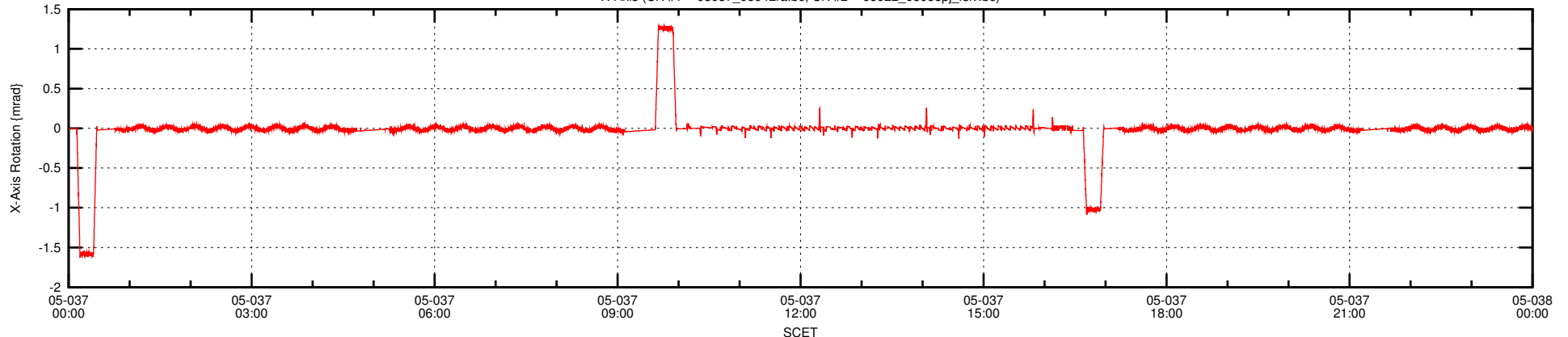
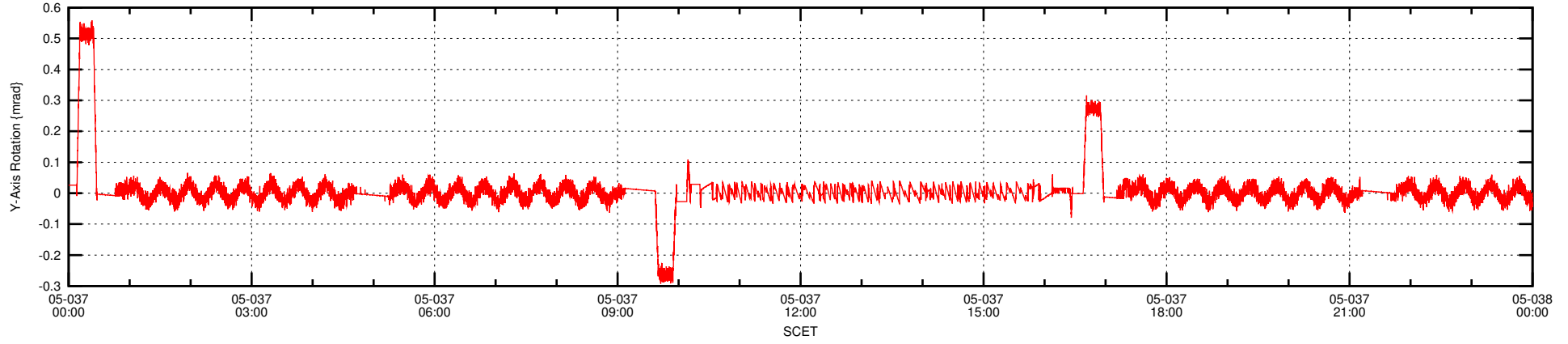


# Rotation From CK #2 to CK #1 (DOY 037-038)

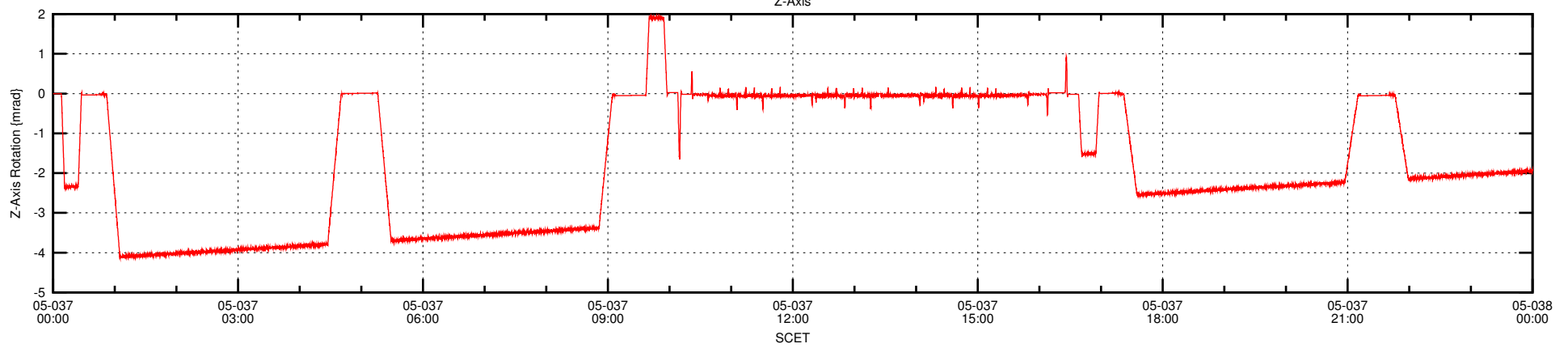
X-Axis (CK #1 = 05037\_05042ra.bc; CK #2 = 05022\_05058pj\_fsiv.bc)



