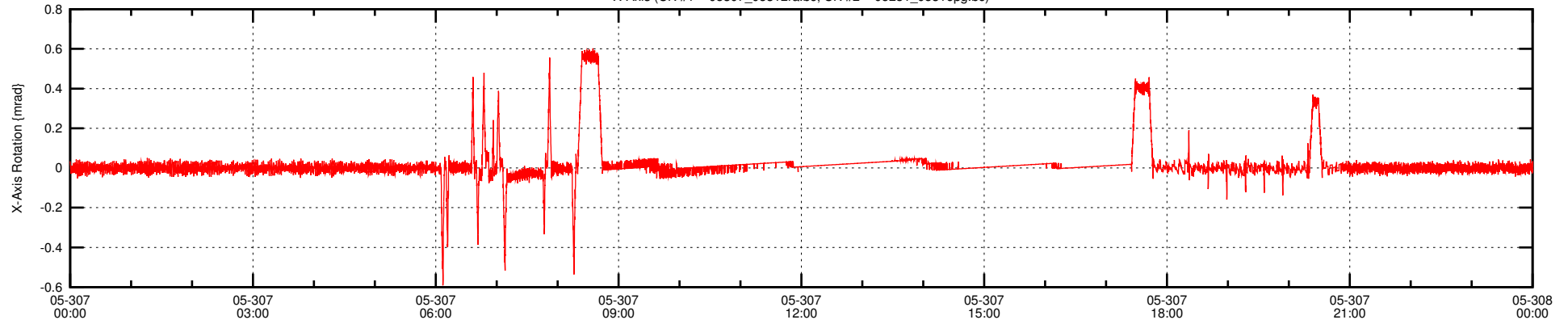
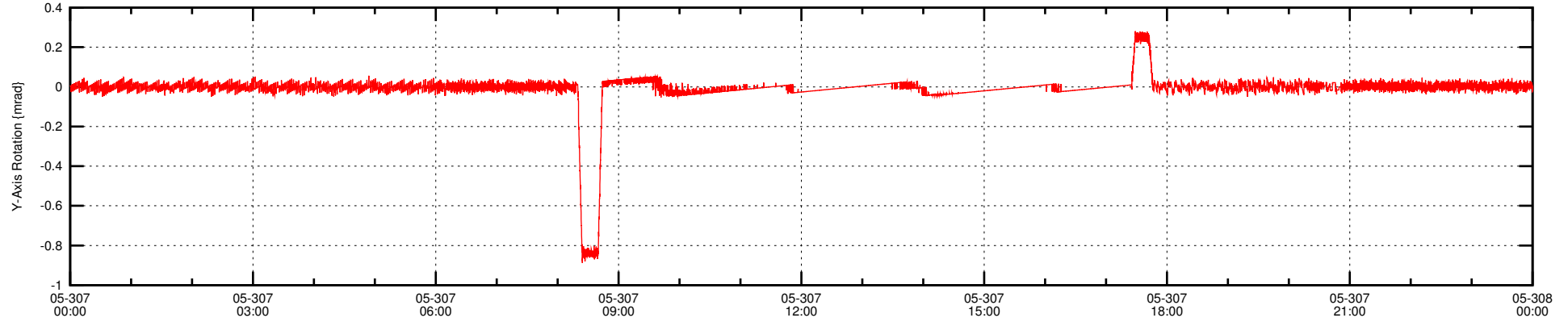


Rotation From CK #2 to CK #1 (DOY 307-308)

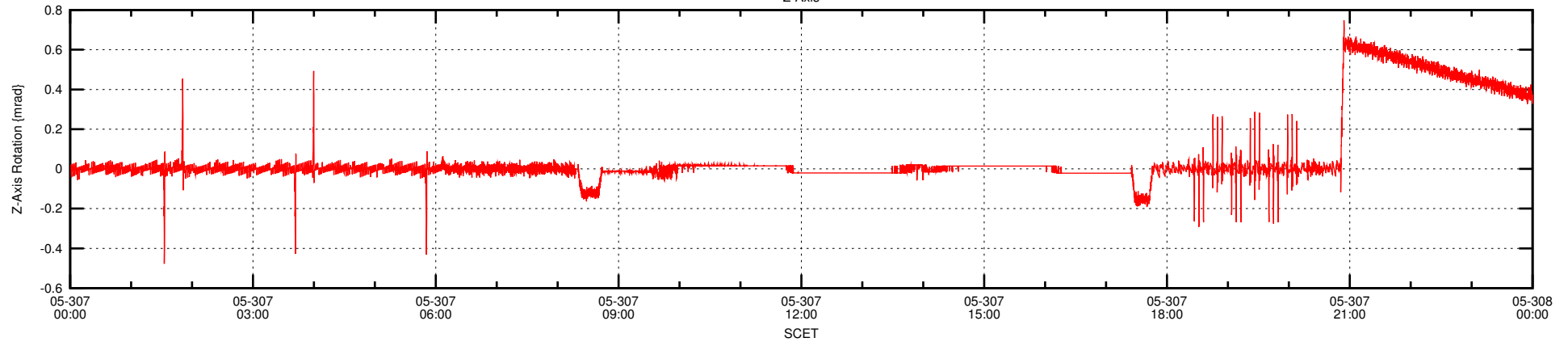
X-Axis (CK #1 = 05307_05312ra.bc; CK #2 = 05281_05316pg.bc)



