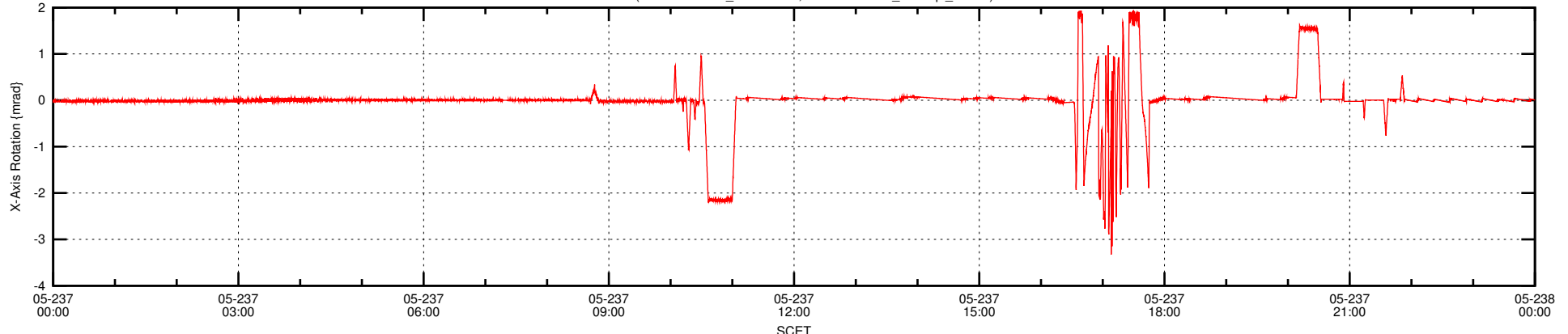
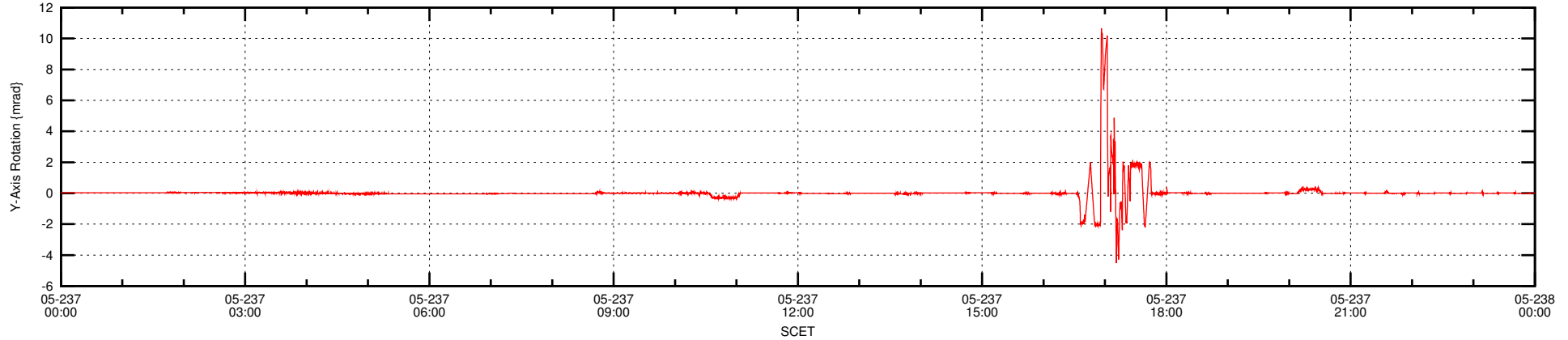


Rotation From CK #2 to CK #1 (DOY 237-238)

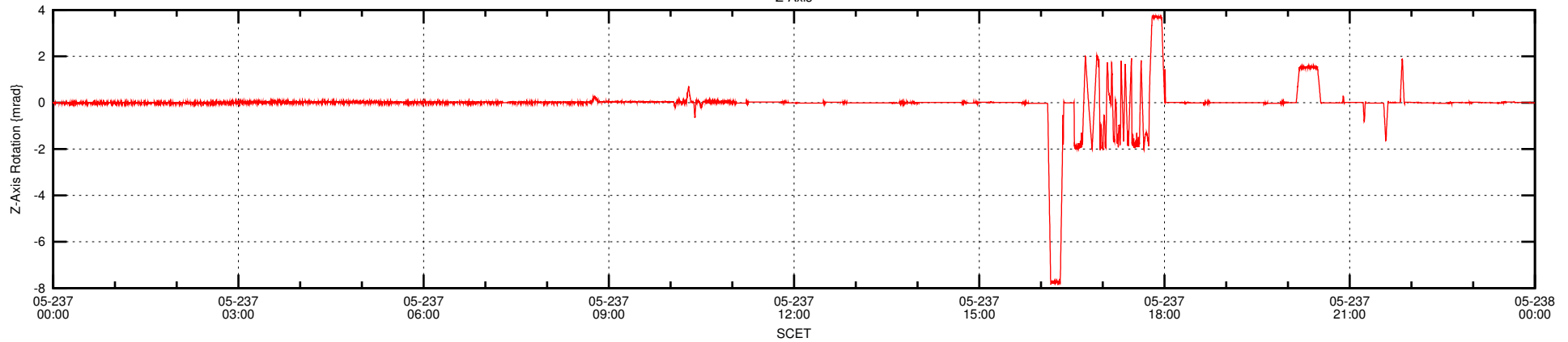
X-Axis (CK #1 = 05237_05242ra.bc; CK #2 = 05212_05242pl_fsiv.bc)