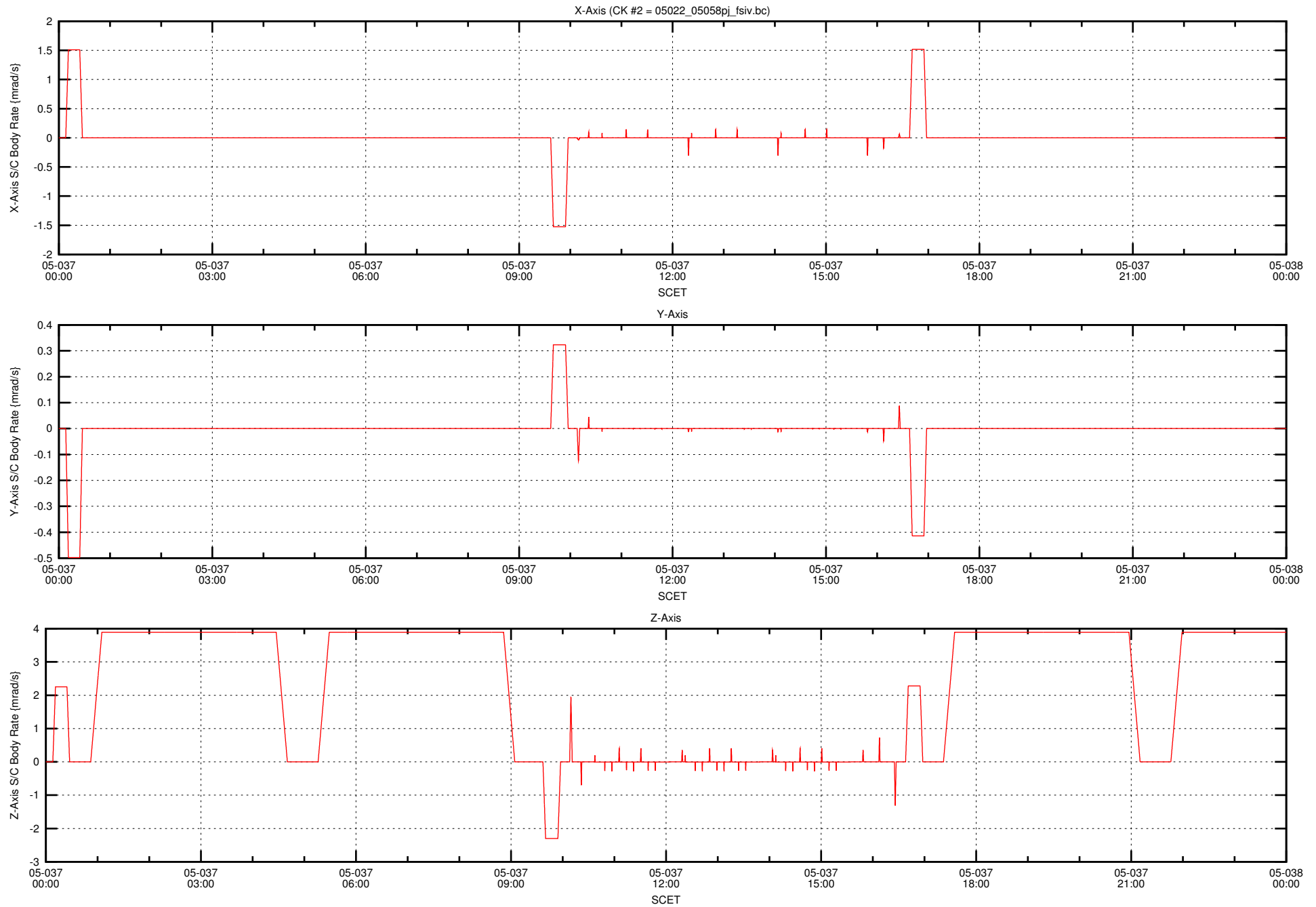
Y-Axis



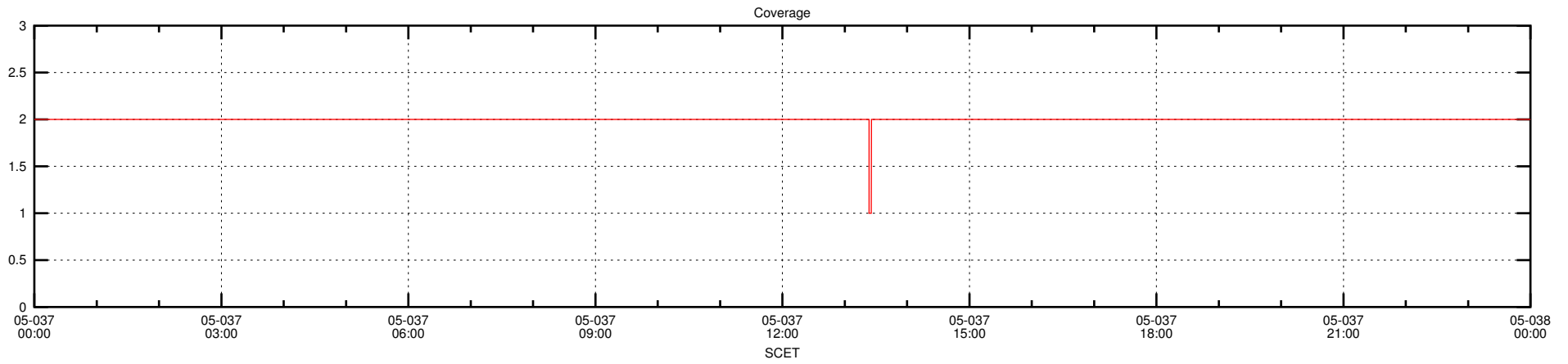
Z-Axis



# CK #2 S/C Body Rates (DOY 037-038)

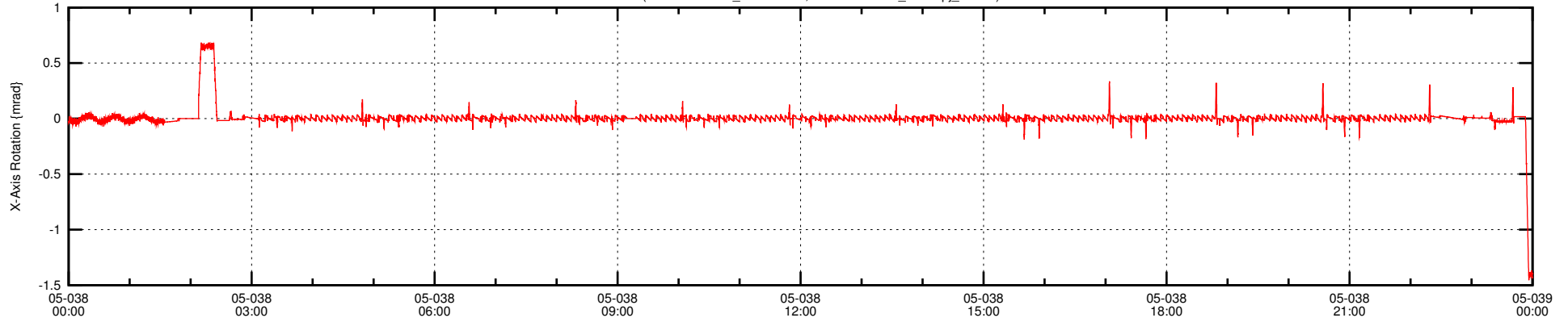


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 037-038)