Y-Axis

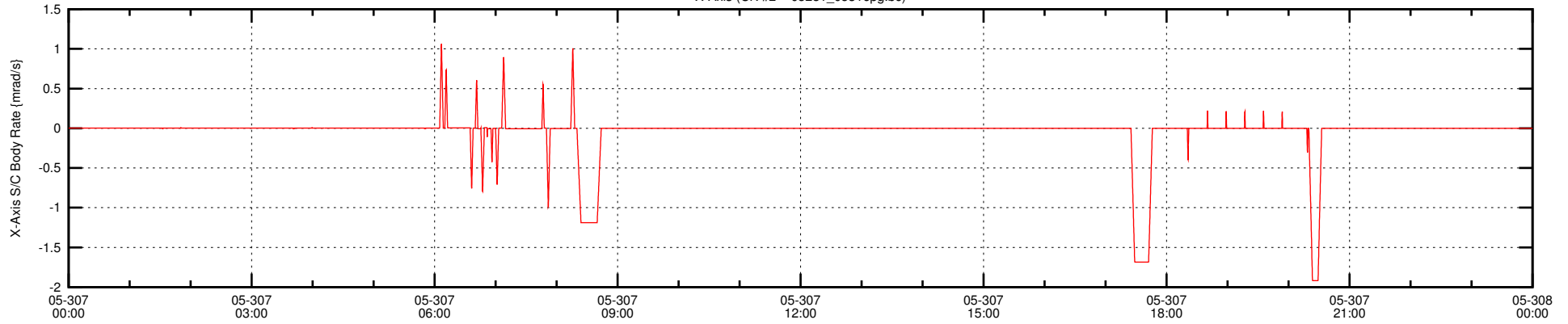


Z-Axis

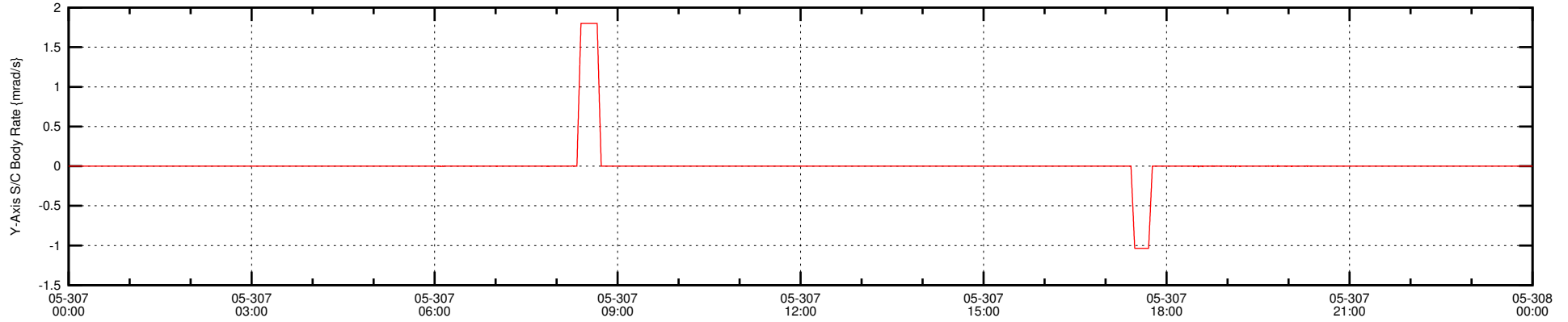


CK #2 S/C Body Rates (DOY 307-308)

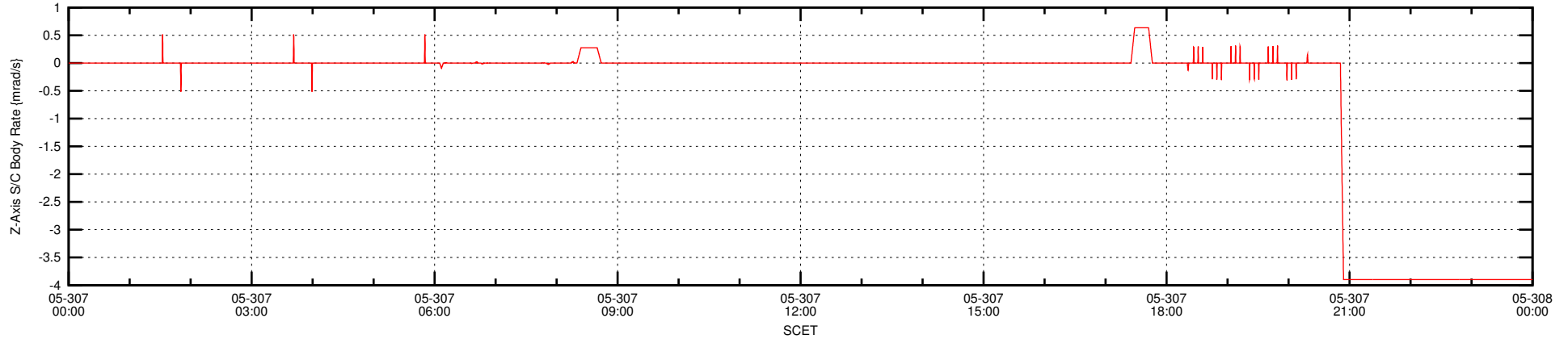
X-Axis (CK #2 = 05281_05316pg.bc)



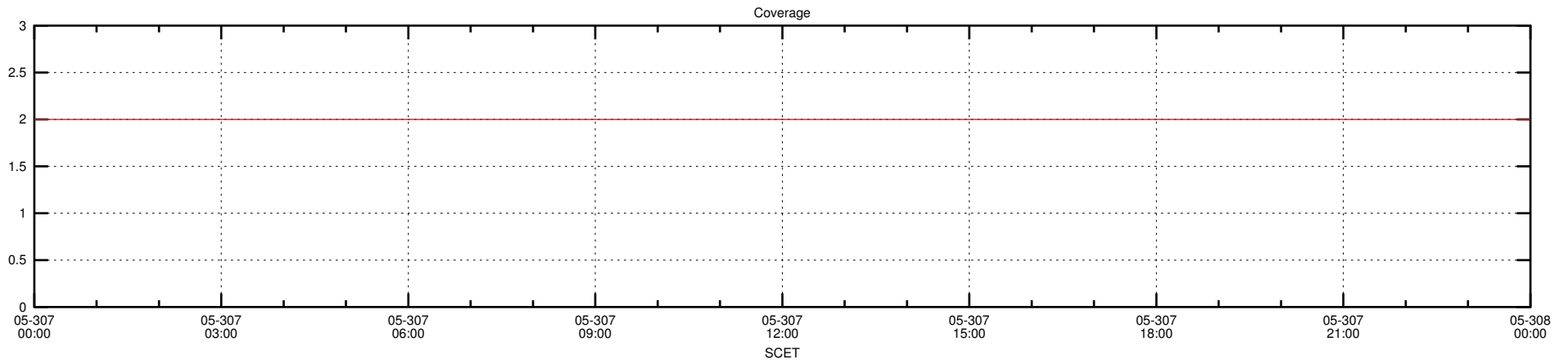
Y-Axis



Z-Axis

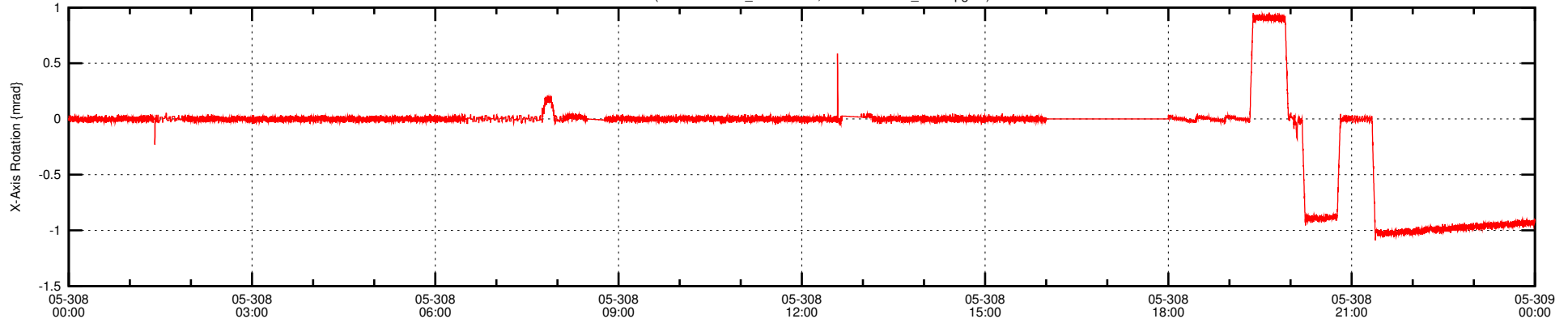


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 307-308)

