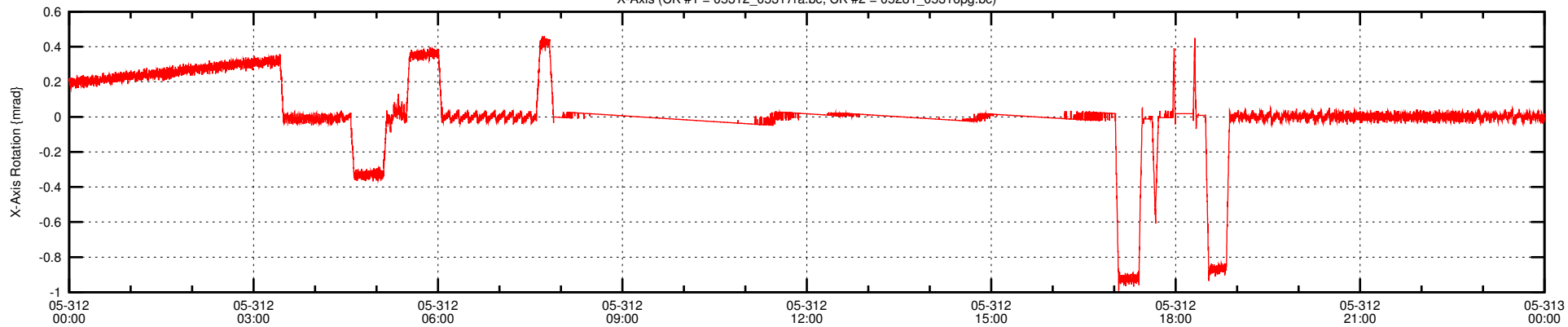
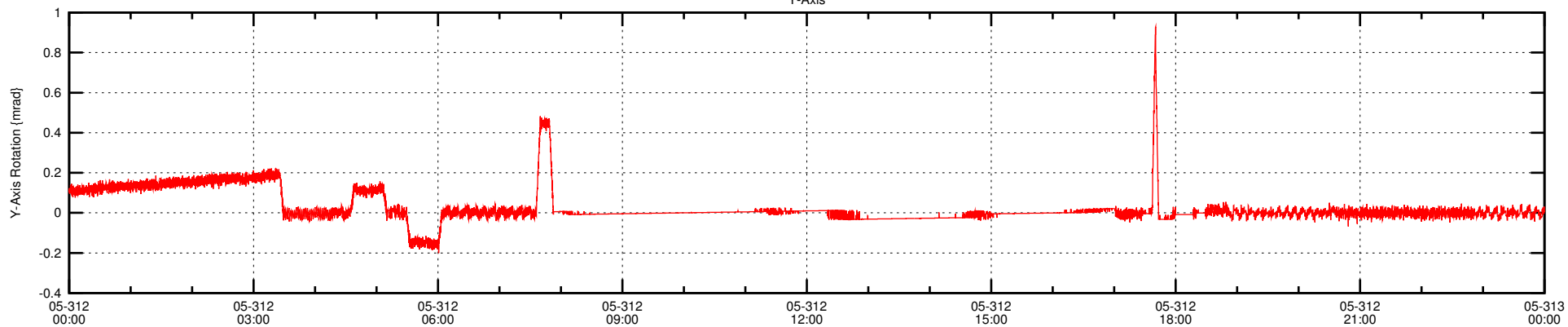


# Rotation From CK #2 to CK #1 (DOY 312-313)

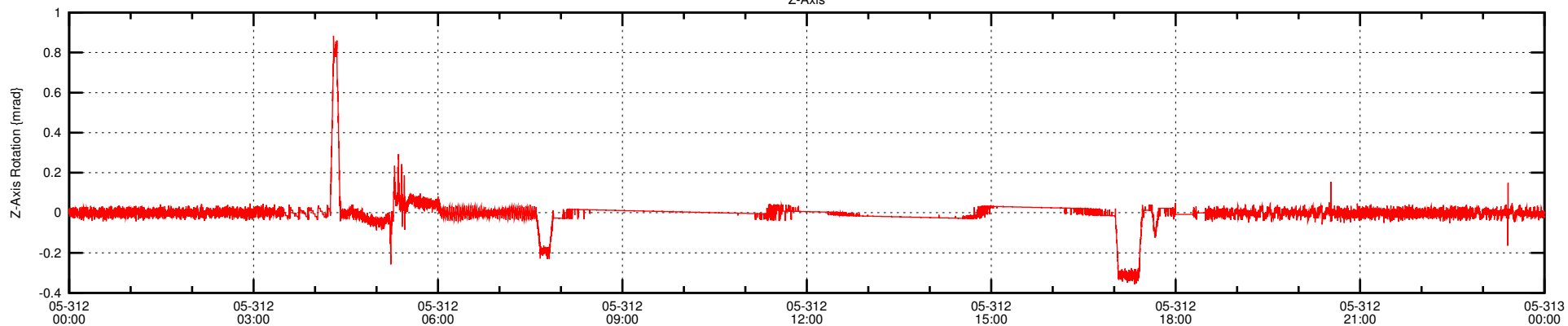
X-Axis (CK #1 = 05312\_05317ra.bc; CK #2 = 05281\_05316pg.bc)



