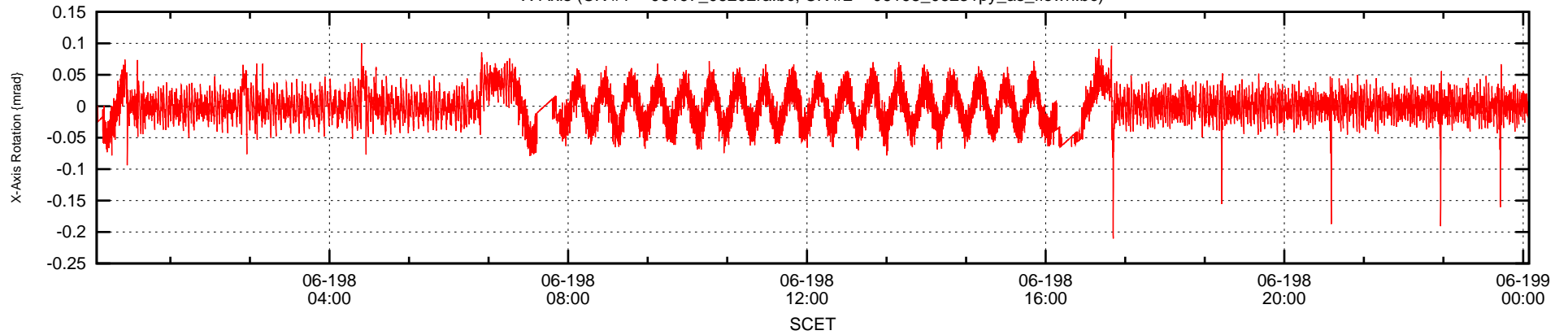
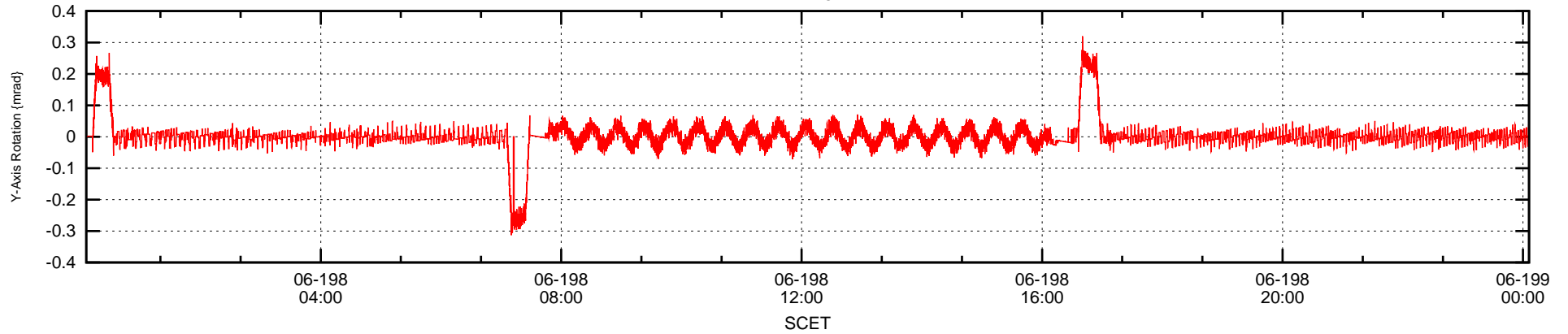


Rotation From CK #2 to CK #1 (DOY 198-199)

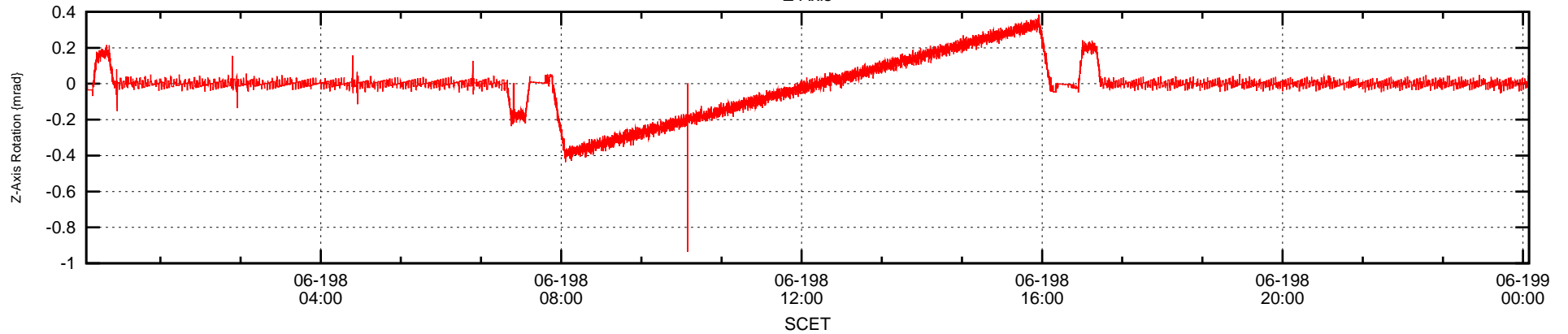
X-Axis (CK #1 = 06197_06202ra.bc; CK #2 = 06198_06231py_as_flown.bc)



