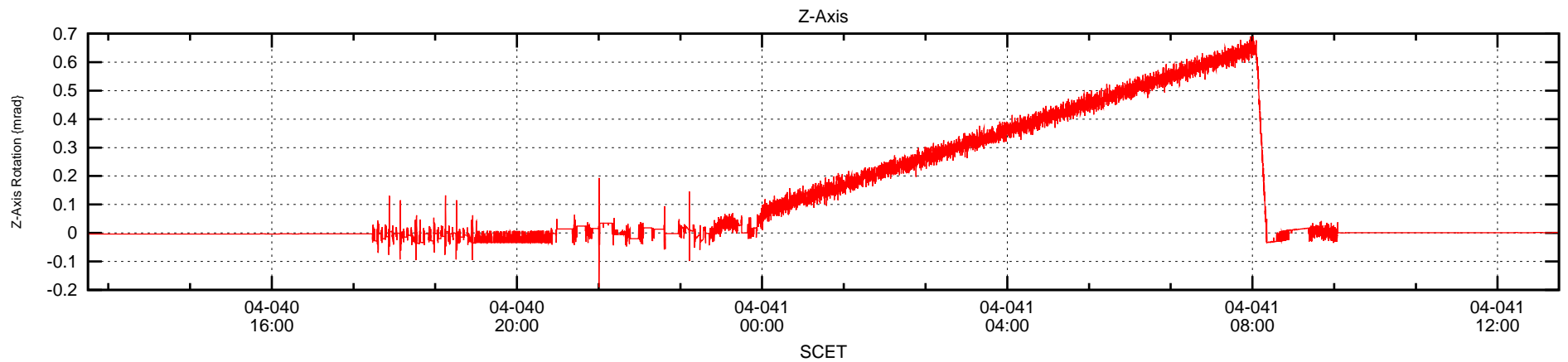
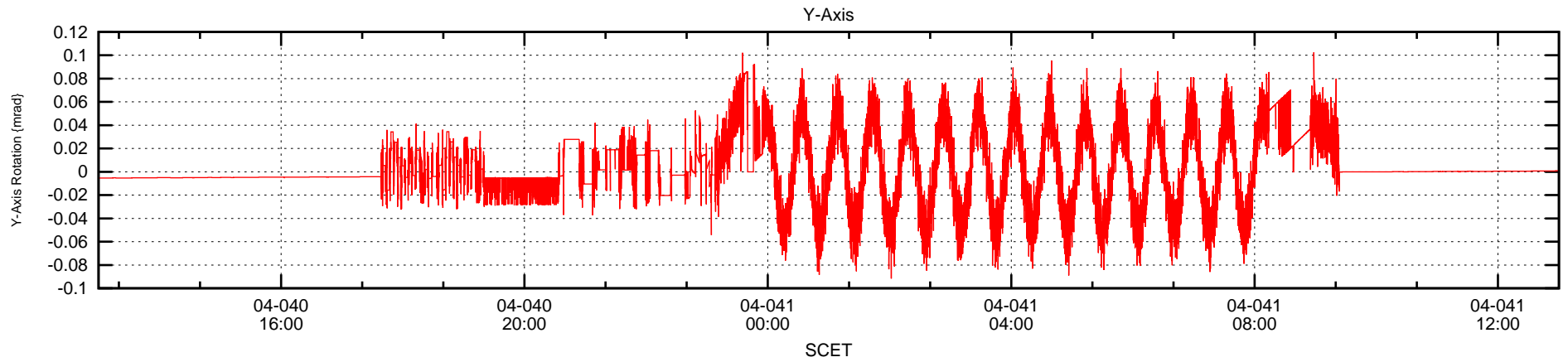
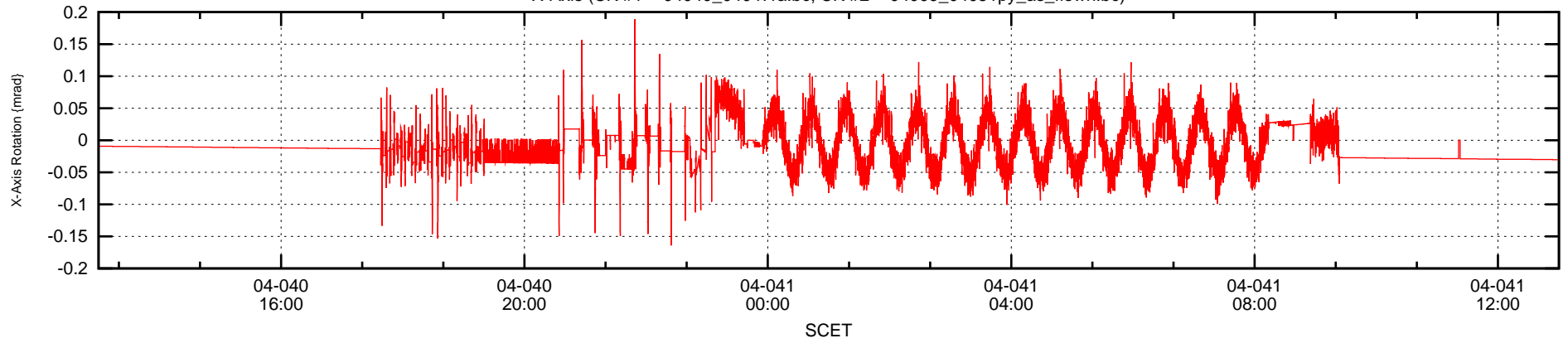


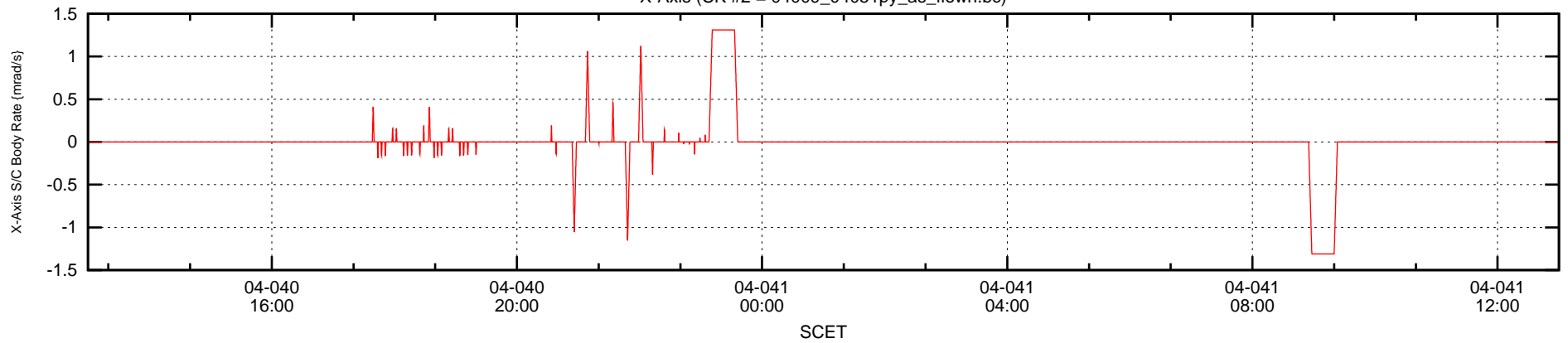
Rotation From CK #2 to CK #1 (DOY 040-041)

X-Axis (CK #1 = 04040_04047ra.bc; CK #2 = 04009_04051py_as_flowm.bc)

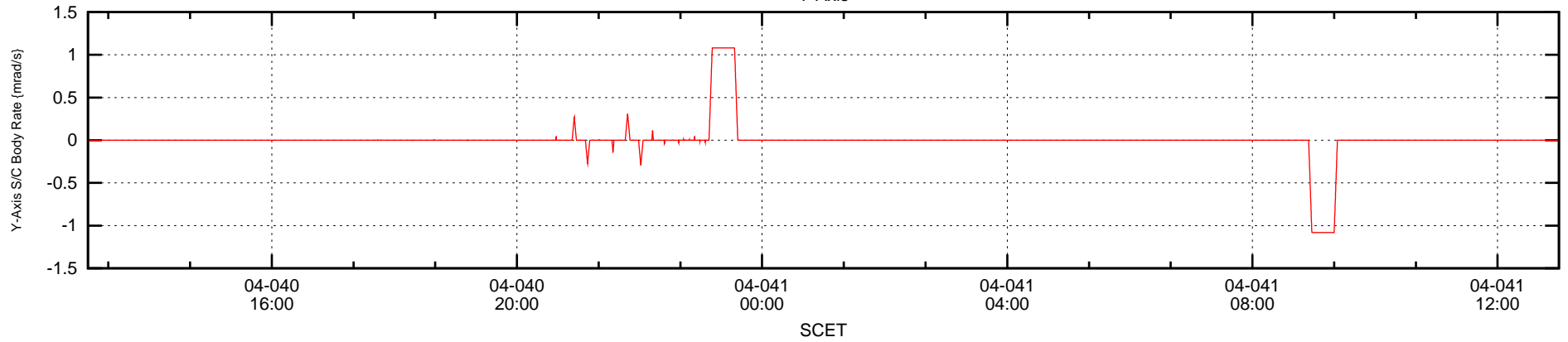


CK #2 S/C Body Rates (DOY 040-041)

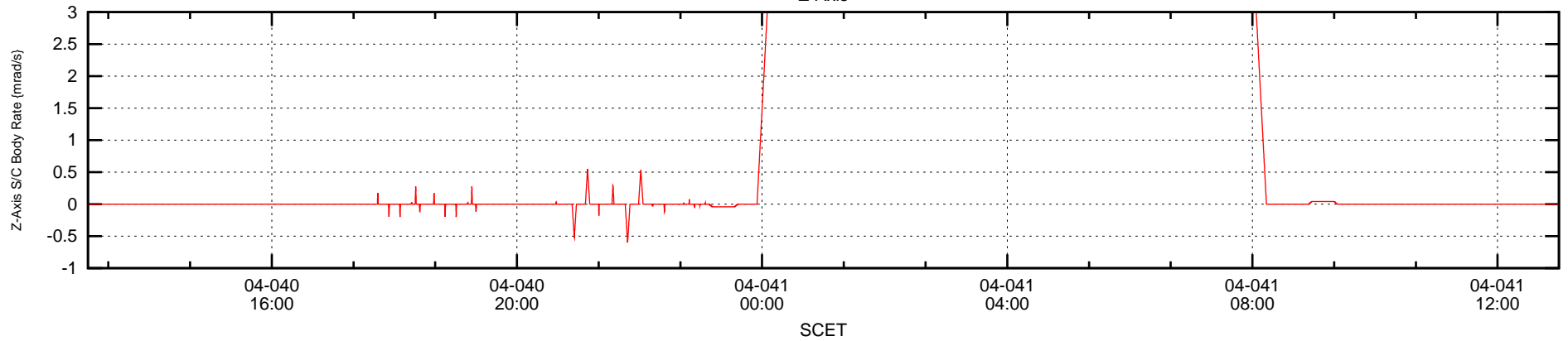
X-Axis (CK #2 = 04009_04051py_as_flown.bc)



