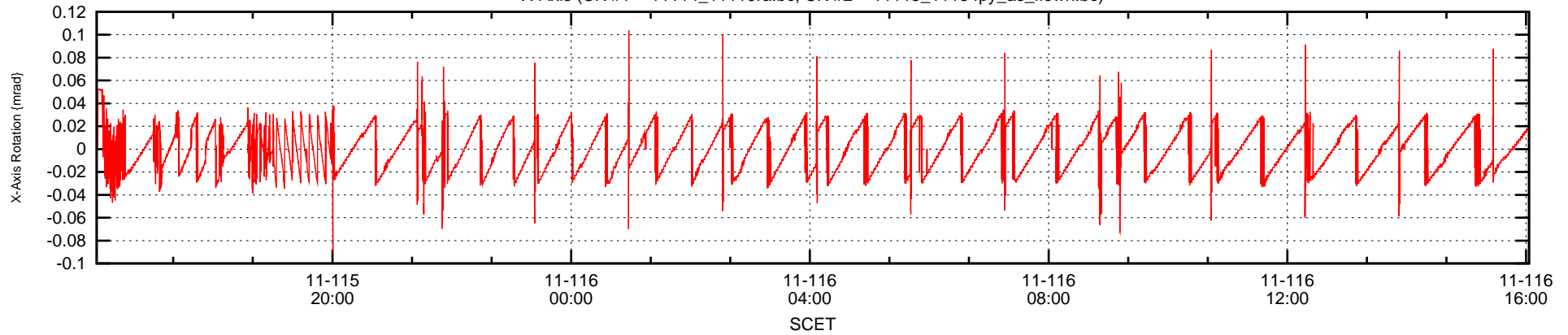
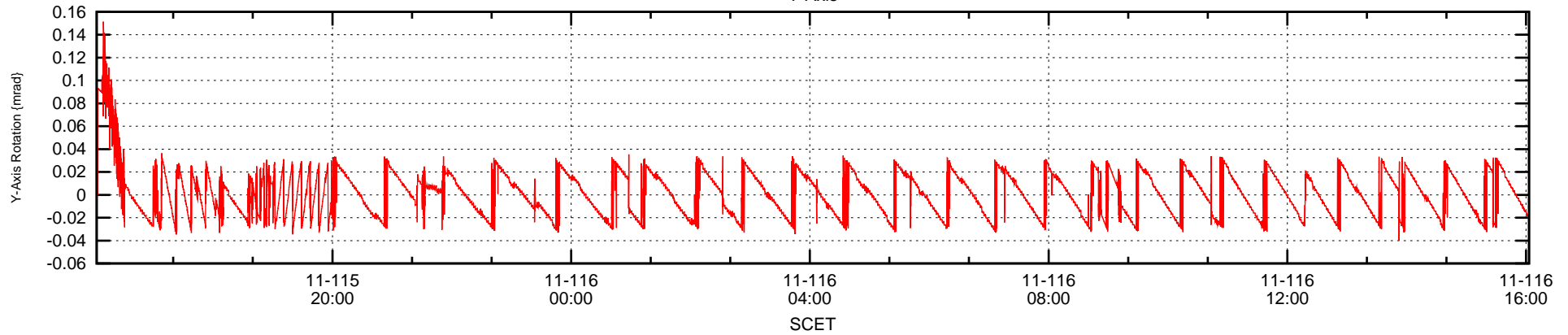


# Rotation From CK #2 to CK #1 (DOY 115-116)

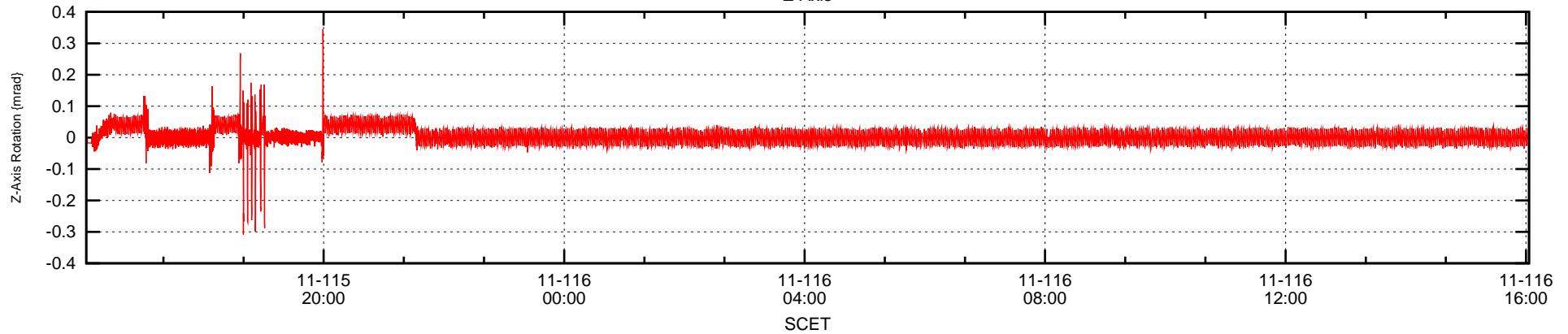
X-Axis (CK #1 = 11114\_11119ra.bc; CK #2 = 11115\_11184py\_as\_flown.bc)