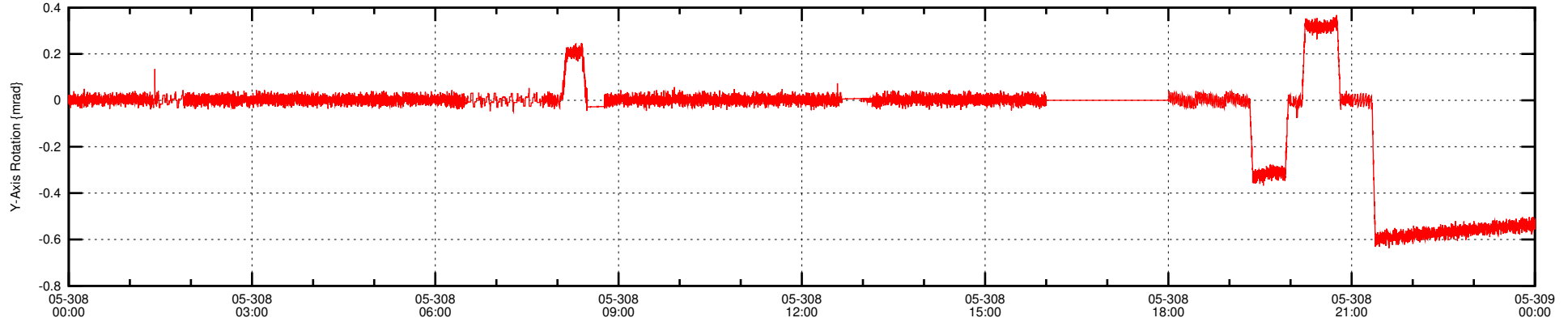


Rotation From CK #2 to CK #1 (DOY 308-309)

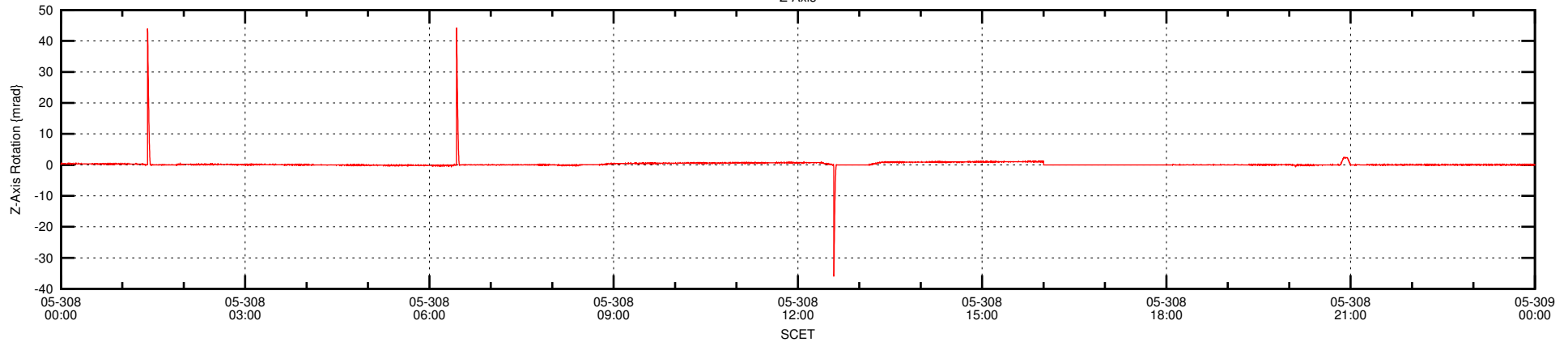
X-Axis (CK #1 = 05307_05312ra.bc; CK #2 = 05281_05316pg.bc)