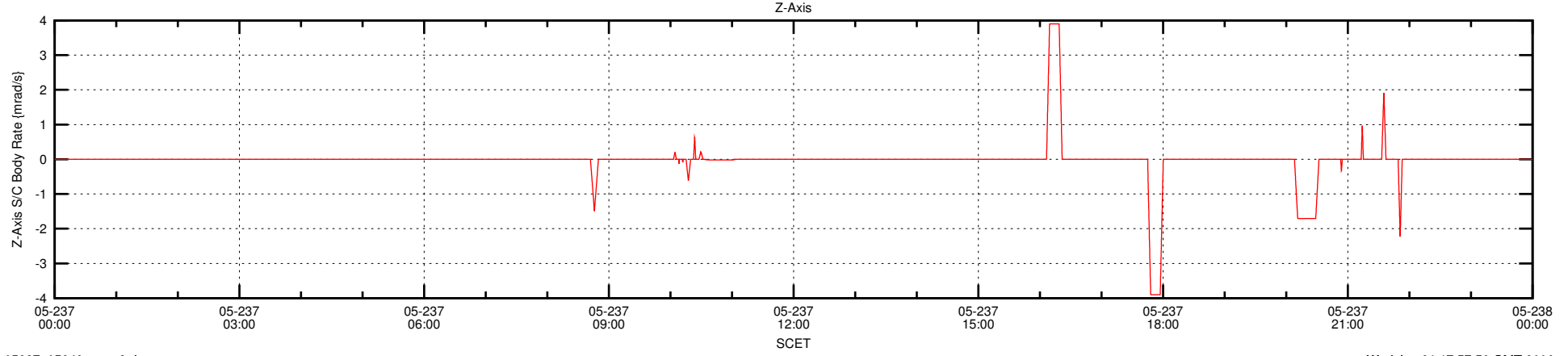
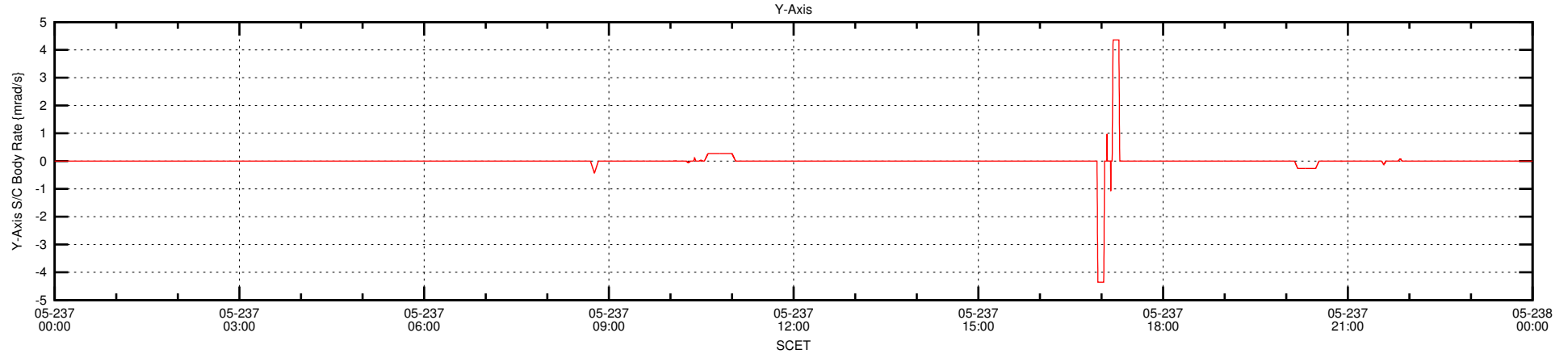
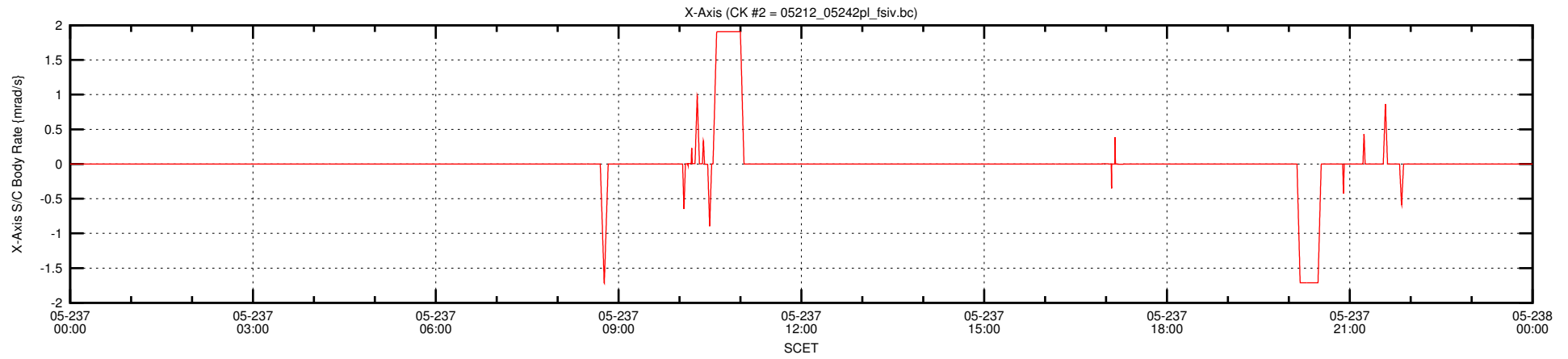
Y-Axis



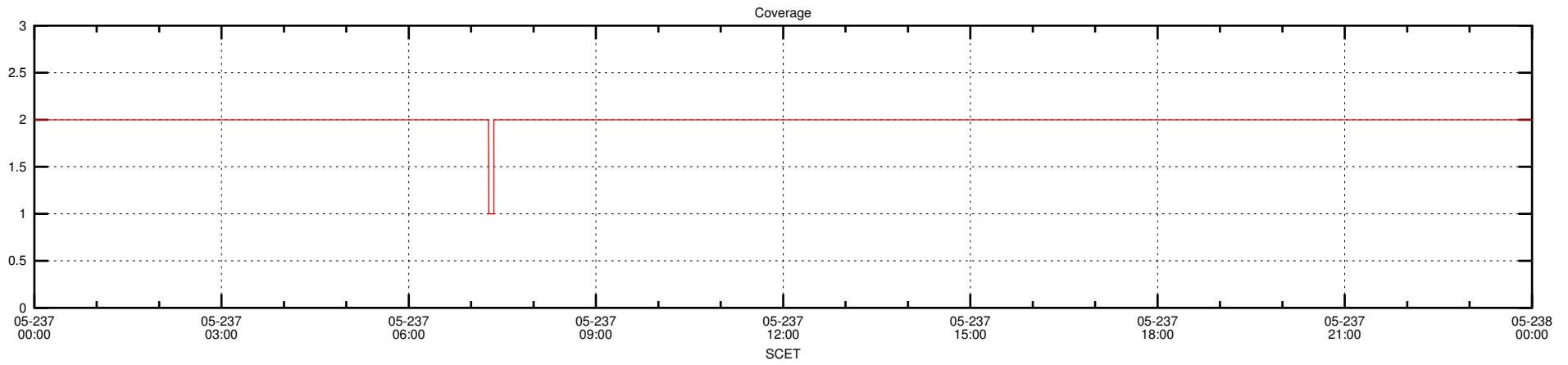
Z-Axis



CK #2 S/C Body Rates (DOY 237-238)

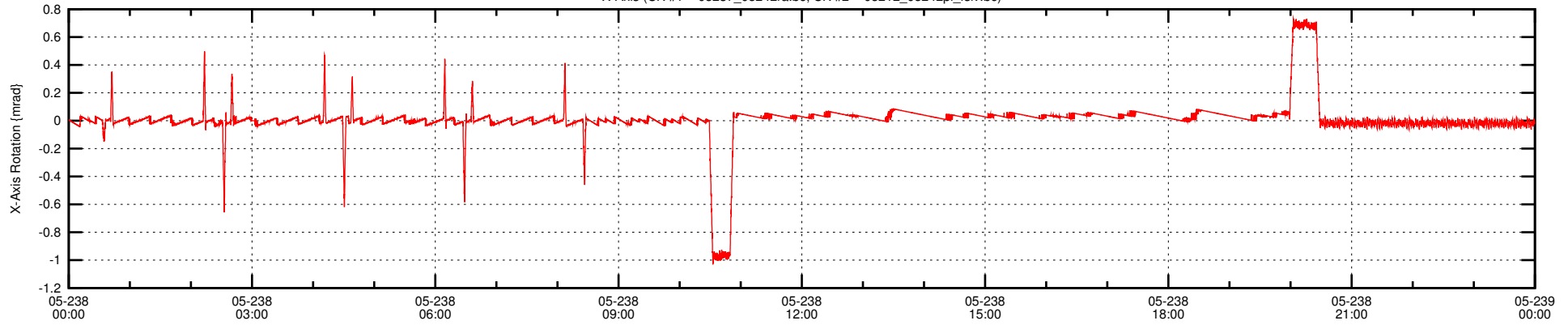


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 237-238)

