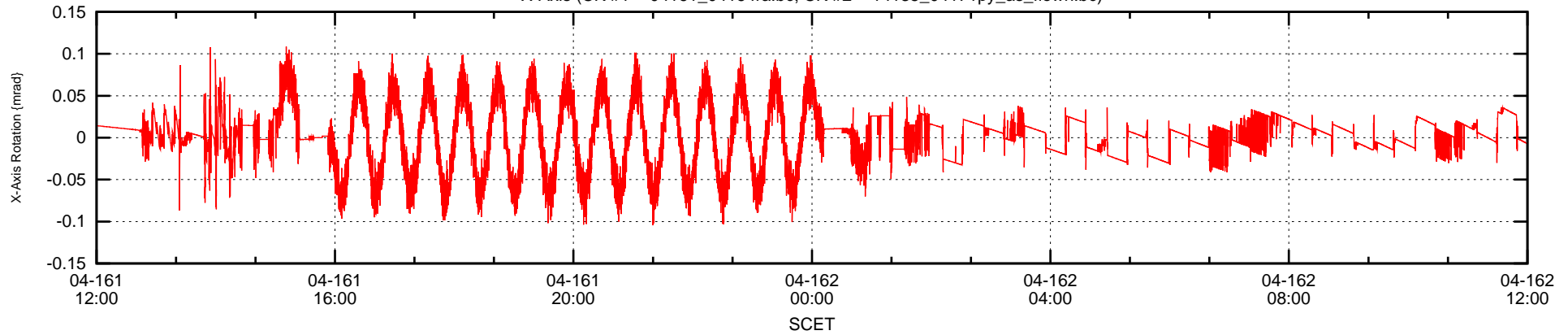
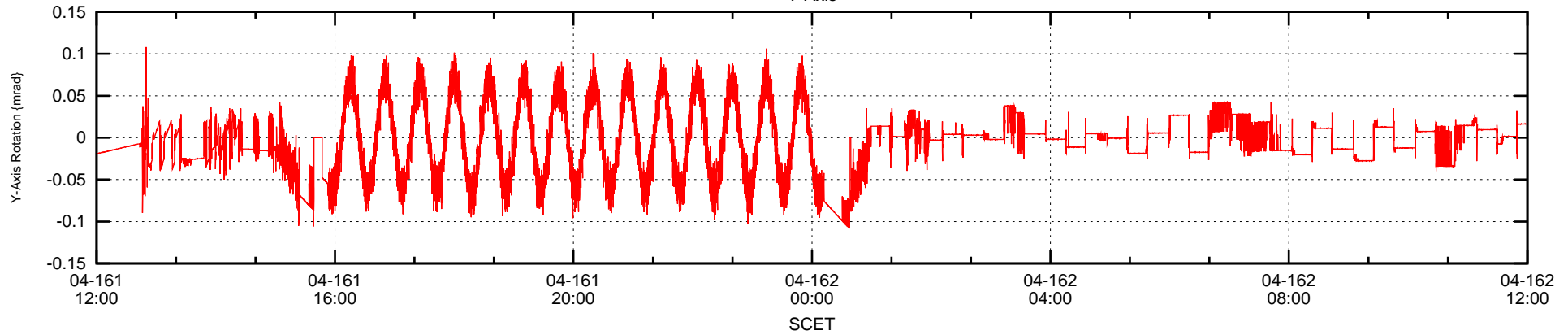


# Rotation From CK #2 to CK #1 (DOY 161-162)

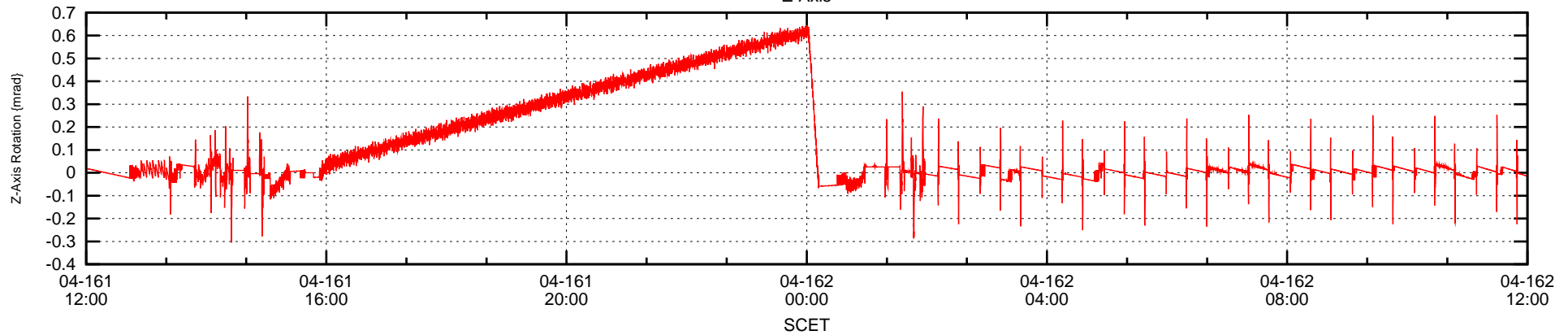
X-Axis (CK #1 = 04161\_04164ra.bc; CK #2 = 14135\_04171py\_as\_flown.bc)