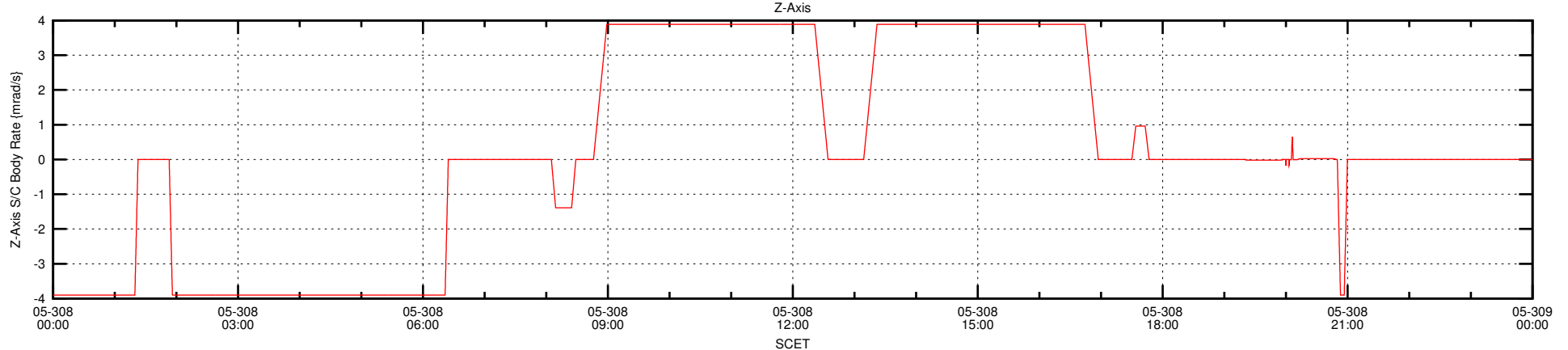
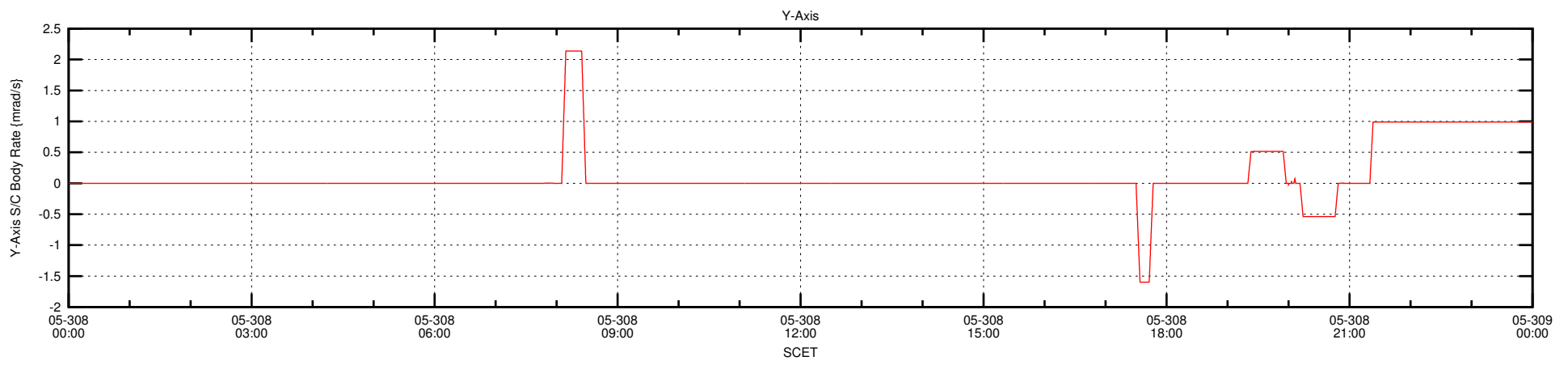
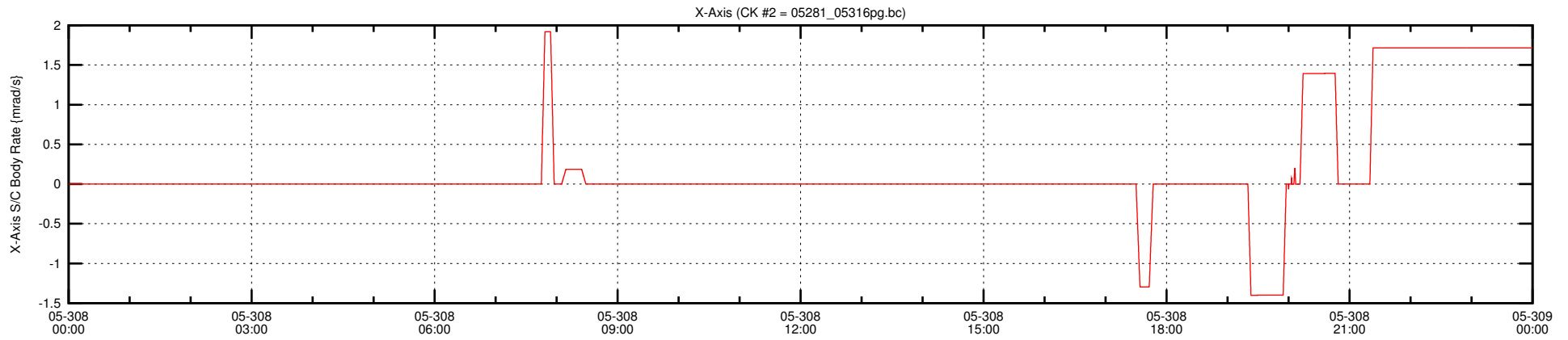
Y-Axis



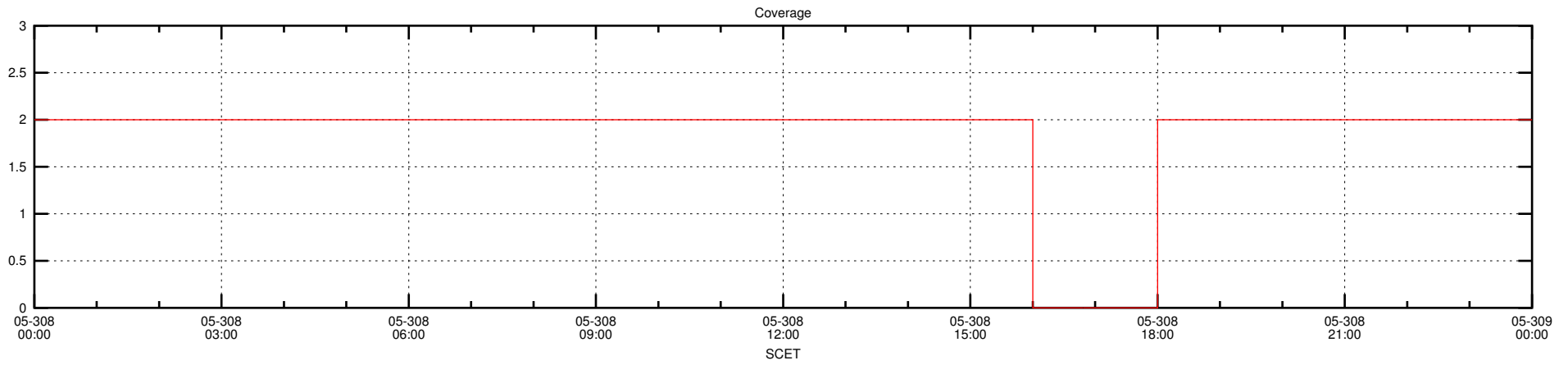
Z-Axis



CK #2 S/C Body Rates (DOY 308-309)

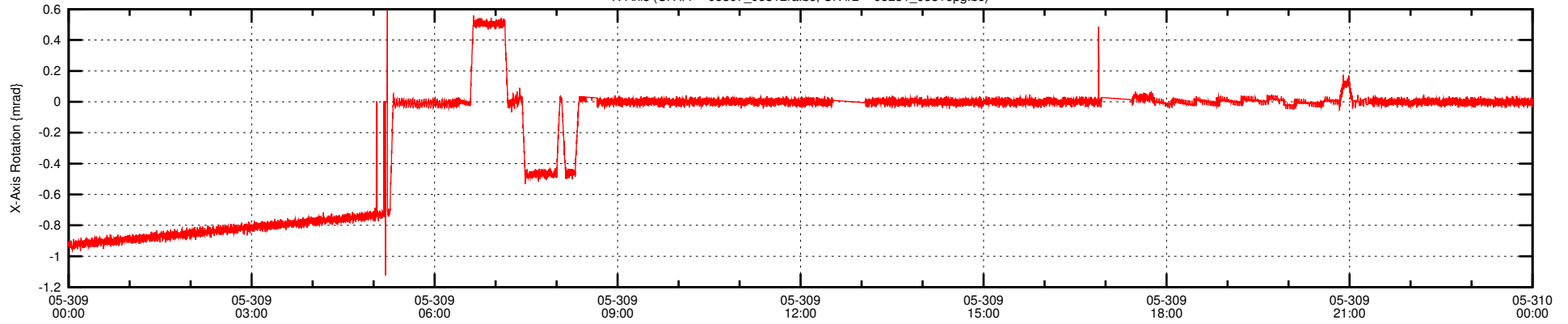


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 308-309)