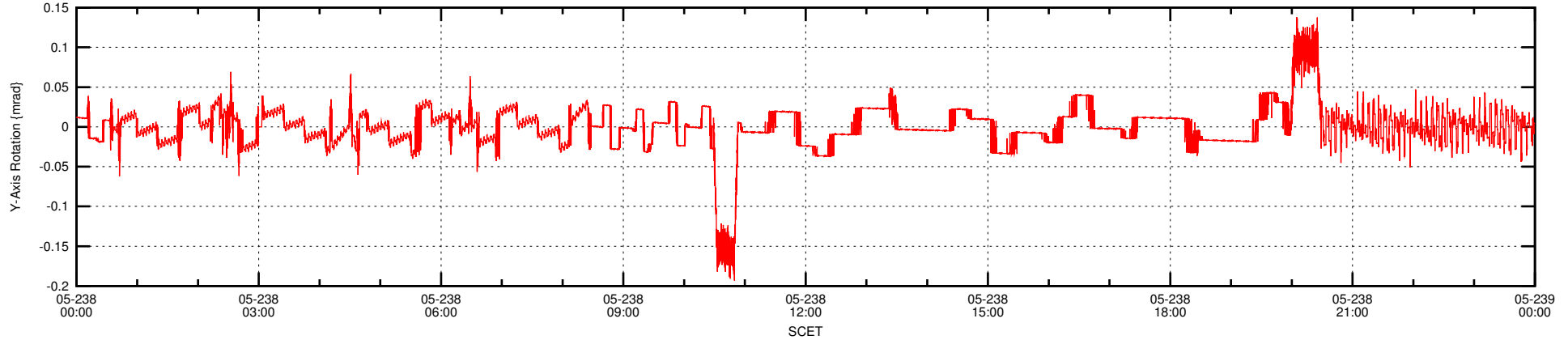


Rotation From CK #2 to CK #1 (DOY 238-239)

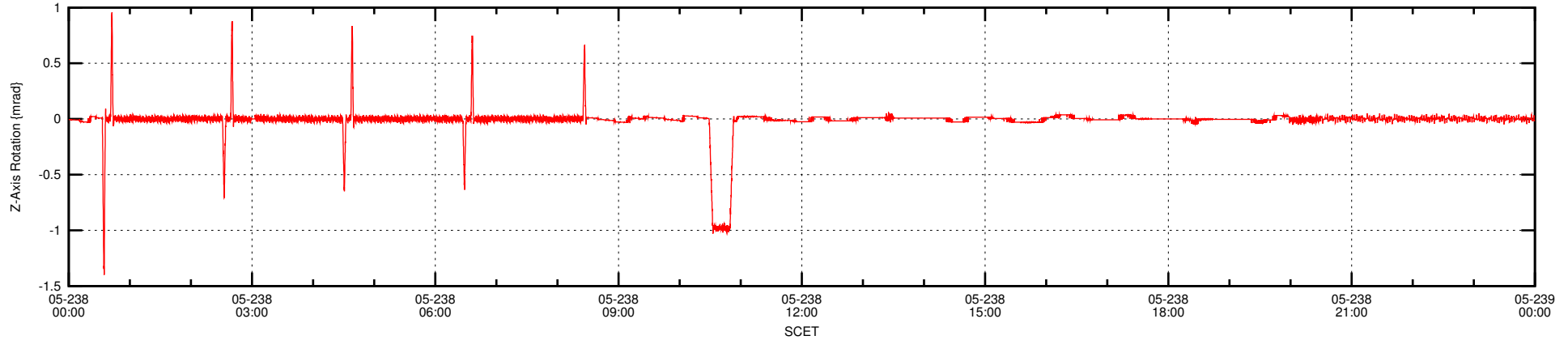
X-Axis (CK #1 = 05237_05242ra.bc; CK #2 = 05212_05242pl_fsiv.bc)



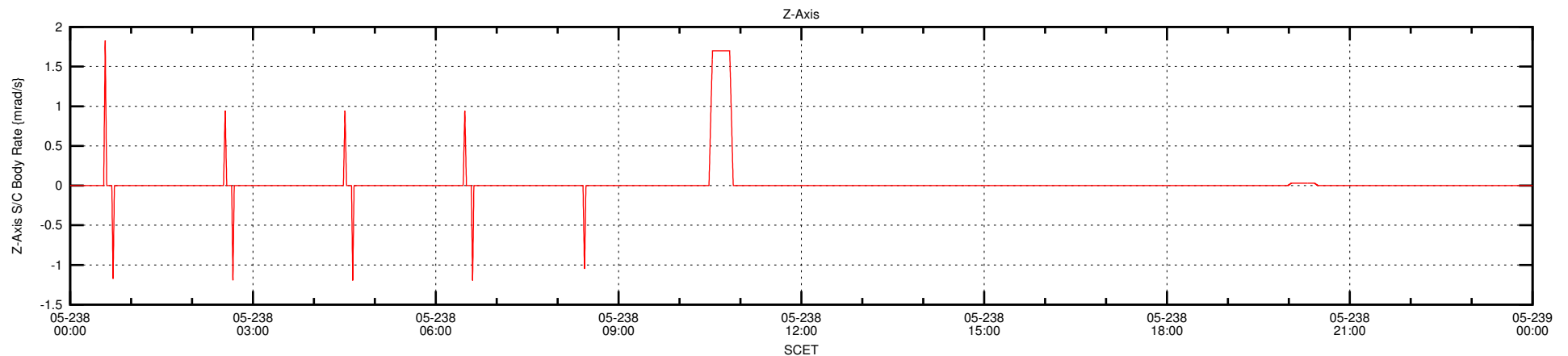
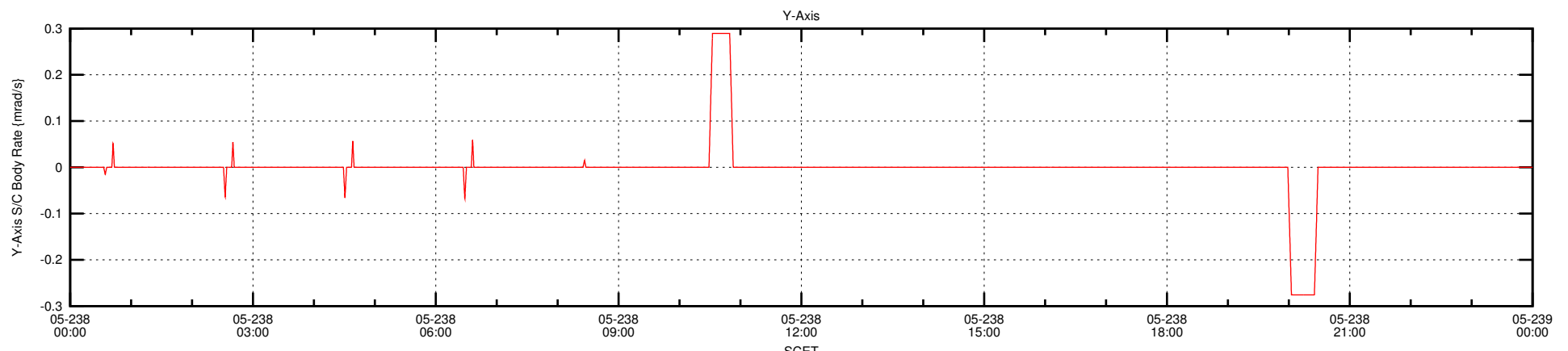
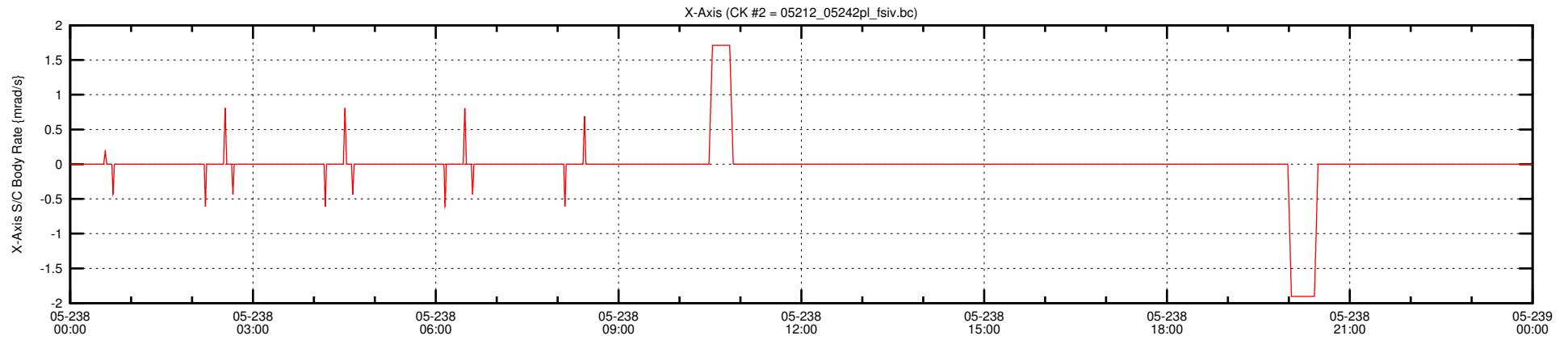
Y-Axis



