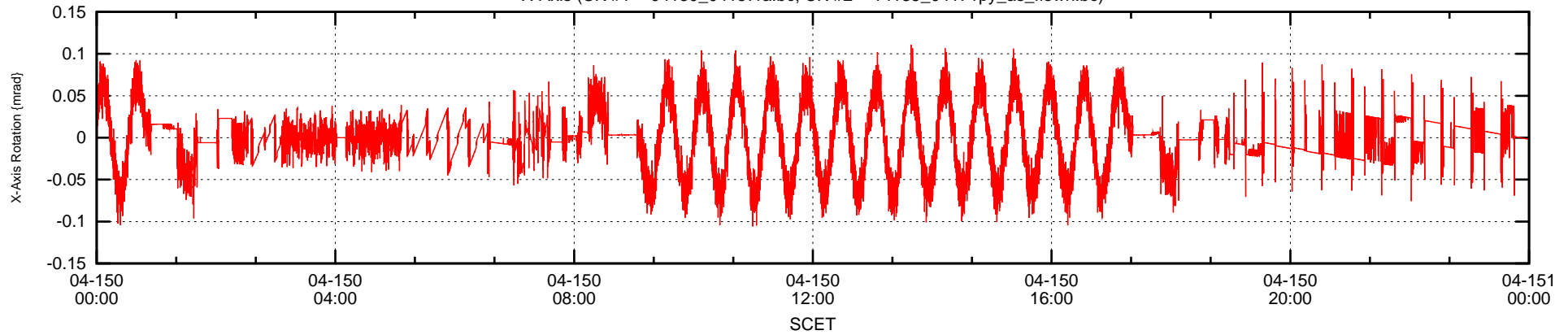
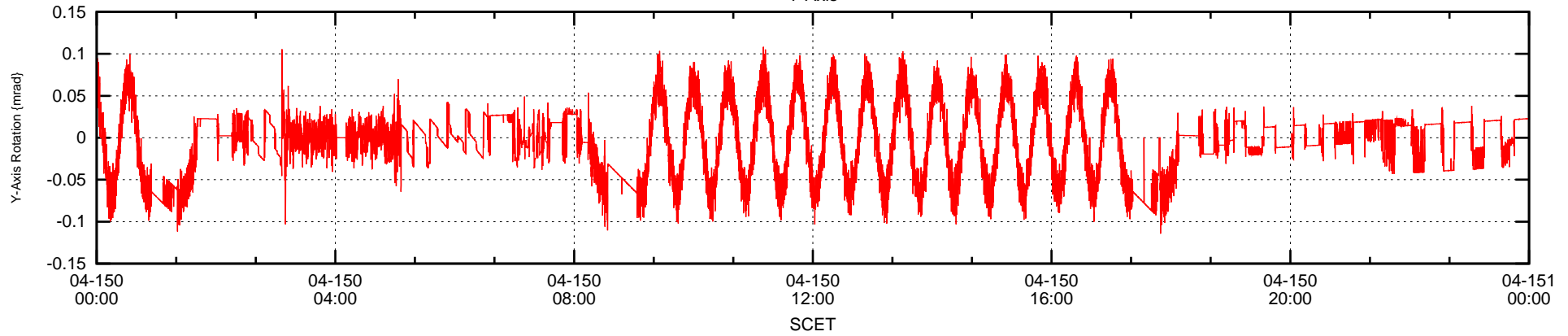


Rotation From CK #2 to CK #1 (DOY 150-151)

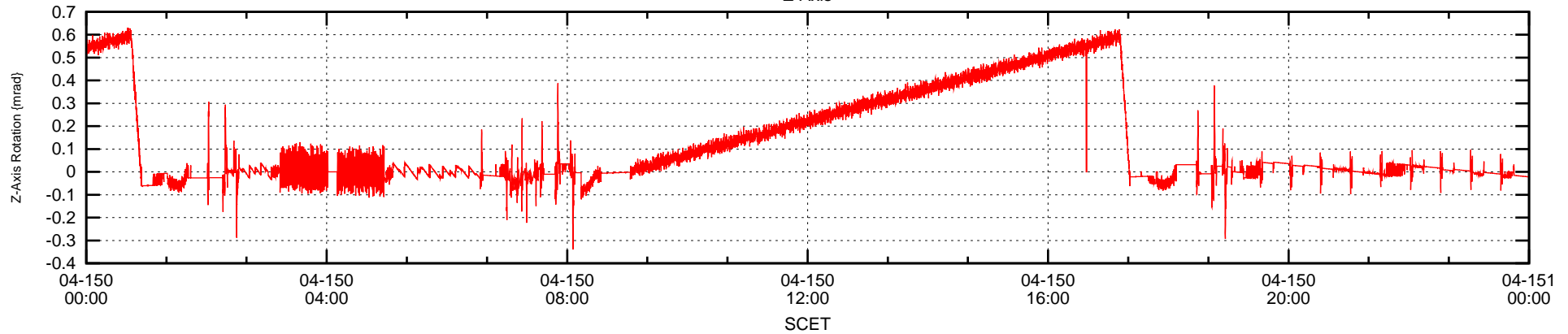
X-Axis (CK #1 = 04150_04157ra.bc; CK #2 = 14135_04171py_as_flowm.bc)



Y-Axis

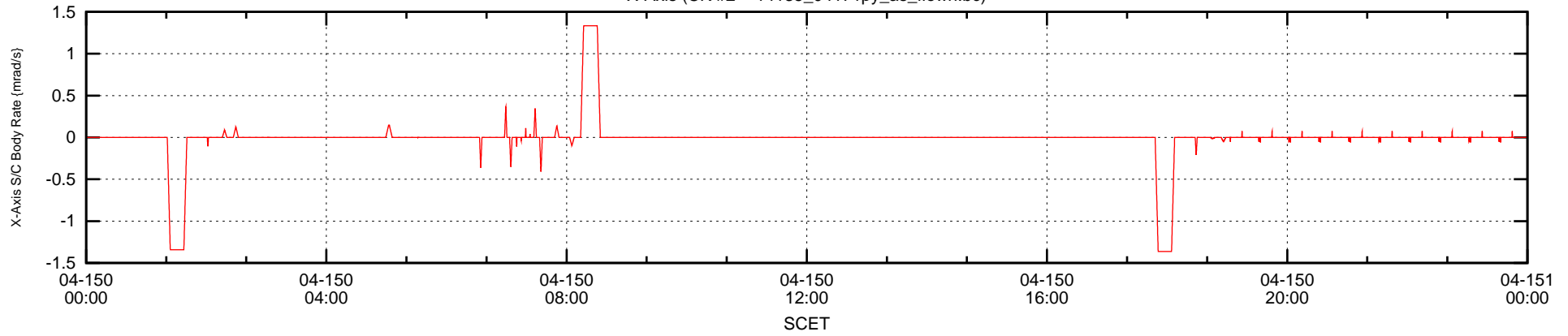


Z-Axis

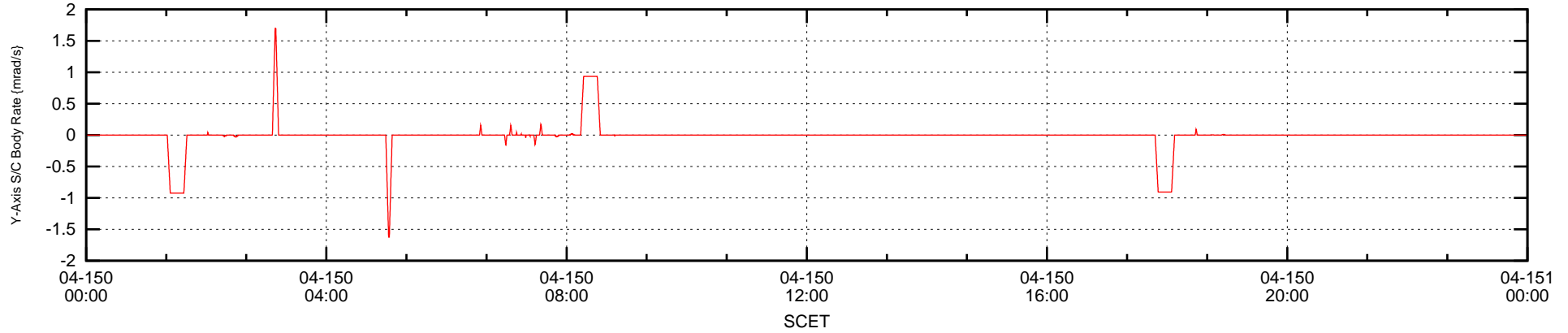


CK #2 S/C Body Rates (DOY 150-151)

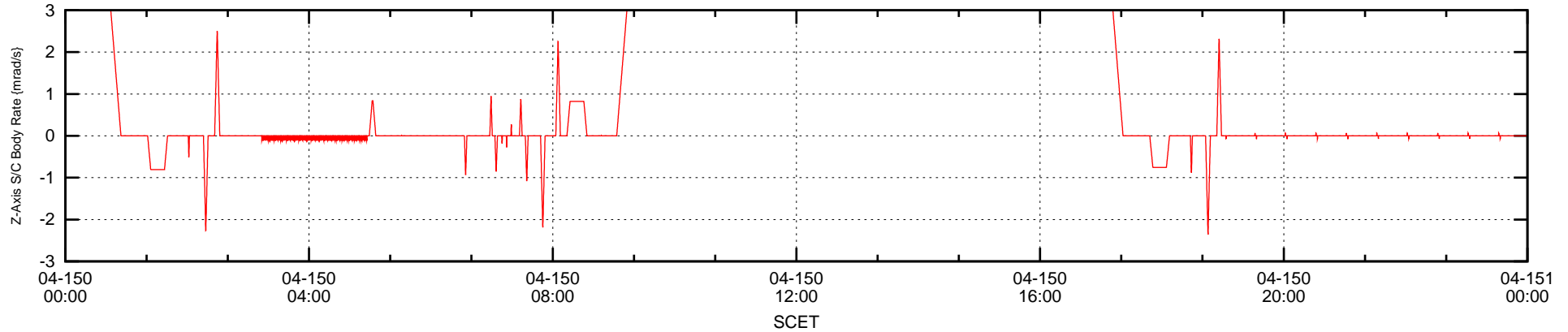
X-Axis (CK #2 = 14135_04171py_as_flow.n.bc)



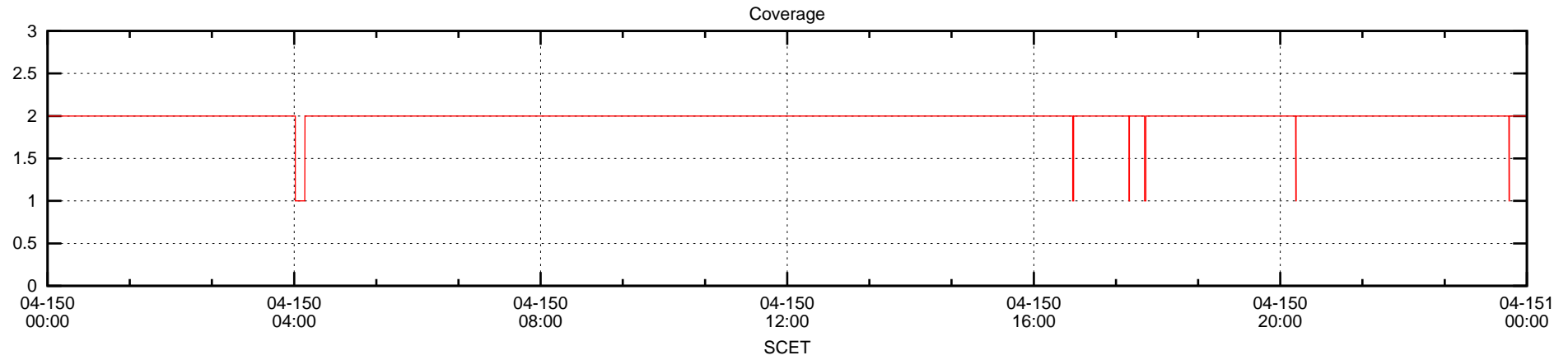
Y-Axis



Z-Axis

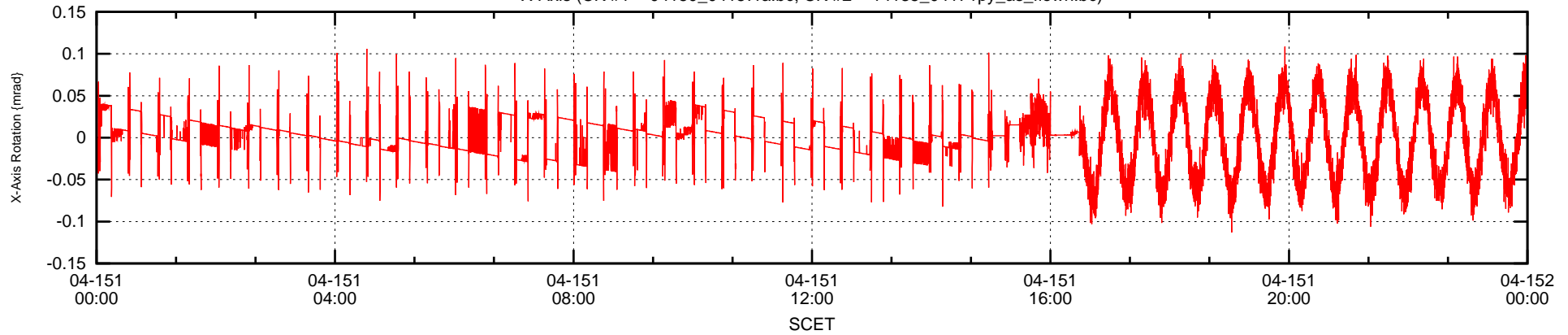


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 150-151)