Y-Axis

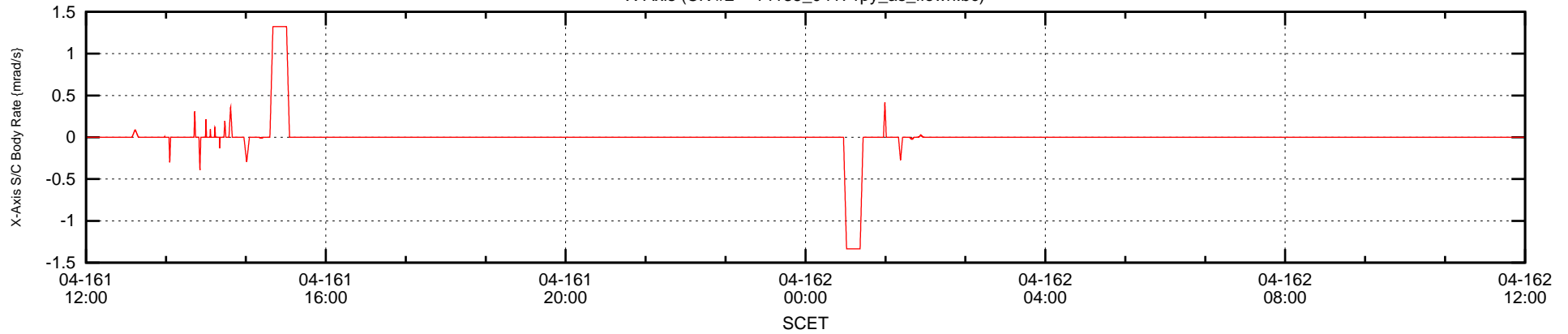


Z-Axis

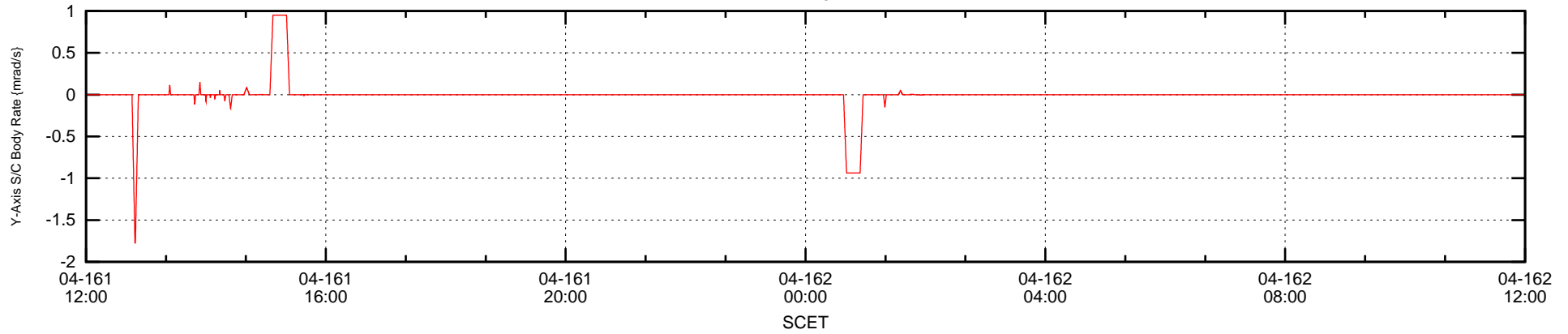


# CK #2 S/C Body Rates (DOY 161-162)

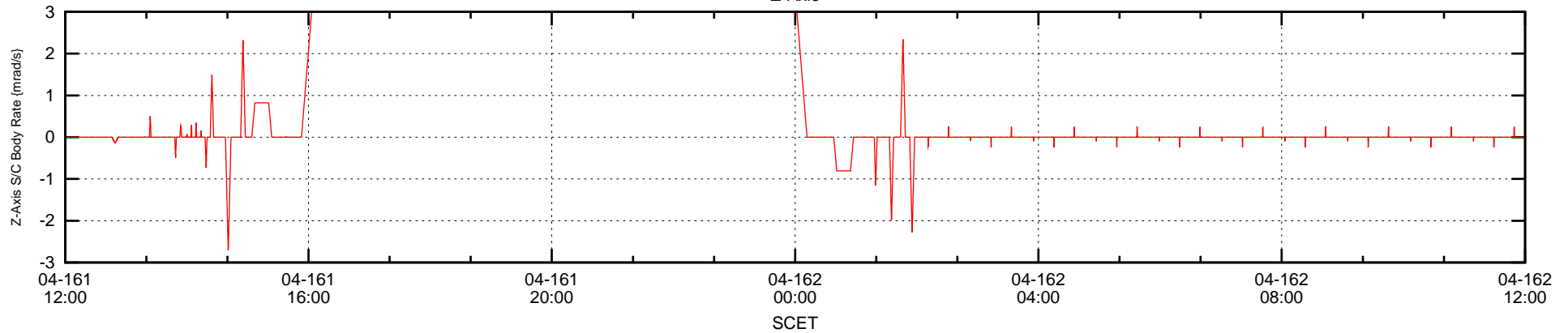
X-Axis (CK #2 = 14135\_04171py\_as\_flowm.bc)