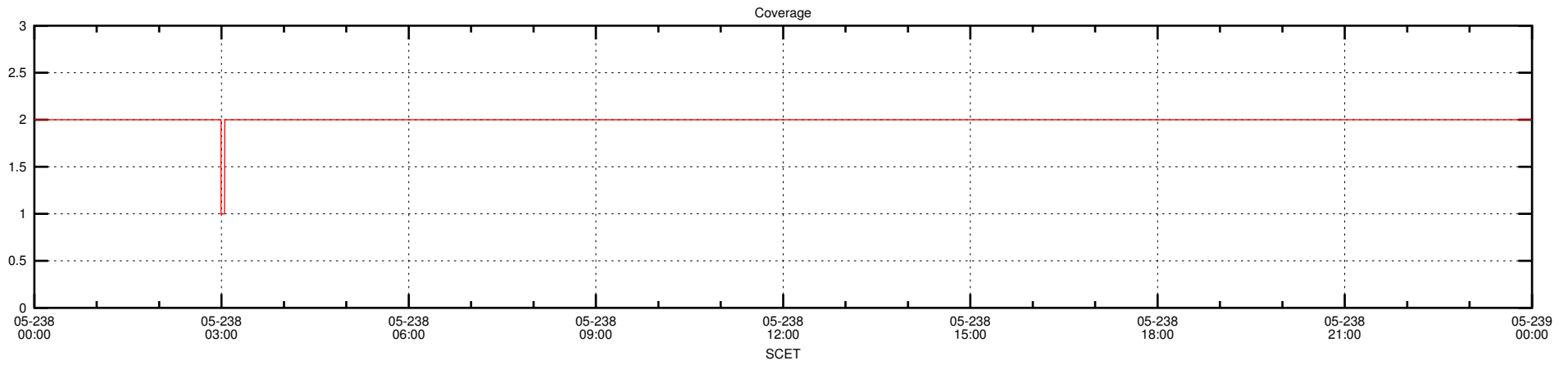
Z-Axis



CK #2 S/C Body Rates (DOY 238-239)

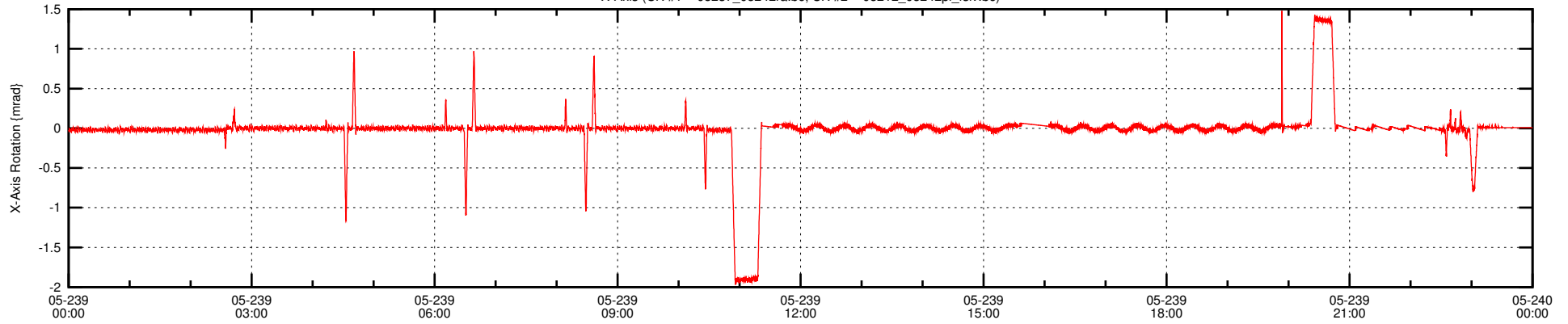


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 238-239)

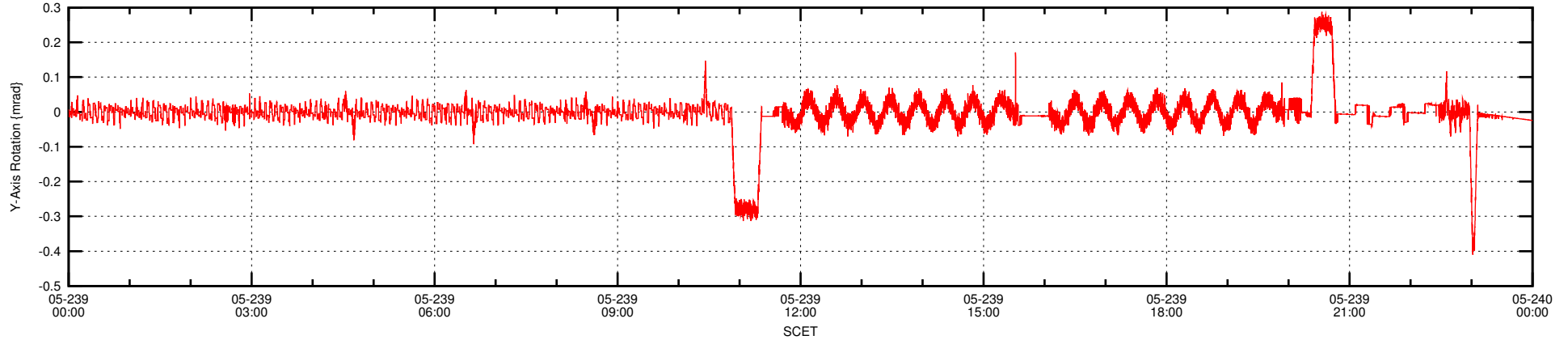


Rotation From CK #2 to CK #1 (DOY 239-240)

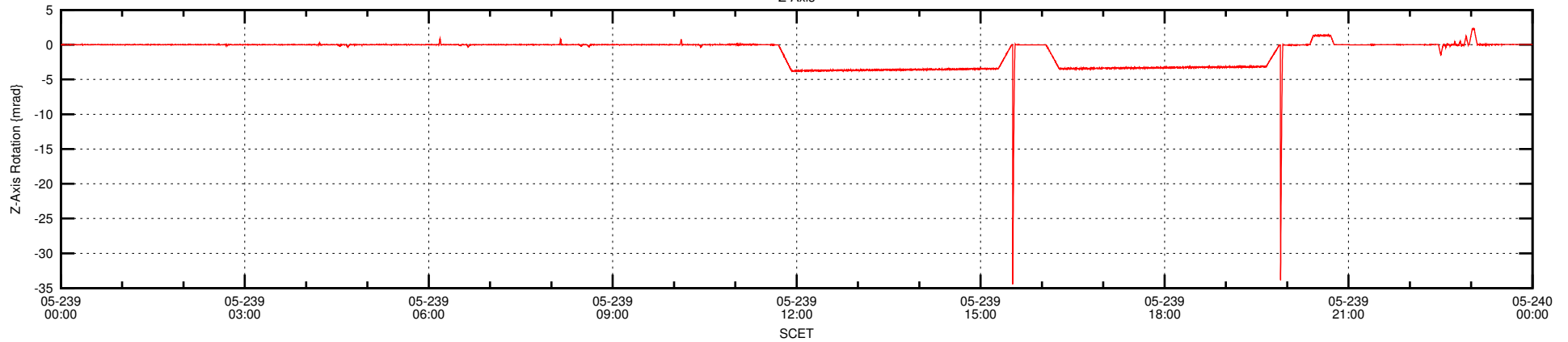
X-Axis (CK #1 = 05237_05242ra.bc; CK #2 = 05212_05242pl_fsiv.bc)