Y-Axis

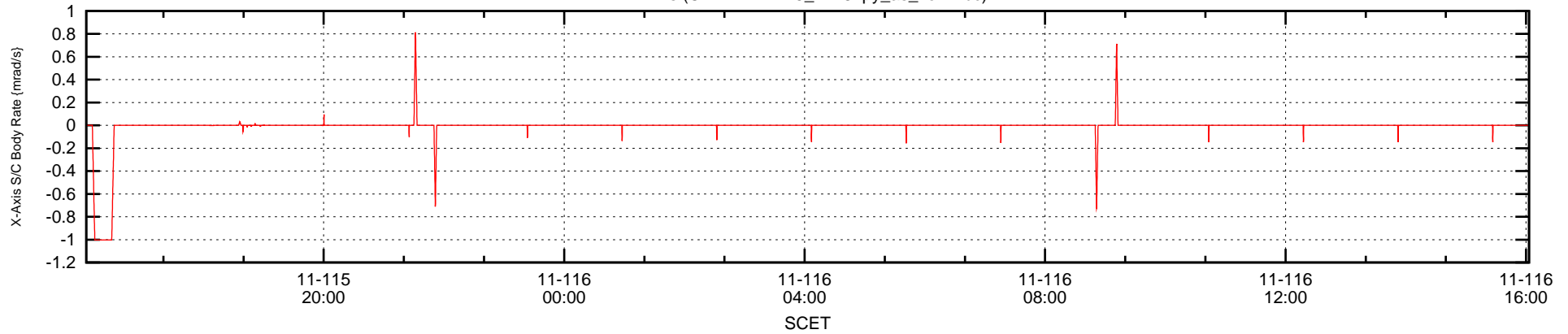


Z-Axis

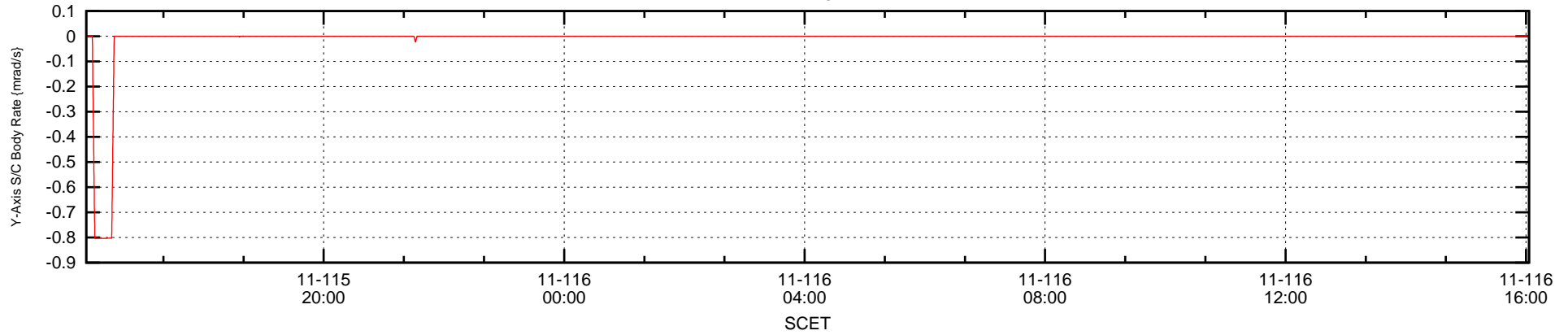


# CK #2 S/C Body Rates (DOY 115-116)

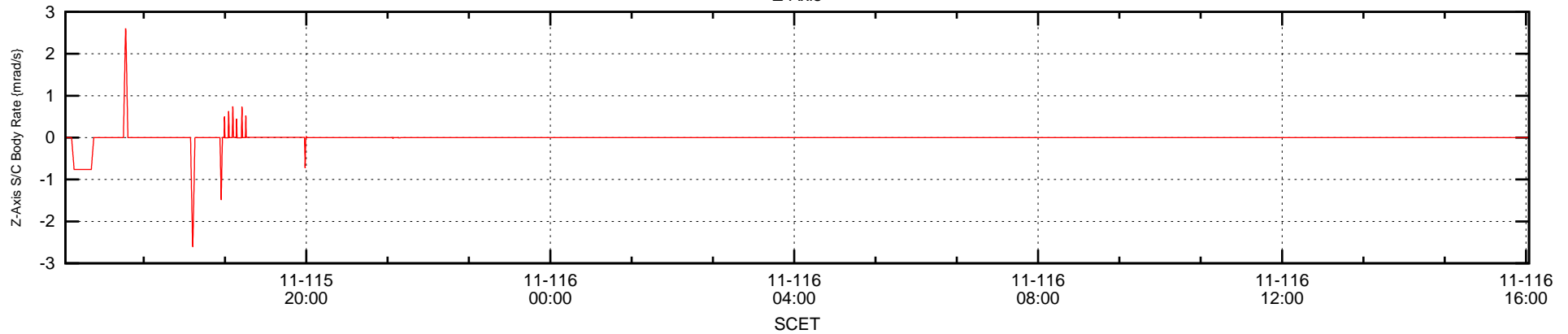
X-Axis (CK #2 = 11115\_11184py\_as\_flowm.bc)



