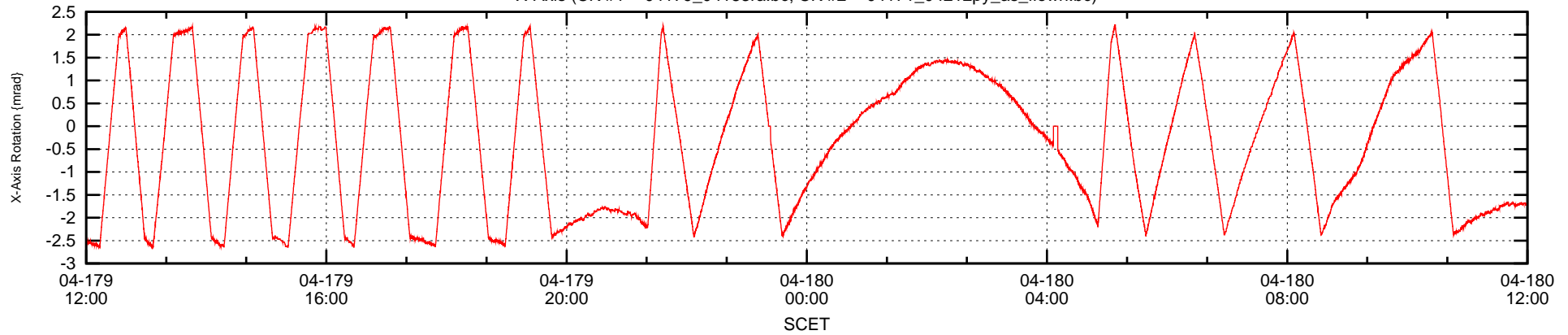
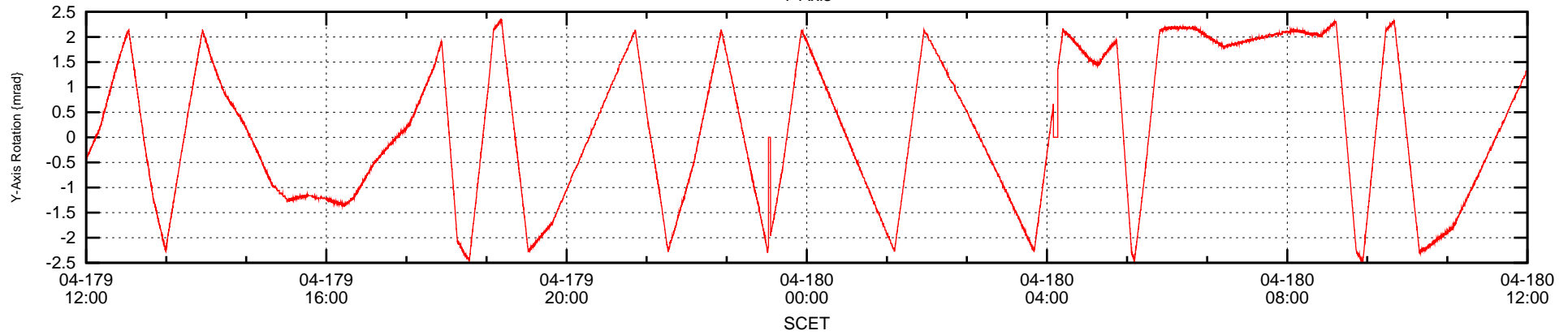


# Rotation From CK #2 to CK #1 (DOY 179-180)

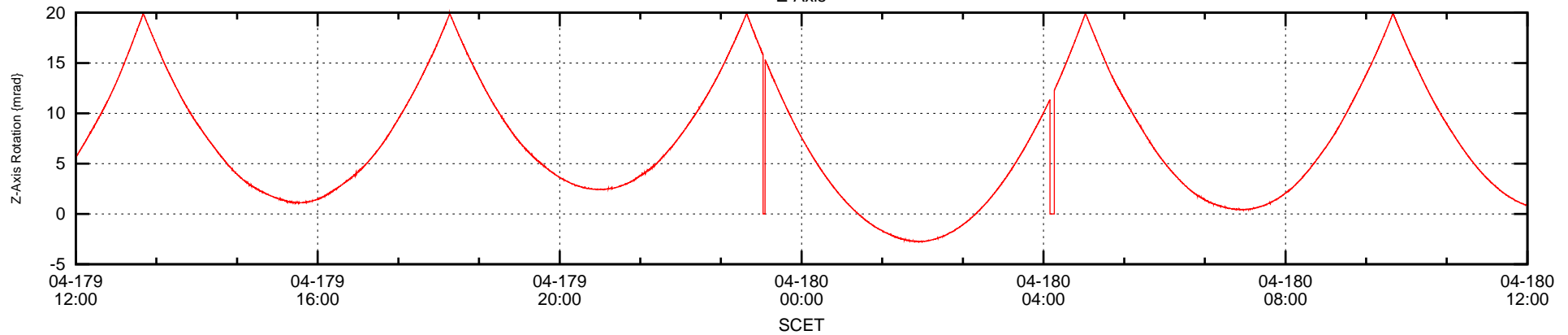
X-Axis (CK #1 = 04179\_04183ra.bc; CK #2 = 04171\_04212py\_as\_flown.bc)



