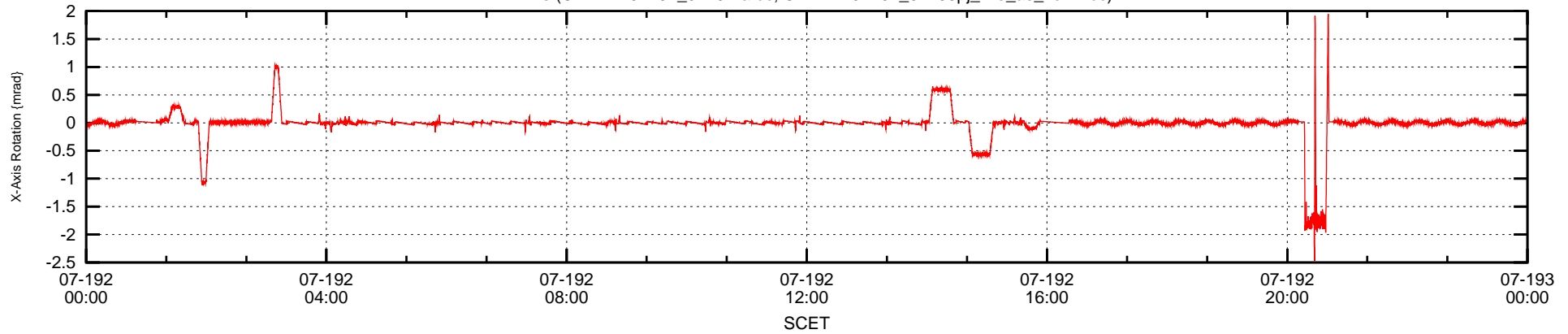
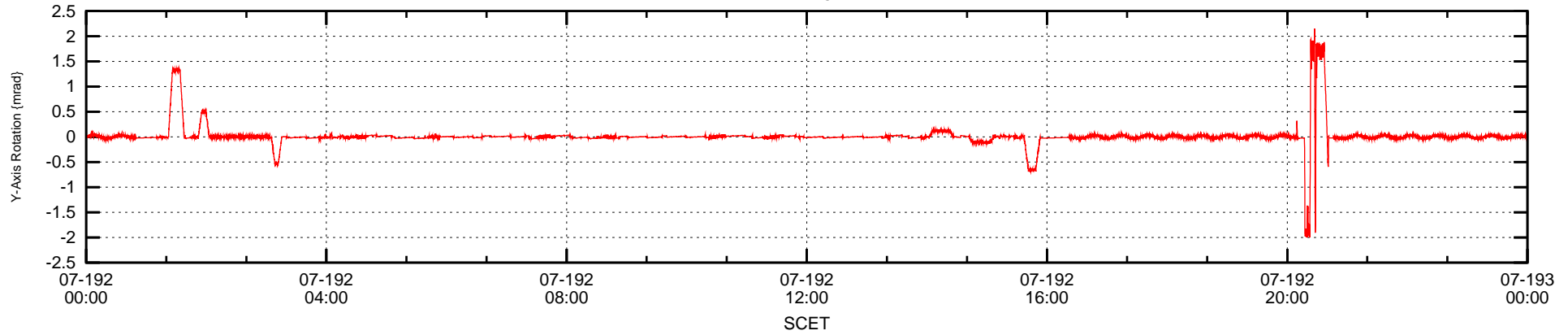


# Rotation From CK #2 to CK #1 (DOY 192-193)

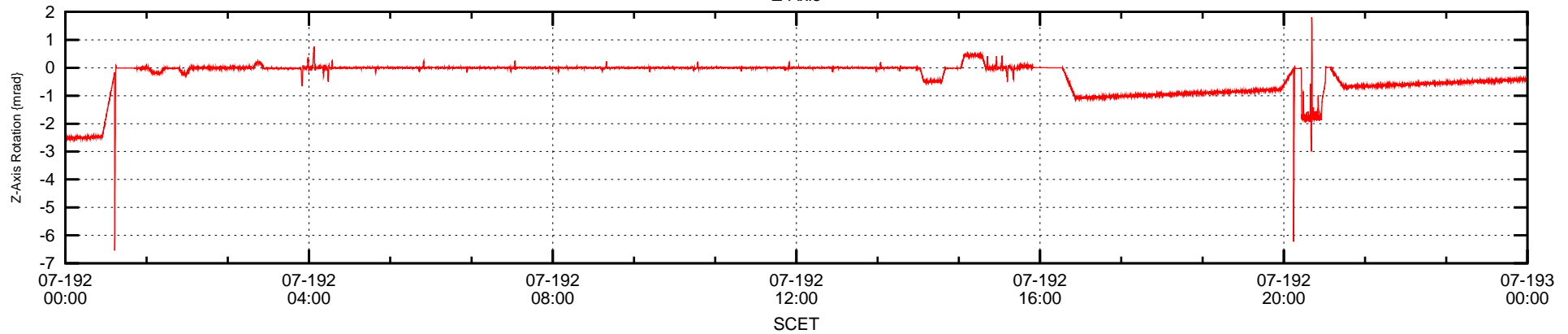
X-Axis (CK #1 = 07192\_07197ra.bc; CK #2 = 07162\_07195pj\_live\_as\_flowm.bc)