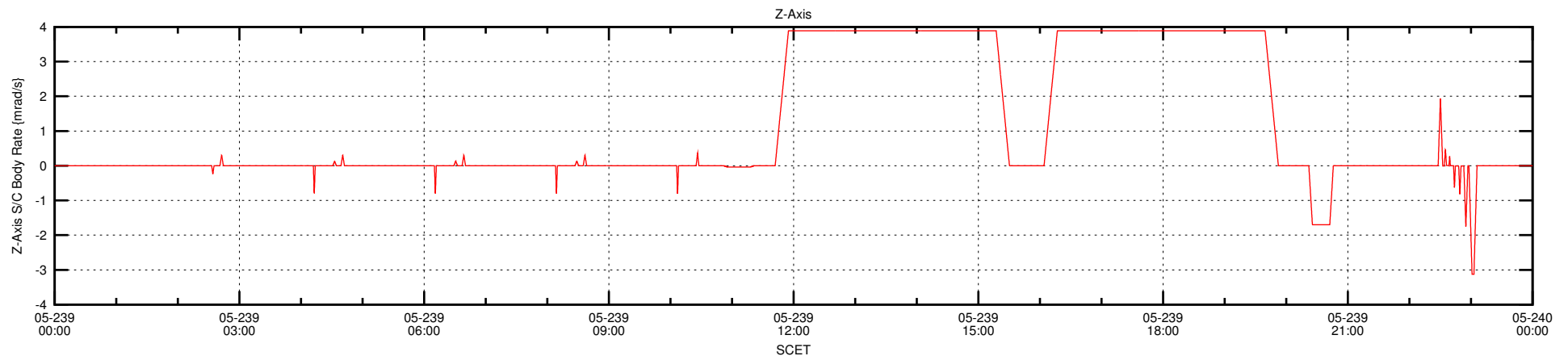
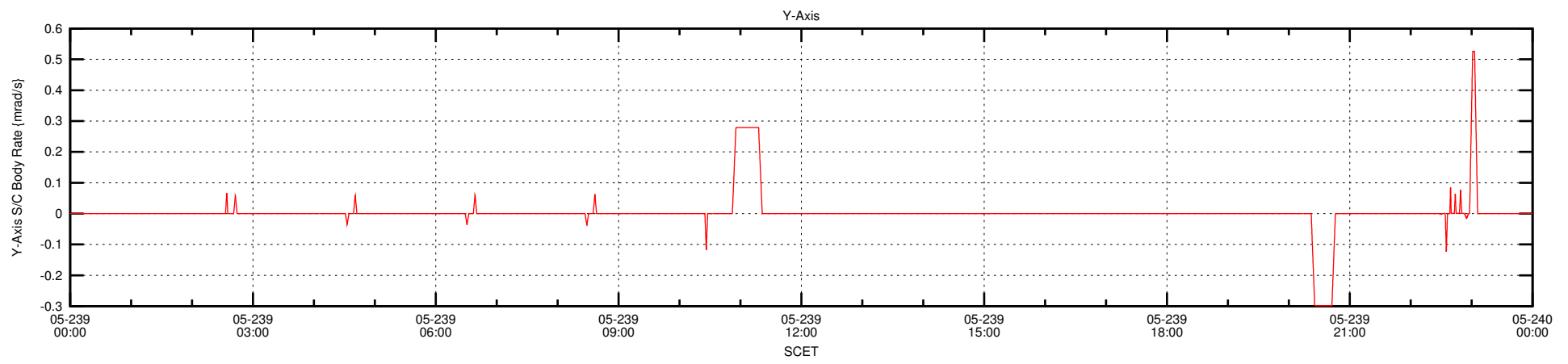
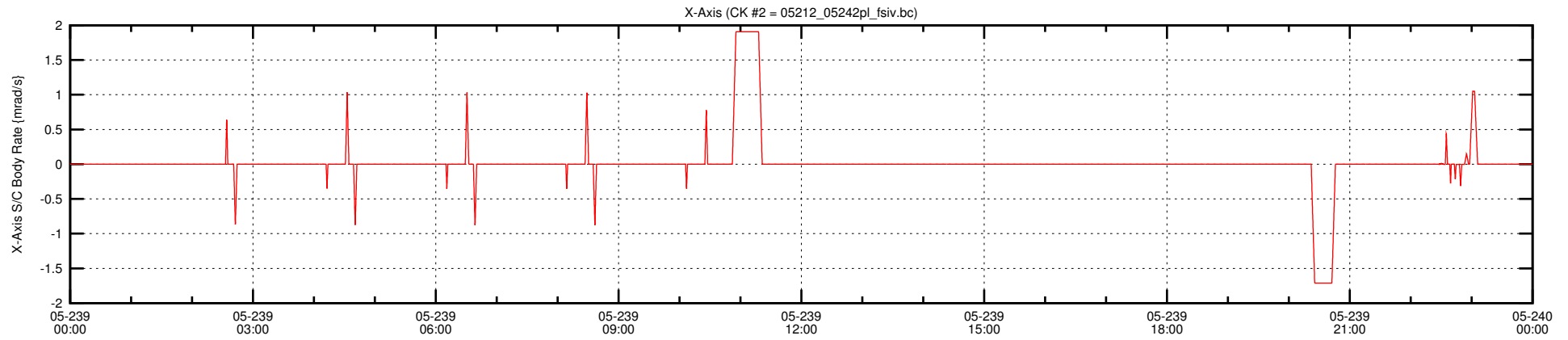
Y-Axis



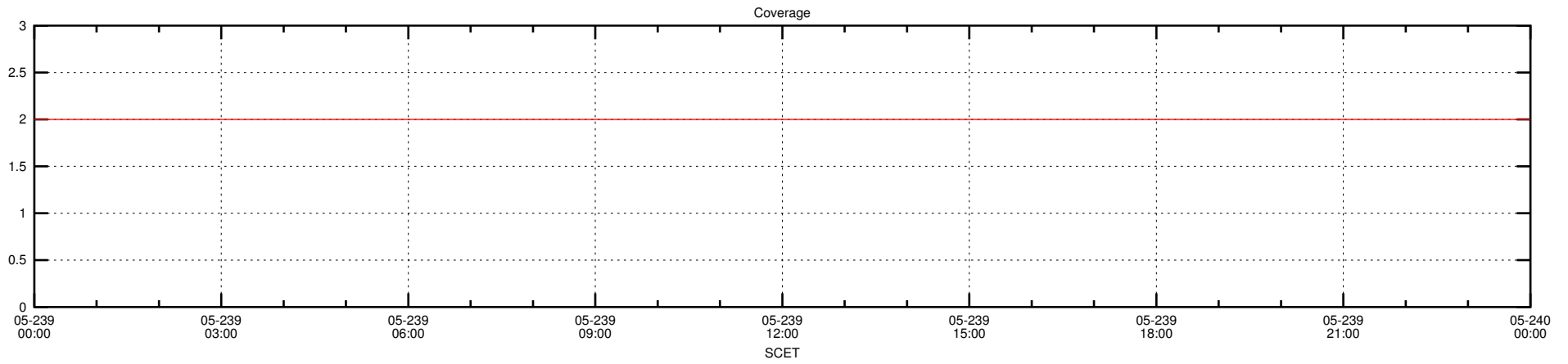
Z-Axis



CK #2 S/C Body Rates (DOY 239-240)

