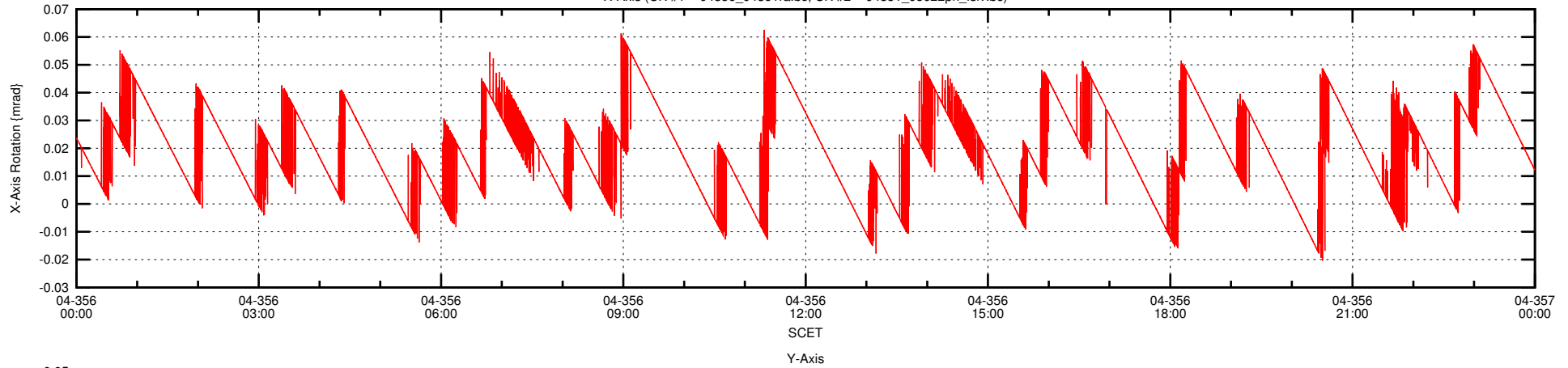
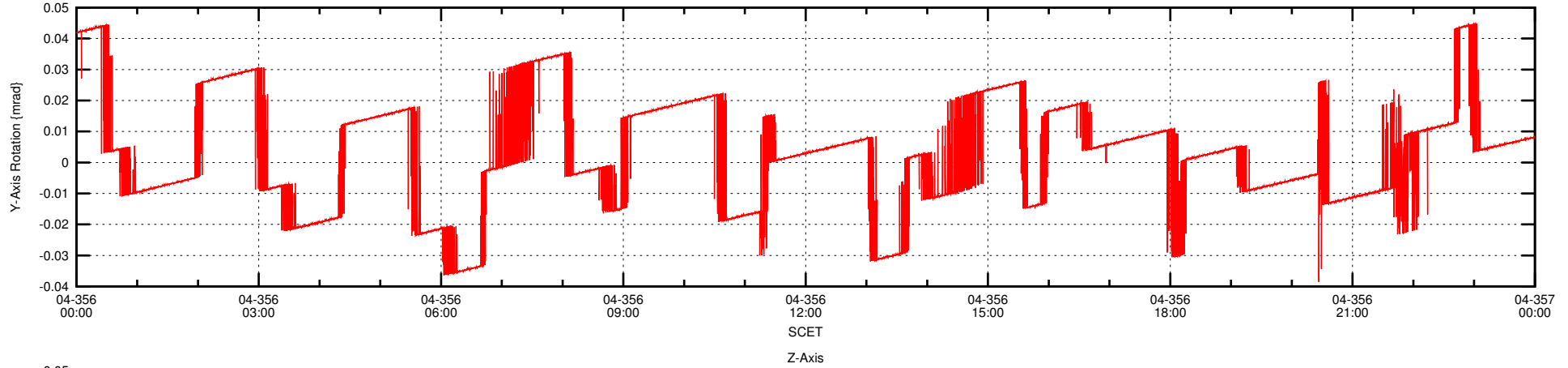


# Rotation From CK #2 to CK #1 (DOY 356-357)

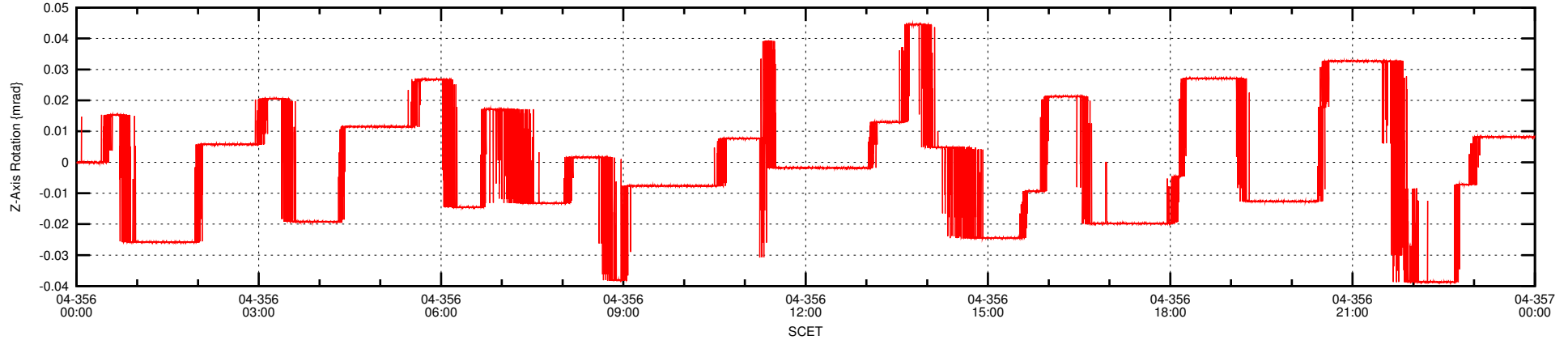
X-Axis (CK #1 = 04356\_04361ra.bc; CK #2 = 04351\_05022ph\_fsiv.bc)



