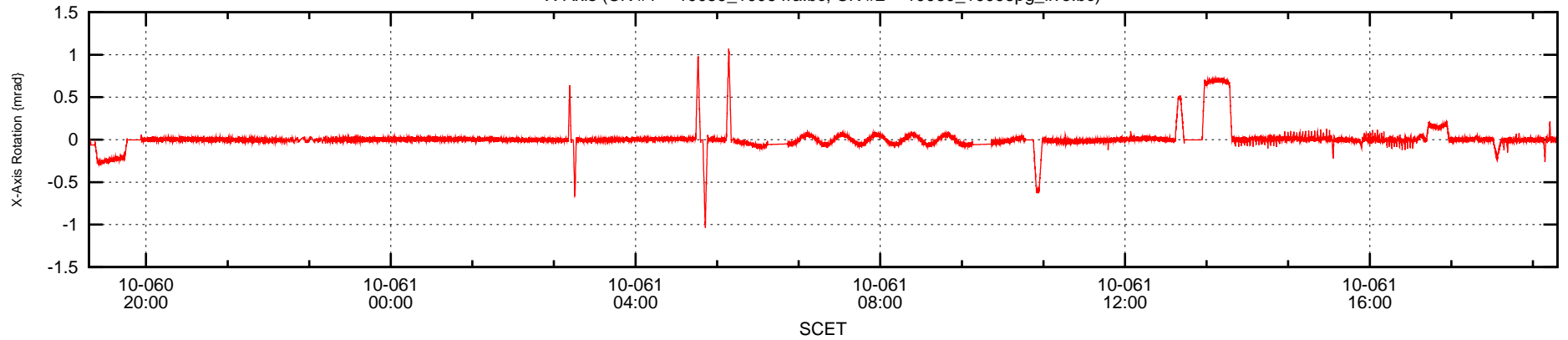
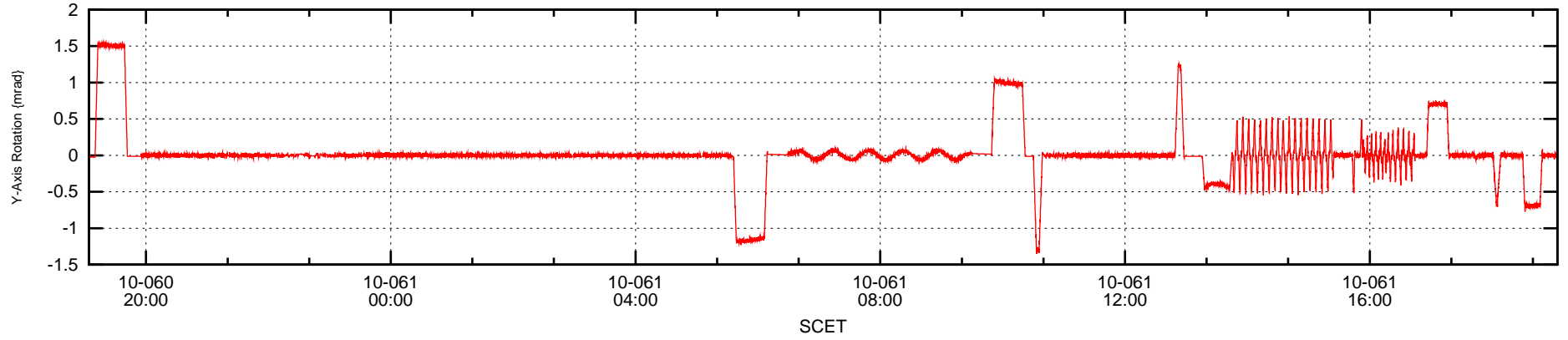


# Rotation From CK #2 to CK #1 (DOY 060-061)

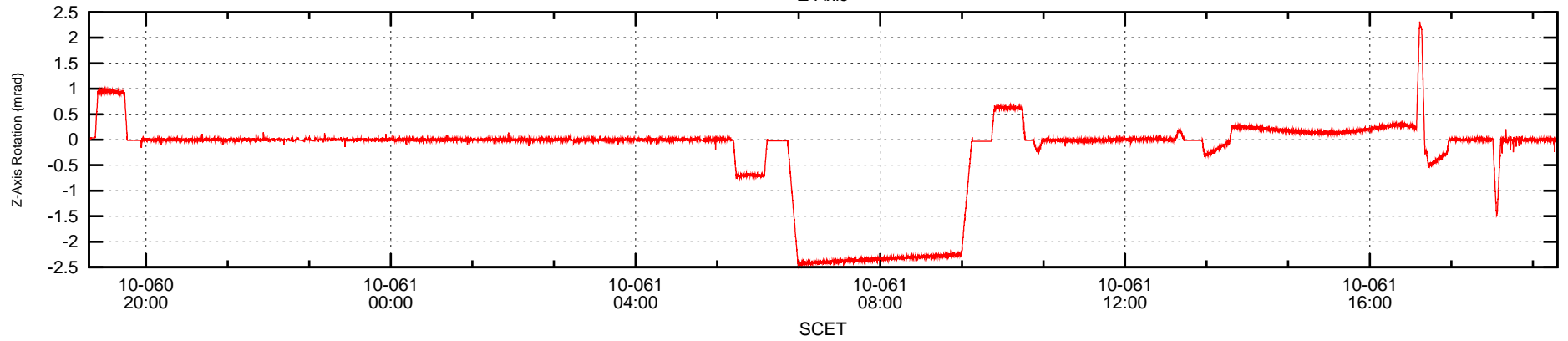
X-Axis (CK #1 = 10059\_10064ra.bc; CK #2 = 10060\_10095pg\_live.bc)