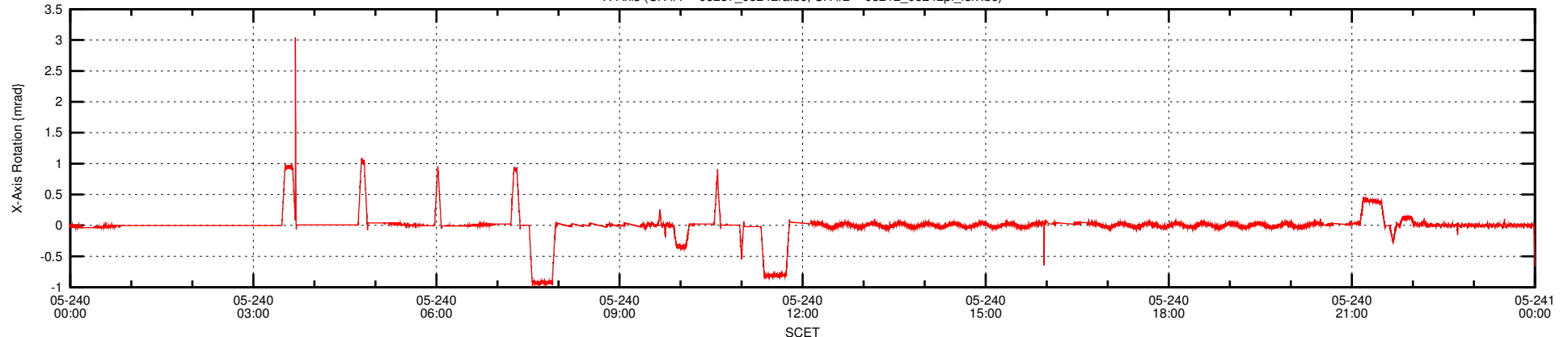


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 239-240)

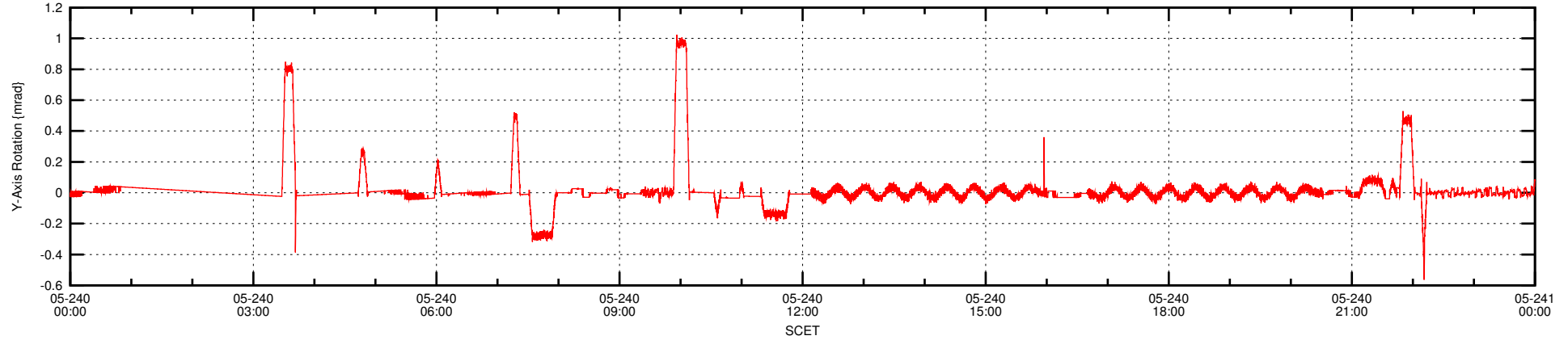


Rotation From CK #2 to CK #1 (DOY 240-241)

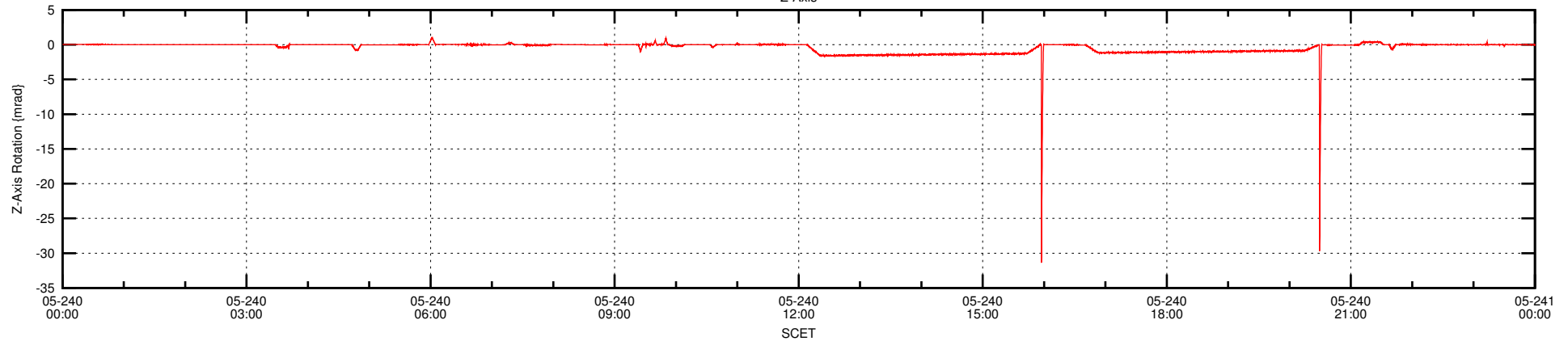
X-Axis (CK #1 = 05237_05242ra.bc; CK #2 = 05212_05242pl_fsiv.bc)