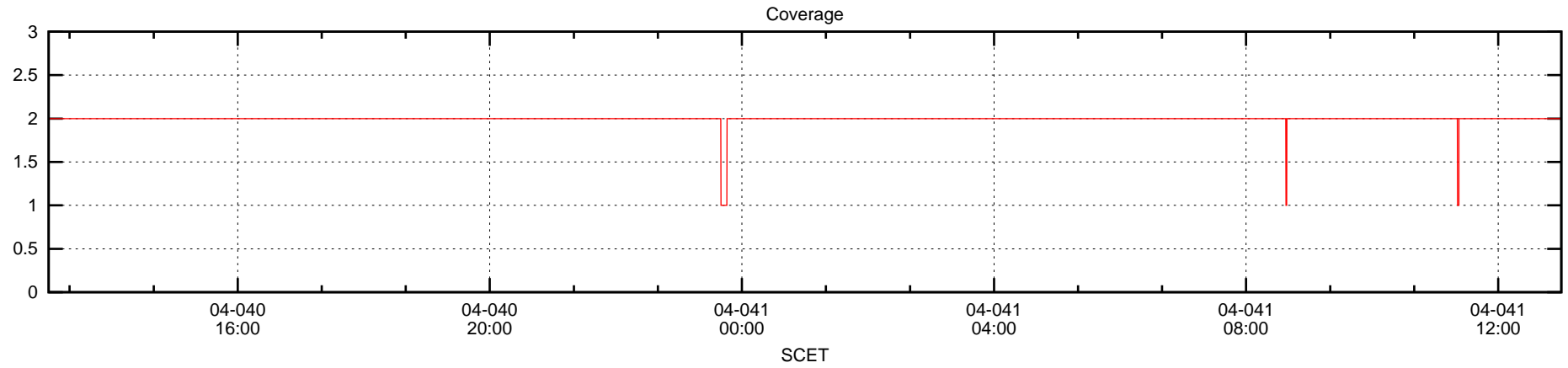
Y-Axis



Z-Axis

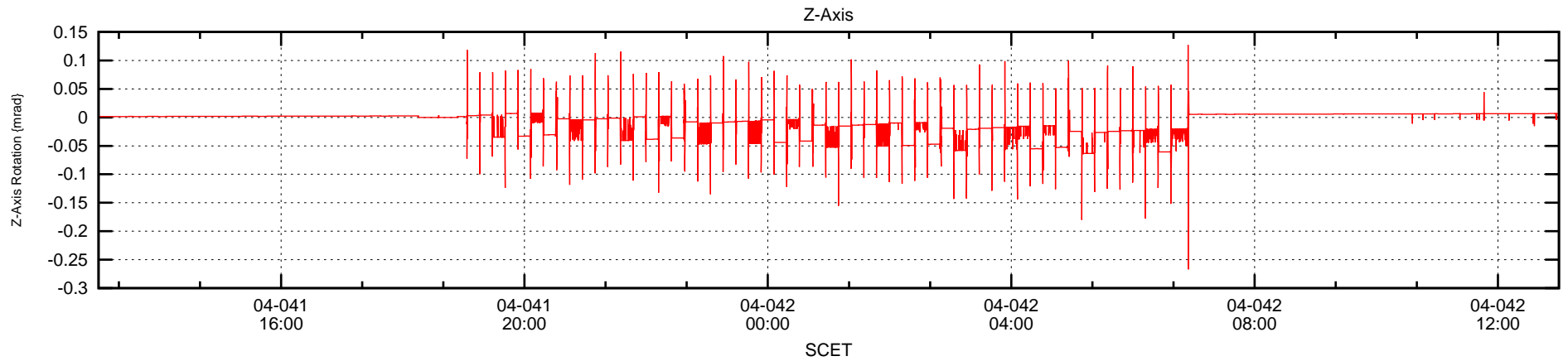
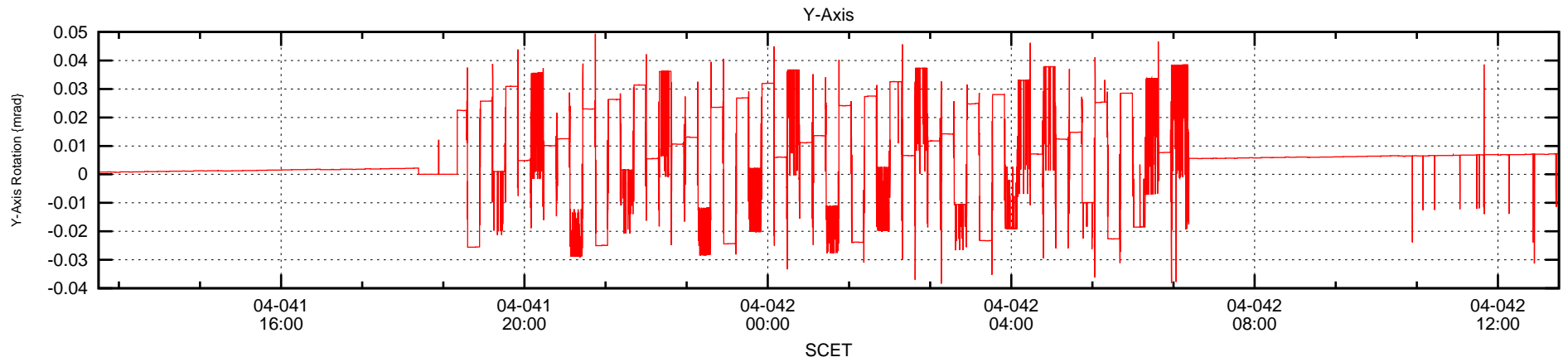
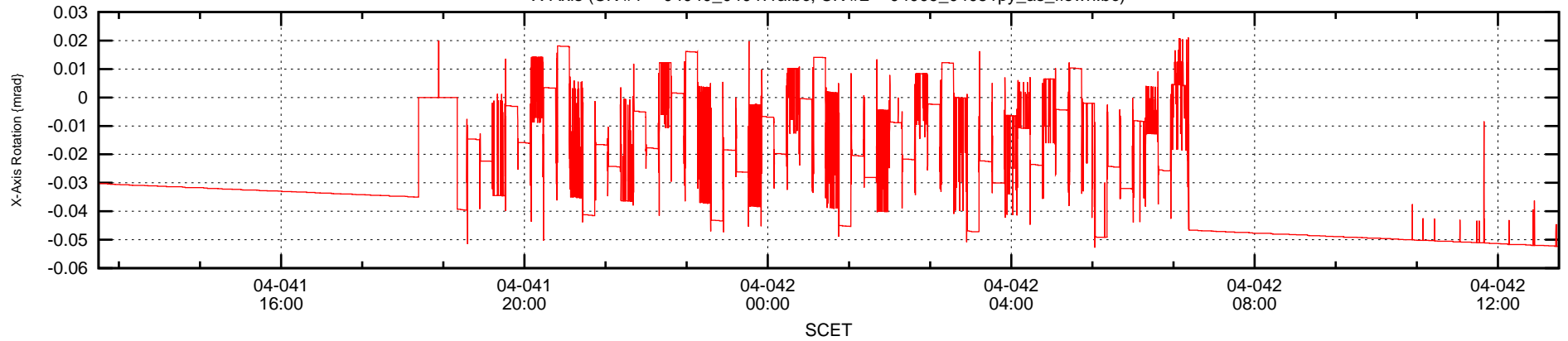


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 040-041)



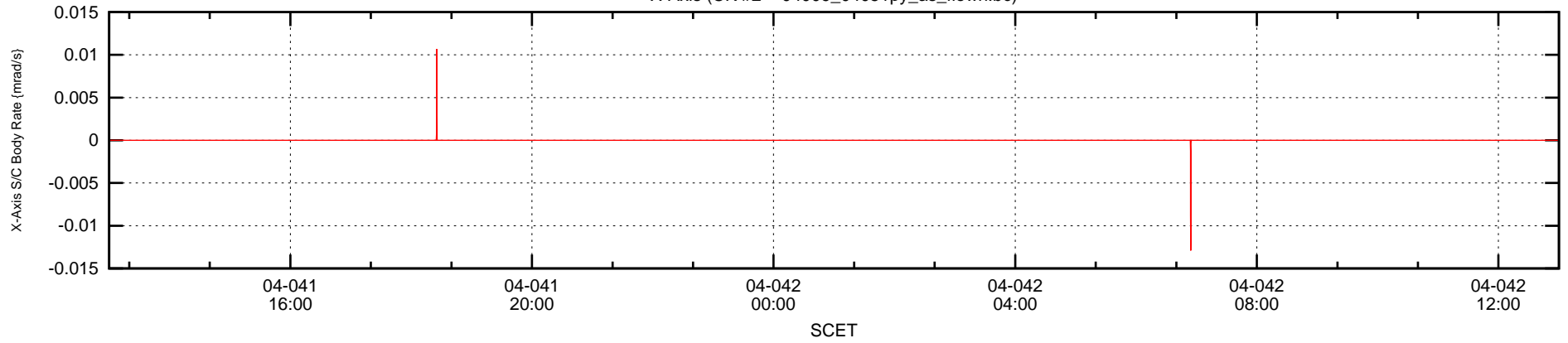
Rotation From CK #2 to CK #1 (DOY 041-042)

X-Axis (CK #1 = 04040_04047ra.bc; CK #2 = 04009_04051py_as_flown.bc)

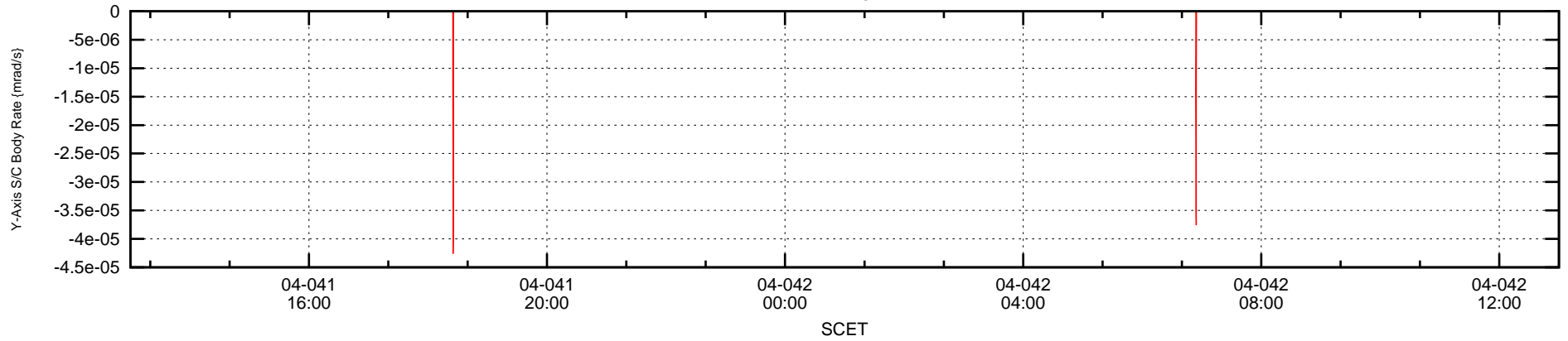


CK #2 S/C Body Rates (DOY 041-042)