Y-Axis

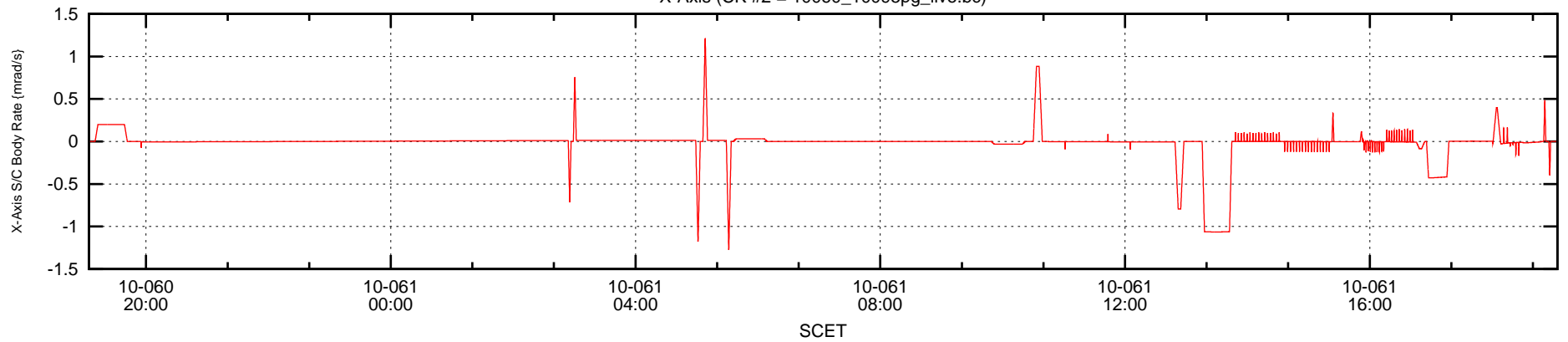


Z-Axis

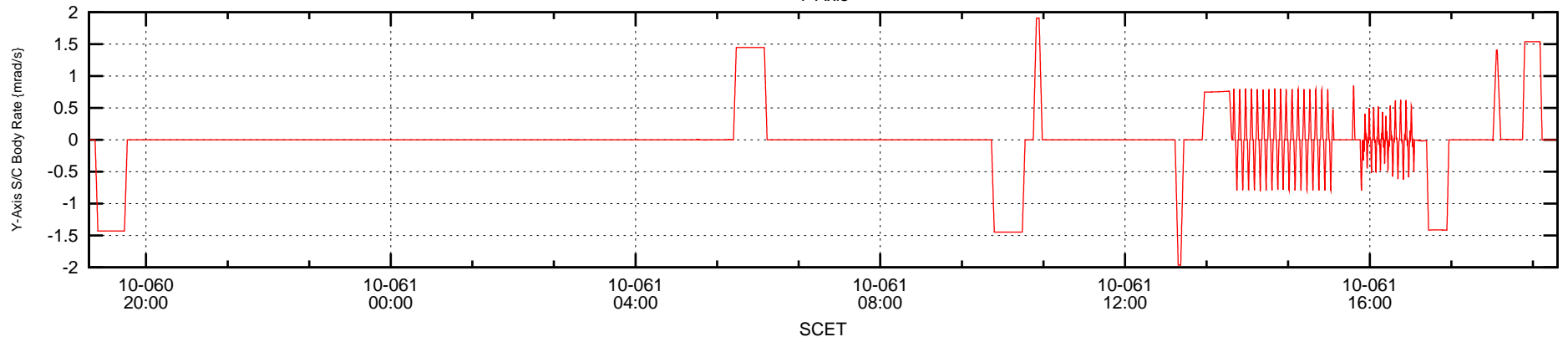


# CK #2 S/C Body Rates (DOY 060-061)

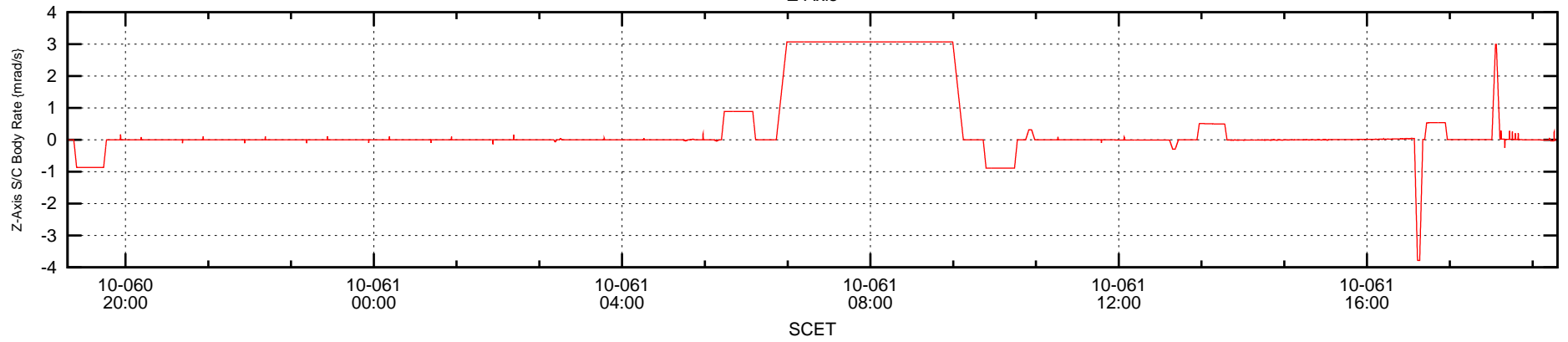
X-Axis (CK #2 = 10060\_10095pg\_live.bc)