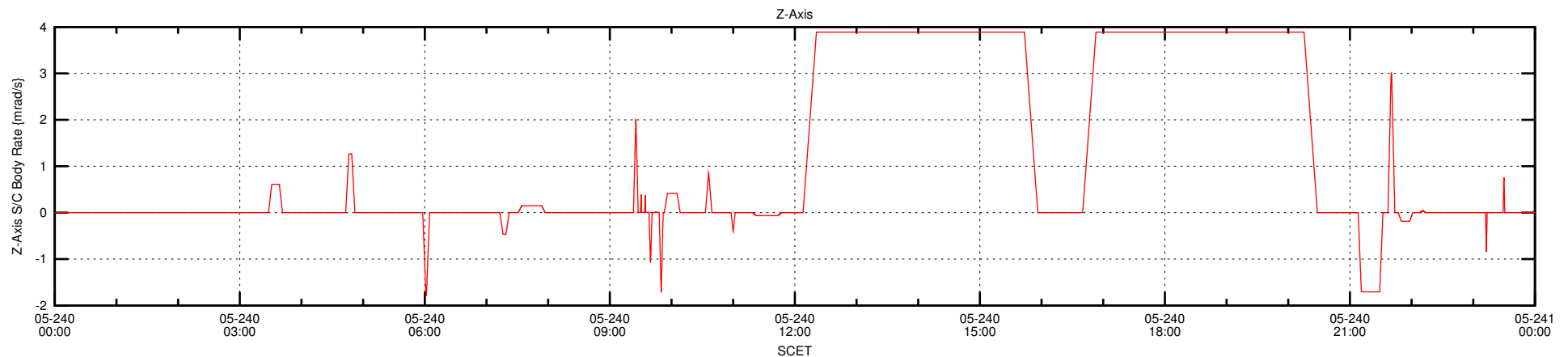
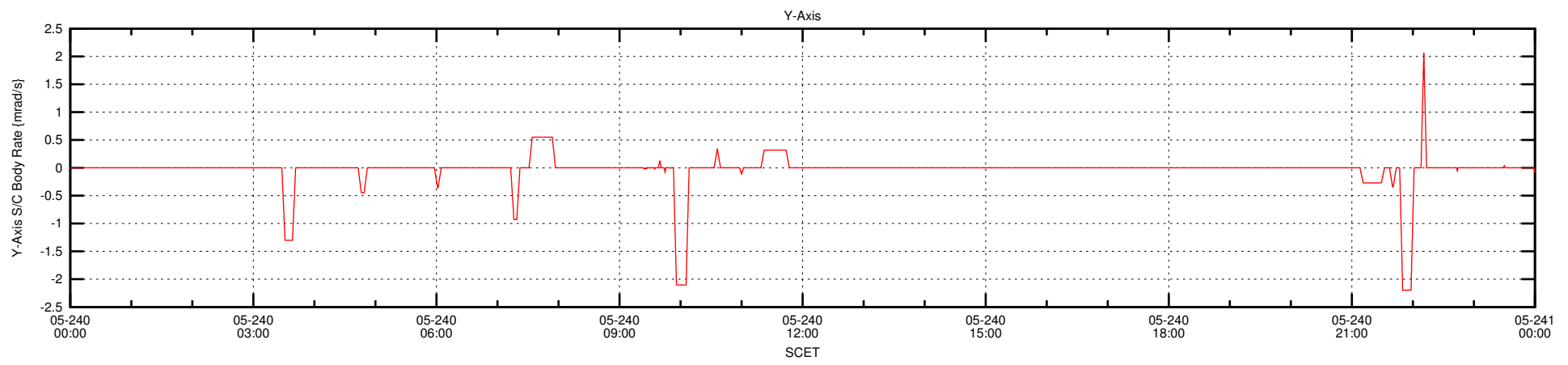
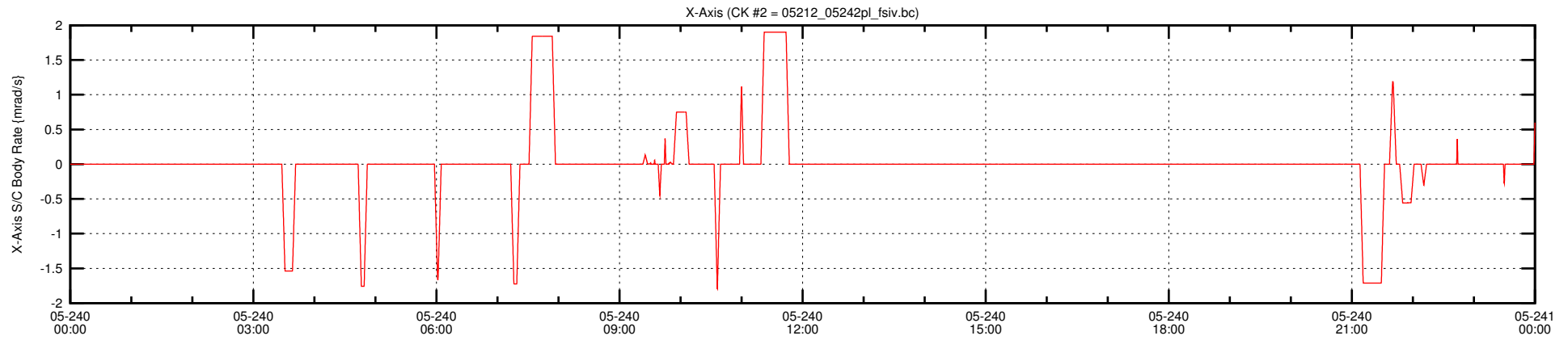
Y-Axis



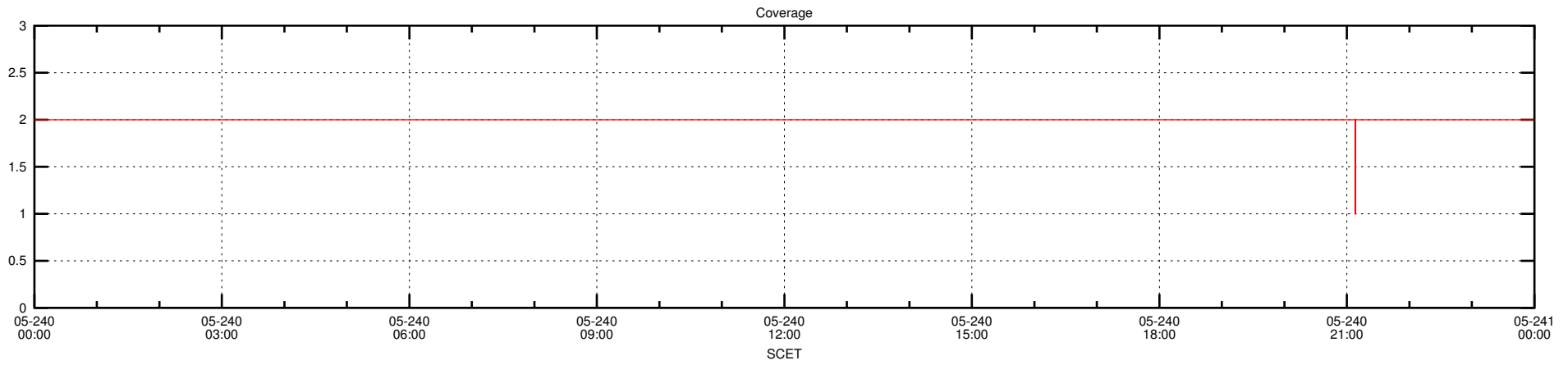
Z-Axis



CK #2 S/C Body Rates (DOY 240-241)

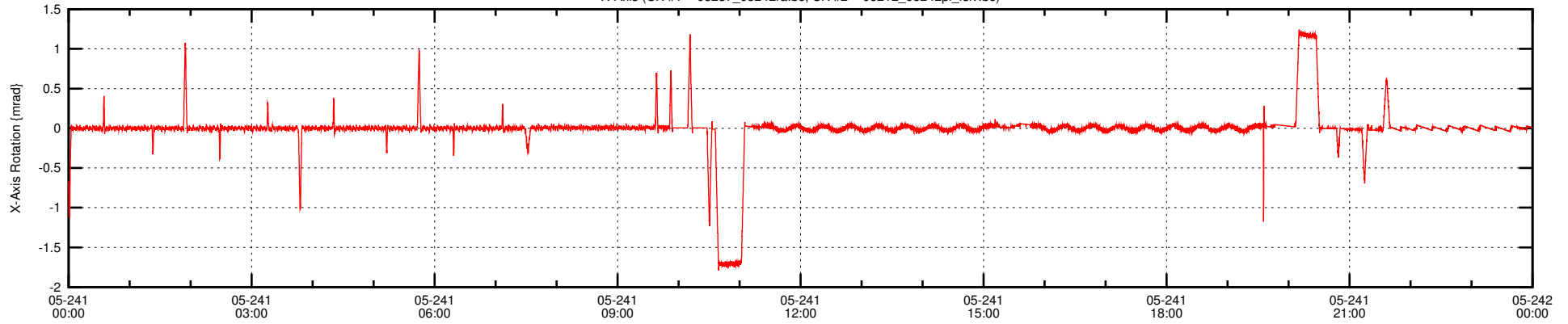


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 240-241)