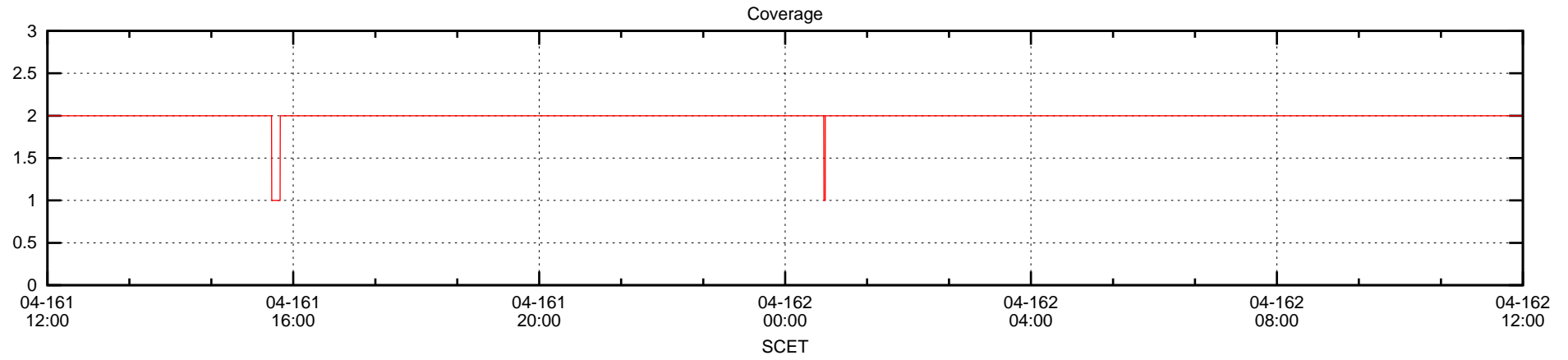
Y-Axis



Z-Axis

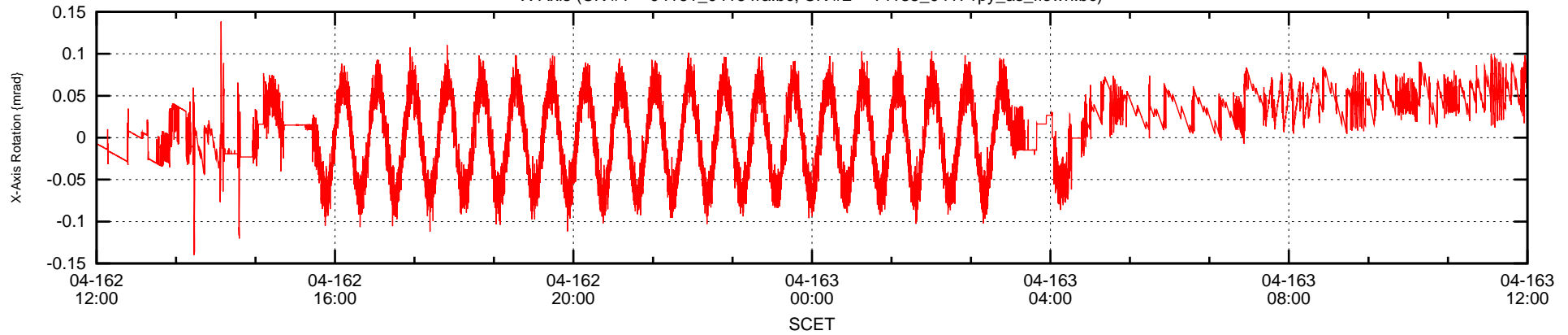


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 161-162)