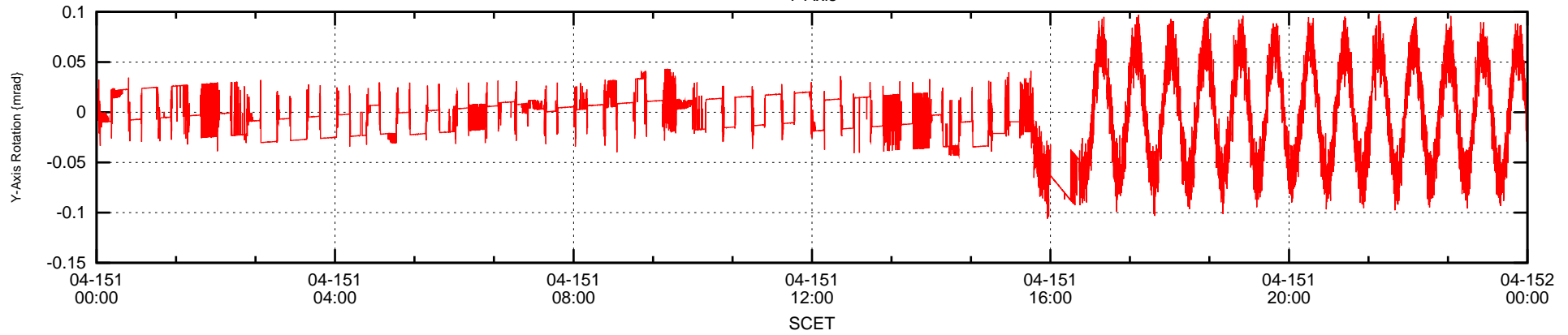


Rotation From CK #2 to CK #1 (DOY 151-152)

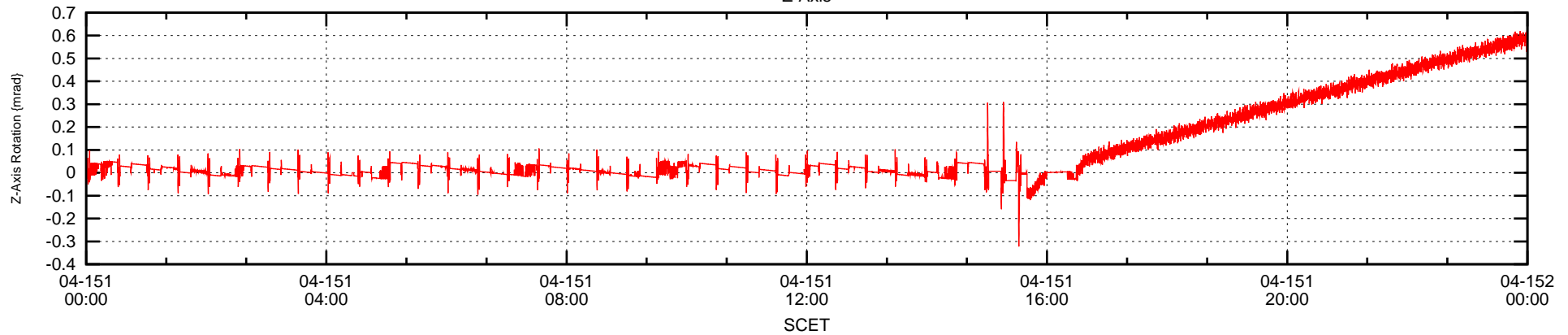
X-Axis (CK #1 = 04150_04157ra.bc; CK #2 = 14135_04171py_as_flown.bc)



Y-Axis

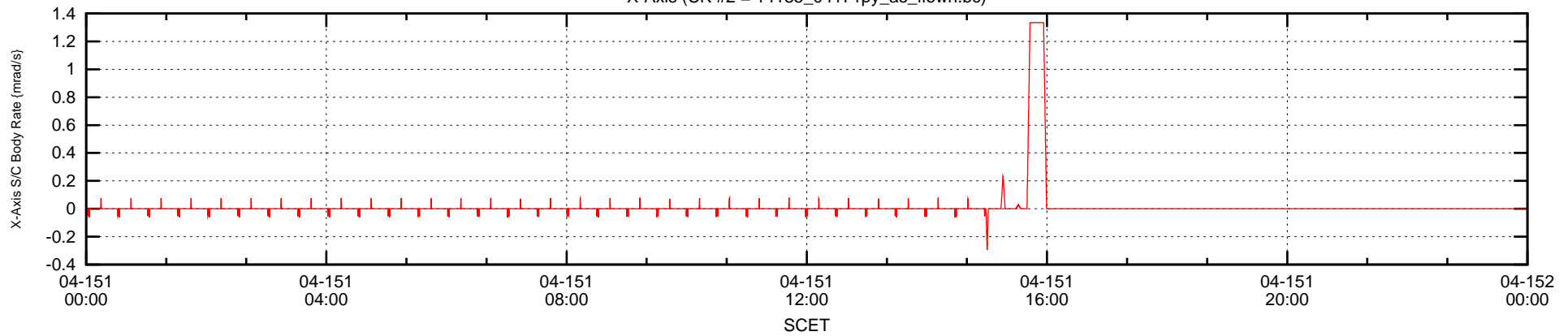


Z-Axis

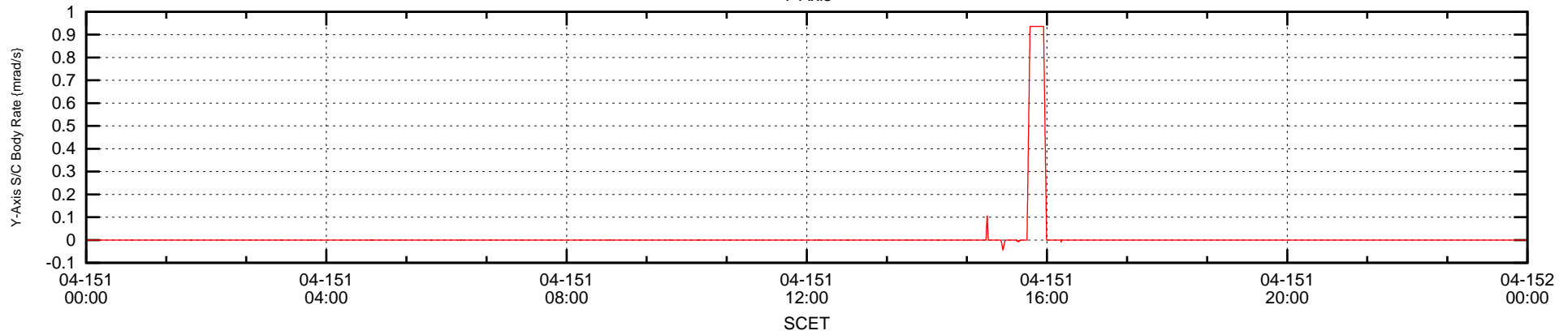


CK #2 S/C Body Rates (DOY 151-152)

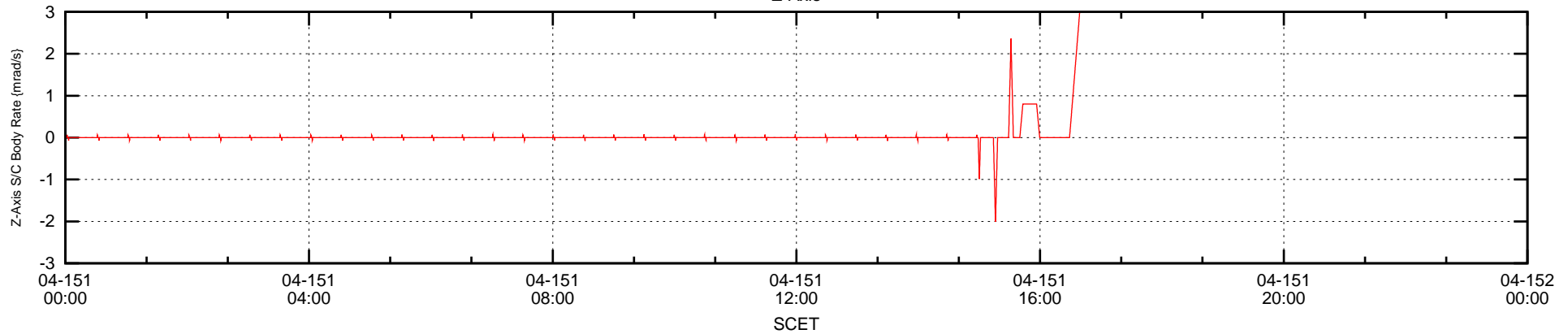
X-Axis (CK #2 = 14135_04171py_as_flowm.bc)