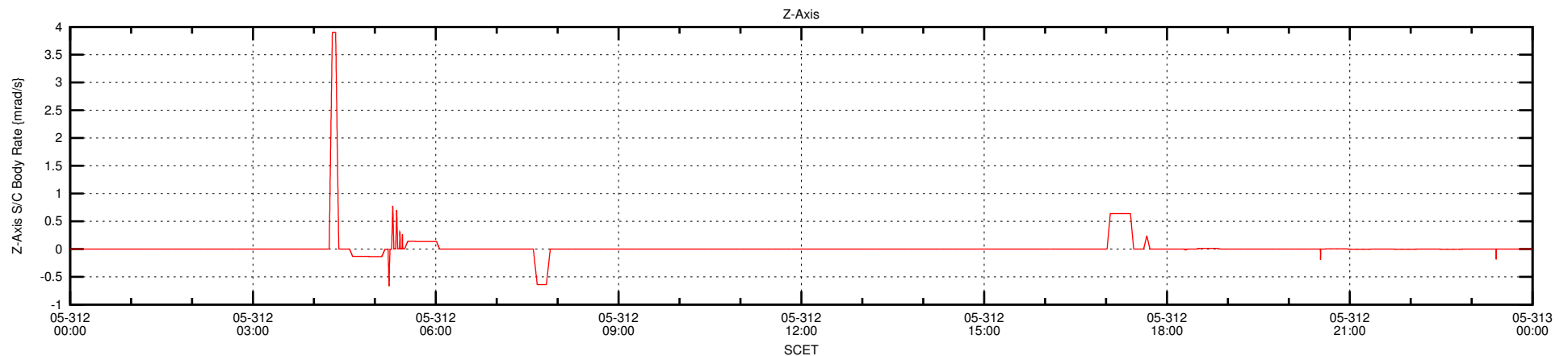
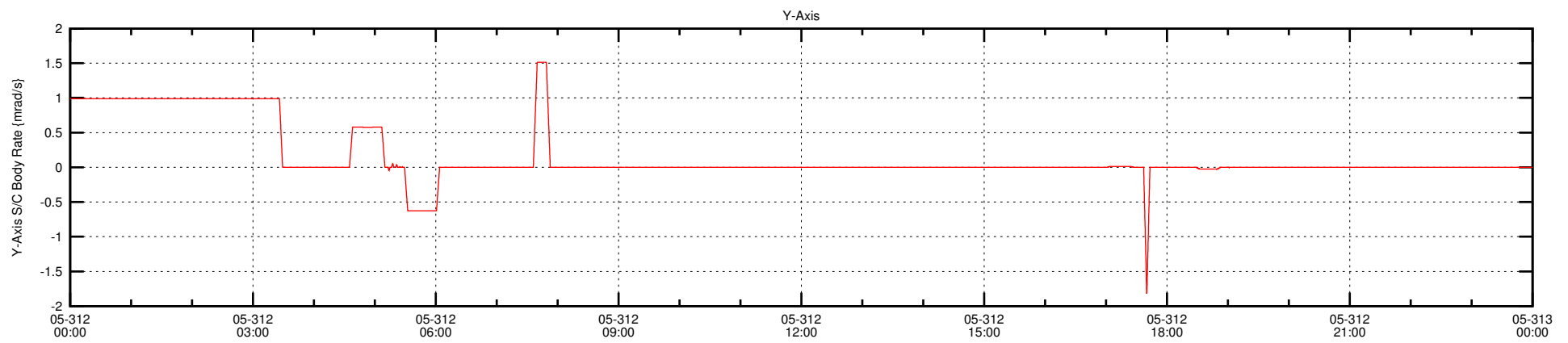
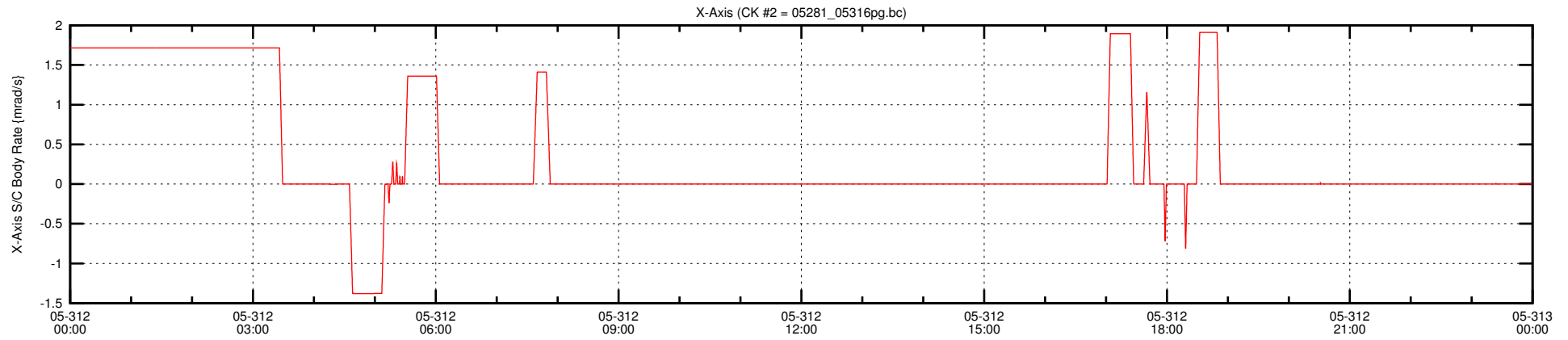
Y-Axis



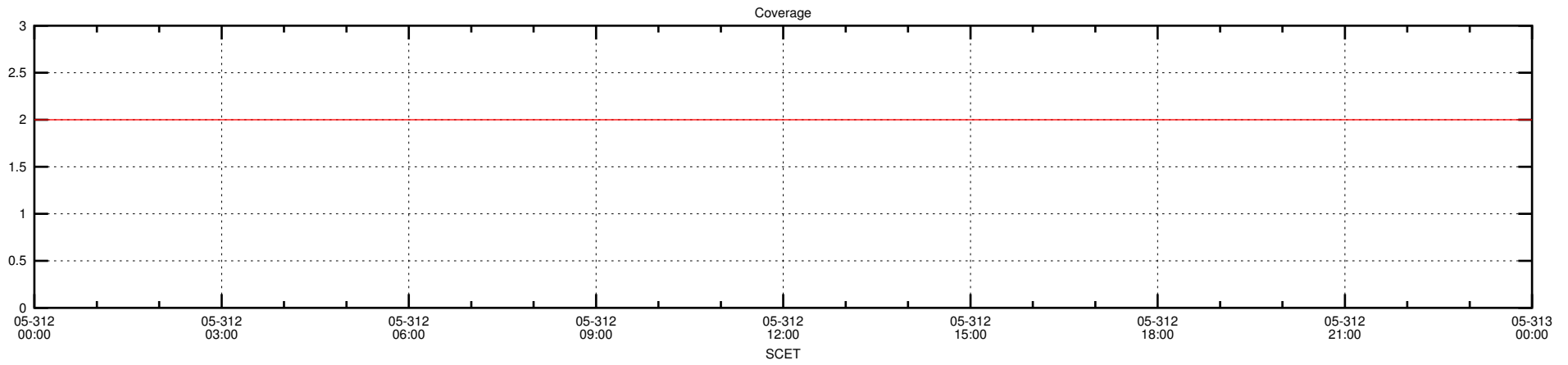
Z-Axis



# CK #2 S/C Body Rates (DOY 312-313)

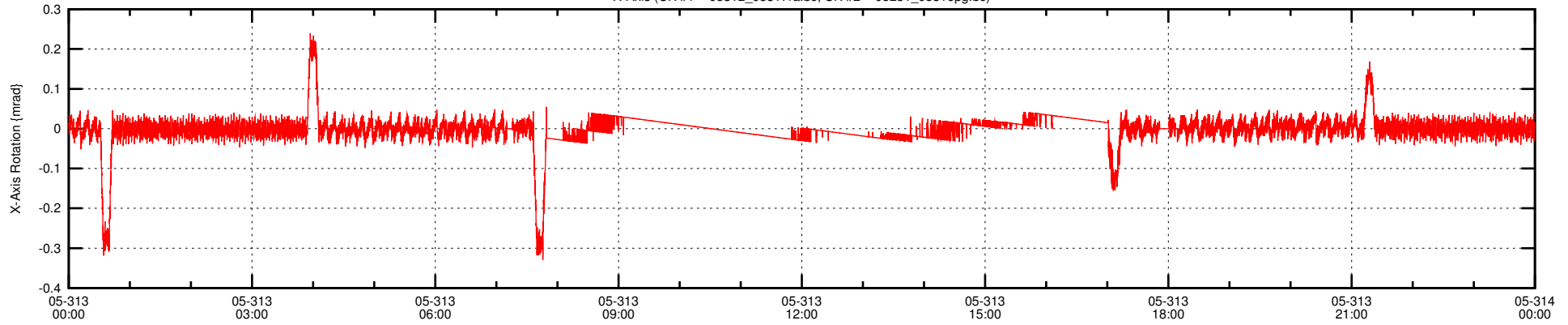


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 312-313)