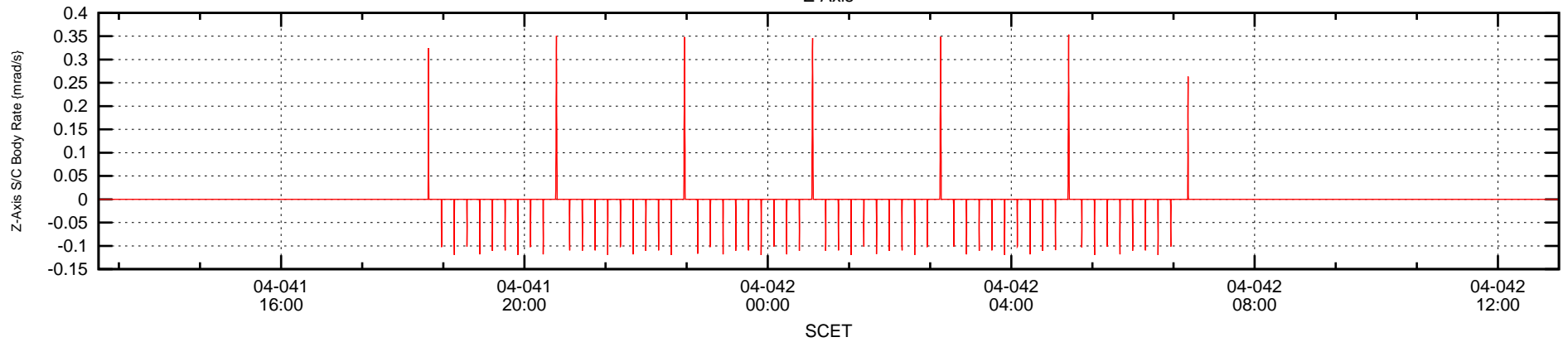
X-Axis (CK #2 = 04009_04051py_as_flowm.bc)



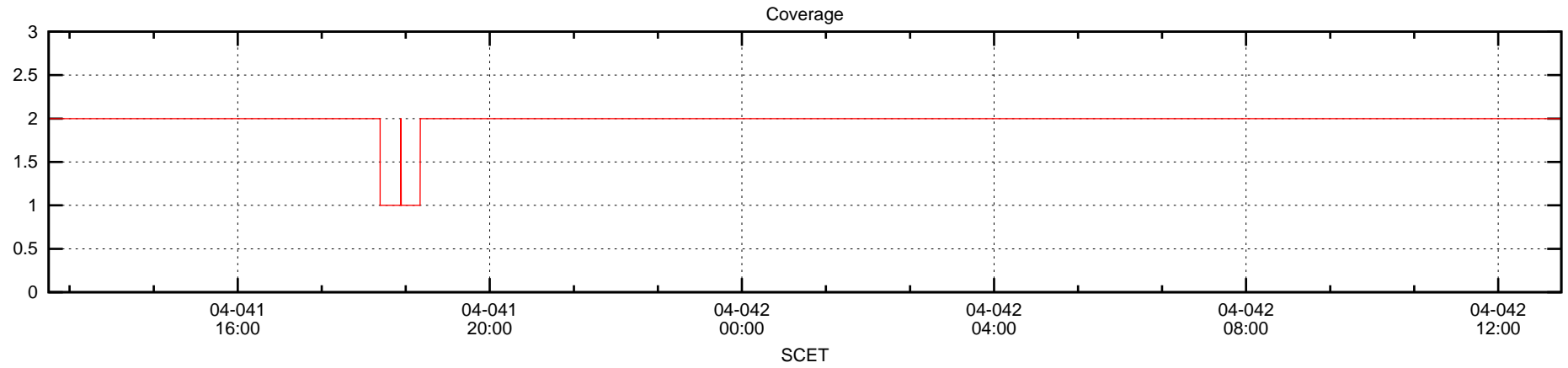
Y-Axis



Z-Axis

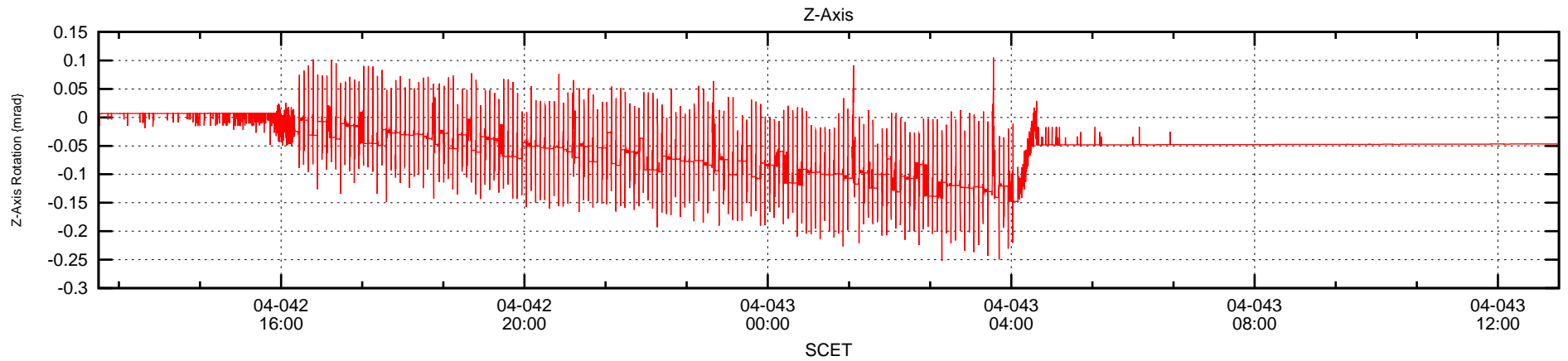
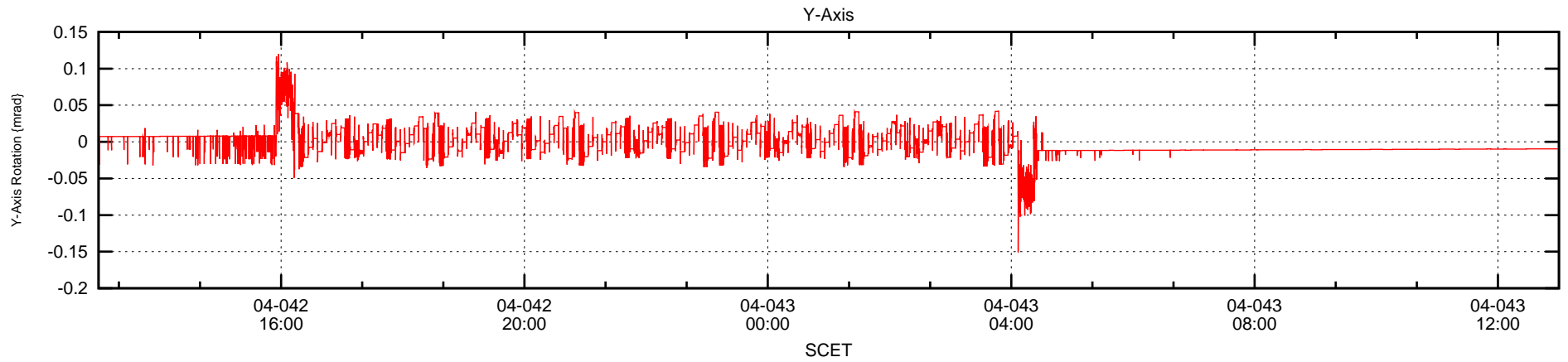
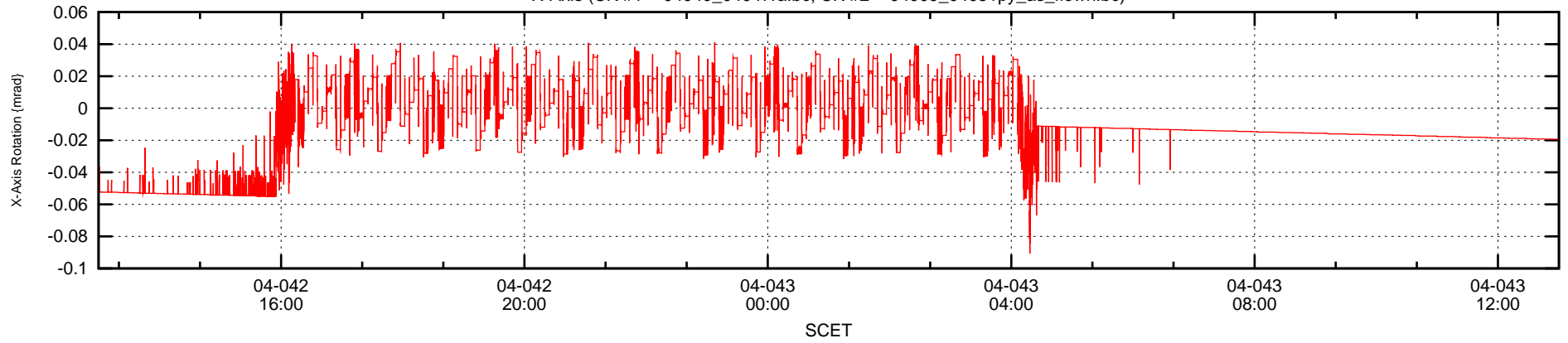


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 041-042)



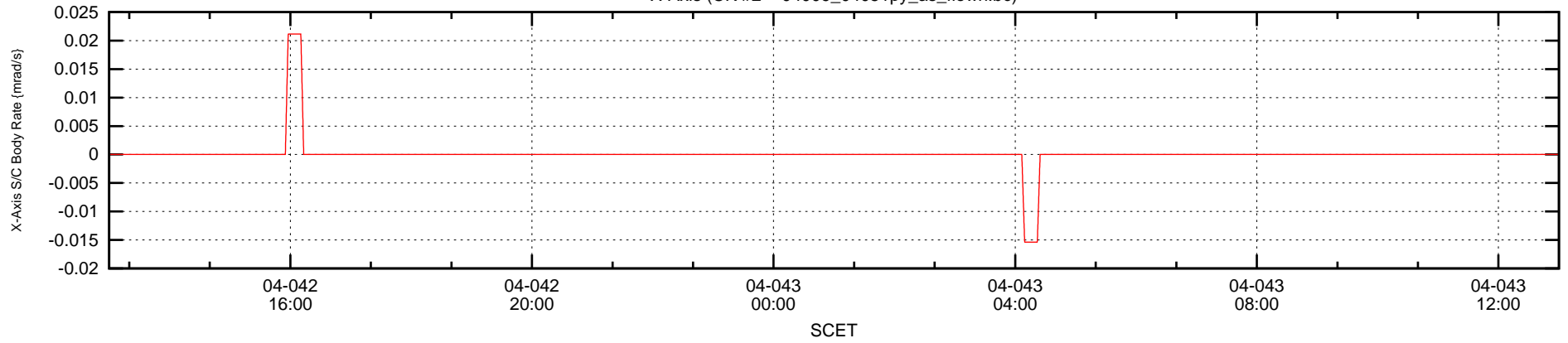
Rotation From CK #2 to CK #1 (DOY 042-043)

X-Axis (CK #1 = 04040_04047ra.bc; CK #2 = 04009_04051py_as_flowm.bc)