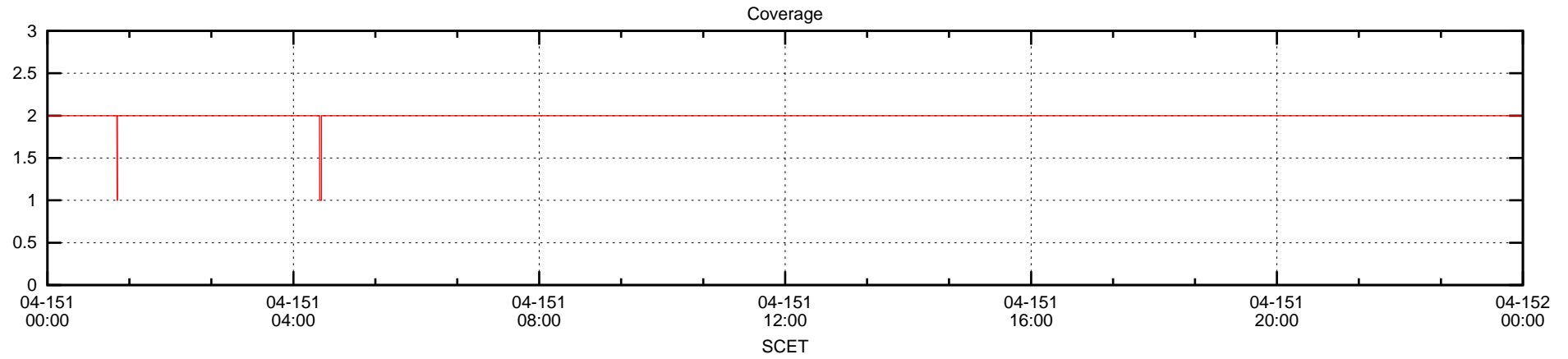
Y-Axis



Z-Axis

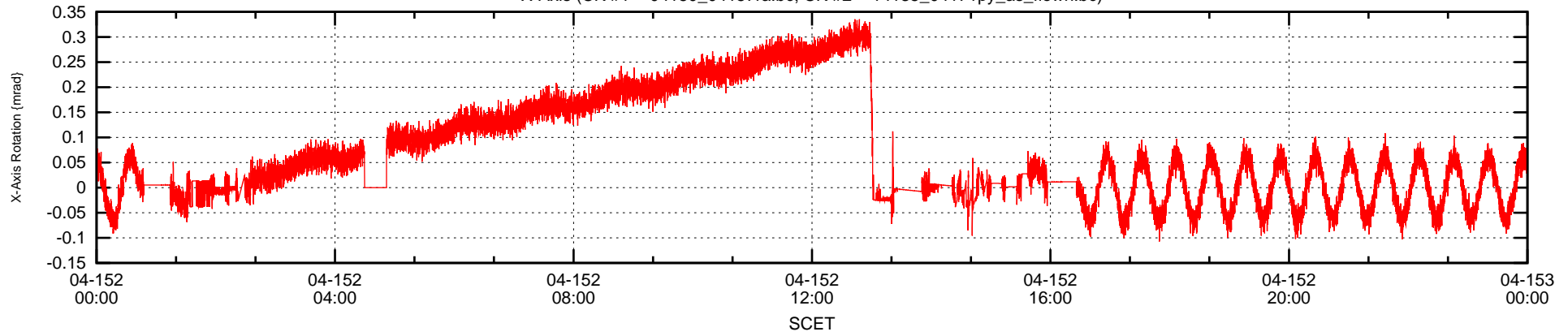


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 151-152)

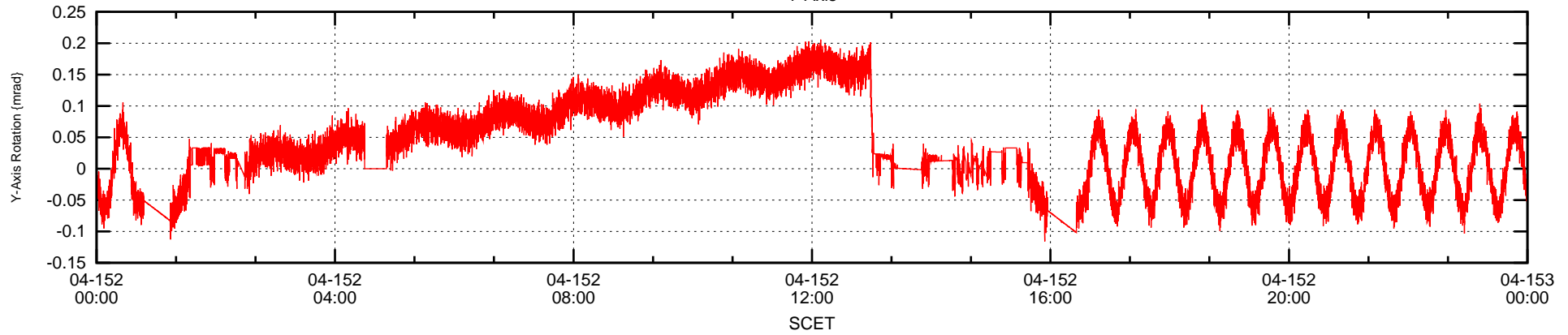


Rotation From CK #2 to CK #1 (DOY 152-153)

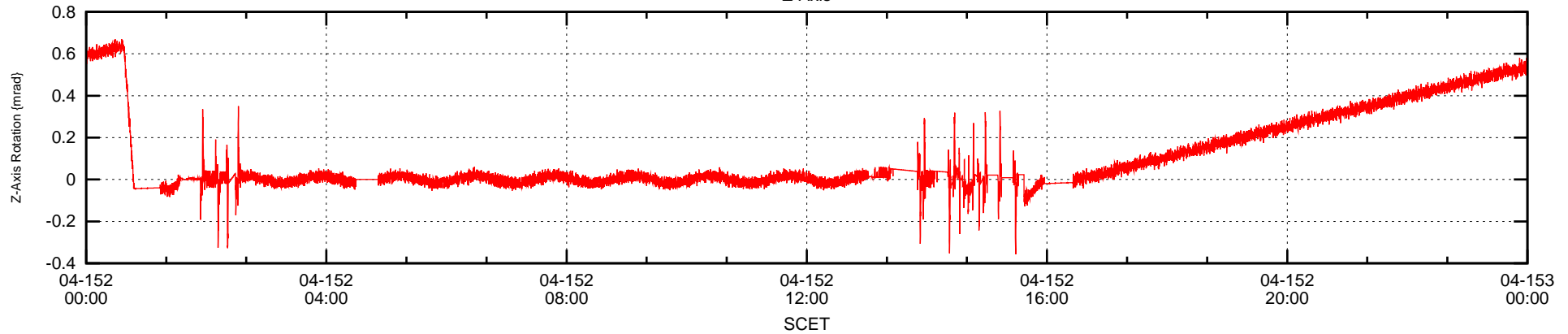
X-Axis (CK #1 = 04150_04157ra.bc; CK #2 = 14135_04171py_as_flown.bc)



Y-Axis

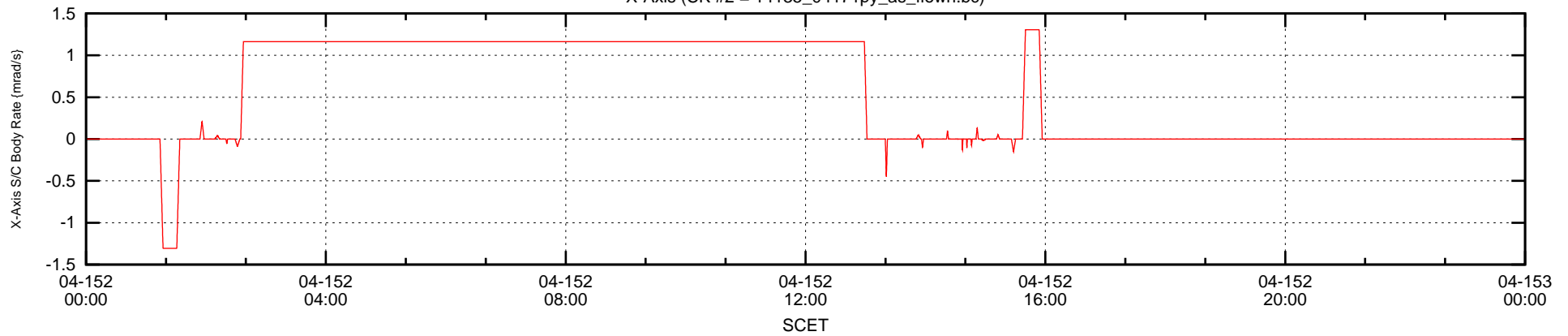


Z-Axis

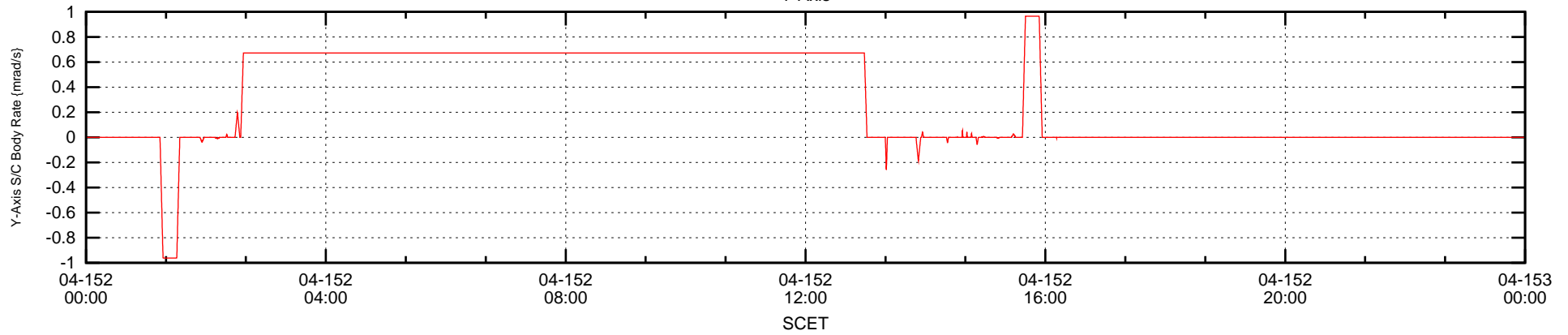


CK #2 S/C Body Rates (DOY 152-153)

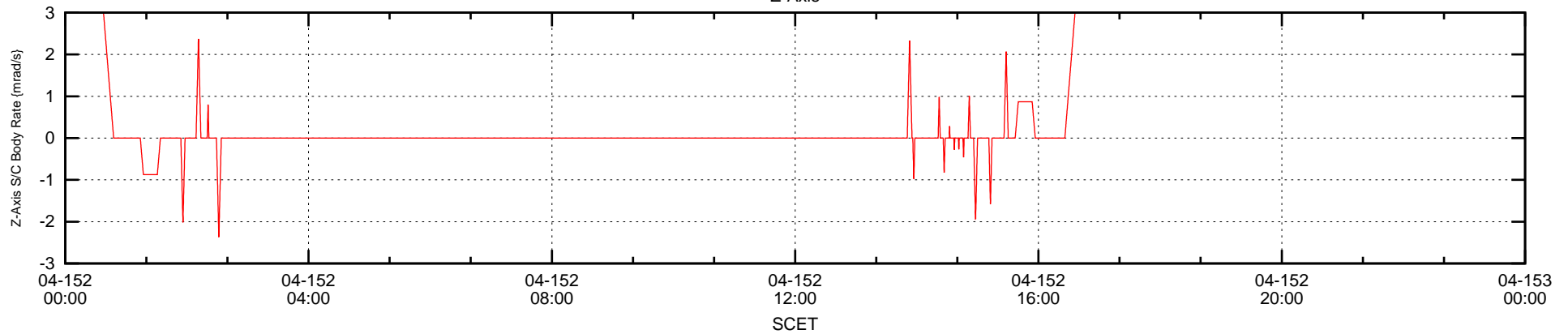
X-Axis (CK #2 = 14135_04171py_as_flowm.bc)