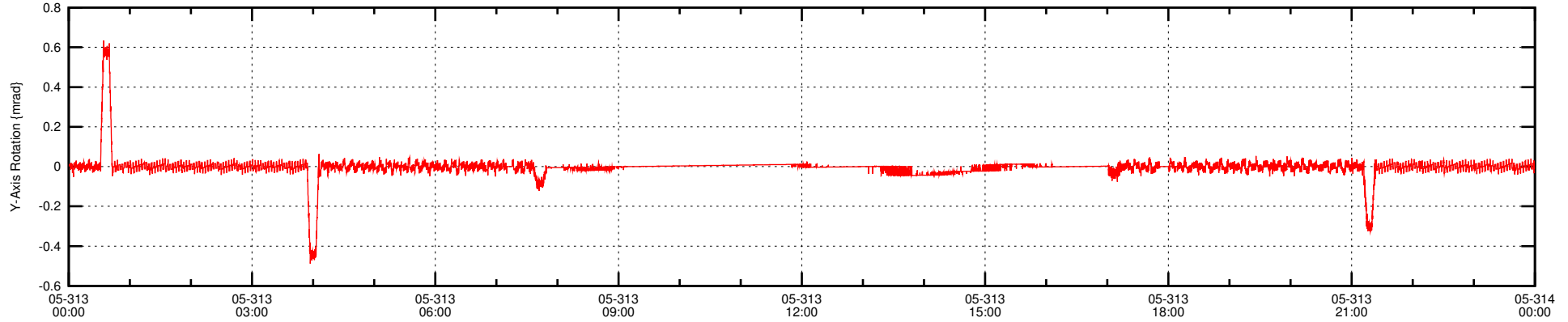


# Rotation From CK #2 to CK #1 (DOY 313-314)

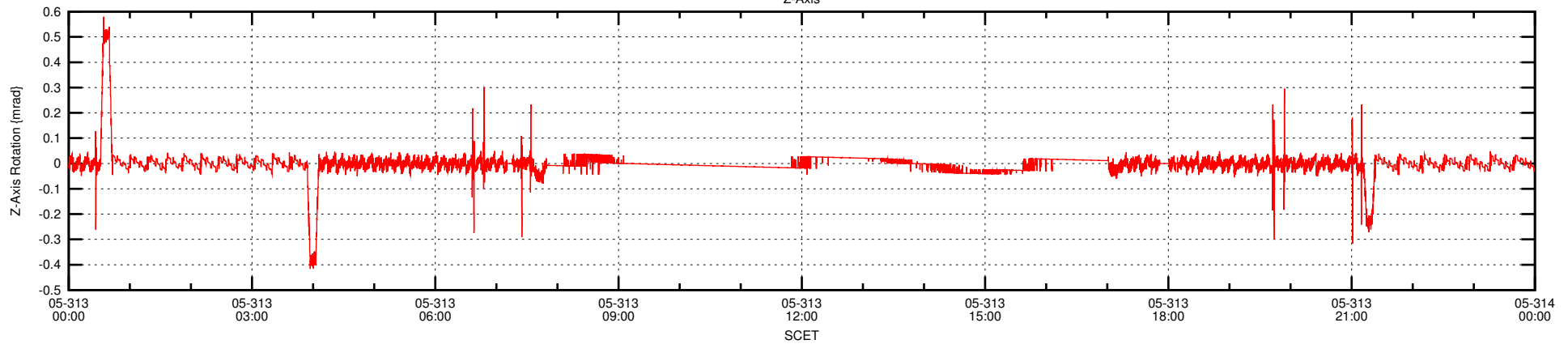
X-Axis (CK #1 = 05312\_05317ra.bc; CK #2 = 05281\_05316pg.bc)