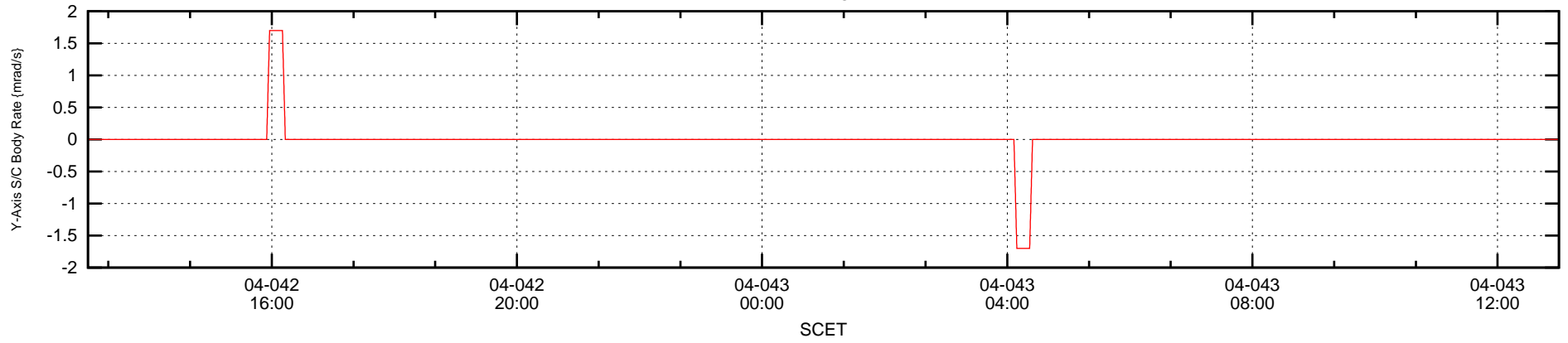


CK #2 S/C Body Rates (DOY 042-043)

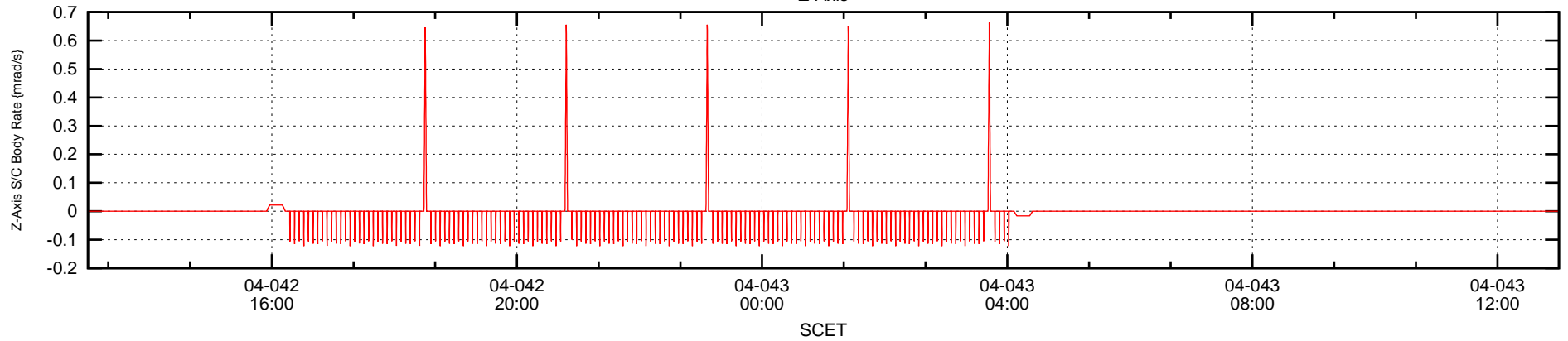
X-Axis (CK #2 = 04009_04051py_as_flowm.bc)



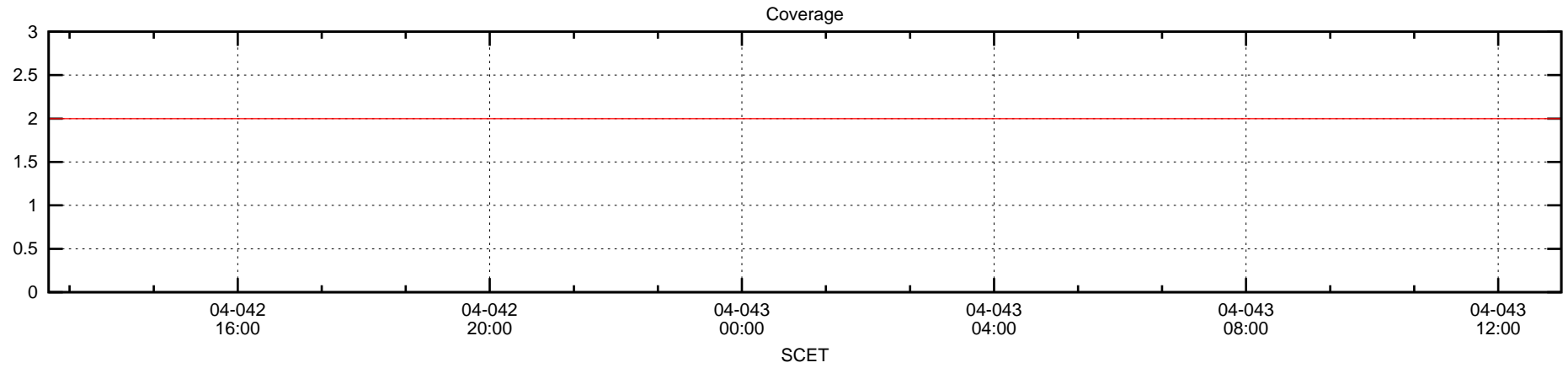
Y-Axis



Z-Axis

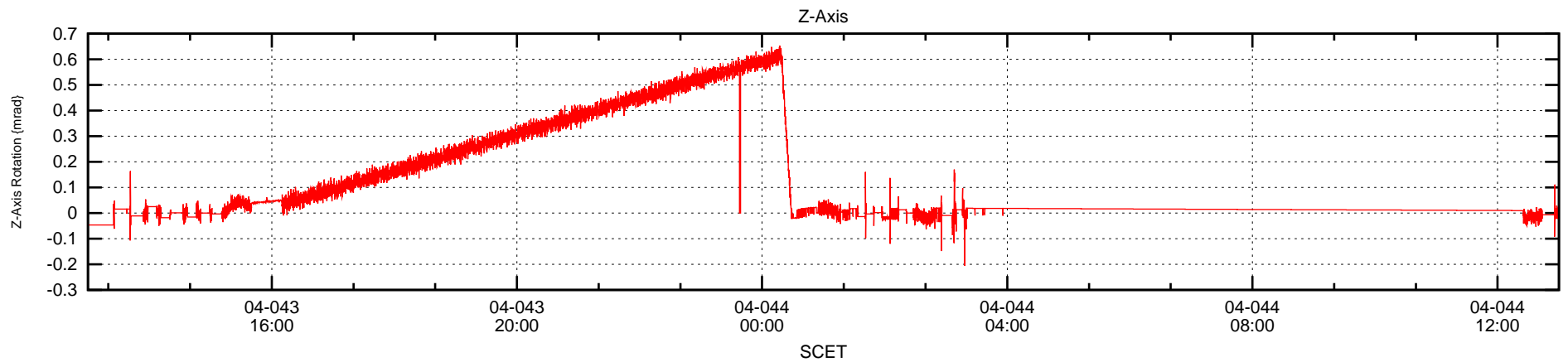
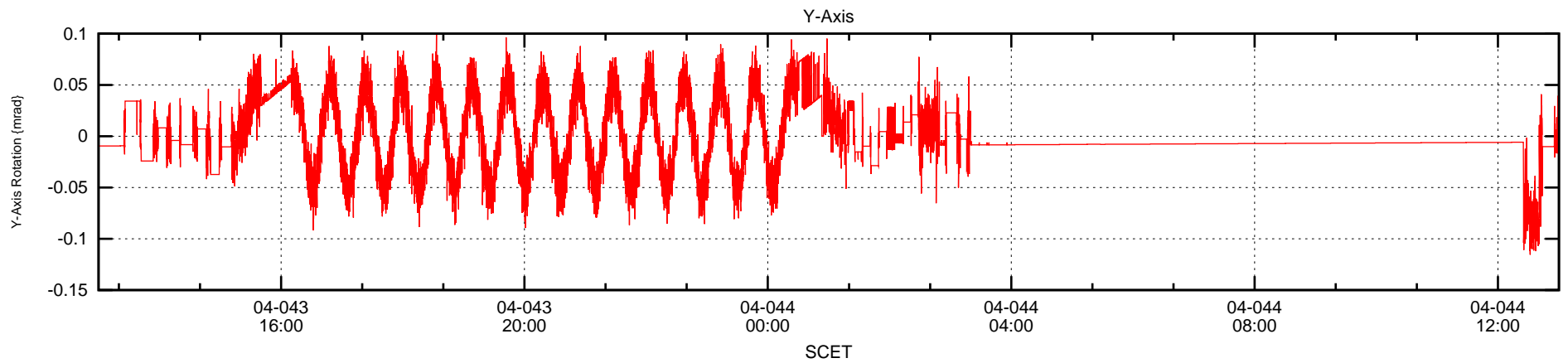
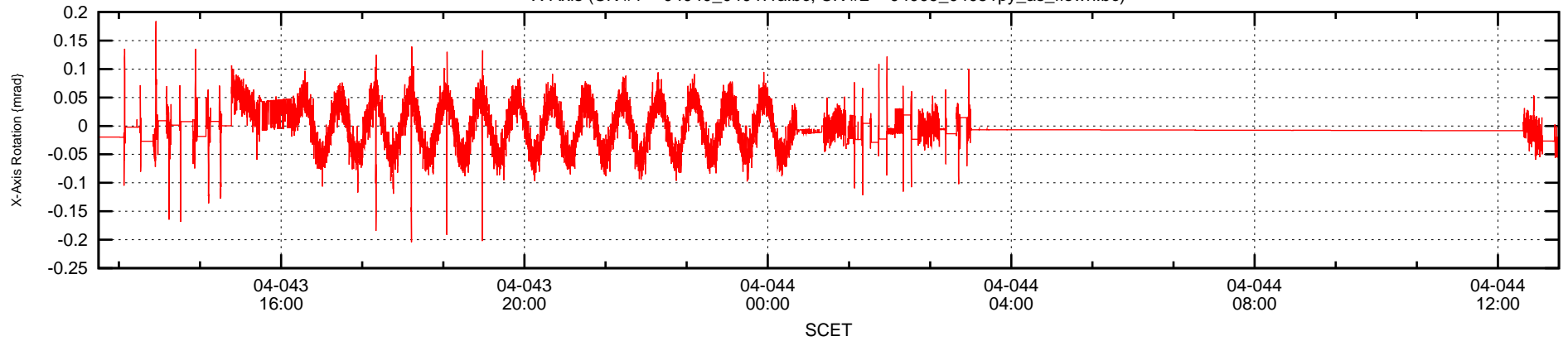


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 042-043)