Y-Axis

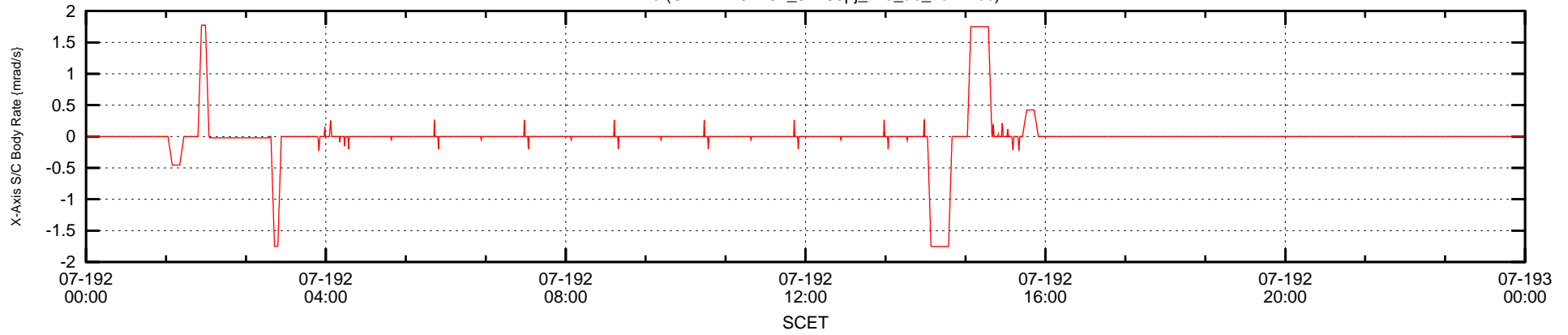


Z-Axis

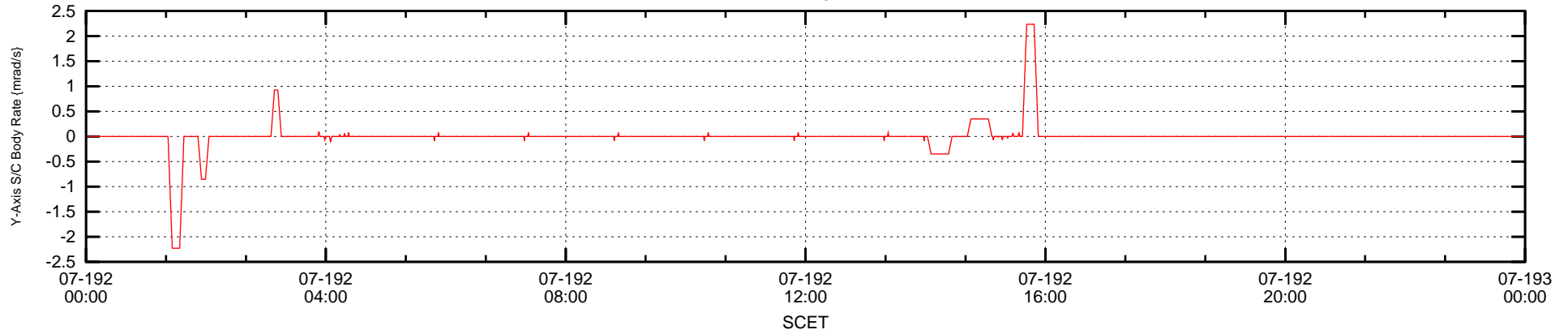


# CK #2 S/C Body Rates (DOY 192-193)

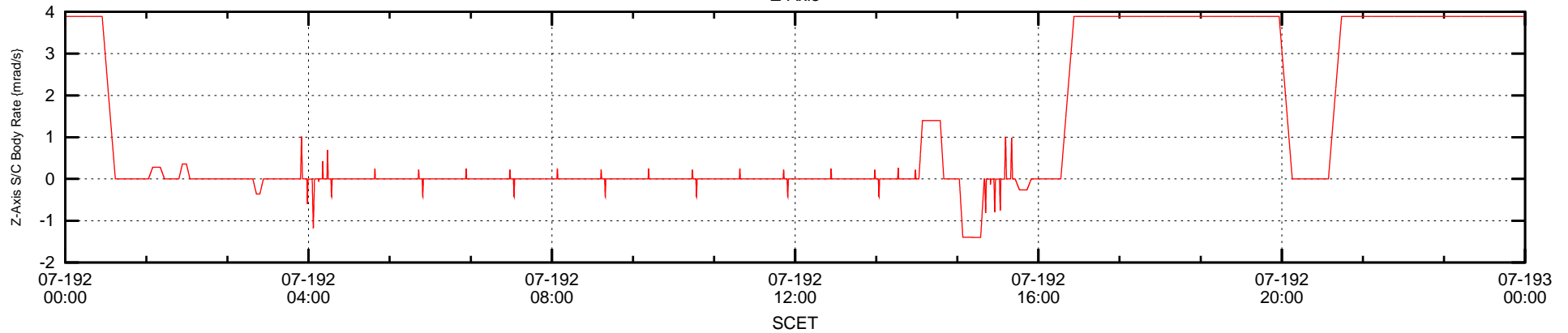
X-Axis (CK #2 = 07162\_07195pj\_live\_as\_flown.bc)