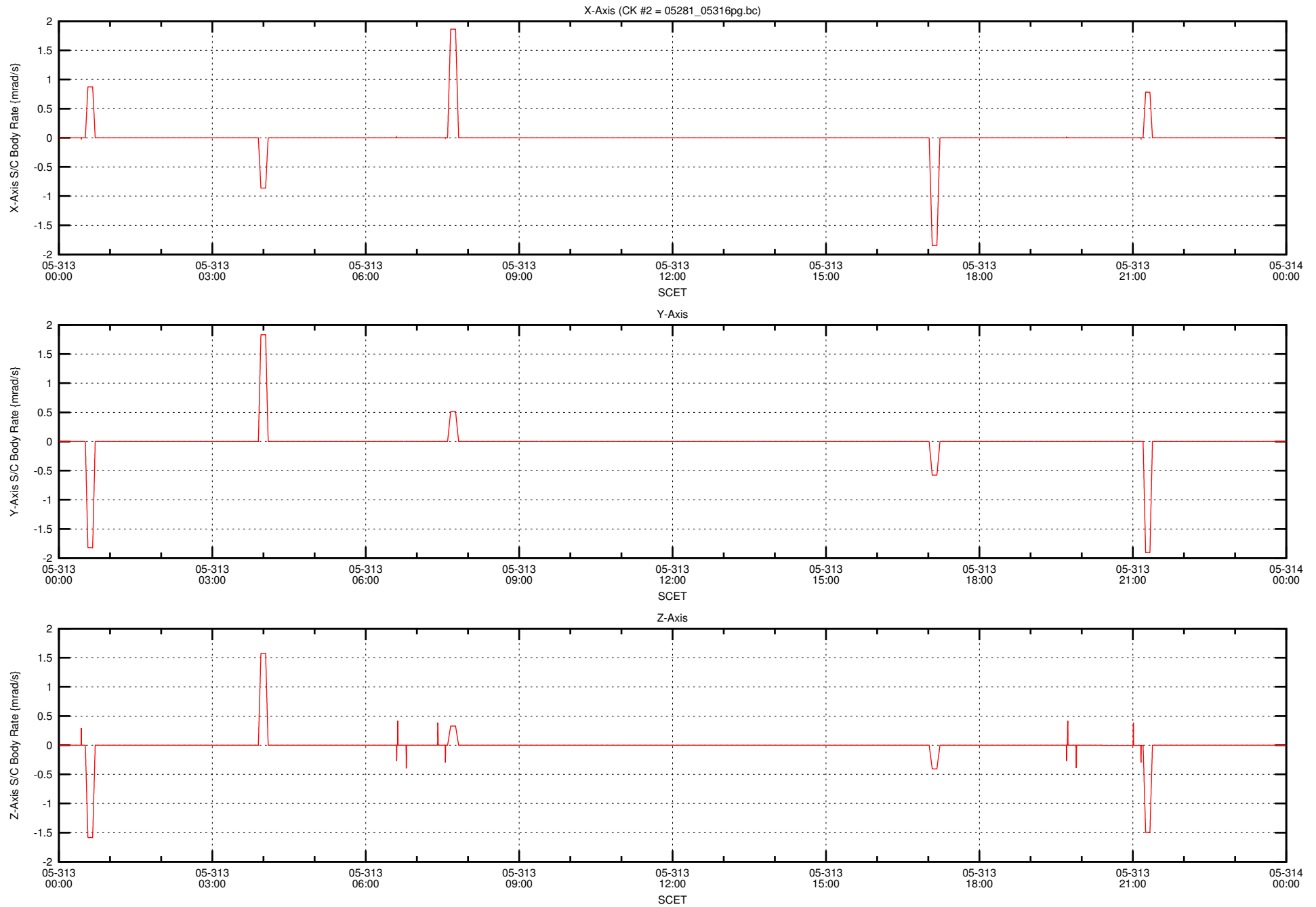
Y-Axis



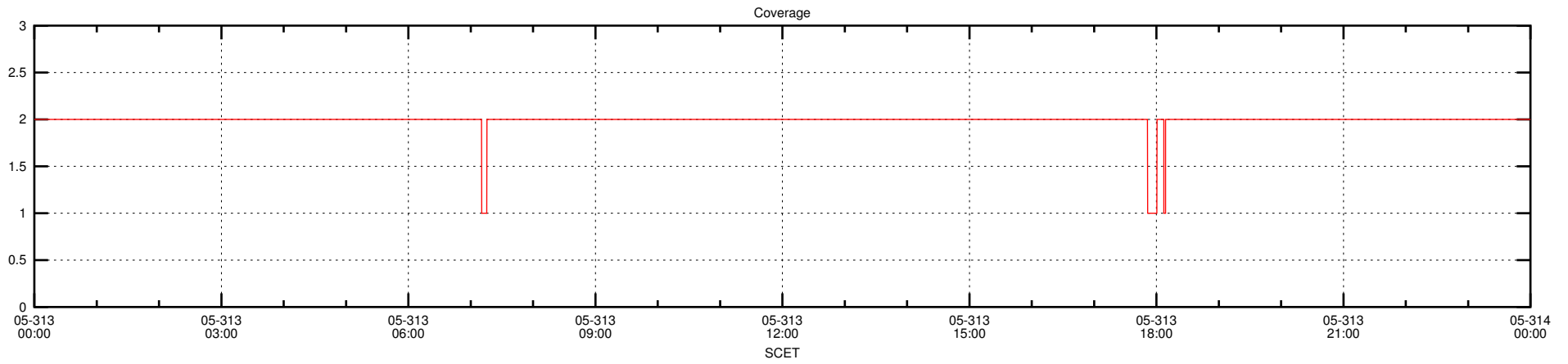
Z-Axis



# CK #2 S/C Body Rates (DOY 313-314)

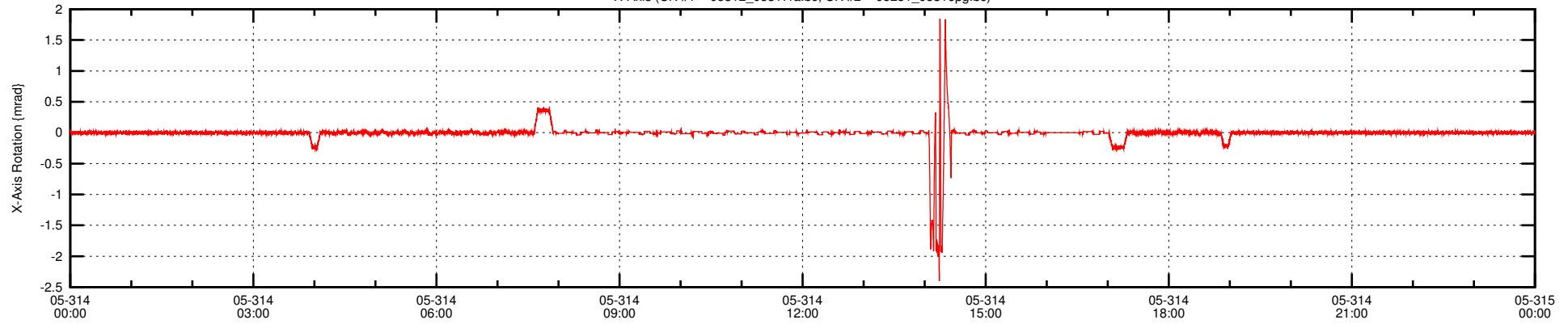


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 313-314)

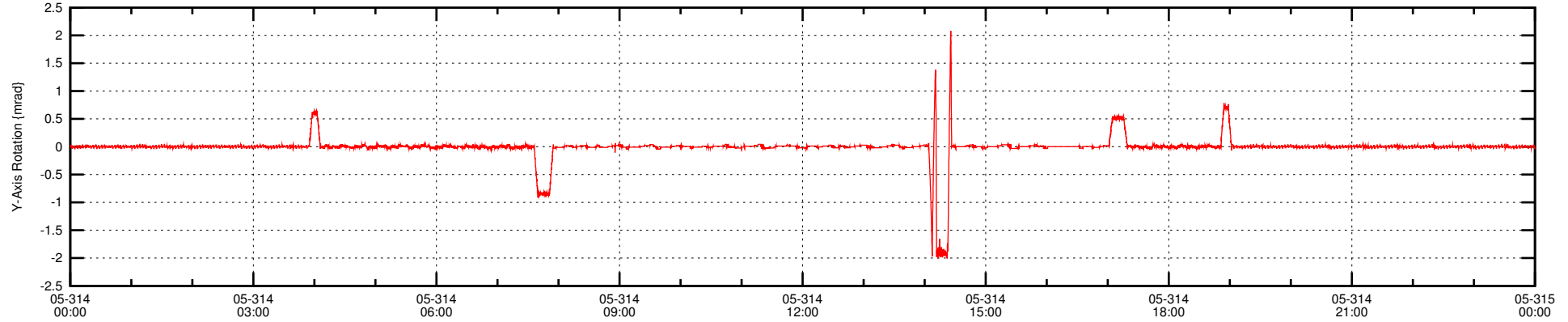


# Rotation From CK #2 to CK #1 (DOY 314-315)

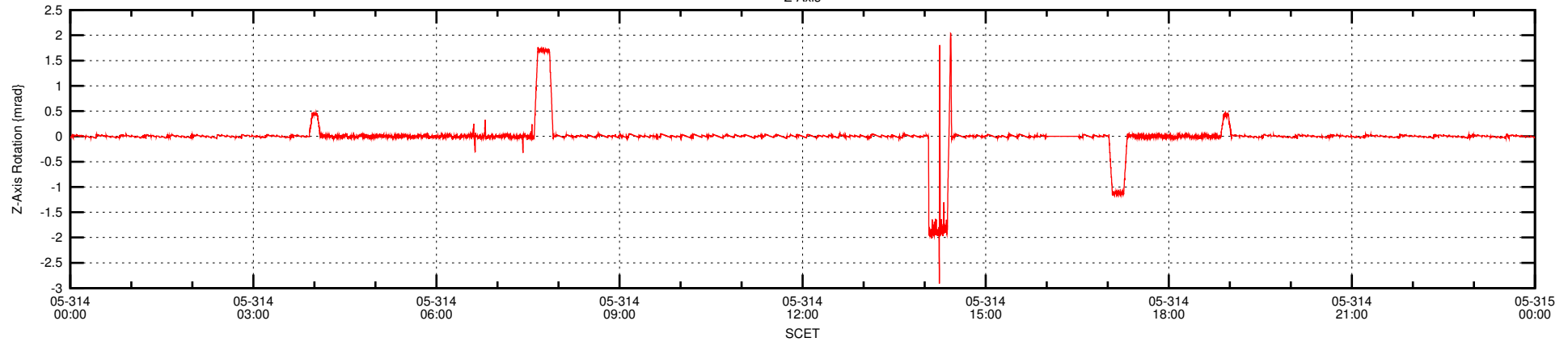
X-Axis (CK #1 = 05312\_05317ra.bc; CK #2 = 05281\_05316pg.bc)