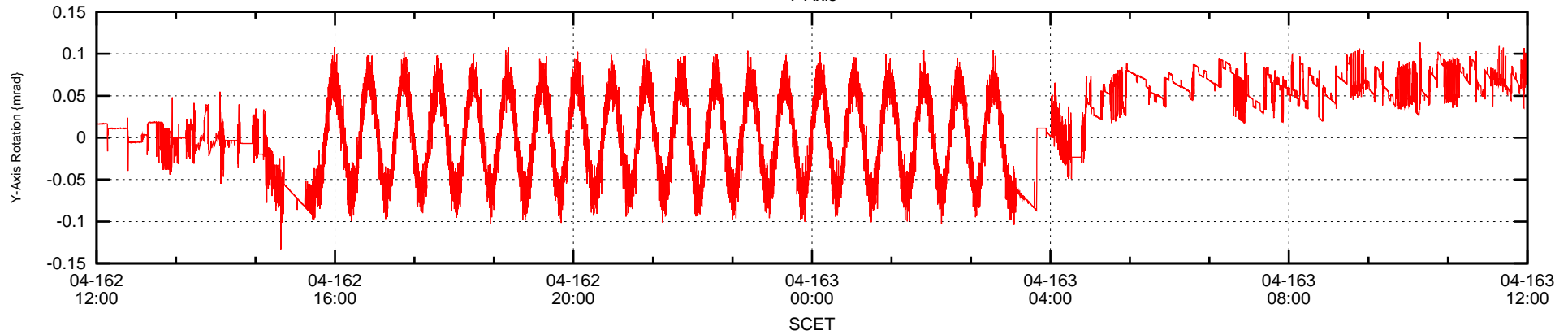


# Rotation From CK #2 to CK #1 (DOY 162-163)

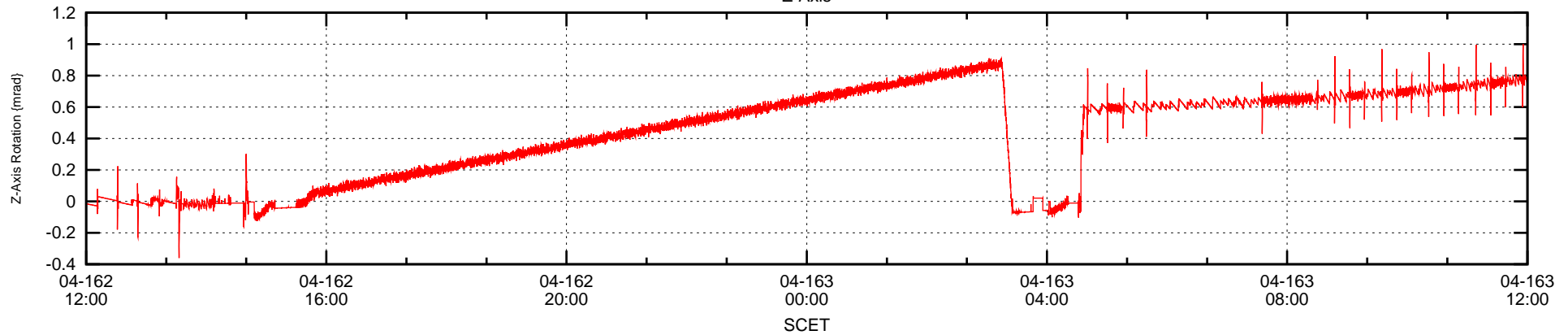
X-Axis (CK #1 = 04161\_04164ra.bc; CK #2 = 14135\_04171py\_as\_flow.n.bc)