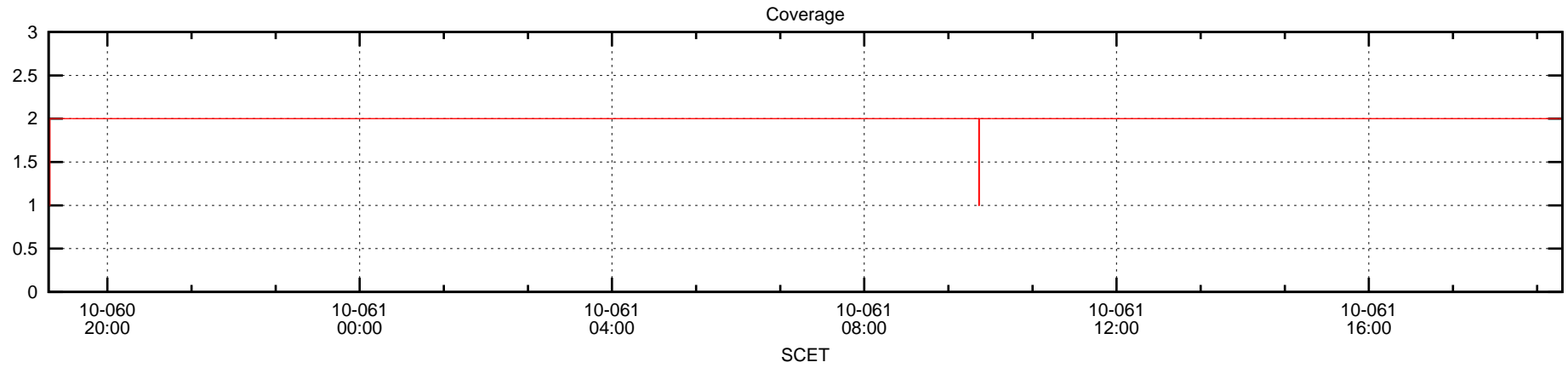
Y-Axis



Z-Axis

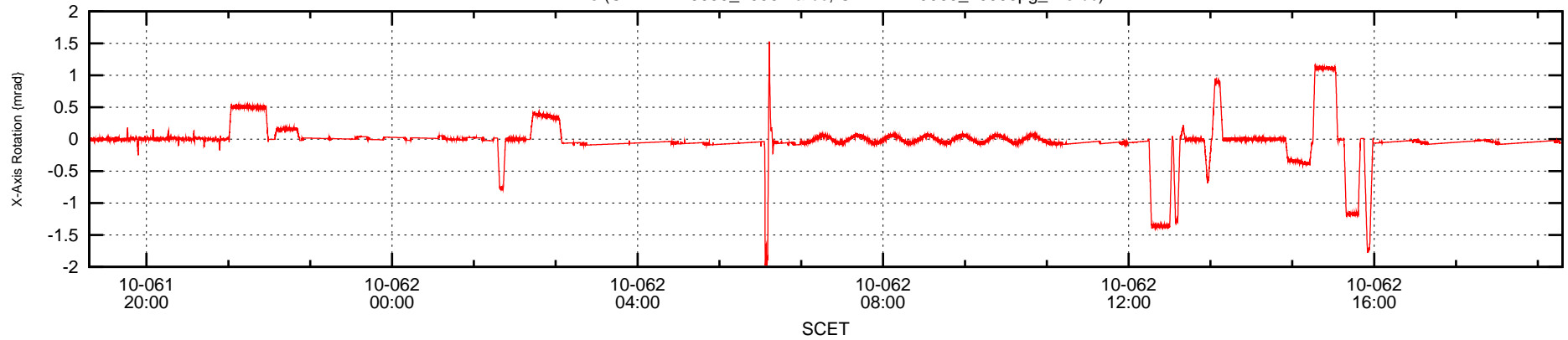


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 060-061)

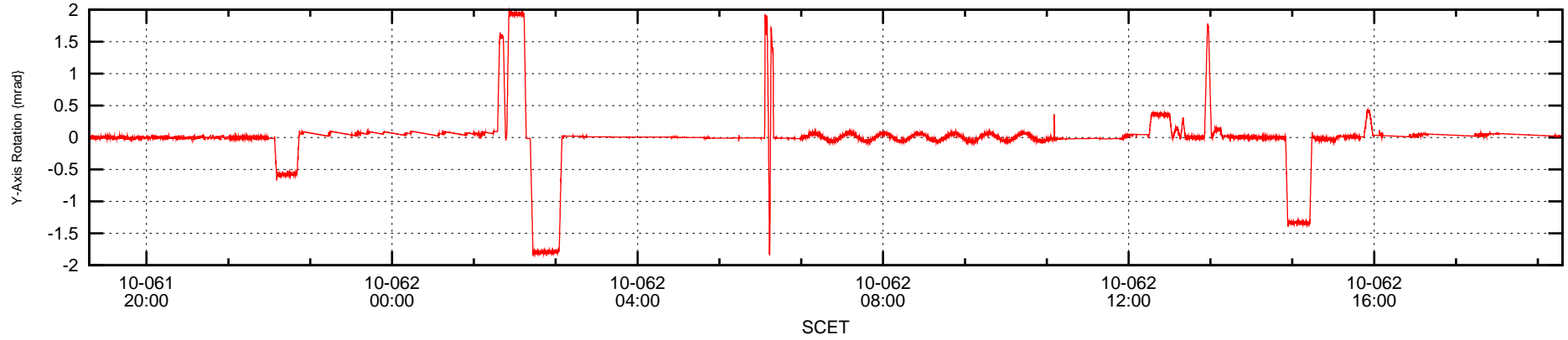


# Rotation From CK #2 to CK #1 (DOY 061-062)

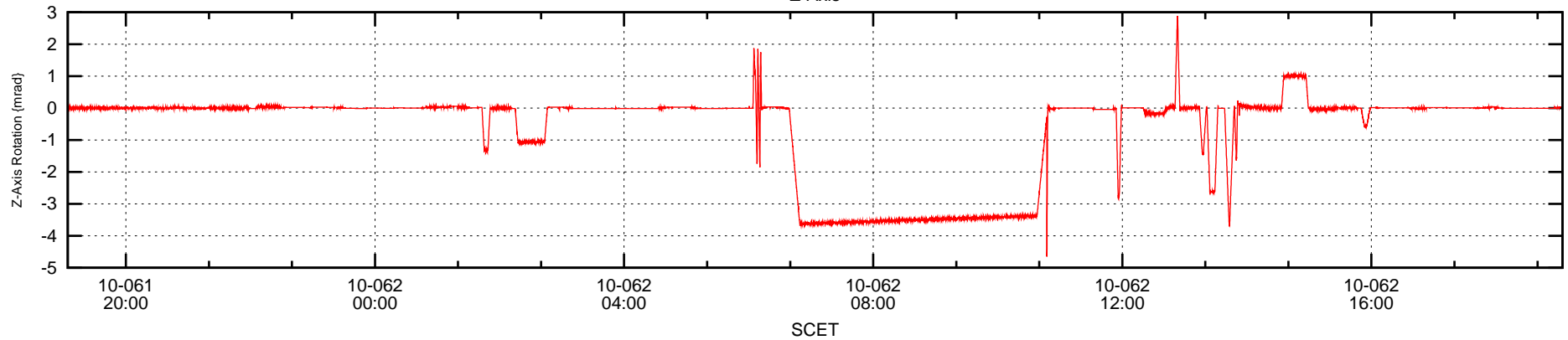
X-Axis (CK #1 = 10059\_10064ra.bc; CK #2 = 10060\_10095pg\_live.bc)