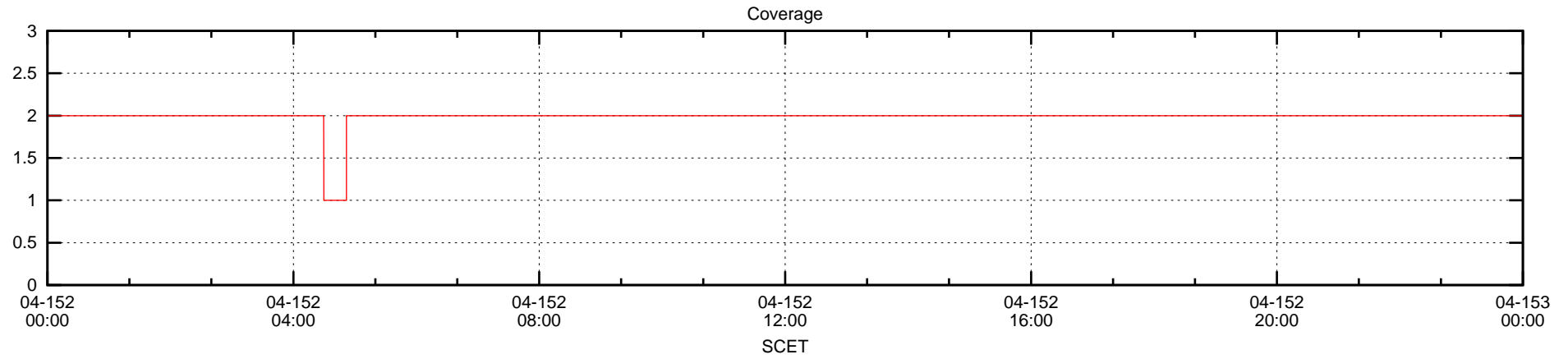
Y-Axis



Z-Axis

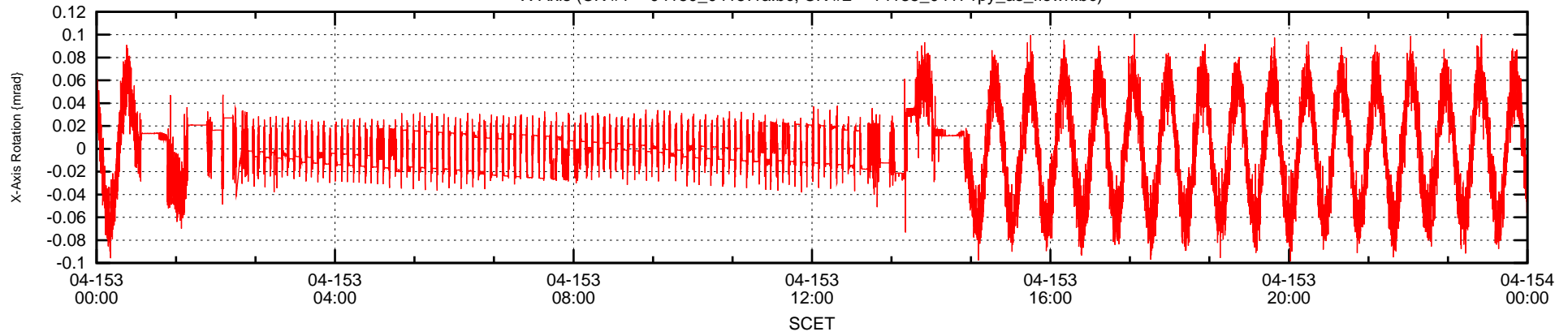


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 152-153)

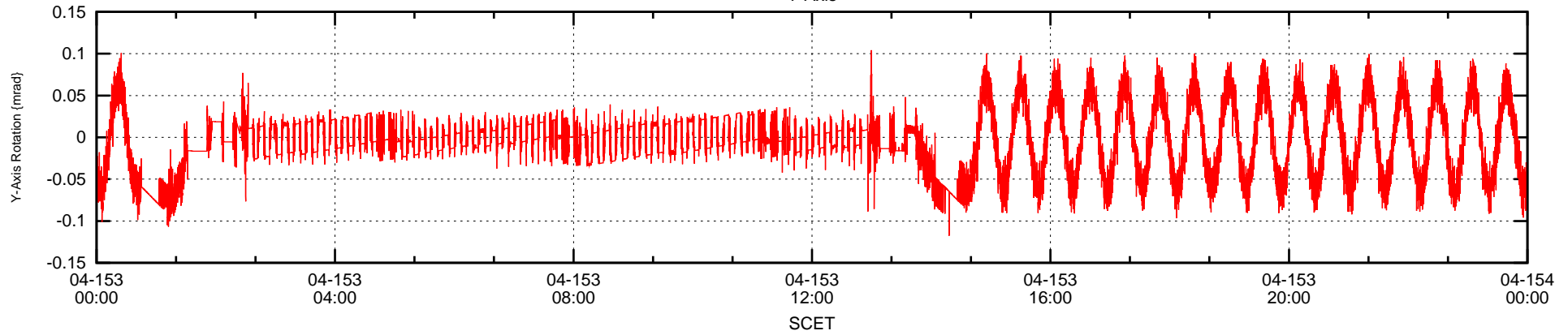


Rotation From CK #2 to CK #1 (DOY 153-154)

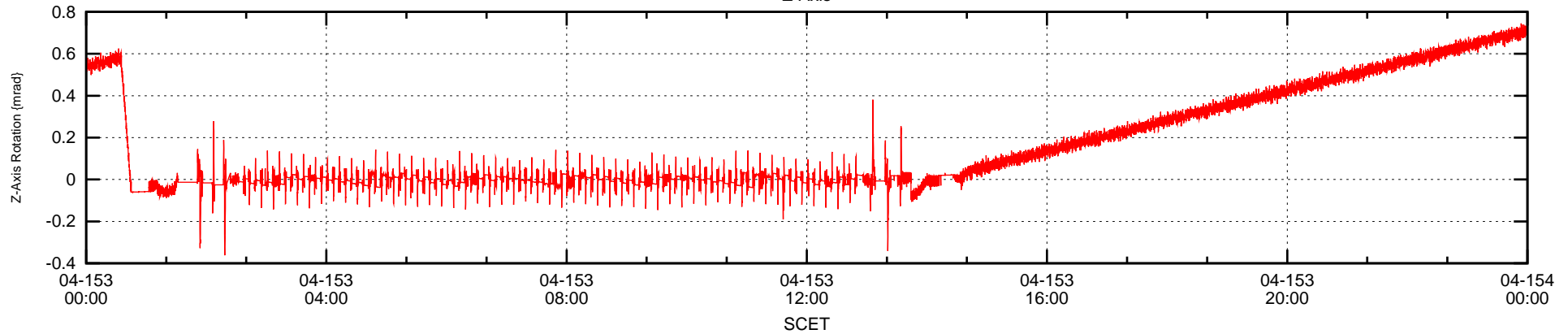
X-Axis (CK #1 = 04150_04157ra.bc; CK #2 = 14135_04171py_as_flowm.bc)



Y-Axis

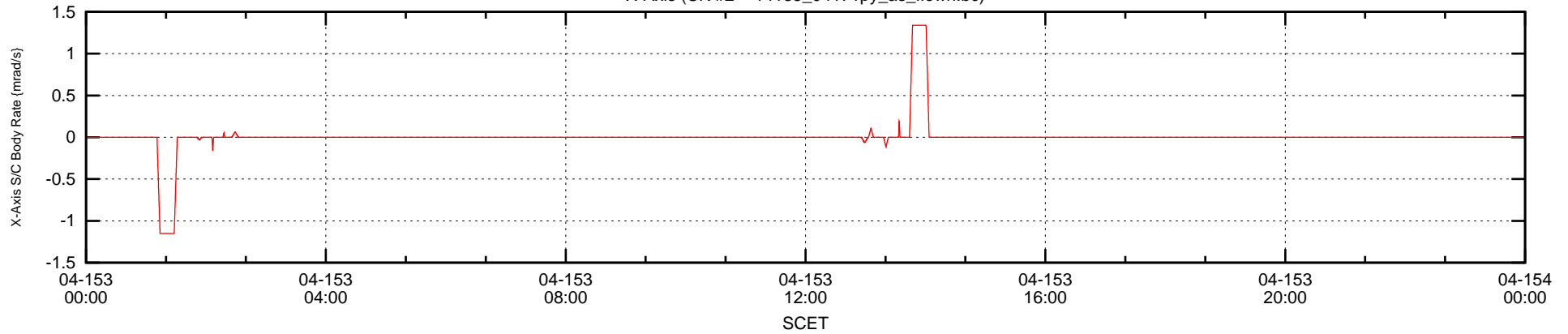


Z-Axis

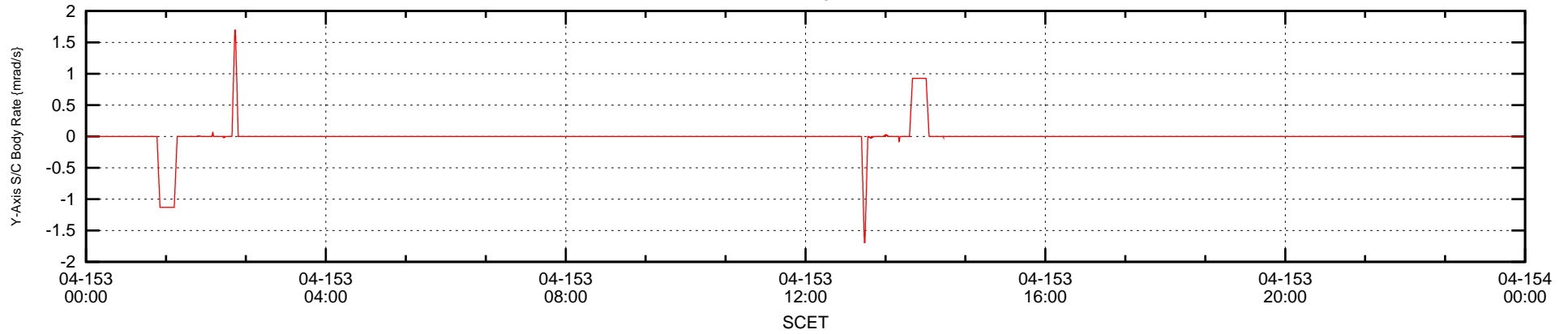


CK #2 S/C Body Rates (DOY 153-154)

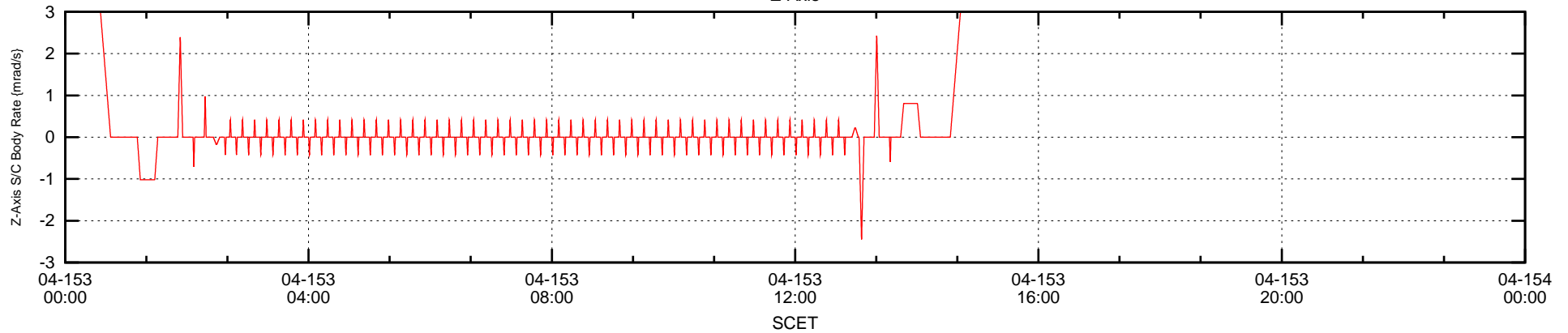
X-Axis (CK #2 = 14135_04171py_as_flow.n.bc)