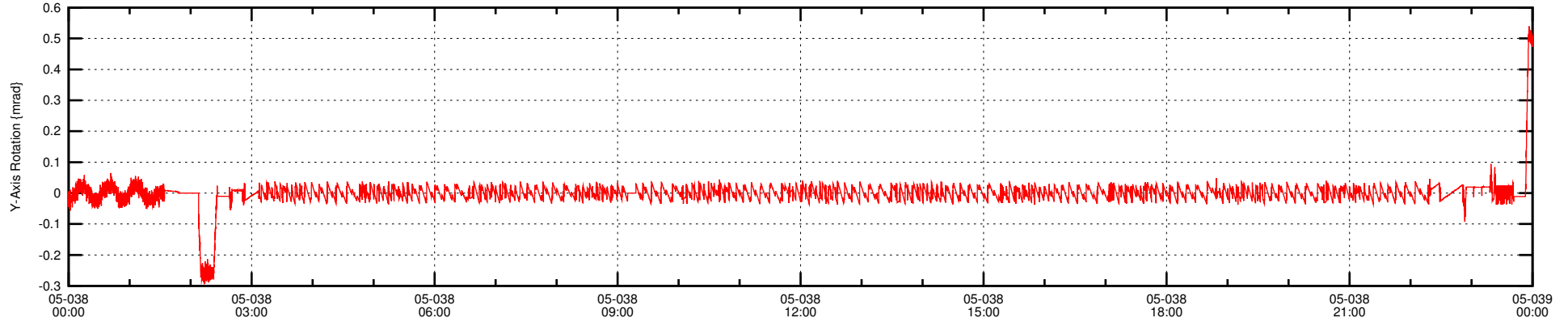


# Rotation From CK #2 to CK #1 (DOY 038-039)

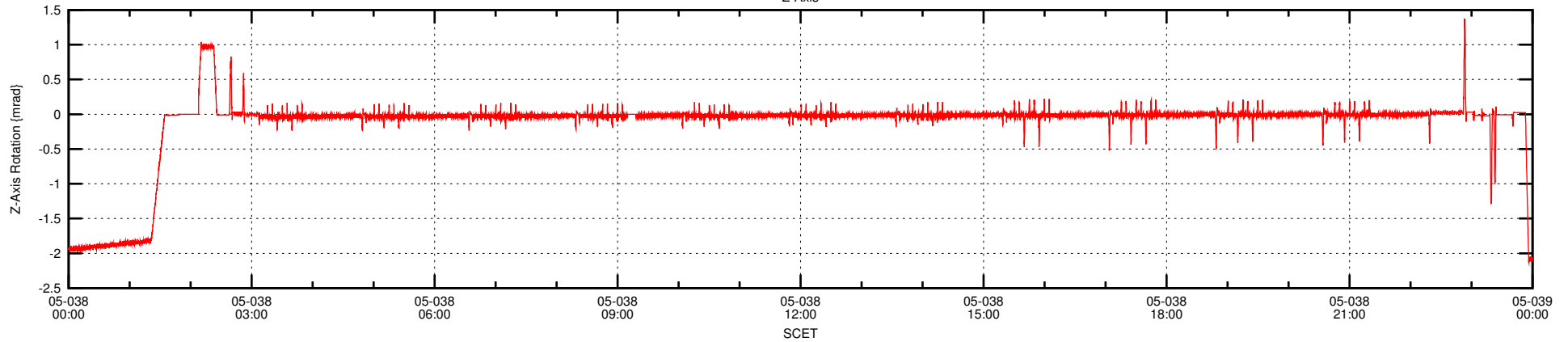
X-Axis (CK #1 = 05037\_05042ra.bc; CK #2 = 05022\_05058pj\_fsiv.bc)