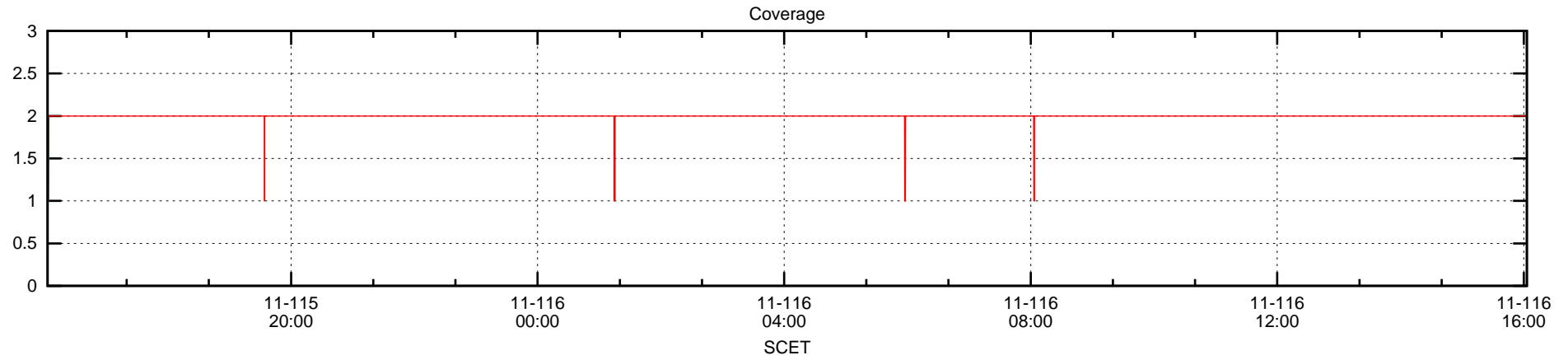
Y-Axis



Z-Axis

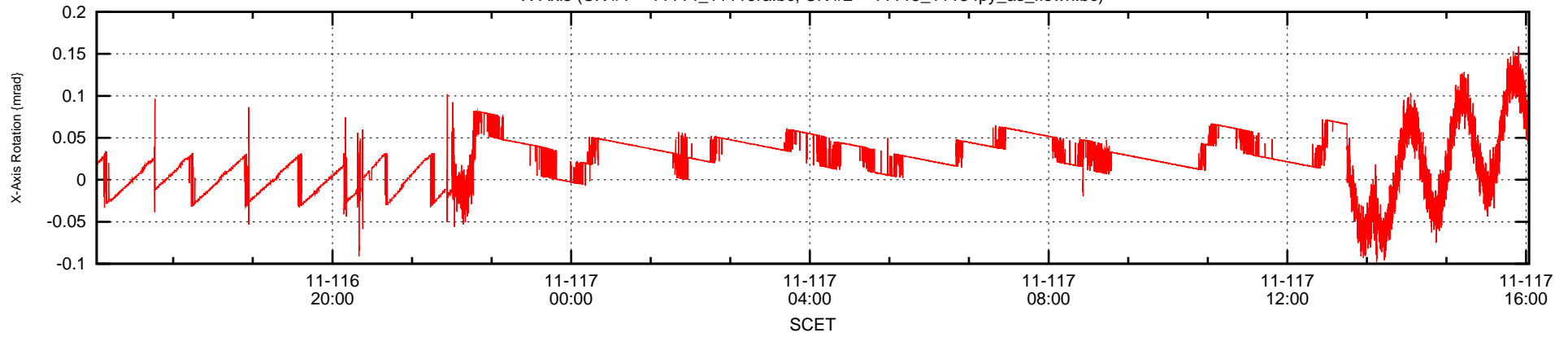


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 115-116)

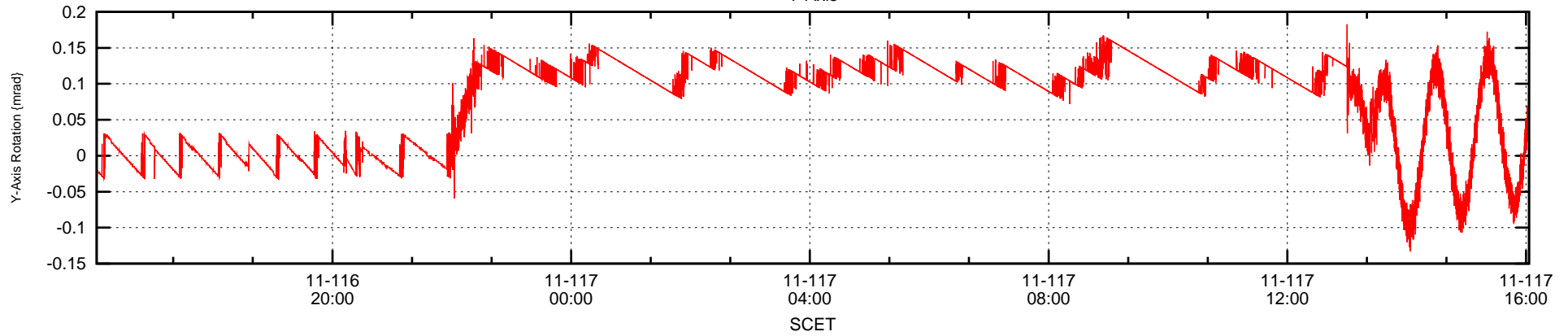


# Rotation From CK #2 to CK #1 (DOY 116-117)

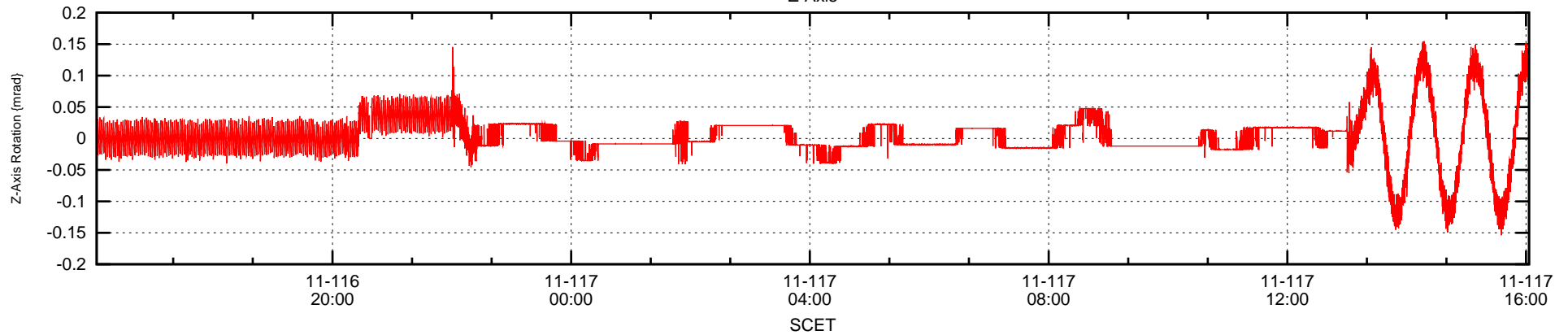
X-Axis (CK #1 = 11114\_11119ra.bc; CK #2 = 11115\_11184py\_as\_flowm.bc)