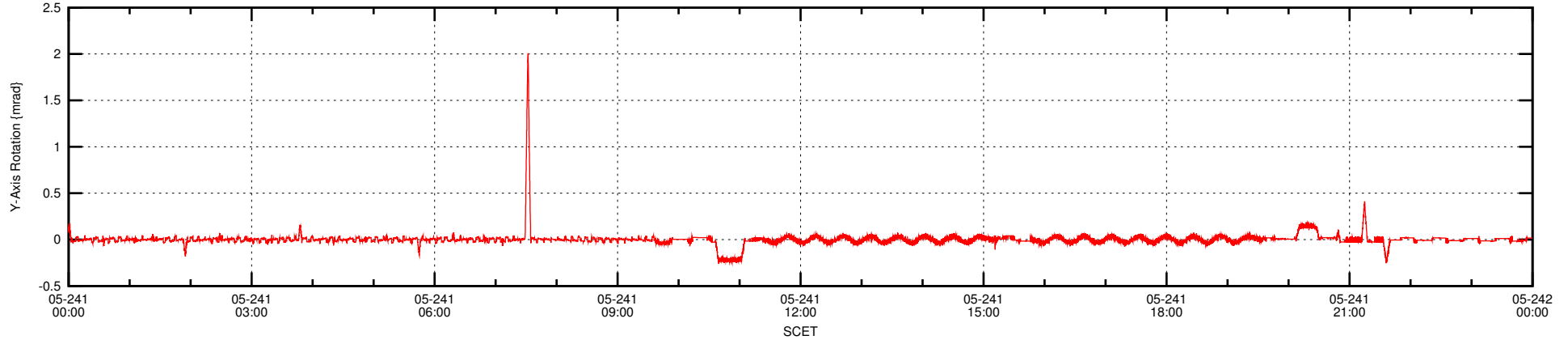


Rotation From CK #2 to CK #1 (DOY 241-241)

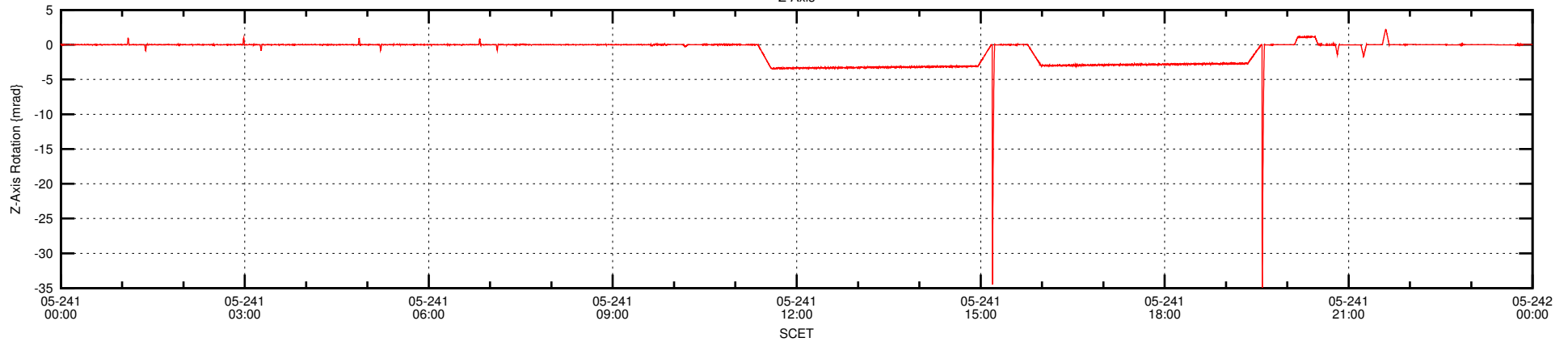
X-Axis (CK #1 = 05237_05242ra.bc; CK #2 = 05212_05242pl_fsiv.bc)



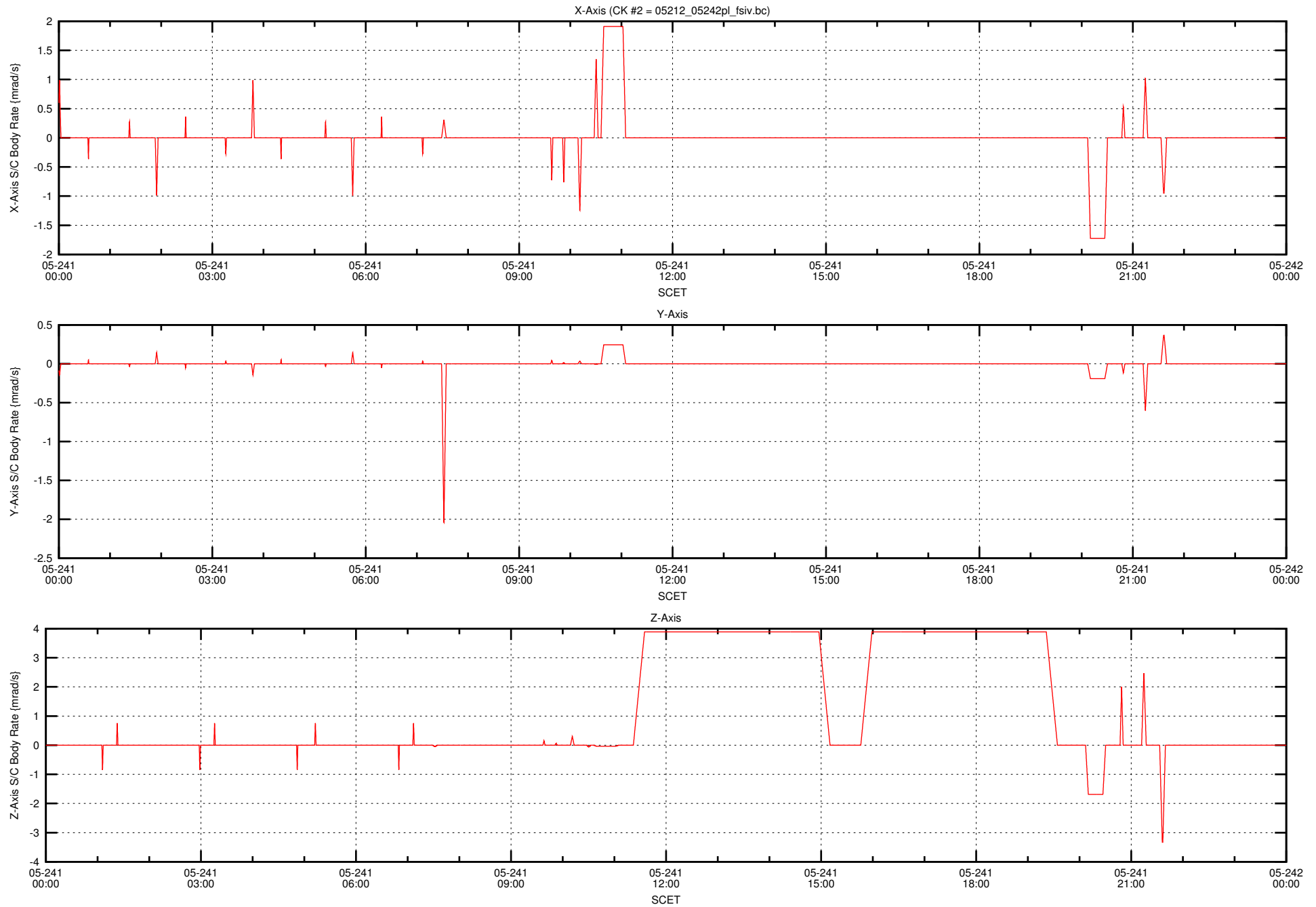
Y-Axis



Z-Axis



CK #2 S/C Body Rates (DOY 241-241)



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 241-241)