Y-Axis

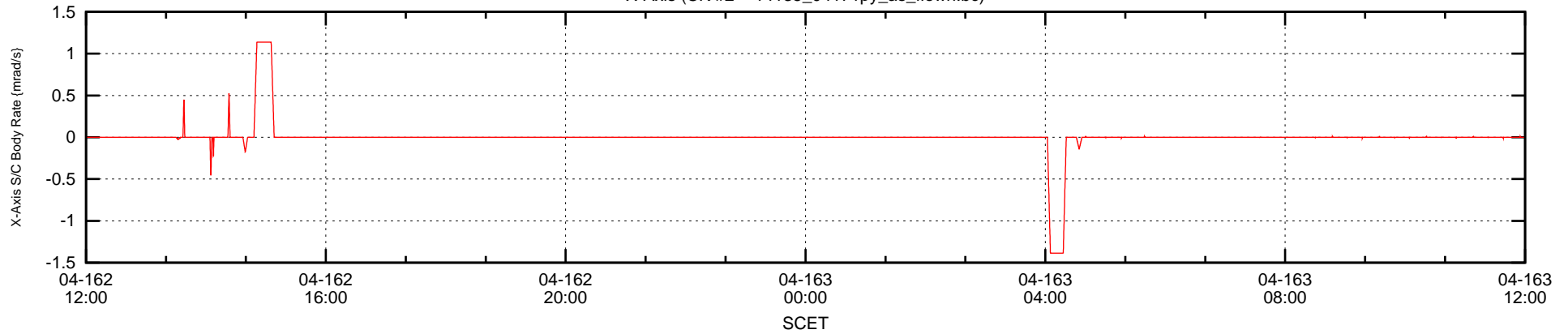


Z-Axis

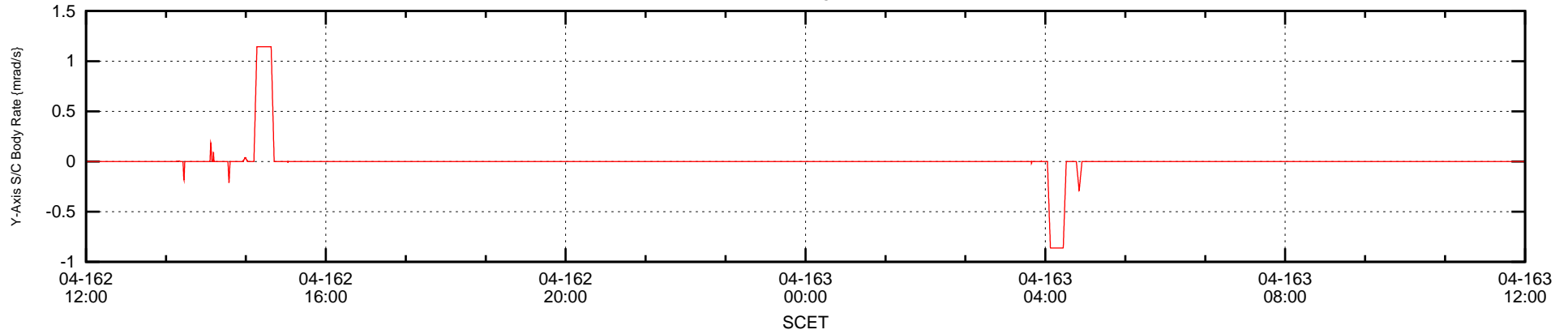


# CK #2 S/C Body Rates (DOY 162-163)

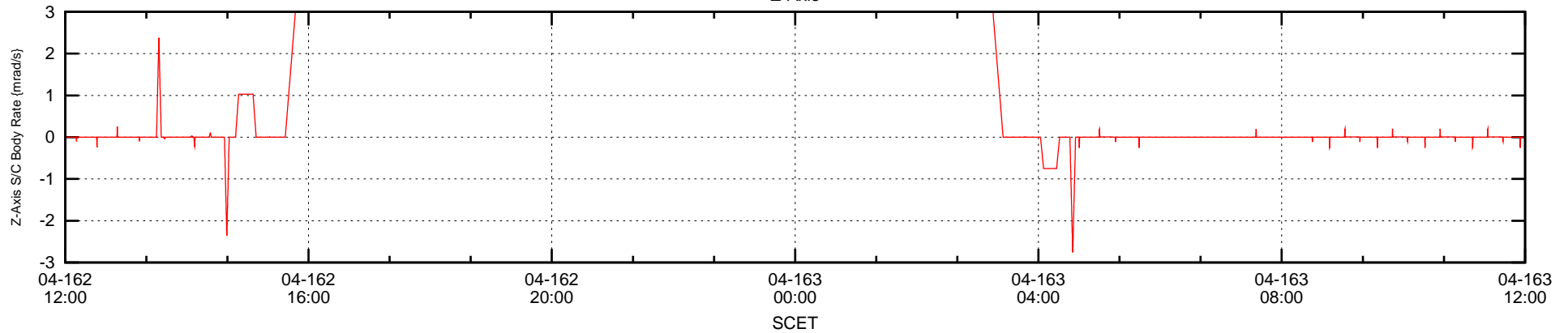
X-Axis (CK #2 = 14135\_04171py\_as\_flowm.bc)