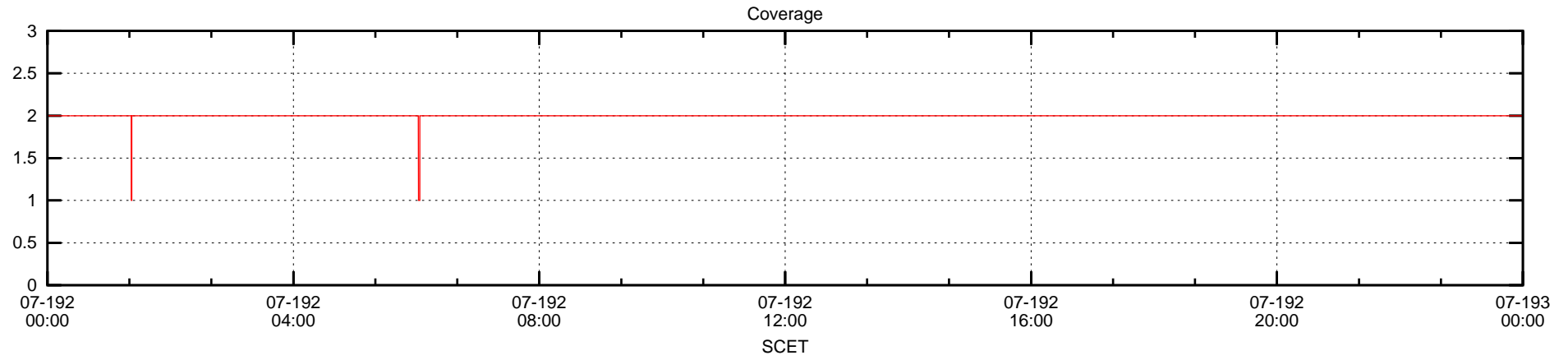
Y-Axis



Z-Axis

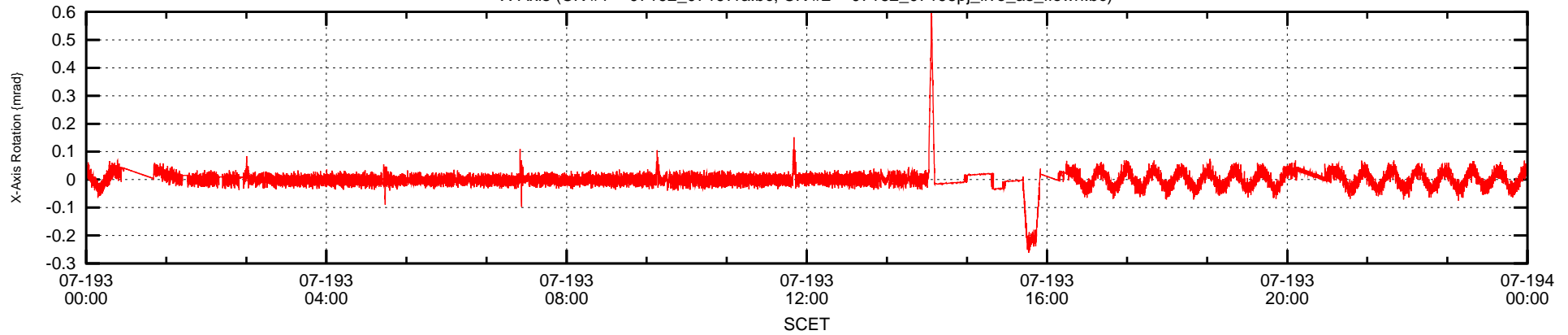


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 192-193)

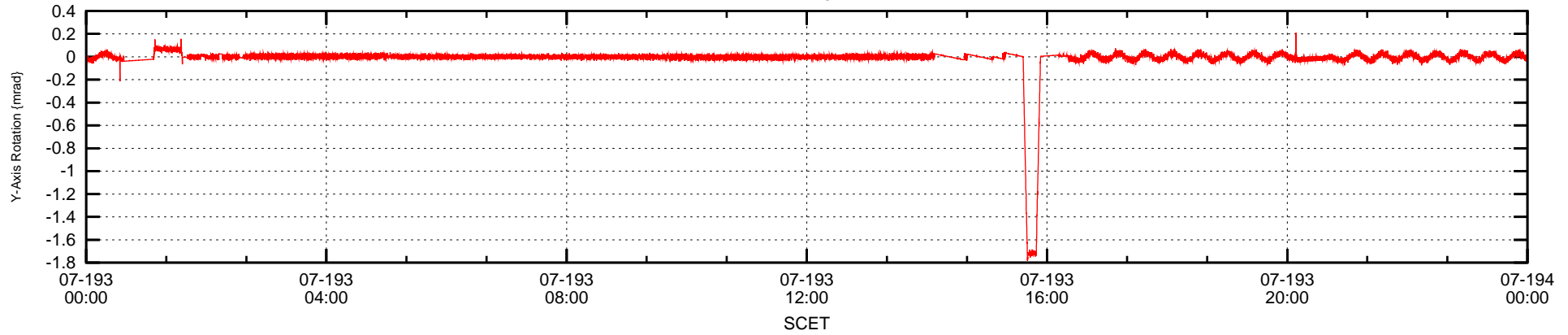


# Rotation From CK #2 to CK #1 (DOY 193-194)

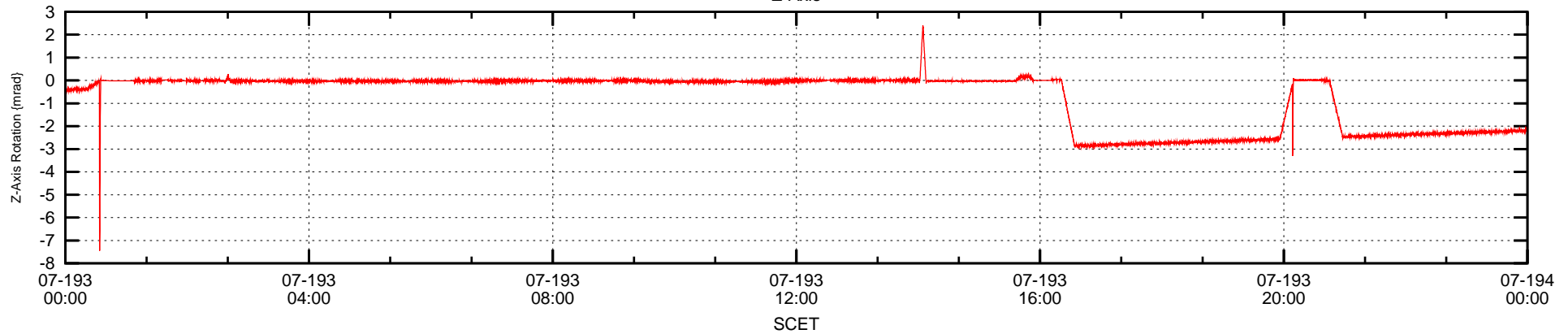
X-Axis (CK #1 = 07192\_07197ra.bc; CK #2 = 07162\_07195pj\_live\_as\_flown.bc)



