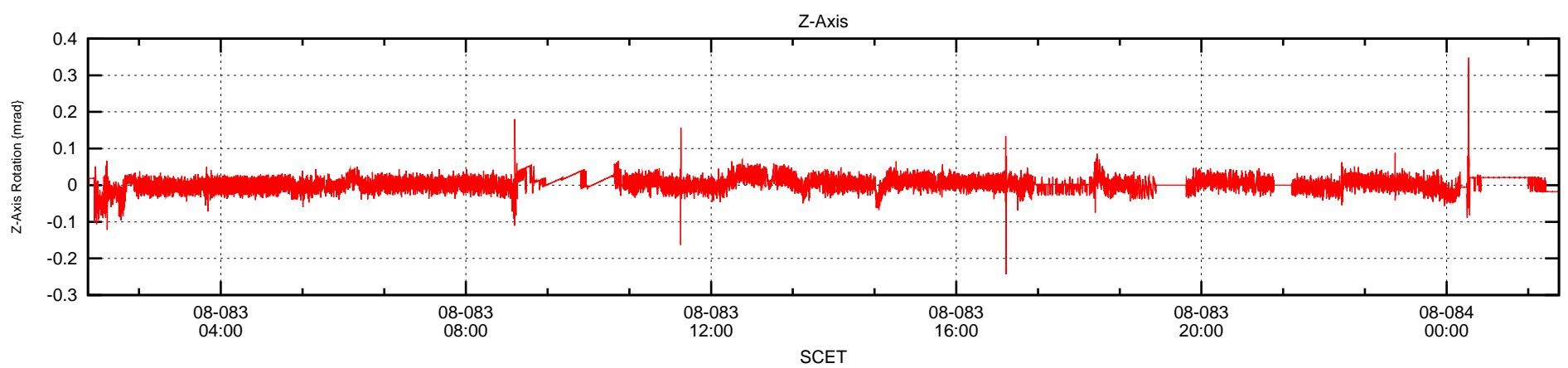
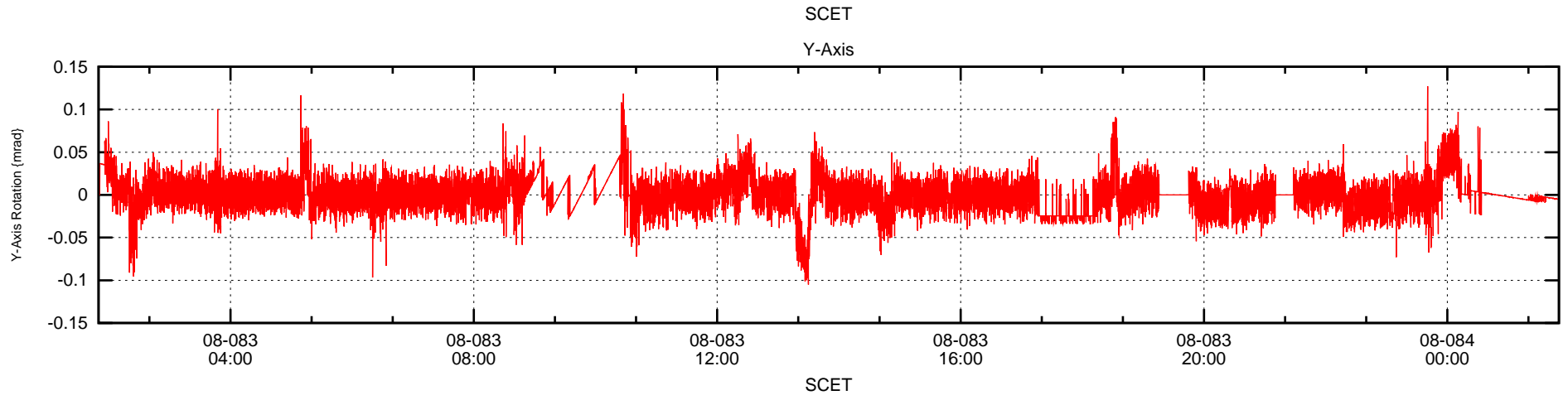
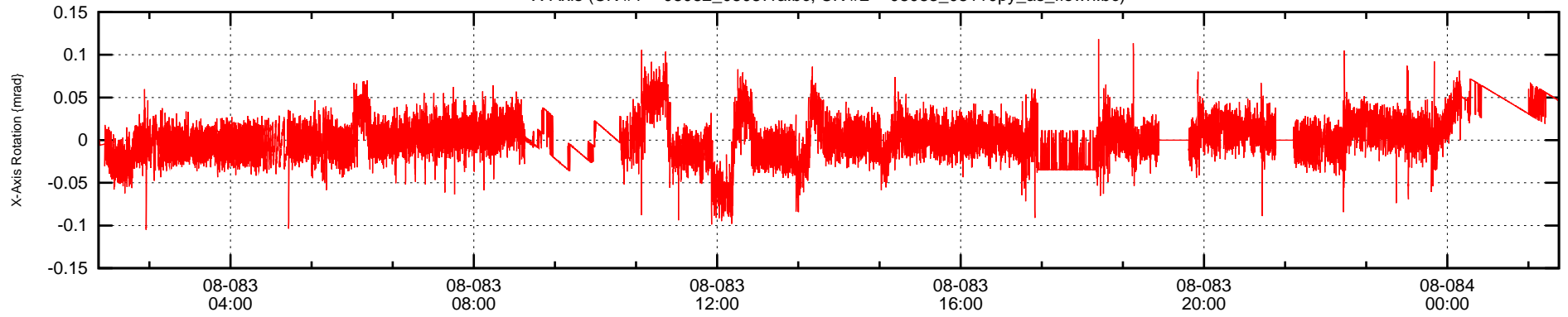