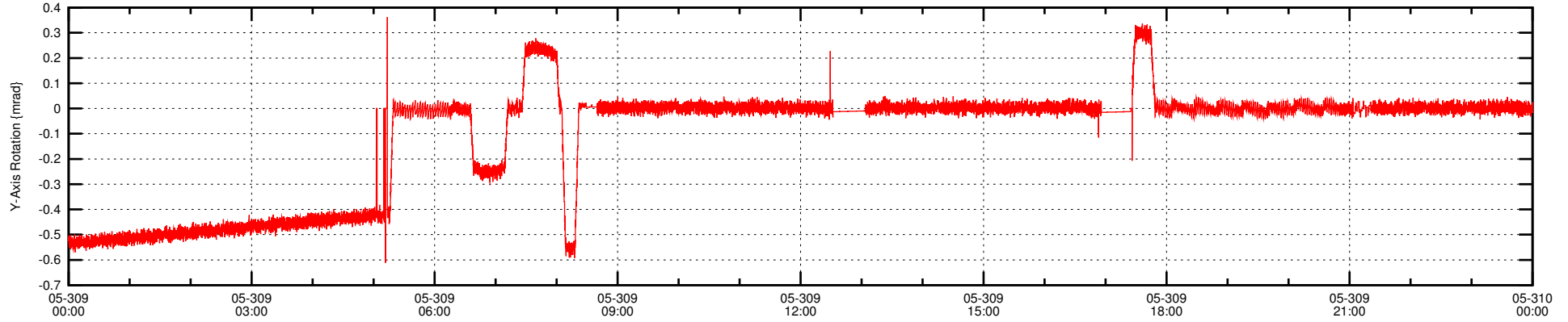


Rotation From CK #2 to CK #1 (DOY 309-310)

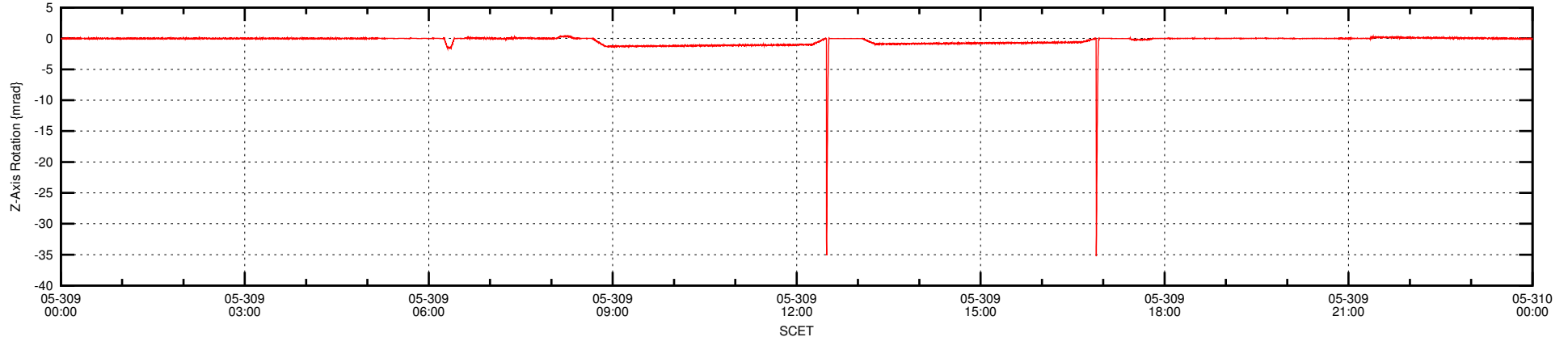
X-Axis (CK #1 = 05307_05312ra.bc; CK #2 = 05281_05316pg.bc)