Y-Axis

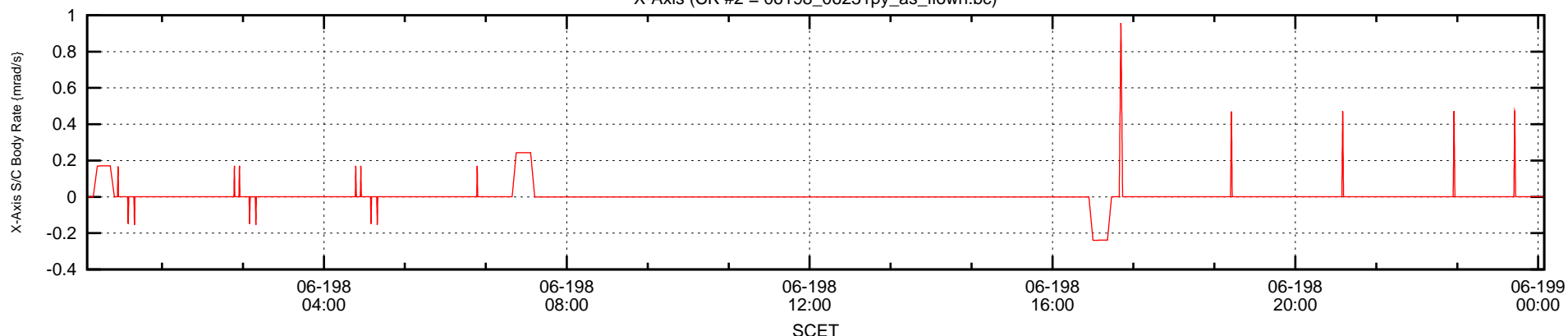


Z-Axis

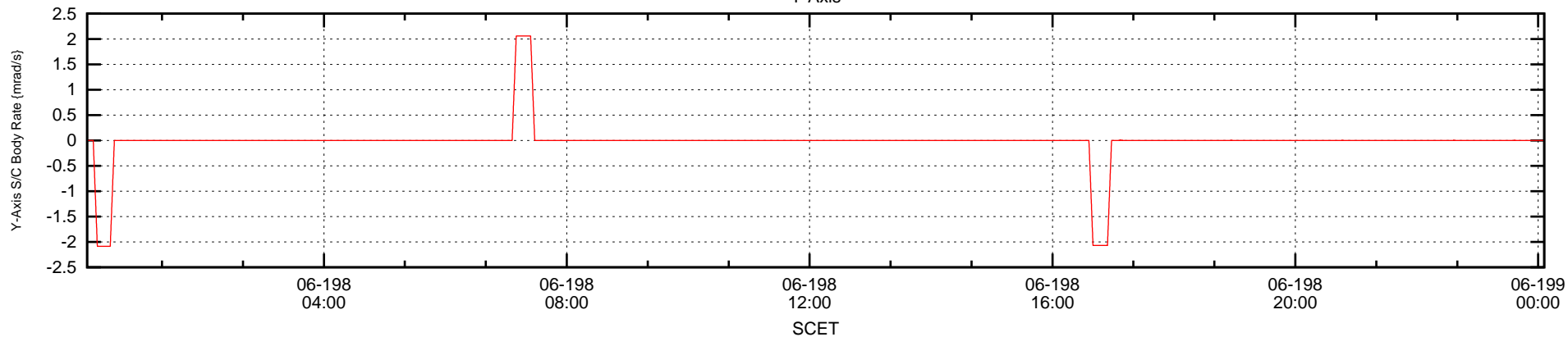


CK #2 S/C Body Rates (DOY 198-199)

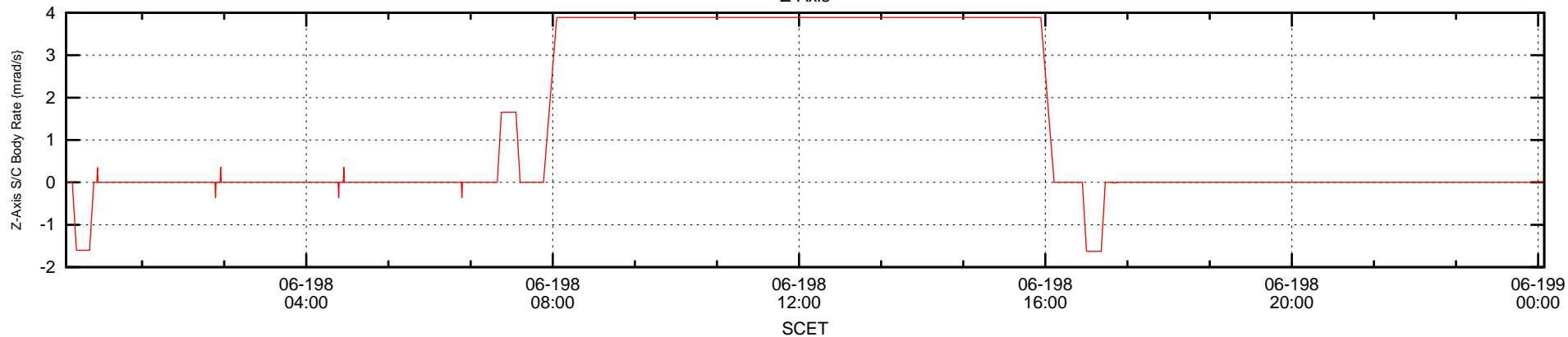
X-Axis (CK #2 = 06198_06231py_as_flowm.bc)