Y-Axis

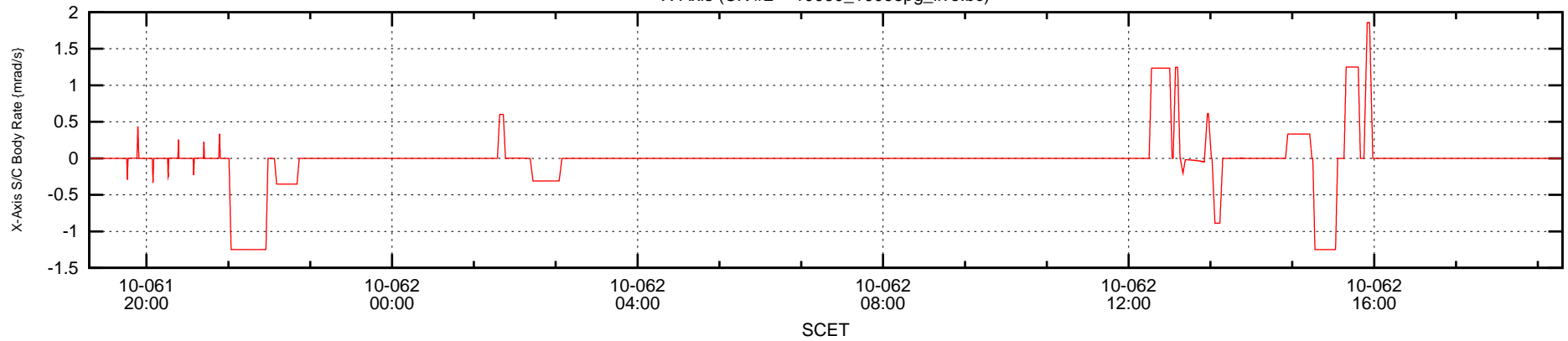


Z-Axis

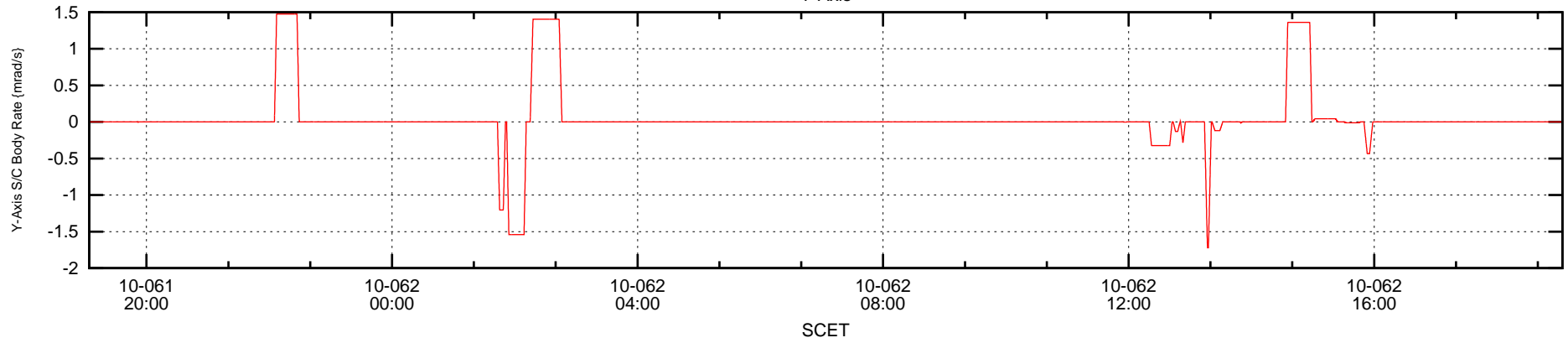


# CK #2 S/C Body Rates (DOY 061-062)

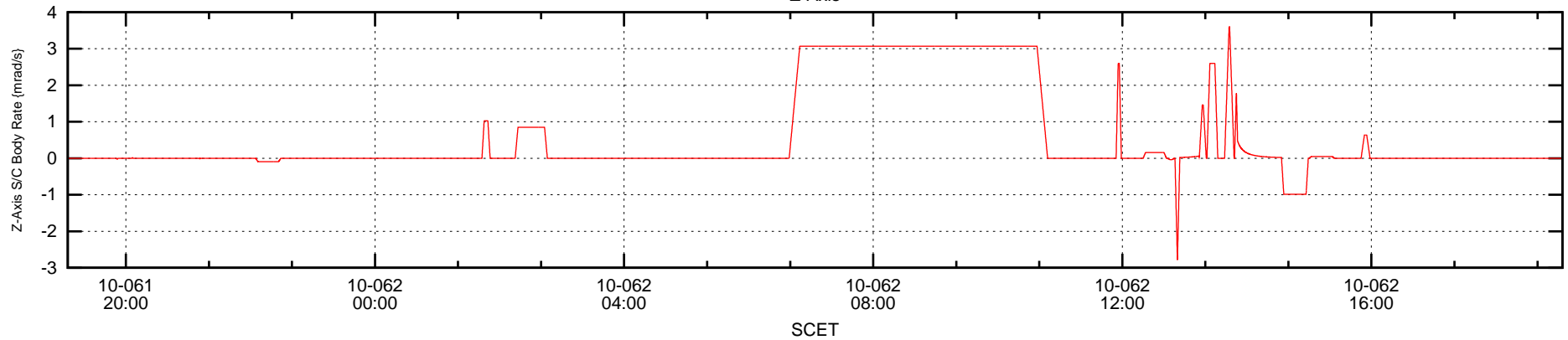
X-Axis (CK #2 = 10060\_10095pg\_live.bc)