Y-Axis

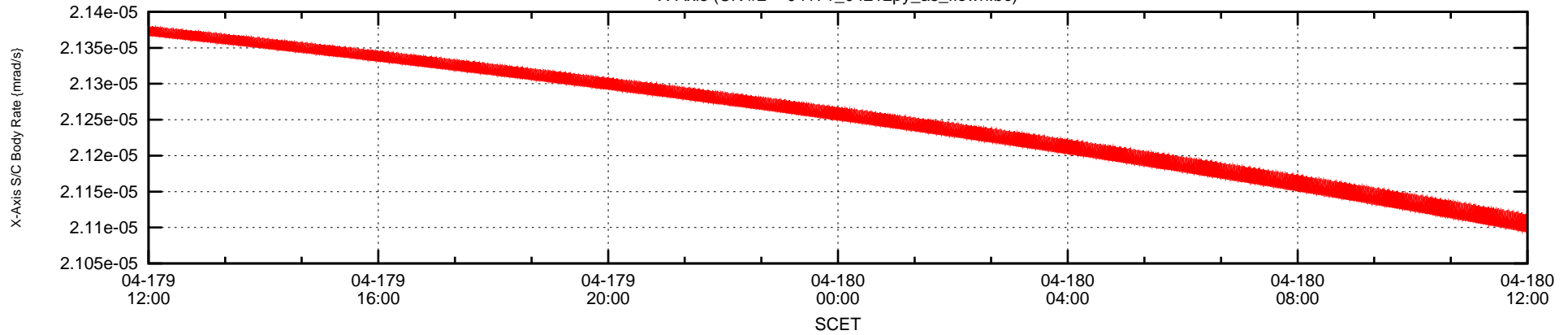


Z-Axis

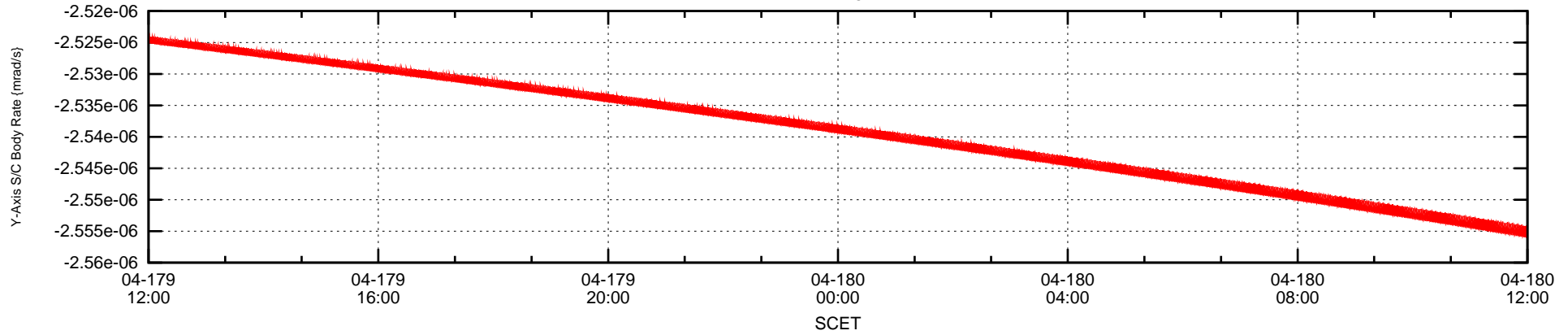


# CK #2 S/C Body Rates (DOY 179-180)

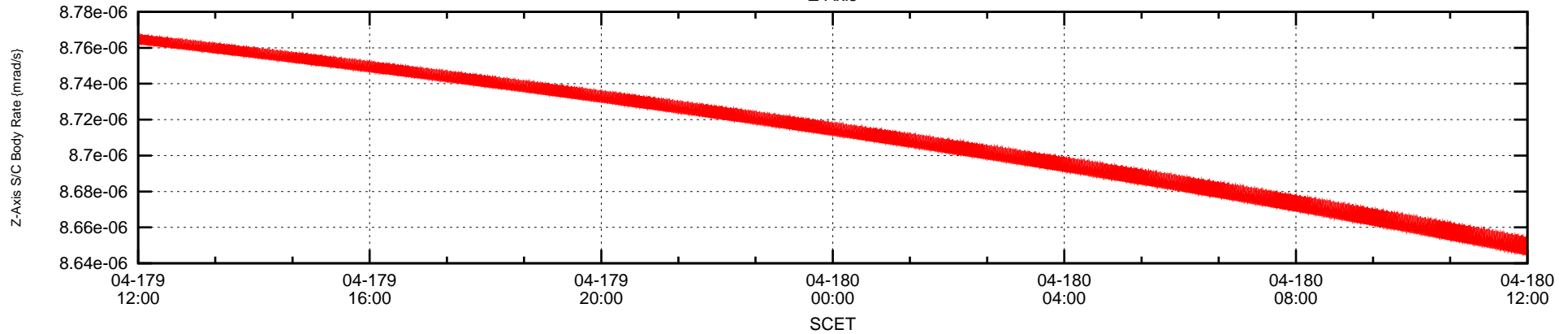
X-Axis (CK #2 = 04171\_04212py\_as\_flowm.bc)