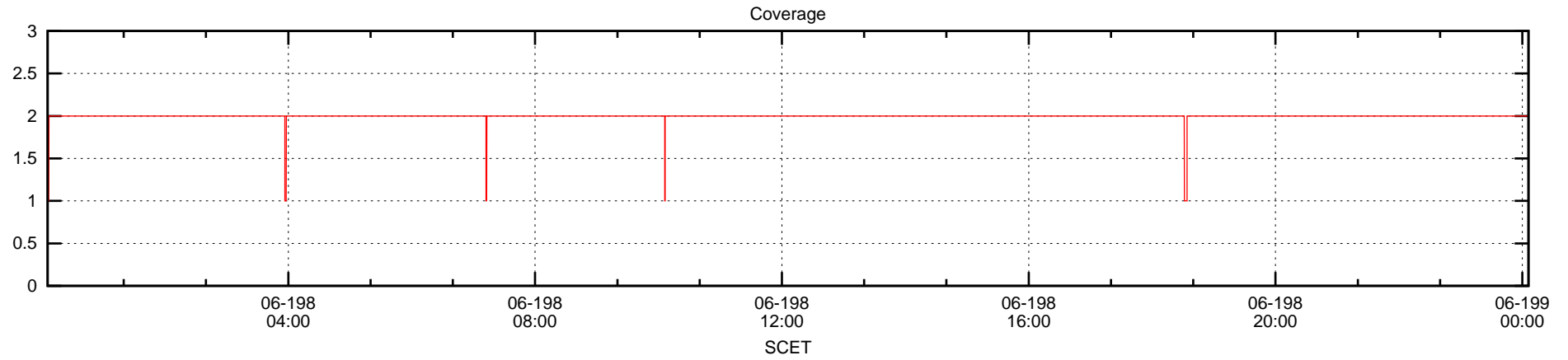
Y-Axis



Z-Axis

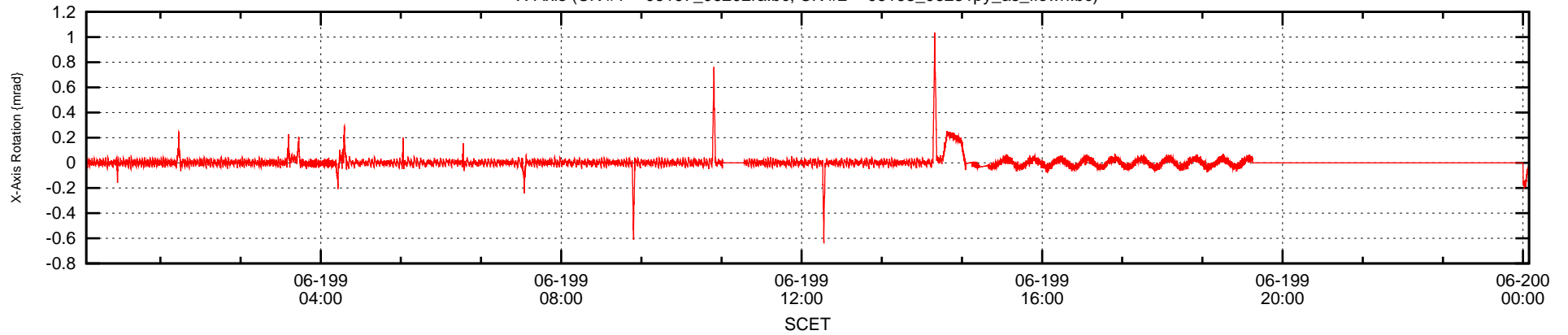


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 198-199)

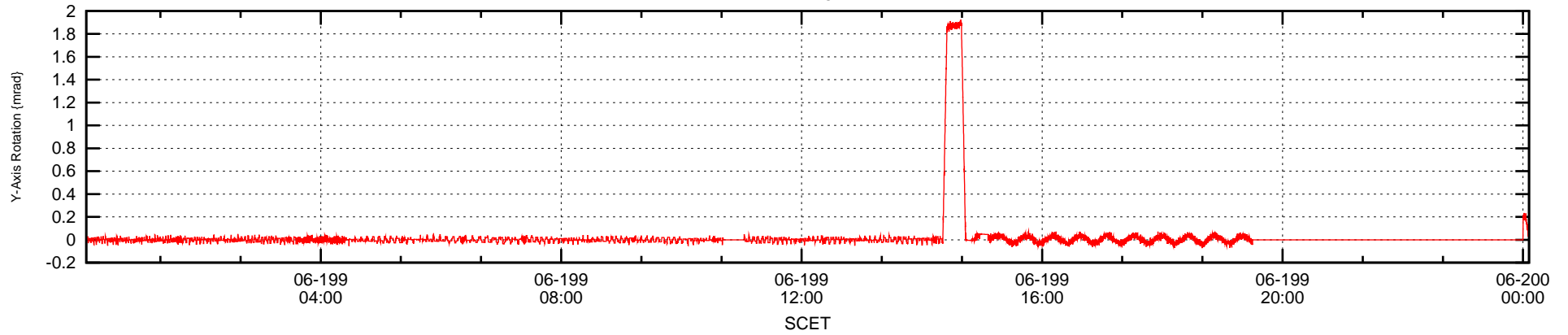


Rotation From CK #2 to CK #1 (DOY 199-200)

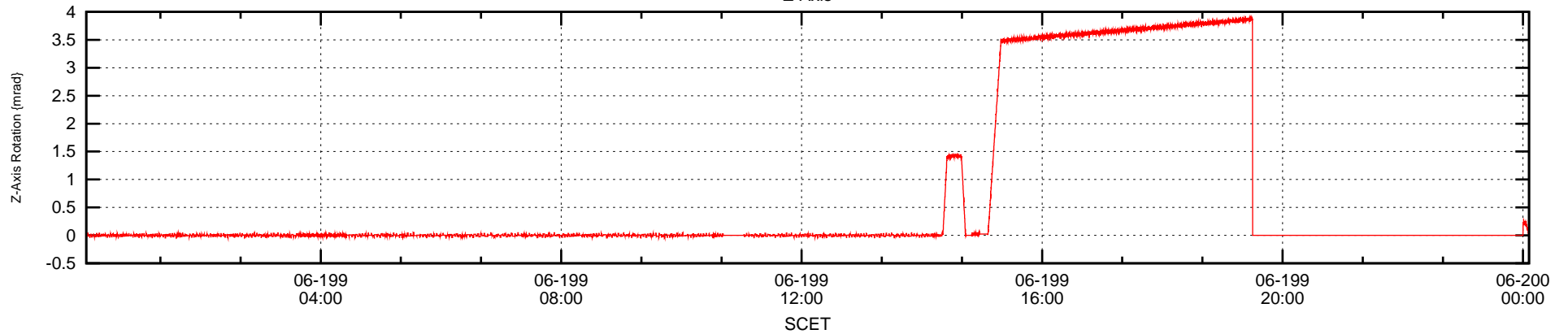
X-Axis (CK #1 = 06197_06202ra.bc; CK #2 = 06198_06231py_as_flowm.bc)