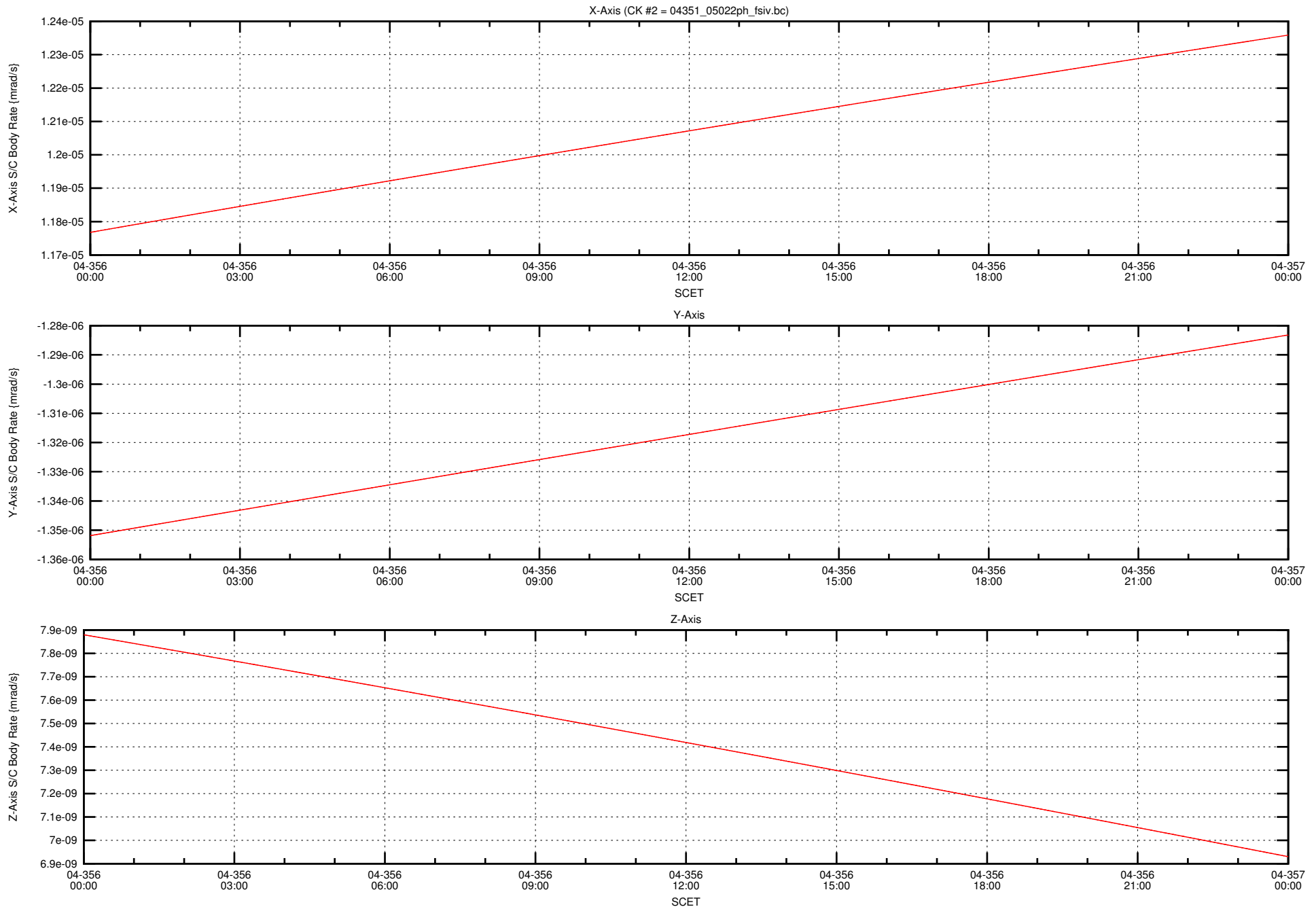
Y-Axis



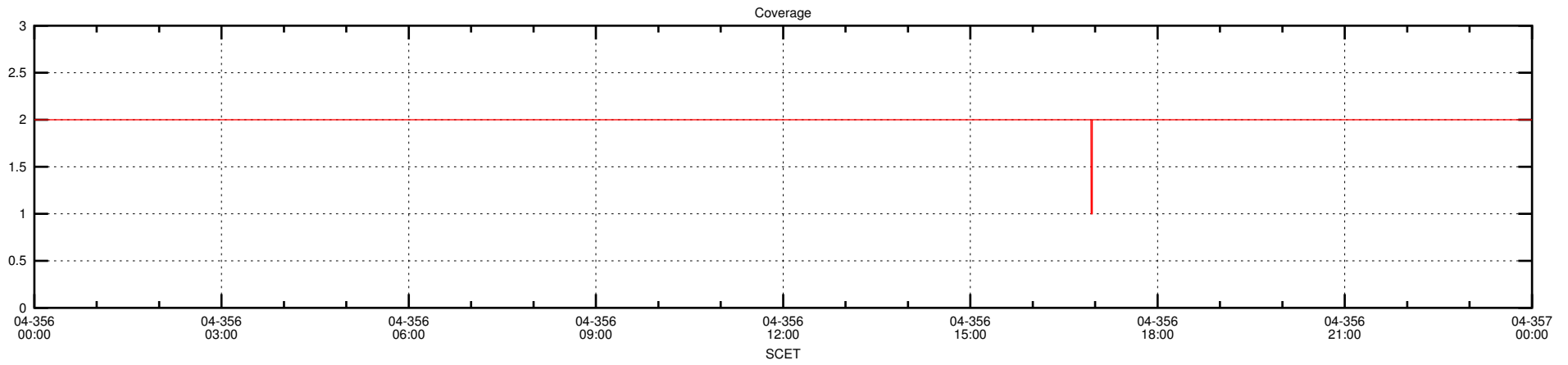
Z-Axis



# CK #2 S/C Body Rates (DOY 356-357)

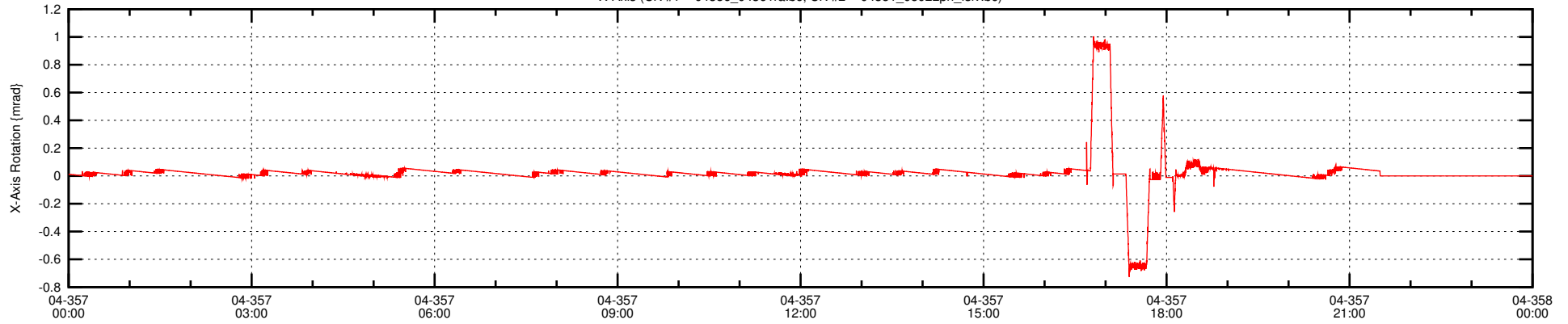


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 356-357)