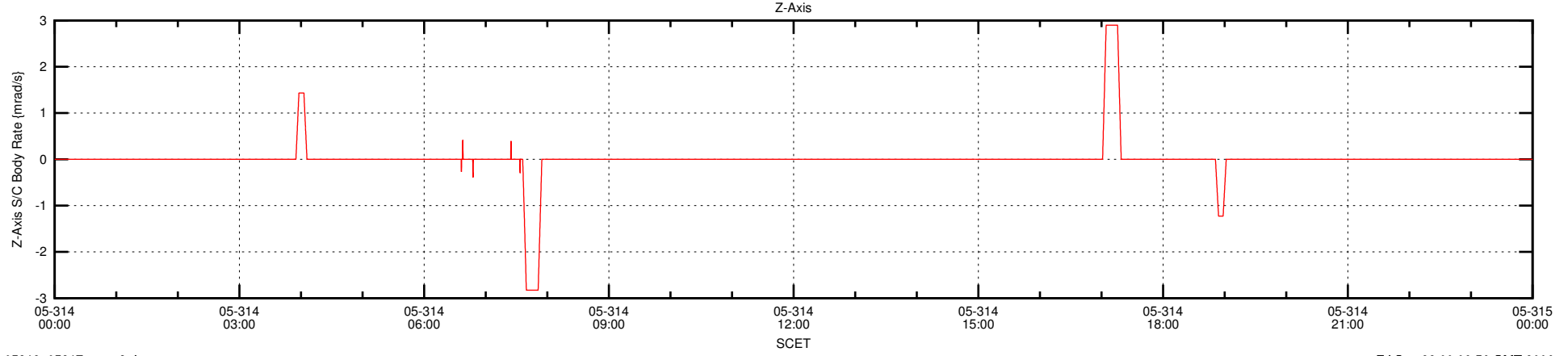
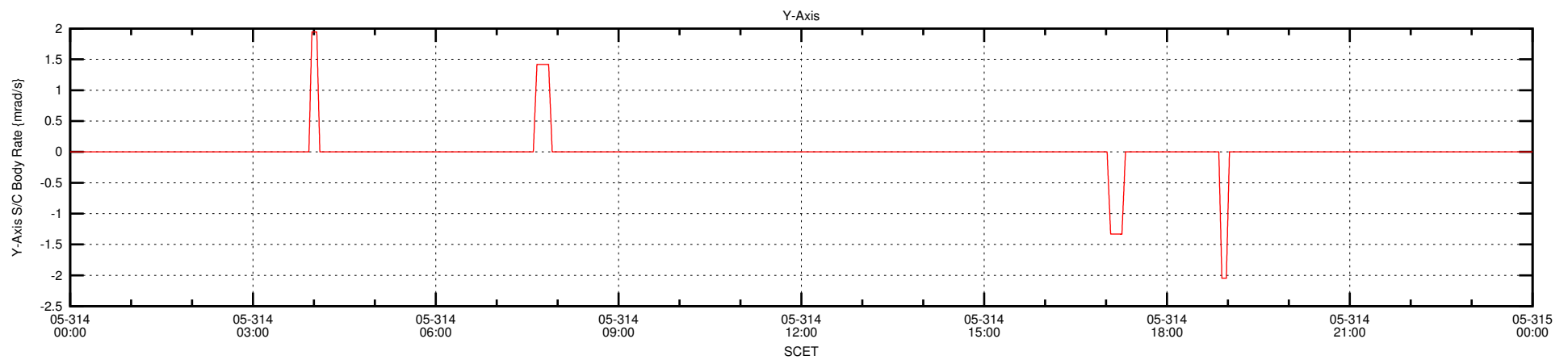
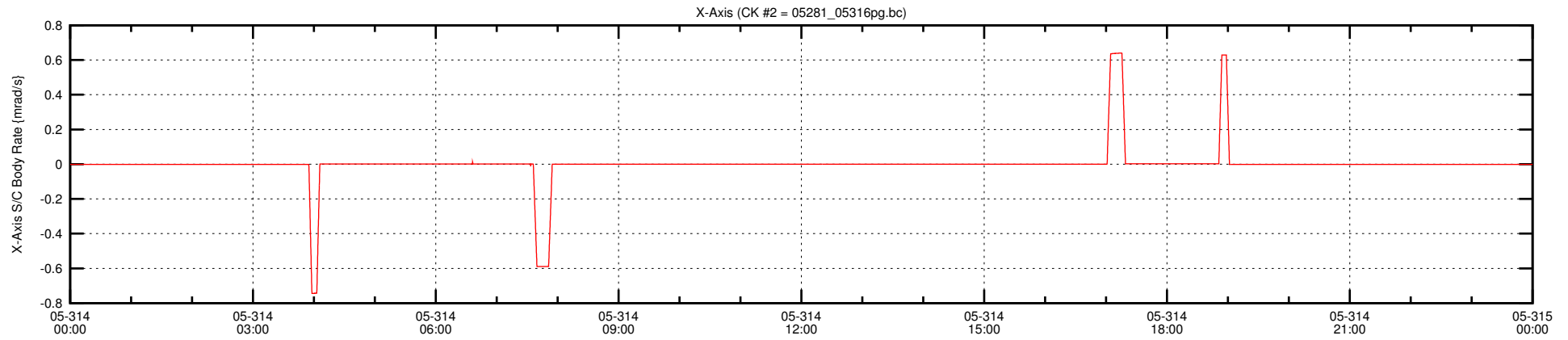
Y-Axis