Y-Axis

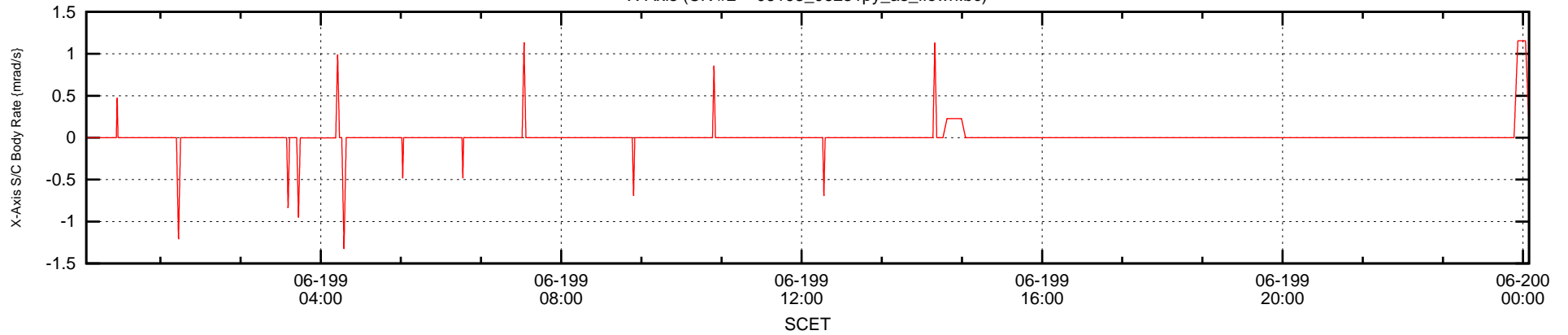


Z-Axis

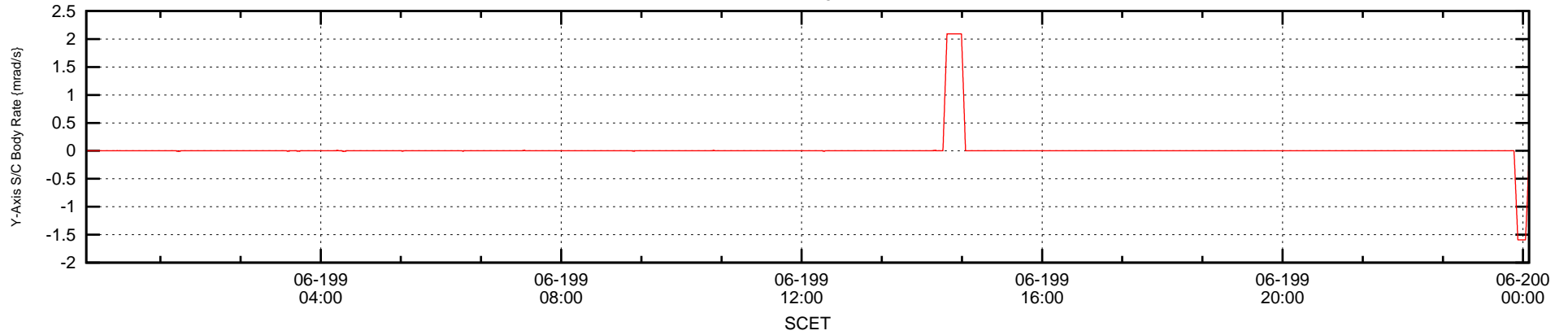


CK #2 S/C Body Rates (DOY 199-200)

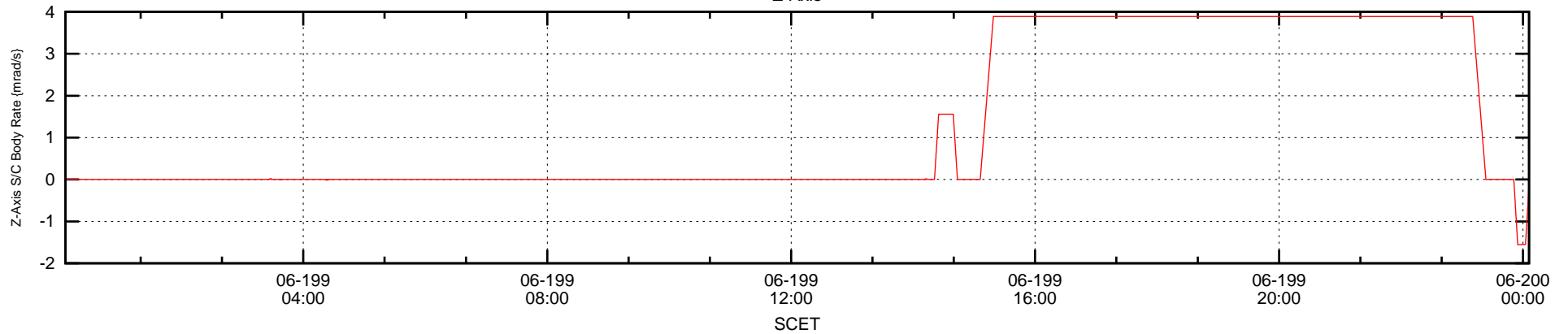
X-Axis (CK #2 = 06198_06231py_as_flown.bc)