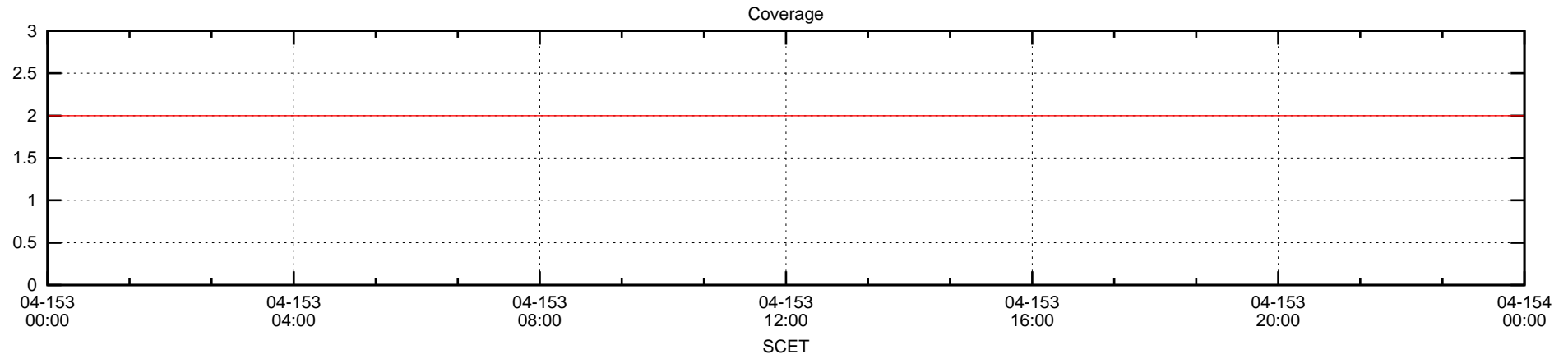
Y-Axis



Z-Axis

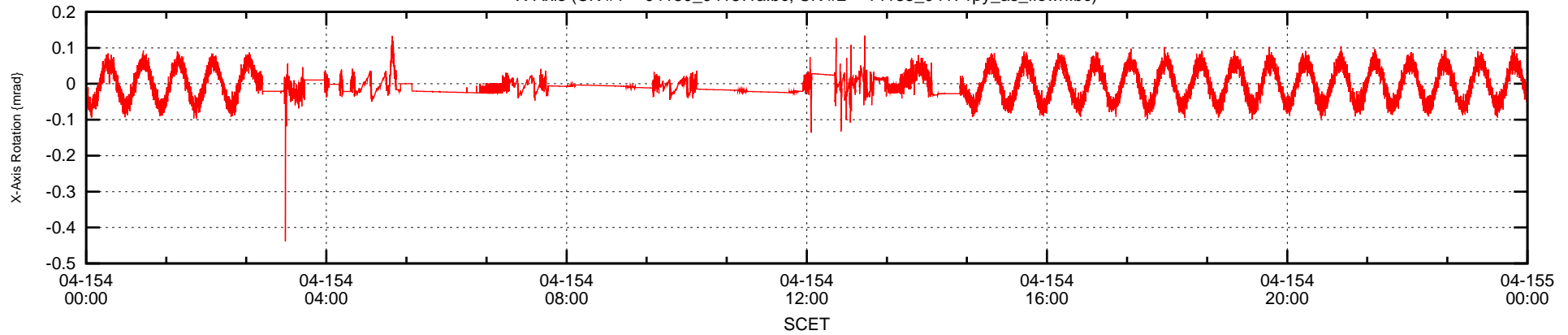


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 153-154)

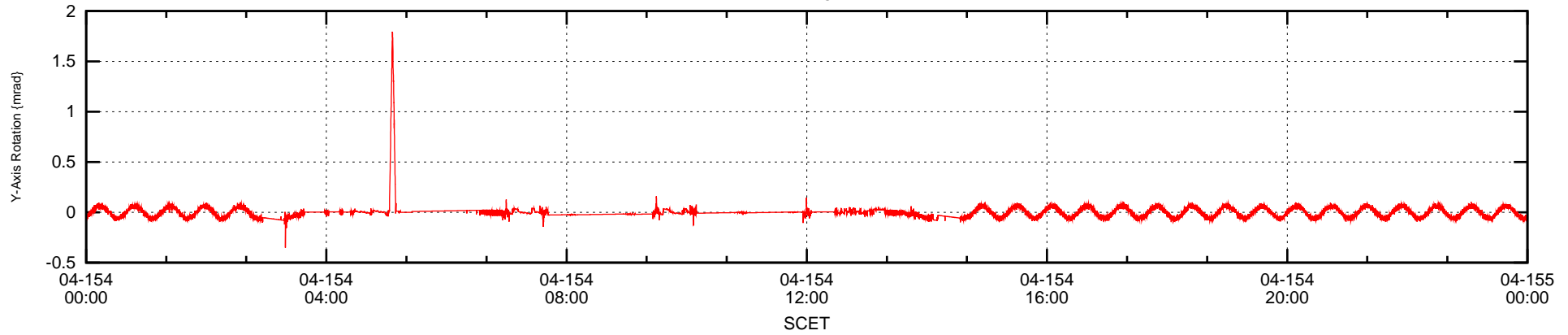


Rotation From CK #2 to CK #1 (DOY 154-155)

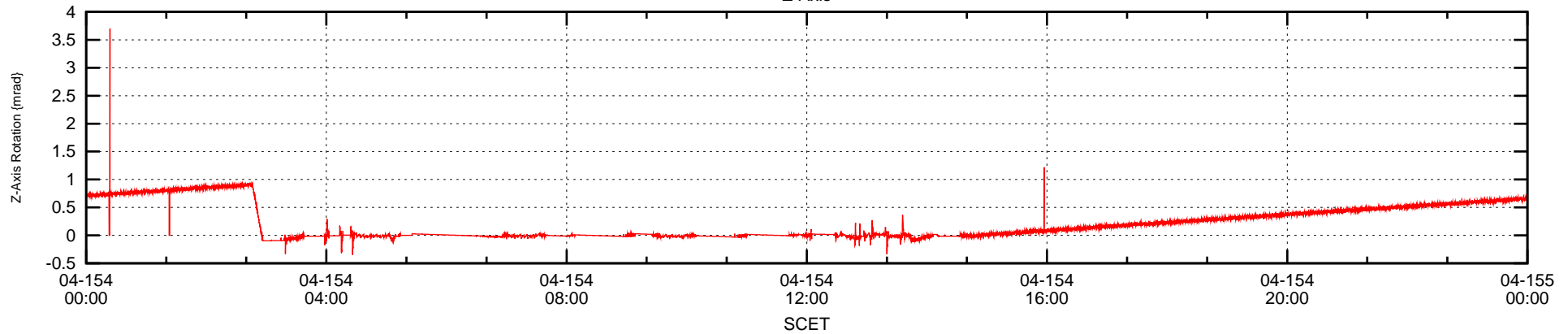
X-Axis (CK #1 = 04150_04157ra.bc; CK #2 = 14135_04171py_as_flowm.bc)



Y-Axis

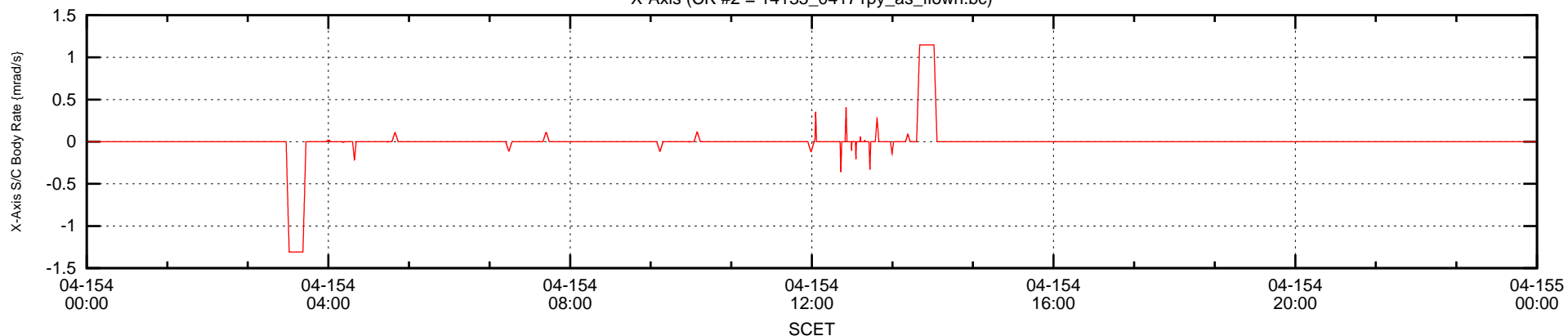


Z-Axis

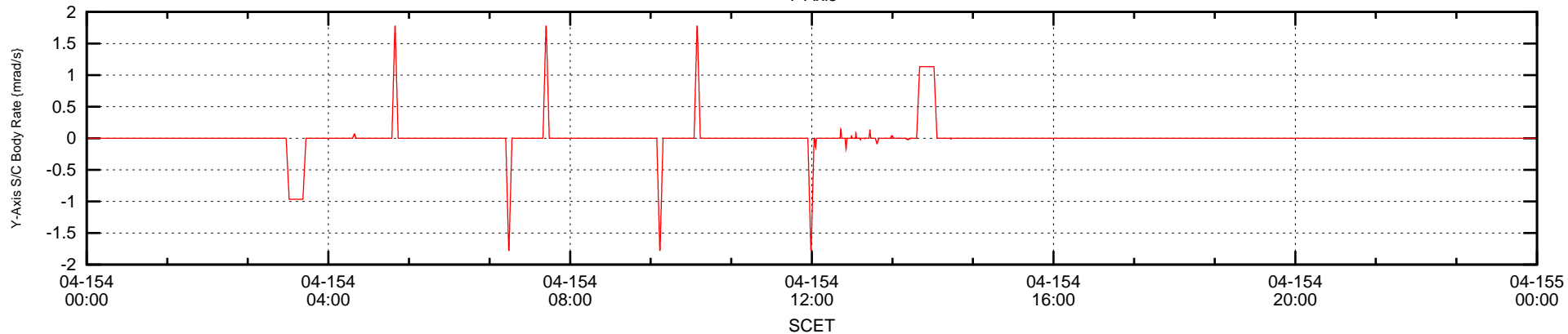


CK #2 S/C Body Rates (DOY 154-155)

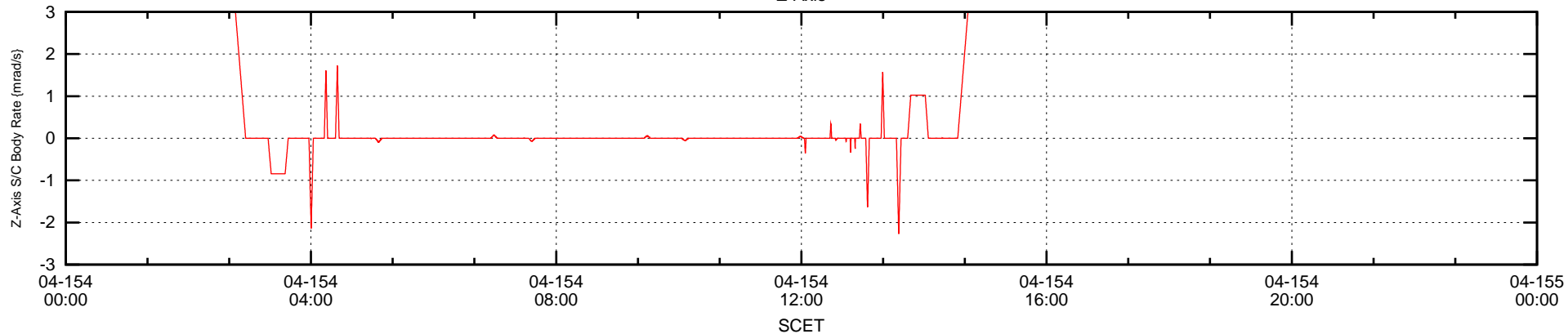
X-Axis (CK #2 = 14135_04171py_as_flow.n.bc)