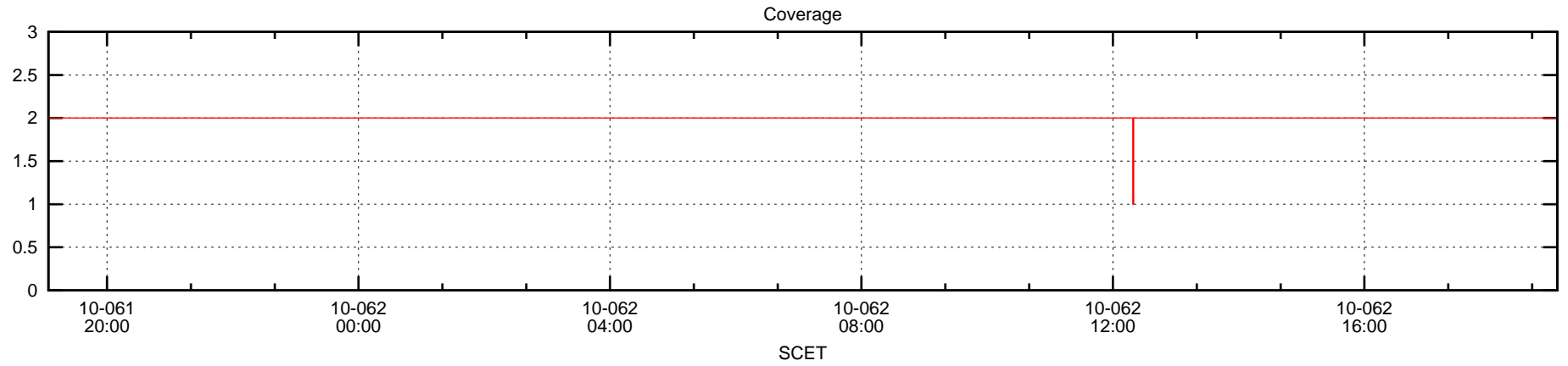
Y-Axis



Z-Axis

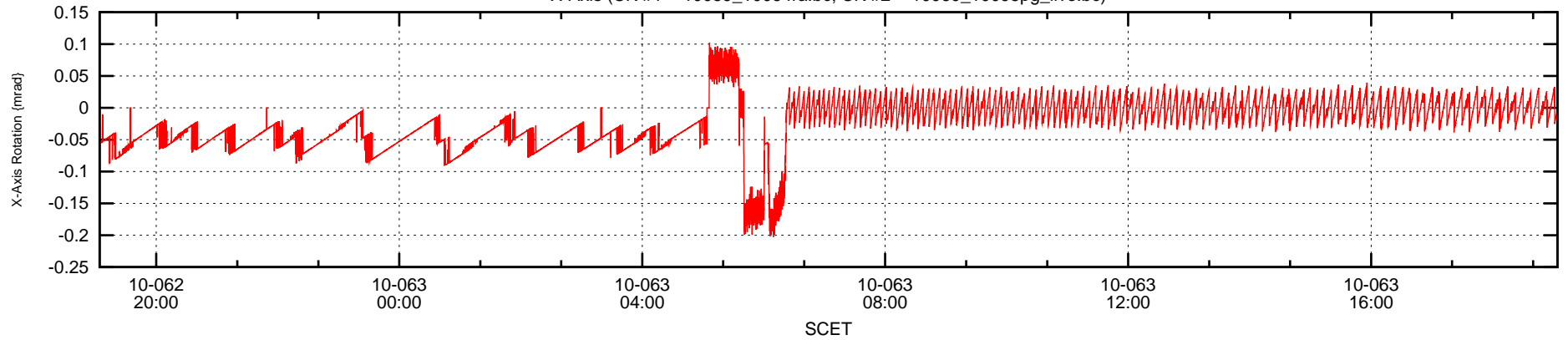


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 061-062)

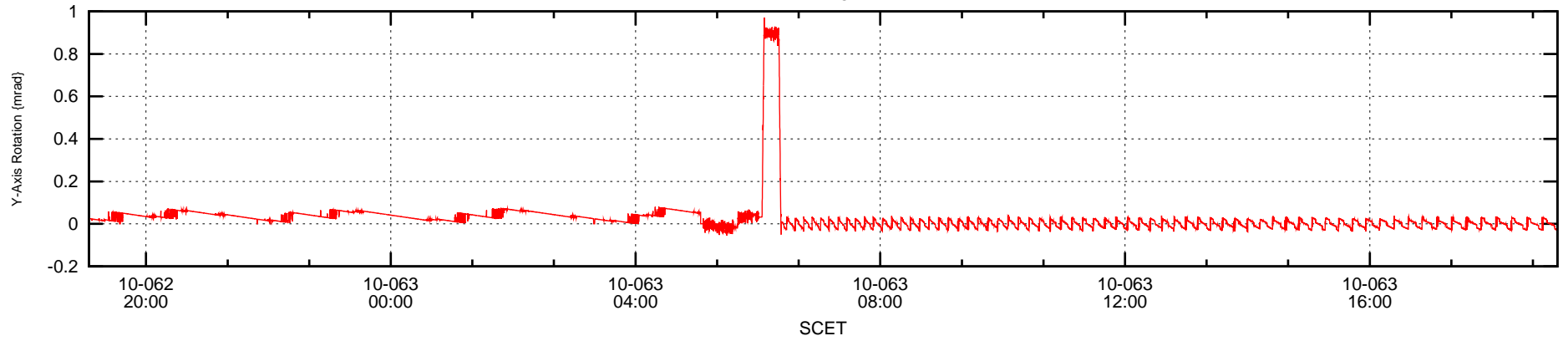


# Rotation From CK #2 to CK #1 (DOY 062-063)

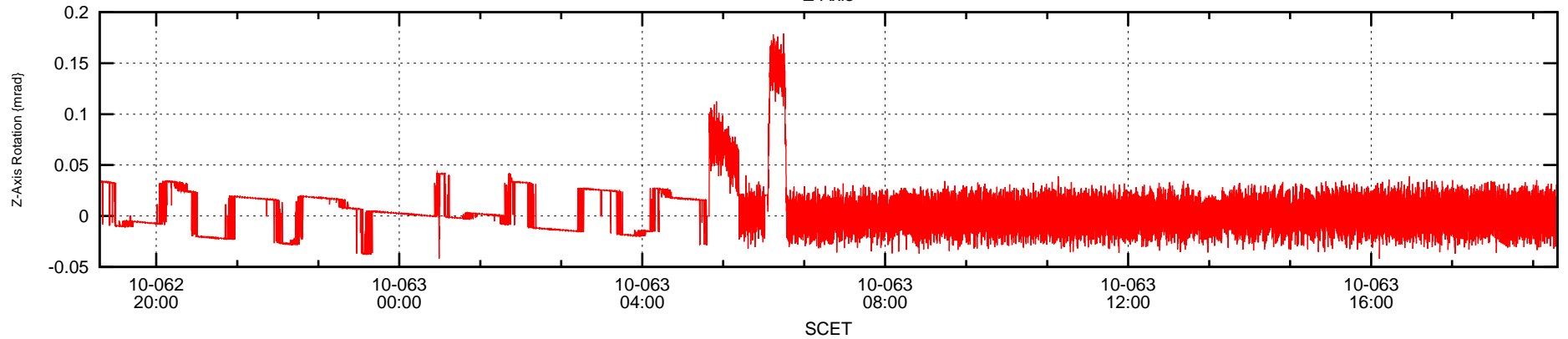
X-Axis (CK #1 = 10059\_10064ra.bc; CK #2 = 10060\_10095pg\_live.bc)