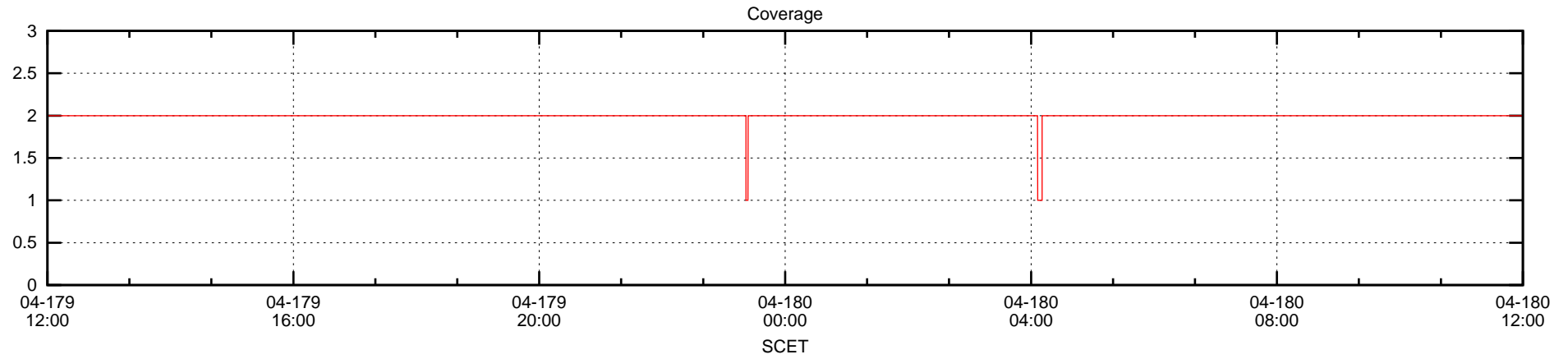
Y-Axis



Z-Axis

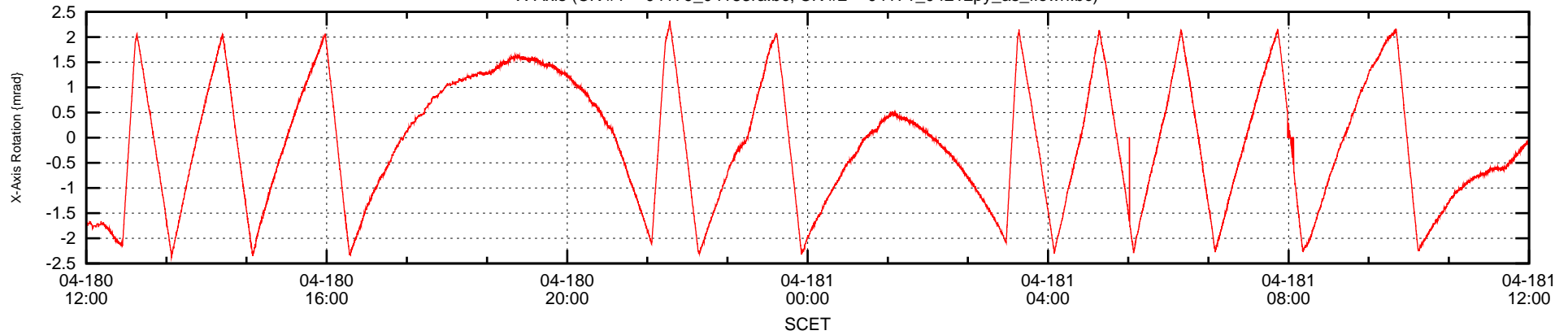


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 179-180)

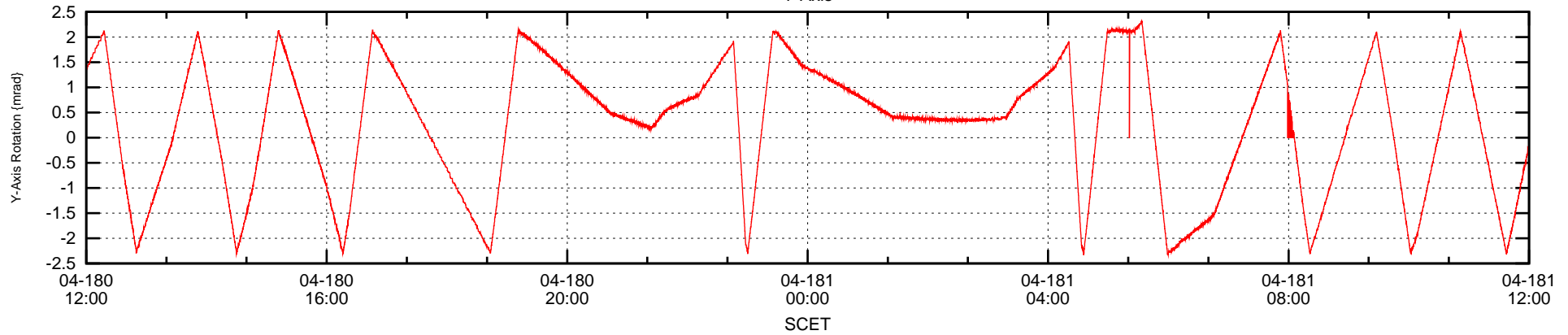


# Rotation From CK #2 to CK #1 (DOY 180-181)

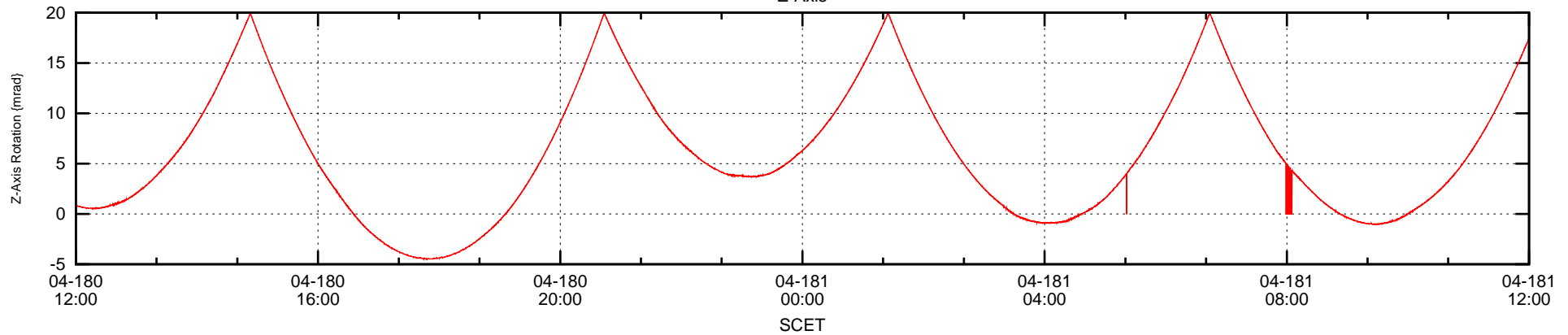
X-Axis (CK #1 = 04179\_04183ra.bc; CK #2 = 04171\_04212py\_as\_flowm.bc)