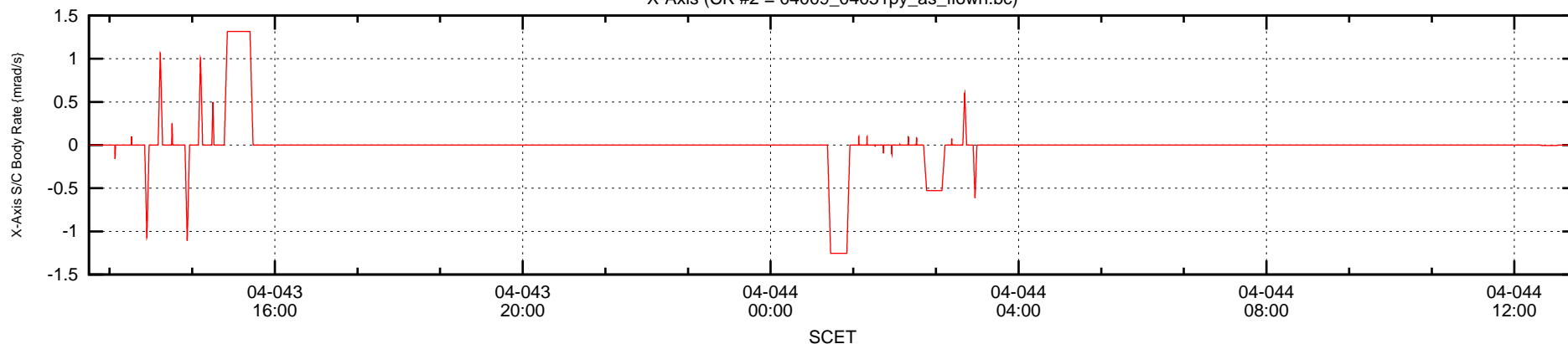
Rotation From CK #2 to CK #1 (DOY 043-044)

X-Axis (CK #1 = 04040_04047ra.bc; CK #2 = 04009_04051py_as_flowm.bc)

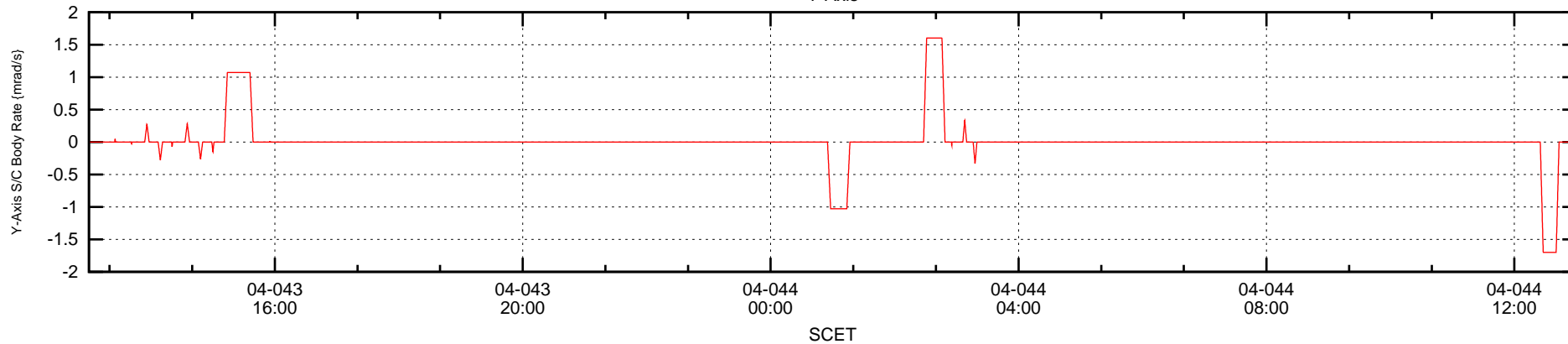


CK #2 S/C Body Rates (DOY 043-044)

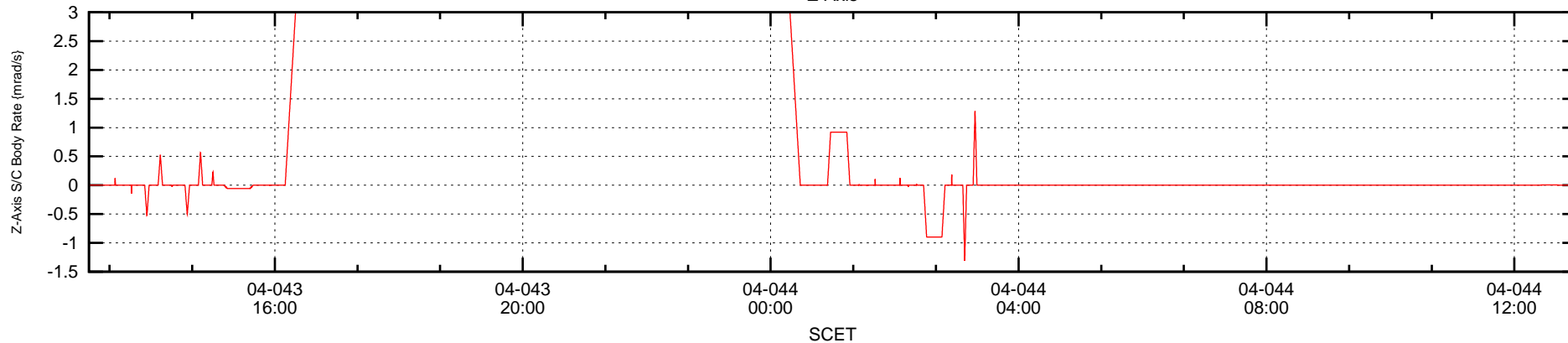
X-Axis (CK #2 = 04009_04051py_as_flowm.bc)



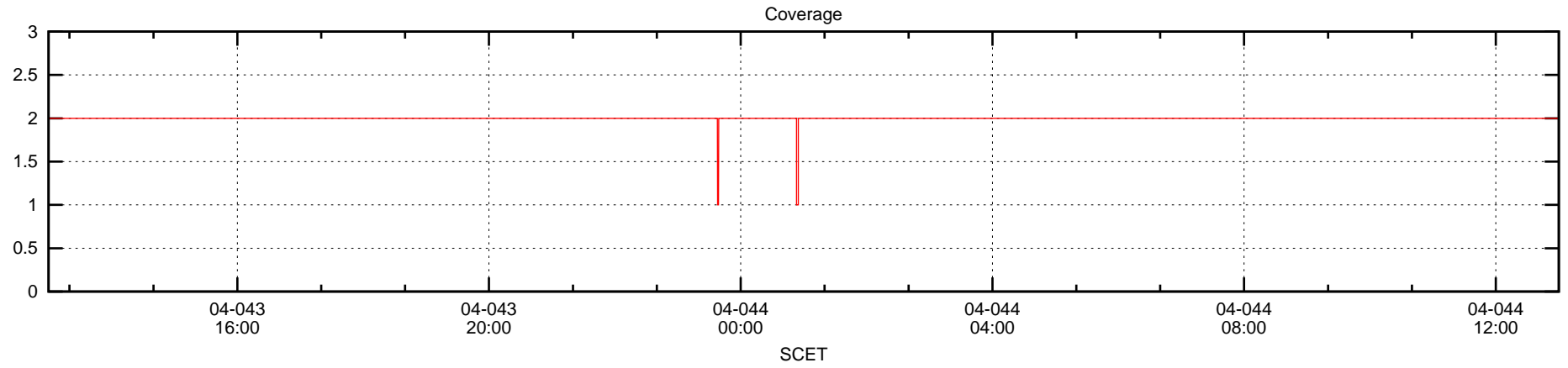
Y-Axis



Z-Axis

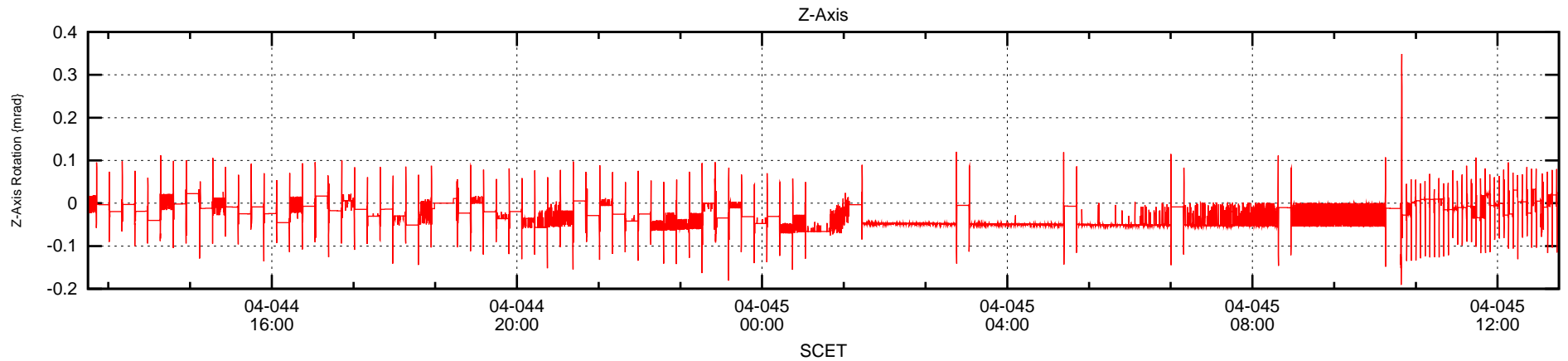
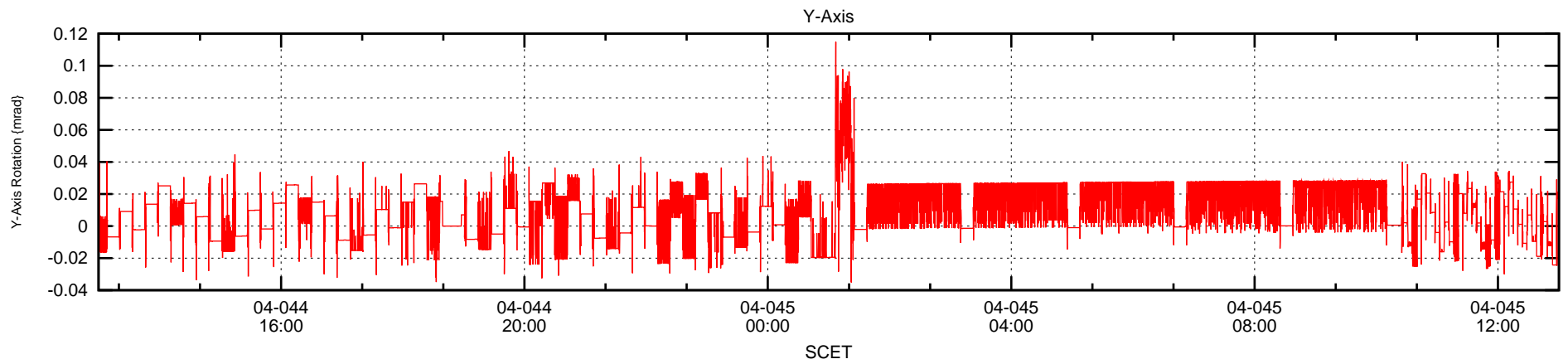
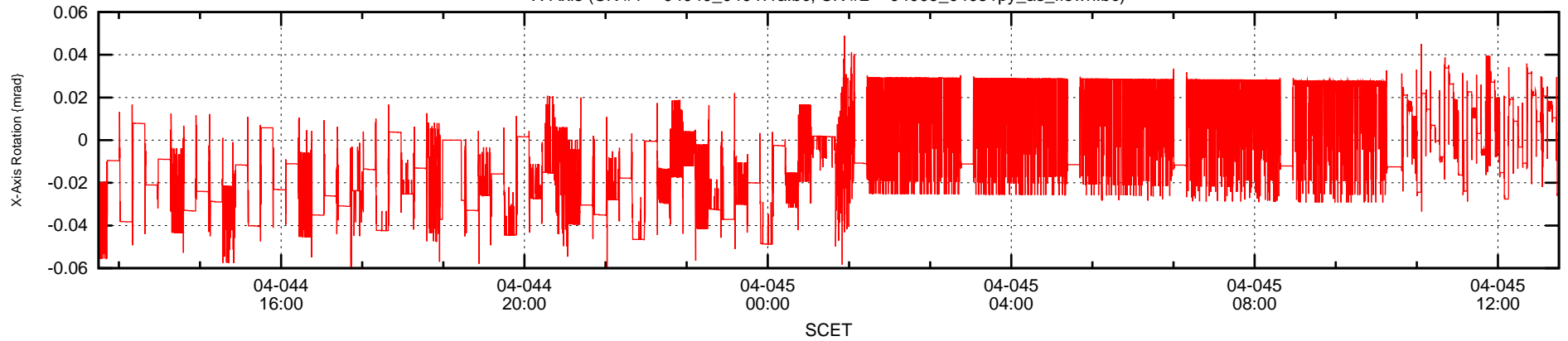