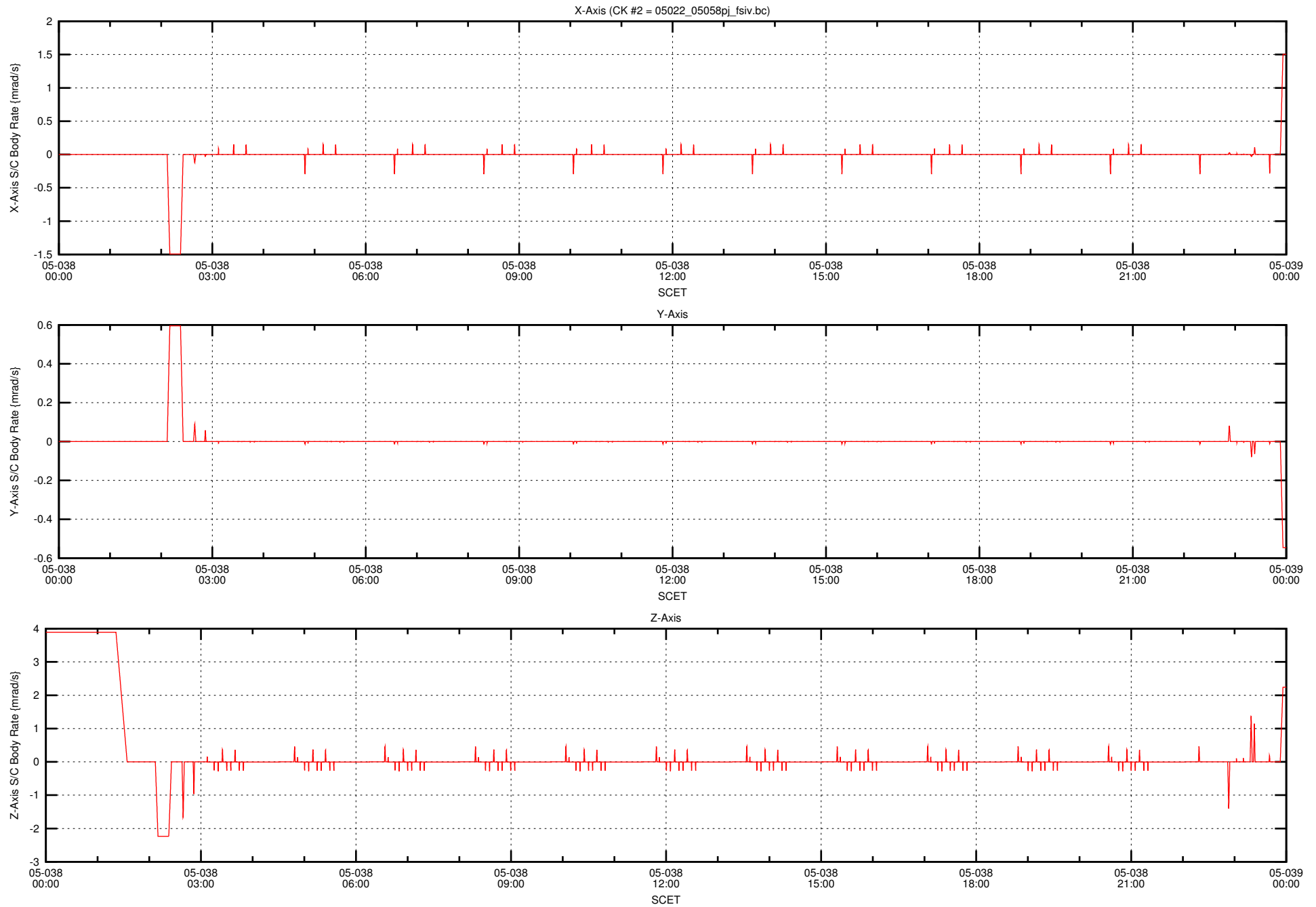
Y-Axis



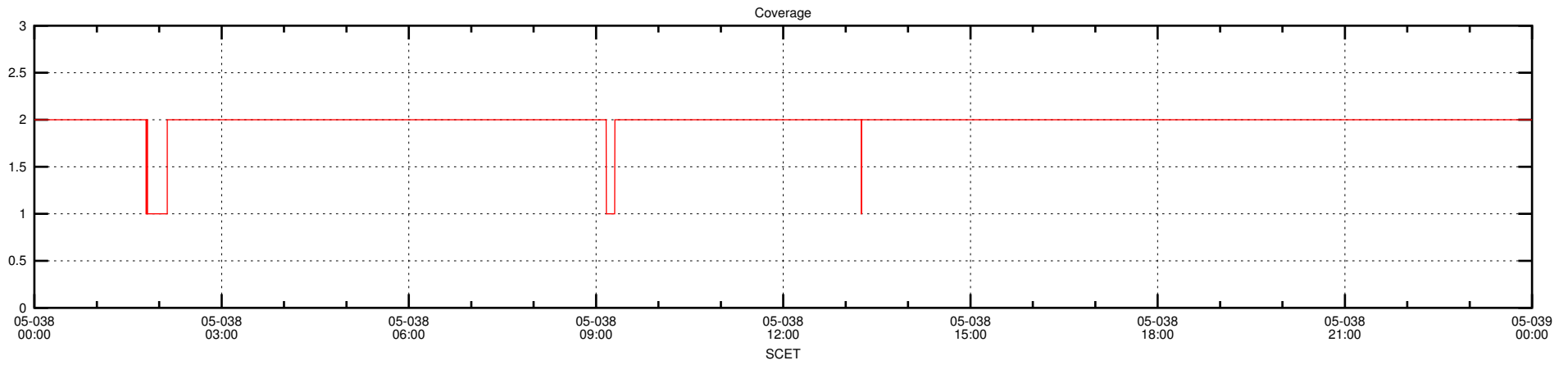
Z-Axis



# CK #2 S/C Body Rates (DOY 038-039)

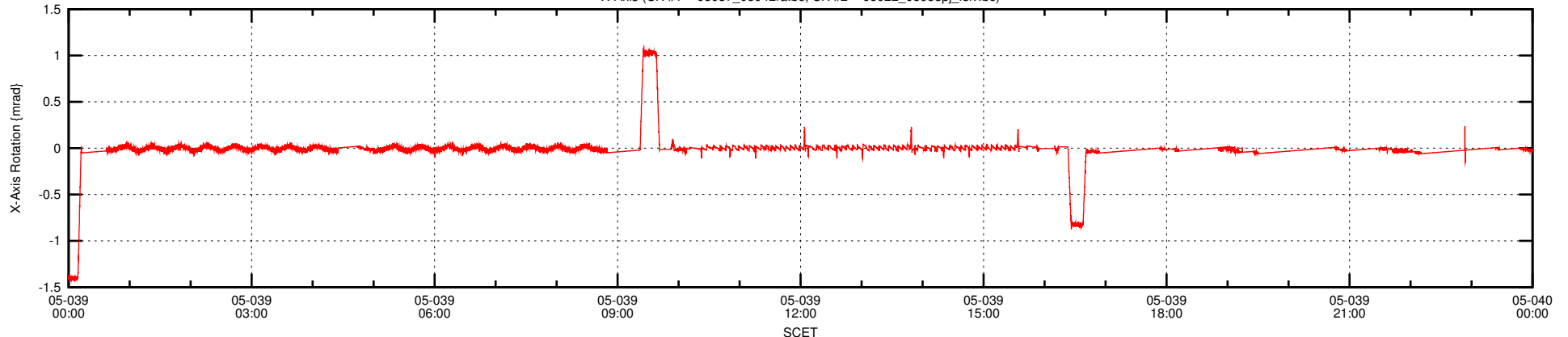


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 038-039)

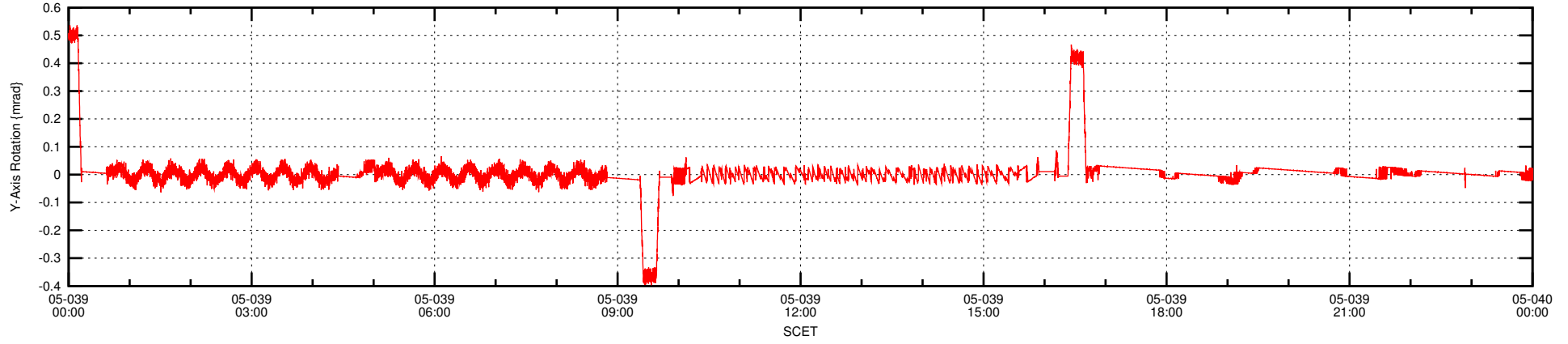


# Rotation From CK #2 to CK #1 (DOY 039-040)

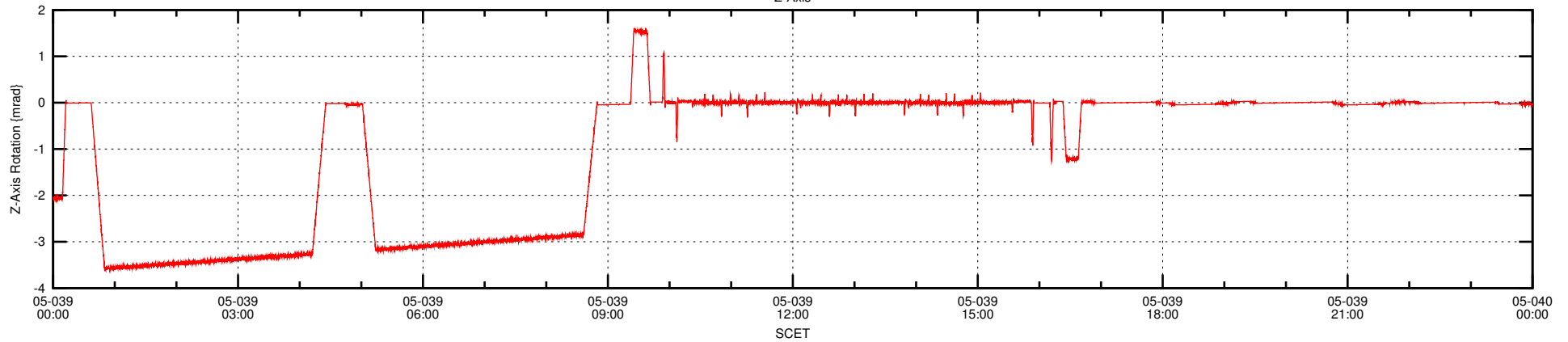
X-Axis (CK #1 = 05037\_05042ra.bc; CK #2 = 05022\_05058pj\_fsiv.bc)