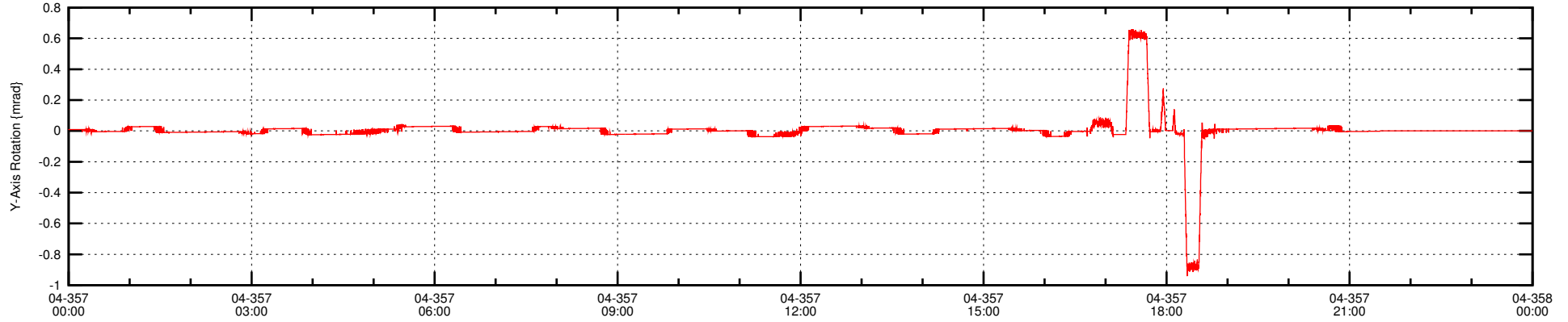


# Rotation From CK #2 to CK #1 (DOY 357-358)

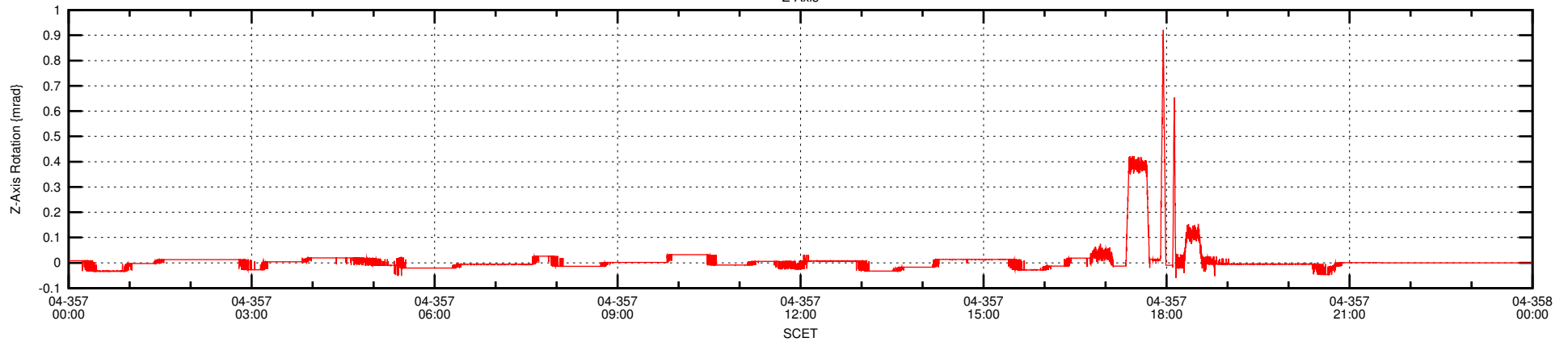
X-Axis (CK #1 = 04356\_04361ra.bc; CK #2 = 04351\_05022ph\_fsiv.bc)



Y-Axis

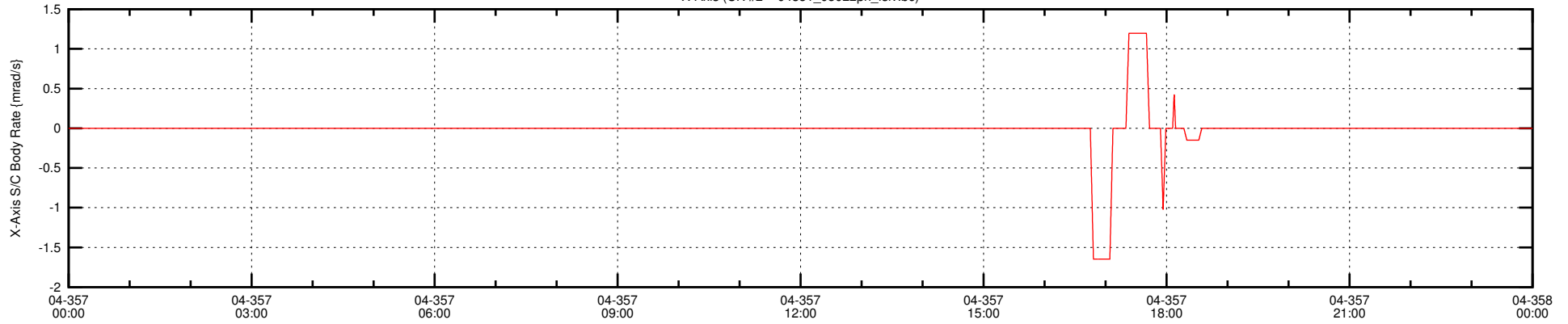


Z-Axis

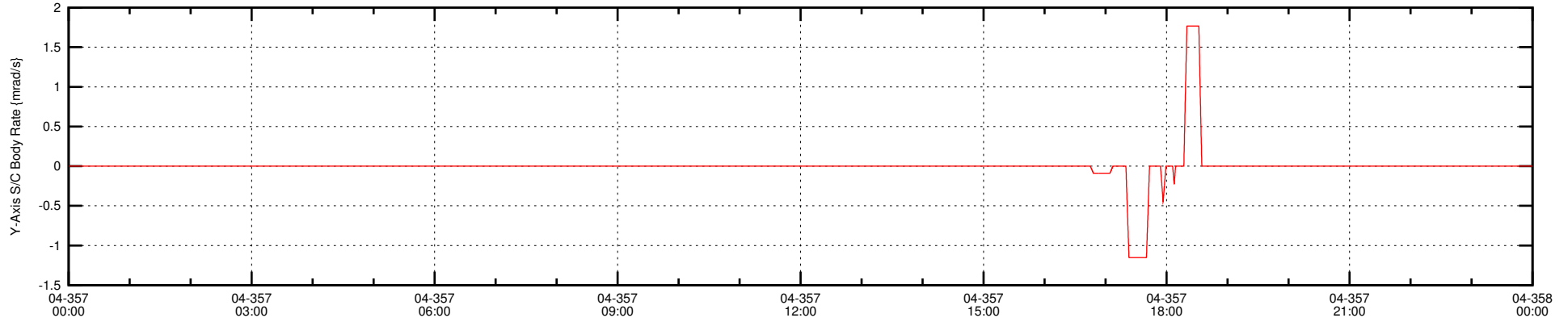


# CK #2 S/C Body Rates (DOY 357-358)

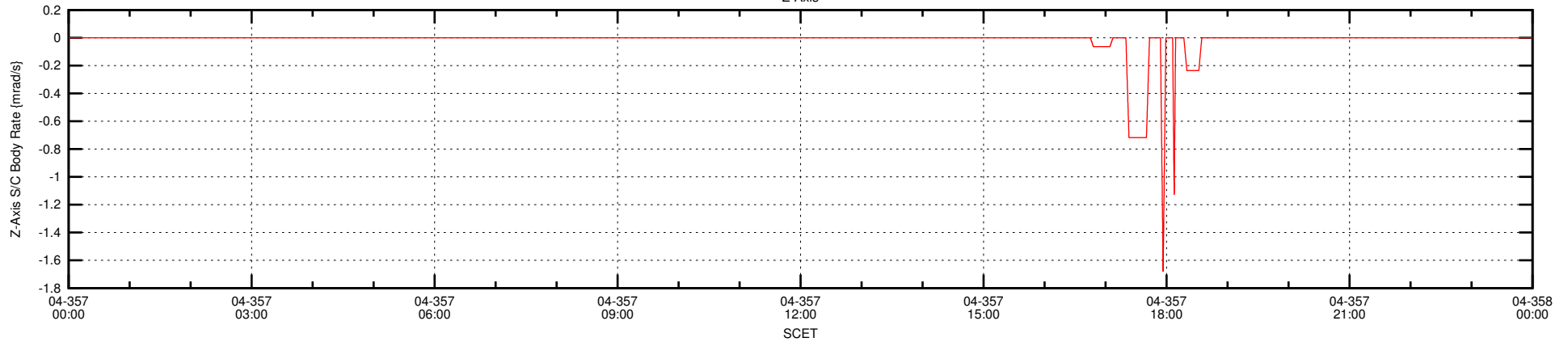
X-Axis (CK #2 = 04351\_05022ph\_fsiv.bc)



