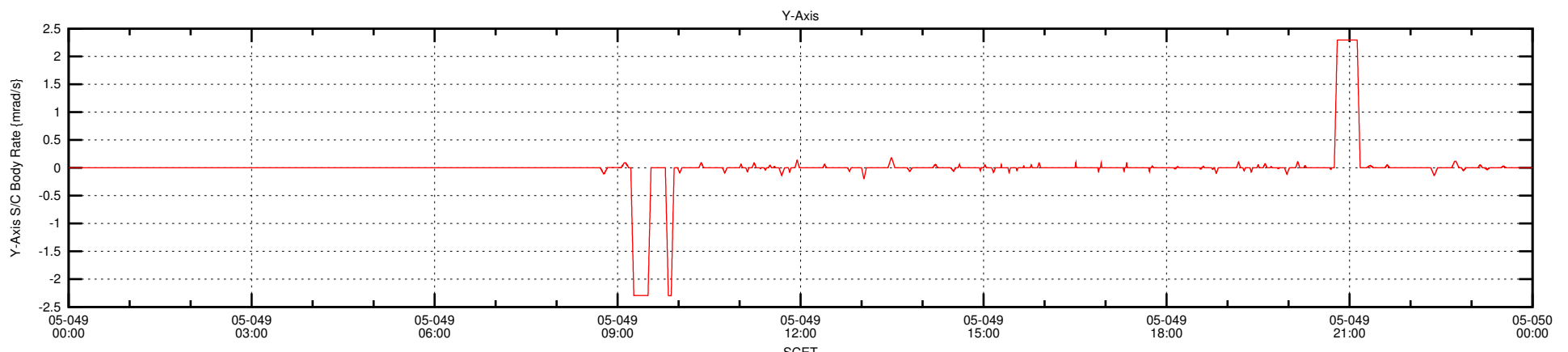
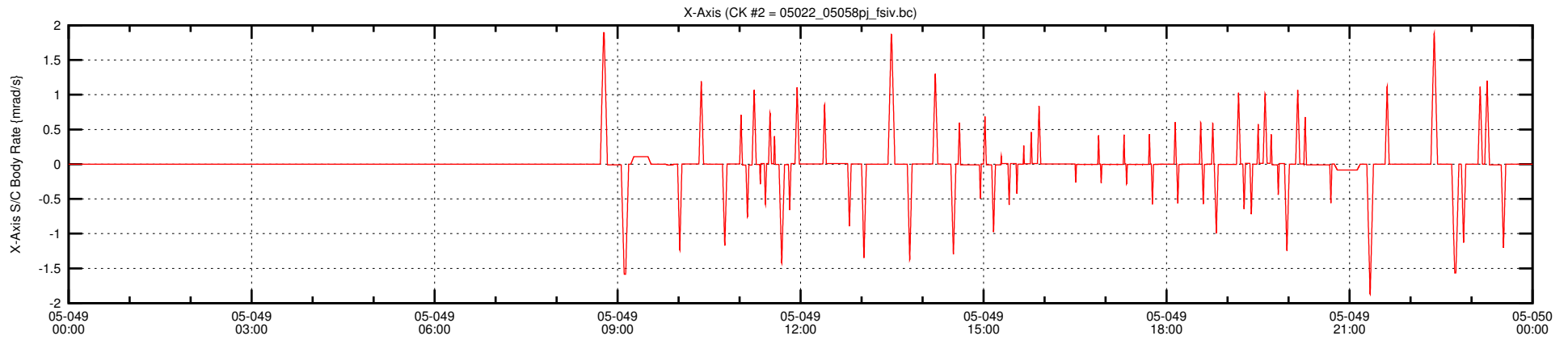
Y-Axis