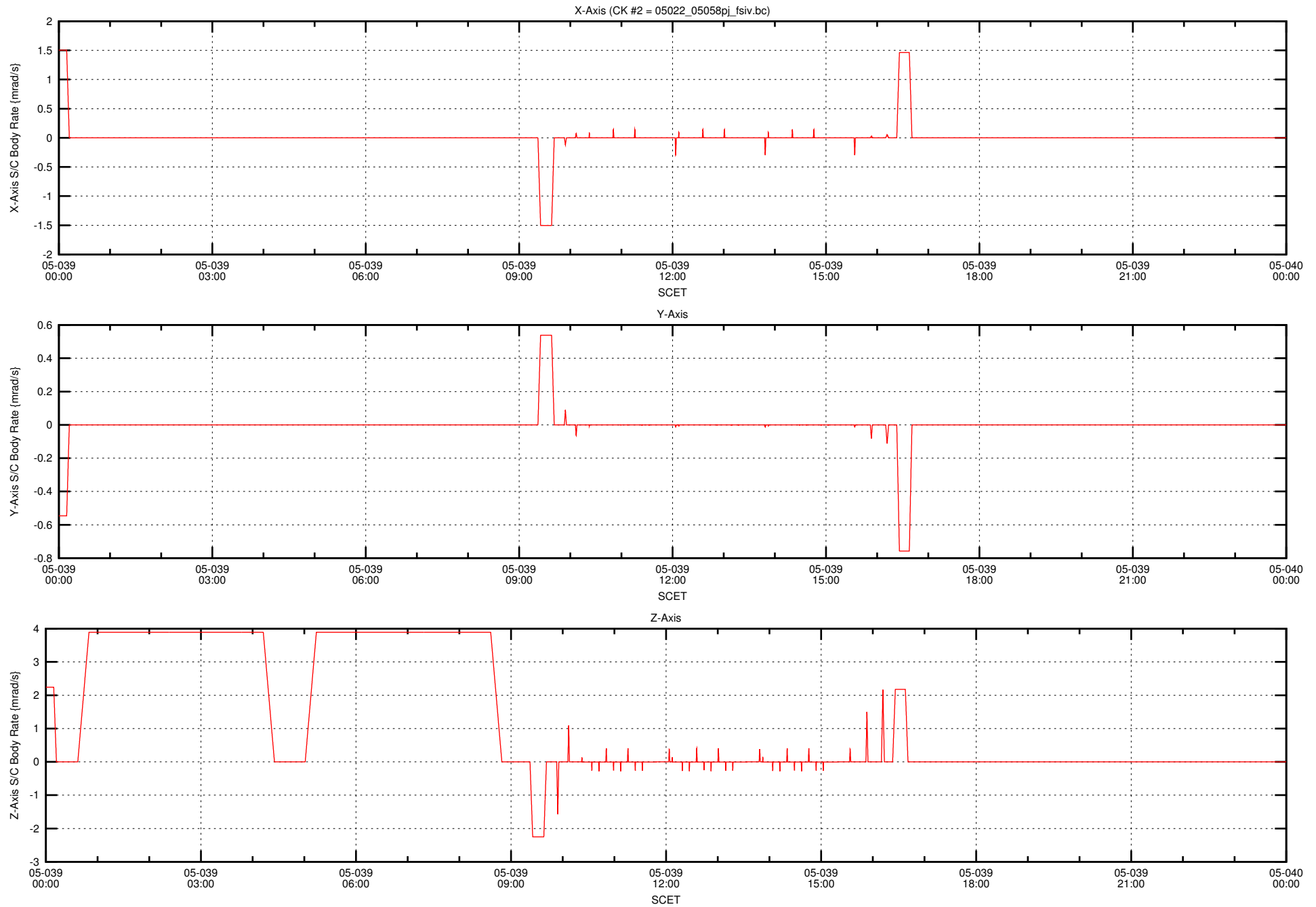
Y-Axis



Z-Axis

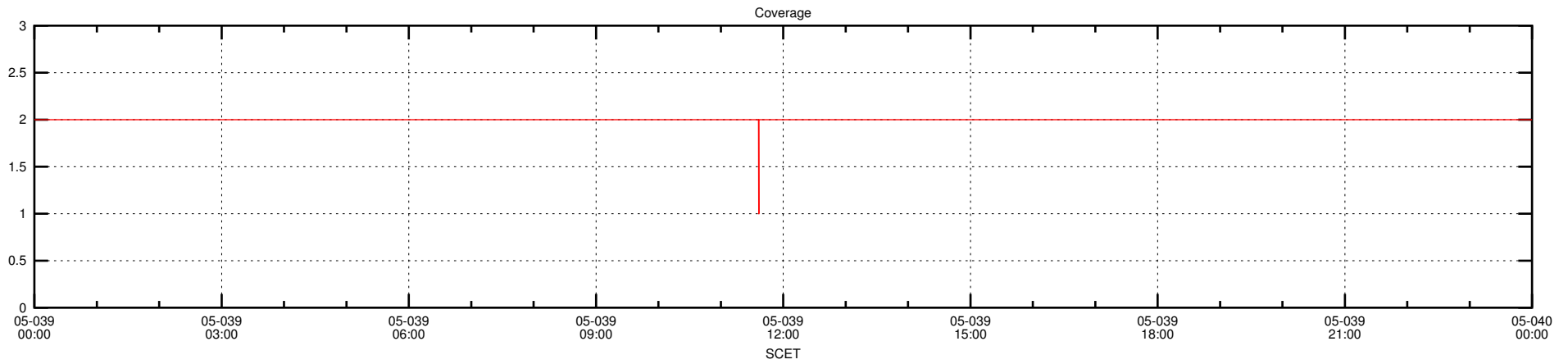


# CK #2 S/C Body Rates (DOY 039-040)



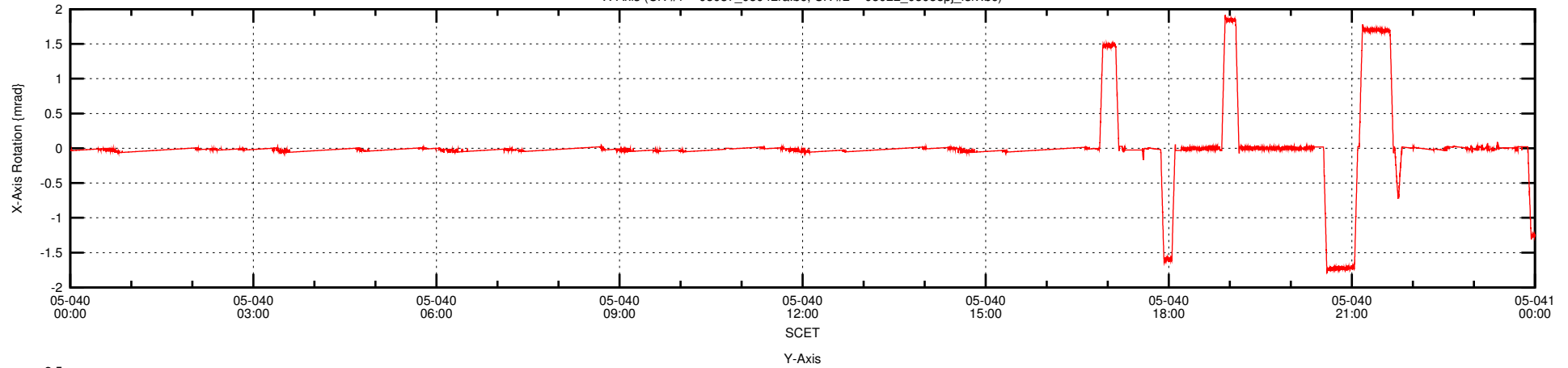


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 039-040)