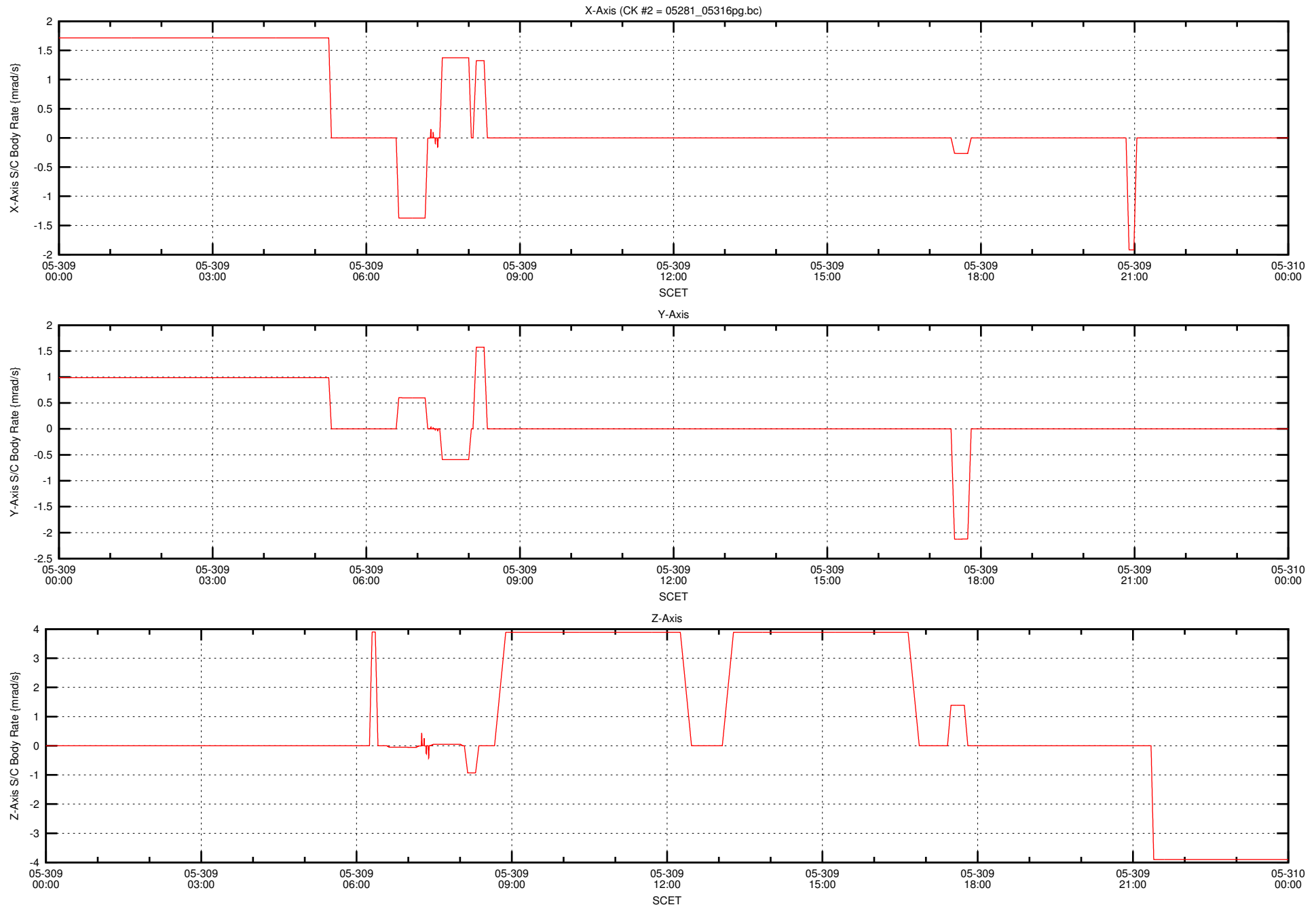
Y-Axis



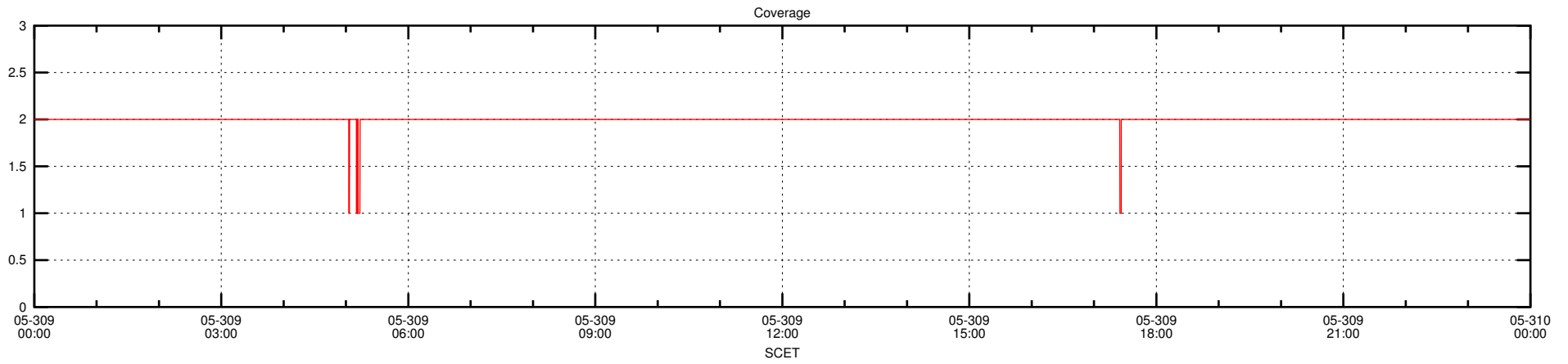
Z-Axis



CK #2 S/C Body Rates (DOY 309-310)

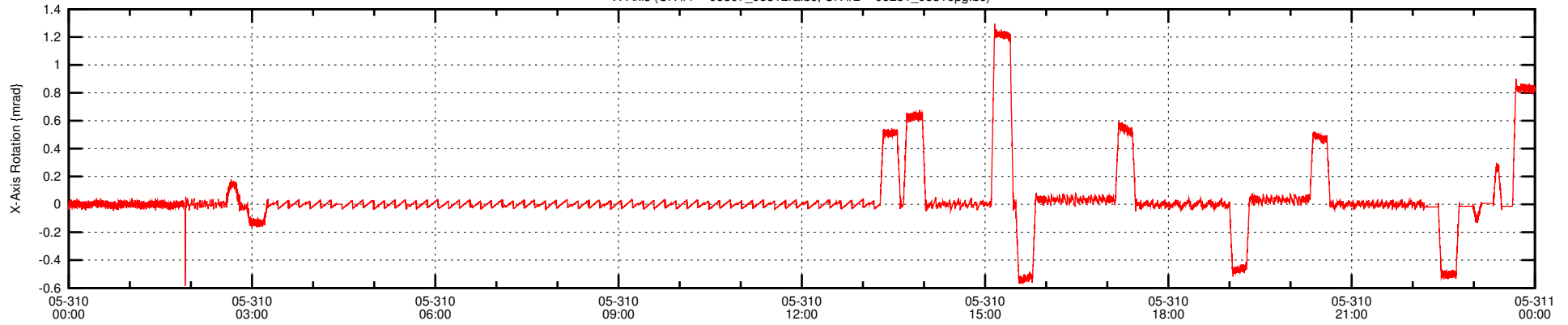


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 309-310)

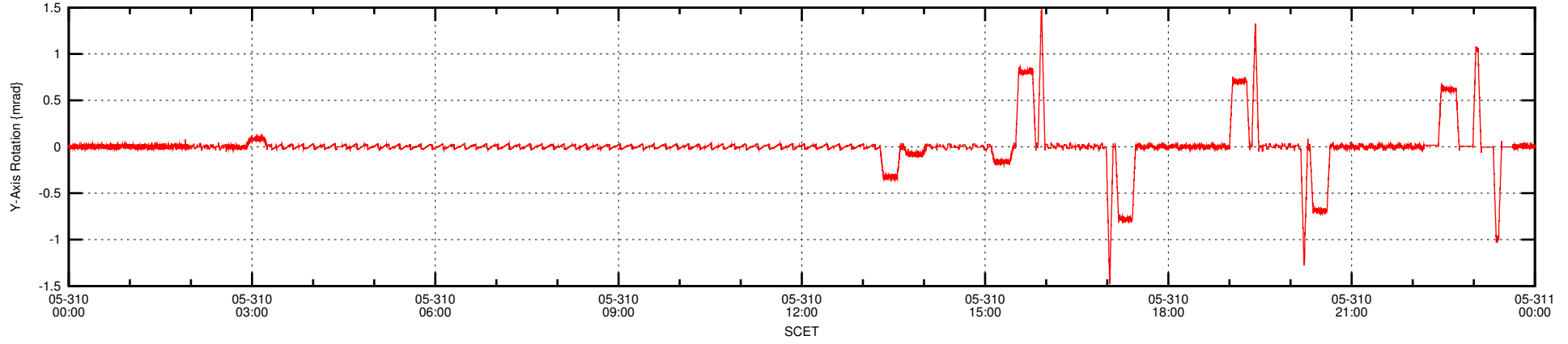


Rotation From CK #2 to CK #1 (DOY 310-311)