Y-Axis

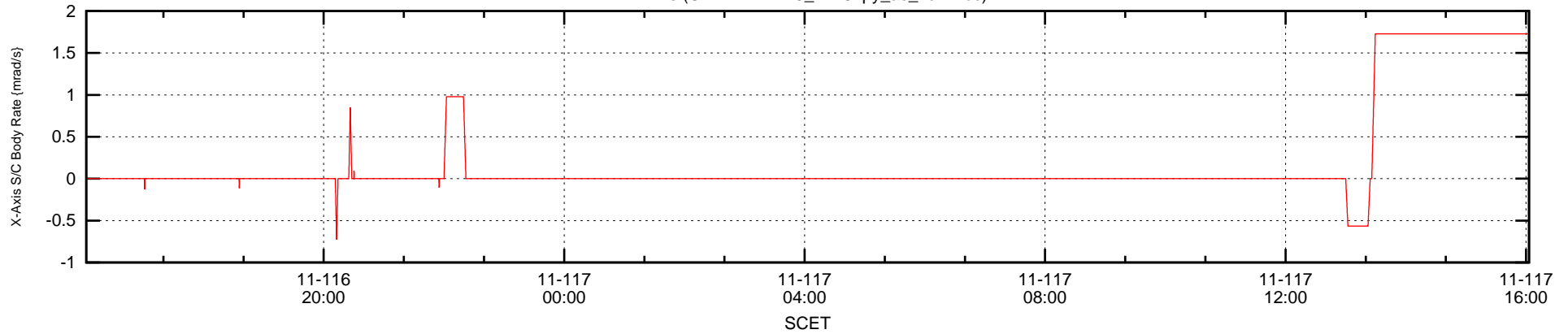


Z-Axis

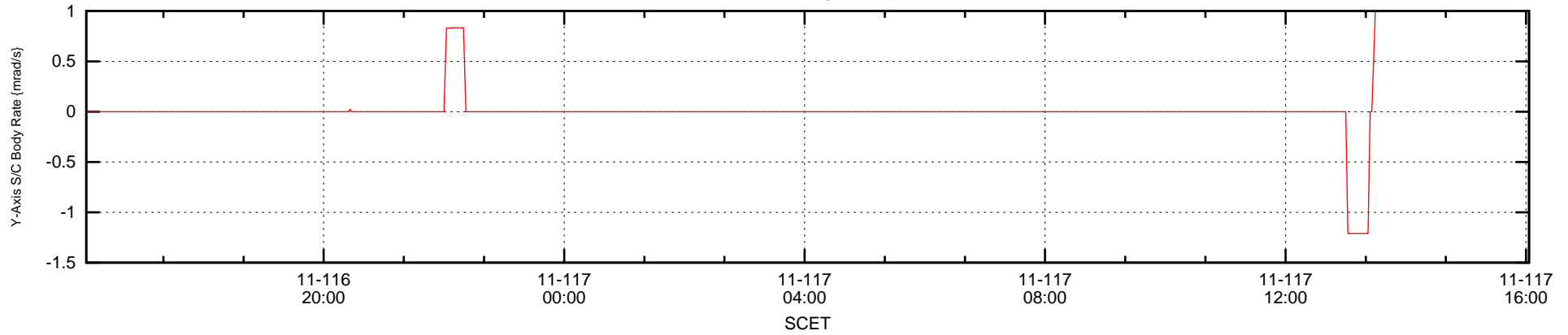


# CK #2 S/C Body Rates (DOY 116-117)

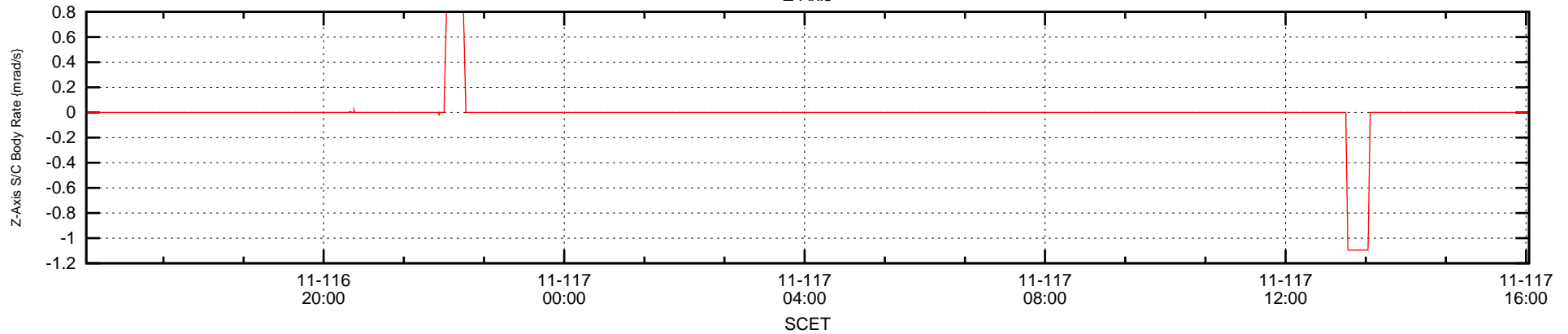
X-Axis (CK #2 = 11115\_11184py\_as\_flowm.bc)