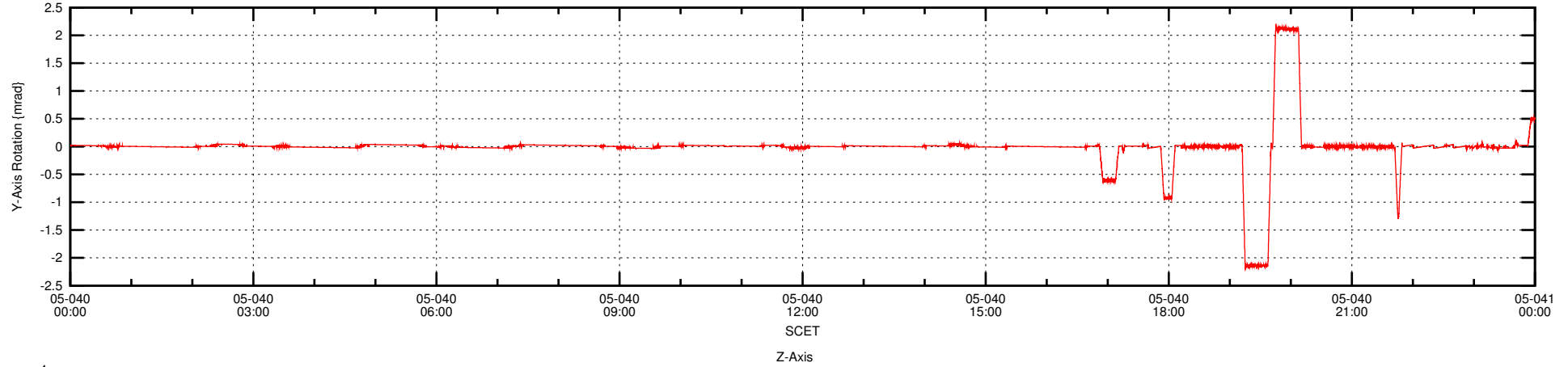


# Rotation From CK #2 to CK #1 (DOY 040-041)

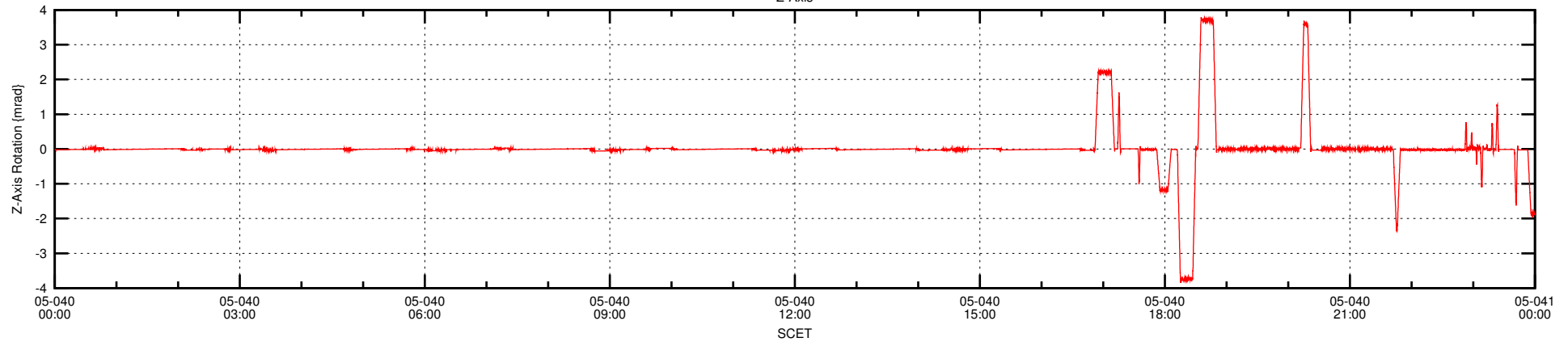
X-Axis (CK #1 = 05037\_05042ra.bc; CK #2 = 05022\_05058pj\_fsiv.bc)



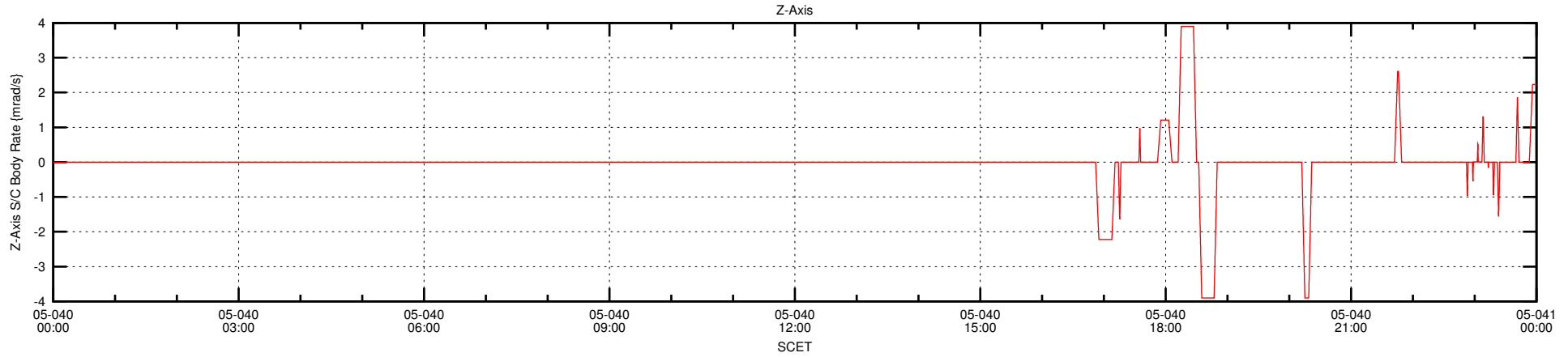
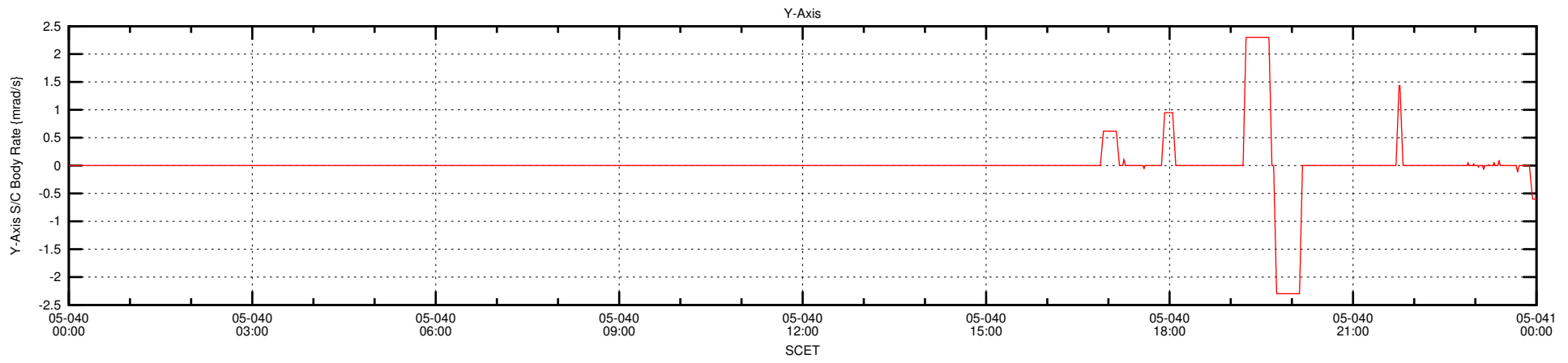
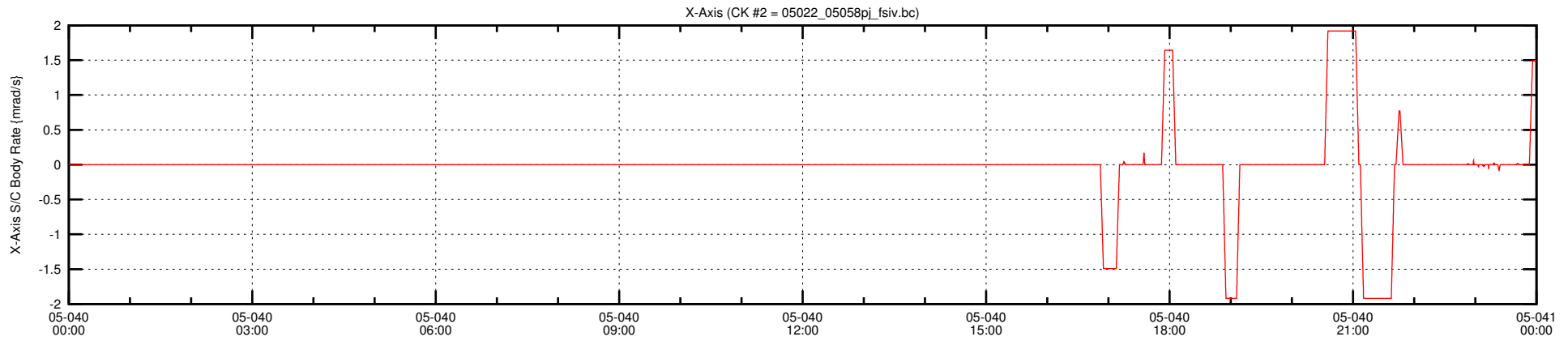
Y-Axis