Y-Axis

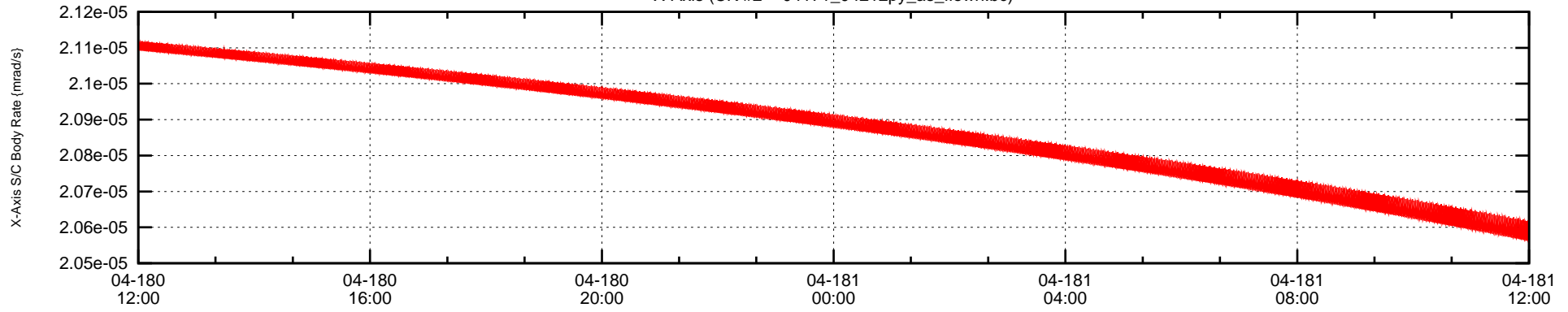


Z-Axis

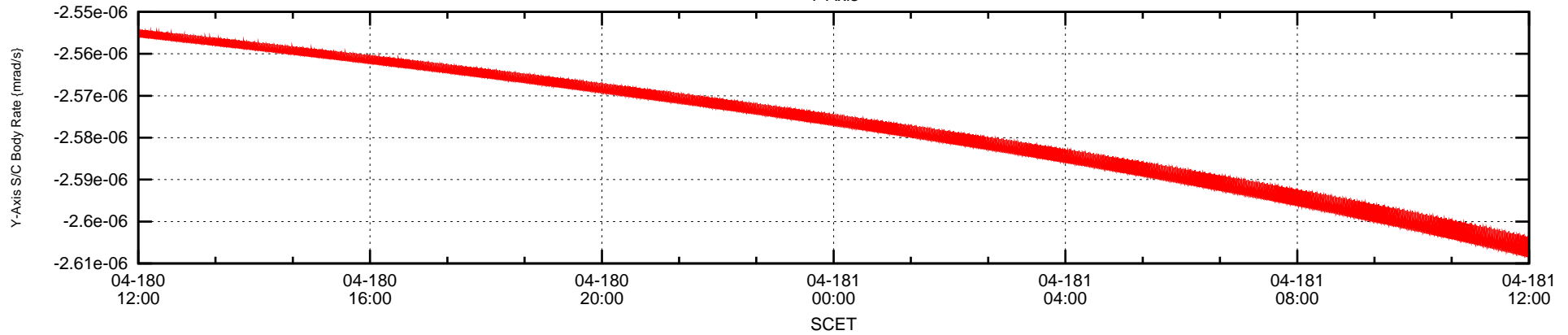


# CK #2 S/C Body Rates (DOY 180-181)

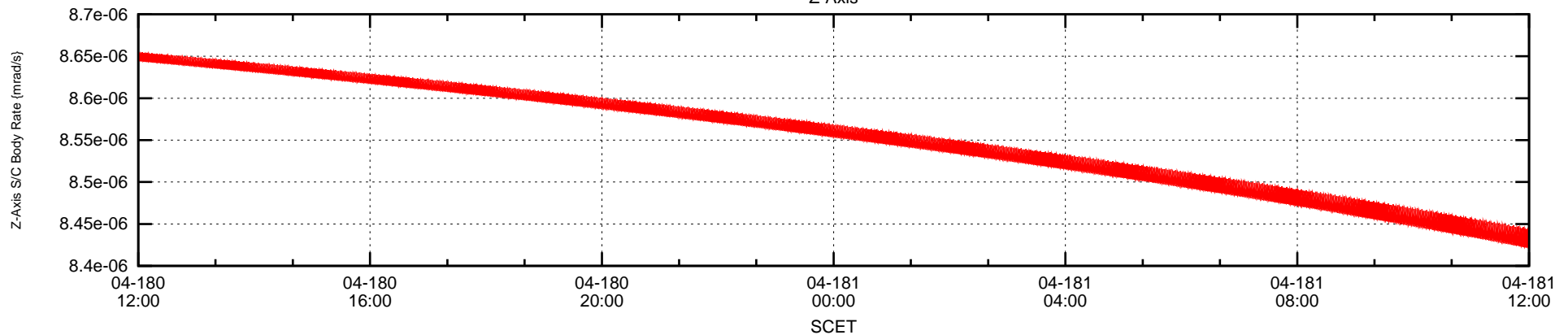
X-Axis (CK #2 = 04171\_04212py\_as\_flown.bc)