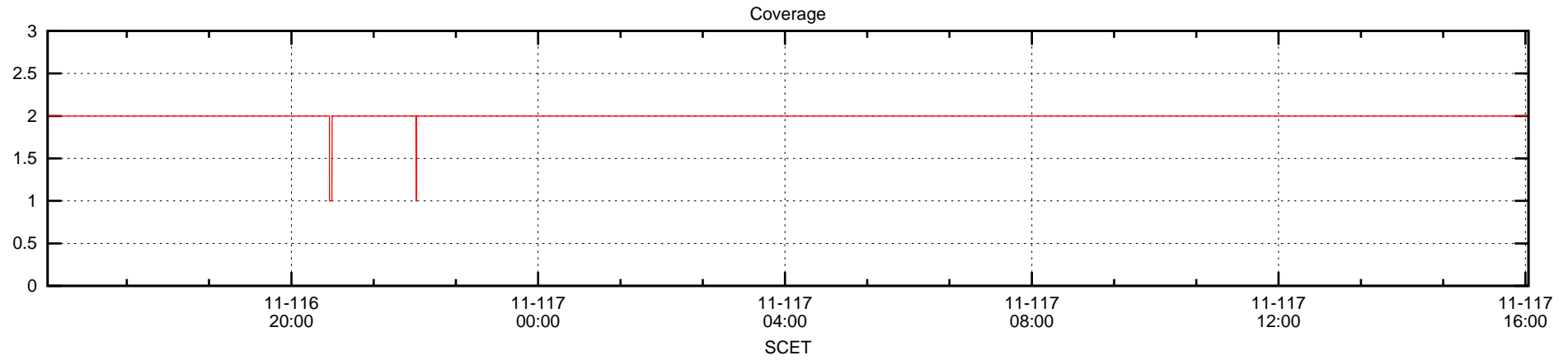
Y-Axis



Z-Axis

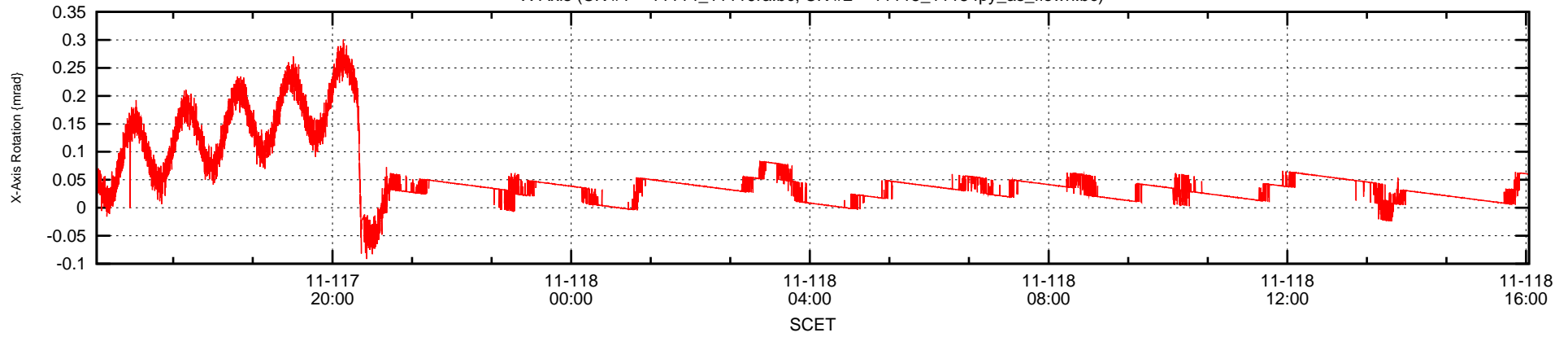


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 116-117)

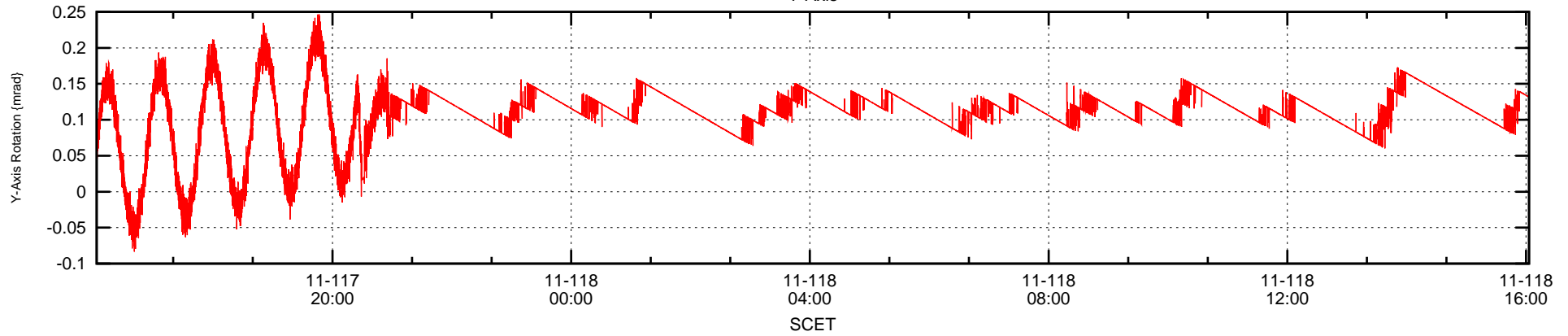


# Rotation From CK #2 to CK #1 (DOY 117-118)

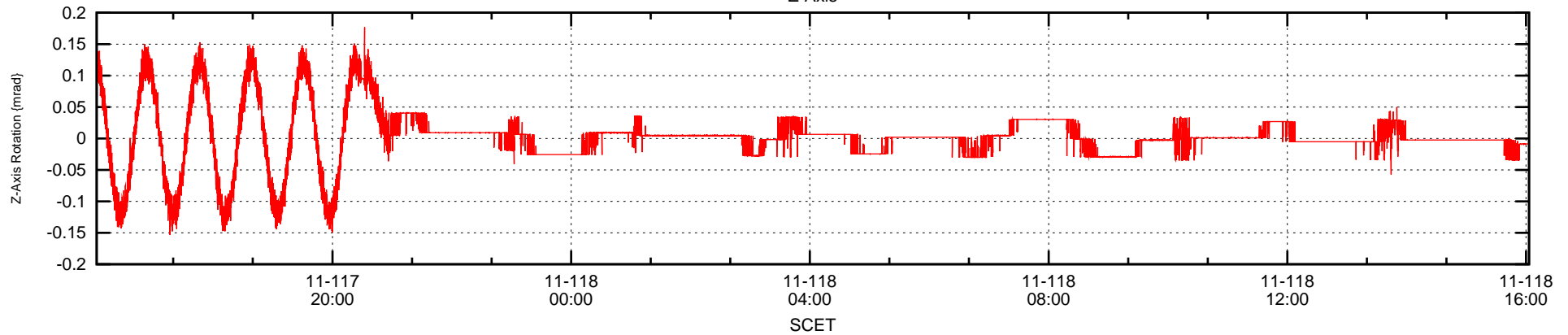
X-Axis (CK #1 = 11114\_11119ra.bc; CK #2 = 11115\_11184py\_as\_flown.bc)