Y-Axis

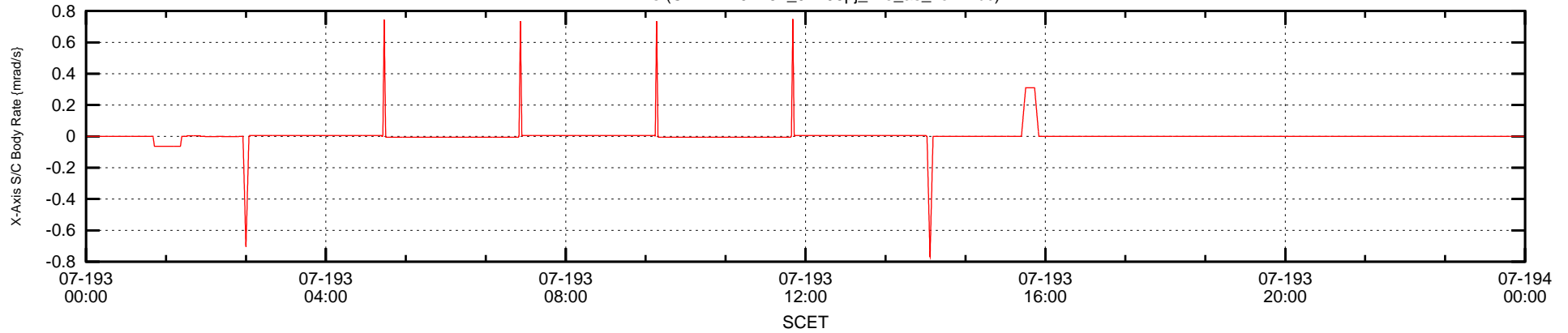


Z-Axis

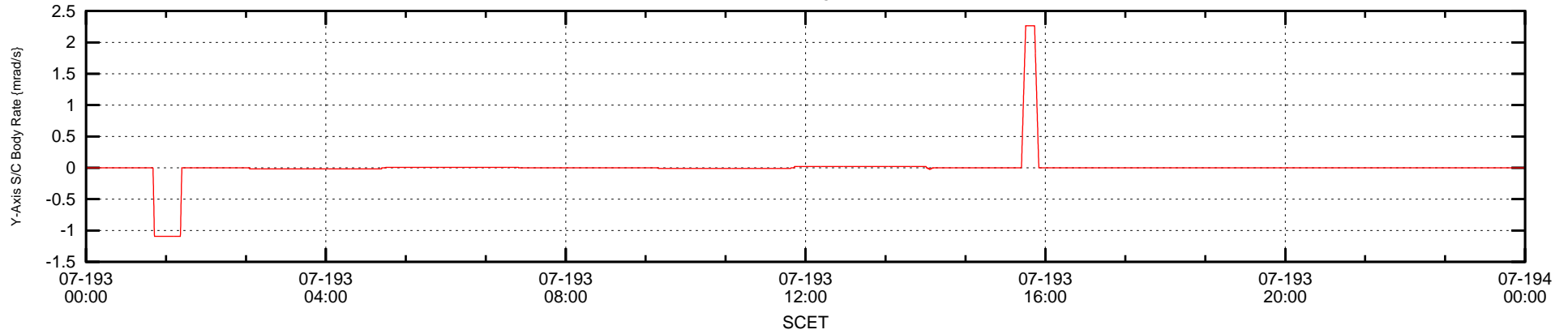


# CK #2 S/C Body Rates (DOY 193-194)

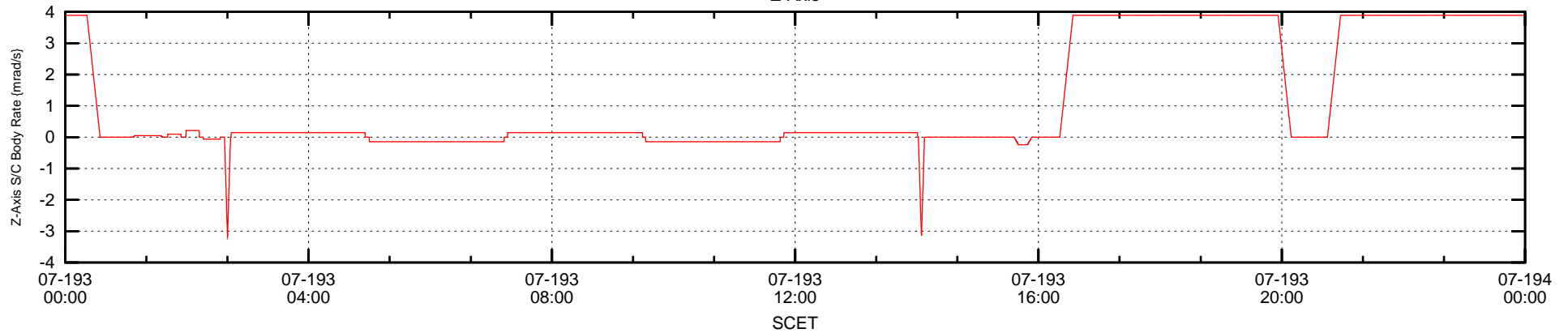
X-Axis (CK #2 = 07162\_07195pj\_live\_as\_flown.bc)