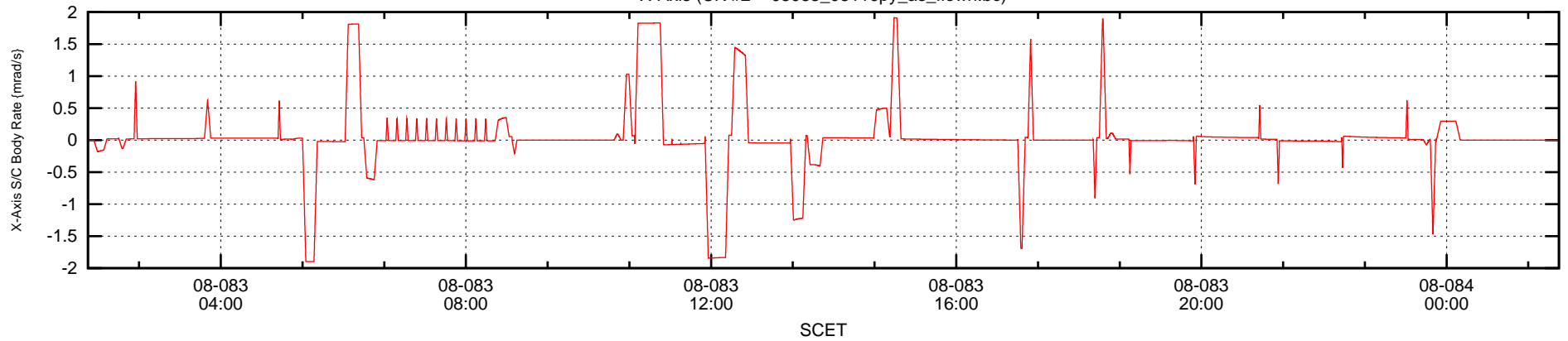
# Rotation From CK #2 to CK #1 (DOY 083-084)

X-Axis (CK #1 = 08082\_08087ra.bc; CK #2 = 08083\_08110py\_as\_flown.bc)



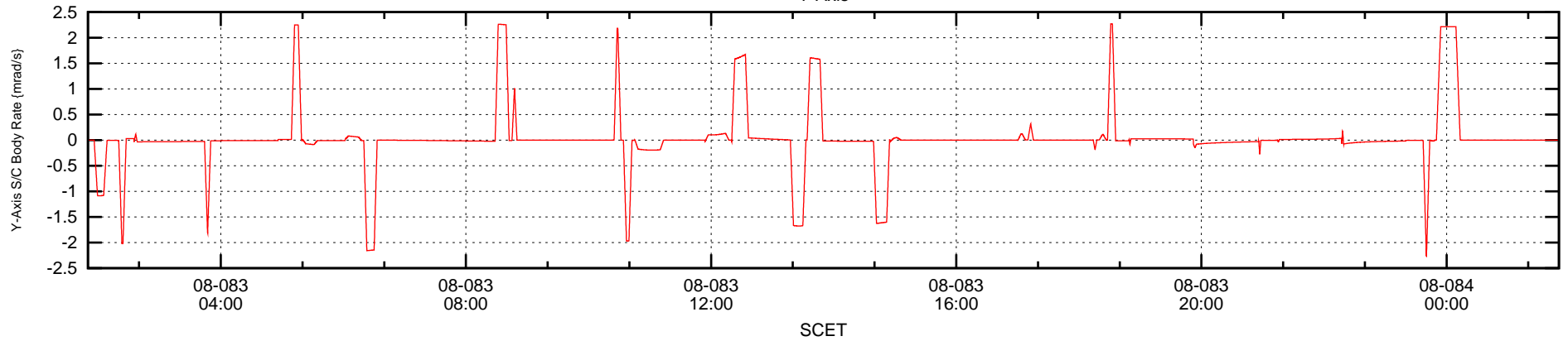
# CK #2 S/C Body Rates (DOY 083-084)

X-Axis (CK #2 = 08083\_08110py\_as\_flown.bc)