Y-Axis

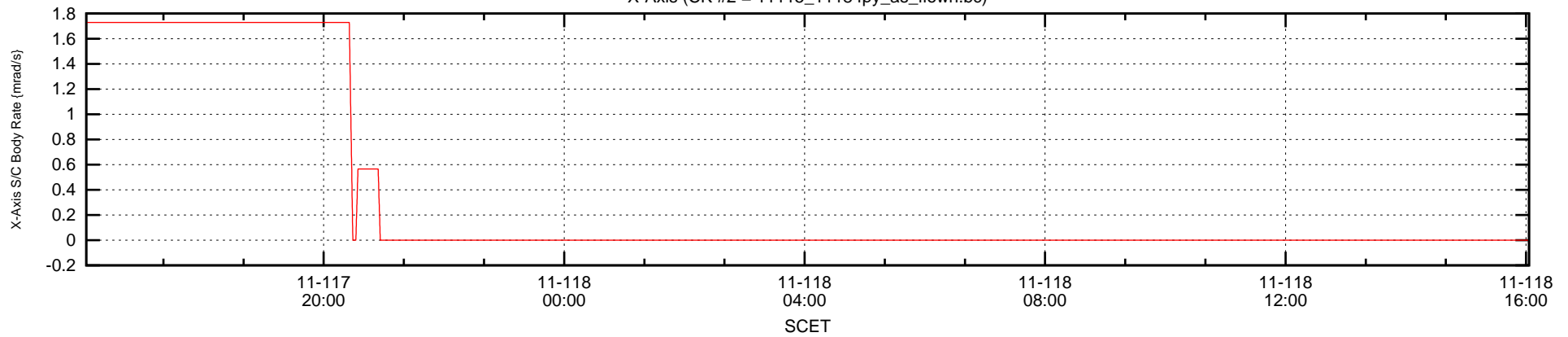


Z-Axis

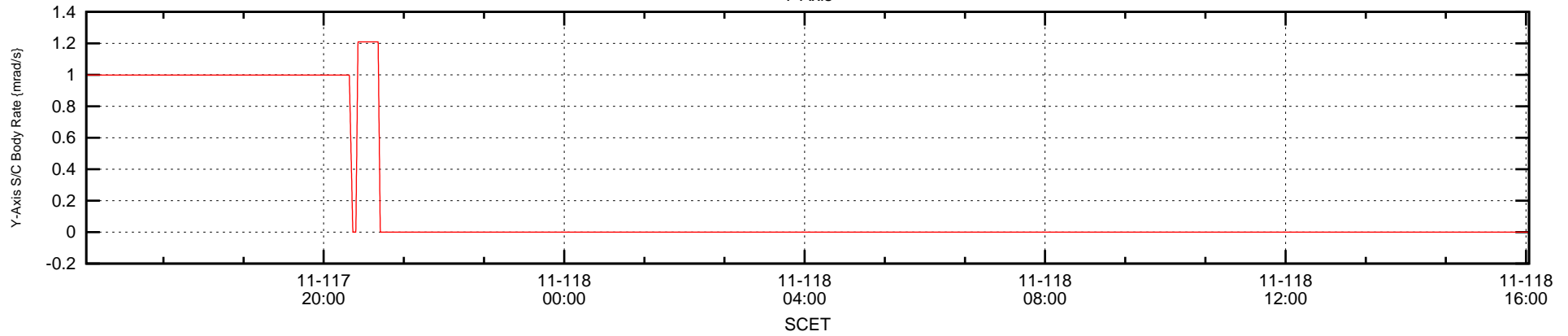


# CK #2 S/C Body Rates (DOY 117-118)

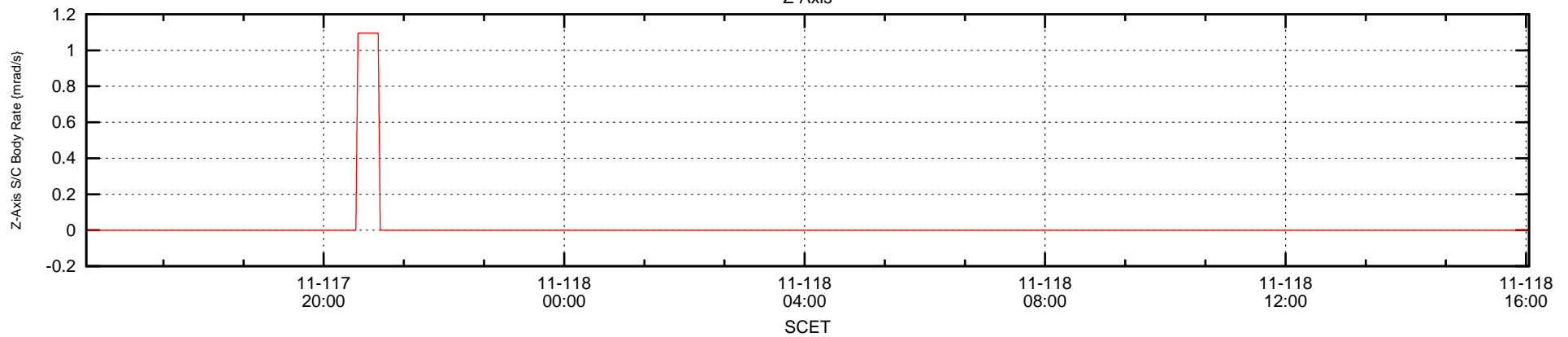
X-Axis (CK #2 = 11115\_11184py\_as\_flowm.bc)