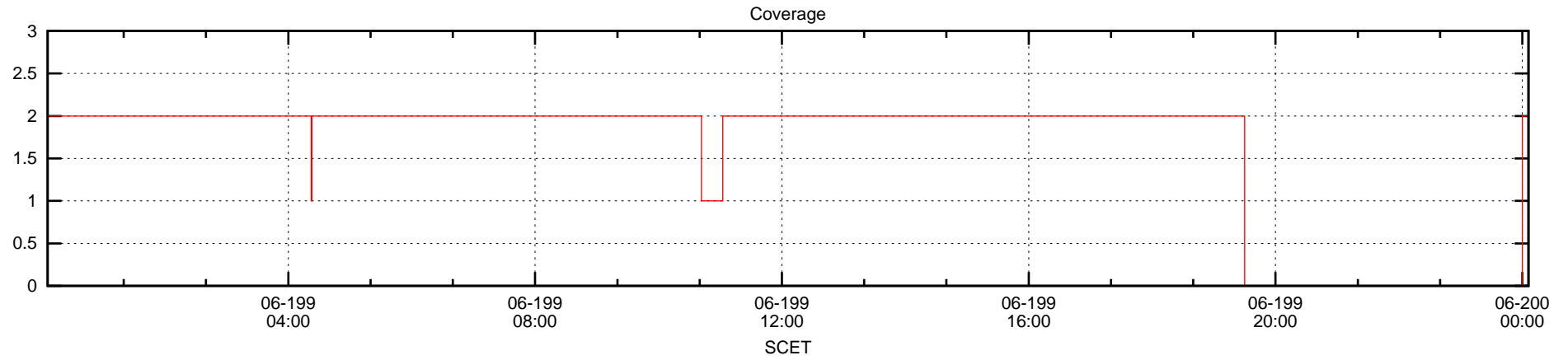
Y-Axis



Z-Axis

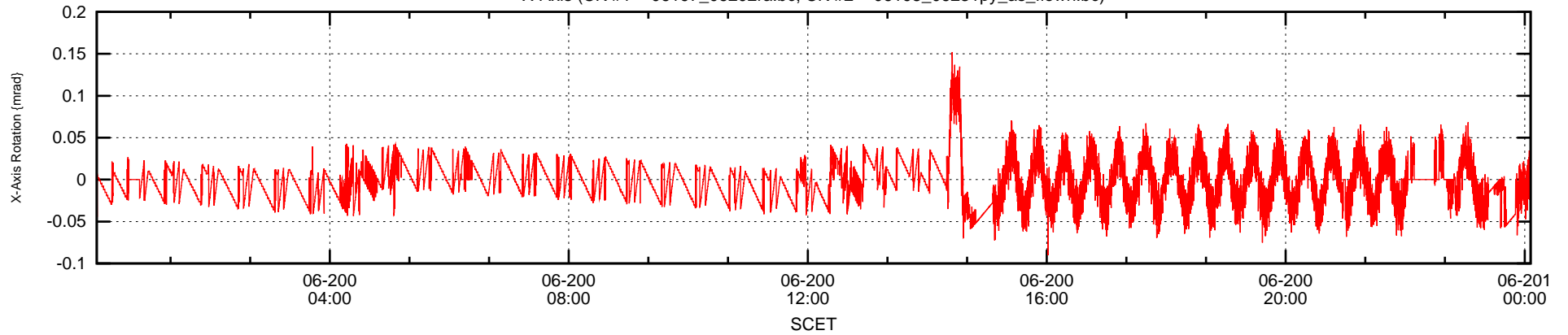


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 199-200)

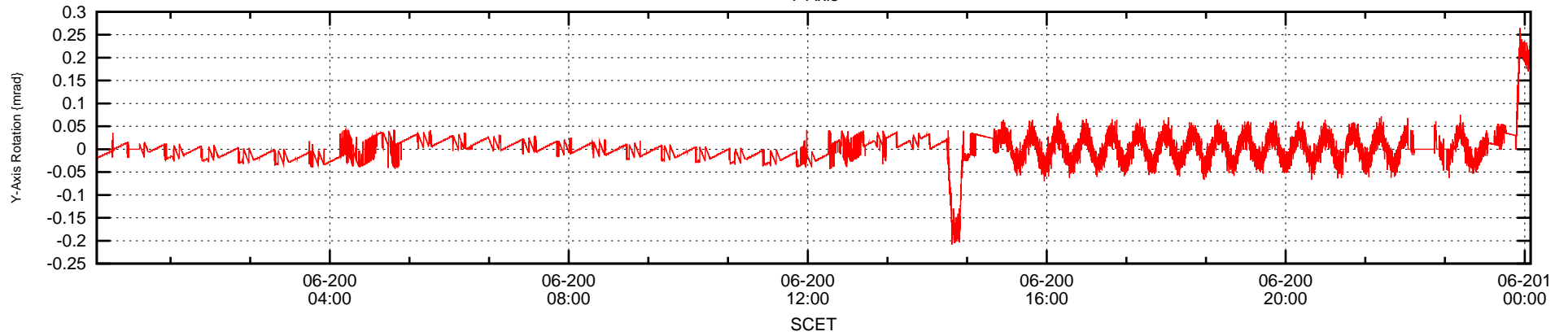


Rotation From CK #2 to CK #1 (DOY 200-201)

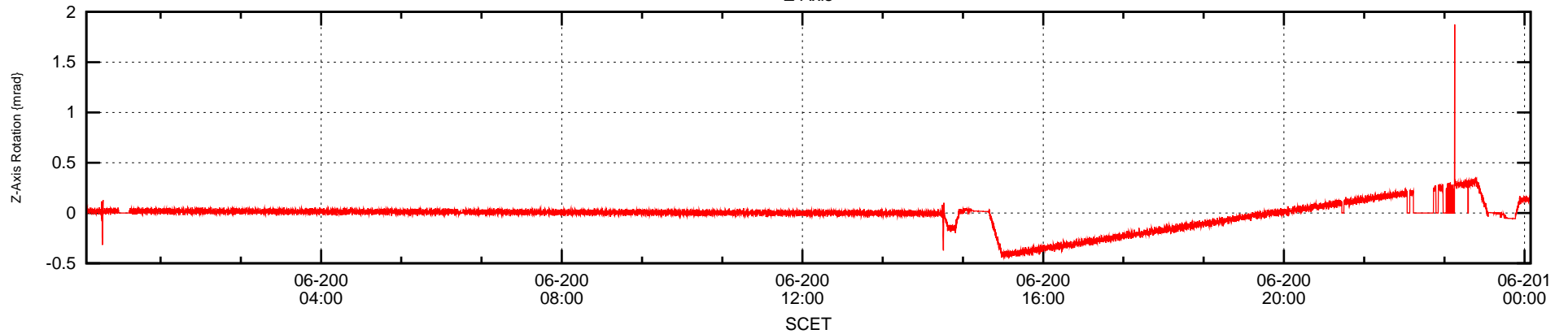
X-Axis (CK #1 = 06197_06202ra.bc; CK #2 = 06198_06231py_as_flowm.bc)