Y-Axis

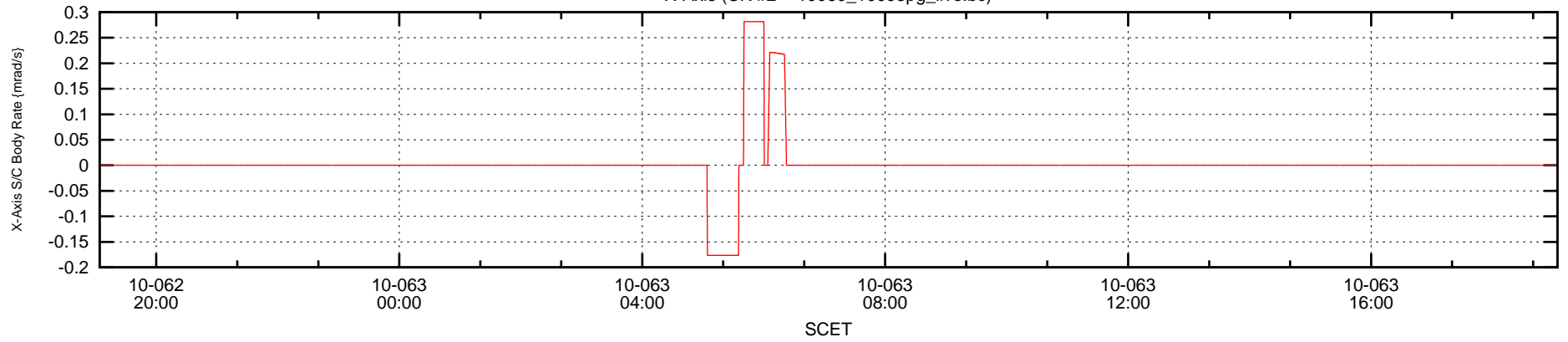


Z-Axis

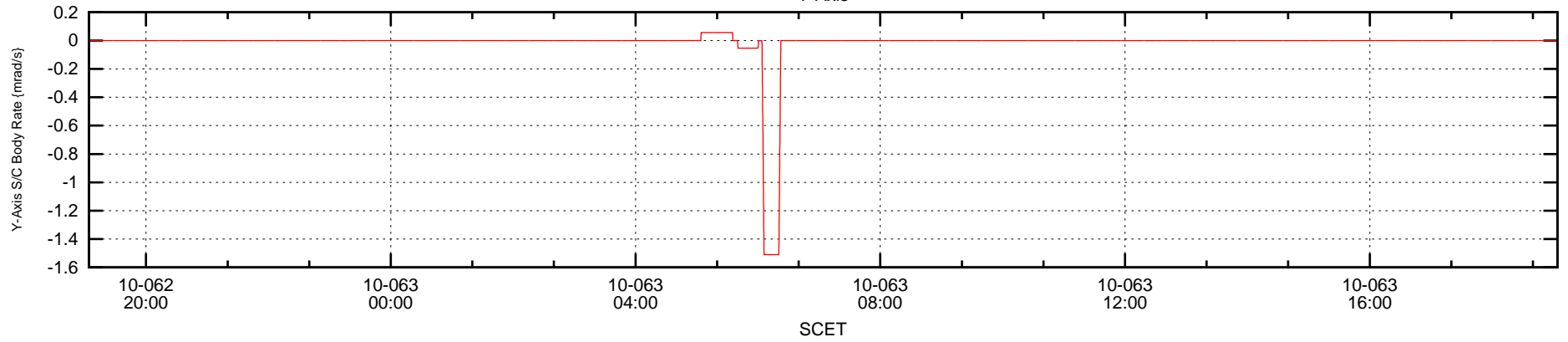


# CK #2 S/C Body Rates (DOY 062-063)

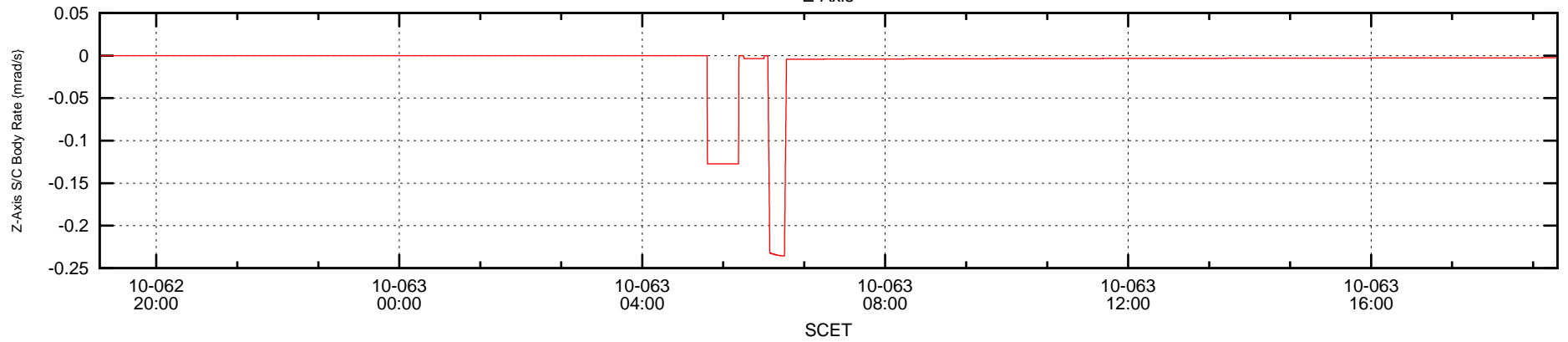
X-Axis (CK #2 = 10060\_10095pg\_live.bc)