Z-Axis

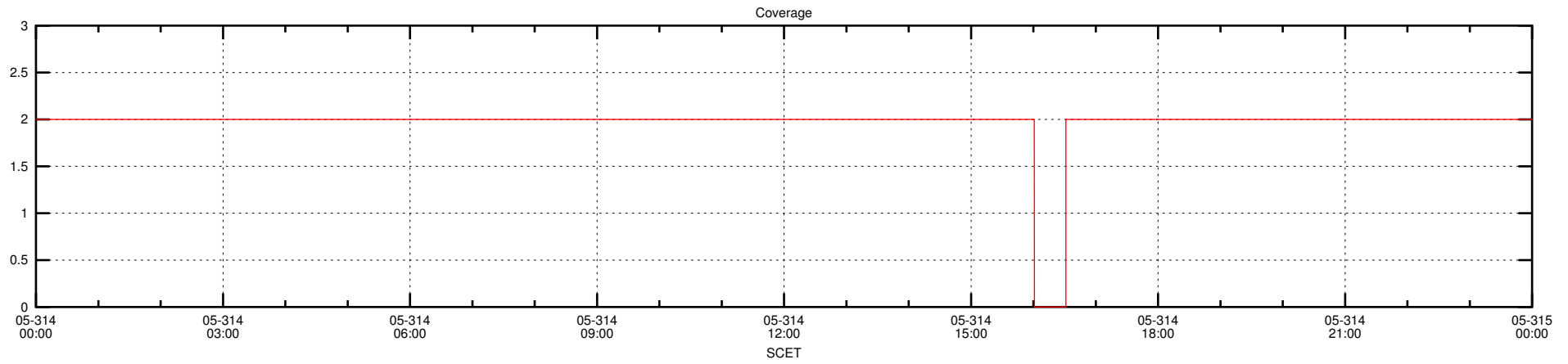


# CK #2 S/C Body Rates (DOY 314-315)



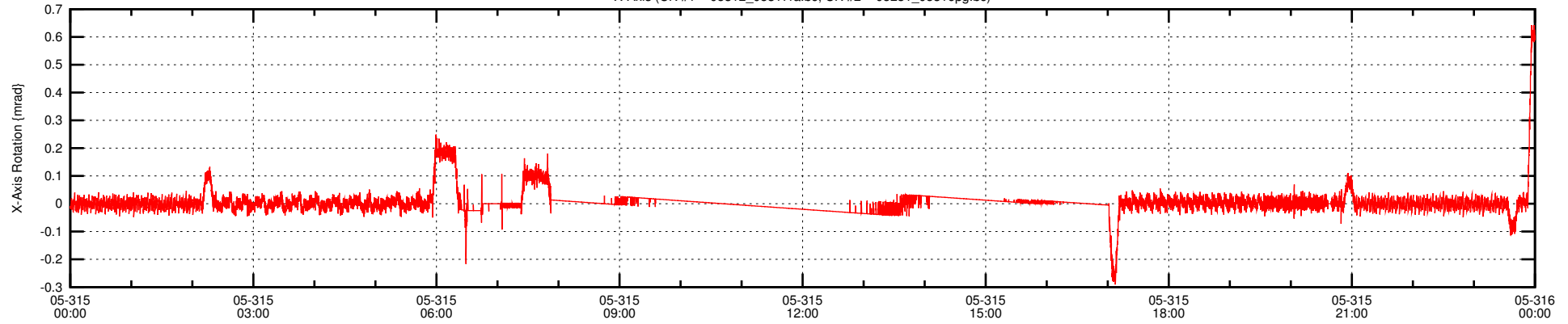


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 314-315)

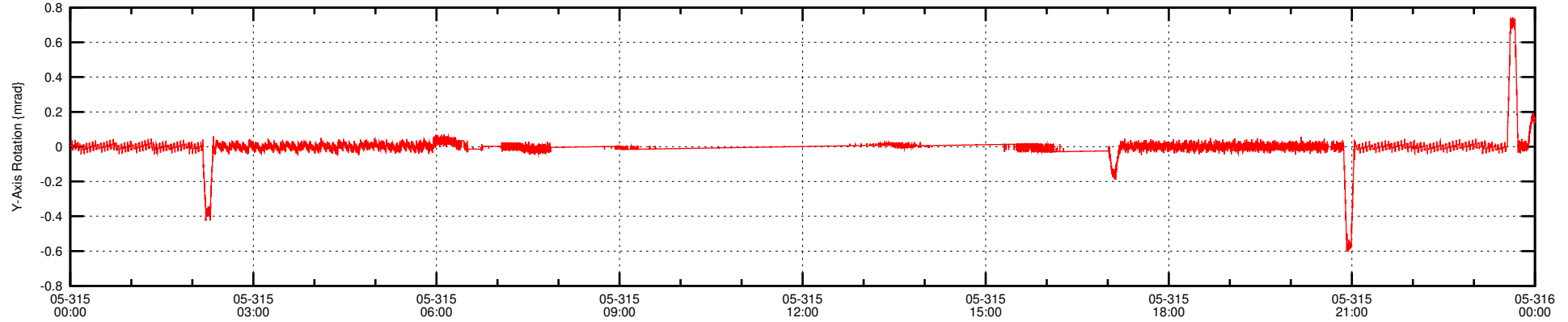


# Rotation From CK #2 to CK #1 (DOY 315-316)

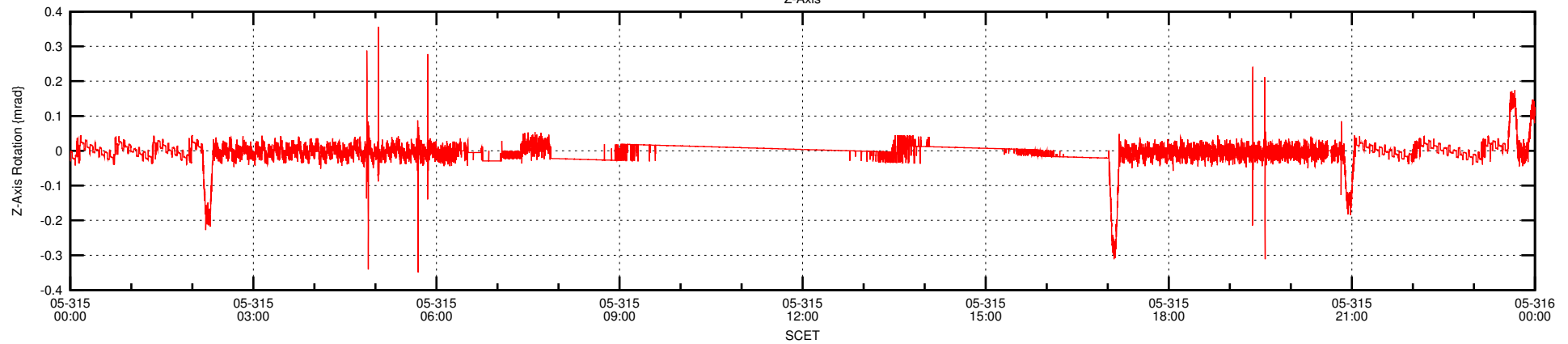
X-Axis (CK #1 = 05312\_05317ra.bc; CK #2 = 05281\_05316pg.bc)