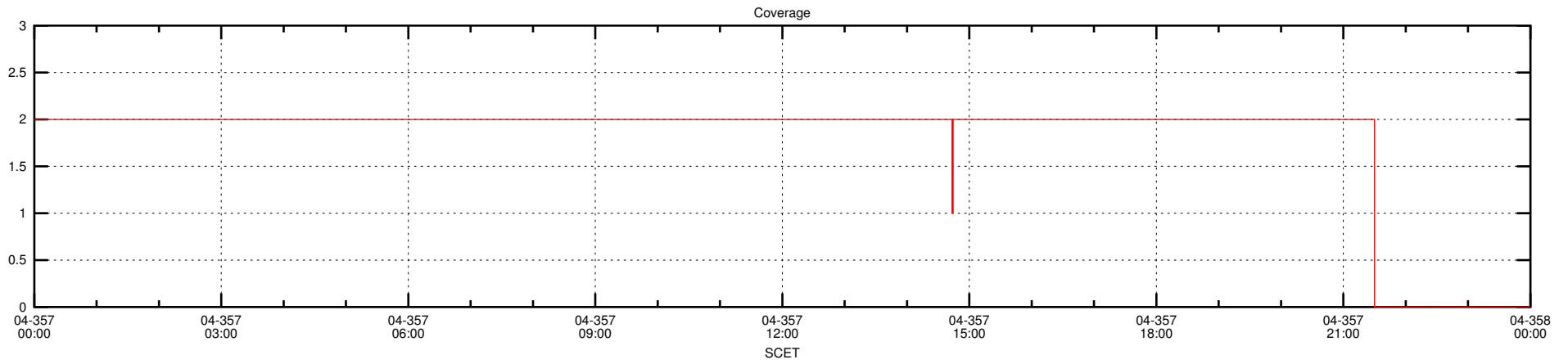
Y-Axis



Z-Axis

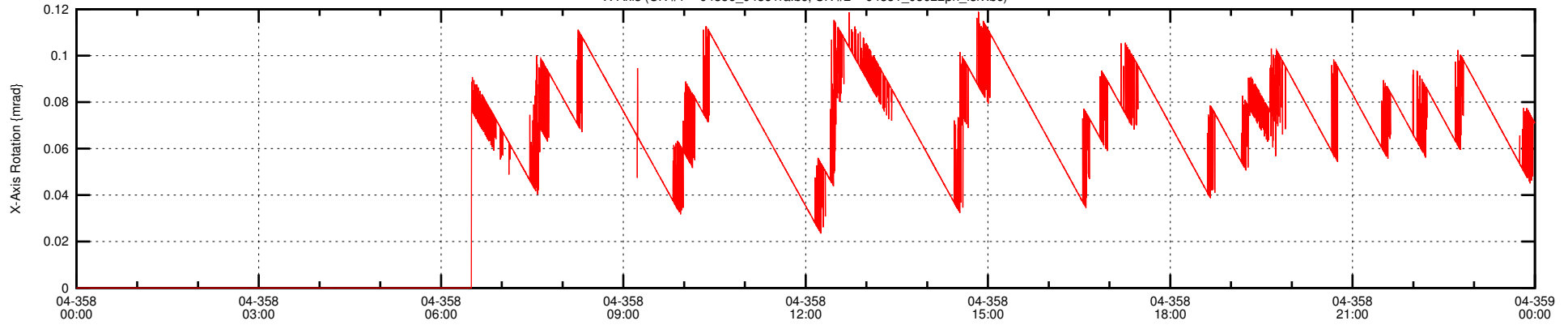


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 357-358)

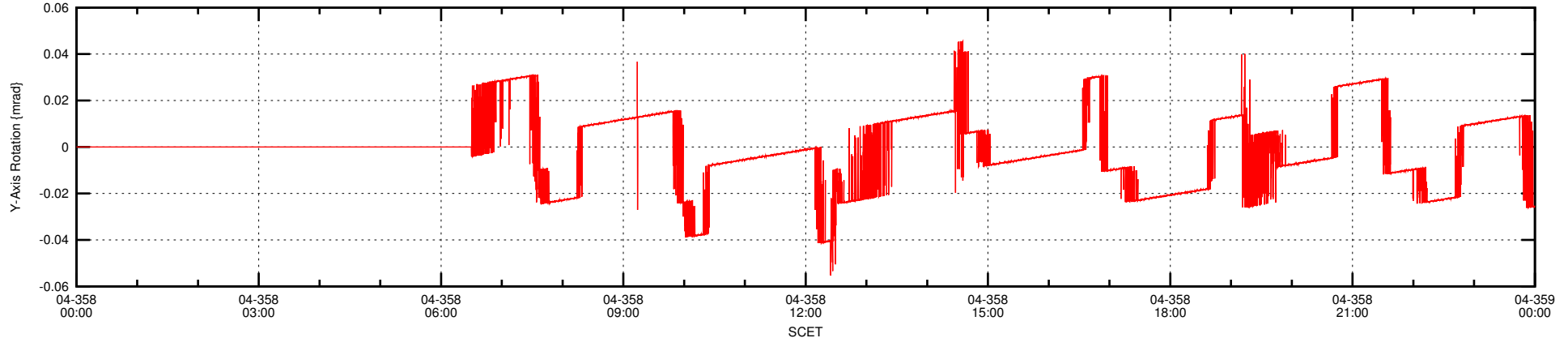


# Rotation From CK #2 to CK #1 (DOY 358-359)

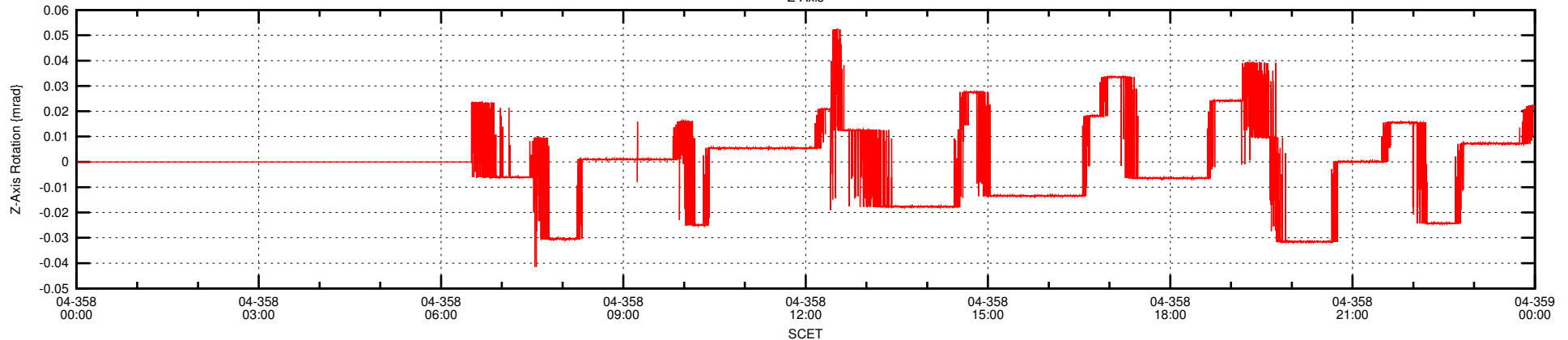
X-Axis (CK #1 = 04356\_04361ra.bc; CK #2 = 04351\_05022ph\_fsiv.bc)