Z-Axis

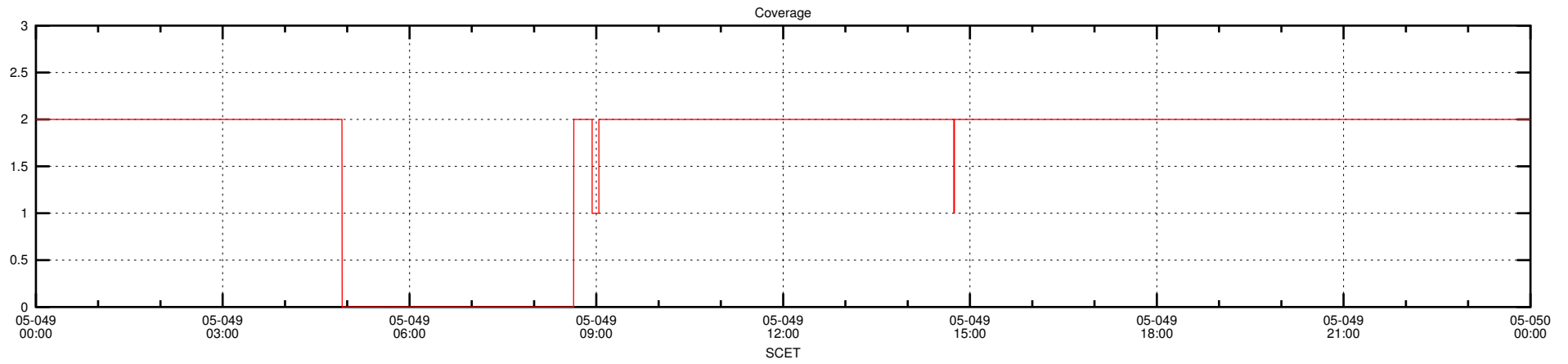


# CK #2 S/C Body Rates (DOY 049-050)



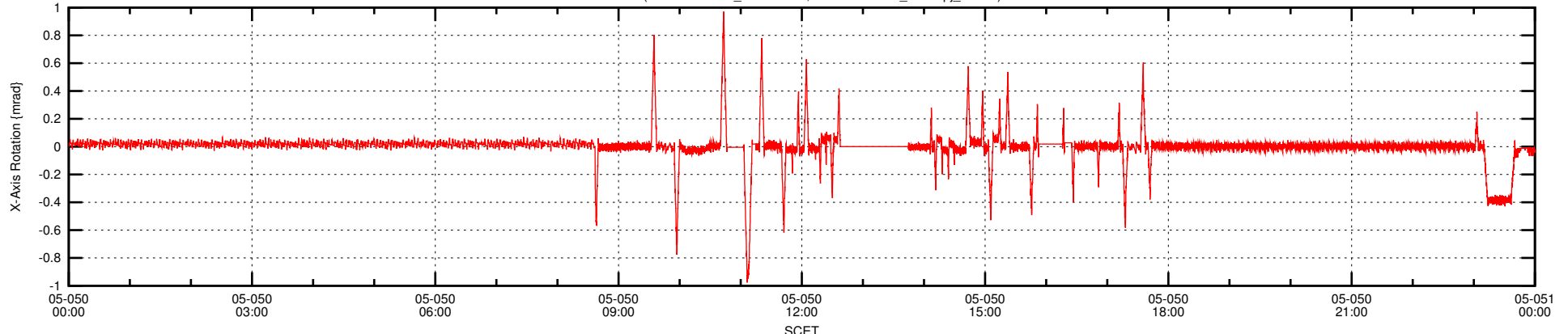


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 049-050)