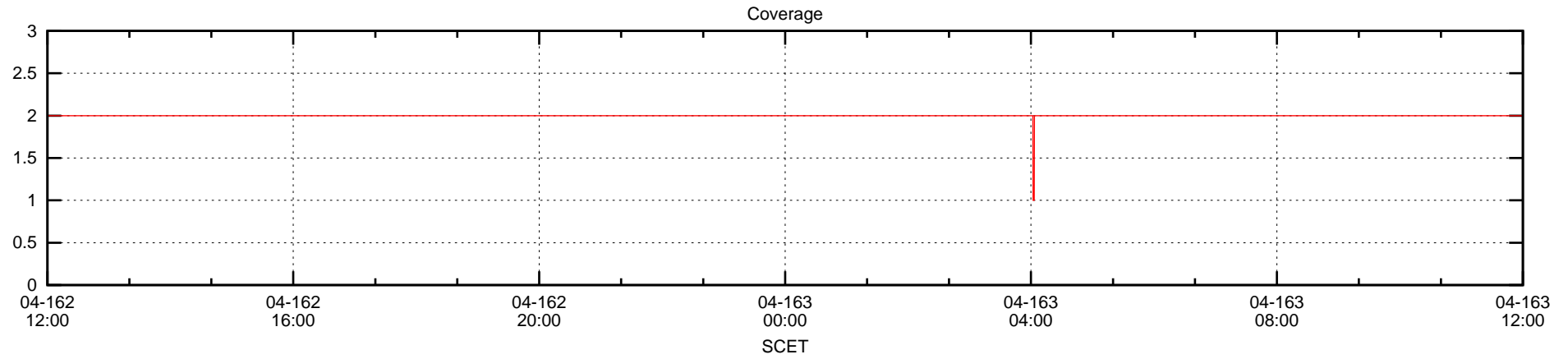
Y-Axis



Z-Axis

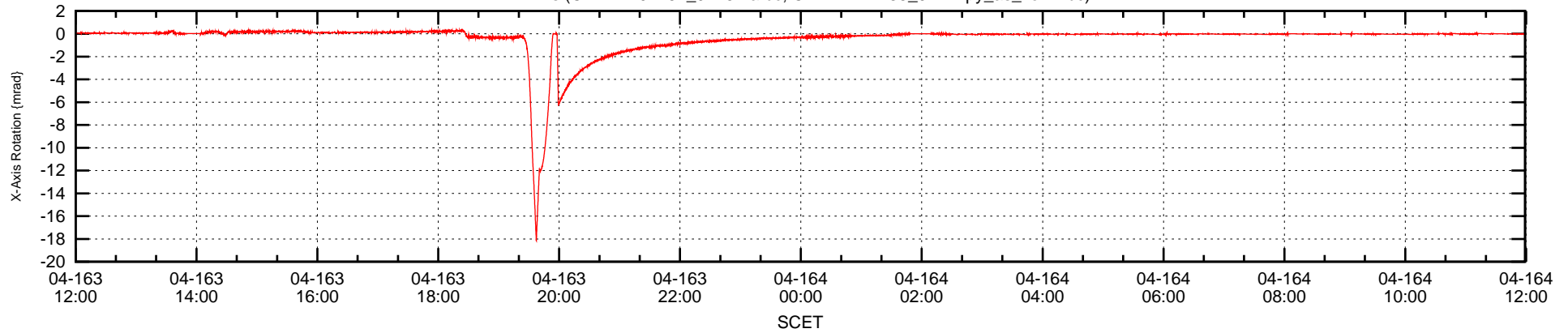


All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 162-163)