Y-Axis

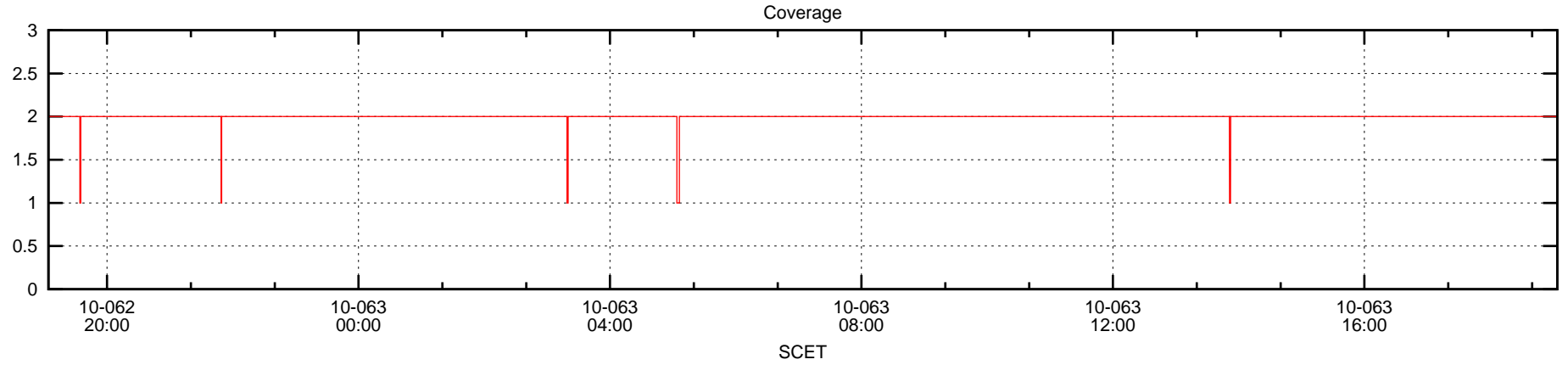


Z-Axis



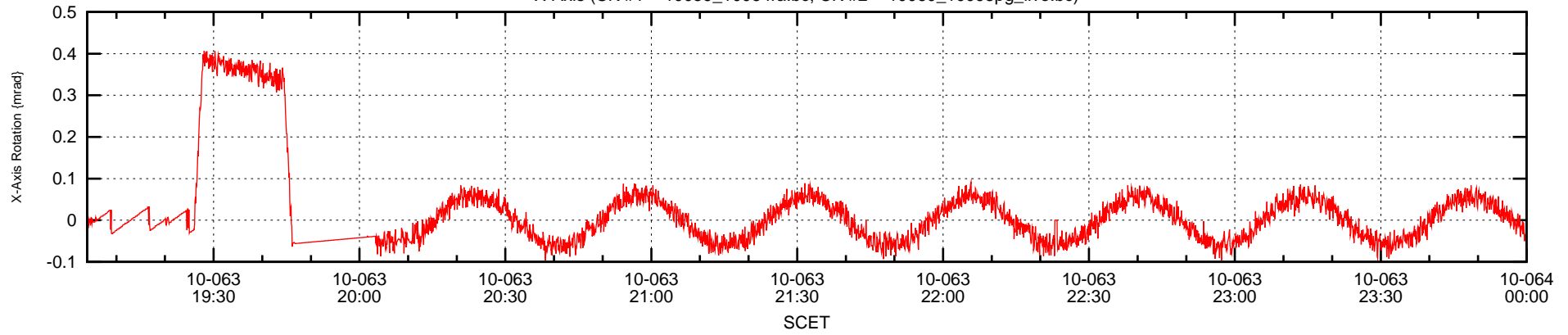


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 062-063)