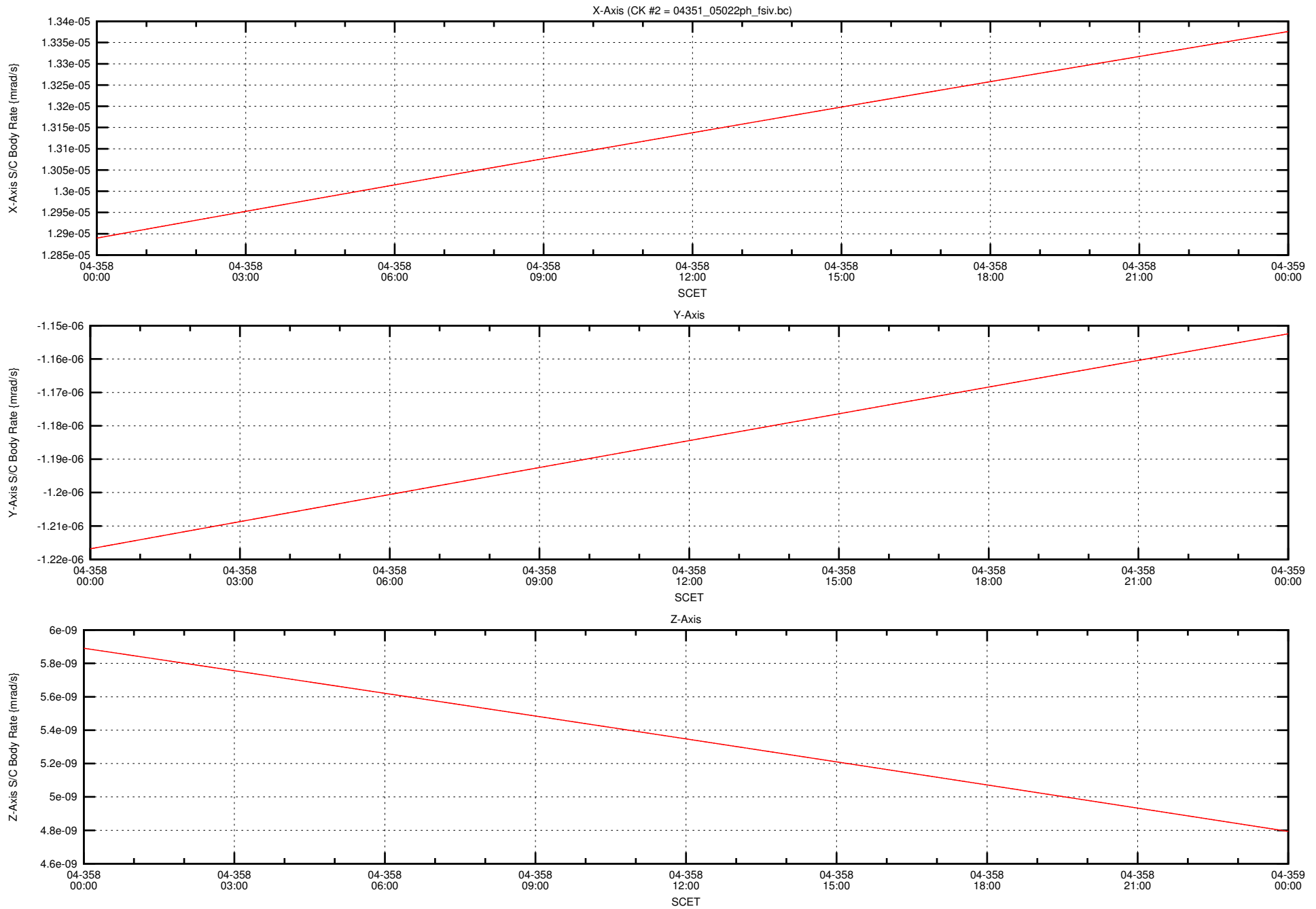
Y-Axis



Z-Axis

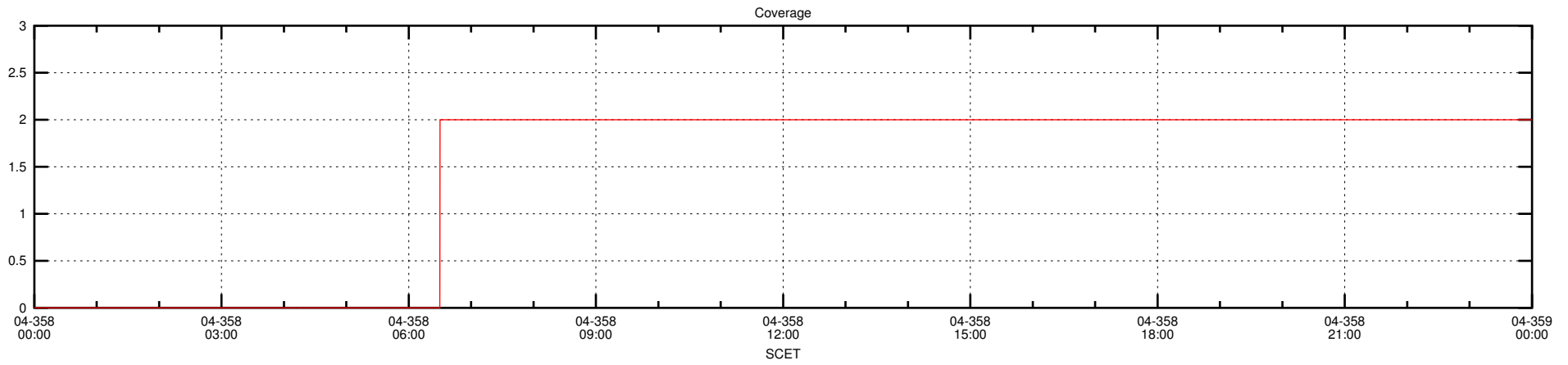


# CK #2 S/C Body Rates (DOY 358-359)



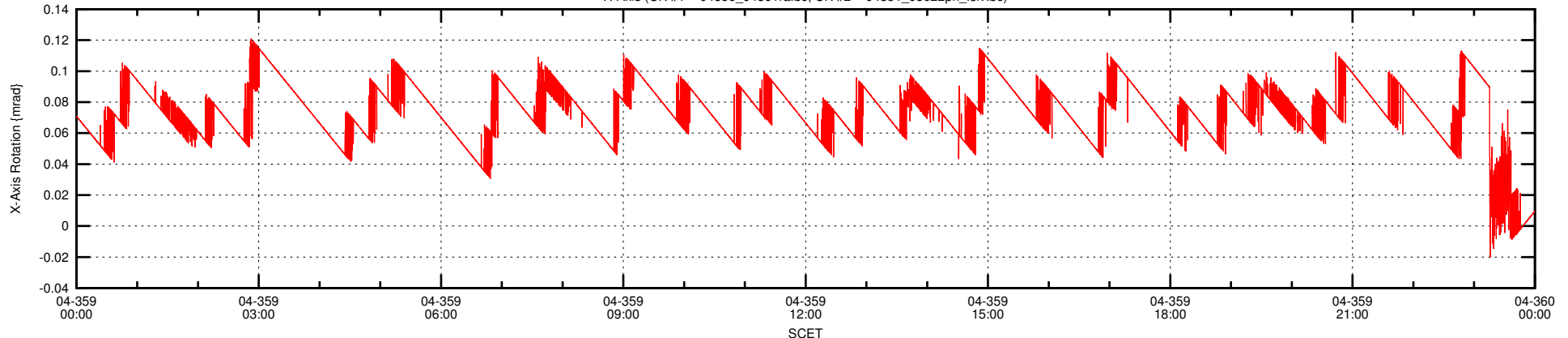


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 358-359)