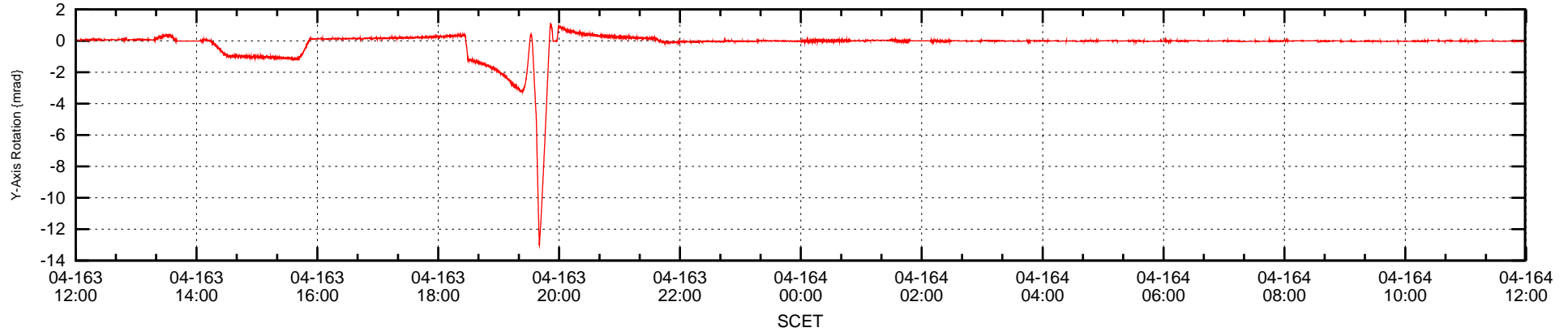


# Rotation From CK #2 to CK #1 (DOY 163-164)

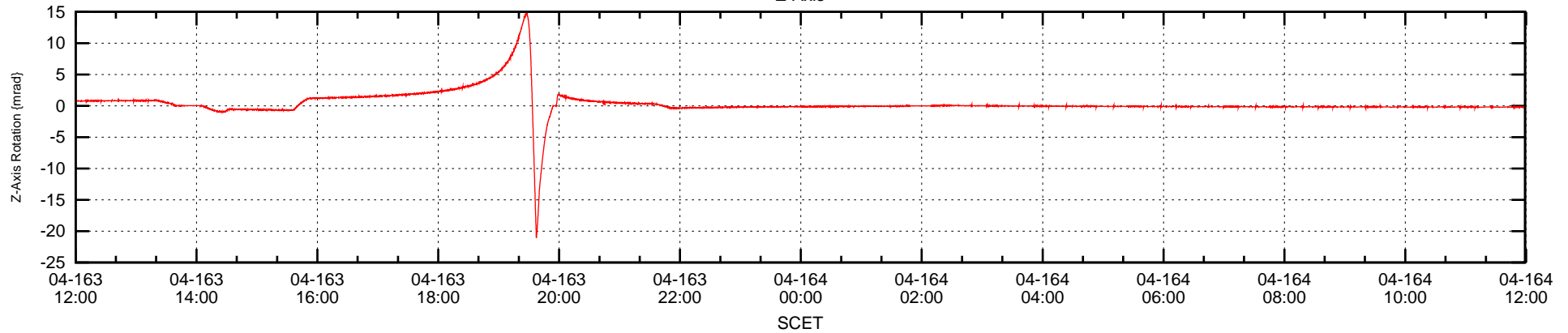
X-Axis (CK #1 = 04161\_04164ra.bc; CK #2 = 14135\_04171py\_as\_flown.bc)