Y-Axis

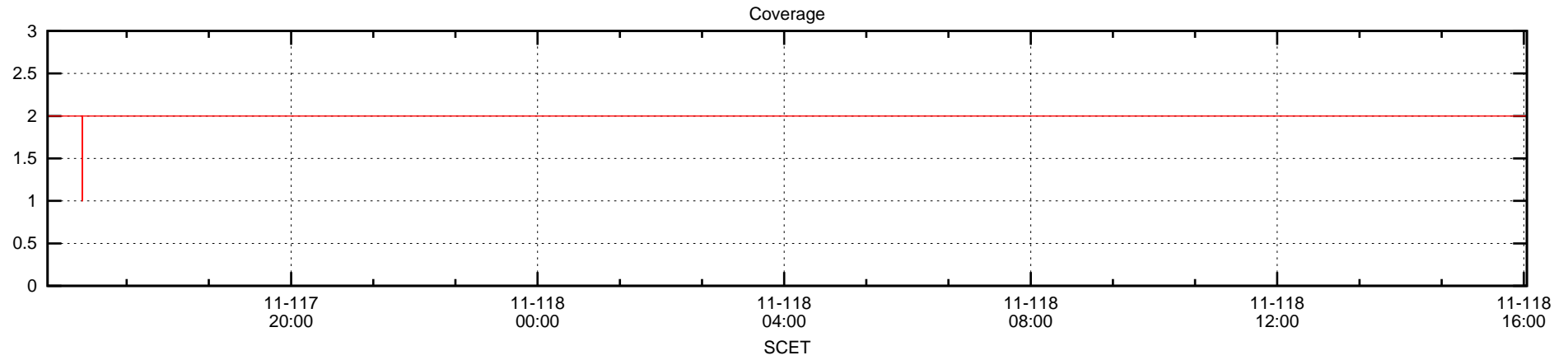


Z-Axis



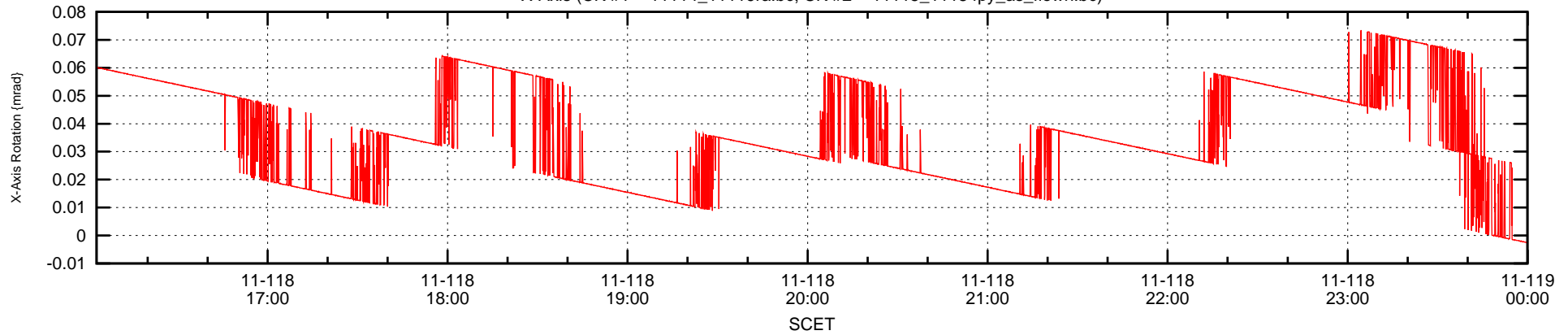


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 117-118)

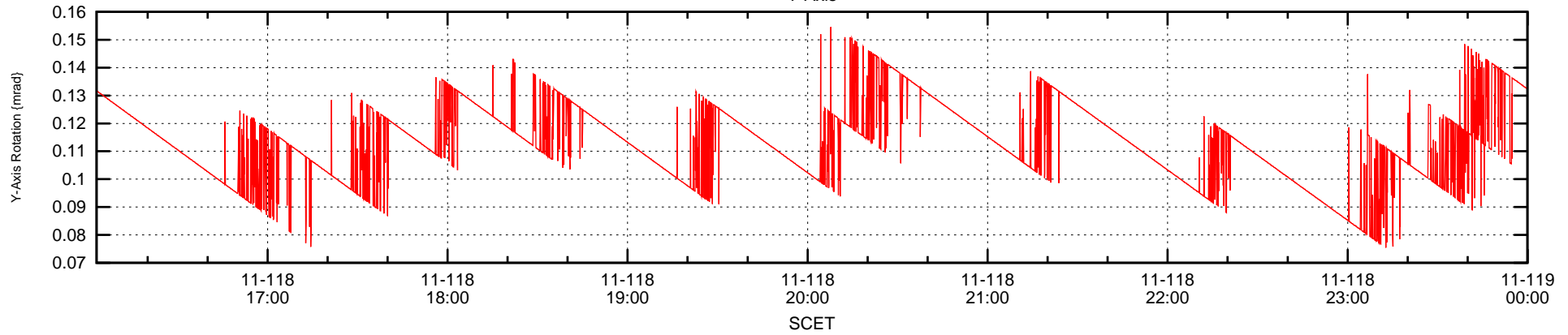


# Rotation From CK #2 to CK #1 (DOY 118-118)

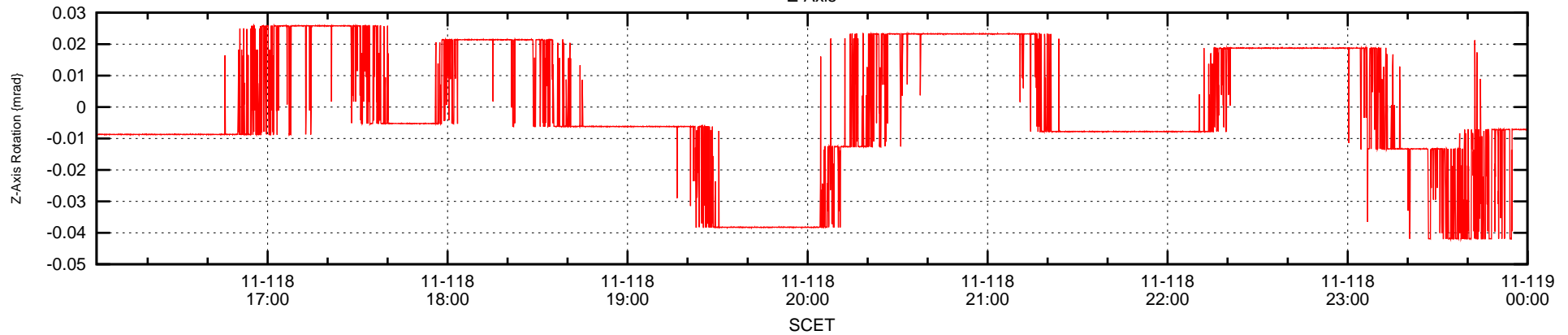
X-Axis (CK #1 = 11114\_11119ra.bc; CK #2 = 11115\_11184py\_as\_flowm.bc)