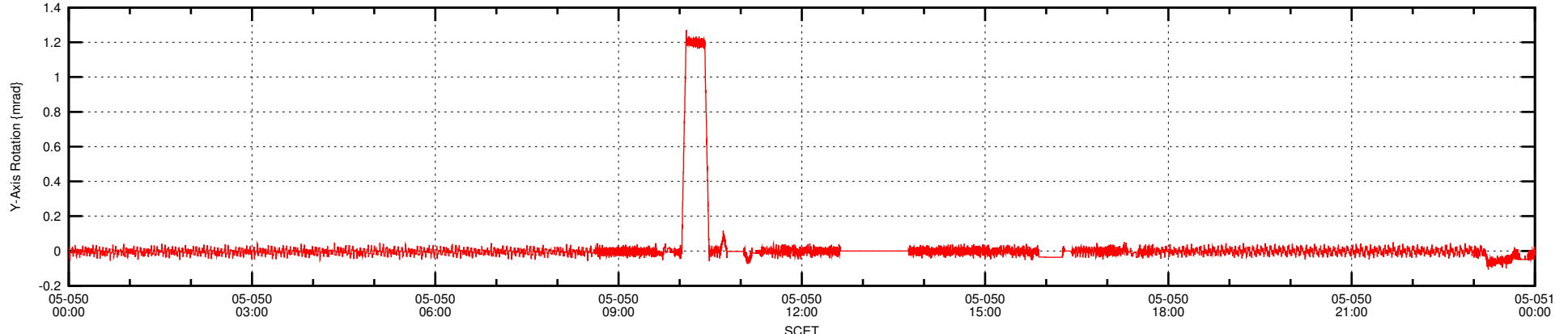


# Rotation From CK #2 to CK #1 (DOY 050-051)

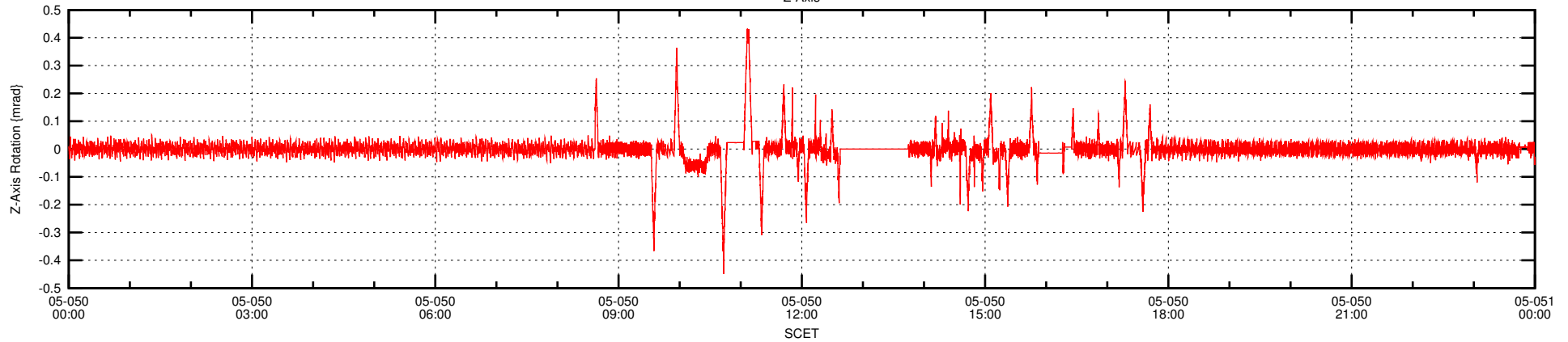
X-Axis (CK #1 = 05047\_05052ra.bc; CK #2 = 05022\_05058pj\_fsiv.bc)