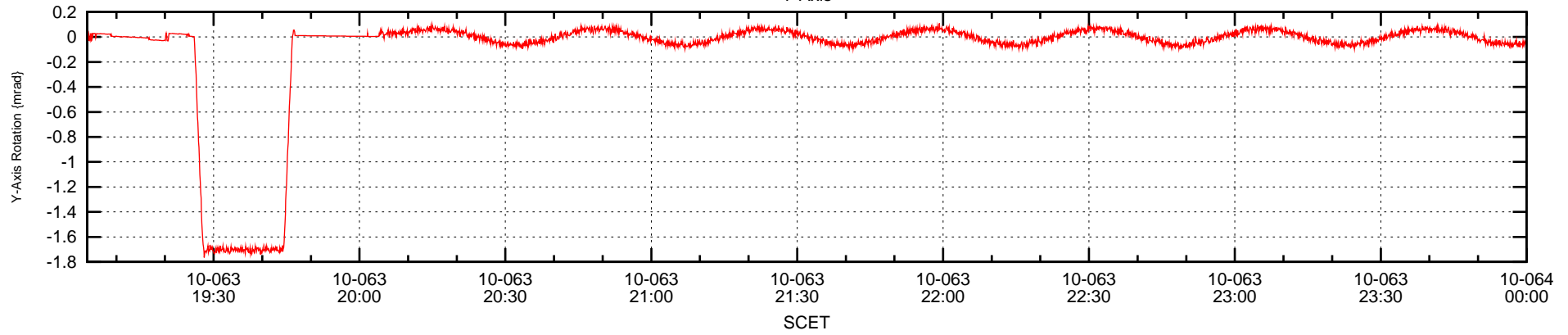


# Rotation From CK #2 to CK #1 (DOY 063-063)

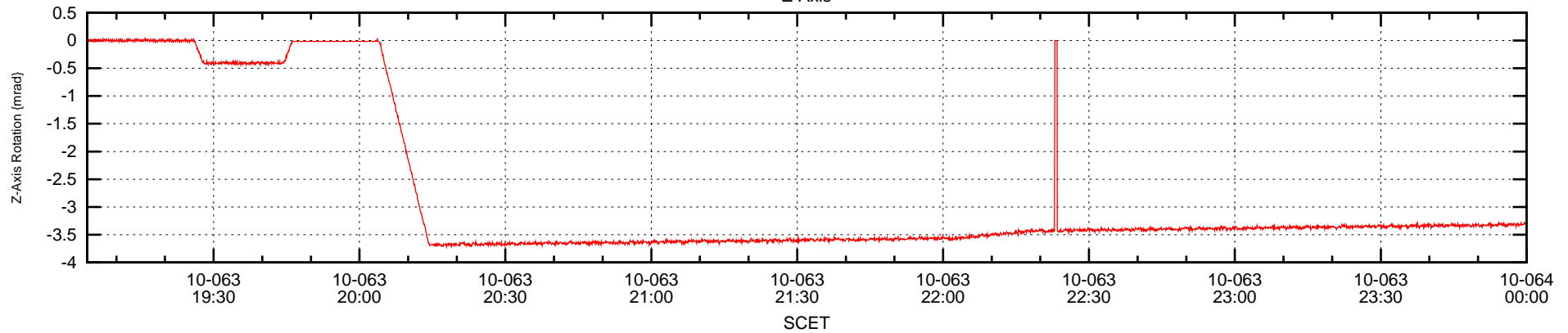
X-Axis (CK #1 = 10059\_10064ra.bc; CK #2 = 10060\_10095pg\_live.bc)



Y-Axis

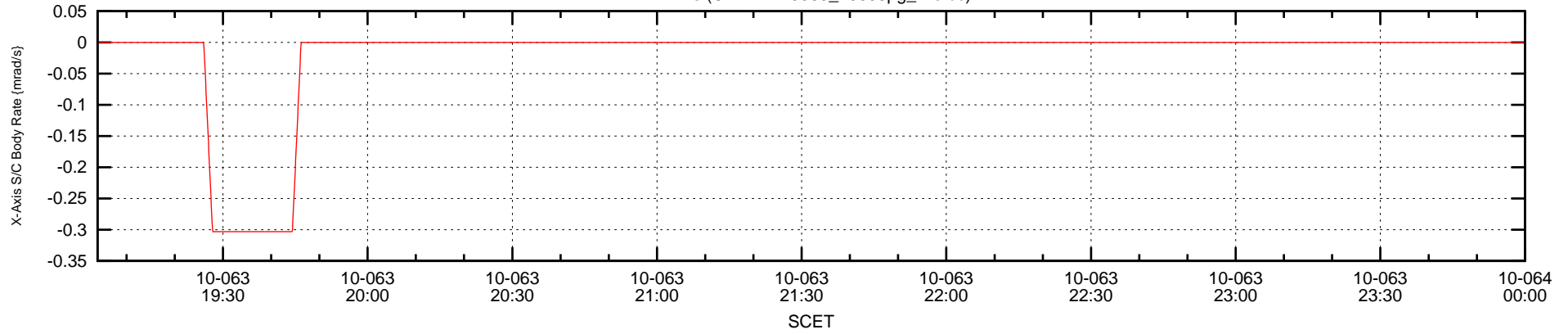


Z-Axis

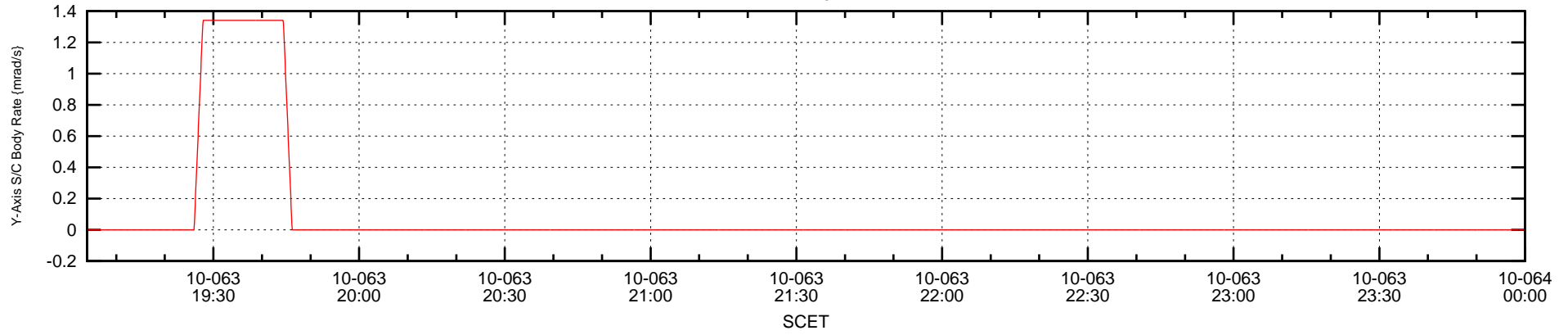


# CK #2 S/C Body Rates (DOY 063-063)

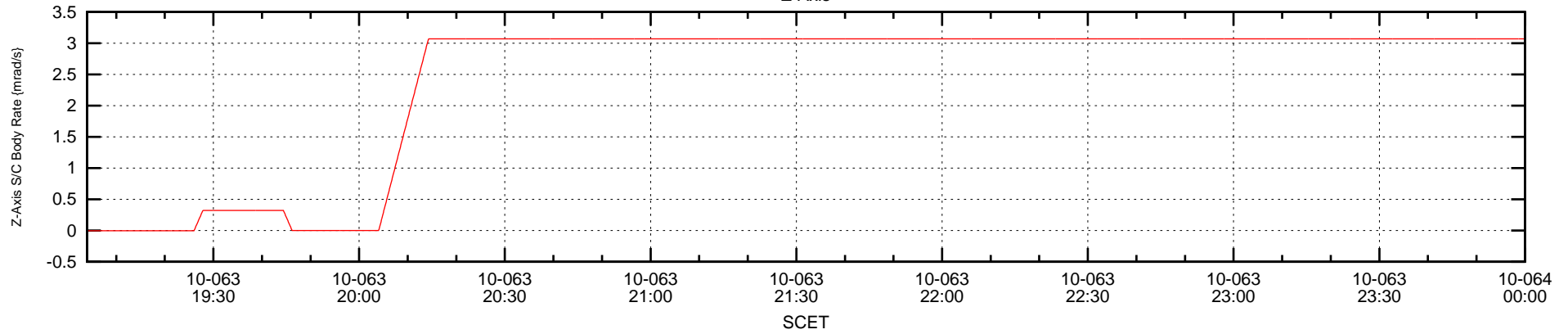
X-Axis (CK #2 = 10060\_10095pg\_live.bc)



Y-Axis



Z-Axis



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 063-063)