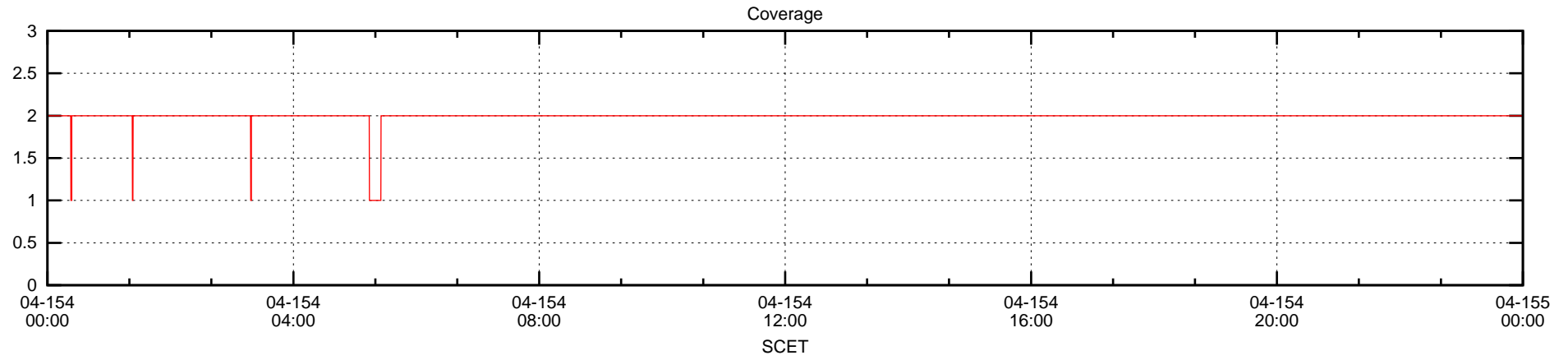
Y-Axis



Z-Axis

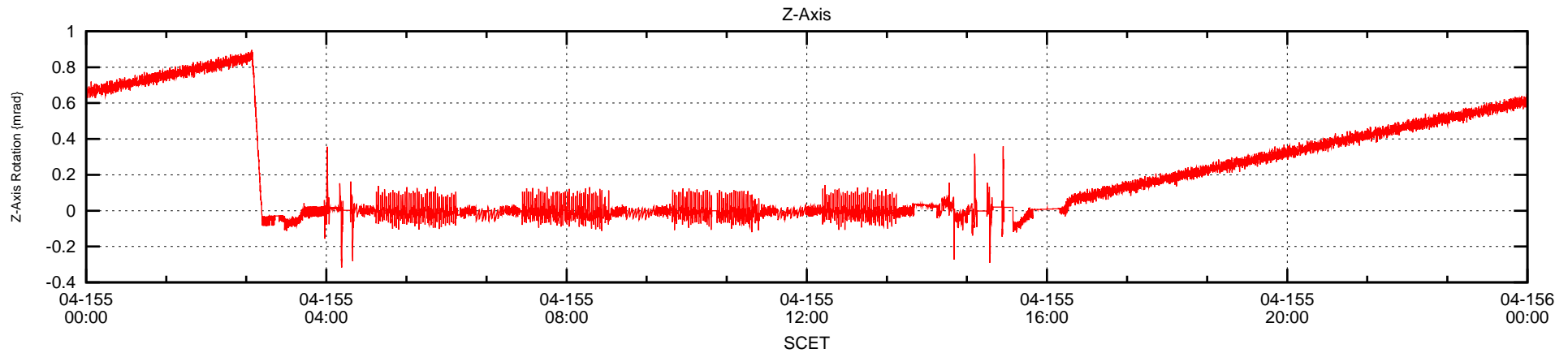
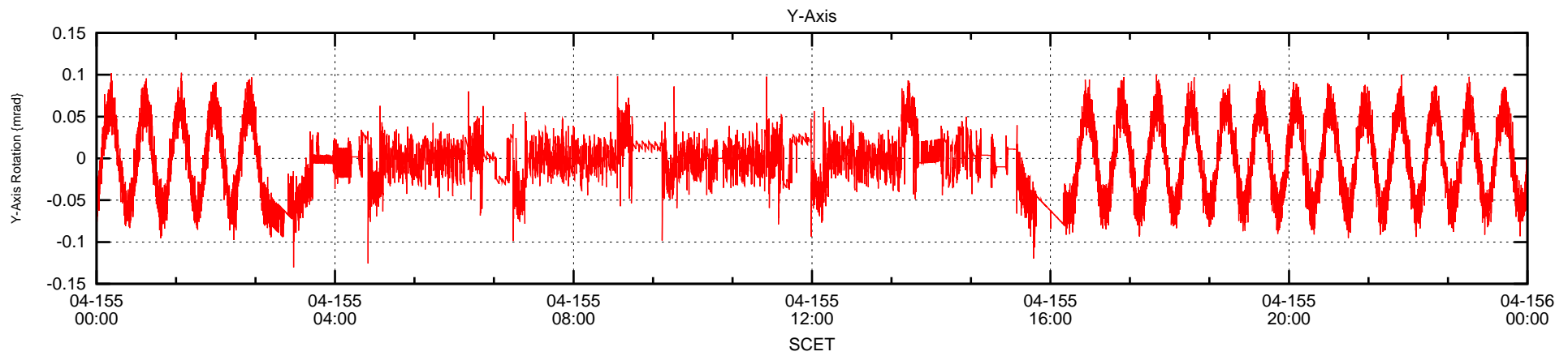
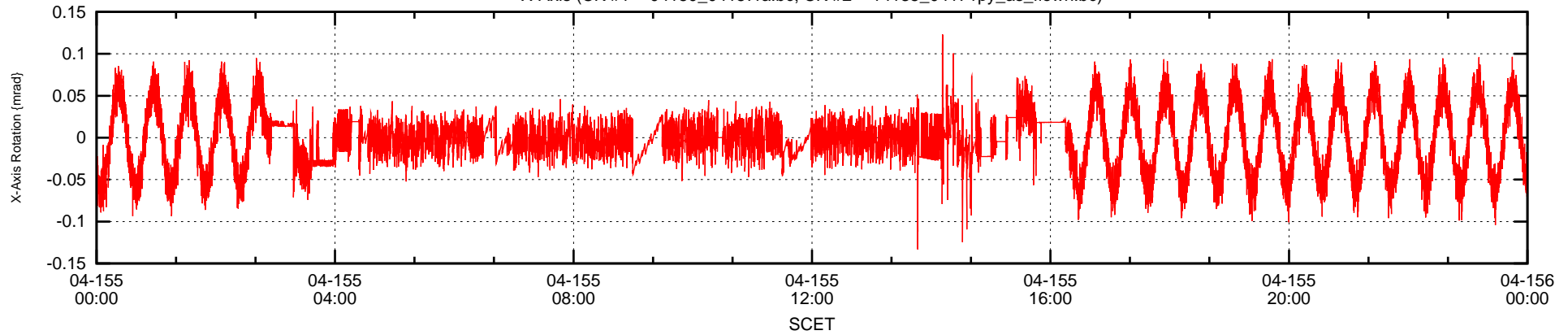


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 154-155)



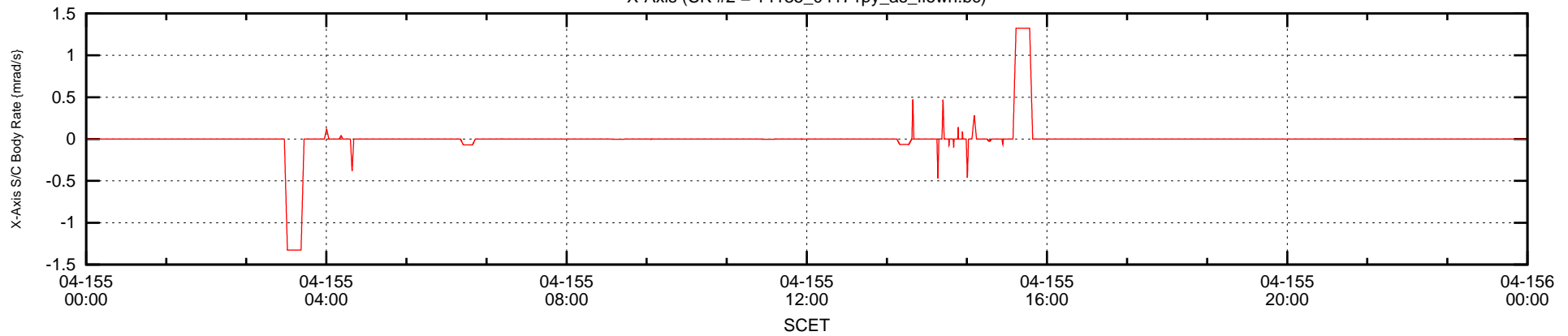
Rotation From CK #2 to CK #1 (DOY 155-156)

X-Axis (CK #1 = 04150_04157ra.bc; CK #2 = 14135_04171py_as_flowm.bc)

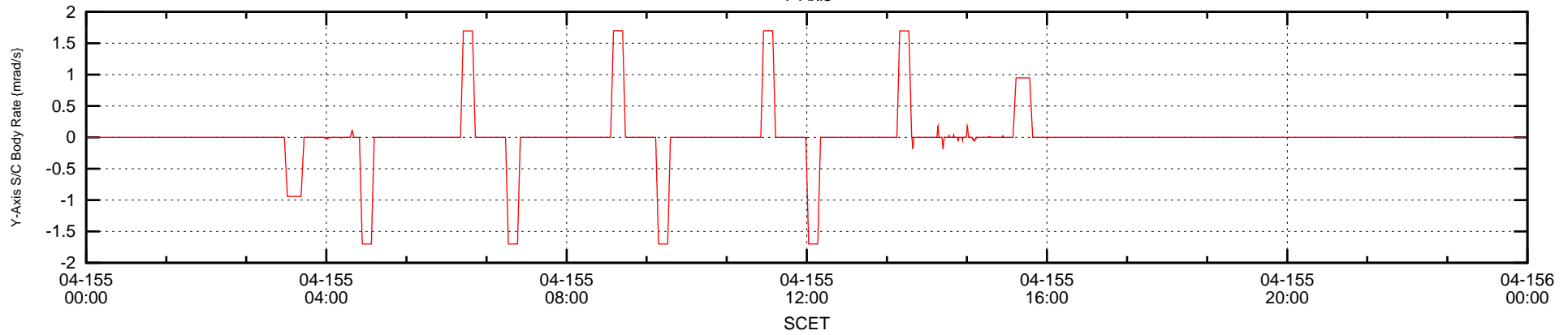


CK #2 S/C Body Rates (DOY 155-156)

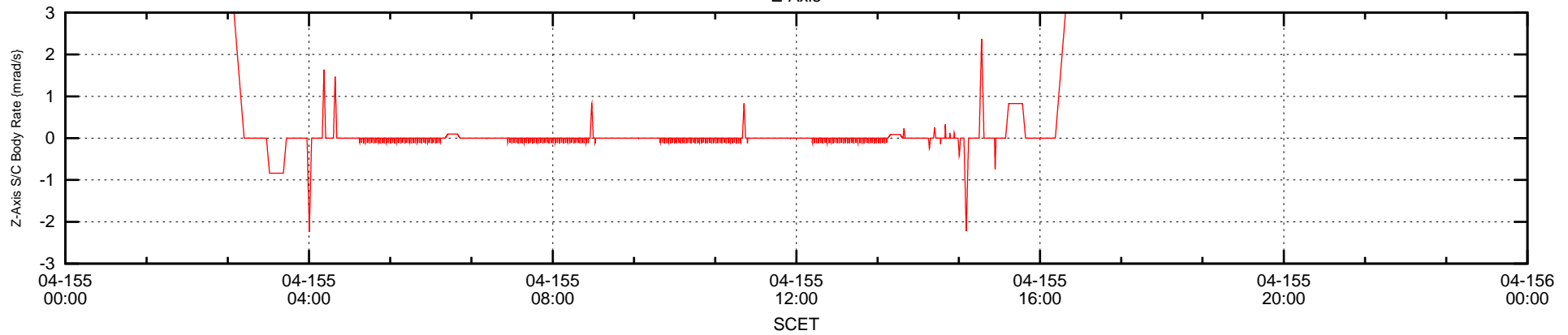
X-Axis (CK #2 = 14135_04171py_as_flowm.bc)