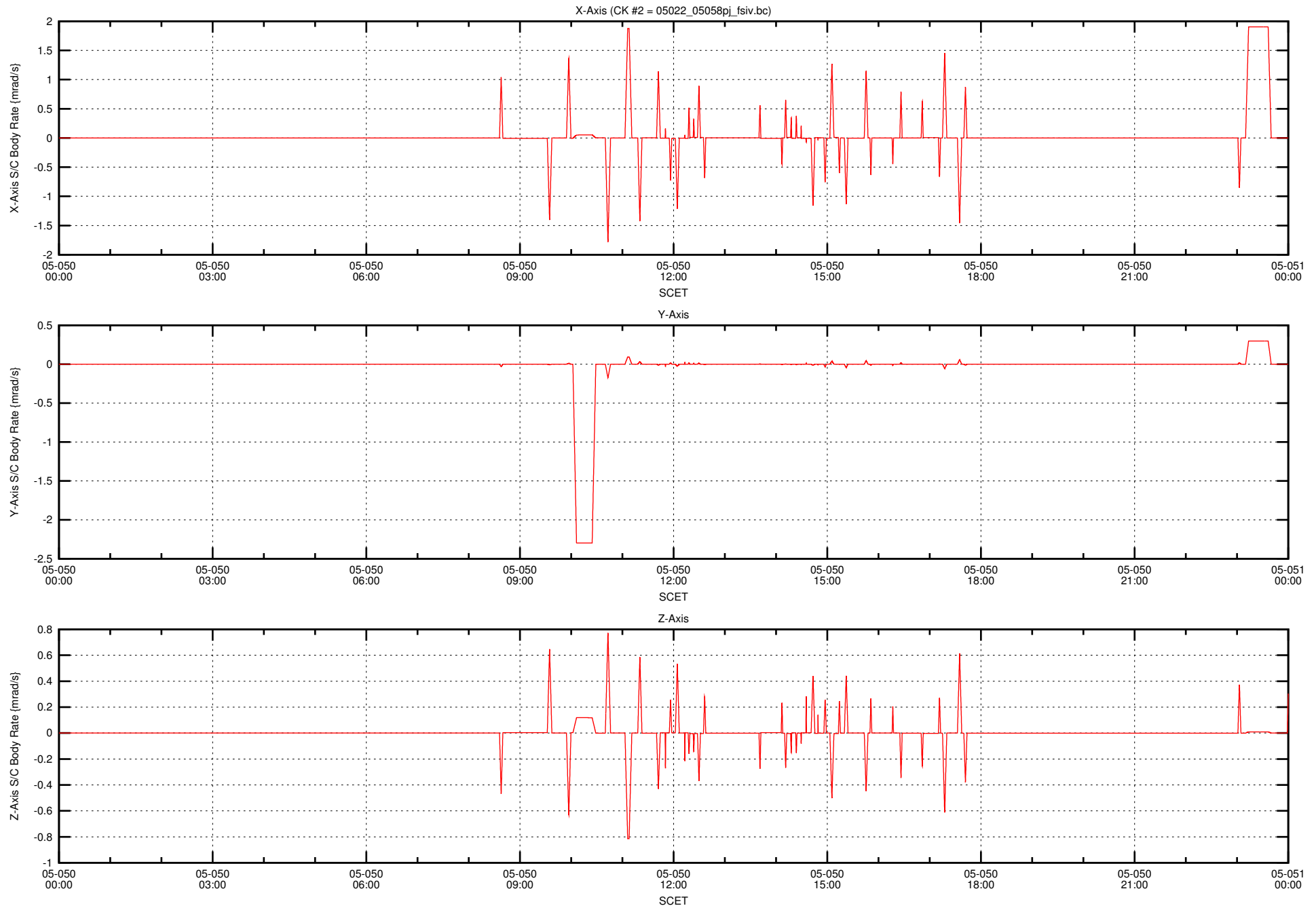
Y-Axis



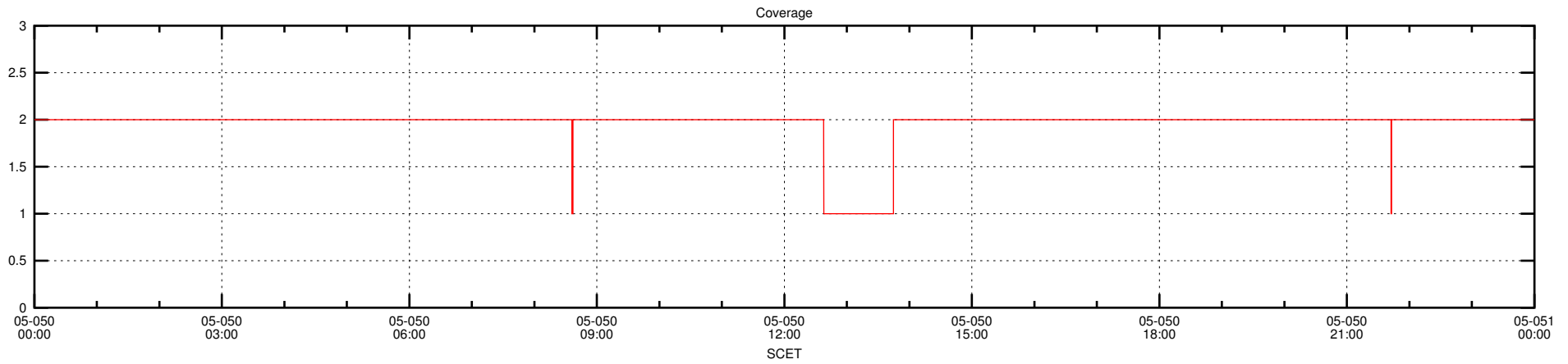
Z-Axis



# CK #2 S/C Body Rates (DOY 050-051)

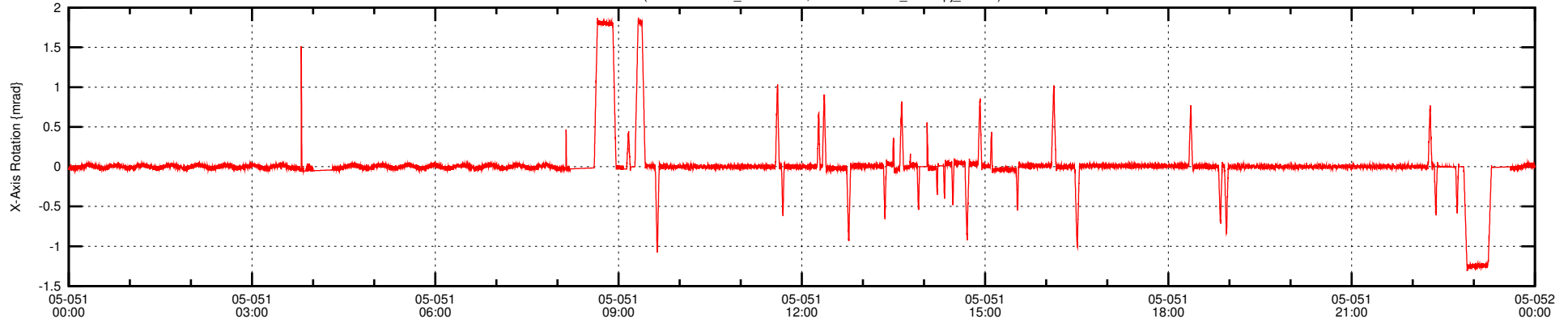


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 050-051)

