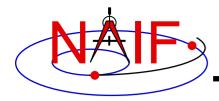


#### **Navigation and Ancillary Information Facility**

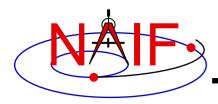
# SPICE Development Plans and Possibilities

**April 2023** 



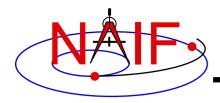
#### SPICE 2.0

- Develop SPICE 2.0: a re-implementation of the SPICE Toolkit from the ground, up, providing thread-safe and object oriented features
  - This is the major NAIF undertaking, started in May 2017
  - It is being implemented in C++11
  - It is expected to take several years
- More details in "SPICE 2.0 Preview" Tutorial (available upon request)
- No worries: none of the current Toolkits will be dropped.



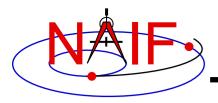
### **DSK Shape Models**

- Extension of the DSK shape model subsystem
  - Complete the Type 4 DSK code for working with digital elevation models developed for SMAP
  - Add more functionality to the tessellated plate model (Type 2 DSK)
    - » The first official version of the Type 2 subsystem, for small, irregularly shaped bodies, was released in the N66 Toolkits
  - Unfortunately NAIF has no real target date in mind for this work



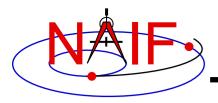
### **Tool Development**

- Continue adding capabilities to the WebGeocalc tool
  - More kinds of calculations
  - More ease-of-use features
  - This work is on-going
- Continue adding capabilities to the Cosmographia
  3D mission visualization program
  - This work is on-going



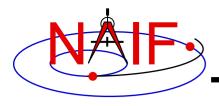
# **Support for More Languages-1**

- Complete the Java Native Interface (JNISpice)
  Toolkit family
  - Capability is parallel to CSPICE, and reliability is very good
    NAIF used JNISpice to implement the WebGeocalc tool
  - Additional documentation needs to be written
- Python interface
  - 3<sup>rd</sup> party SpiceyPy enjoys wide adoption and use, fulfilling the needs of the community
  - Because of that, NAIF does not plan to do its own Python work in the foreseeable future



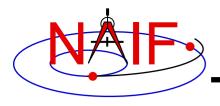
# **Support for More Languages-2**

- 3<sup>rd</sup> parties have also implemented Ruby, Swift, Julia, Rust, Unreal Engine interfaces to CSPICE
  - NAIF server provides links to some of them
    - » <a href="https://naif.jpl.nasa.gov/naif/links.html">https://naif.jpl.nasa.gov/naif/links.html</a>
  - NAIF hasn't tried testing any of these packages
  - NAIF does not know how complete they are
  - Give them a try, but use due caution as you do so
    - » You might be able to do some one-off tests using the WebGeocalc tool as a "gold bar"
    - » You could try using the "spice\_discussion" bulletin board to see what other people have to say about these interfaces



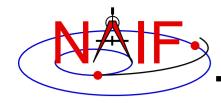
#### **Some Other Possibilities?**

- More high-level SPICE 1.0 (current SPICE) computations, such as specular point
- More "geometry finder" computations
- Develop a more flexible and extensible instrument modeling mechanism



#### **Programmatic Expansion**

- NAIF is helping the Republic of South Korea implement SPICE on their Korean Pathfinder Lunar Orbiter (KPLO) mission
- Colleagues at LASP are helping the United Arab Emirates deploy SPICE in support of their upcoming Hope mission to Mars
- We hope to find the means to support upcoming planetary science-focused SmallSat/CubeSat missions and Commercial Lunar Payload Systems (CLPS) program



#### What do You Suggest?

- NAIF solicits suggestions from you!
  - How might we improve SPICE?
  - How might we improve SPICE training?
  - How might we improve NAIF's operations?
  - How might we improve SPICE operability across the large and still growing space exploration community?
- We're interested in programmatic ideas as well as technical ones.