Y-Axis

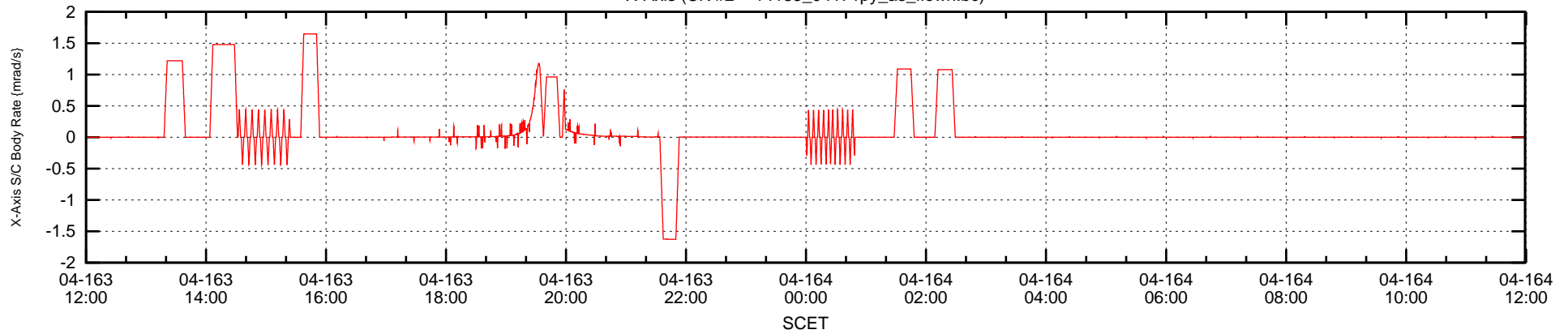


Z-Axis

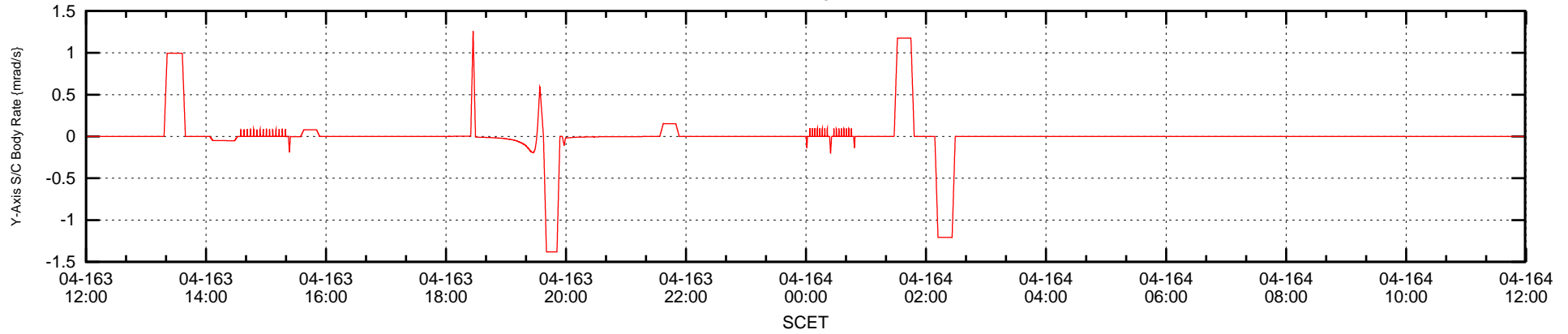


# CK #2 S/C Body Rates (DOY 163-164)

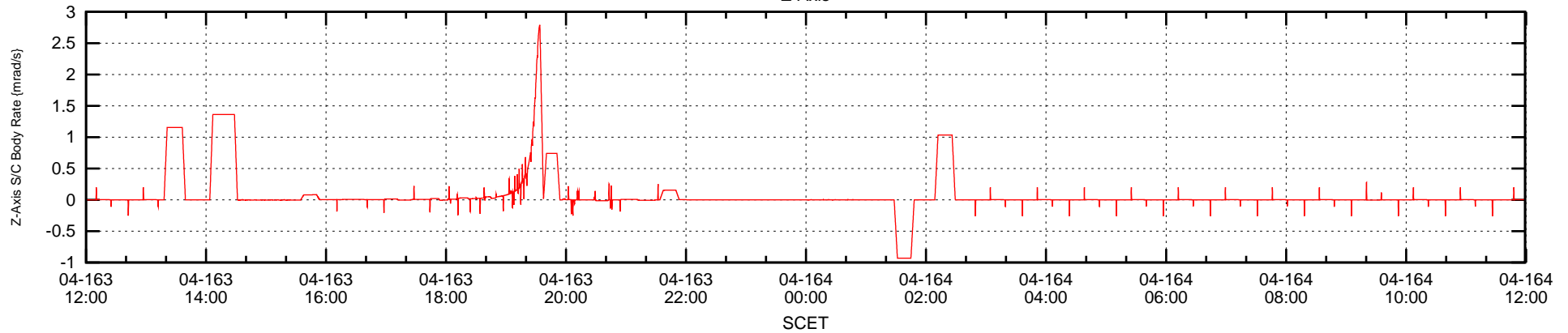
X-Axis (CK #2 = 14135\_04171py\_as\_flown.bc)



Y-Axis



Z-Axis





All Data Present = 2, Recon Missing = 1, Real-Time Activity (Predict Not Applicable) = 0 (DOY 163-164)