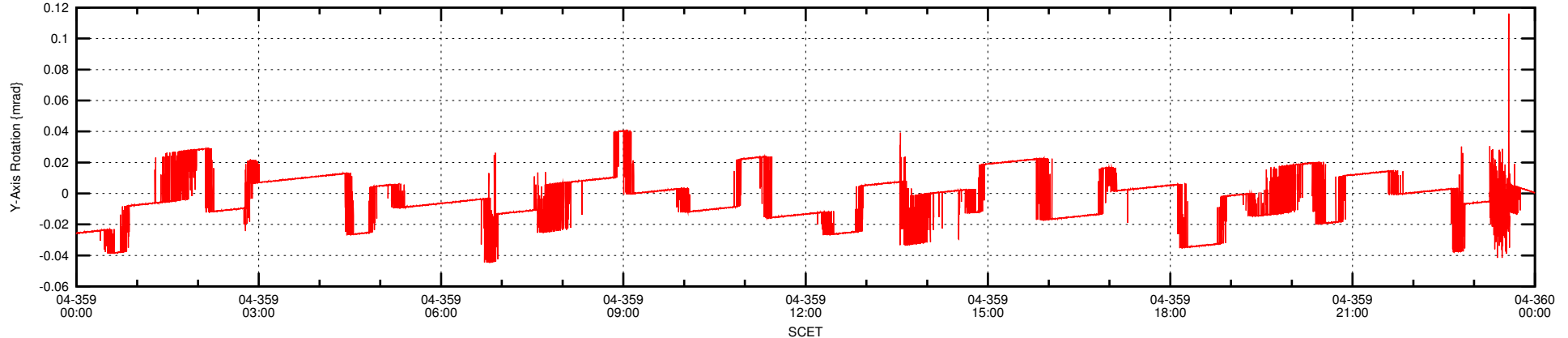


# Rotation From CK #2 to CK #1 (DOY 359-360)

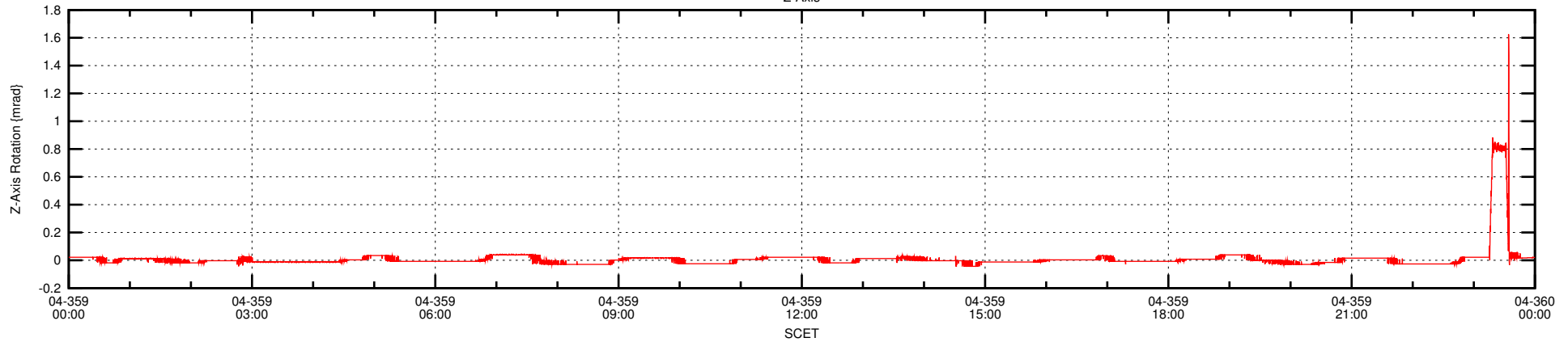
X-Axis (CK #1 = 04356\_04361ra.bc; CK #2 = 04351\_05022ph\_fsiv.bc)