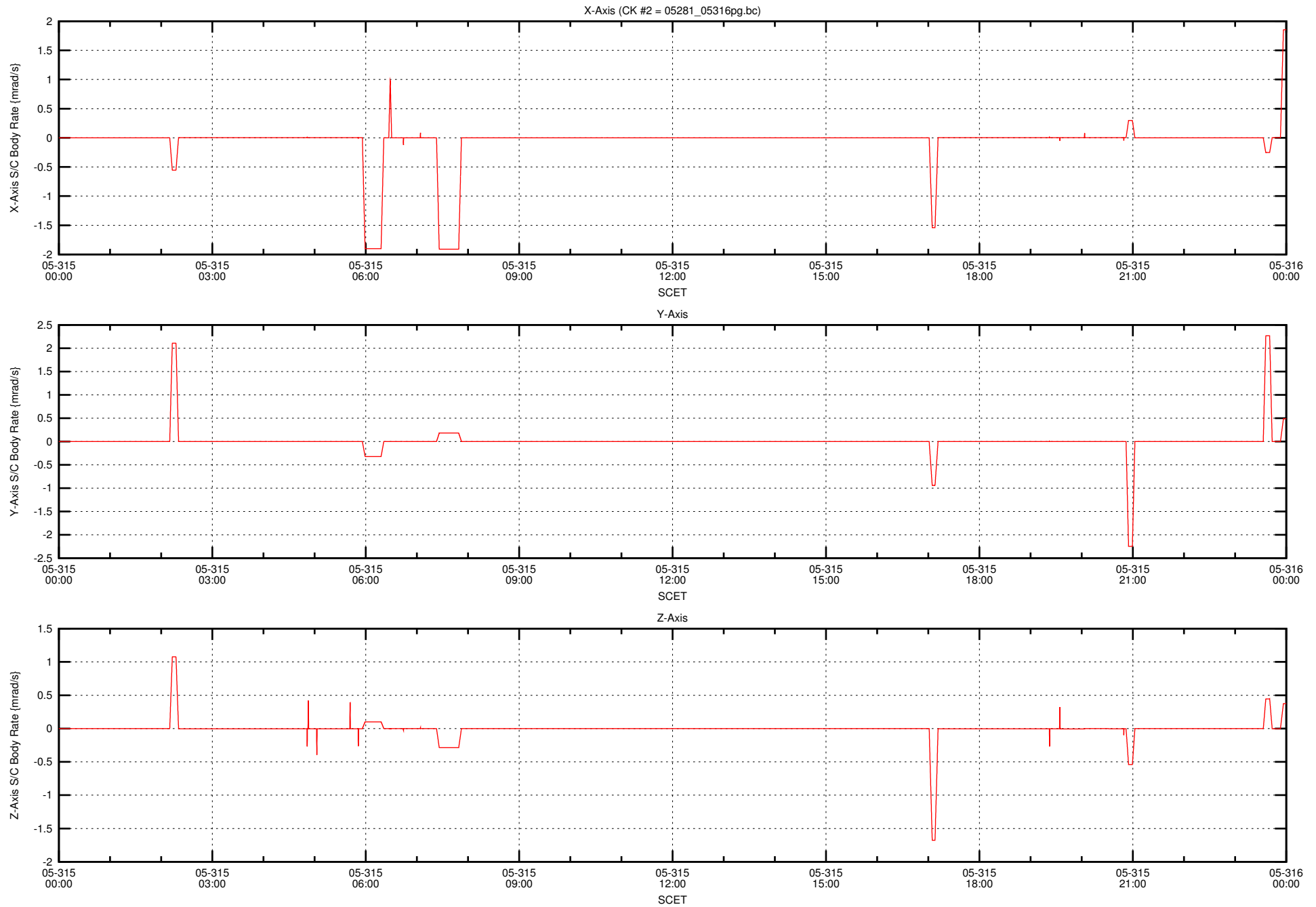
Y-Axis



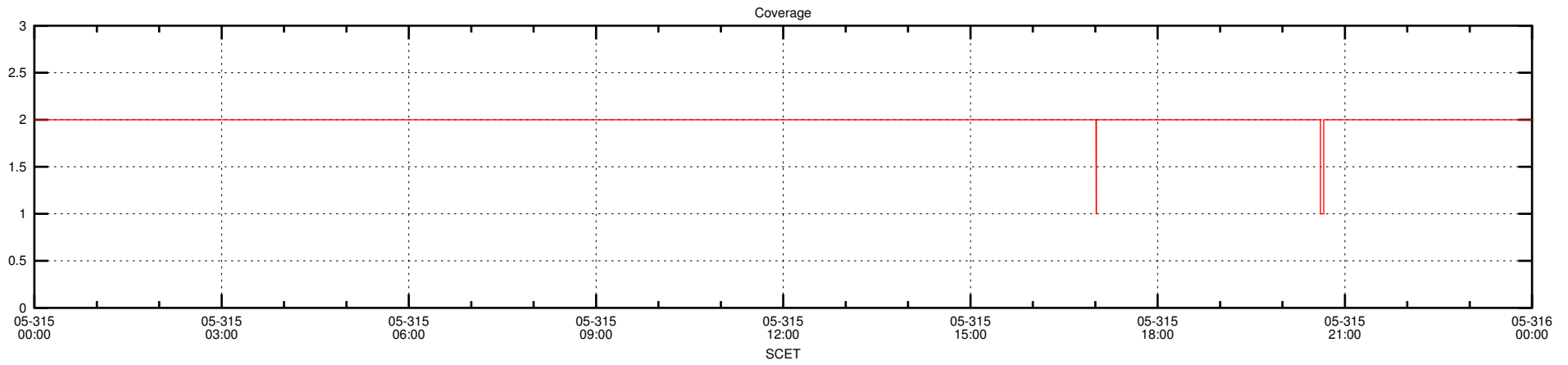
Z-Axis



# CK #2 S/C Body Rates (DOY 315-316)

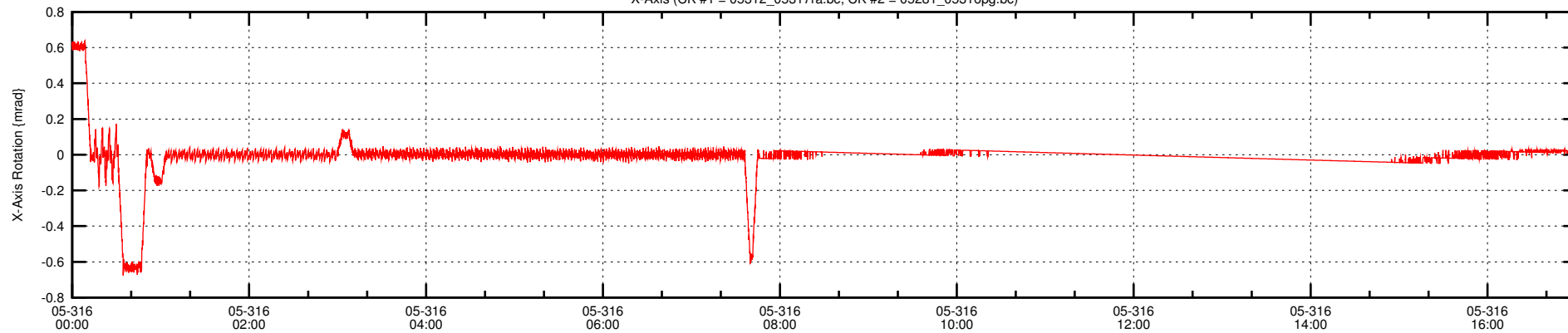


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 315-316)