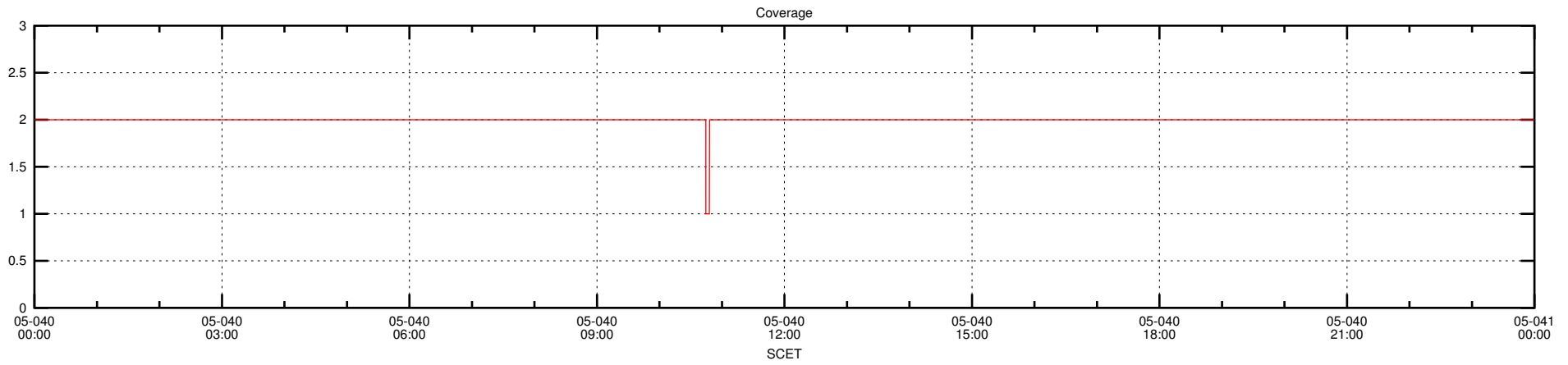
Z-Axis



# CK #2 S/C Body Rates (DOY 040-041)

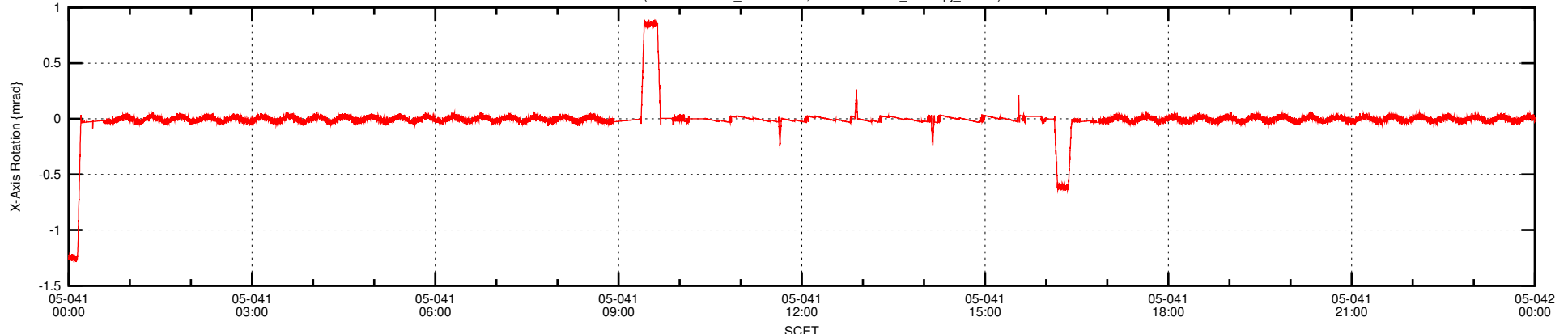


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 040-041)