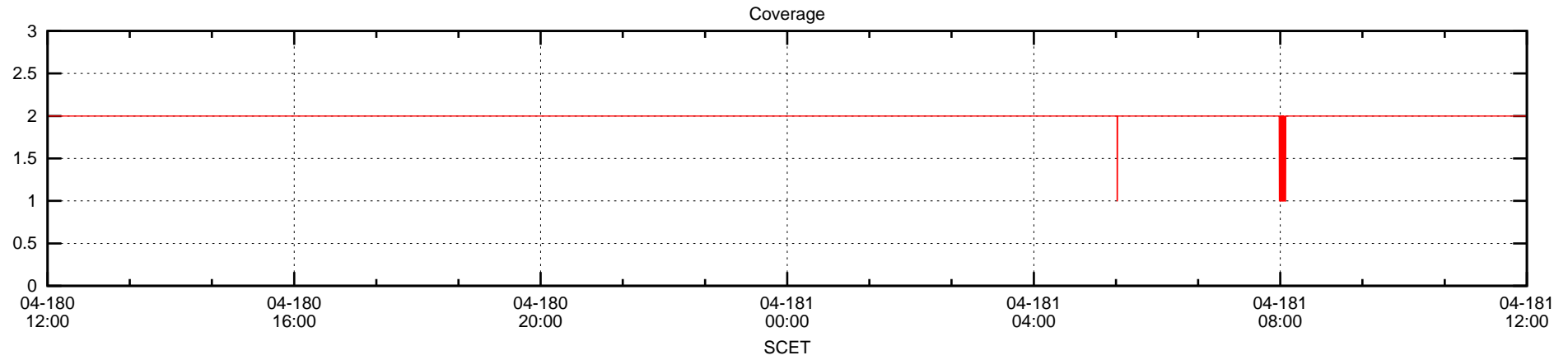
Y-Axis



Z-Axis

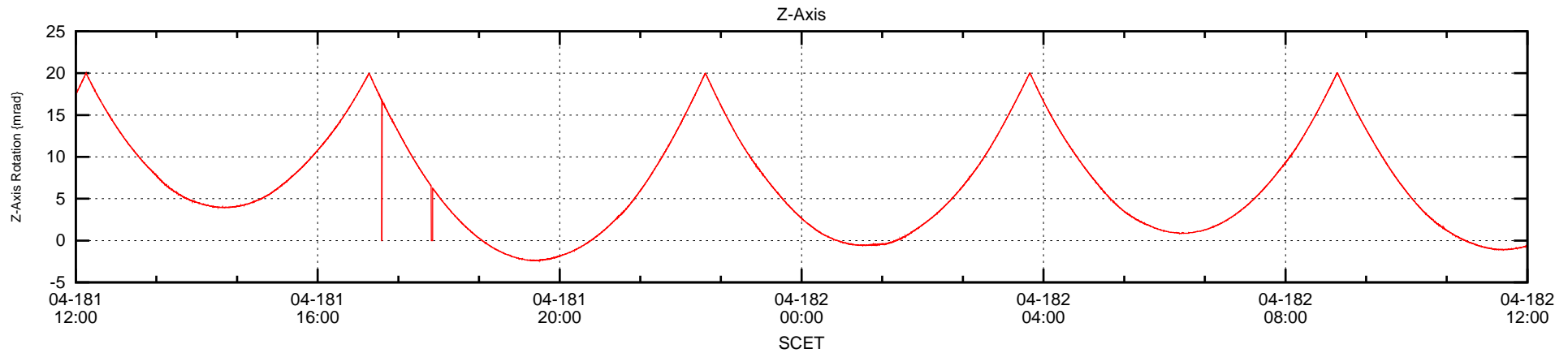
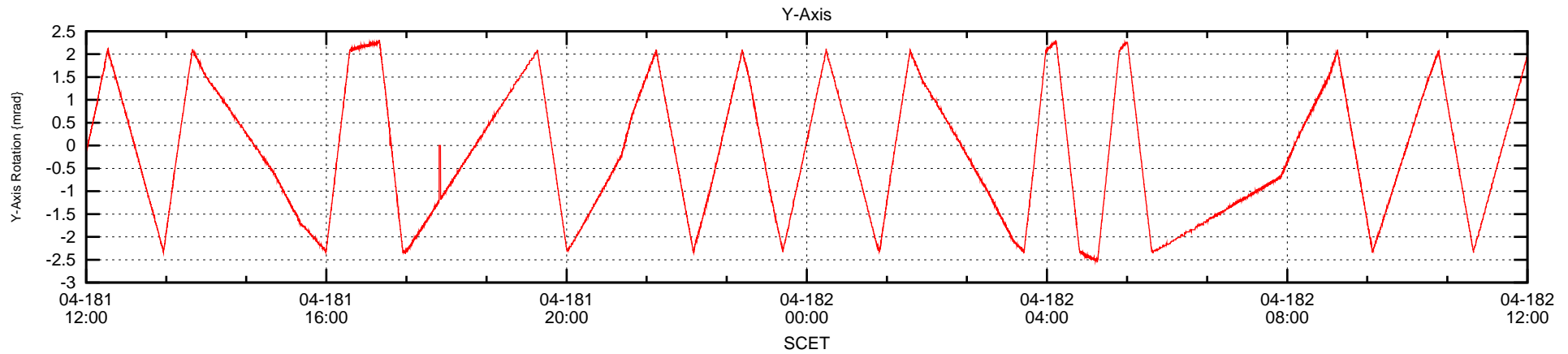
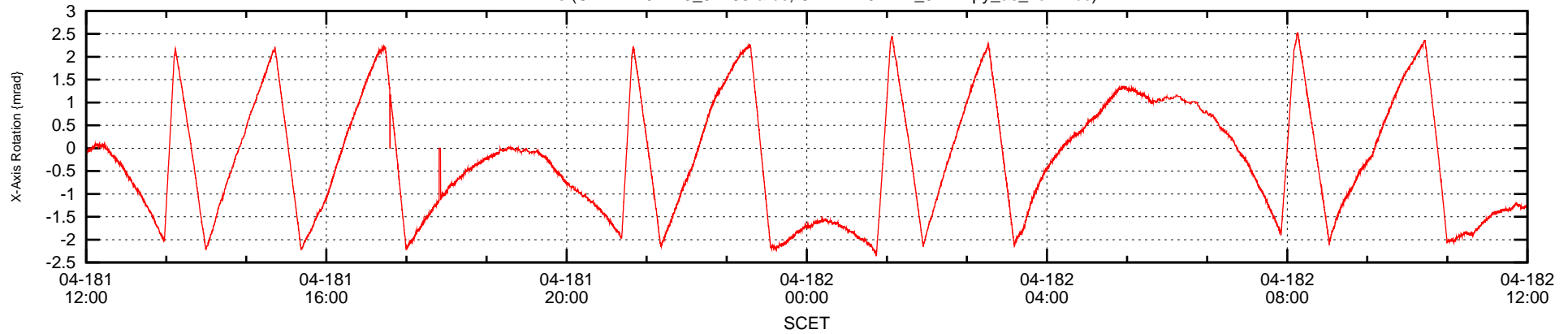