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 043-044)



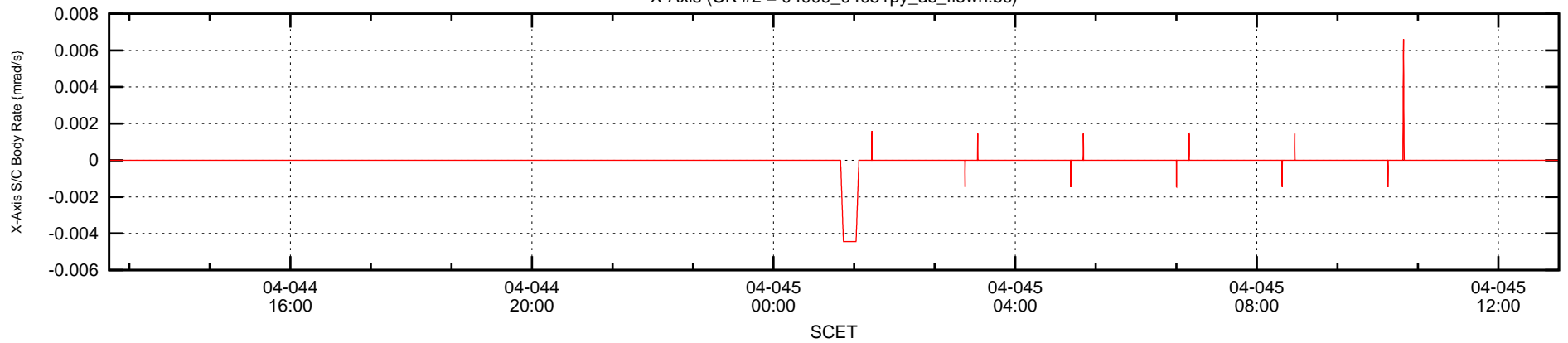
Rotation From CK #2 to CK #1 (DOY 044-045)

X-Axis (CK #1 = 04040_04047ra.bc; CK #2 = 04009_04051py_as_flowm.bc)

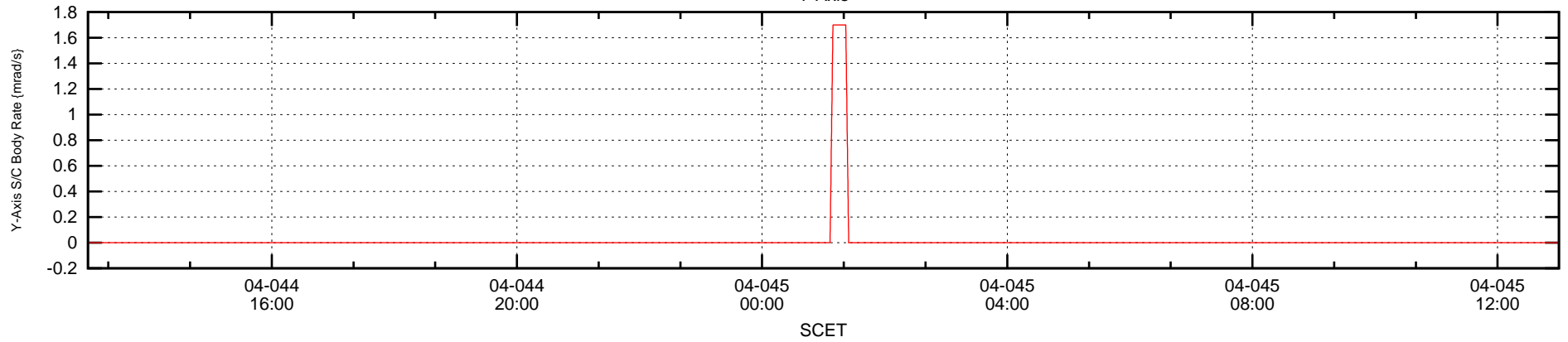


CK #2 S/C Body Rates (DOY 044-045)

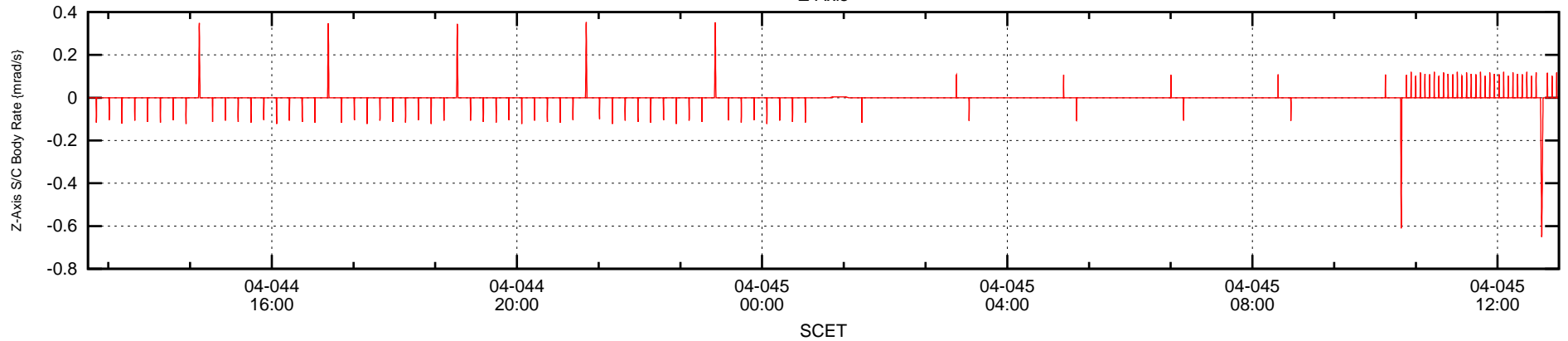
X-Axis (CK #2 = 04009_04051py_as_flowm.bc)