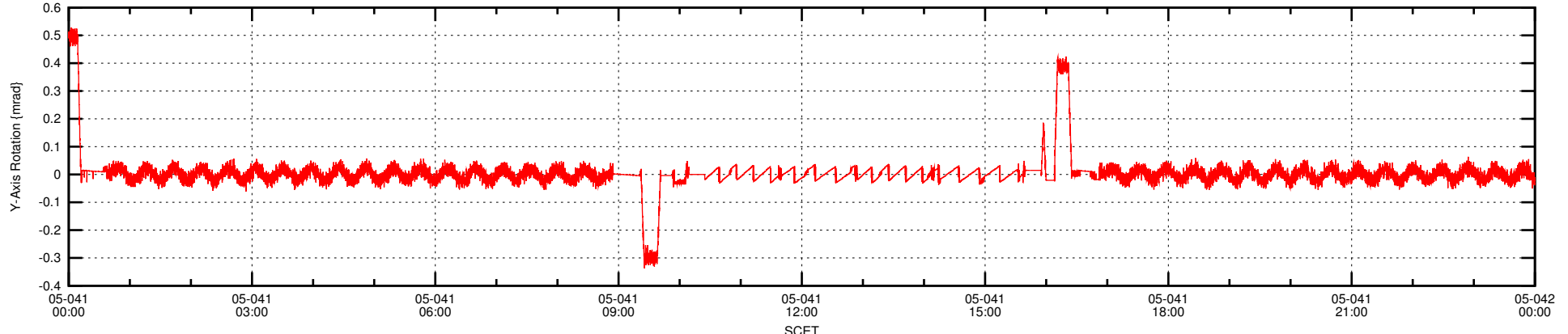


# Rotation From CK #2 to CK #1 (DOY 041-041)

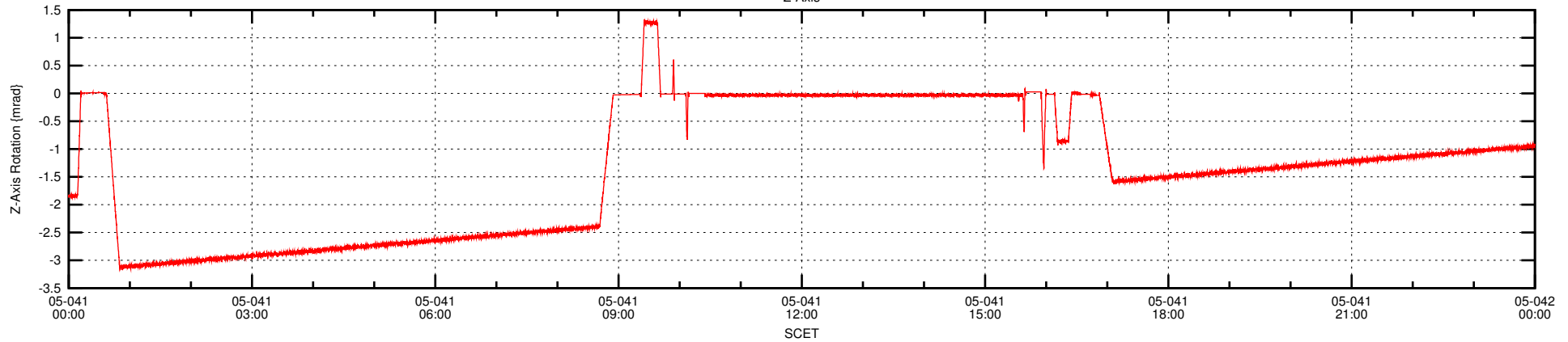
X-Axis (CK #1 = 05037\_05042ra.bc; CK #2 = 05022\_05058pj\_fsiv.bc)



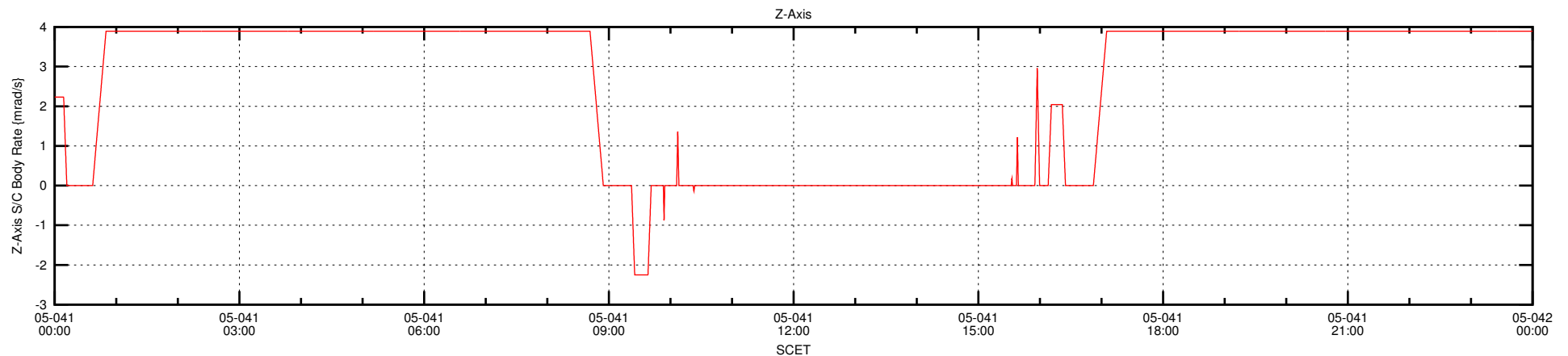
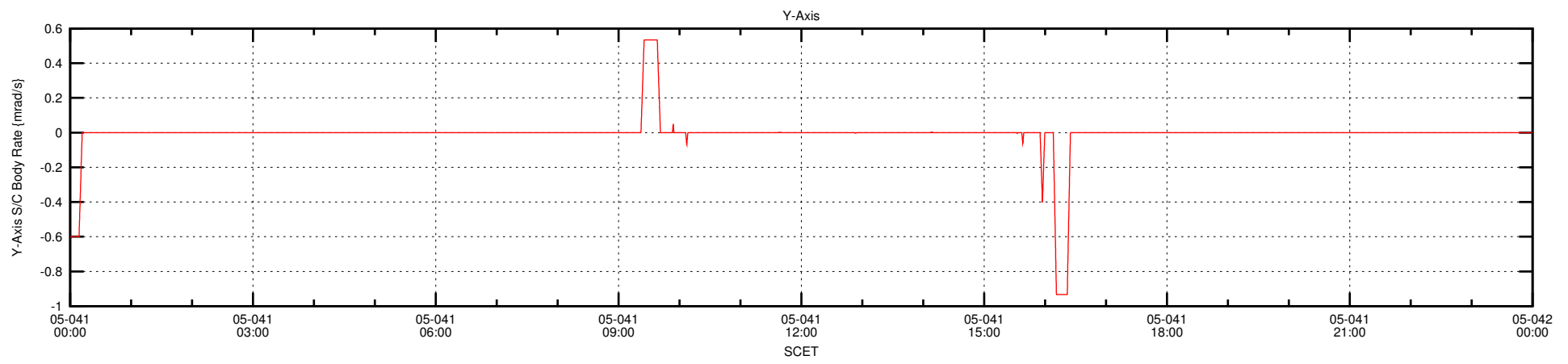
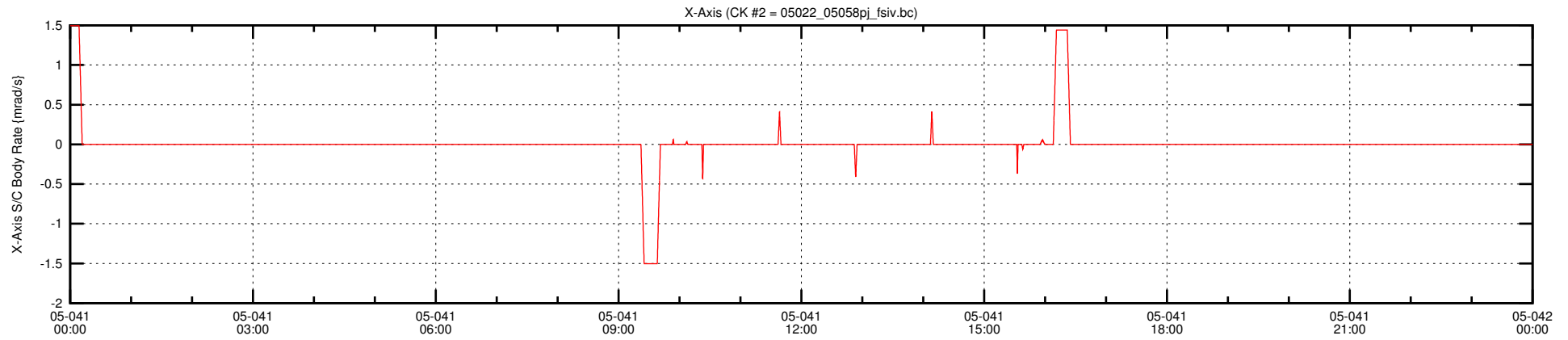
Y-Axis



Z-Axis



# CK #2 S/C Body Rates (DOY 041-041)



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 041-041)