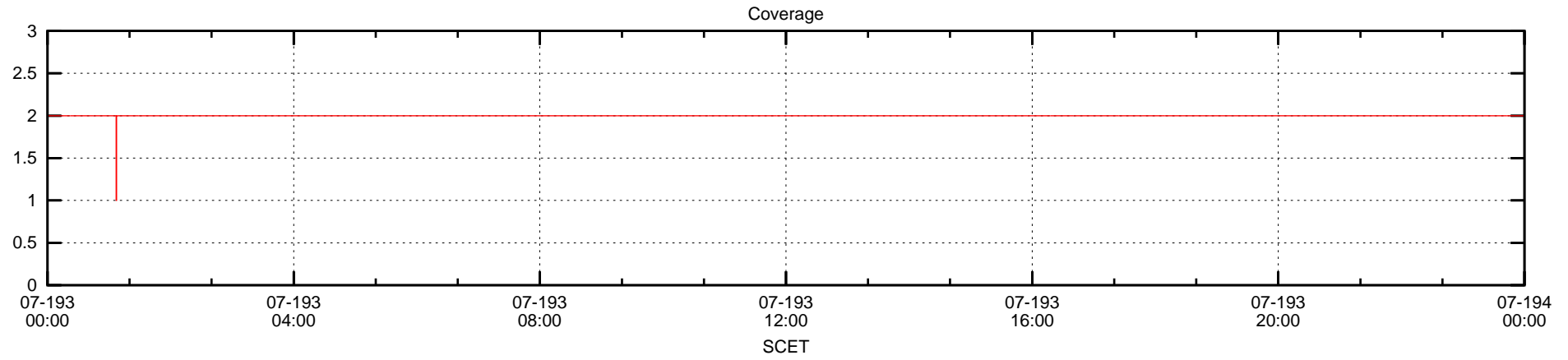
Y-Axis



Z-Axis

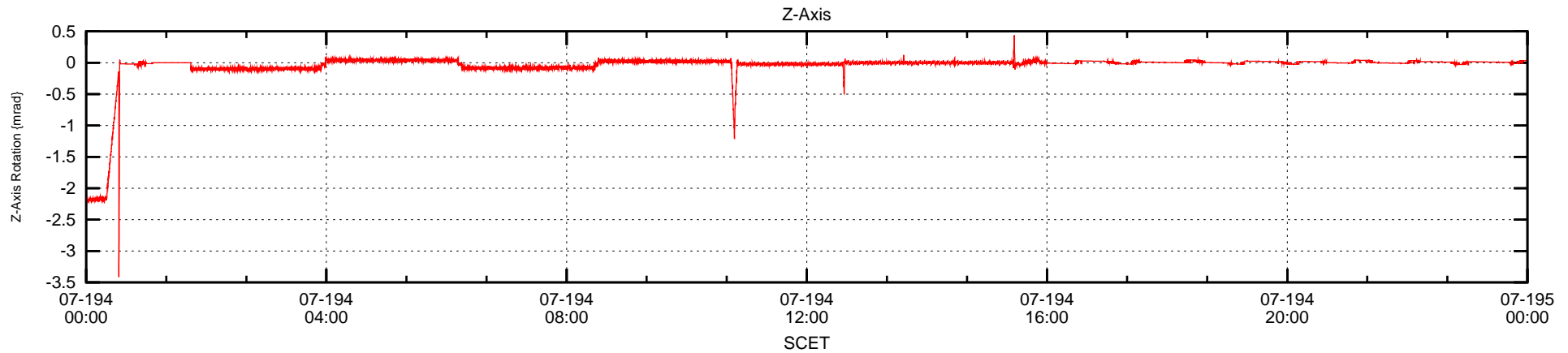
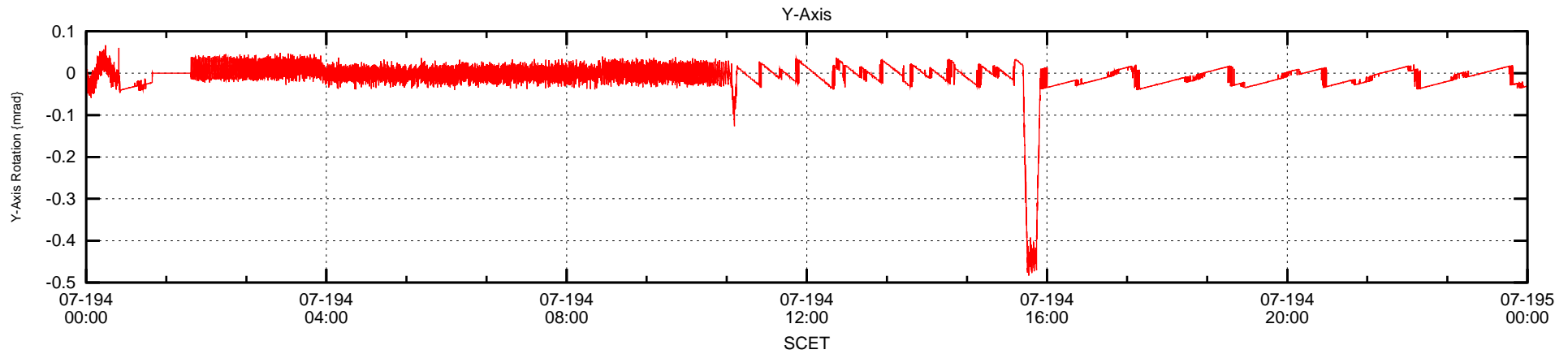
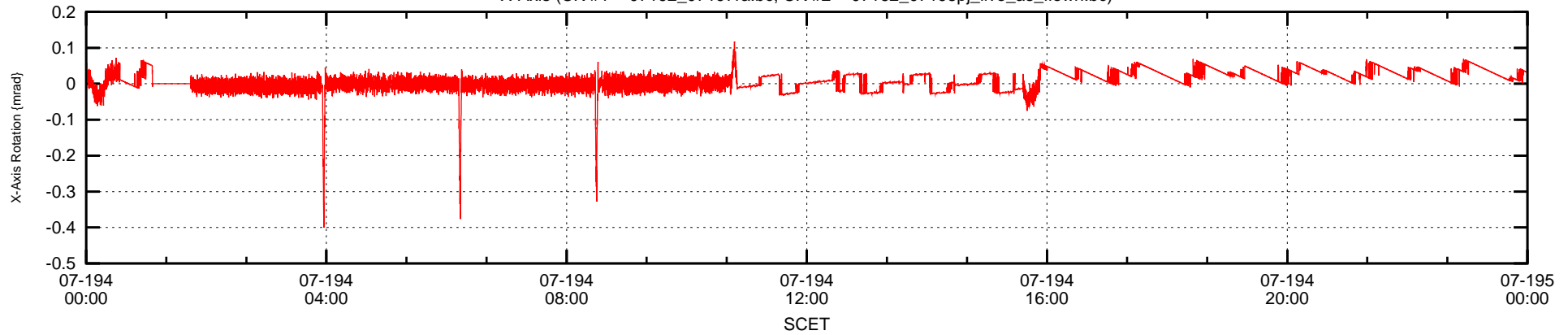


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 193-194)