Y-Axis

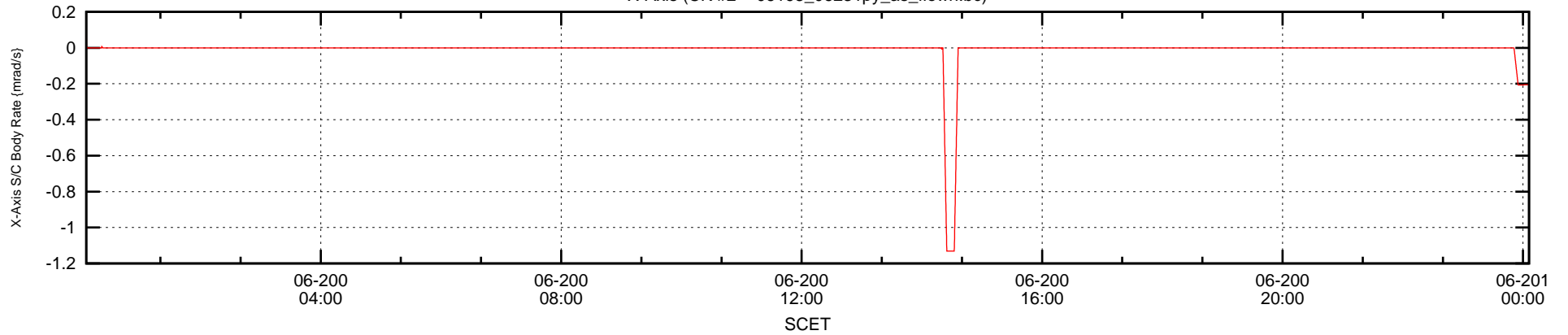


Z-Axis

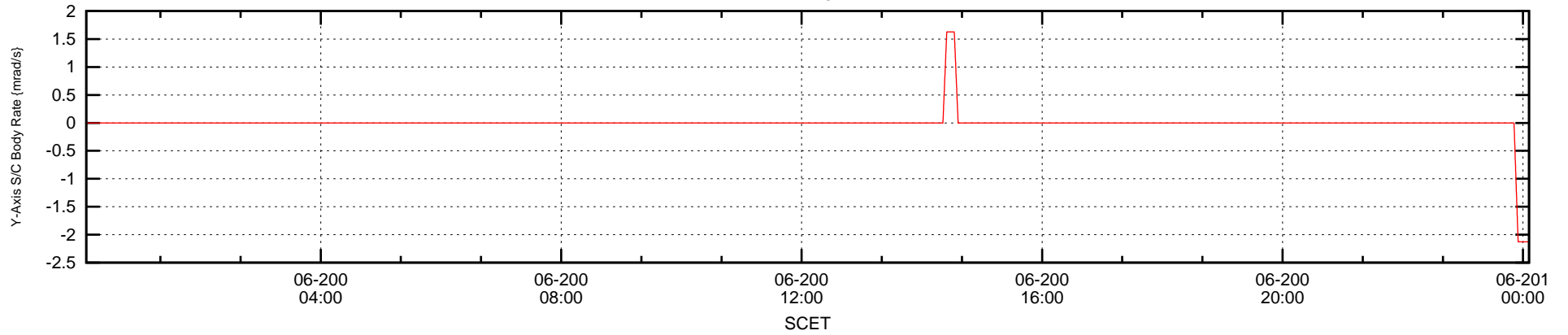


CK #2 S/C Body Rates (DOY 200-201)

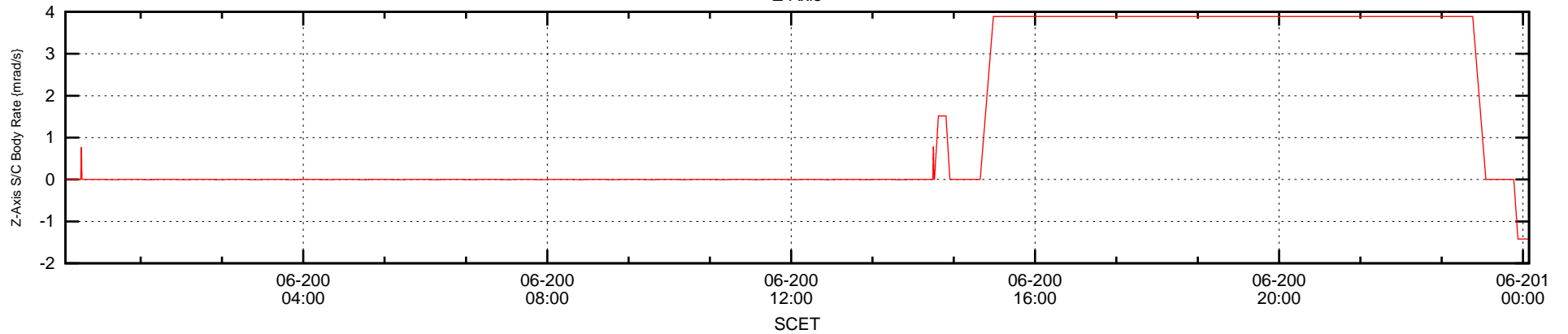
X-Axis (CK #2 = 06198_06231py_as_flown.bc)