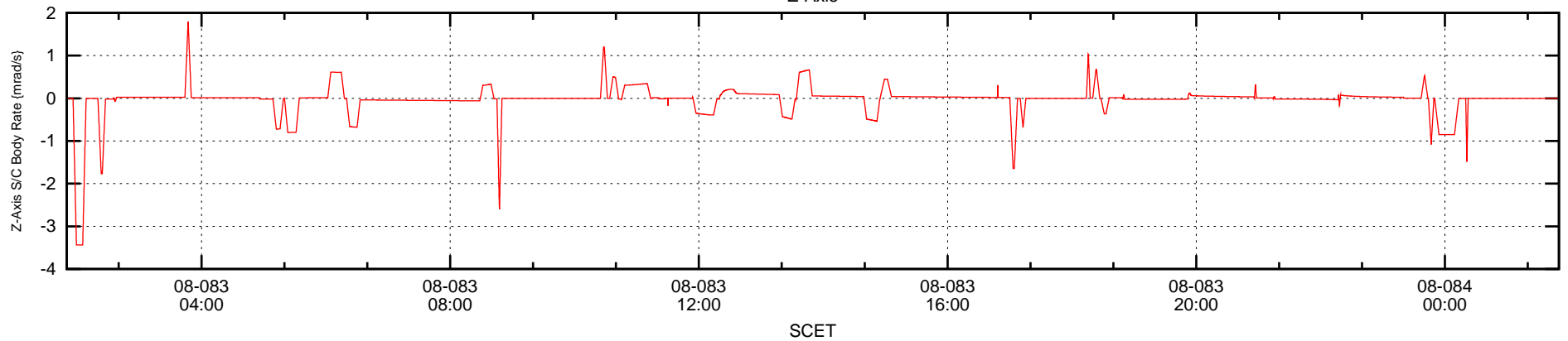
SCET

Y-Axis



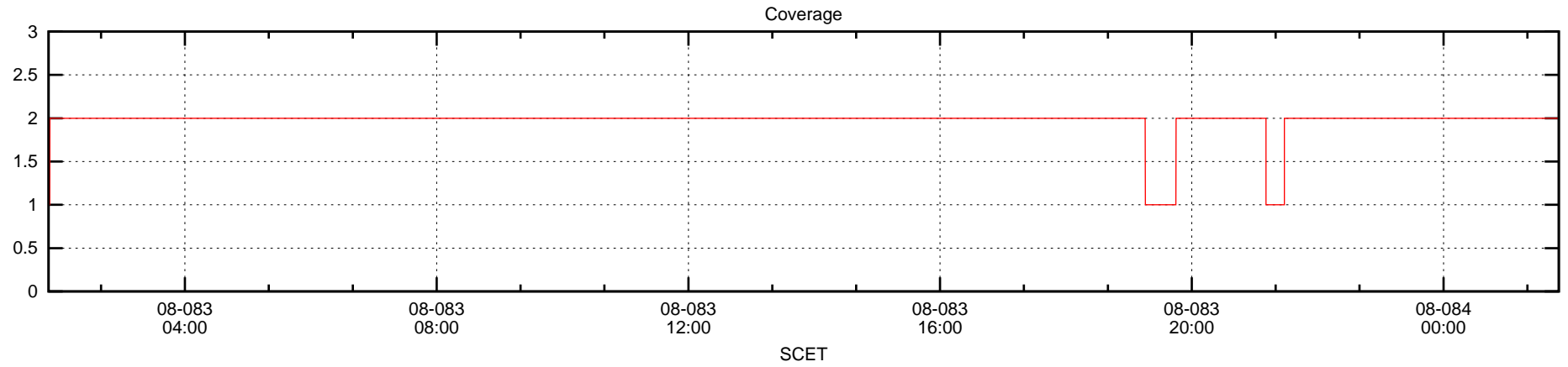
SCET

Z-Axis



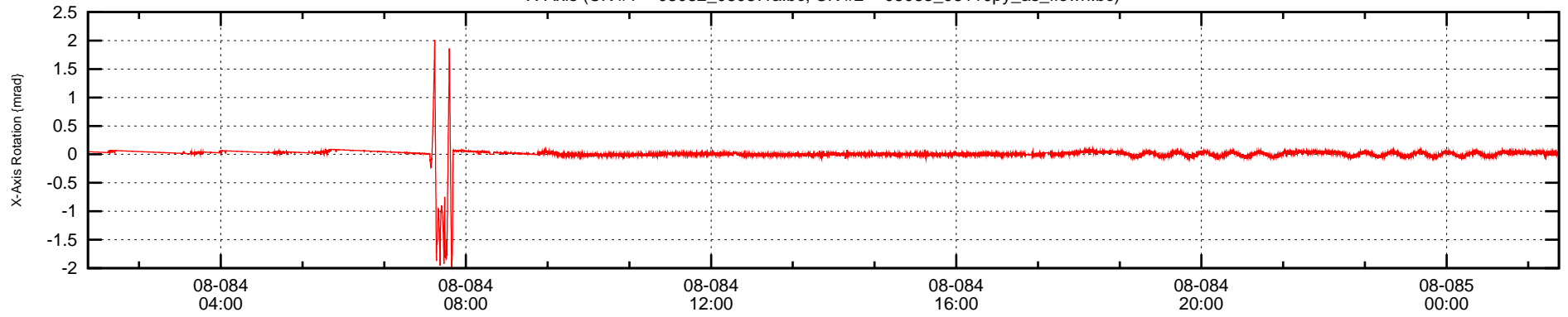
SCET

All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 083-084)



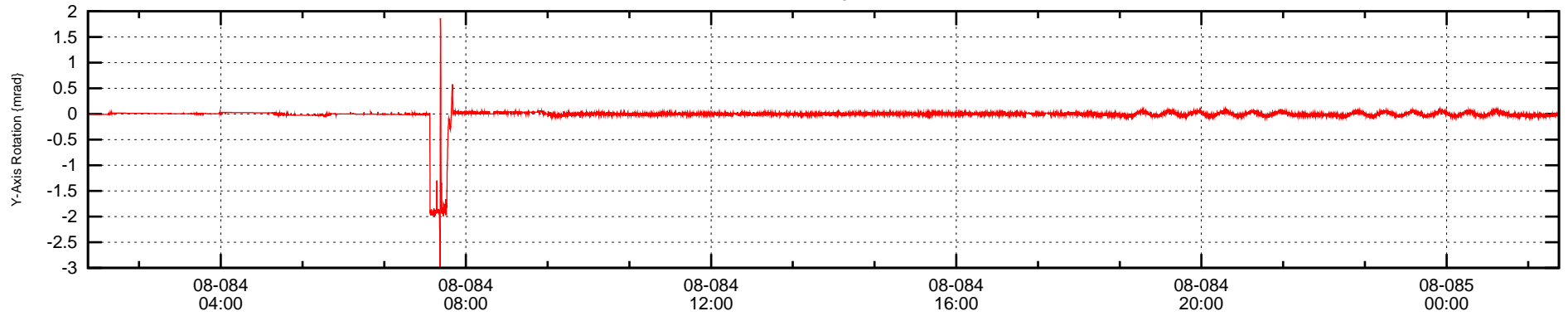
# Rotation From CK #2 to CK #1 (DOY 084-085)

X-Axis (CK #1 = 08082\_08087ra.bc; CK #2 = 08083\_08110py\_as\_flowm.bc)