Y-Axis

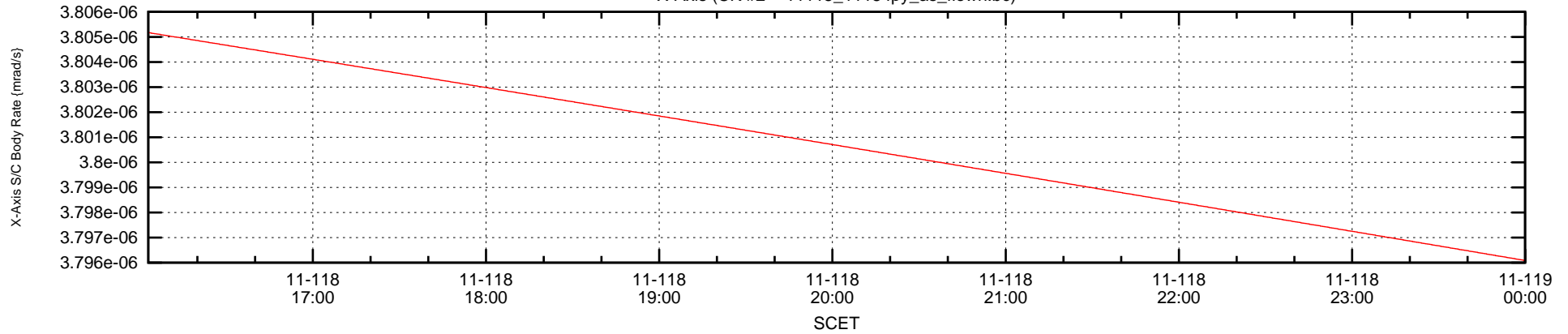


Z-Axis

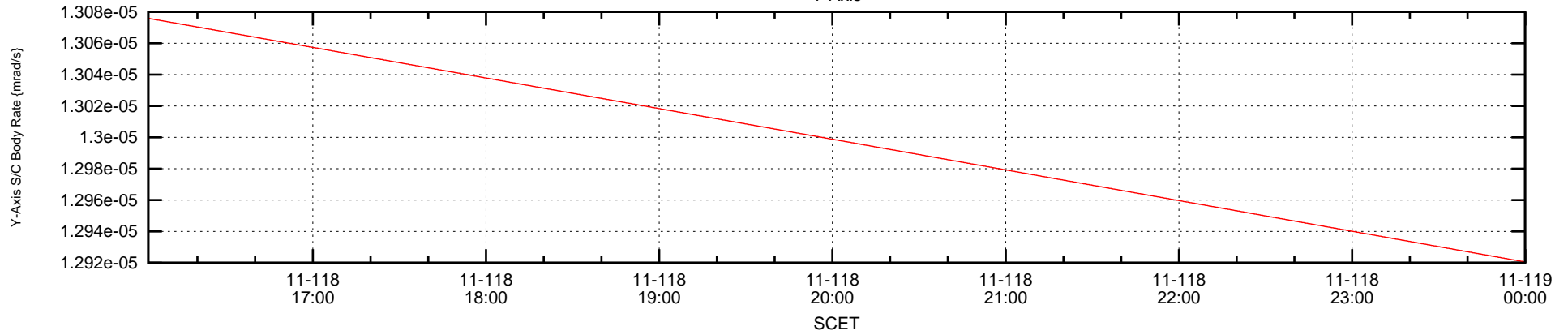


# CK #2 S/C Body Rates (DOY 118-118)

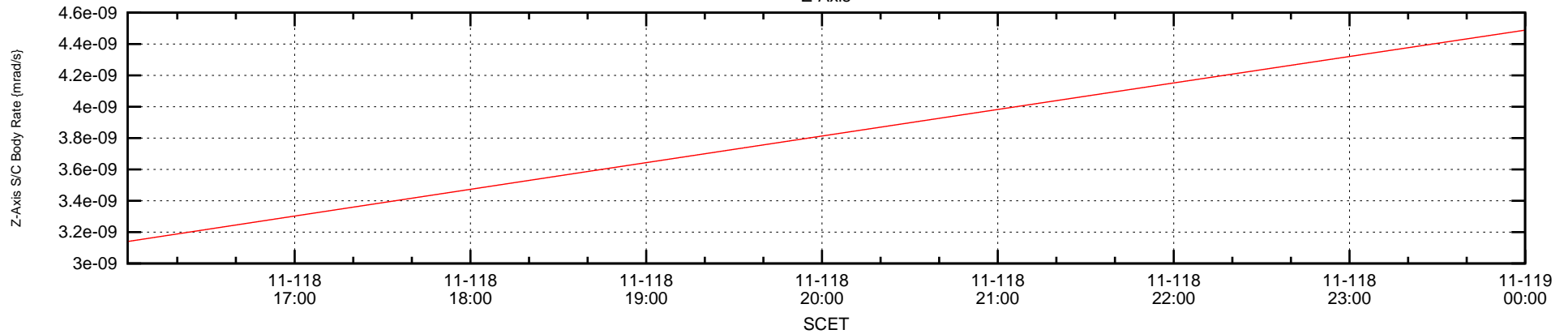
X-Axis (CK #2 = 11115\_11184py\_as\_flown.bc)



Y-Axis



Z-Axis



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 118-118)