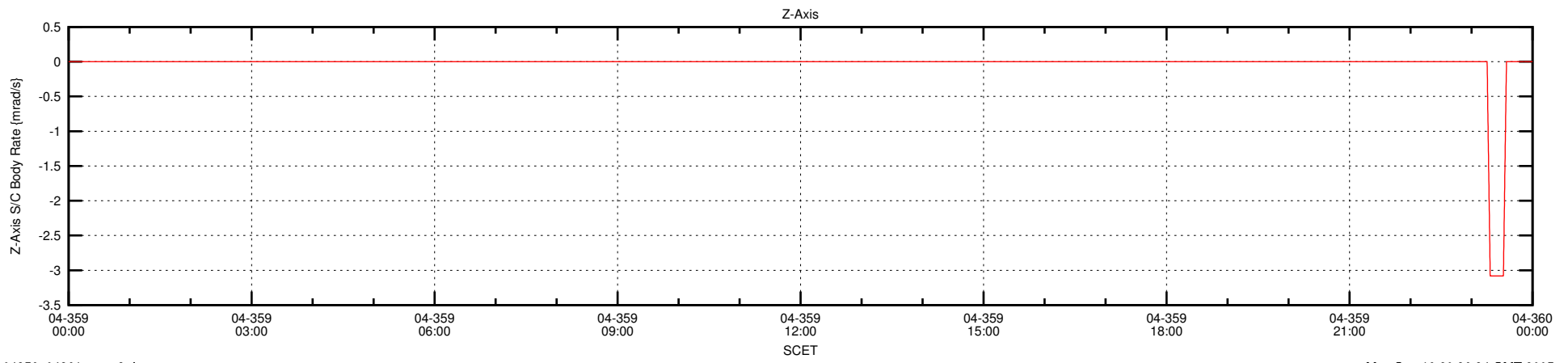
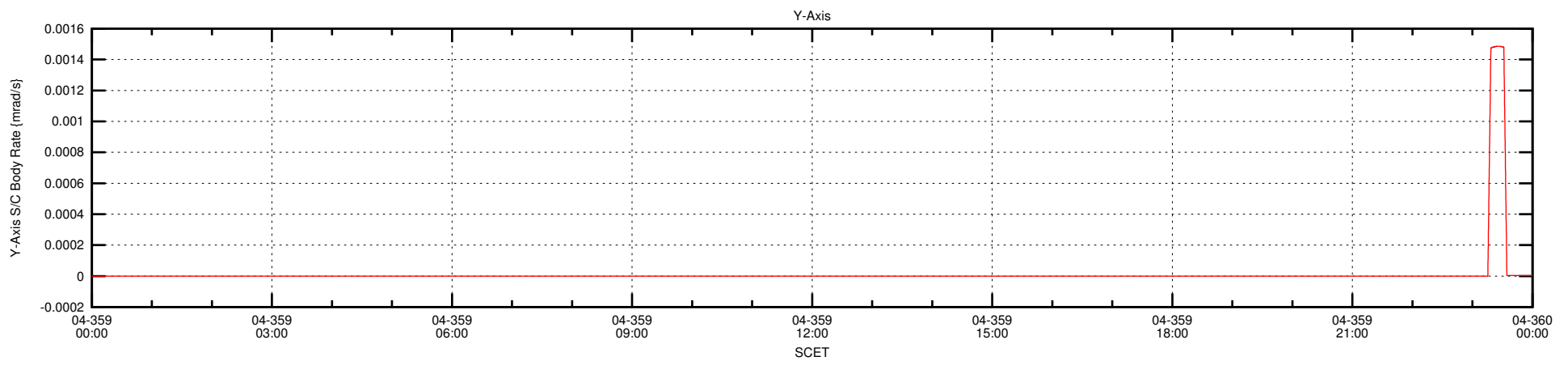
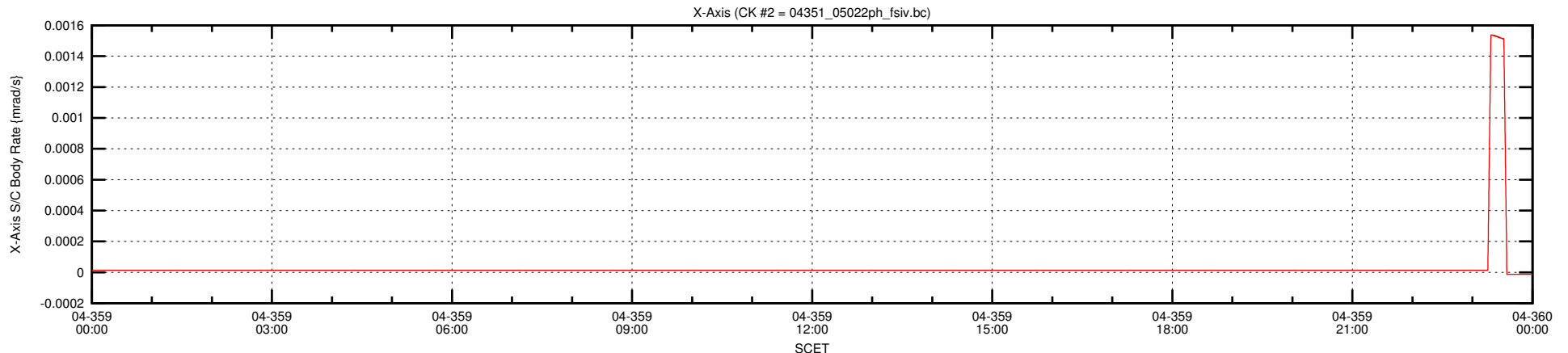
Y-Axis



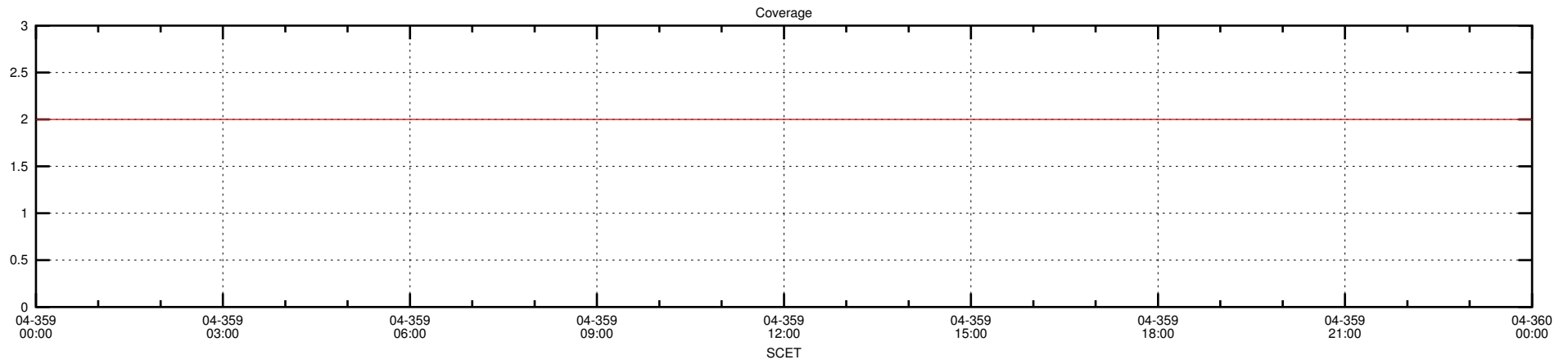
Z-Axis



# CK #2 S/C Body Rates (DOY 359-360)

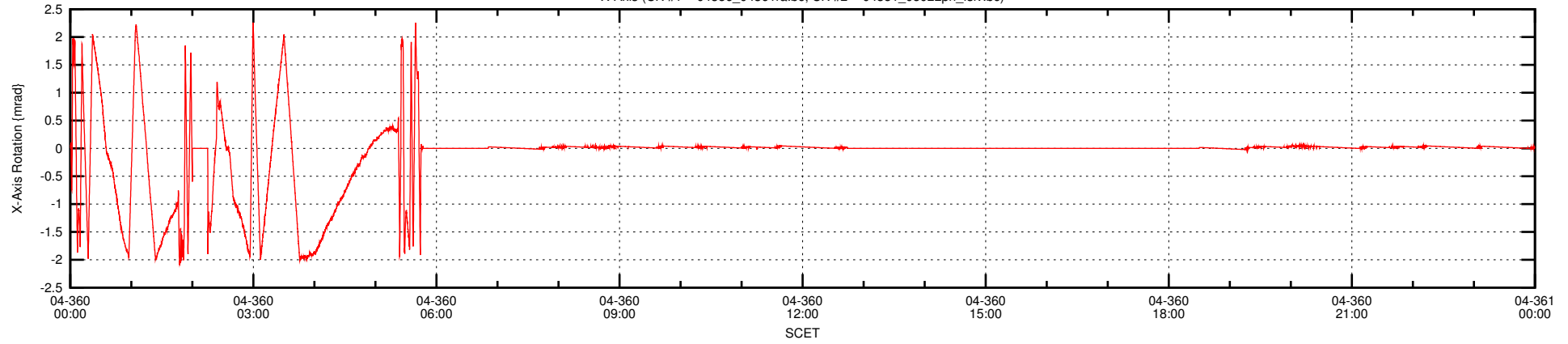


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 359-360)