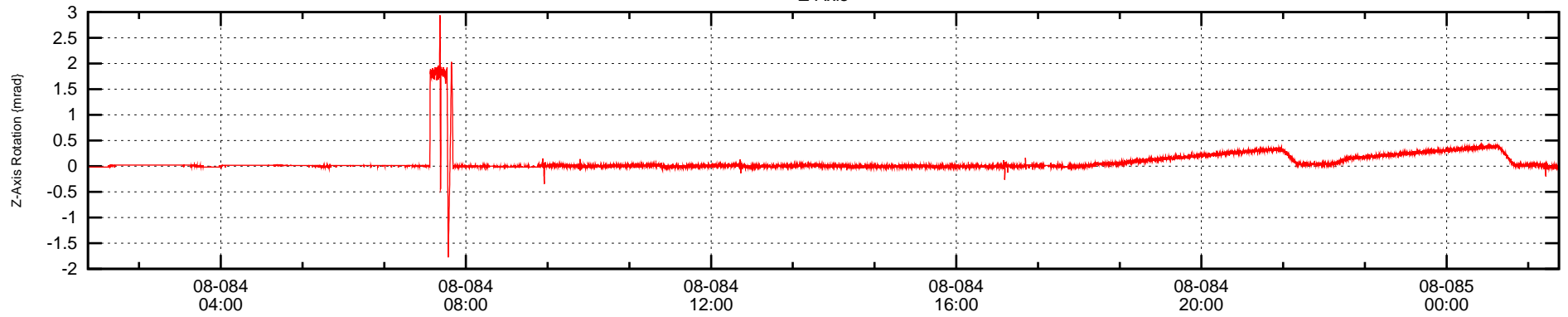
SCET

Y-Axis



SCET

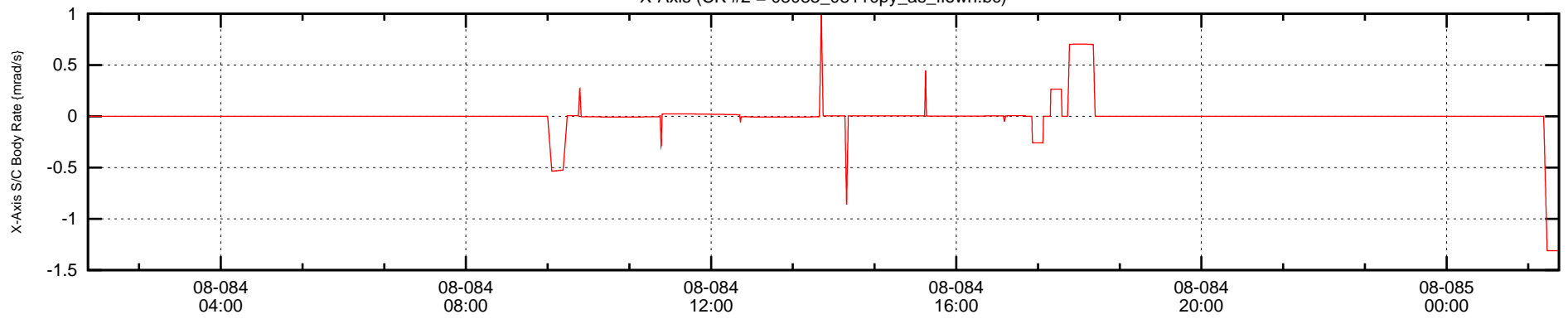
Z-Axis



SCET

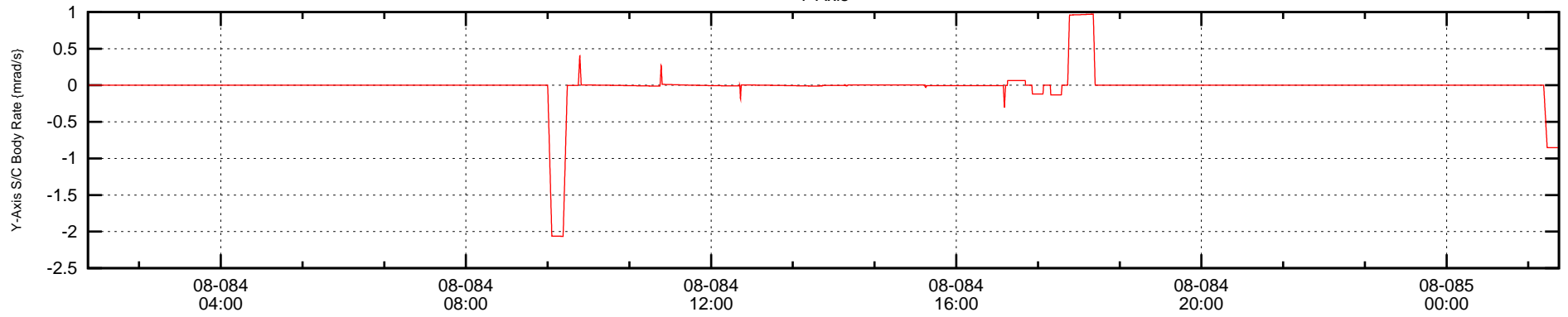
# CK #2 S/C Body Rates (DOY 084-085)

X-Axis (CK #2 = 08083\_08110py\_as\_flowm.bc)