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 180-181)



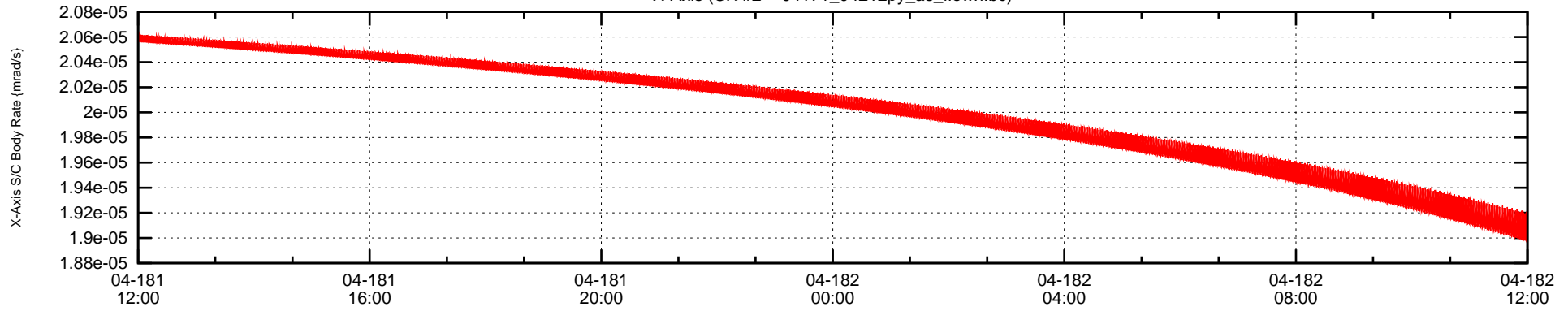
# Rotation From CK #2 to CK #1 (DOY 181-182)

X-Axis (CK #1 = 04179\_04183ra.bc; CK #2 = 04171\_04212py\_as\_flown.bc)

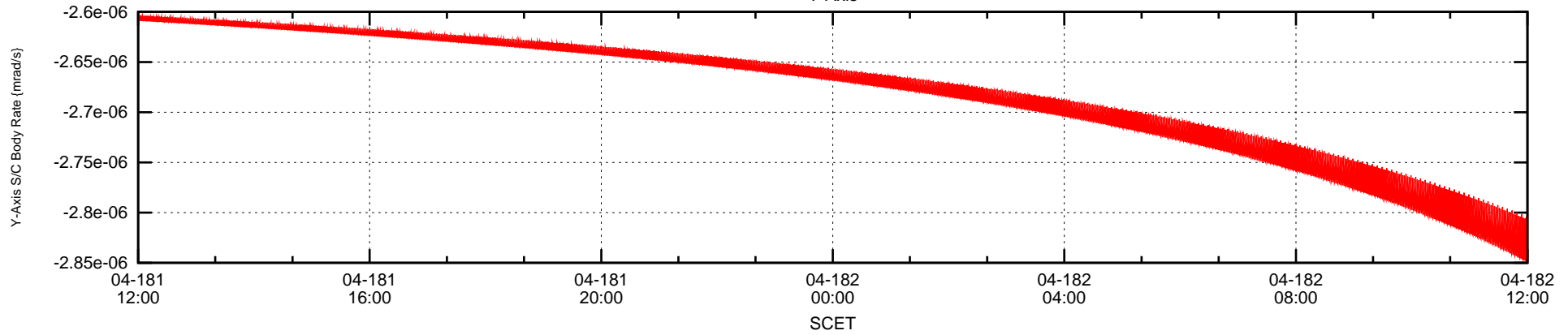


# CK #2 S/C Body Rates (DOY 181-182)

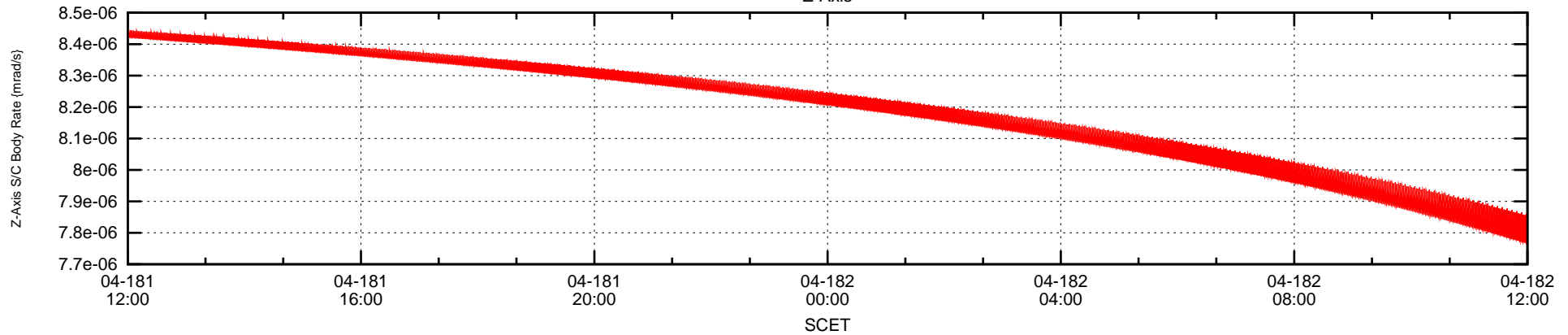
X-Axis (CK #2 = 04171\_04212py\_as\_flown.bc)