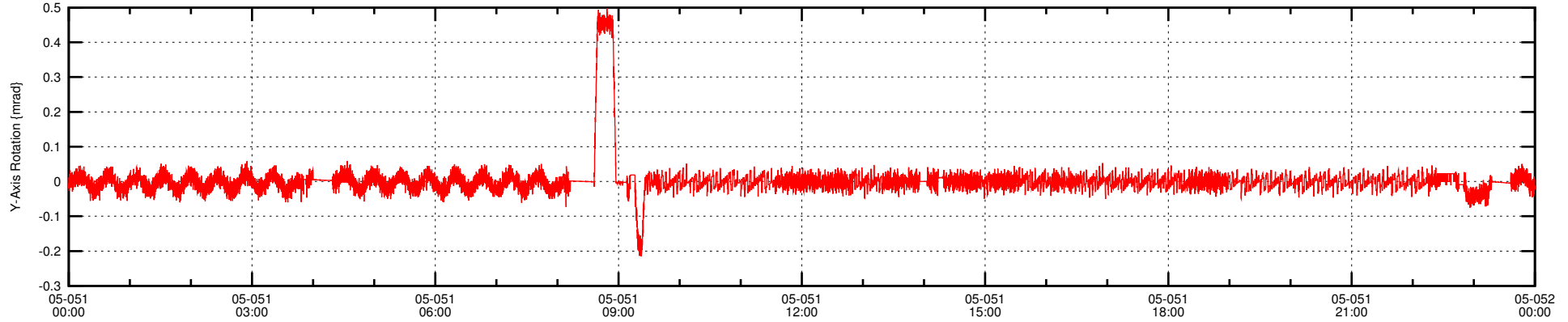


# Rotation From CK #2 to CK #1 (DOY 051-051)

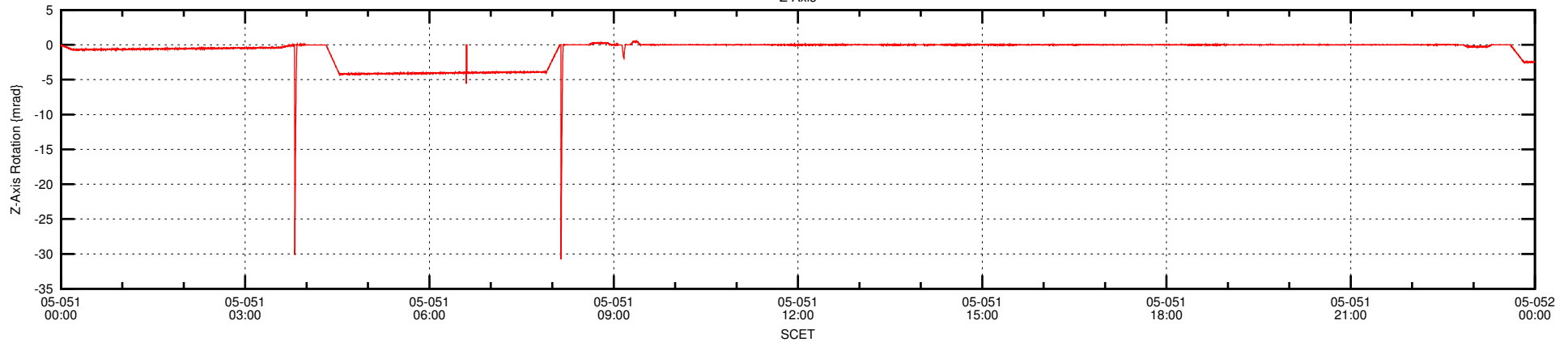
X-Axis (CK #1 = 05047\_05052ra.bc; CK #2 = 05022\_05058pj\_fsiv.bc)