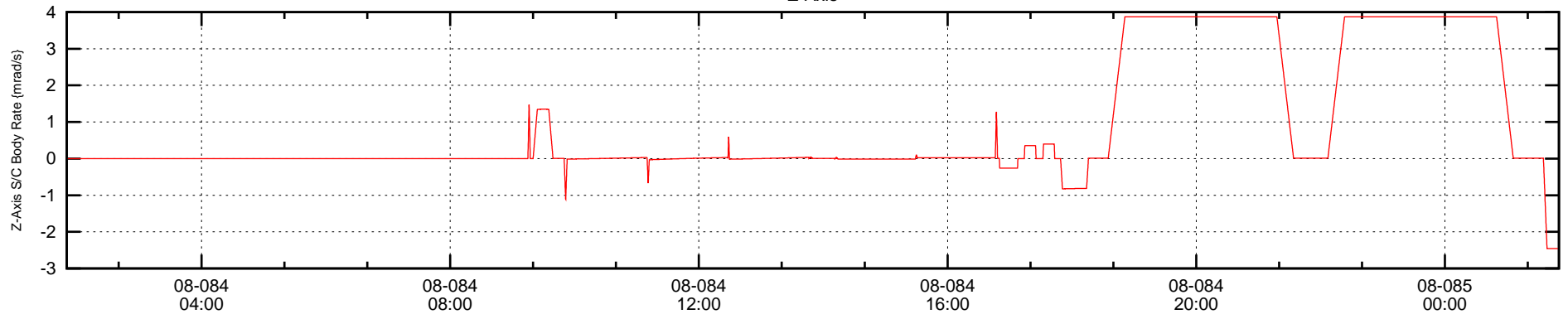
SCET

Y-Axis



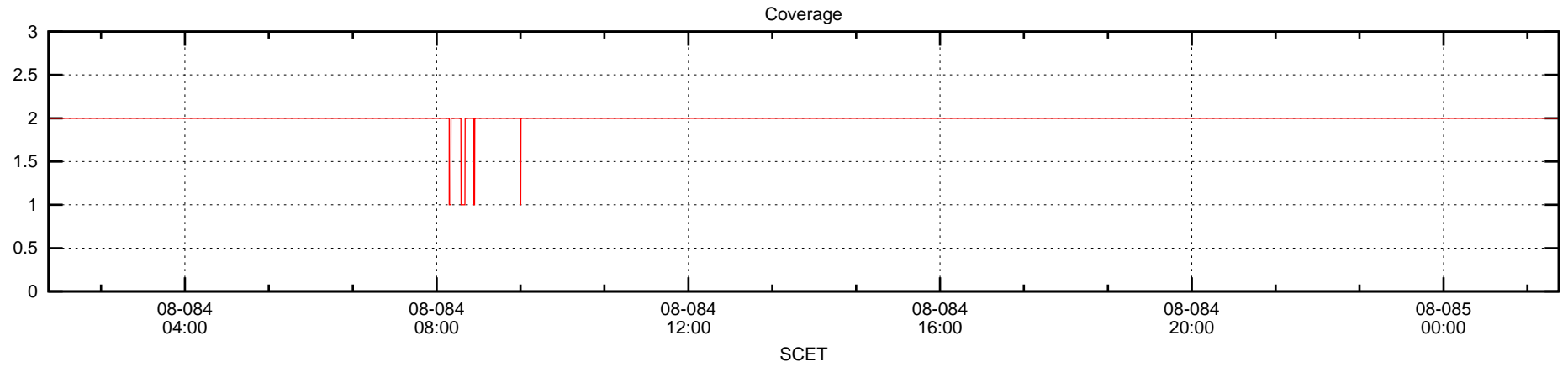
SCET

Z-Axis



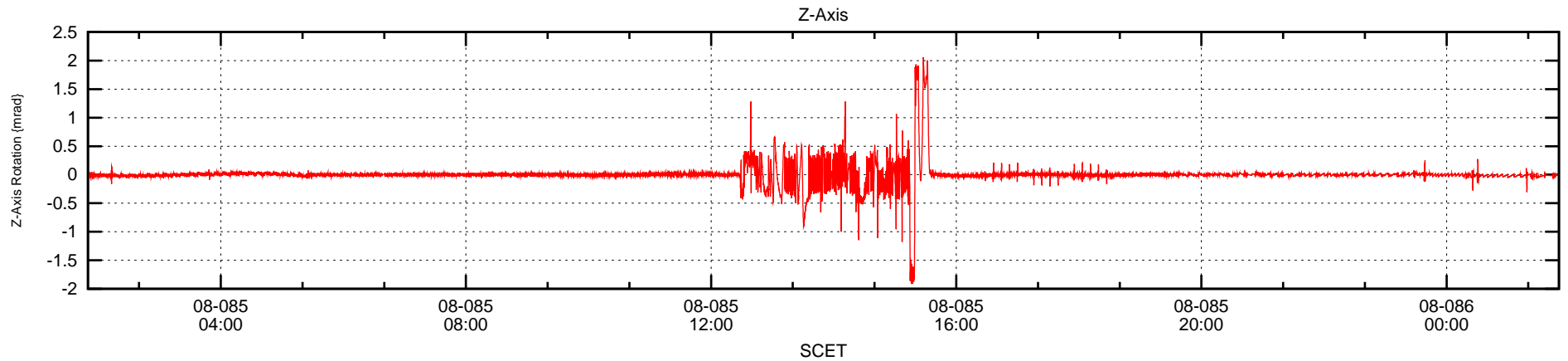
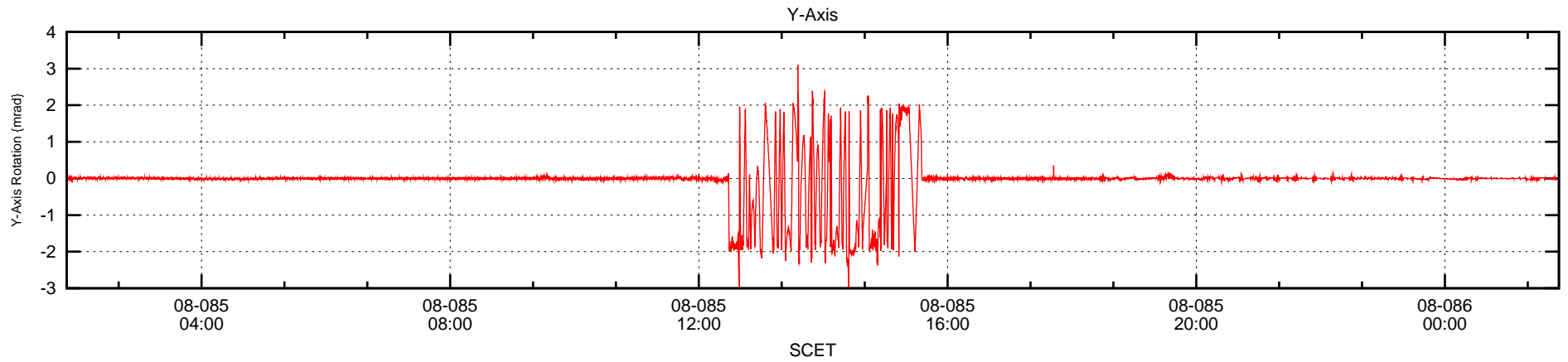
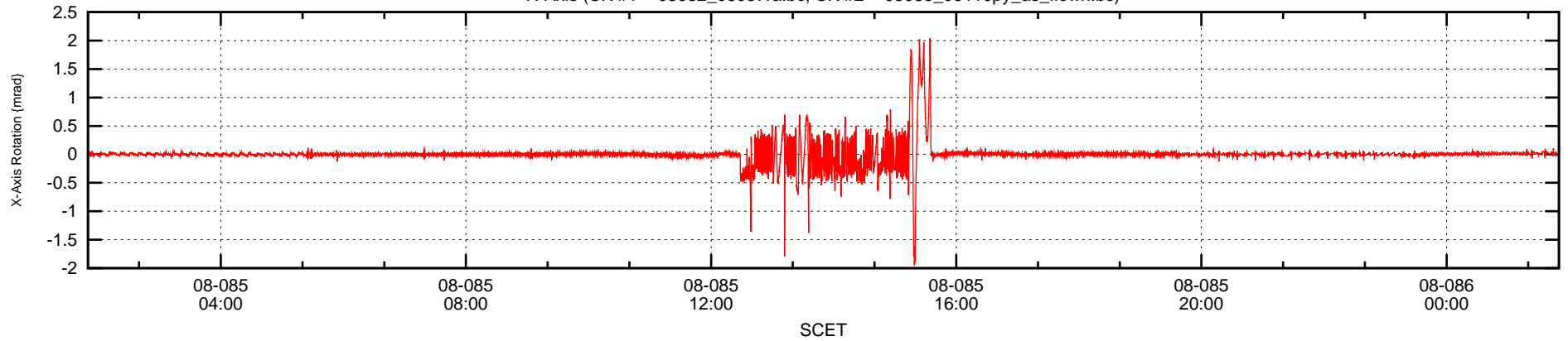
SCET