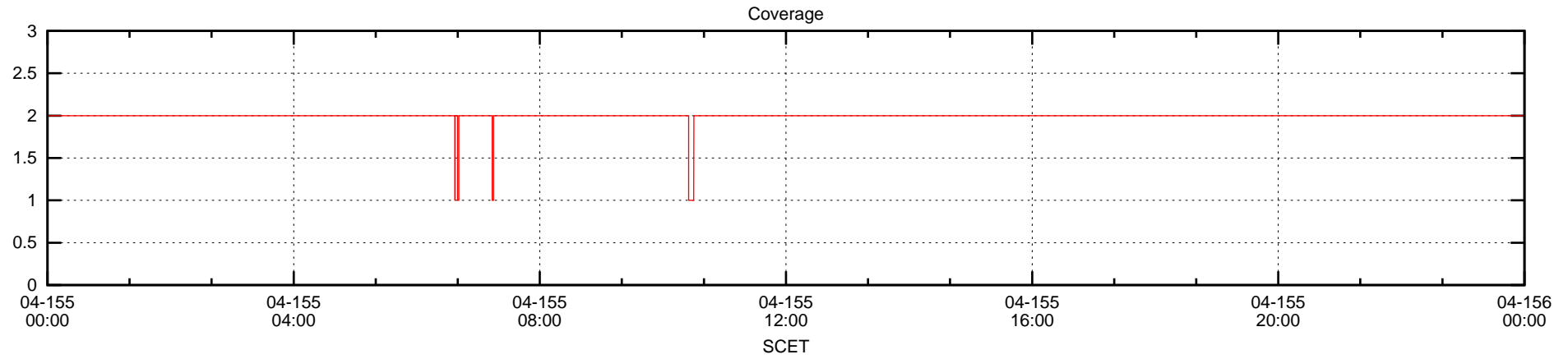
Y-Axis



Z-Axis

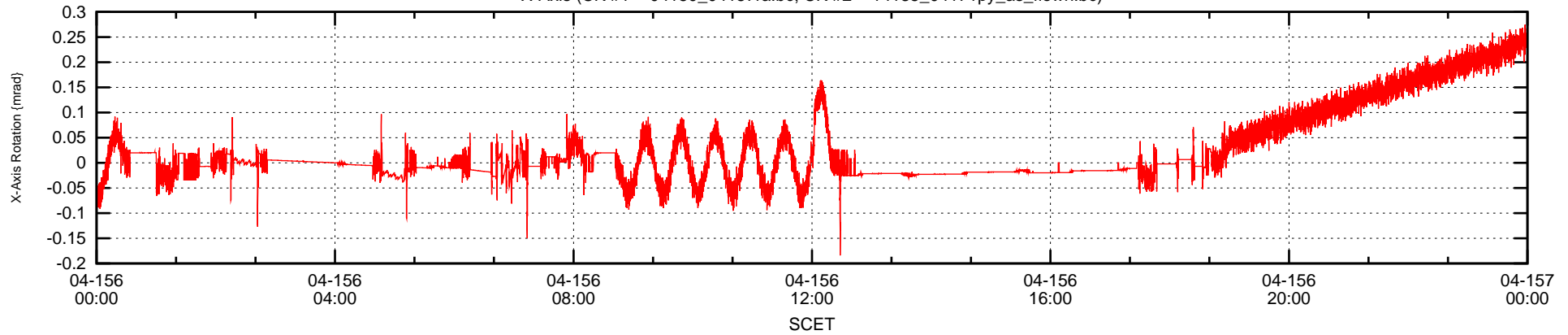


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 155-156)

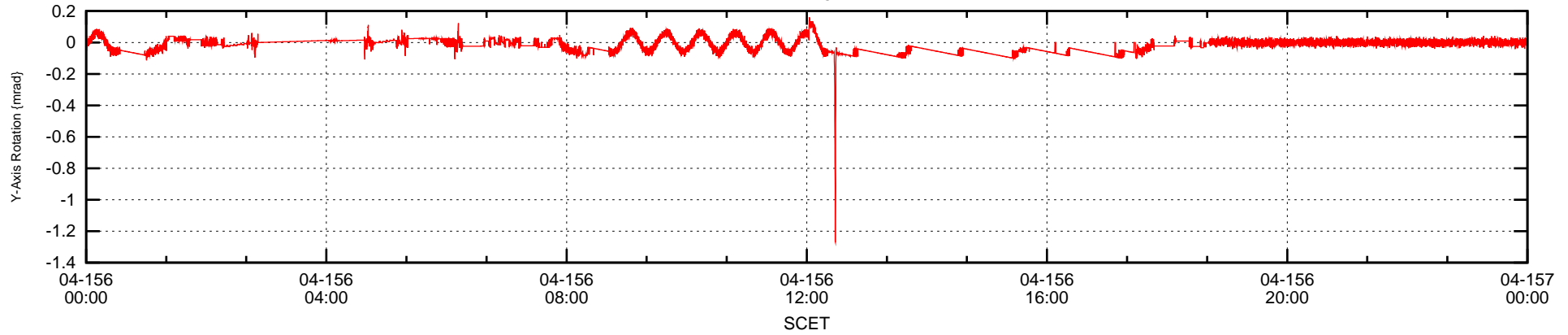


Rotation From CK #2 to CK #1 (DOY 156-157)

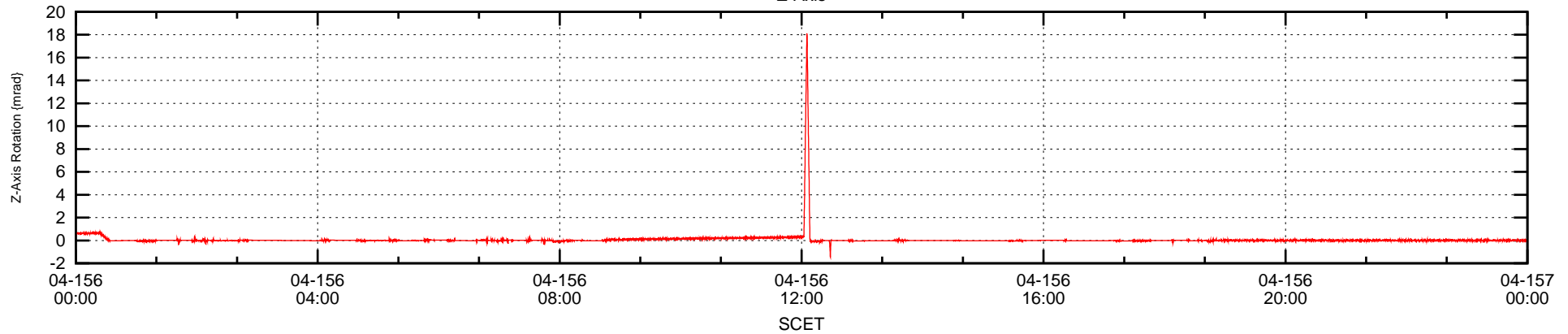
X-Axis (CK #1 = 04150_04157ra.bc; CK #2 = 14135_04171py_as_flown.bc)



Y-Axis

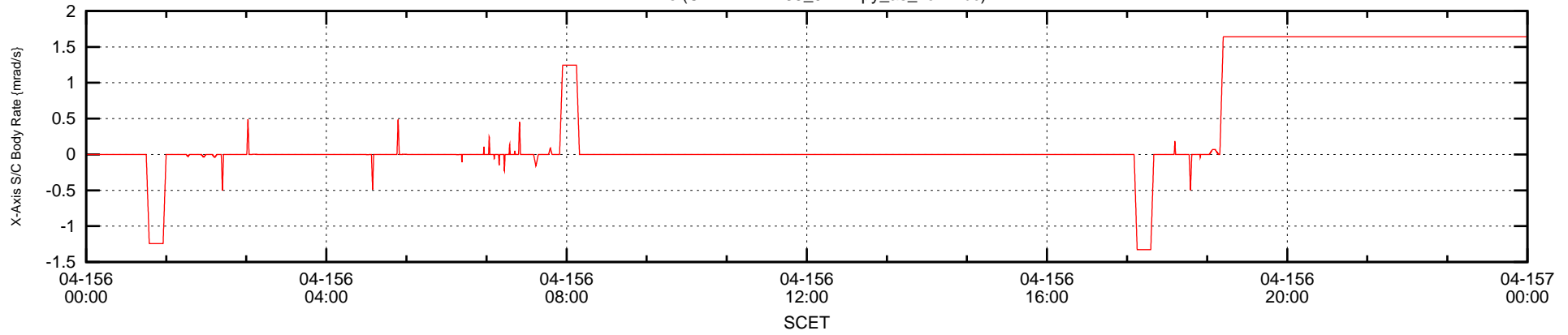


Z-Axis

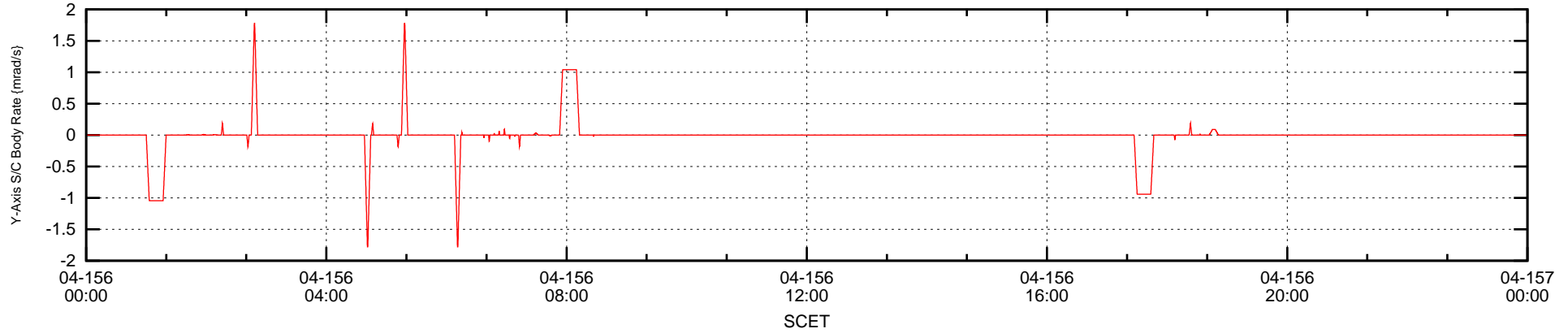


CK #2 S/C Body Rates (DOY 156-157)

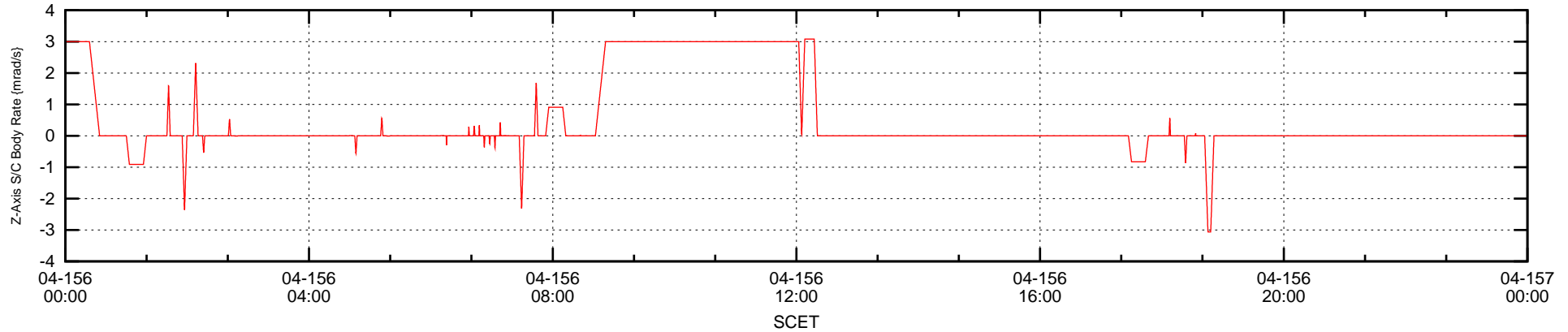
X-Axis (CK #2 = 14135_04171py_as_flowm.bc)