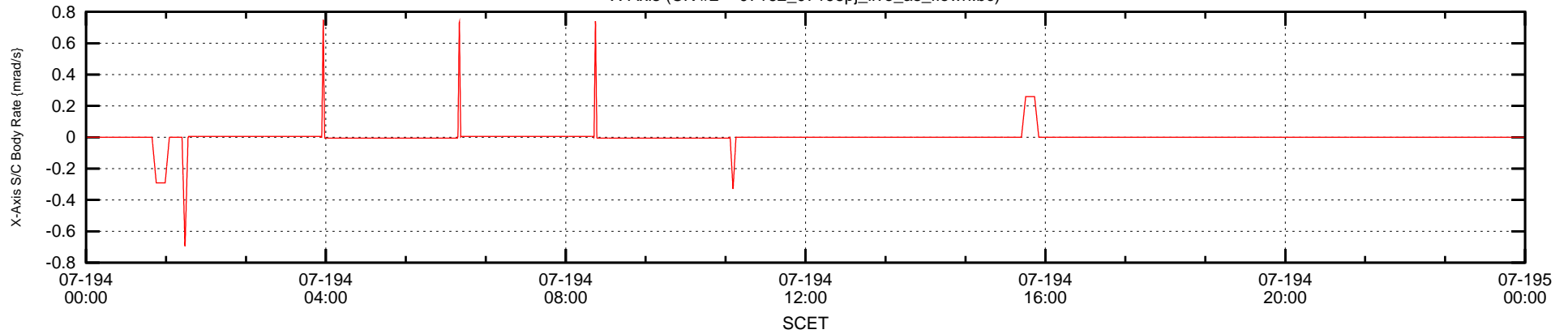
# Rotation From CK #2 to CK #1 (DOY 194-195)

X-Axis (CK #1 = 07192\_07197ra.bc; CK #2 = 07162\_07195pj\_live\_as\_flow.bc)

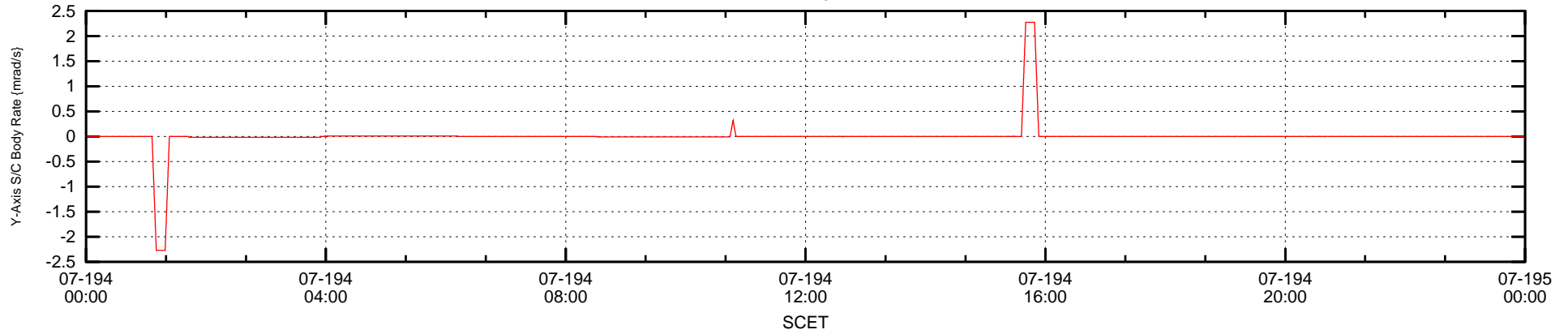


# CK #2 S/C Body Rates (DOY 194-195)

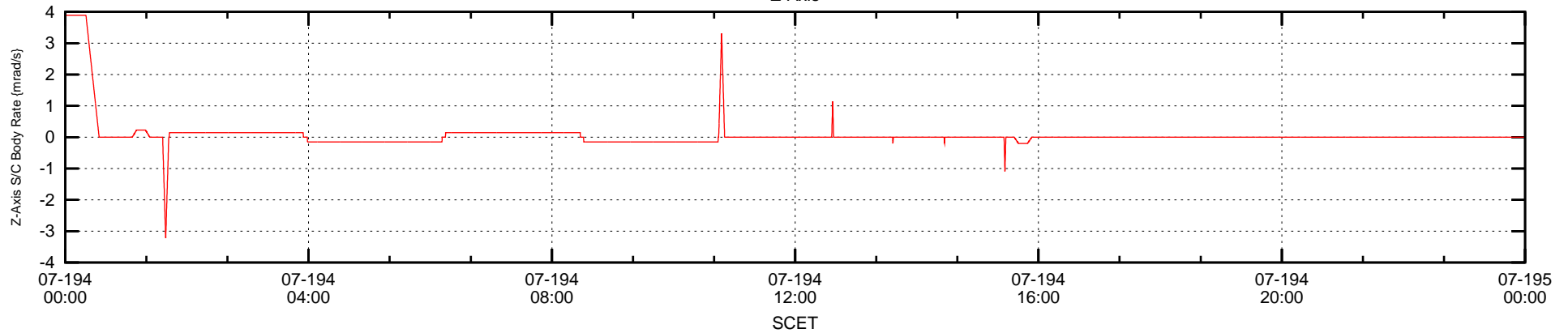
X-Axis (CK #2 = 07162\_07195pj\_live\_as\_flown.bc)