All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 084-085)



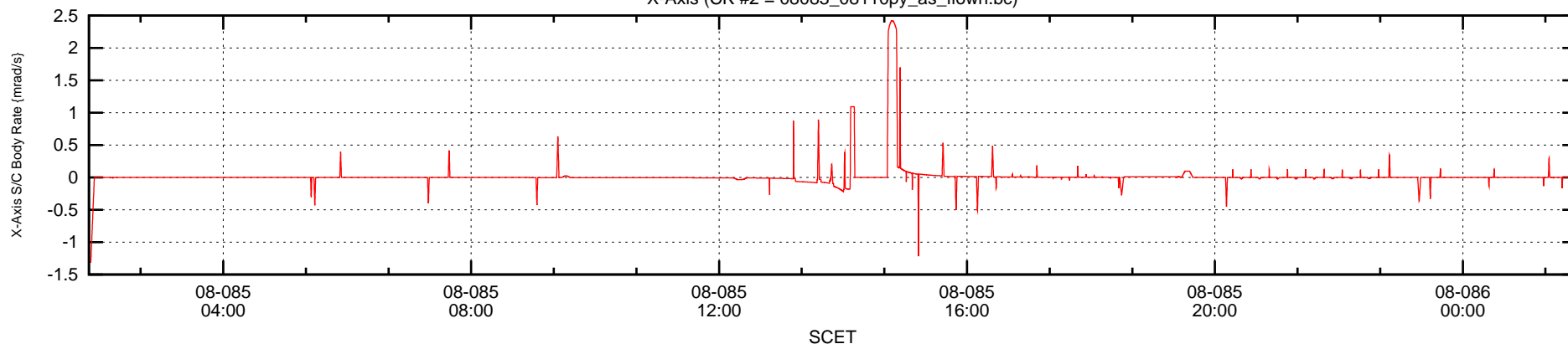
# Rotation From CK #2 to CK #1 (DOY 085-086)

X-Axis (CK #1 = 08082\_08087ra.bc; CK #2 = 08083\_08110py\_as\_flown.bc)

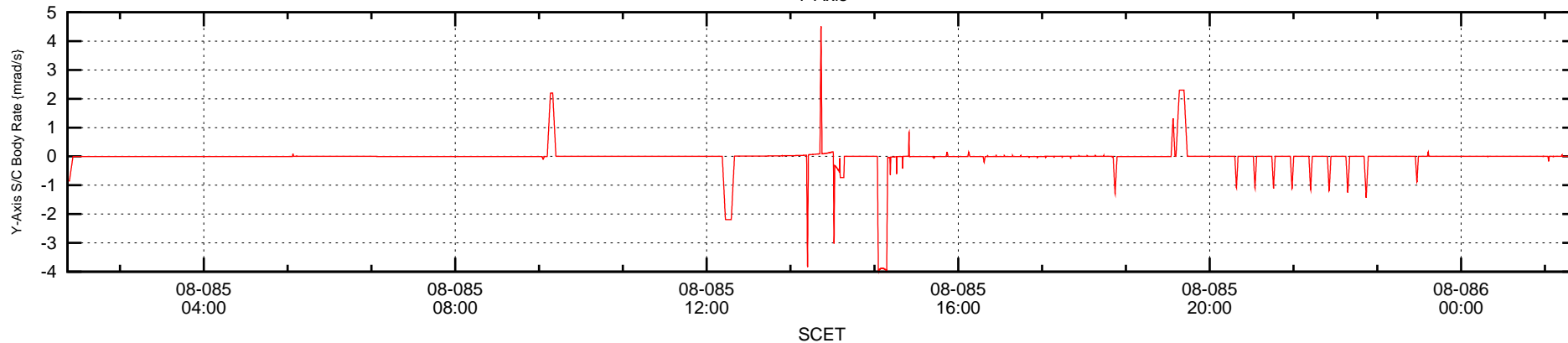


# CK #2 S/C Body Rates (DOY 085-086)

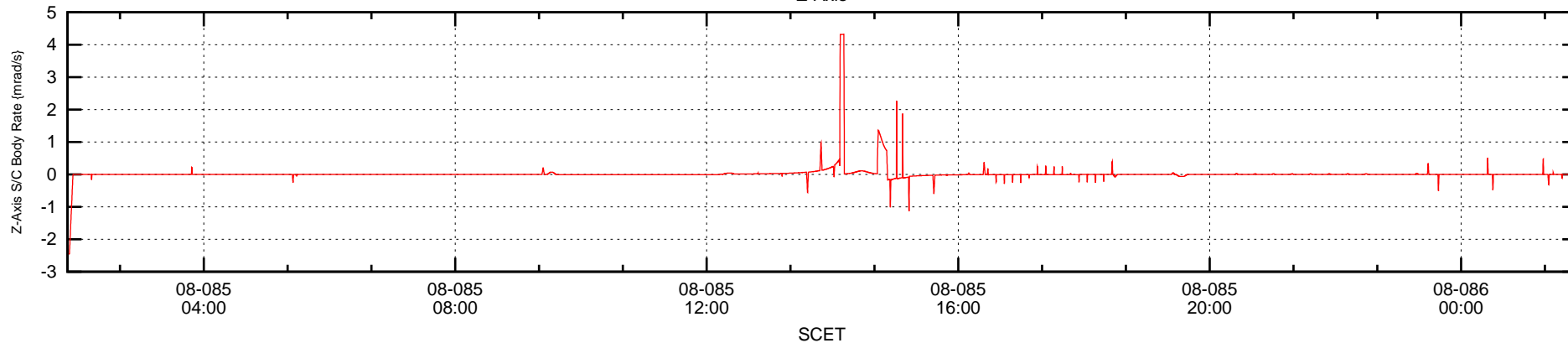
X-Axis (CK #2 = 08083\_08110py\_as\_flown.bc)