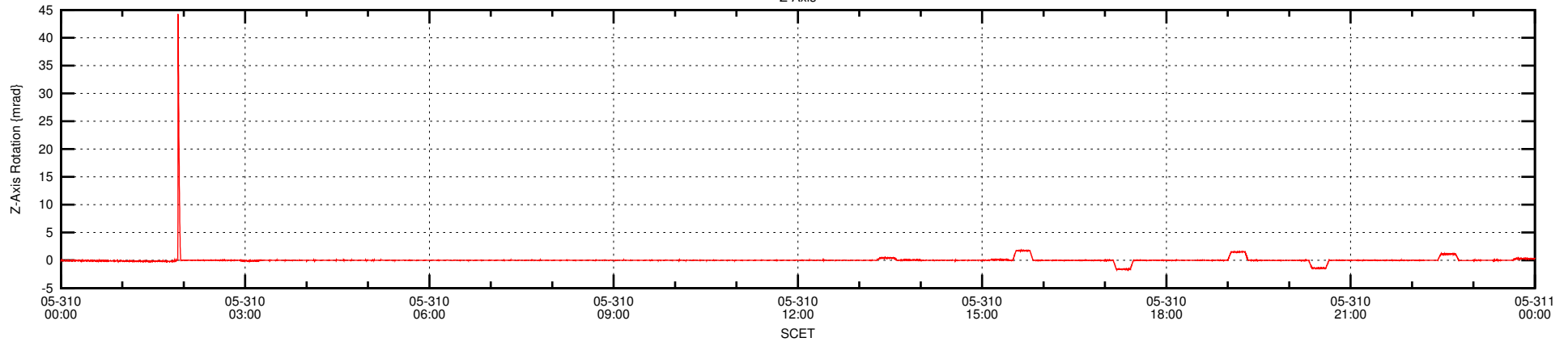
X-Axis (CK #1 = 05307_05312ra.bc; CK #2 = 05281_05316pg.bc)