Y-Axis

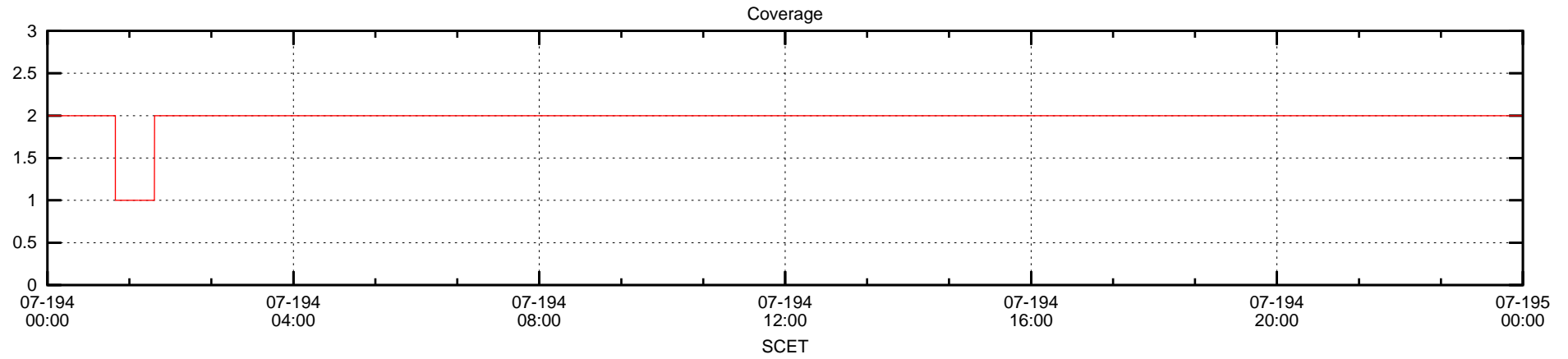


Z-Axis



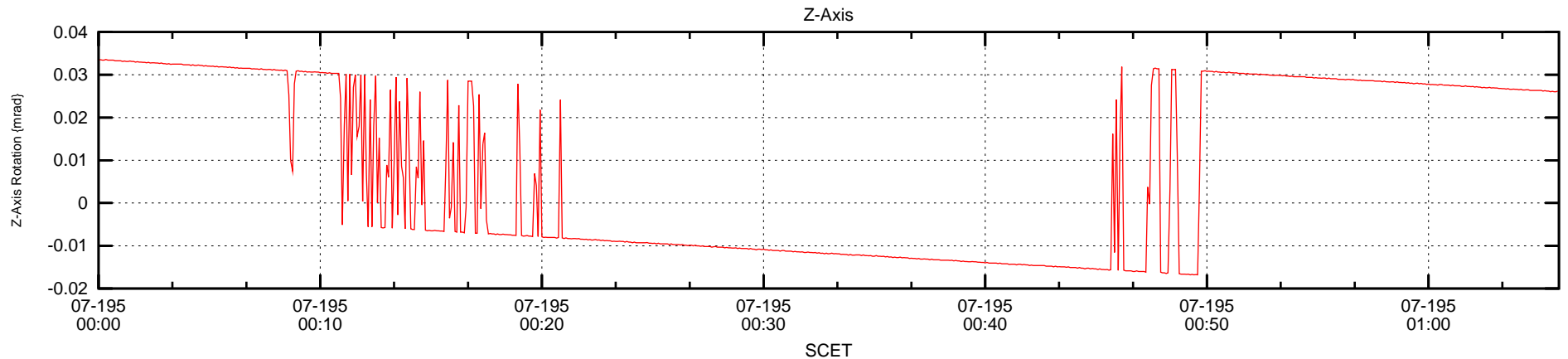
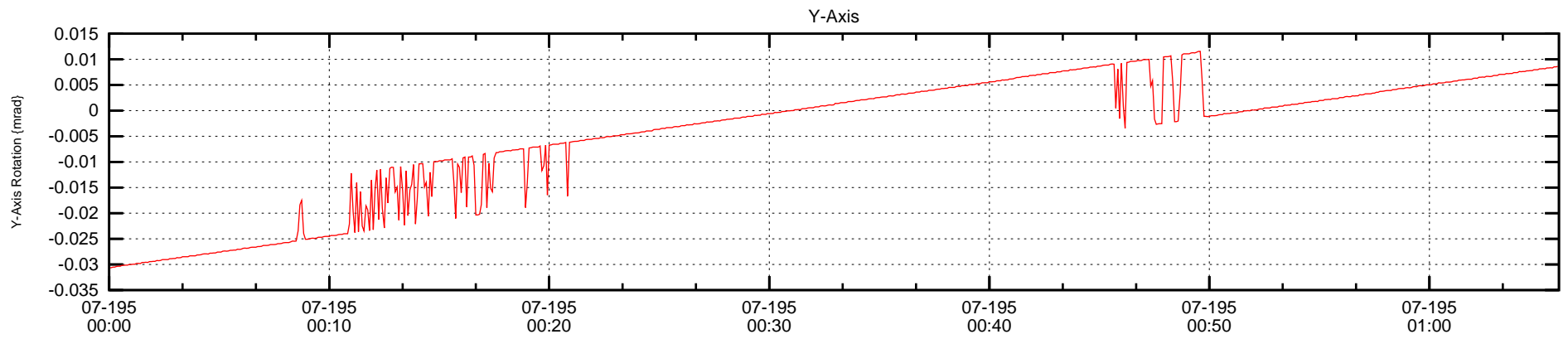
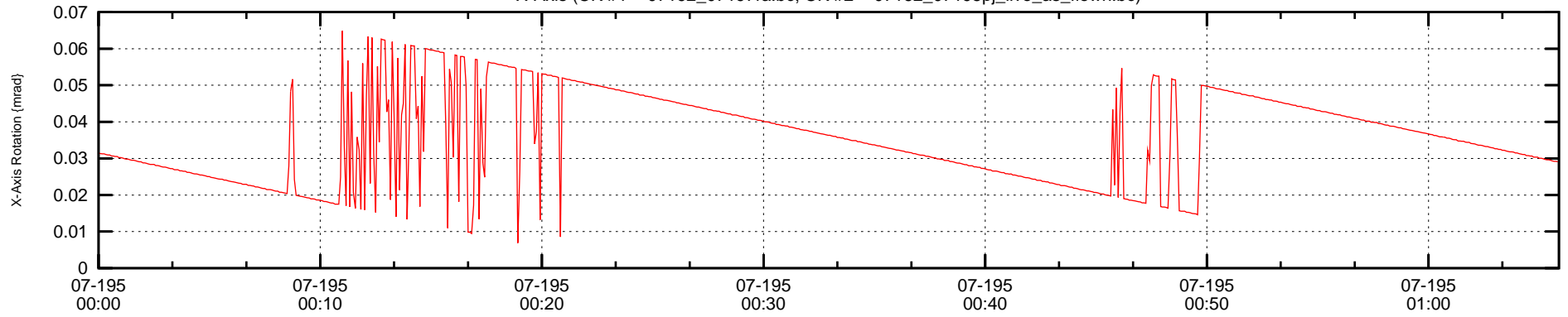