Y-Axis

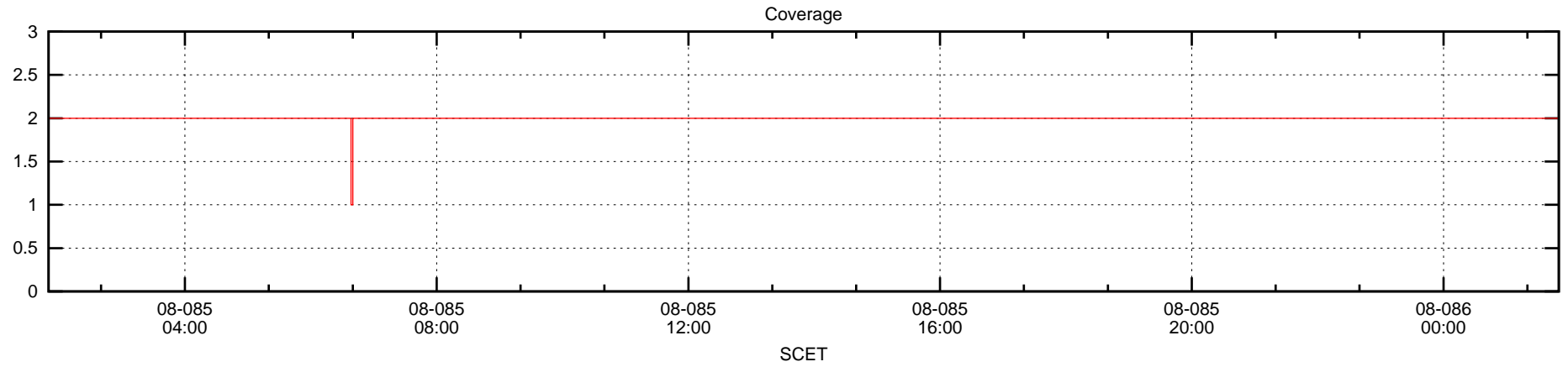


Z-Axis



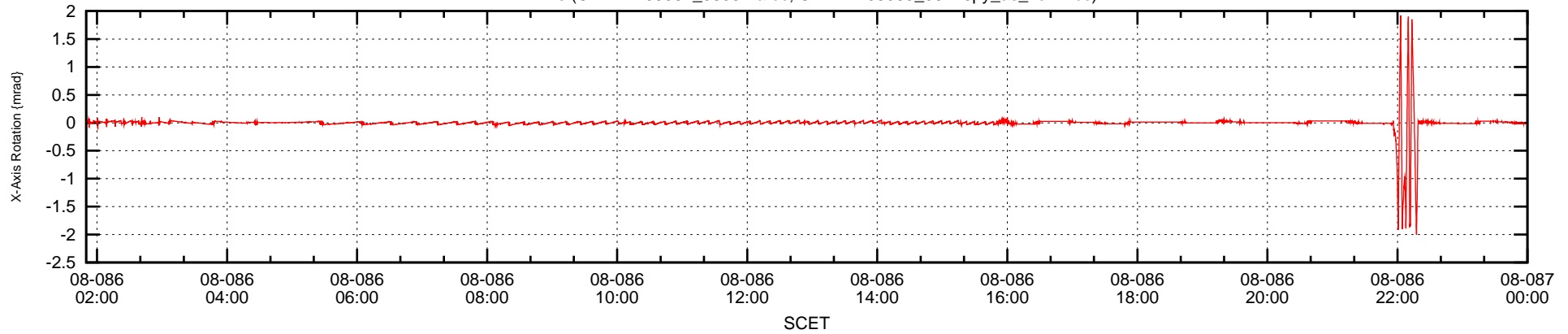


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 085-086)