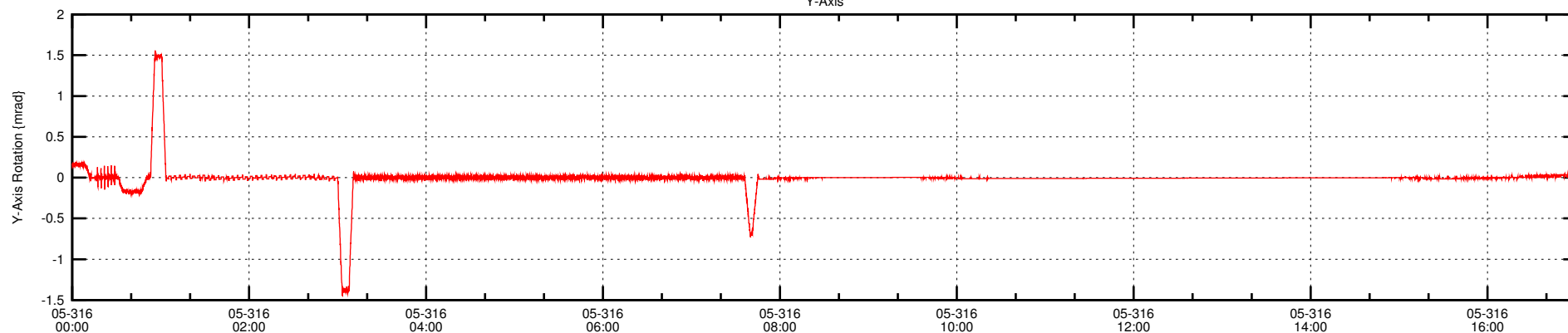


# Rotation From CK #2 to CK #1 (DOY 316-316)

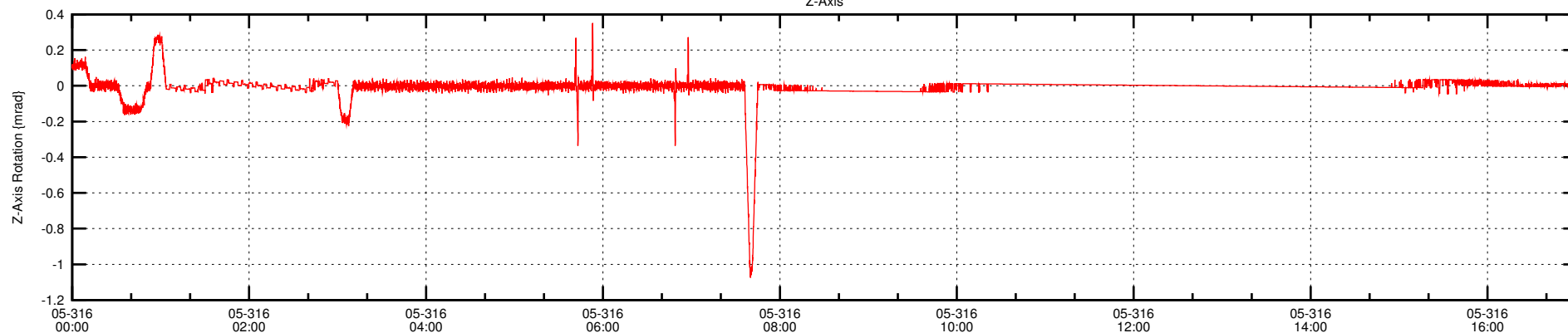
X-Axis (CK #1 = 05312\_05317ra.bc; CK #2 = 05281\_05316pg.bc)



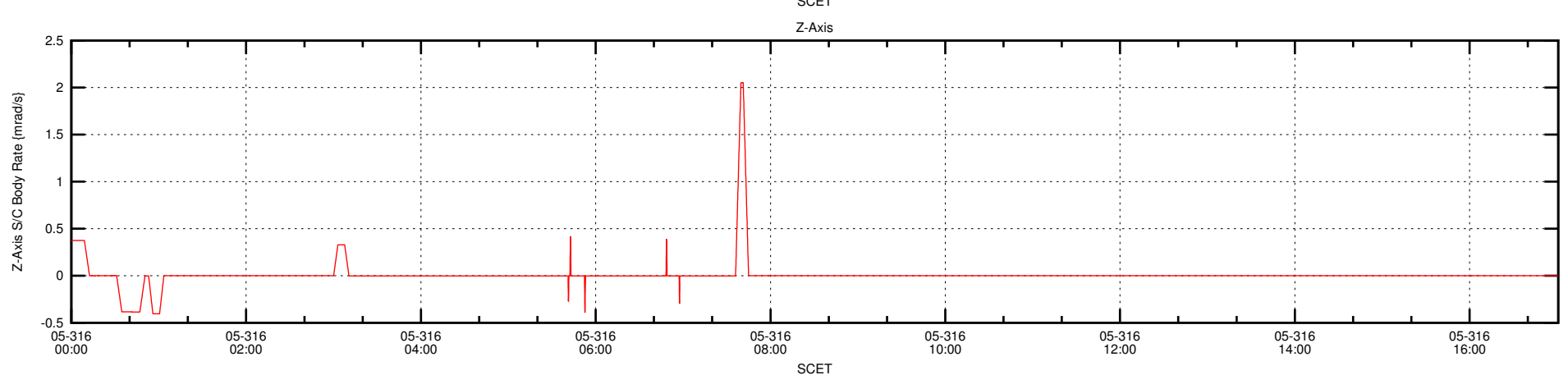
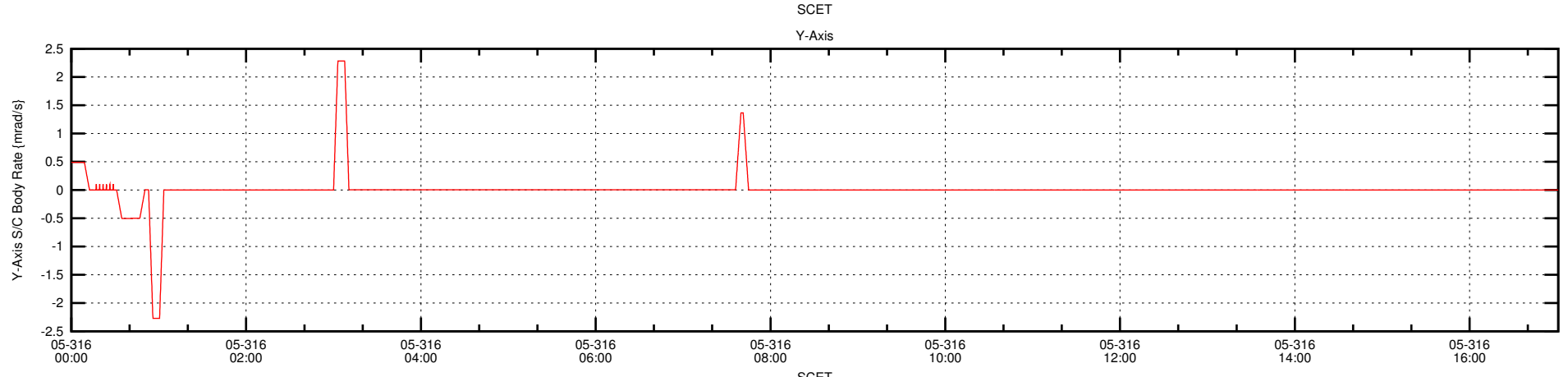
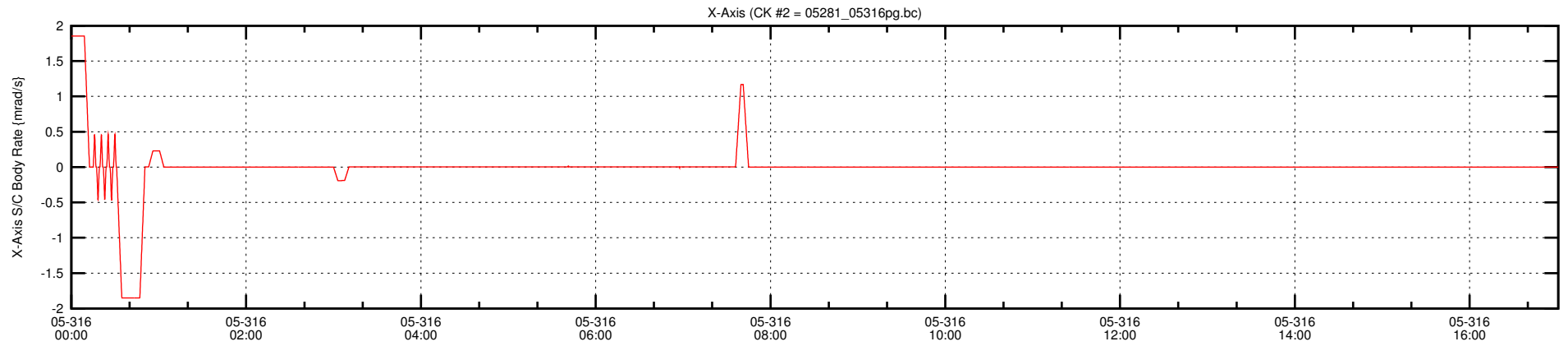
Y-Axis



Z-Axis



# CK #2 S/C Body Rates (DOY 316-316)



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 316-316)