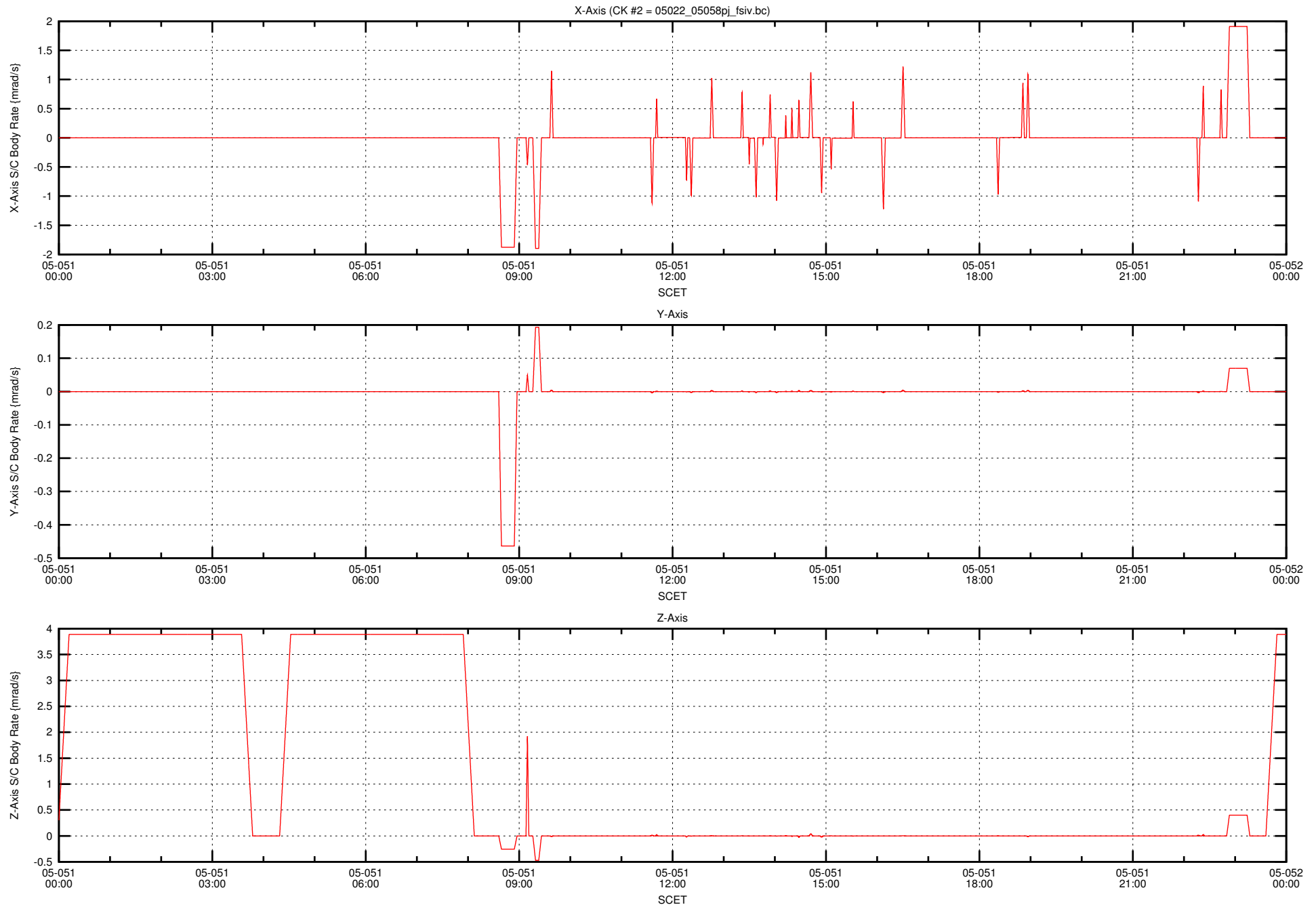
Y-Axis



Z-Axis



# CK #2 S/C Body Rates (DOY 051-051)



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 051-051)