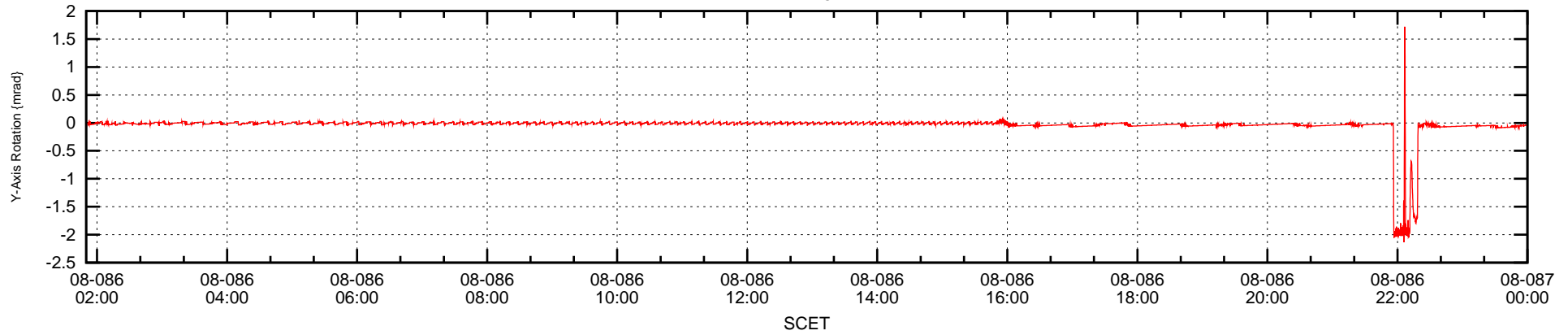


# Rotation From CK #2 to CK #1 (DOY 086-086)

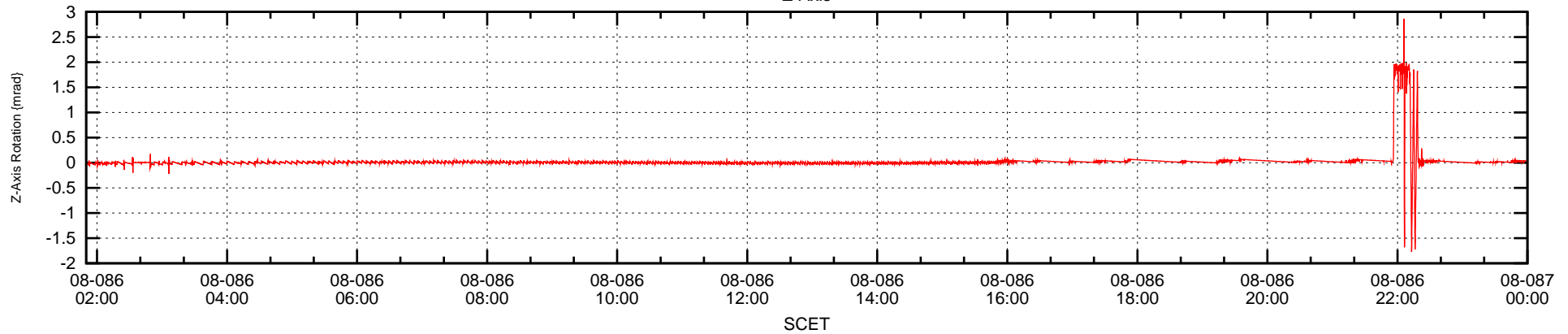
X-Axis (CK #1 = 08082\_08087ra.bc; CK #2 = 08083\_08110py\_as\_flowm.bc)



Y-Axis

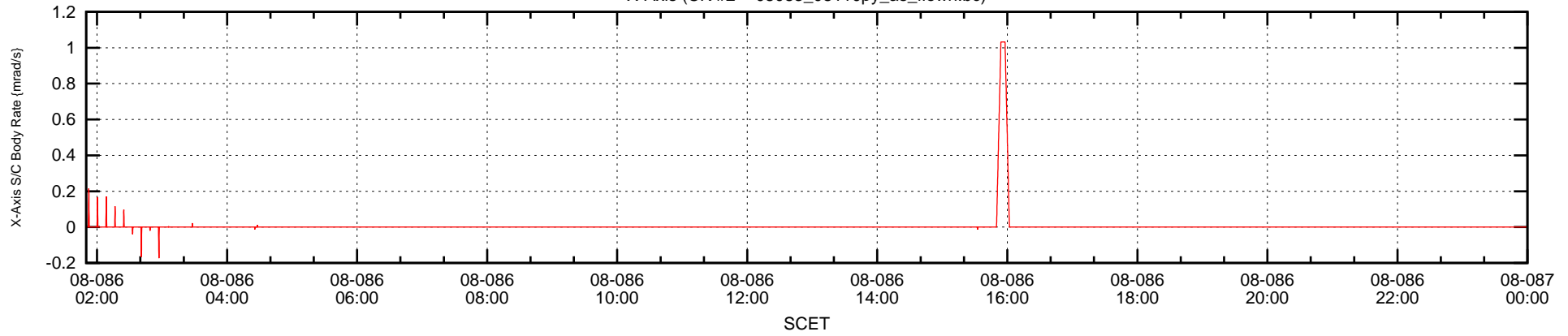


Z-Axis

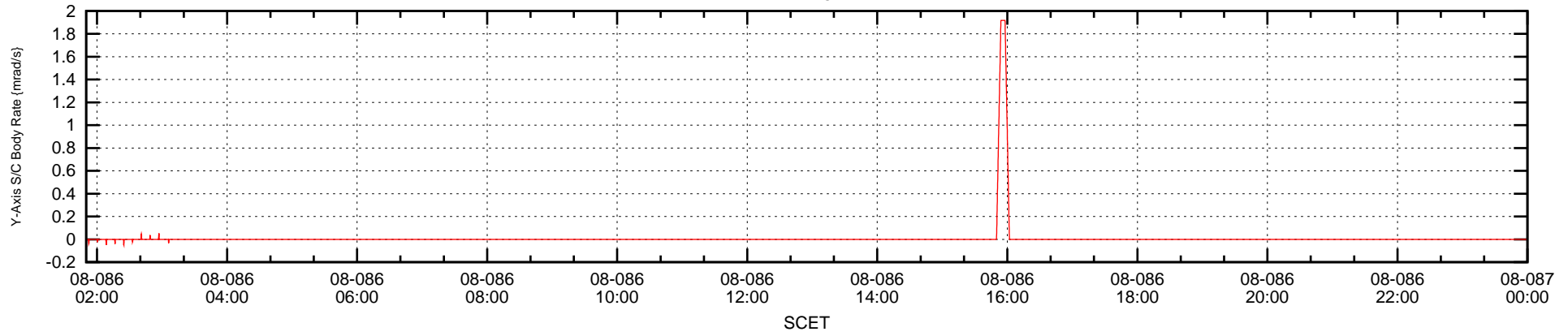


# CK #2 S/C Body Rates (DOY 086-086)

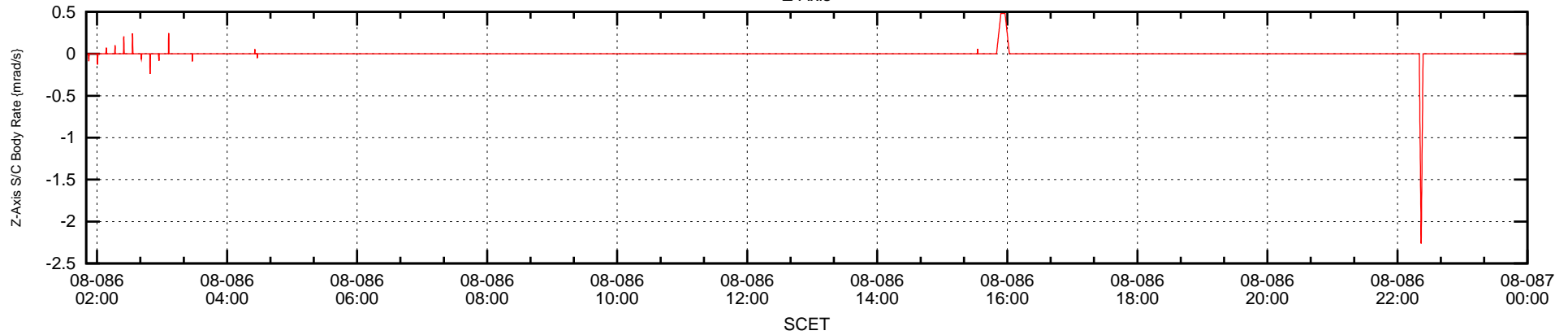
X-Axis (CK #2 = 08083\_08110py\_as\_flowm.bc)



Y-Axis



Z-Axis



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 086-086)