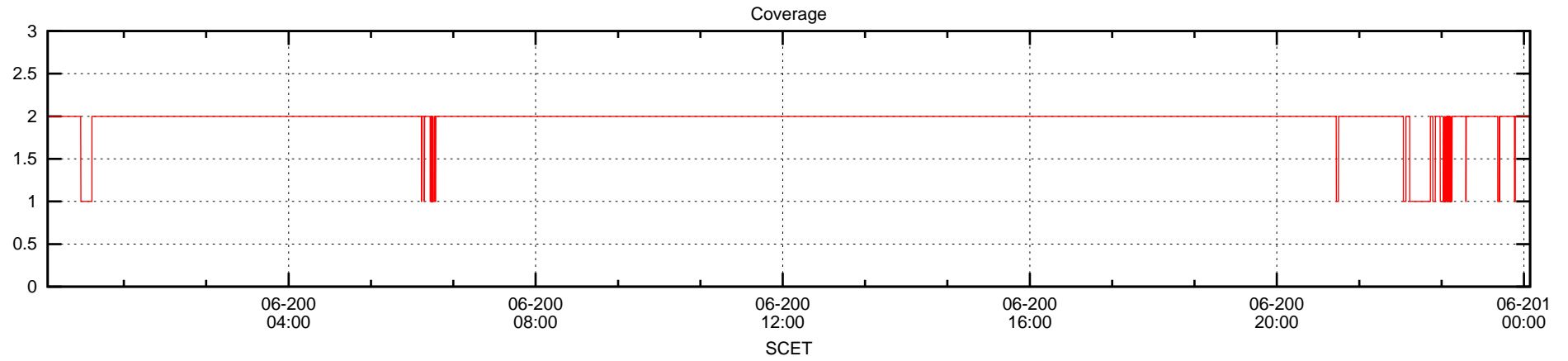
Y-Axis



Z-Axis

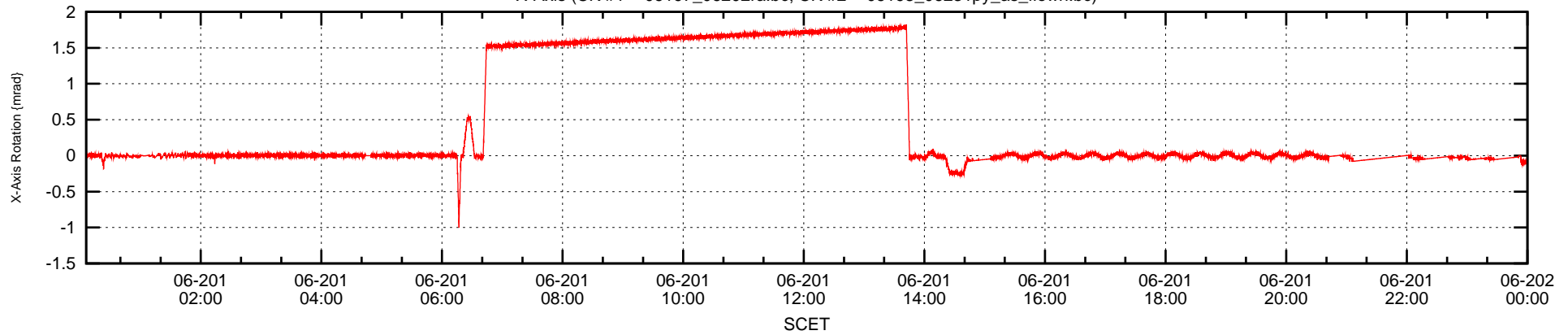


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 200-201)

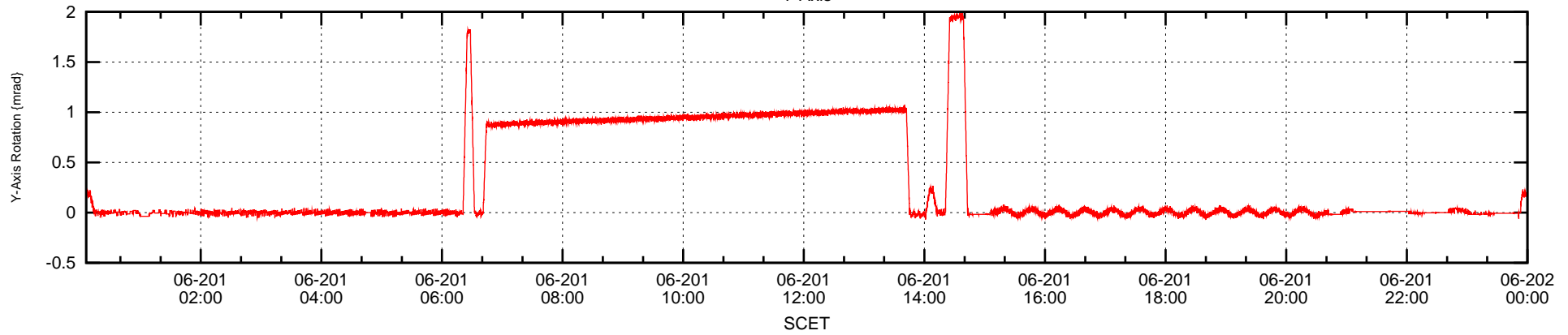


Rotation From CK #2 to CK #1 (DOY 201-201)

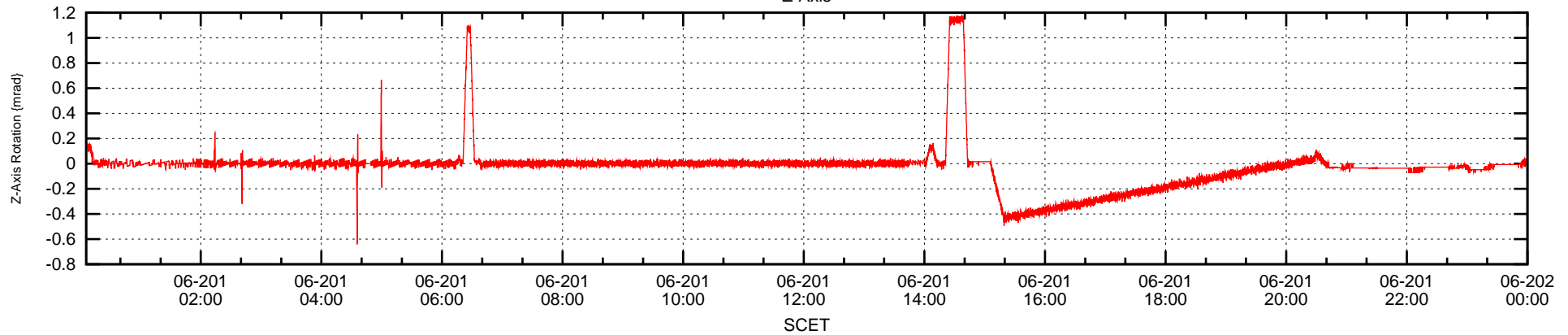
X-Axis (CK #1 = 06197_06202ra.bc; CK #2 = 06198_06231py_as_flowm.bc)