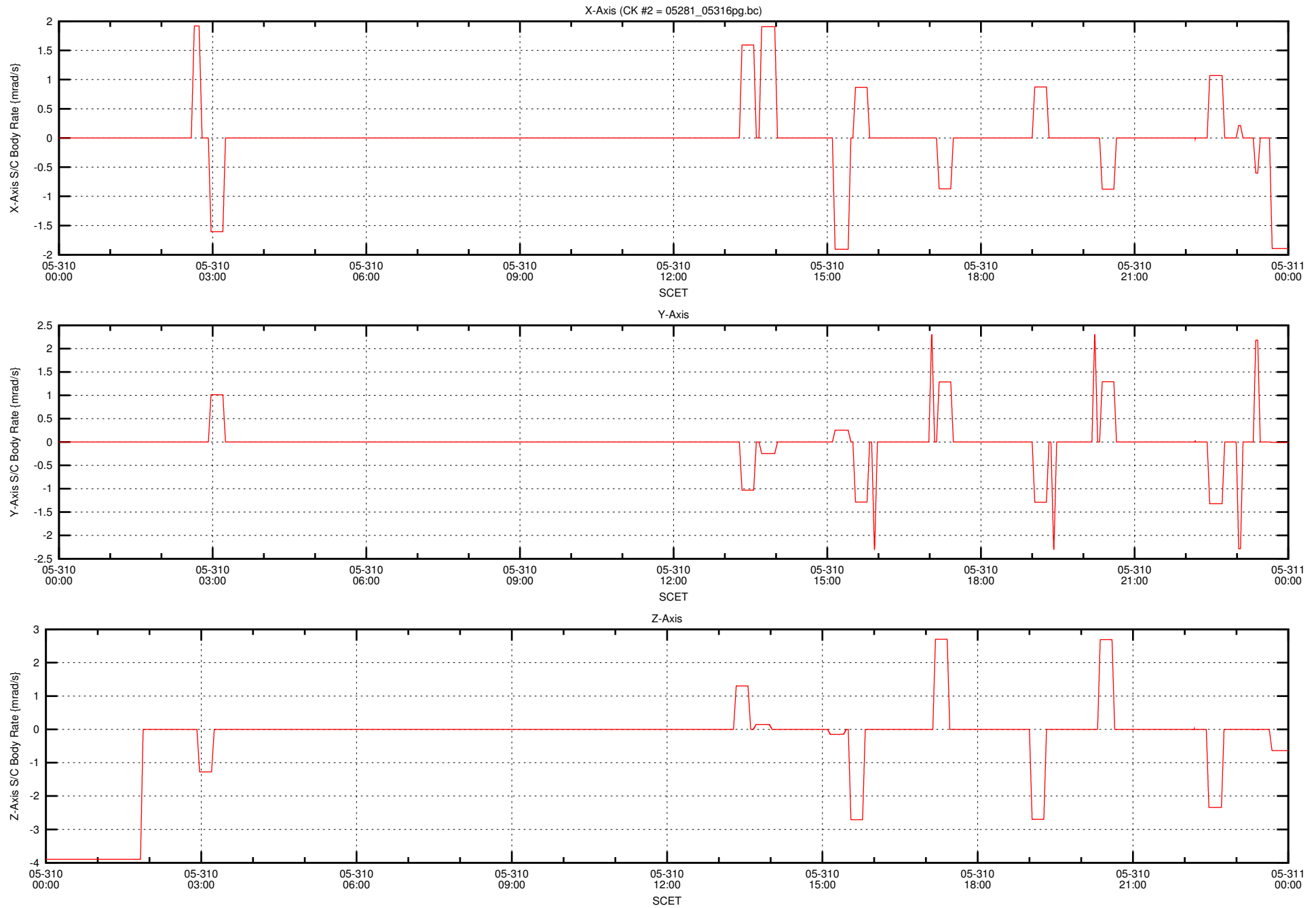
Y-Axis



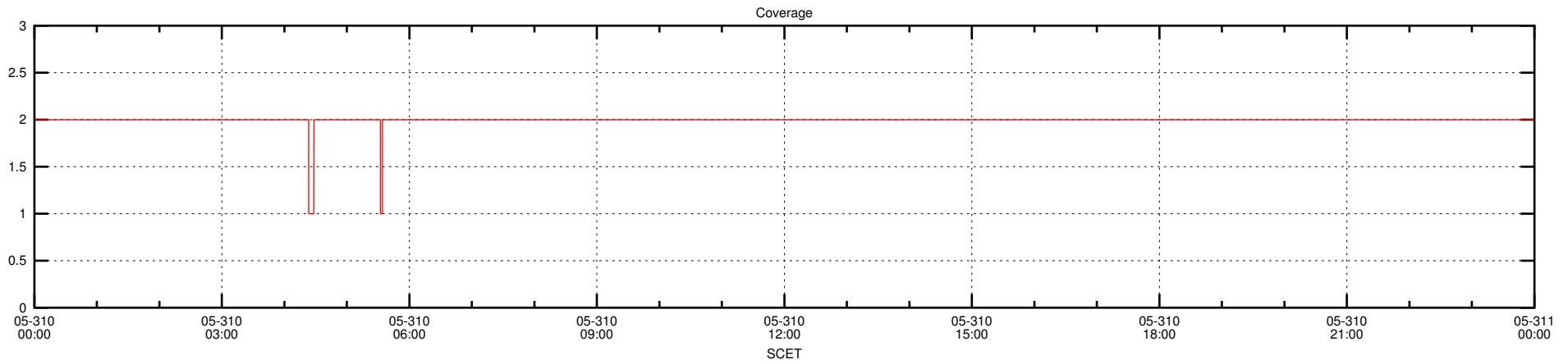
Z-Axis



CK #2 S/C Body Rates (DOY 310-311)

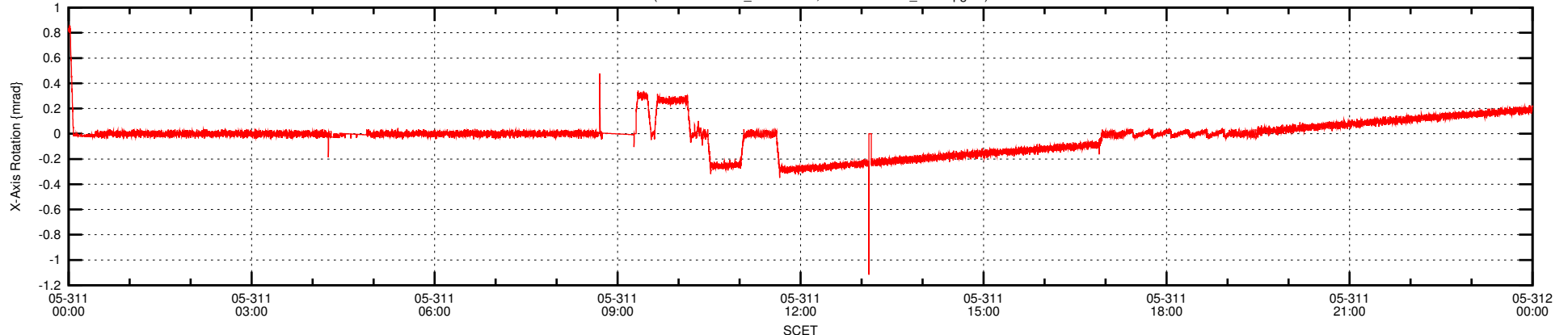


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 310-311)

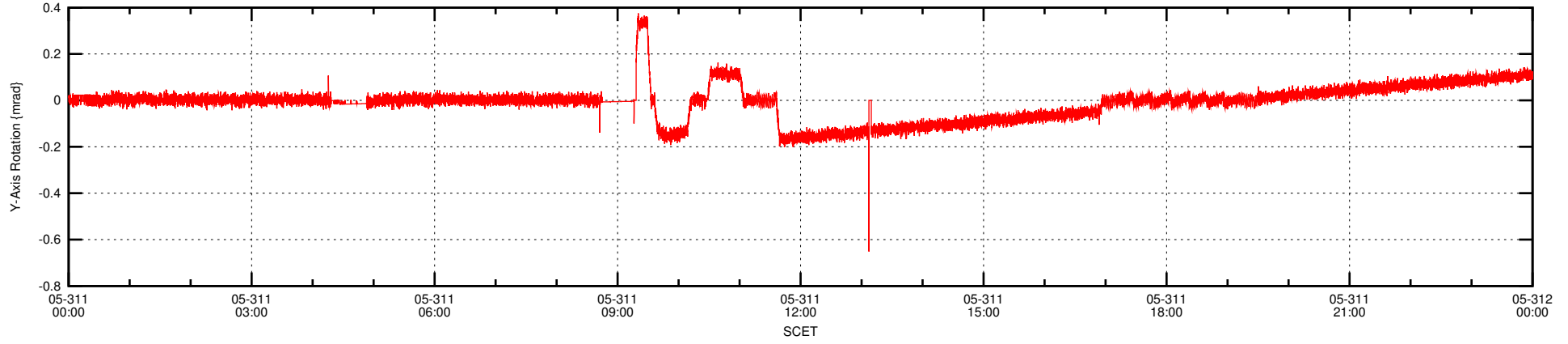


Rotation From CK #2 to CK #1 (DOY 311-311)

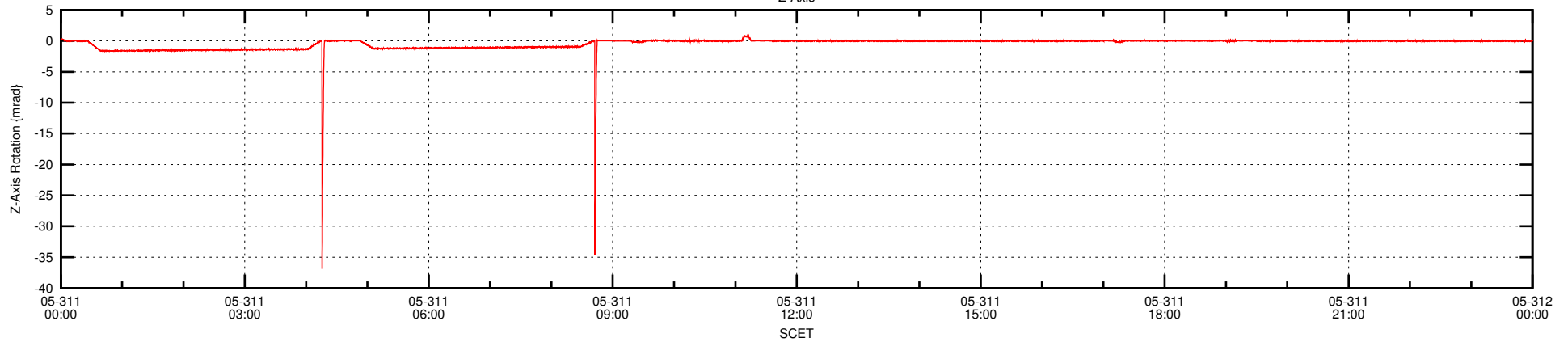
X-Axis (CK #1 = 05307_05312ra.bc; CK #2 = 05281_05316pg.bc)



Y-Axis



Z-Axis



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 311-311)