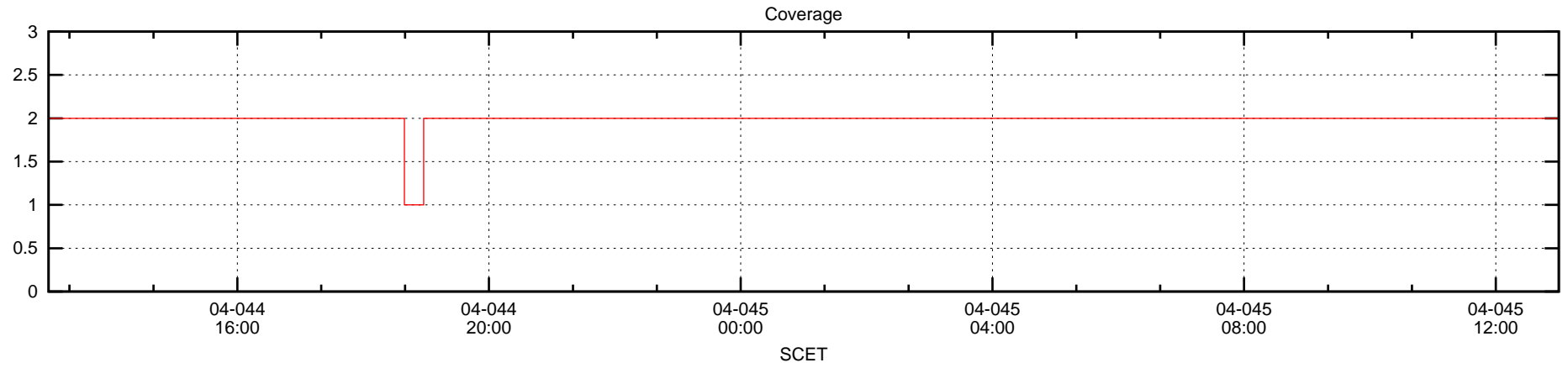
Y-Axis



Z-Axis

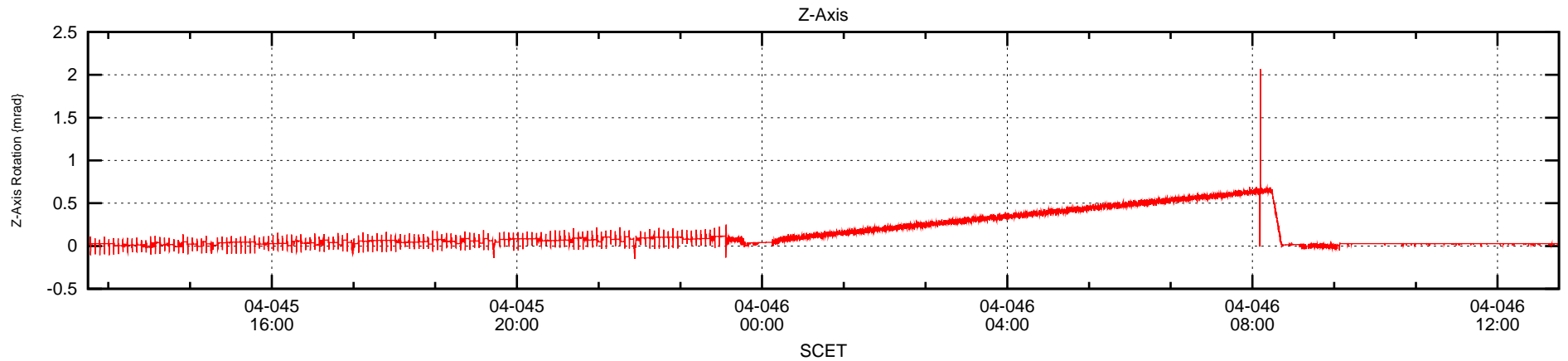
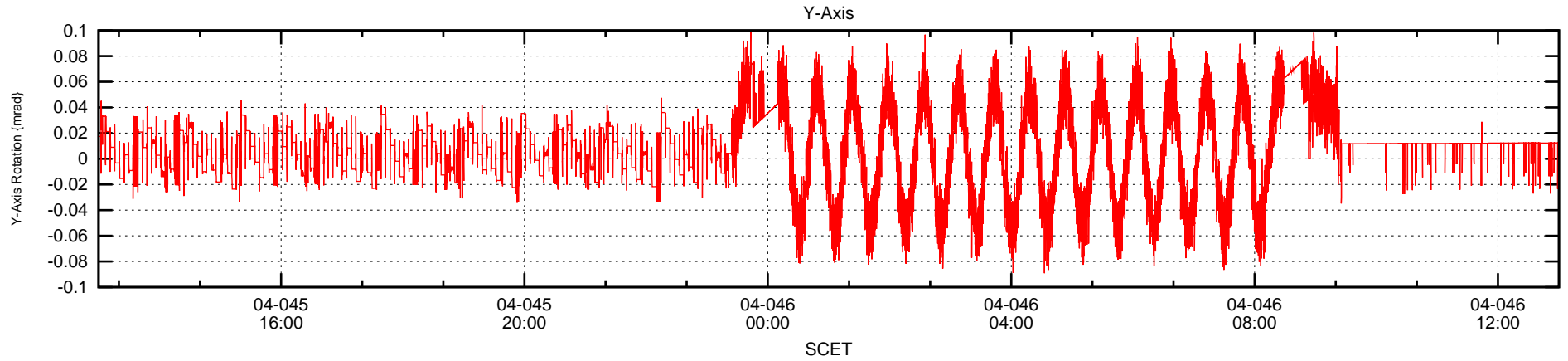
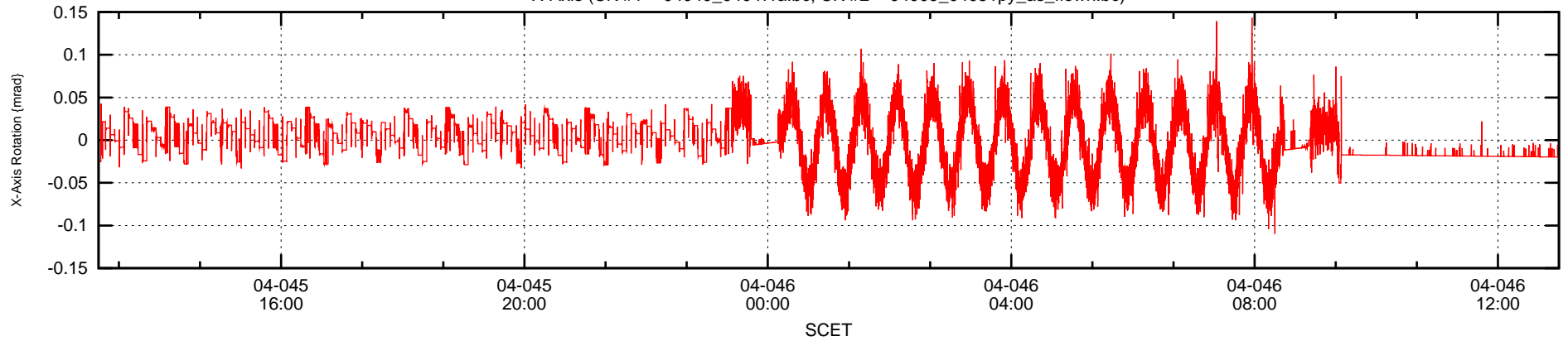


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 044-045)



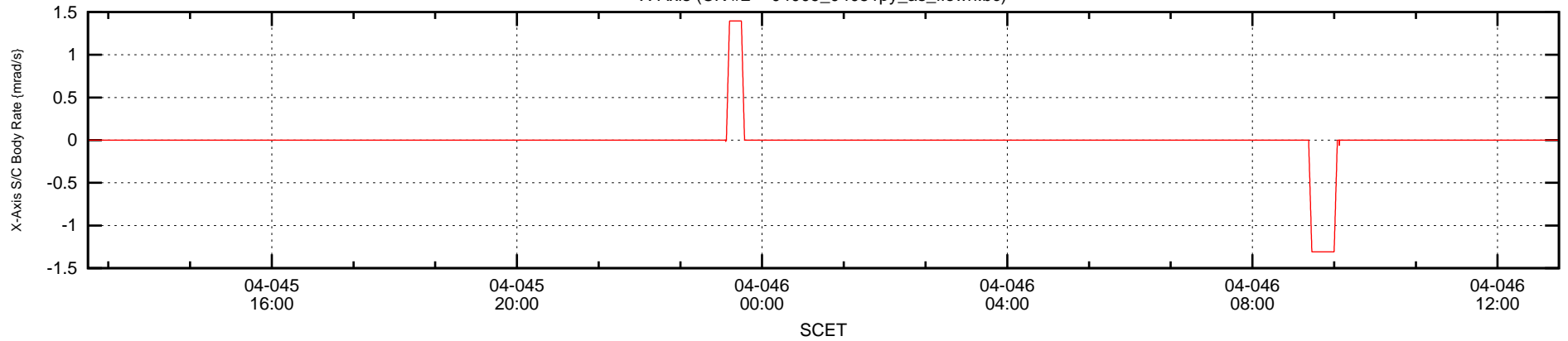
Rotation From CK #2 to CK #1 (DOY 045-046)

X-Axis (CK #1 = 04040_04047ra.bc; CK #2 = 04009_04051py_as_flowm.bc)

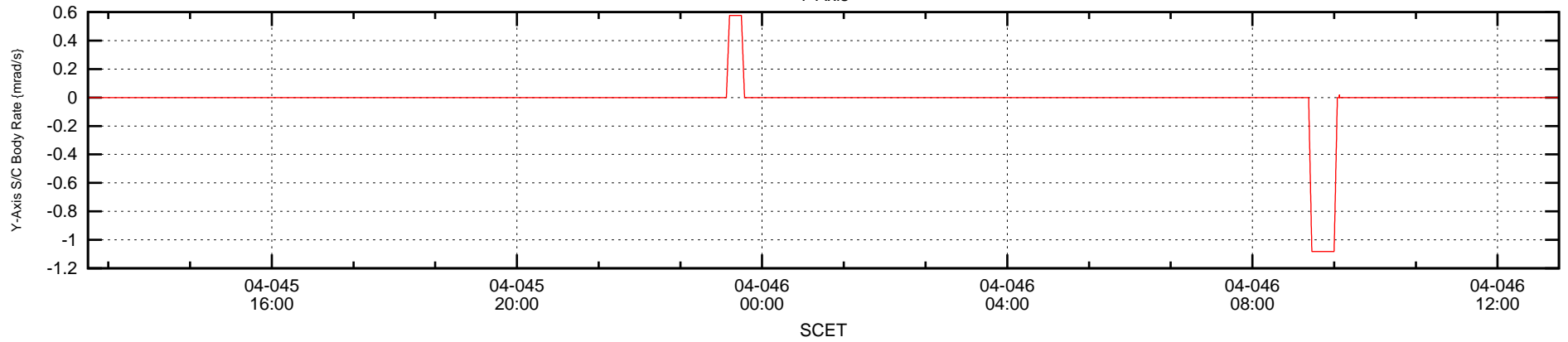


CK #2 S/C Body Rates (DOY 045-046)

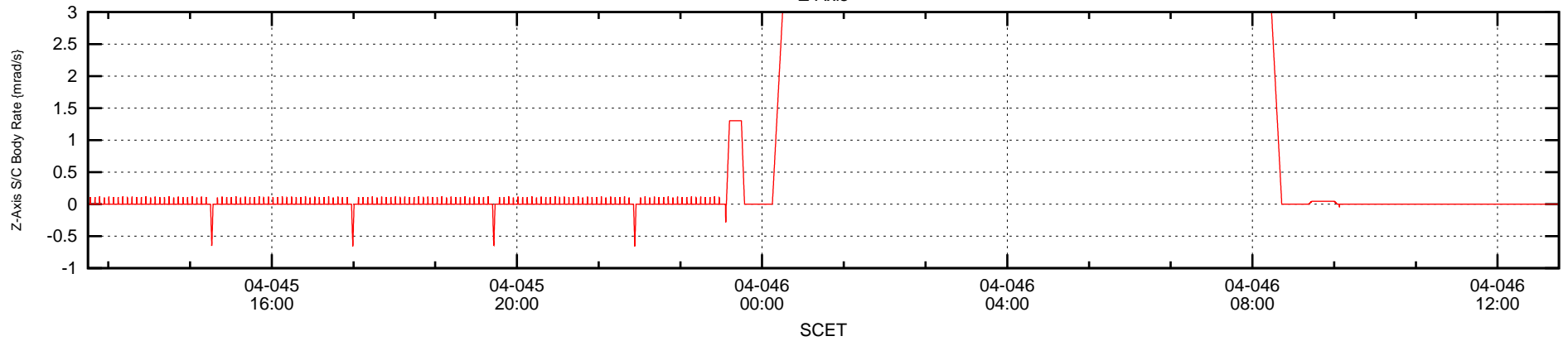
X-Axis (CK #2 = 04009_04051py_as_flown.bc)