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 194-195)



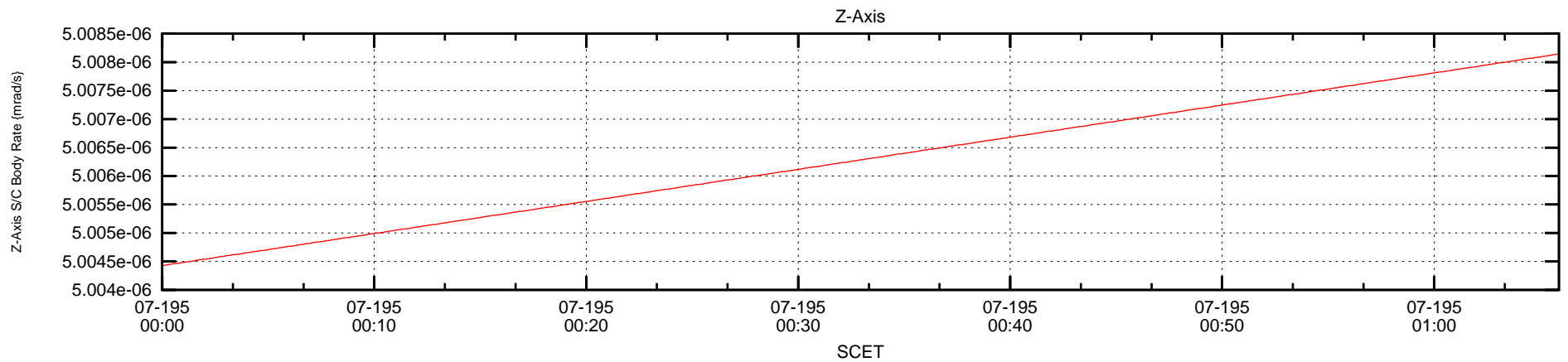
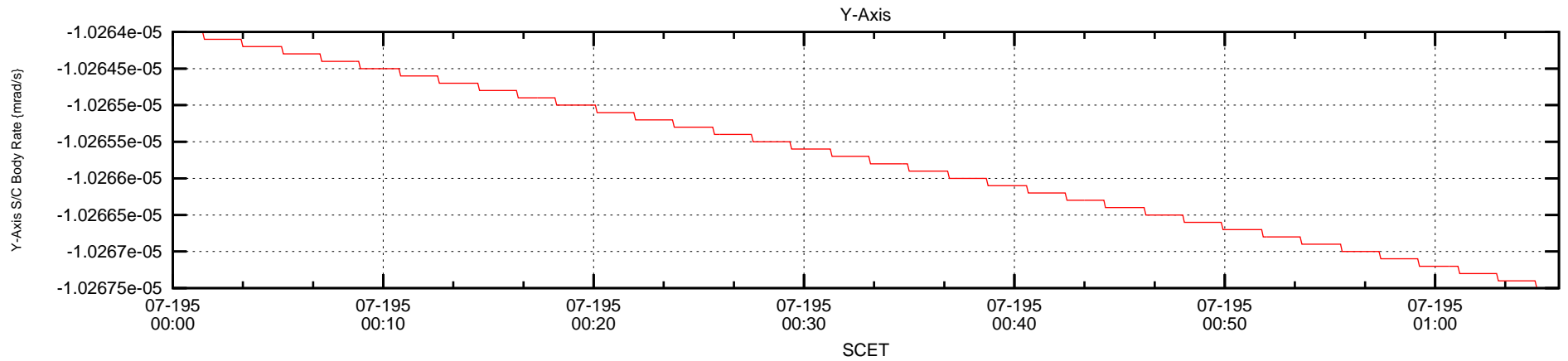
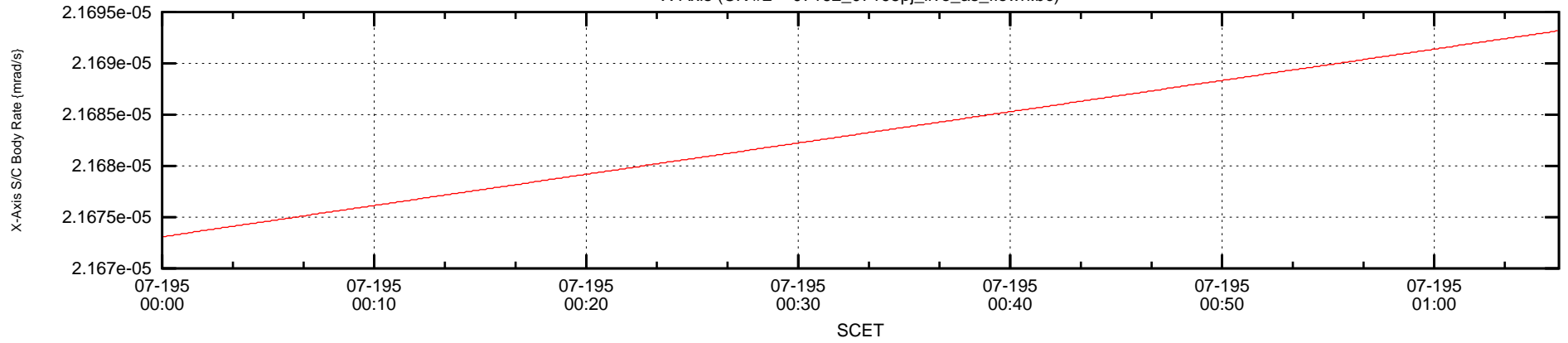
# Rotation From CK #2 to CK #1 (DOY 195-195)

X-Axis (CK #1 = 07192\_07197ra.bc; CK #2 = 07162\_07195pj\_live\_as\_flown.bc)



# CK #2 S/C Body Rates (DOY 195-195)

X-Axis (CK #2 = 07162\_07195pj\_live\_as\_flown.bc)



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 195-195)