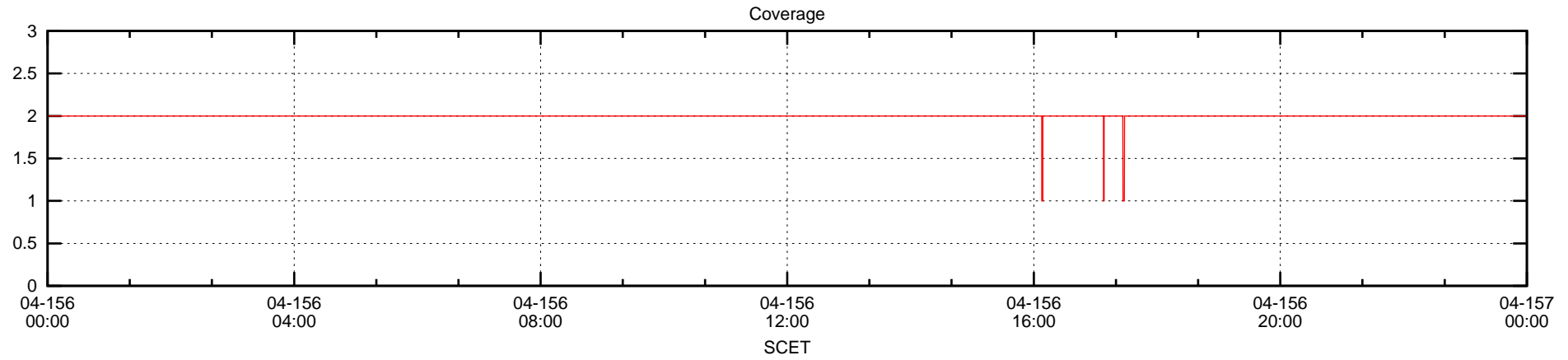
Y-Axis



Z-Axis

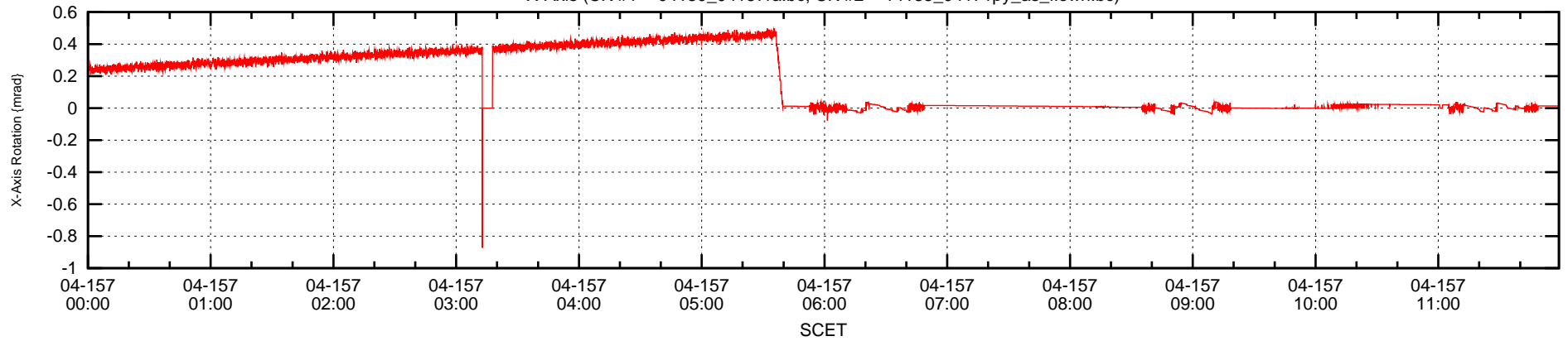


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 156-157)

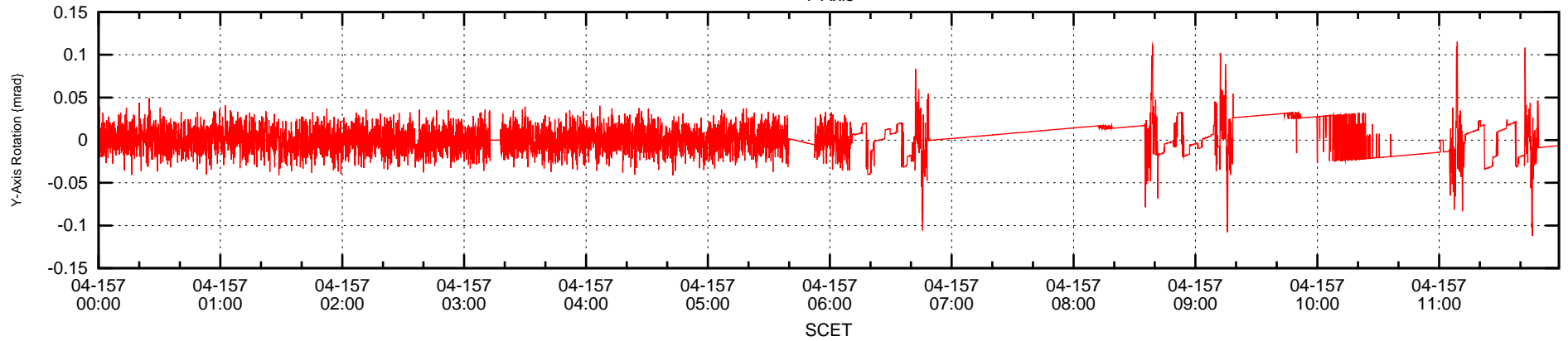


Rotation From CK #2 to CK #1 (DOY 157-157)

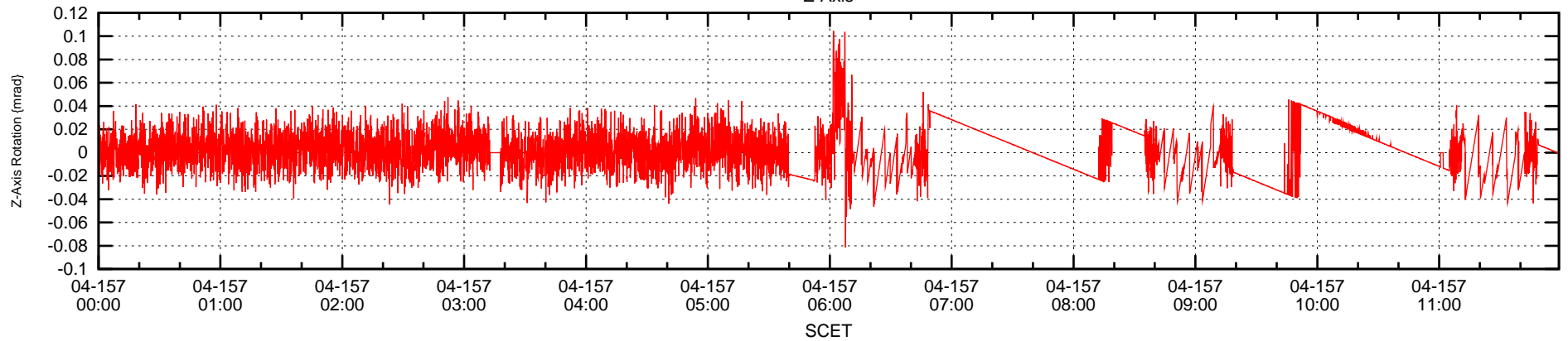
X-Axis (CK #1 = 04150_04157ra.bc; CK #2 = 14135_04171py_as_flowm.bc)



Y-Axis

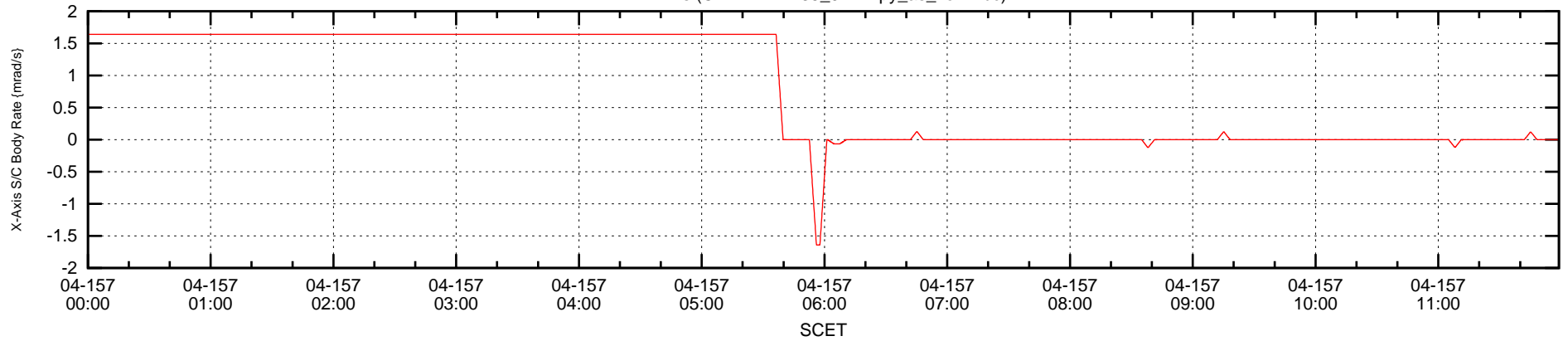


Z-Axis

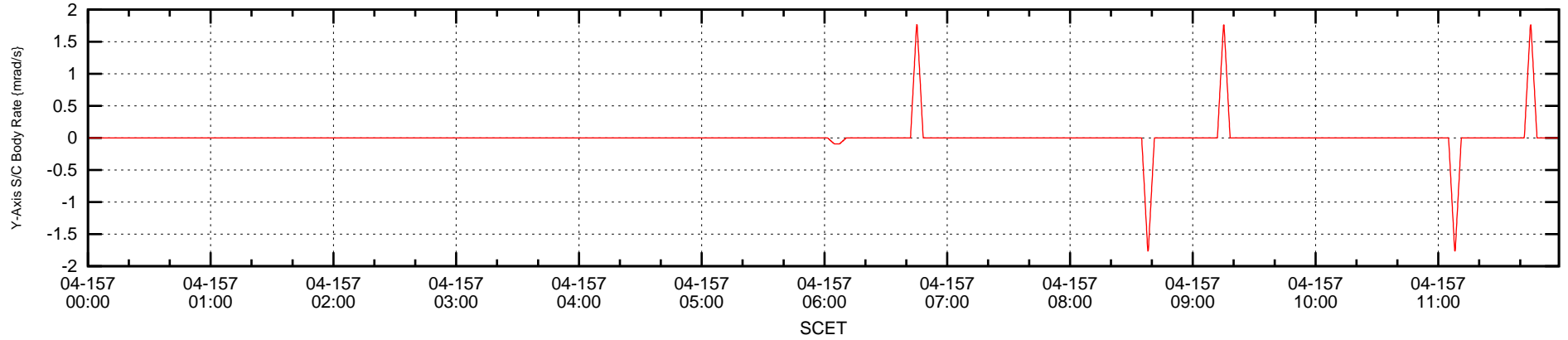


CK #2 S/C Body Rates (DOY 157-157)

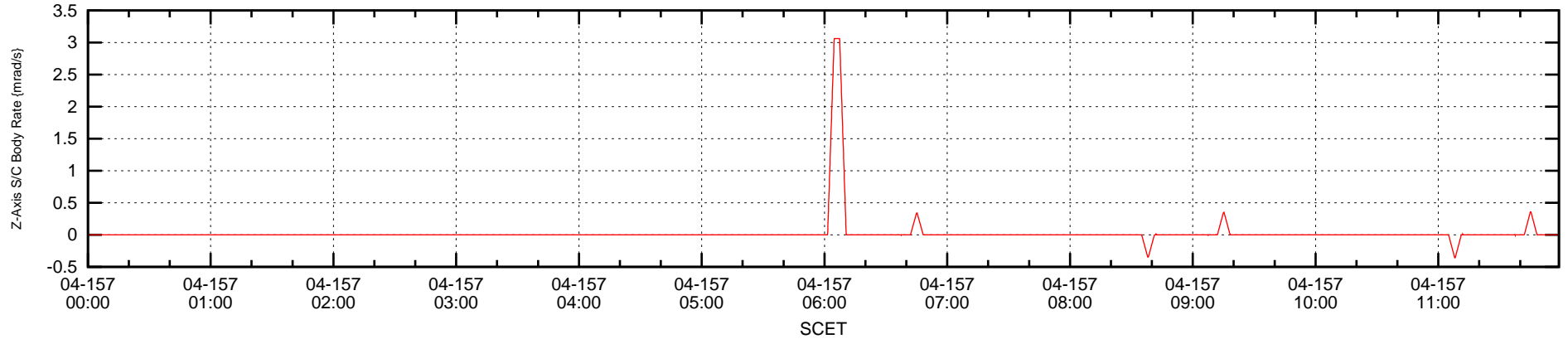
X-Axis (CK #2 = 14135_04171py_as_flowm.bc)



Y-Axis



Z-Axis



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 157-157)