Y-Axis

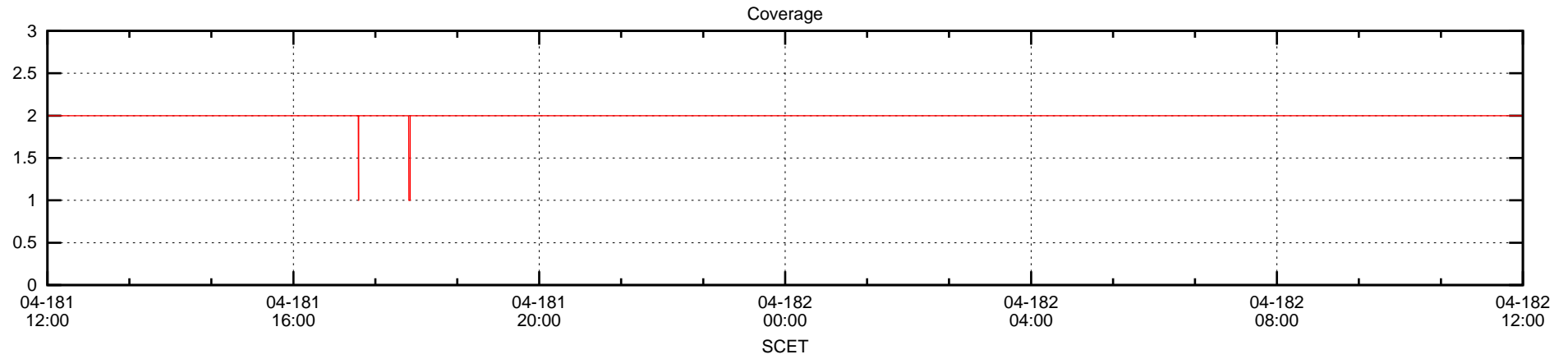


Z-Axis



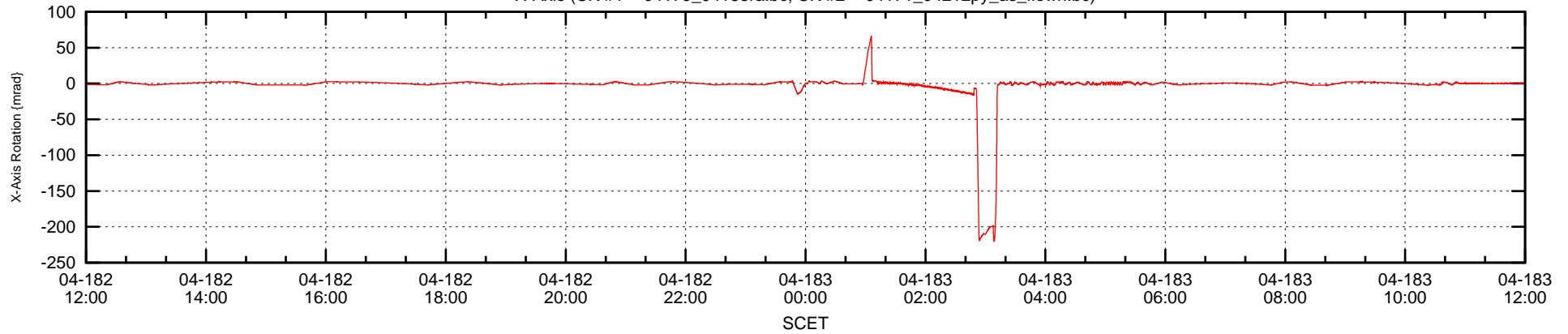


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 181-182)

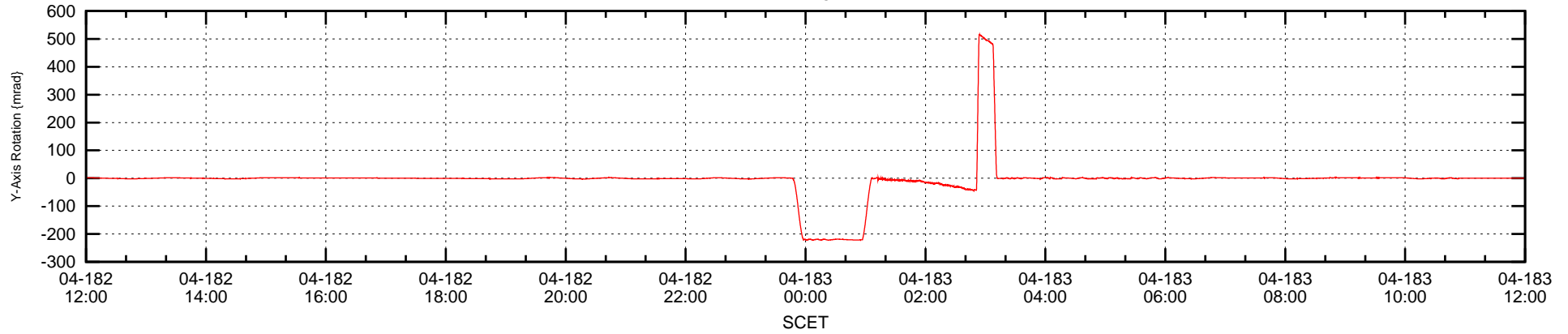


# Rotation From CK #2 to CK #1 (DOY 182-183)

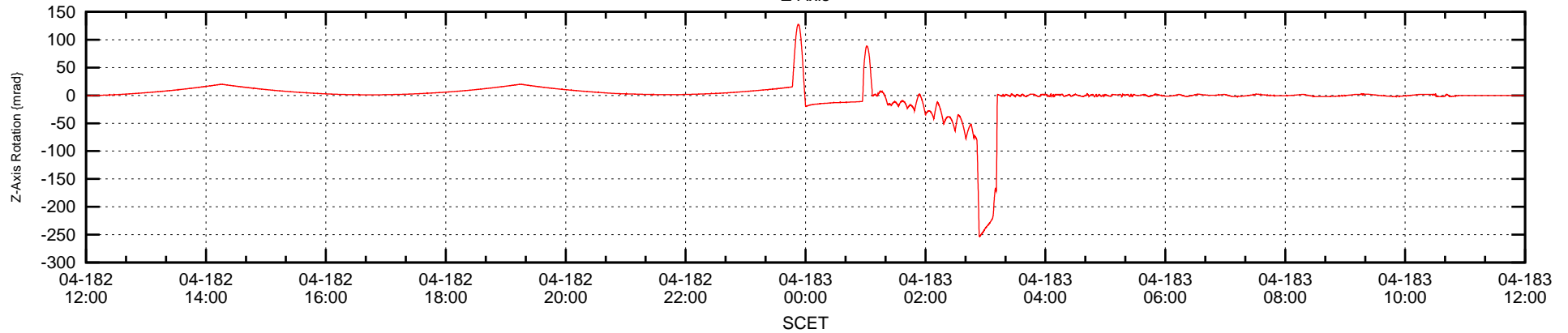
X-Axis (CK #1 = 04179\_04183ra.bc; CK #2 = 04171\_04212py\_as\_flowm.bc)