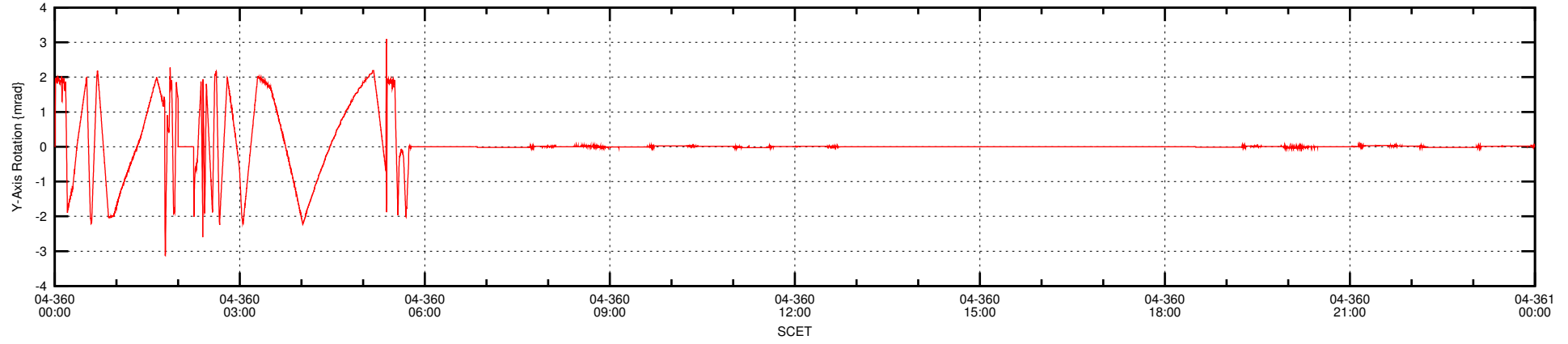


# Rotation From CK #2 to CK #1 (DOY 360-360)

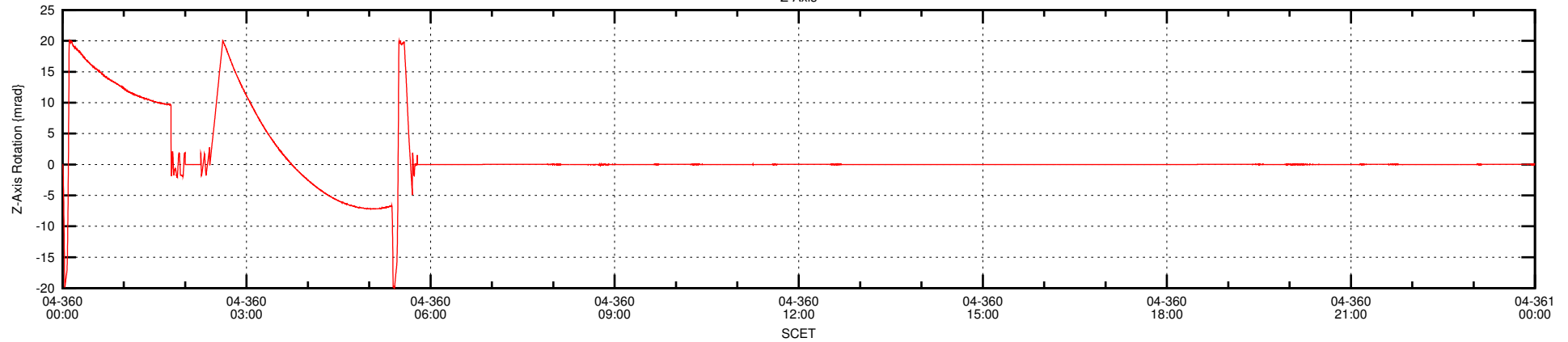
X-Axis (CK #1 = 04356\_04361ra.bc; CK #2 = 04351\_05022ph\_fsiv.bc)



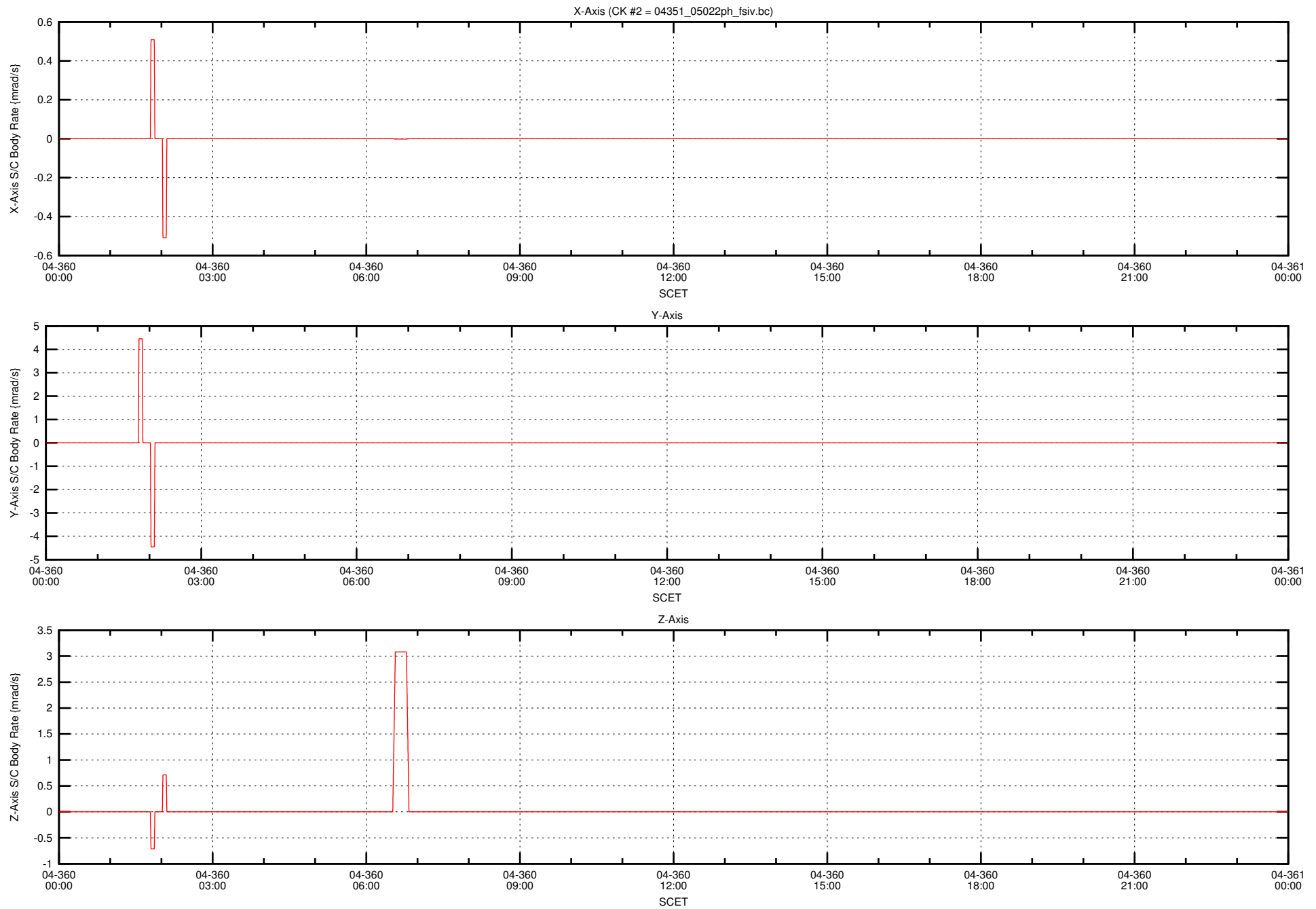
Y-Axis



Z-Axis



# CK #2 S/C Body Rates (DOY 360-360)



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 360-360)