Y-Axis

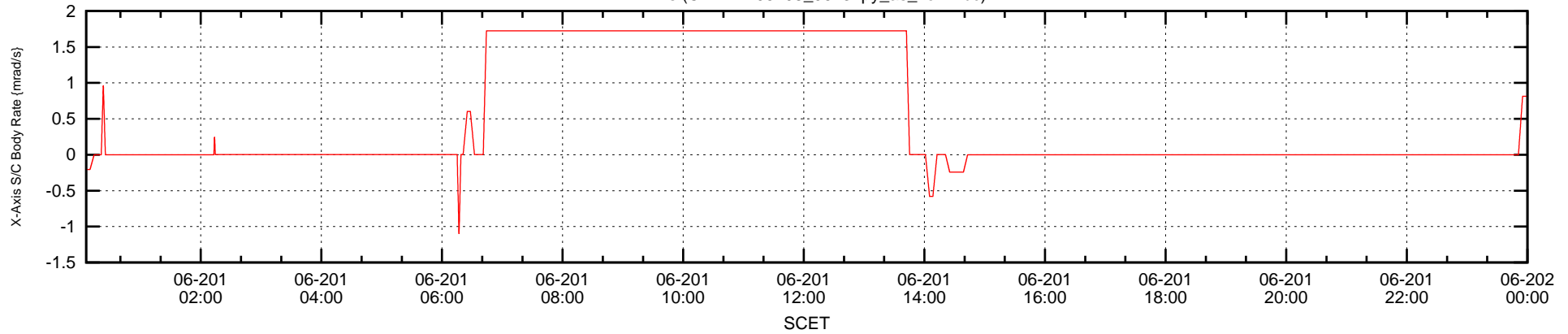


Z-Axis

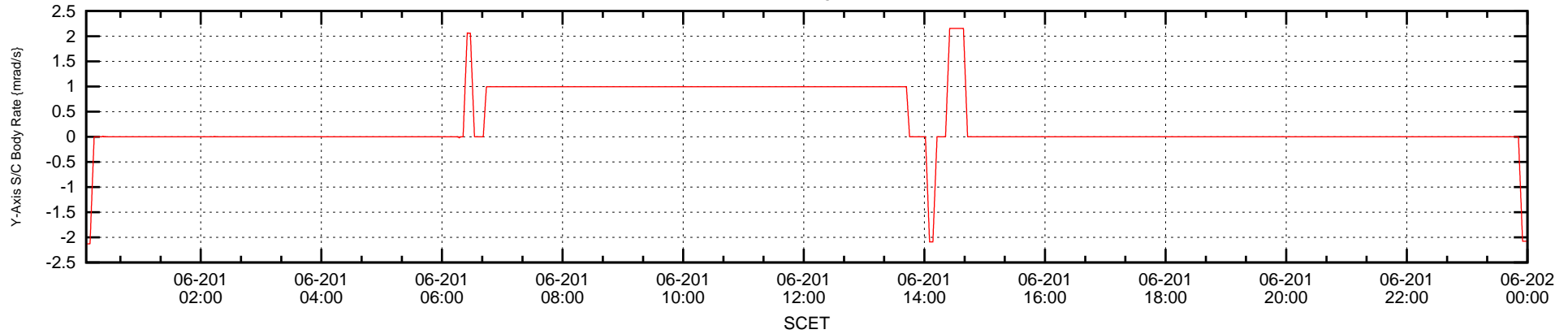


CK #2 S/C Body Rates (DOY 201-201)

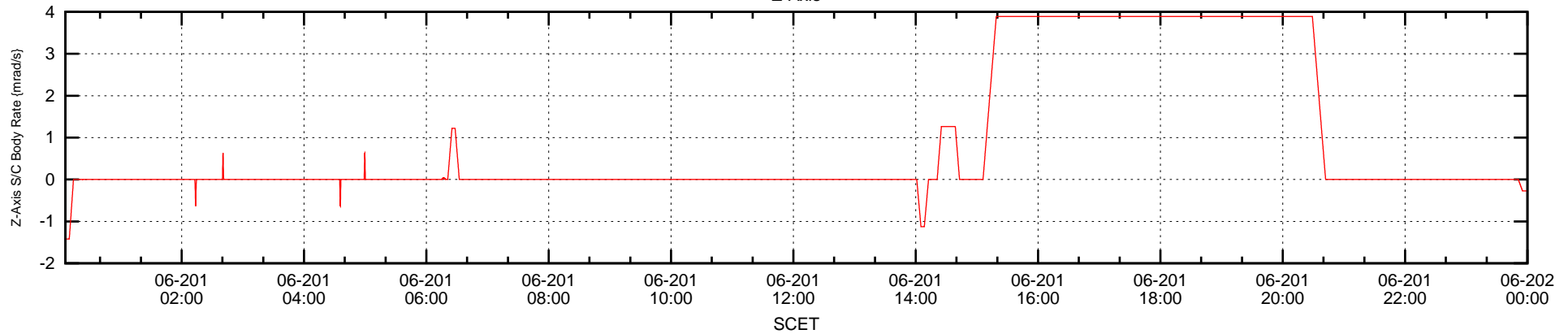
X-Axis (CK #2 = 06198_06231py_as_flowm.bc)



Y-Axis



Z-Axis



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 201-201)