Y-Axis

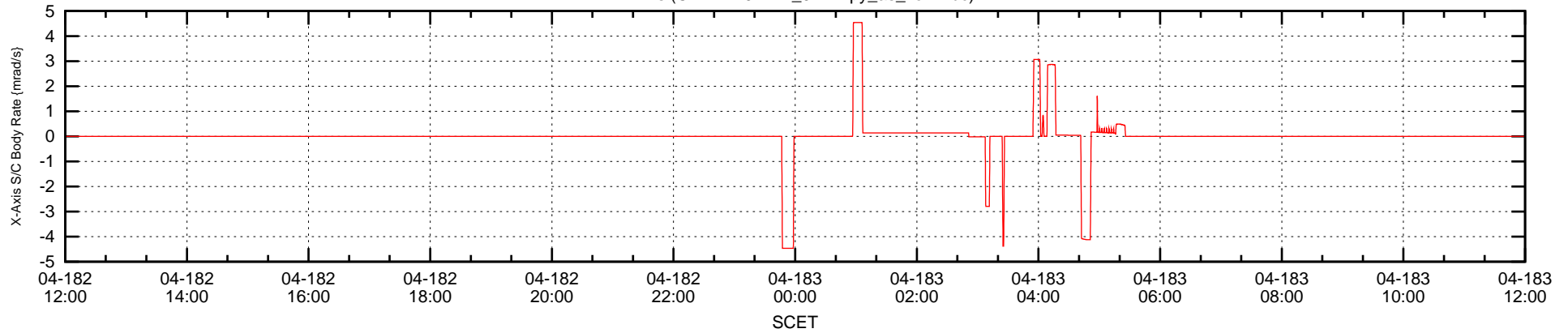


Z-Axis

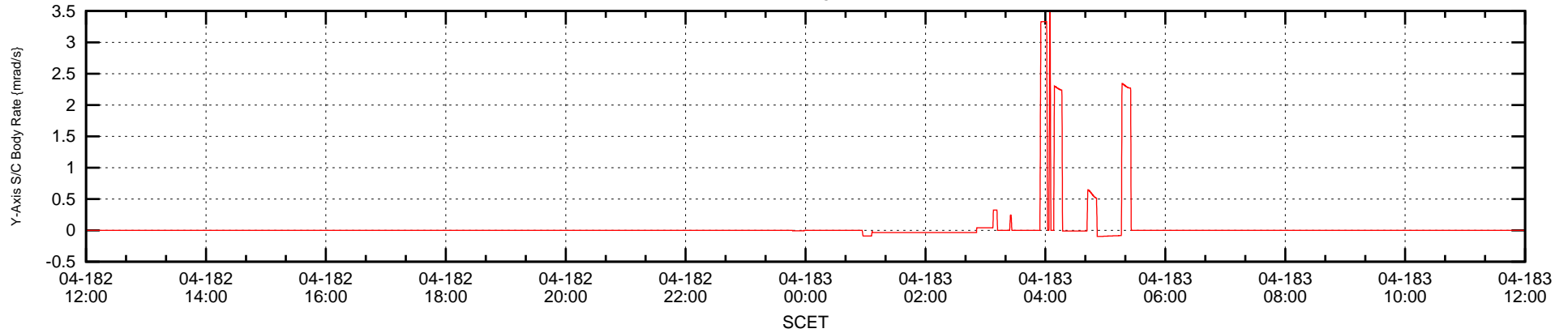


# CK #2 S/C Body Rates (DOY 182-183)

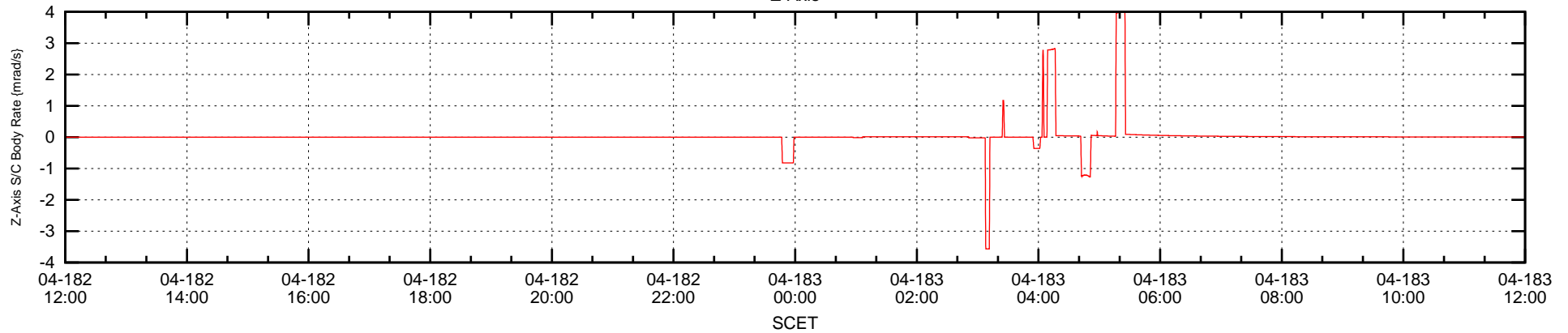
X-Axis (CK #2 = 04171\_04212py\_as\_flown.bc)



Y-Axis



Z-Axis



All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 182-183)