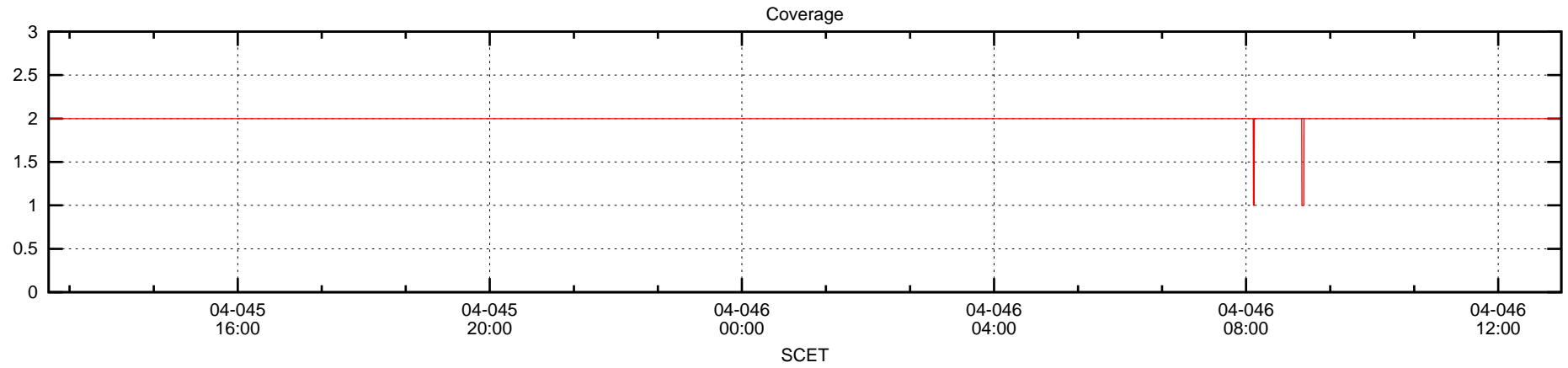
Y-Axis



Z-Axis

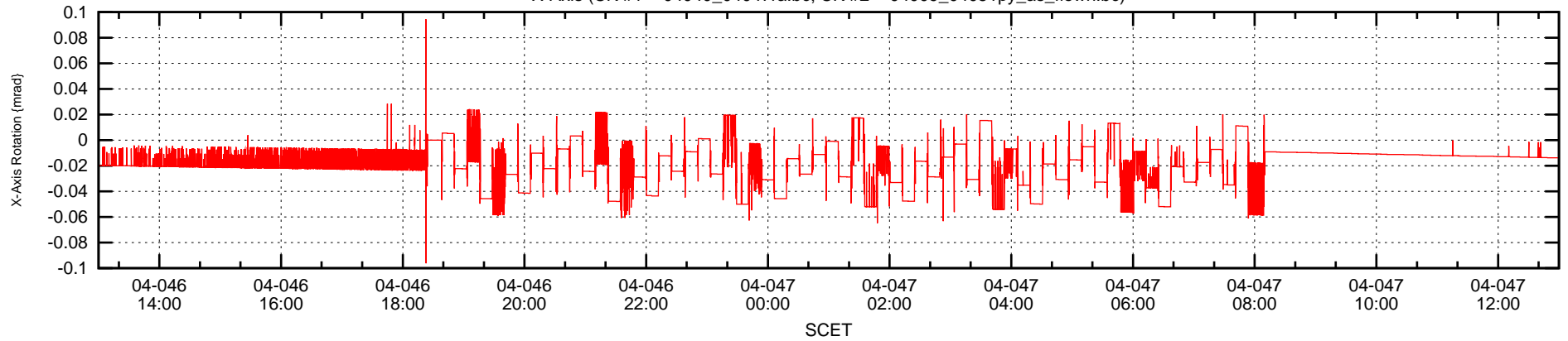


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 045-046)

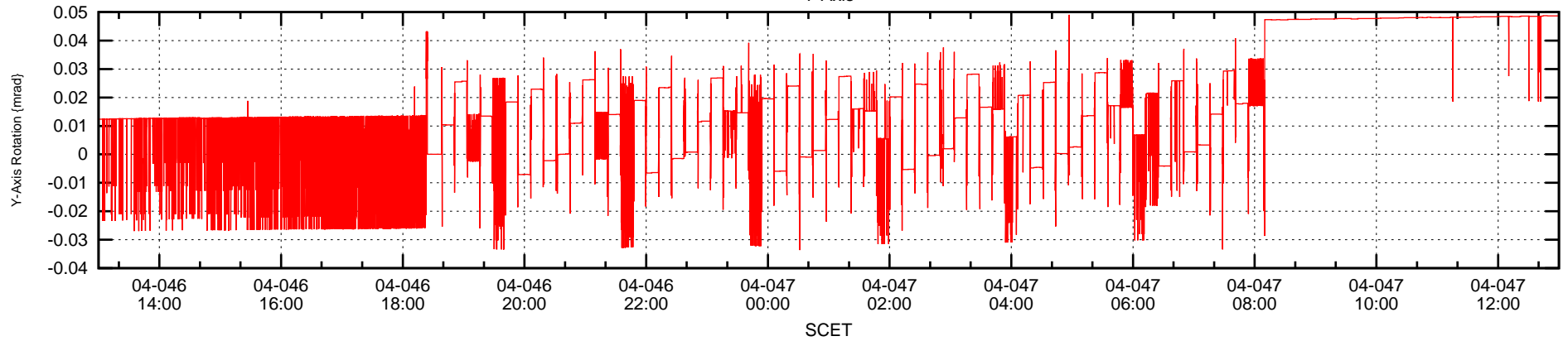


Rotation From CK #2 to CK #1 (DOY 046-047)

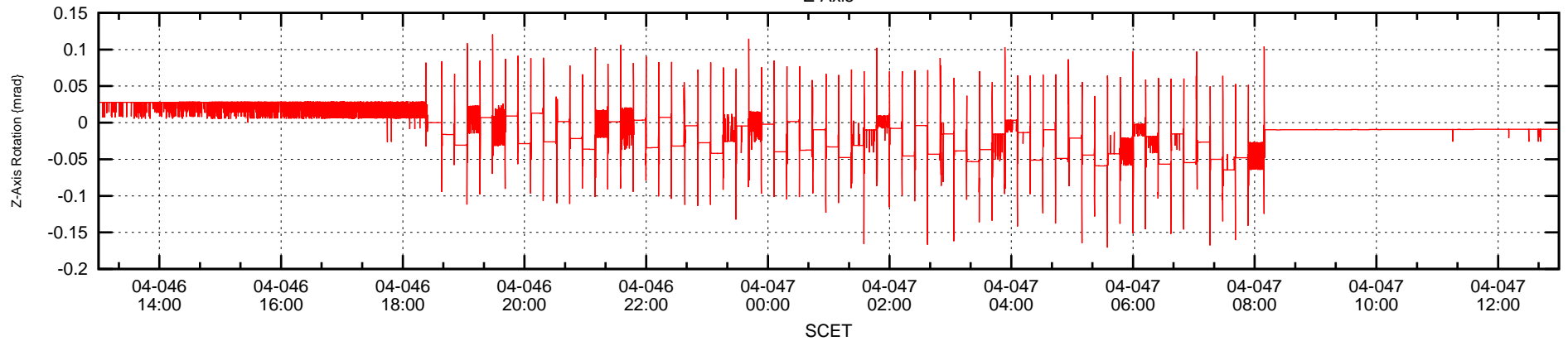
X-Axis (CK #1 = 04040_04047ra.bc; CK #2 = 04009_04051py_as_flown.bc)



Y-Axis

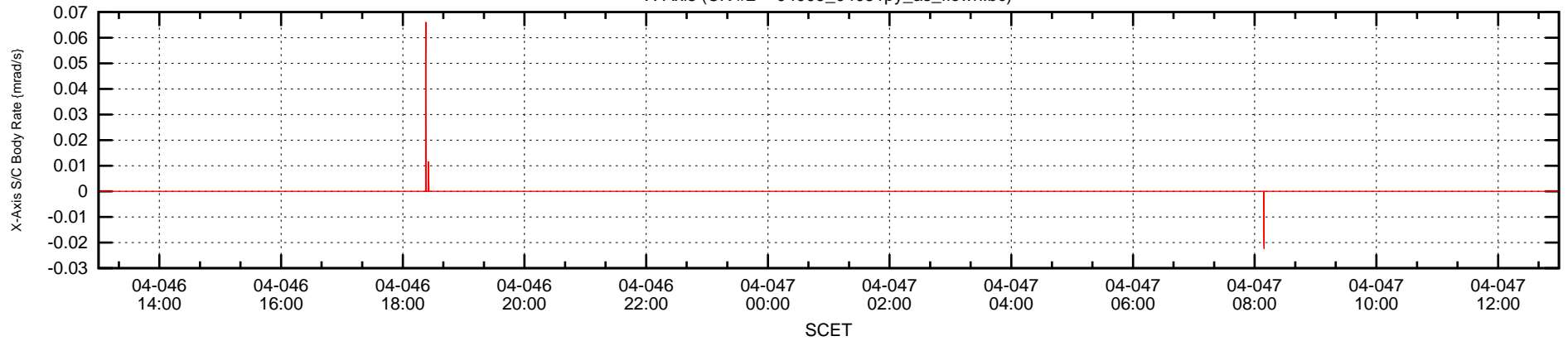


Z-Axis

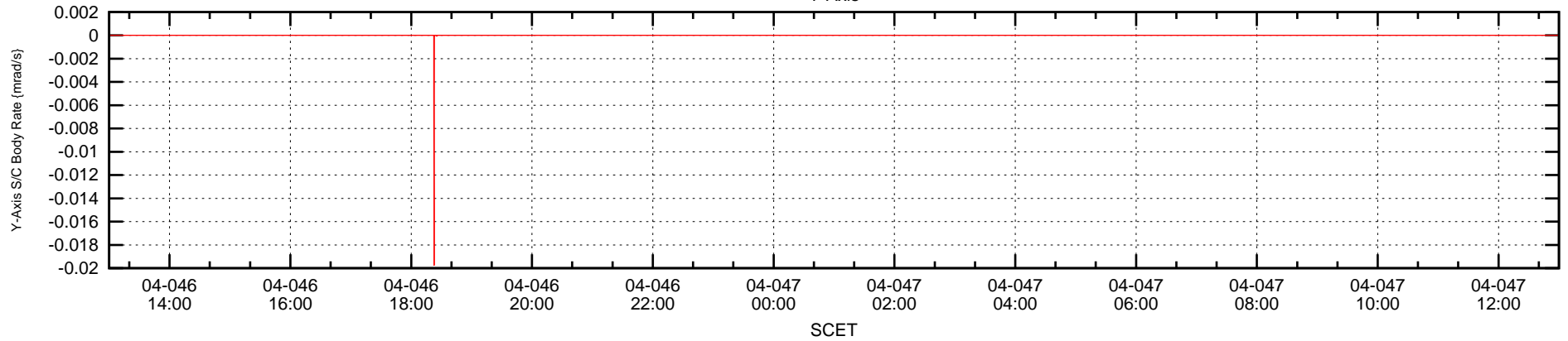


CK #2 S/C Body Rates (DOY 046-047)

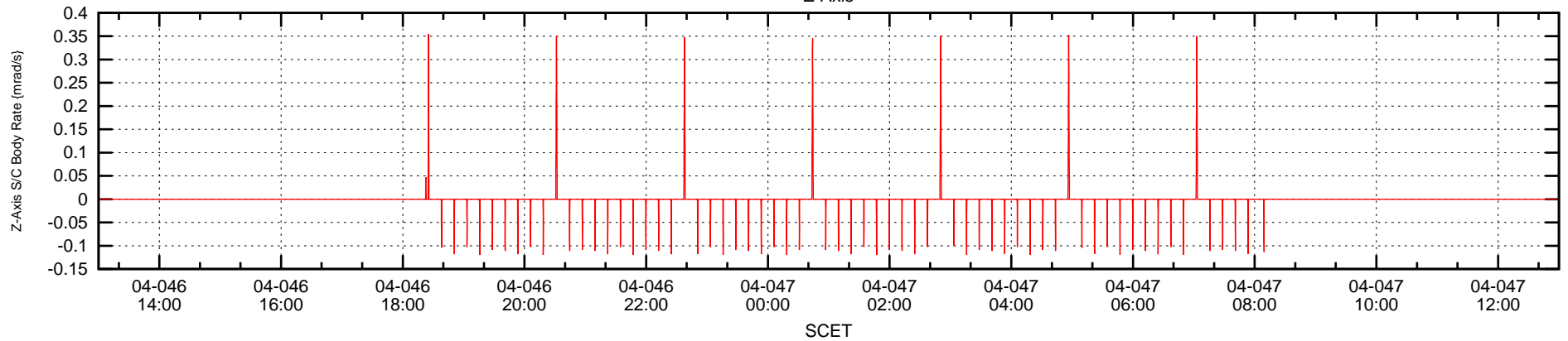
X-Axis (CK #2 = 04009_04051py_as_flown.bc)



Y-Axis



Z-Axis



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 046-047)

